

Assessing Walkability Through Parking Prices*

Mauricio Arango[†]

Abstract

This paper uses data on prices and locations of garages, along with characteristics of all census tracts in New York City and Chicago, to build an objective market-driven measure of walkability for the two cities. The concept is as follows: as drivers wish to park close to their destination the cost of walking is embedded in parking prices. The paper lays out and estimates a theoretical model of price competition between garage operators that explains the dynamic between parking prices and the cost of walking, this produces a framework to measure walkability that can be extended to other cities. The Walkability Index presented in this paper combines several elements considered to affect walkability by the urban planning literature. This index shows a strong correlation with the proportion of non-car commuters.

JEL Classification: O18, R12, R32, and R41

Keywords: pedestrian-friendly, walkable, location characteristics, amenities, garages, parking, price competition, spatial panel estimation.

Preliminary and incomplete. Do not cite or distribute without permission of the author.

1 Introduction

The last decade has seen a strong push towards pedestrian-friendly cities.

*I received comments from Lewis Lehe, and Anna Piil Damm. Enlightening conversation with David Albouy, Daniel McMillen, and Minchul Shin were great sources of guidance in the writing of this paper. I will also like to thank conference participants of ITEA 2019, UEA 2019, NARSC 2020, and AREUEA-ASSA 2021 poster session for their feedback

[†]University of Illinois Urbana-Champaign. email: arangoi2@illinois.edu

From Barcelona’s Superblocks to Oslo’s downtown car restrictions, many cities around the world are shaping their downtown areas into more walkable places. The trend towards walkability is fueled by concerns for the environment, congestion, and public health, along with a desire for vibrant downtowns that stimulate the local economies. Existing literature has linked walkability with positive outcomes in health (Doyle et al. (2007)), pollution (Frank et al. (2005a)), street safety (McDonald et al. (2014); DiMaggio and Li (2013)), property values (Pivo and Fisher (2011); Boyle et al. (2014)), crime (Gilderbloom et al. (2015)) and social fabric (Leyden (2003)) among other benefits. The existing evidence seems to be compelling enough to produce waves among some urban planners and city authorities that advocate increasingly for pedestrian-friendly cities, as described in Speck (2012).

Investments and policies aimed to build walkable streetscapes raise the question of how to measure walkability. Existing measures of walkability are based on the literature’s consensus on the characteristics of a pedestrian-friendly area; for instance, The Walk Score® uses proximity to different amenities to measure walkability—locations with a wide range of amenities within a walkable distance of 2 miles or less have a high score. The National Walkability Index from the Environmental Protection Agency (EPA) combines street intersection density, mix of block employment type (such as residential, office, industrial), and percentage of occupied housing, among other characteristics, to assess the degree of walkability of a given area. The way variables are selected and weighted in the Walk Score®, the National Walkability Index, and other measures of walkability is based on the author’s educated opinion. As such, the measures are subjective.

This paper produces an objective Walkability Index (WI), where variables are selected and weighted based on their relation with an indirect valuation of the cost of walking. As in other measures of walkability, the WI bundles different locations’ characteristics associated with pedestrian-friendly zones into one measure. However, unlike existing measures, the variable selection and weighting process depends on a market valuation, making the WI a market-driven index. To my knowledge, this is the first index of walkability that is based on an indirect valuation of people’s willingness to walk obtained through market prices. One common approach is using physical activity as a proxy of willingness-to-walk. However, physical activity can be induced by health and well-being concerns. This approach helps to isolate the effect of the urban environment from this type of causalities that can bias measures based on physical

activity.

The assessment of the cost of walking used in this paper is based on an economic model of spatial competition between garage operators. The theoretical model shows how the cost of walking is embedded in parking prices. The concept is straightforward: imagine you are planning your next trip to an appointment and you are choosing where to park on an online prepaid parking platform.¹ Several options appear on your computer or smartphone. Common sense dictates that you are likely to pick your parking spot based on the price and proximity to your destination. Drivers will be willing to pay more for spots closer to their destination and less for those further away. In this sense, the difference in prices is partially affected by the willingness-to-walk. The reasons for using parking services to identify the effect of walking on prices is three fold: 1) parking is differentiated by location, 2) parking is mostly homogeneous on features other than location, and 3) people walk after they park. Price data from online platforms, as used in this paper, offer one extra advantage over prices offered on site;² online customers avoid the cost of searching and cruising that is inherent to more traditional ways of parking, thus providing a cleaner relation between parking prices and the willingness-to-walk.

Using a novel spatial panel data set of parking services sold online, this paper provides estimates of the WI for New York City and Chicago. The proposed WI has a correlation above 60% with the proportion of commuters that do not use their personal car for commuting.³ This manuscript also provides some insight on the pricing behavior of garage operators. By the estimates of this paper, a one dollar increase in prices by neighboring competitors produces an average hike in prices of five to ten cents. Also, as predicted by the theoretical model, the effect of neighboring competitors on prices fades in less pedestrian-friendly locations. The paper uses data from Chicago’s downtown area to show the connection between walkability and this pricing behavior.

Due to data limitations, projections of the index are provided only for New York City and Chicago. However, the methodology described in the paper can be applied to cities outside of the original sample, as there are no city-specific effects. After this introduction, the rest of the paper goes as follows: section two reviews previous works on walkability and the parking literature related to this work, section three describes the theoretical model, section four gives an

¹Examples of this are spothero.com and parkwhiz.com.

²Prices on site are those offer to customer at the garage’s physical address.

³This result only uses data for New York City.

example of the behavior predicted by the model in Chicago, section five discusses how the econometric model adapts the data to the theoretical model, section six describes the data set, section seven explains and shows the numerical results, section eight explores the validity of the WI by comparing projections of the WI to variables related to pedestrian-friendly locations and other measures of walkability, and section nine discusses the paper’s limitations along with some final remarks.

2 Previous Literature

Much of the work on the effects of the urban environment on walking has roots in the occupational and public health literature. This inheritance has produced an emphasis on physical activity. For example, Frank et al. (2005b) advance a walkability index that depends on the mix of land use, residential density, and intersection density. The authors use the correlation between physical activity and the urban form to weight each variable in the total index.⁴ This approach is based on the notion that dense areas with a mixed use are more appealing to pedestrians than single-use low density areas. Similarly, Porta and Renne (2005) focus on the access to side walks. Their measure depends on the fraction of the total area that is accessible through safe sidewalks. Kuzmyak et al. (2007) provide a measure of walkability that accounts for the access to amenities (walk opportunities) and the intersection density at a given location.⁵ The weight assigned to each walking opportunity depends on a rank of attractions given by a local survey. Meanwhile, intersections are weighted in a manner such that the weight of four-way intersection, is twice that of three-way. Four-way intersection with a main road received the same weight of a three-way intersection.

