

Input:

C : regularization parameter

tol : numerical tolerance

max_passes : max # of times to iterate over α 's without changing $(x^{(1)}, y^{(1)}), \dots, (x^{(m)}, y^{(m)})$: training data

Output:

$\alpha \in \mathbb{R}^m$: Lagrange multipliers for solution

$b \in \mathbb{R}$: threshold for solution

- Initialize $\alpha_i = 0, \forall i, \quad b = 0$.
- Initialize $passes = 0$.
- **while** ($passes < max_passes$)
 - $num_changed_alphas = 0$.
 - **for** $i = 1, \dots, m$,
 - Calculate $E_i = f(x^{(i)}) - y^{(i)}$ using (2).
 - **if** ($(y^{(i)} E_i < -tol \ \&\& \ \alpha_i < C) \ || \ (y^{(i)} E_i > tol \ \&\& \ \alpha_i > 0)$)
 - Select $j \neq i$ randomly.
 - Calculate $E_j = f(x^{(j)}) - y^{(j)}$ using (2).
 - Save old α 's: $\alpha_i^{(old)} = \alpha_i, \alpha_j^{(old)} = \alpha_j$.
 - Compute L and H by (10) or (11).
 - **if** ($L == H$)
 - **continue** to next i .
 - Compute η by (14).
 - **if** ($\eta \geq 0$)
 - **continue** to next i .
 - Compute and clip new value for α_j using (12) and (15).
 - **if** ($|\alpha_j - \alpha_j^{(old)}| < 10^{-5}$)
 - **continue** to next i .
 - Determine value for α_i using (16).
 - Compute b_1 and b_2 using (17) and (18) respectively.
 - Compute b by (19).
 - $num_changed_alphas := num_changed_alphas + 1$.
 - **end if**
 - **end for**
 - **if** ($num_changed_alphas == 0$)
 - $passes := passes + 1$
 - **else**
 - $passes := 0$
 - **end while**