

# 1 Forward process

Adding Noise in T steps using:

$$q(\mathbf{x}_t|\mathbf{x}_{t-1}) = \mathcal{N}(\mathbf{x}_t; \sqrt{1 - \beta_t}\mathbf{x}_{t-1}, \beta_t)$$

How can we sample  $\mathbf{x}_t$  in one step? We use the following definitions and identities:

$$\alpha_t = 1 - \beta_t, \quad \bar{\alpha}_t = \prod_{s=0}^t \alpha_s$$

$$\mathcal{N}(x; \mu_1, \sigma_1^2) * \mathcal{N}(x; \mu_2, \sigma_2^2) = \mathcal{N}(x; \mu_1 + \mu_2, \sigma_1^2 + \sigma_2^2)$$

In the following  $\epsilon$  is a random number taken from a standard normal distribution:

$$q(\mathbf{x}_t|\mathbf{x}_{t-1}) = \mathcal{N}(\mathbf{x}_t; \sqrt{1 - \beta_t}\mathbf{x}_{t-1}, \beta_t)$$

$$\Rightarrow \mathbf{x}_t = \sqrt{1 - \beta_t}\mathbf{x}_{t-1} + \sqrt{\beta_t}\epsilon_t$$

Performing one recursive step yields:

$$\begin{aligned} \mathbf{x}_t &= \sqrt{\alpha_t}\sqrt{\alpha_{t-1}}\mathbf{x}_{t-2} + \sqrt{\alpha_t\beta_{t-1}}\epsilon_{t-1} + \sqrt{\beta_t}\epsilon_t \\ &= \sqrt{\alpha_t\alpha_{t-1}}\mathbf{x}_{t-2} + \sqrt{\alpha_t\beta_{t-1} + \beta_t}\epsilon \\ &= \sqrt{\alpha_t\alpha_{t-1}}\mathbf{x}_{t-2} + \sqrt{1 - \alpha_t\alpha_{t-1}}\epsilon \end{aligned}$$

After  $t$  steps we get:

$$\mathbf{x}_t = \sqrt{\bar{\alpha}_t}\mathbf{x}_0 + \sqrt{1 - \bar{\alpha}_t}\epsilon$$

This means that  $\mathbf{x}_t$  is also normally distributed:

$$\mathbf{x}_t \sim q(\mathbf{x}_t|\mathbf{x}_0) = \mathcal{N}(\mathbf{x}_t; \sqrt{\bar{\alpha}_t}\mathbf{x}_0, 1 - \bar{\alpha}_t)$$

We can precompute  $\bar{\alpha}_t \Rightarrow$  we can compute  $\mathbf{x}_t$  directly from  $\mathbf{x}_0$

# 2 Reverse process

For the reverse process we need to find  $q(\mathbf{x}_{t-1}|\mathbf{x}_t, \mathbf{x}_0)$ . Bayes' theorem gives us:

$$q(\mathbf{x}_{t-1}|\mathbf{x}_t, \mathbf{x}_0)q(\mathbf{x}_t|\mathbf{x}_0) = q(\mathbf{x}_t|\mathbf{x}_{t-1}, \mathbf{x}_0)q(\mathbf{x}_{t-1}|\mathbf{x}_0)$$

The markov property of the forward process means:

$$q(\mathbf{x}_t|\mathbf{x}_{t-1}, \mathbf{x}_0) = q(\mathbf{x}_t|\mathbf{x}_{t-1})$$

Since  $q(\mathbf{x}_t|\mathbf{x}_0)$  is independent of  $\mathbf{x}_{t-1}$  we can write:

$$q(\mathbf{x}_{t-1}|\mathbf{x}_t, \mathbf{x}_0) \propto q(\mathbf{x}_t|\mathbf{x}_{t-1})q(\mathbf{x}_{t-1}|\mathbf{x}_0)$$

We know the second term from the forward process. We can rewrite  $q(\mathbf{x}_t|\mathbf{x}_{t-1})$  in terms of  $\mathbf{x}_{t-1}$  as follows:

$$\begin{aligned} q(\mathbf{x}_t|\mathbf{x}_{t-1}) &\propto \exp\left(-\frac{1}{2\beta_t}(\mathbf{x}_t - \sqrt{\alpha_t}\mathbf{x}_{t-1})^2\right) \\ &= \exp\left(-\frac{1}{2\beta_t}(\mathbf{x}_t - \sqrt{\alpha_t}\mathbf{x}_{t-1})^2\right) \\ &\propto \exp\left(-\frac{\alpha_t}{2\beta_t}\left(\mathbf{x}_{t-1} - \frac{\mathbf{x}_t}{\sqrt{\alpha_t}}\right)^2\right) \end{aligned}$$