Another common approach is using access to amenities to measure walkability. Under this concept, a place is deemed walkable if common errands (opportunities) can be easily completed by walking. An example is the Walkscore®.⁶ The Walkscore® uses the distance to 13 different types of amenities (grocery stores, restaurants, coffee shops, bars, movie theaters, schools, parks, libraries, bookstores, gyms, drug stores, hardware stores, and clothing and music stores)

⁴Using physical activity as the target, the authors tested different sets of parameters and chose the one with the highest explanatory power.

⁵Intersection density is usually deemed a positive factor, as it enables shorter trips through possible shortcuts.

⁶walkscore.com

to provide a pedestrian accessibility index. The closer a location is to one of the 13 amenities, the higher the Walkscore®. All the categories are then integrated in one final score that ranks from zero to one hundred, where one hundred is the highest degree of walkability.⁷ The Walkscore® is a well-known measure that has been used in works such as Gilderbloom et al. (2015) and Boyle et al. (2014) to measure the impact of walkability on housing prices.

Manaugh and El-Geneidy (2011) examine the impact of the four walkability indexes described above (Frank et al. (2005b), Porta and Renne (2005), Kuzmyak et al. (2007), and Walkscore®) on the travel behavior of people in Montréal, Canada.⁸ They find that all measures have a significant impact on the probability of walking trips regardless of their nature (school or shopping). This type of finding provides support to a multi-dimensional approach, where walkability depends on the access to infrastructure (e.g. intersection density or access to sidewalks), characteristics of the urban environment (e.g. mix between commercial and residential use), and proximity to different amenities. However, the question of what variables should be included in the calculation of a walkability index, and how they should be weighted remains unaddressed.

Models of spatial competition, such as Hotelling (1929) and Salop (1979), show the effect of transportation cost on vendors pricing strategies. In summary, in a symmetric equilibrium, higher transportation cost leads to higher prices. Also, in an asymmetric framework, higher transportation cost can lead to higher differences in prices between locations. Froeb et al. (2003) and Arnott (2006) use this type of spatial competition framework to analyze the behavior of parking garage operators. In their models, the demand for parking spaces at a given location depends on the cost of walking from the garage to the driver's destination, among other factors. This cost of walking is the transportation cost in spatial competition models. Empirical analysis of the off-street parking industry (Froeb et al. (2003), Choné and Linnemer (2012), Kobus et al. (2013), and Lin and Wang (2012)) incorporate the cost of walking as a factor that enables monopolistic competition.⁹ In general, the parking literature assumes the cost of walking is the opportunity cost of time (see Arnott and Rowse (1999), Arnott and Inci (2006), Arnott and Rowse (2009), and Anderson and de Palma (2004) among others). This paper goes beyond this approach and assumes that the

⁷ A place with a Walkscore® between 90 to 100 is labeled as a "Walker's Paradise", and 0 to 24 is a "Car Dependent" location.

⁸The authors use the 2003 Montréal Origin-Destination survey.

⁹See Inci (2015).

urban environment affects people’s willingness to walk and hence their parking decisions: e.g. drivers can be deterred from using a garage surrounded by major highways or over passes, even if it is close to their destination, since the cost of walking is increased by the location’s unwelcoming surroundings. Inserting this relation between the urban environment and the cost of walking in a price competition model of garage operators, produces the theoretical framework used in this paper as the blueprint of a market-driven measure of walkability.

3 The Flat City Model

Concentrations of pedestrians in promenades and downtown areas suggest that people are more likely to walk in places with certain characteristics. The model is built on the premise that willingness to walk changes across locations, affecting price competition among garage operators. The measure of walkability provided in this paper uses a spatial competition model of garages, where parking prices are a function of competitors’ prices, the unit cost, and the cost of walking between competitors. To illustrate this relations, this paper uses a modified version of the model in Arnott (2006), where the cost of walking not only depends on the characteristics of the individual, but also on the location’s attributes.

3.1 The Demand for Parking

The model considers a flat city (i.e. with the same cost of moving in any direction) divided in small tracts, each formed by a few blocks laid in a uniform street grid. Each section is described by a vector of attributes Θ . Garages are placed in fixed locations that are at equal distance from each other, their sole business is renting parking spots by the hour. Two types of clients rent those parking spots, discount customers and loyal customers. Loyal customers are drivers with strong preferences for one location; an example of this is every day commuters and customers with a high opportunity cost of time. There are many reasons why drivers prefer one garage above all, for instance, the garage can be located in the same building as their work place or offer amenities valued by customers (e.g. valet parking, elevators, or outlets for electric vehicles). On the other hand, discount customers are drivers that shop around looking for lower prices. They regard parking as a homogeneous service only differentiated by price and location, hence they base their decision of parking on the cost per unit of time r and the cost of walking back and forth to their destination. For

the average discount driver, the cost of walking one unit of distance depends on the average cost of time, v , and the location's characteristics ($w(v, \Theta)$). Then, if the average discount driver parks for T hours at a garage that is at distance x from their destination, the full price of parking is $rT + 2xw(v, \Theta)$.

3.1.1 Market Area

Discount drivers choose the garage with the lowest full price. The full price depends on the distance between garage and destination. Every parking lot is surrounded by a set of destinations for which, the parkinglot provides the lowest full price. These destination are within the garage's market area (M), as named by Arnott (2006). A destination is located at the border of the market area if the full price of two garages is equal, this is:

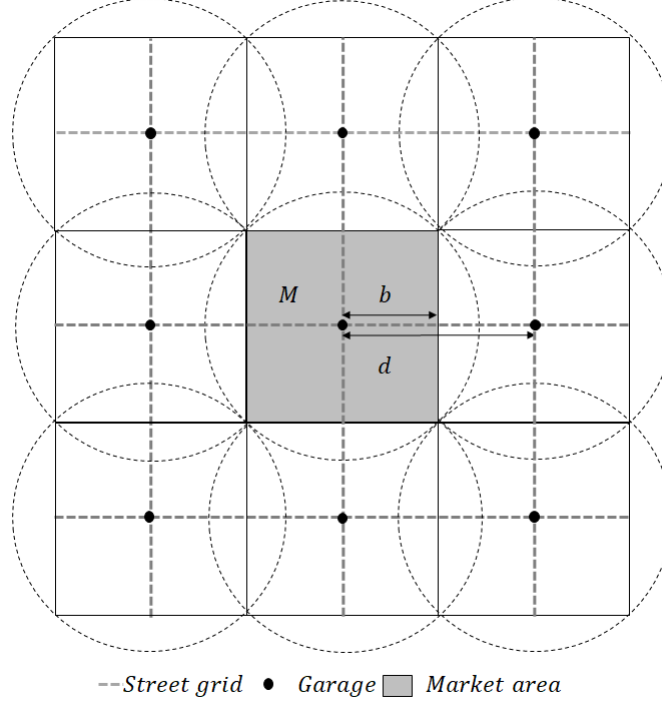
$$rT + 2bw = \bar{r}T + 2(d - b)w, \quad (1)$$

where d is the distance between garages, b is the distance from the garages to the edge of the market area, and \bar{r} is the rate per unit of time charged by the neighboring garage (see Figure 1).

