



# The Bellman-Ford Algorithm

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## Internet Routing

Algorithms: Design  
and Analysis, Part II

# From Bellman-Ford to Internet Routing

Note: the Bellman-Ford algorithm is intuitively "distributed".

Toward a routing protocol:

- ① switch from source-driven to destination-driven  
[just reverse all directions in the Bellman-Ford algorithm]
    - every vertex  $v$  stores shortest-path distance from  $v$  to destination  $t$  and the first hop of a shortest path  
[for all relevant destinations  $t$ ]
- ("distance vector protocols")

# Handling Asynchrony

② Can't assume all  $A[i, v]$ 's get computed before all  $A[i-1, v]$ 's

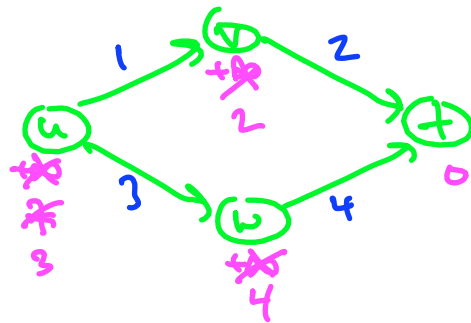
Fix: Switch from "pull-based" to "push-based": as soon as  $A[i, v] < A[i-1, v]$ ,  $v$  notifies all of its neighbors.

fact: algorithm guaranteed to converge eventually.  
(assuming no negative cycles)

[reason: updates strictly decrease sum of shortest-path estimates]

⇒ RIP, RIP2 Internet routing protocols  
very close to this algorithm (see RFC 1058)

Example



# Handling Failures

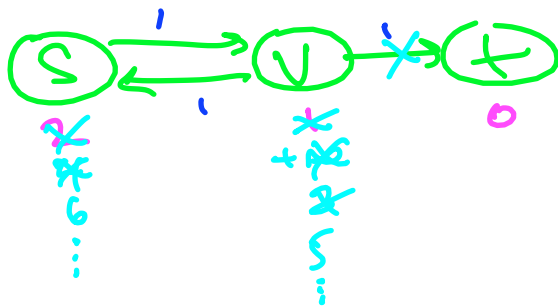
Problem: convergence guaranteed only for static networks (not true in practice).

Counting to Infinity:

Fix: each  $v$  maintains entire shortest path to  $t$ , not just the next hop.

Con: more space required.

Prot#1: more robust to failures.



"path vector protocol"

"Border Gateway Protocol (BGP)"

Prot#2: permits more sophisticated route selection (e.g., if you care about intermediate stops).