With this we can now write down an expression for the needed conditional distribution:

$$q(\mathbf{x}_{t-1}|\mathbf{x}_t, \mathbf{x}_0) \propto \mathcal{N}\left(\mathbf{x}_{t-1}; \frac{\mathbf{x}_t}{\sqrt{\alpha_t}}, \frac{\beta_t}{\alpha_t}\right) \mathcal{N}(\mathbf{x}_{t-1}; \sqrt{\bar{\alpha}_{t-1}}\mathbf{x}_0, 1 - \bar{\alpha}_{t-1})$$

When multiplying two gaussian the result is also proportional to a gaussian. The following rules apply for the variance and mean:

$$\frac{1}{\sigma^2} = \frac{1}{\sigma_1^2} + \frac{1}{\sigma_2^2} \quad , \quad \frac{\mu}{\sigma^2} = \frac{\mu_1}{\sigma_1^2} + \frac{\mu_2}{\sigma_2^2}$$

Using this we finally get an analytic tractable form:

$$q(\mathbf{x}_{t-1}|\mathbf{x}_t, \mathbf{x}_0) \propto \mathcal{N}\left(\mathbf{x}_{t-1}; \tilde{\boldsymbol{\mu}}_t(\mathbf{x}_t, \mathbf{x}_0), \tilde{\beta}_t\right)$$

With the following variance and mean:

$$\tilde{\beta}_t = \frac{\beta_t(1 - \bar{\alpha}_{t-1})}{1 - \bar{\alpha}_t}$$

$$\tilde{\mu}_t(\mathbf{x}_t, \mathbf{x}_0) = \frac{\sqrt{\bar{\alpha}_{t-1}}\beta_t}{1 - \bar{\alpha}_t}\mathbf{x}_0 + \frac{\sqrt{\alpha_t}(1 - \bar{\alpha}_{t-1})}{1 - \bar{\alpha}_t}\mathbf{x}_t$$

Now we express the mean in terms of  $\mathbf{x}_0$  only, by using the following identity:

$$\mathbf{x}_t = \sqrt{\bar{\alpha}_t}\mathbf{x}_0 + \sqrt{1 - \bar{\alpha}_t}\boldsymbol{\varepsilon} \implies \mathbf{x}_0 = \frac{1}{\sqrt{\bar{\alpha}_t}}(\mathbf{x}_t - \sqrt{1 - \bar{\alpha}_t}\boldsymbol{\varepsilon}(\mathbf{x}_t, t))$$

This results in the following simplified formula for the mean:

$$\tilde{\mu}_t(\mathbf{x}_t) = \frac{1}{\sqrt{\bar{\alpha}_t}}\left(\mathbf{x}_t - \frac{\beta_t}{\sqrt{1 - \bar{\alpha}_t}}\boldsymbol{\varepsilon}(\mathbf{x}_t, t)\right)$$

Here the  $\boldsymbol{\varepsilon}(\mathbf{x}_t, t)$  is not just a random number from a standard normal distribution, it now depends on  $\mathbf{x}_t$  and  $t$ . This makes it the perfect quantity to be predicted by our model. We will call our model prediction  $\boldsymbol{\varepsilon}_\theta(\mathbf{x}_t, t)$ .

### 3 Algorithm

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#### Training

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- 1: repeat
  - 2:  $\mathbf{x}_0 \sim q(\mathbf{x}_0)$
  - 3:  $t \sim \text{Uniform}(\{1, \dots, T\})$
  - 4:  $\boldsymbol{\varepsilon} \sim \mathcal{N}(0, 1)$
  - 5: Take gradient descent step on  
 $\nabla_\theta \|\boldsymbol{\varepsilon} - \boldsymbol{\varepsilon}_\theta(\sqrt{\bar{\alpha}_t}\mathbf{x}_0 + \sqrt{1 - \bar{\alpha}_t}\boldsymbol{\varepsilon}, t)\|^2$
  - 6: until converged
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#### Sampling

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- 1:  $\mathbf{x}_T \sim \mathcal{N}(0, 1)$
  - 2: **for**  $t = T, \dots, 1$  **do**
  - 3:    $\mathbf{z} \sim \mathcal{N}(0, 1)$  if  $t > 1$ , else  $\mathbf{z} = 0$
  - 4:    $\mathbf{x}_{t-1} = \frac{1}{\sqrt{\alpha_t}}\left(\mathbf{x}_t - \frac{1 - \alpha_t}{\sqrt{1 - \bar{\alpha}_t}}\boldsymbol{\varepsilon}_\theta(\mathbf{x}_t, t)\right) + \sigma_t\mathbf{z}$
  - 5: **end for**
  - 6: return  $\mathbf{x}_0$
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