The uniform street grid makes taxi-cab distance the relevant metric between two locations; this generates square-shaped market areas, as shown in Figure (1). Using the shape of the market area and equation (1), it follows that the market area is:

$$M = 4 \left(\frac{(\bar{r} - r)T}{4w} + \frac{d}{2} \right)^2.$$

Figure 1: Street Diagram



3.2 Garage Operators

Loyal drivers pay a price that is above the cost of providing a parking spot. For the sake of simplicity, assume that garage operators can always rent a spot to a loyal customer, hence the price paid by those customers (c) constitutes the opportunity cost of renting a spot to a discount driver.¹⁰ Discount drivers visit a wide range of businesses and amenities (coffee shops, doctors' offices, and parks, among many others), making the demand for parking spots per unit of area (D) uniformly distributed within each tract. The representative garage operator takes the demand for parking and the competitor's price as exogenous, so price at time t is such that:¹¹

¹⁰Loyal driver can have monthly contracts that charge low fix rates by hour. e.g. a \$2000 monthly fee is less than a \$3 per hour rate.

¹¹In a high frequency framework, hour by hour, price by unit of time (r) and parking spot demand by unit of area (D) are the only variables that change.

$$\begin{aligned}
& \max_{r_t} \Pi = r_t M D_t T - c M D_t T \\
& \text{subject to:} \\
& M = 4 \left(\frac{(\bar{r}_t - r_t) T}{4w(v, \Theta)} + \frac{d}{2} \right)^2.
\end{aligned} \tag{2}$$

Solving the garage operator optimization problem yields the best response function:

$$r_t = \frac{2}{3} \left(c + \frac{dw(v, \Theta)}{T} \right) + \frac{1}{3} \bar{r}_t. \tag{3}$$

Equation (3) shows how parking prices are a function of: one dynamic factor, competitor's price (\bar{r}_t), and two static factors: the opportunity cost (c) and the cost of walking $\frac{dw(v, \Theta)}{T}$. From the relation in (3), it follows that in pedestrian-friendly locations ($w(v, \Theta) \approx 0$) price competition will represent a bigger share of the total price. In a way, price competition among garages is more fierce in walkable locations because of the lower cost of switching garages.

4 Prices, Disconnected Markets, and Walkability

The situation described in section (3.1) can be summarized by saying that drivers park in garage i at time t , if and only if it offers the lowest full price:

$$\begin{aligned}
r_{i,t} T + 2bw(v, \Theta_i) &\leq \min(r_{j,t} T + 2(d-b)w(v, \Theta_j)) \\
&\forall i \neq j.
\end{aligned} \tag{4}$$

Equation (4) describes how drivers might avoid parking at one place because prices are too high or because it is costly to walk from the garage to their destination; this paper focuses on the latter. Let's think for instance of two neighboring locations called north side and south side. The two locations are divided by a barrier that makes moving between locations costly, e.g. a highway or overpass that makes walking unpleasant. The cost of crossing this barrier can be such that visitors of one location can't be lured by lower prices to cross to the other side. In this case the physical barrier creates a disconnect between prices in the two locations, i.e. a change in the price of a garage on one side only affects competitors on that same side, despite how close competitors are in

the neighboring location.

A situation like the one described above can be found in Chicago’s downtown, in the area surrounding Congress Parkway. Readers familiar with downtown Chicago will recognize that north of Congress Parkway is Chicago’s main business area. It has important buildings like the Willis Tower, the Board of Trade, and city hall, among others. South of the Congress Parkway is a less busy and more residential area. The average two-hour price for an off-street spot north of Congress Parkway is lower during weekends as the demand by week day commuters is reduced (Figure 2). Meanwhile, the weekend effect is not observed south of Congress Parkway (Figure 3). The result not only suggests that garages on the south side are less affected by changes during the weekend, but that there is little competition between garages on the north and south sides, even if they are close to each other. Figure (4) digs deeper into this issue by plotting the estimated weekend effects ($\beta_{j, WE}$) of the following model,

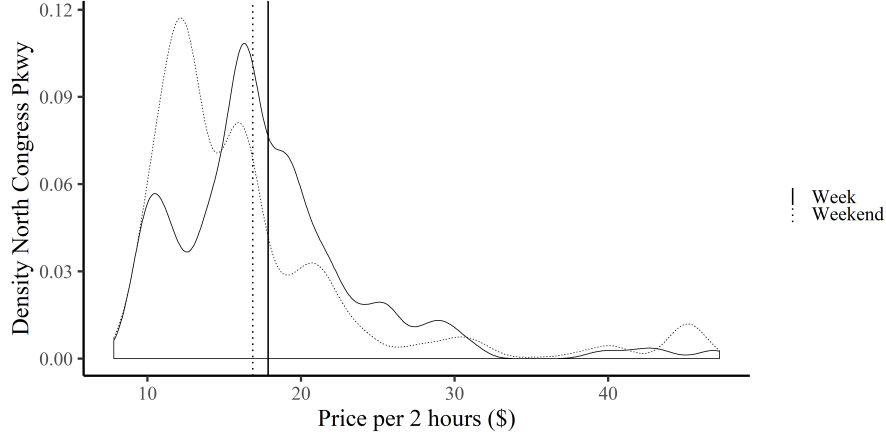
$$r_{j,t} = \beta_j + \beta_{j, WE} \mathbb{1}_{t, WE} + \sum_{h=3}^{18} \beta_h \mathbb{1}_{t, h} + \sum_{h=3}^{18} \beta_{h, WE} \mathbb{1}_{t, h} \mathbb{1}_{t, WE} + \epsilon_{j,t}, \quad (5)$$

where $\mathbb{1}_{t, h}$ is the indicator functions of the h hour of the day, and $\mathbb{1}_{t, WE}$ is an indicator function for the weekends. The X axis of Figure (4) is the distanced to the City Business District (CBD).¹² Chicago’s city hall is on the north side of Congress Parkway, so all garages on the north side are in the left hand side of Figure (4) and garages on the south side are in the right hand side. Garages on the south side have a uniform smaller response to the weekend than their competitors on the north side, suggesting a disconnect between both locations. In the lights of the model, this disconnect can be the consequence of two things: The discount offered by garages on the south side to attract drivers during weekdays is such that it leaves little to no room to reduce prices during the weekend; the second option is that garages south of Congress Parkway only engage in competition with each other. In both cases the effect of crossing and walking south of Congress Parkway is evident.

The higher dispersion of the weekend effect in the north side observed in Figure (4) can be attributed to the higher concentration of tall office buildings and locations with different amenities that offer their own parking services. The presence of this types of buildings and locations affect the opportunity cost of

¹²CBD is defined as the location of the city hall.

Figure 2: Street Diagram



garage operators, for example: a garage located in the basement of a tall office building has a higher than average opportunity cost during weekdays and a low opportunity cost during weekends, meanwhile a garage that serves a theater will have a higher opportunity cost during function days.

5 Estimation

5.1 Competitors and the W Matrix

Expression (3) is built under assumptions of symmetry and uniformity that make it easy to isolate the competitors that define the market area of each garage. Cities however are irregular, making symmetry and uniformity more a novelty than a rule. To finesse this difficulty I simulate an average competitor that defines the market area of each garage. The average competitor is built based on the price of surrounding parking lots, where the weight of each competitor is an inverse function of the distance between garages. The first step is to define a W matrix that weights the prices of each competitor within a radius of length d , by the inverse of the distance:

Figure 3: Street Diagram

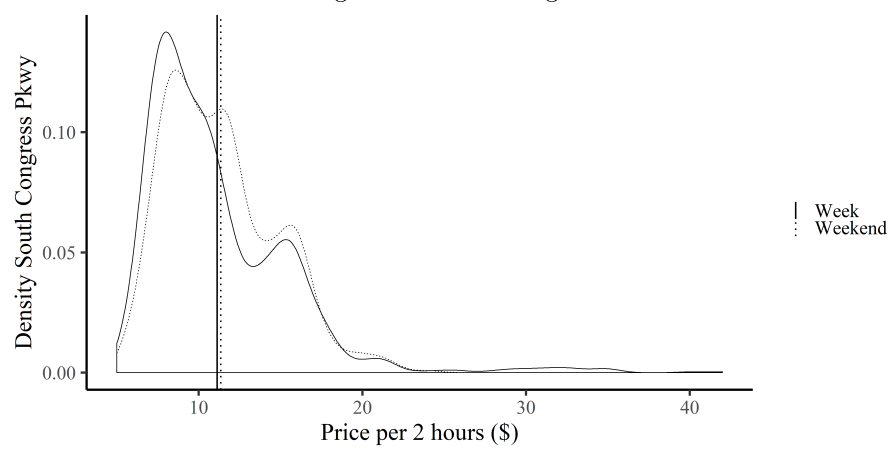
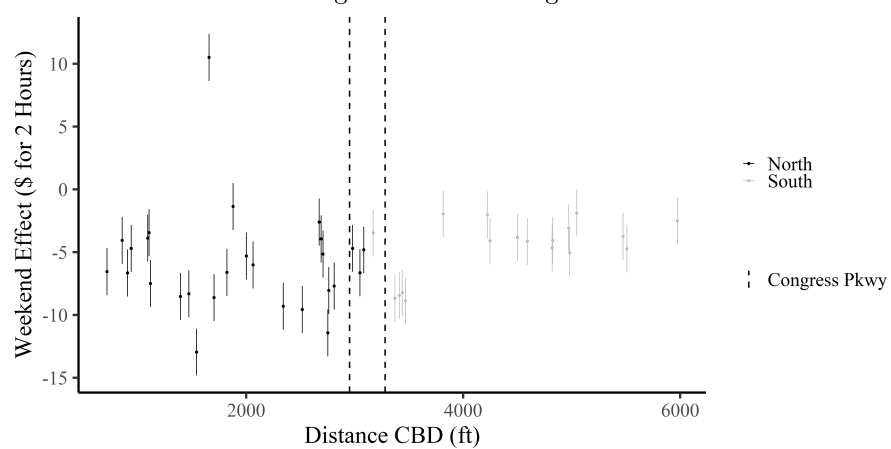


Figure 4: Street Diagram



$$W = \begin{bmatrix} 0 & W_{1,2} & \cdots & W_{1,n} \\ W_{2,1} & 0 & & \vdots \\ \vdots & & \ddots & W_{n-1,n} \\ W_{n,1} & \cdots & W_{n,n-1} & 0 \end{bmatrix}$$

$$W_{jk} = \begin{cases} W_{ij} = \frac{1}{d_{jk}} & \text{if } d_{ij} \leq d \\ W_{ij} = 0 & \text{if } d_{ij} > d \end{cases}.$$

Using the definition of W to represent expression (3) in a spatial panel framework, yields the following regression equation:

$$r_{it} = \alpha_i + \lambda W_i r_t + \varepsilon_{it}, \quad (6)$$

where α_i accounts for the unit cost plus the cost of walking for the average driver $\left(\alpha_i = \frac{2}{3}c_i + \frac{2d^n w_i(v, \Theta_i)}{3T}\right)$.

This approach uses a simulated a market area that can differ from the real one. Figure (5) illustrates two simple examples of this situation, where the gray polygon represents the real market area, and the stripes square the simulated market area used in equation (6). As the market area and simulated market can differ, it is reasonable to assume that the price signal of the average competitor in equation (6) has a smaller effect on r_{it} than that of the neighbor garage in (3). Hence the estimate of λ are expected to be equal or less than one third.

Table (1) shows the estimates of λ in equation (6) for different definitions of the threshold in the W matrix. Under the understanding that the price signal is fuzzy, the results are consistent with the model as the estimated λ remains between 0 and 1/3.

5.2 Cost of Walking

As described before the cost of walking one unit of distance depends on the opportunity cost of time, and the characteristics of a location $(w(v, \Theta))$. Assuming that a first order Taylor expansion around the origin provides a good approximation of w yields that:

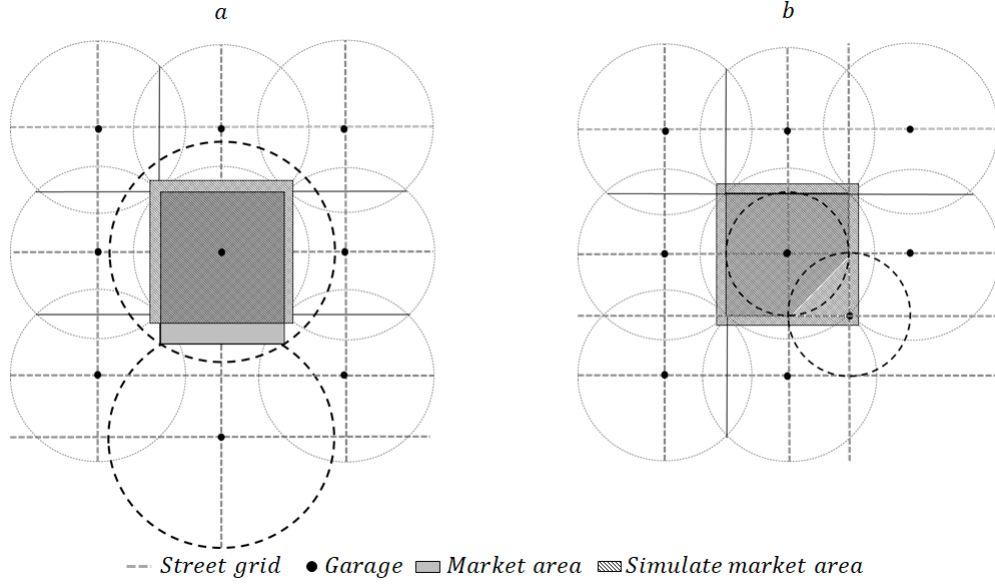
$$w_i = \frac{\partial w}{\partial v} v + \delta_{\Theta} \Theta_i + \varepsilon_{wi}, \quad (7)$$

where δ_{Θ} is a vector that contains the partial derivatives of w with respect

Table 1: Estimates best response function. Different definitions of the W matrix by distance thresholds.

	W distance thresholds (miles)			
	0.25 (1)	0.5 (2)	0.75 (3)	1 (4)
λ	0.05 (0.00)	0.05 (0.01)	0.11 (0.01)	0.09 (0.01)
P-val $\lambda \leq 1/3$	1.00	1.00	1.00	1.00
R^2	0.80	0.82	0.78	0.80

Figure 5: Street Diagram



to each variables in Θ , and $\varepsilon_{wi} \sim (0, \sigma_w)$ is the difference between the first order approximation and the cost of walking. From (3), (6), and (7) follows that:

$$\hat{\alpha}_i = a + \rho\Theta_i + \eta_i, \quad (8)$$

where $a = \frac{2}{3} \frac{d}{T} \frac{\partial w}{\partial v} v$, $\rho = \frac{2d}{3T} \delta_\Theta$, and $\eta_i = \frac{2}{3} c_i + \frac{2d}{3T} \varepsilon_{wi}$. Each element in ρ provides a relative measure of the impact of variables in Θ on the cost of walking. This means that, despite of not being clean cut estimate of δ_Θ , parameters in ρ can be use to weight the importance of each factor on the cost of walking relative to all other variables in Θ , as all parameters in ρ are multiplied by the same positive constant term $(\frac{2d^n}{3T})$.

5.3 Controlling for the Unit Cost

Equation shows how (3) the cost of renting to discount drivers is affected by the opportunity cost of long term contracts. Location characteristics are can be correlated with the price of long term contracts, hence Θ_i is potentially be correlated with η_i , making the OLS estimators of ρ in equation (8) likely to be biased. The logic is simple, elements that affect the cost of walking can affect the the cost of providing one parking spot.¹³ To alleviate this concern I a use a property value differential that accounts for changes in value driven by location characteristics. The differential is obtained regressing property prices per square foot (p) on property characteristics (X) and a census tracts indicator (μ),

$$p_i = X_i\beta_p + \mu_j + \varepsilon_{pi},$$

where for each property i in census tract j , X accounts for the number of bedrooms, and number of bathrooms, while μ_j is the census tract price differential.

Using $\hat{\alpha}$ as proxy of the cost of walking, I regress $\hat{\alpha}$ on the location characteristics (Θ) and $\hat{\mu}$ as a control for the location effects,

$$\hat{\alpha}_i = a + \hat{\mu}_j\beta_\alpha + \rho\Theta_i + \varepsilon_{\alpha i}. \quad (9)$$

Estimates of all parameter in equation (9) are presented in the appendix, table (2). A word of caution: despite controlling for property values, estimates

¹³For example: charming pedestrian-friendly locations can attract firms that pay high wages (e.g. financial institutions or law firms). With high incomes, employees of this firms can afford expensive long term parking contracts increasing the opportunity cost of renting to a discount driver.

of ρ can still be confounded by the effect of Θ_i on c_i . Given the data available to me at the moment I can't provide unbiased estimates of the effects of location characteristics on the cost of walking so under no circumstance estimate of equation (9) should be interpreted as measures of the impact of the urban environment on walkability.

6 Data

The model presented in section three describes a market where garage operators can easily change prices at no cost, and customers can compare prices at no cost, eliminating the need of cruising for parking. This two conditions are met by online parking platforms, where garages can change prices through the platform, and all the information about prices, location, and amenities, is free and accessible to all customers with an internet enabled device. On the other hand, the model is not a good fit for more traditional parking markets. Where operators publish their prices on billboards that are hard and costly to modify, and drivers cruise around the block trying to compare prices that, most of the time, are not visible from the street. A good example of this situation is shown in the Appendix in Figure (11). To estimate equation (6) I collected data on prices, location, and characteristics of 2331 parking lots listed on parkwiz.com. A website that rents off-street parking of different providers in all major cities in the US. Some descriptive statistics of the data are provided in the Appendix, Table (3).

Information on prices and availability was collected every hour during 2 months (from July 25th 2019 to August 25th 2020). The dates of the data collection process provide a sample with no major seasonal irregularities, like significant changes in the weather or big holidays. Since most locations were unavailable at some time during the period of data collection the original data set has several missing values. In order to obtain a balanced panel I used the average price for every hour of the week between 6:00 am and 11:00 pm. After dropping all locations with missing observations the data set is reduced to 903 locations with 119 observations per location.¹⁴

To weight the effect of infrastructure, mixed use, and the proximity to different amenities in the WI, I estimate of equation (9) using the following data:

¹⁴The 119 observations are the result of using 17 hours (6:00 am to 11:00 pm) for the 7 days of the week.

- Intersection density at census tracts level (2010 census) from the United States Environmental Protection Agency (EPA).
- Mix of land use, commercial and housing in every census tracts (2010 census) from the EPA.
- The proximity of each parking location to thirteenth different amenities¹⁵, data collected using the Google places API.

Finally, the paper uses data at census tract level on the proportion on non car commutes,¹⁶ the Walk Score[®],¹⁷ and the EPA's National Walkability Index to check the relation of the WI with these variables.

7 The Walkability Index

Two major assumptions are established to limit the distortions rising from the confounding factors in equation (9), specially those related to the effect of Θ_i on c_i :

- No disamenities: All variables included in vector Θ are amenities.
- Equal bias: If estimates of ρ are bias, the size of the bias is the same for all variables (all elements of ρ are over estimated or all elements of ρ are under estimated)

Under the no disamenities assumption, and in the lights of the theoretical model, a variable in Θ only has a negative effect on α ($\rho < 0$) if it reduces the cost of walking. Therefore negative elements of $\hat{\rho}$ are related to variables that reduce the cost of walking. On the other hand, variables in Θ that have a positive effect on α ($\rho > 0$) are likely affect by the effect of Θ on c .¹⁸ Under the equal

¹⁵Those amenities are: grocery stores, restaurants, coffee shops, bars, movie theaters, schools, parks, libraries, bookstores, fitness centers, drug stores, hardware stores , and clothing and music stores.

¹⁶from the Census Transportation Planning Products Service <https://ctpp.transportation.org/>.

¹⁷For more information visit www.walkscore.com/cities-and-neighborhoods/

¹⁸See 13.

sign bias assumption, estimates of $\hat{\rho}$ can be biased, but the relative weights they provide are consistent with the driver's valuation.

Based on these assumptions, the proposed WI has the following formula:

$$WI = |\hat{\rho}|\underline{\Theta},$$

where $\hat{\rho}$ and $\underline{\Theta}$ are vectors that contain the subset of parameters and variables that have a negative correlation with the proxy of the cost of walking ($\hat{\alpha}$). This selection process leads to the following set of variables ($\underline{\Theta}$) and weights ($|\hat{\rho}|$) that form the WI:

- Number of restaurants with a weight of 2.11
- Mix of land use (entropy) with a weight of 1.17¹⁹
- Number of clothing stores in one mile with a weight of 0.31
- Number of coffee shops in one mile with a weight of 0.20
- Number of libraries in one mile with a weight of 0.09
- Number of grocery stores in one mile with a weight of 0.06
- Number of book stores in one mile with a weight of 0.03
- Number of bars in one mile with a weight of 0.02

Values of $\hat{\rho}$ are used in absolute values for the sake of interpretation.

The measure of walkability provided here is intended to compare location. It should be read as an ordinal number, indicating that on location is more or less walkable than other but not by how much.²⁰

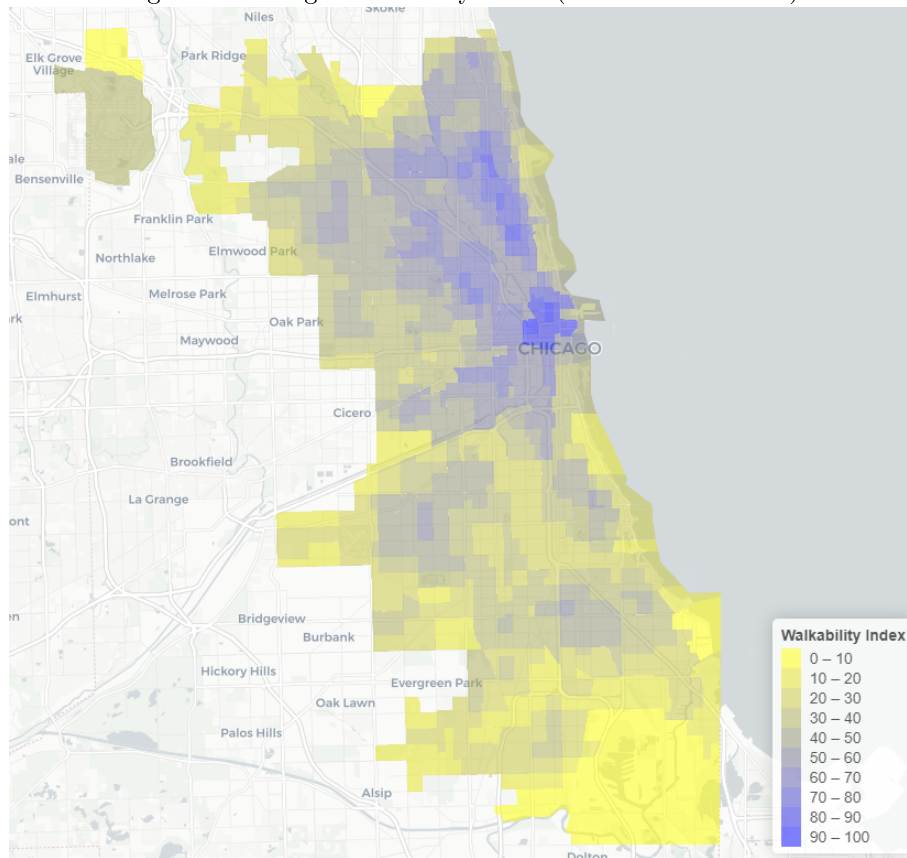
Figures (6) and (7) presents projection of the WI for Chicago and New York City. The indicator shows that the most walkable areas are the loop in Chicago, and Midtown Manhattan and Brooklyn in New York. In both cases the city

¹⁹Measure of entropy calculated by the EPA using eight different categories. for more information see variable D2b_E8Mix at <https://www.epa.gov/smartgrowth/smart-location-mapping>

²⁰For example if location A has a WI of 60 and location B a WI of 66, the WI indicates that location B is more walkable than A, but not that location B is 10% more walkable than A

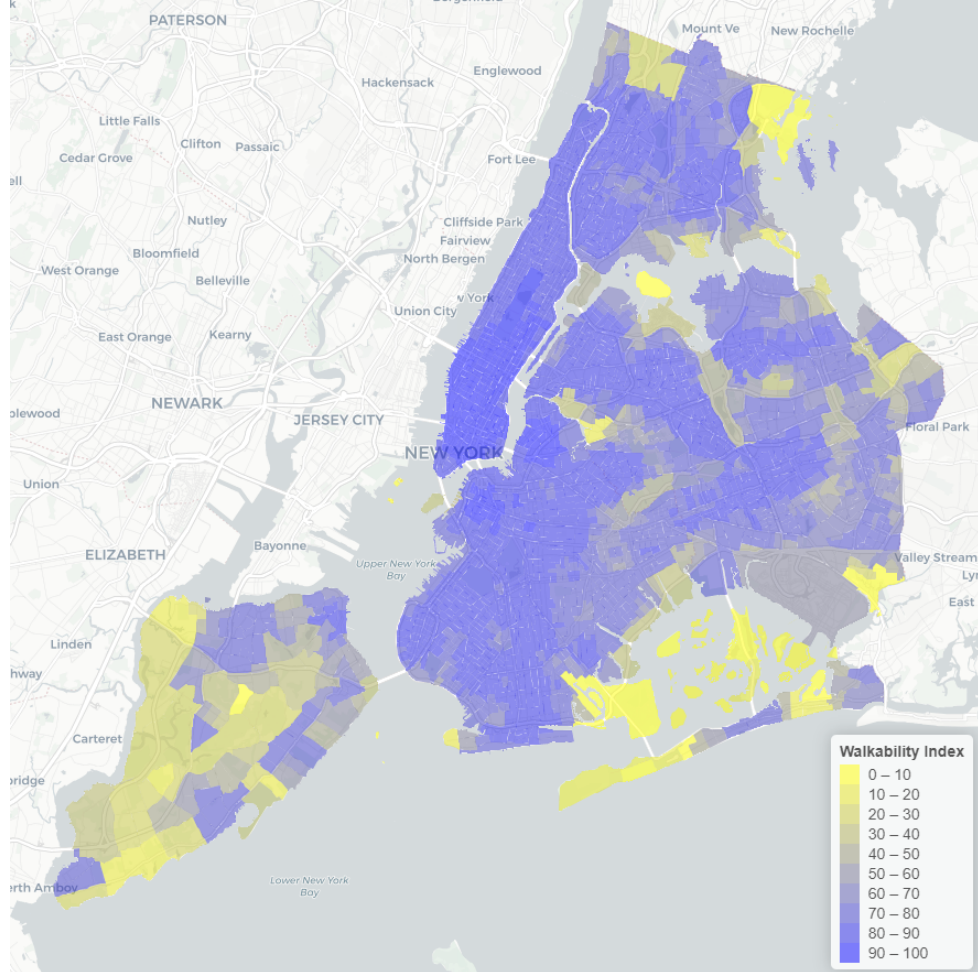
tends to become less walkable as one moves away from this areas, with some exceptions.

Figure 6: Chicago Walkability Index (2010 Census Tracts).



A more detailed version of this map can be found in <https://www.mauricio-arango.com/walkability-index-chi>

Figure 7: New York City Walkability Index (2010 Census Tracts).



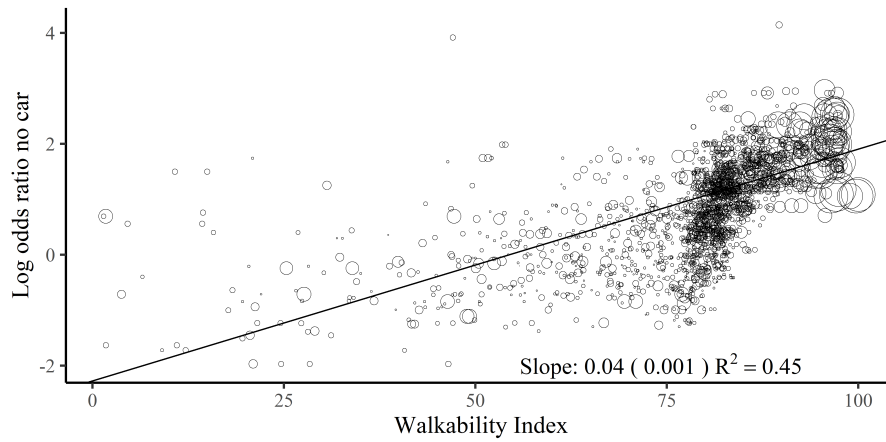
A more detailed versions of this map can be found in
<https://www.mauricio-arango.com/walkability-index-nyc>

8 Validating the Walkability Index

Figure (8) shows the relation between the WI and the log odds ratio of a no car commute for all census tracts in New York City. The figure shows a positive correlation, above 0.65, between the fraction of people that commute to one tract by means other than car and the value of the WI. The regression

and figure are weighted by the number of workers in each census tract. Figure (9) compares the WI with the Walk Score \textcircled{R} . The relation is also positive and strong with a correlation coefficient of 0.82. Figure (10), shows a weak relation between the WI and the EPA's National Walkability Index.

Figure 8: Walkability Index and Percentage of No-Car Commuters by Census Tract in New York City



The size of the marker is proportional to the number of workers in each census tract. The regression is weighted by the number of workers in each census tract.

Figure 9: Walkability Index and The Walk Score \textcircled{R}

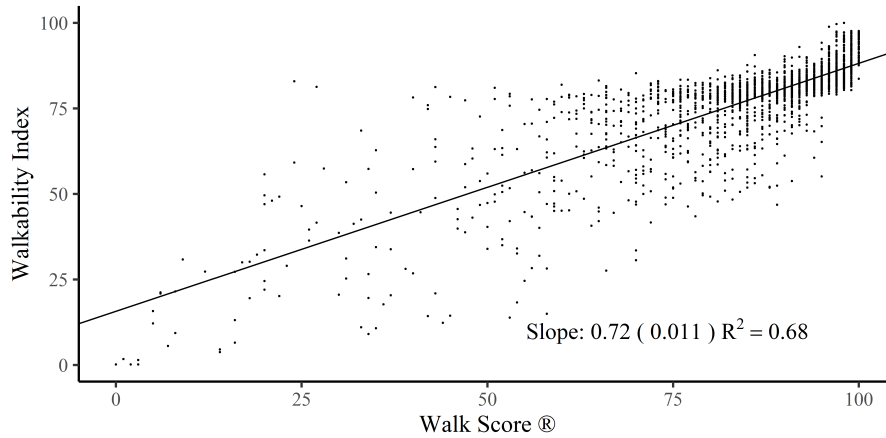
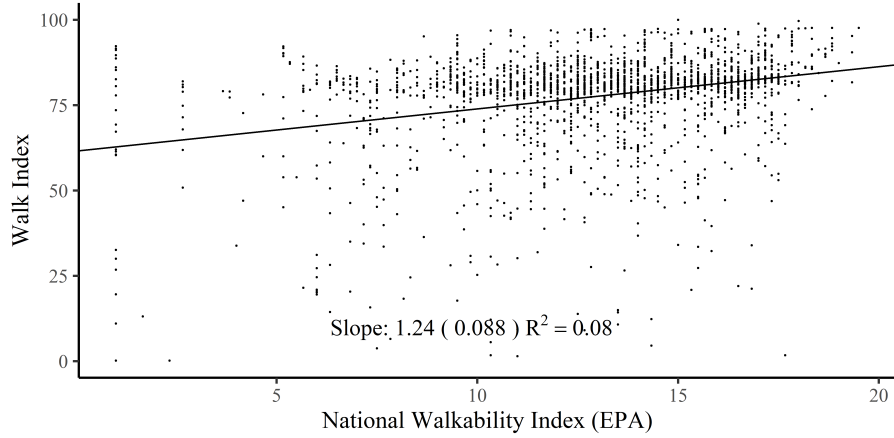


Figure 10: Walkability Index and The National Walkability Index



9 Final Remarks

This paper use estimates of a spatial competition model of garage operators, to measure the cost of walking. Estimates of the cost of walking are used to parameterize a market-driven Walkability Index that depends on the characteristics of each location. The resulting index summarizes some of the existing theories and measures of walkability. The used methodology can be applied in cities outside of the original sample. This methodology also provides an objective way to include new characteristics in future measures. A simple validation exercise shows that the Walkability Index build in this paper has a strong positive correlation with the fraction of non car commuters in New York City.

The parameterization of the Walkability Index is built around the concept of willingness to walk. However, such a variable is unobservable. What this paper provides is a mere approximation using parking prices. This, along with the bias that might arise from possible omitted variables, limits the interpretation of the results presented in this manuscript. It is not the intention of this paper to prove causality nor to provide unbiased estimators. The results presented in this paper should be understood as a way to rank different characteristics of the urban environment based on their relation with driver's willingness to walk.

References

- Anderson, S. P. and de Palma, A. (2004). The economics of pricing parking. *Journal of Urban Economics*, 55(1):1–20.
- Arnott, R. (2006). Spatial competition between parking garages and downtown parking policy. *Transport Policy*, 13(6):458–469.
- Arnott, R. and Inci, E. (2006). An integrated model of downtown parking and traffic congestion. *Journal of Urban Economics*, 60(3):418–442.
- Arnott, R. and Rowse, J. (1999). Modeling Parking. *Journal of Urban Economics*, 45(1):97–124.
- Arnott, R. and Rowse, J. (2009). Downtown parking in auto city. *Regional Science and Urban Economics*, 39(1):1–14.
- Boyle, A., Barrilleaux, C., and Scheller, D. (2014). Does Walkability Influence Housing Prices? *Social Science Quarterly*, 95(3):852–867.
- Choné, P. and Linnemer, L. (2012). No Title.
- DiMaggio, C. and Li, G. (2013). Effectiveness of a Safe Routes to School Program in Preventing School-Aged Pedestrian Injury. *PEDIATRICS*, 131(2):290–296.
- Doyle, S., Kelly-Schwartz, A., Schlossberg, M., and Stockard, J. (2007). Journal of the American Planning Association Active Community Environments and Health: The Relationship of Walkable and Safe Communities to Individual Health. *Individual Health, Journal of the American Planning Association*, 72(1):19–31.
- Frank, L. D., Chair, B., and Engelke, P. (2005a). MULTIPLE IMPACTS OF THE BUILT ENVIRONMENT ON PUBLIC HEALTH: WALKABLE PLACES AND THE EXPOSURE TO AIR POLLUTION. 28(2).
- Frank, L. D., Schmid, T. L., Sallis, J. F., Chapman, J., and Saelens, B. E. (2005b). Linking objectively measured physical activity with objectively measured urban form: Findings from SMARTRAQ. In *American Journal of Preventive Medicine*, volume 28, pages 117–125.

- Froeb, L., Tschantz, S., and Crooke, P. (2003). Bertrand competition with capacity constraints: mergers among parking lots. *Journal of Econometrics*, 113(1):49–67.
- Gilderbloom, J. I., Riggs, W. W., and Meares, W. L. (2015). Does walkability matter? An examination of walkability’s impact on housing values, foreclosures and crime. *Cities*, 42(PA):13–24.
- Hotelling, H. (1929). Stability in Competition. *The Economic Journal*, 39(153):41.
- Inci, E. (2015). A review of the economics of parking. *Economics of Transportation*, 4(1-2):50–63.
- Kobus, M. B., Gutiérrez-i Puigarnau, E., Rietveld, P., and Van Ommeren, J. N. (2013). The on-street parking premium and car drivers’ choice between street and garage parking. *Regional Science and Urban Economics*, 43(2):395–403.
- Kuzmyak, J., Baber, C., and Savory, D. (2007). Use of Walk Opportunities Index to Quantify Local Accessibility. *Transportation Research Record: Journal of the Transportation Research Board*, 1977:145–153.
- Leyden, K. M. (2003). Social Capital and the Built Environment: The Importance of Walkable Neighborhoods. Technical Report 9.
- Lin, H. and Wang, Y. (2012). Competition and Price Discrimination in the Parking Garage Industry. *SSRN Electronic Journal*.
- Manaugh, K. and El-Geneidy, A. (2011). Validating walkability indices: How do different households respond to the walkability of their neighborhood? *Transportation Research Part D: Transport and Environment*, 16(4):309–315.
- McDonald, N. C., Steiner, R. L., Lee, C., Smith, T. R., Zhu, X., and Yang, Y. (2014). Impact of the safe routes to school program on walking and bicycling. *Journal of the American Planning Association*, 80(2):153–167.
- Pivo, G. and Fisher, J. D. (2011). The walkability premium in commercial real estate investments. *Real Estate Economics*, 39(2):185–219.
- Porta, S. and Renne, J. L. (2005). Linking urban design to sustainability: Formal indicators of social urban sustainability field research in Perth, Western Australia. *Urban Design International*, 10(1):51–64.

Salop, S. C. (1979). Monopolistic Competition with Outside Goods. Technical Report 1.

Speck, J. (2012). *Walkable city : how downtown can save America, one step at a time*. Farrar, Straus and Giroux.

Appendix

Table 2: Estimates Equation (9)

	Estimate	Std. Error	t value	Pr(> t)
Intercept	53.41	12.55	4.26	0.00
Tract price differential (μ)	2.63	0.28	9.36	0.00
Street intersection density	0	0	-0.84	0.40
Mix of use type	-1.17	1.45	-0.81	0.42
Number of grocery stores in one mile	-0.06	0.11	-0.5	0.62
Number of coffee shops in one mile	-0.2	0.15	-1.37	0.17
Number of movie theaters in one mile	0.6	0.08	7.22	0.00
Number of parks in one mile	0.17	0.08	2.17	0.03
Number of bookstores in one mile	-0.03	0.1	-0.33	0.74
Number of drug stores in one mile	0.03	0.11	0.3	0.77
Number of clothing stores in one mile	-0.31	0.06	-5	0.00
Number of restaurants in one mile	-2.11	0.74	-2.83	0.00
Number of bars in one mile	-0.02	0.17	-0.11	0.91
Number of schools in one mile	-0.17	0.35	-0.5	0.62
Number of libraries in one mile	-0.09	0.08	-1.04	0.30
Number of fitness centers in one mile	0.52	0.13	3.92	0.00
Number of hardware stores in one mile	0.39	0.07	5.45	0.00

Table 3: Descriptive Statistics

	Mean (1)	Median (2)	SD (3)	Min (4)	Max (5)
Mix of employment types and occupied housing	0.63	0.66	0.18	0.03	0.96
Mix of employment types	0.64	0.68	0.17	0	0.93
Street intersection density	128.65	100.34	129.63	0	1155.68
Number of grocery stores	3.26	3	2.52	0	14
Number of coffe shops	5.09	4	3.84	0	20
Number of movie theater	1.13	0	1.76	0	13
Number of parks	1.51	1	1.46	0	9
Number of bookstores	1.53	1	1.67	0	10
Number of drugstores	2	2	1.8	0	8
Number of clothing stores	1.27	0	2.43	0	19
Number of restaurants	10.89	11	5.44	0	20
umber of bars	7.37	7	5.15	0	20
Number of schools	6.13	6	4.29	0	20
Number of libraries	1.85	1	2.17	0	12
Number of fitness center	3.4	3	2.94	0	17
Number of hardware stores	0.92	0	1.24	0	7

Figure 11: On-the-spot Parking Price

