Computational complexity – Homework

Marc CHEVALIER

October 26, 2014

1 NP-Hardness

1.1 Halting problem

Let be φ an instance of SAT problem. We denote by n the number of variables.

Let be M a TURING machine which tests in a cycle all the 2^n possible assignations of the previous formula : when M has tested all assignations, it starts again. This machine halts if and only if φ is satisfiable. This reduction is polynomial, therefore $SAT \leqslant_p$ HALT, ie. HALT is NP-hard since SAT is NP-hard.

HALT is not NP-complete otherwise it was decidable by a TURING-machine, but HALT is unsatisfiable.

1.2 $TQBF$

All instance of SAT problem is an instance of $TQBF$. Without transformation, we have a polynomial reduction, ie. $SAT \leqslant_p TQBF$ so $TQBF$ is NP-hard.

This problem is known for being PSPACE-complete. It's not NP-complete.

1.3 $NAE - 3 - SAT$

Let be φ an instance of $NAE - 3 - SAT$.

$$\varphi = \bigwedge_{i=1}^{n} (x_{i,1} \vee x_{i,2} \vee x_{i,3})$$

We will describe the "not all equal" condition is term of formula.

$$\bigwedge_{i=1}^{n} \neg(x_{i,1} \wedge x_{i,2} \wedge x_{i,3}) \wedge \neg(\neg x_{i,1} \wedge \neg x_{i,2} \wedge \neg x_{i,3})$$

using DE MORGAN's law:

$$\psi := \bigwedge_{i=1}^{n} (\neg x_{i,1} \vee \neg x_{i,2} \vee \neg x_{i,3}) \wedge (x_{i,1} \vee x_{i,2} \vee x_{i,3})$$

$|\psi| \sim 2|\varphi| \Rightarrow |\psi| = \mathcal{O}(|\varphi|)$.

Let $\varpi := \varphi \wedge \psi$. ϖ is an instance of SAT and the reduction is polynomial. If there is an solution to the SAT problem ξ, then φ is satisfied and, thanks to ψ, the "not all equal" condition is true.

Reciprocally, if there is a solution of the $NAE-3-SAT$ problem φ, then this assignation makes ξ true.

Consequently, $SAT \leqslant_p NAE-3-SAT$ and $NAE-3-SAT$ is NP-hard.

Moreover, $NAE-3-SAT$ is clearly NP: a valid assignation is a sufficient witness. We can check in polynomial time if this assignation makes the formula true and if the "not all equal" condition is satisfied. Then $NAE-3-SAT$ is NP-complete.

1.4 MaxCut

Let F be an instance of $NAE-3-SAT$

$$F = \bigwedge_{i=1}^{m} C_i$$

We produce a graph $G = (V, E)$ which has a vertex for each literal of F. There is a edge between two vertices if there is a clause which contains this two literals. So each clause is described by a triangle. Moreover, we add $|F|_{x_i}$ (the number of occurrences of x_i in F) edges between x_i and $\neg x_i$. The size of the cut we search is at least $5m$.

If we have an assignment of the $NAE-3-SAT$, we take the vertices which are true in S and the other in $\overline{S}$. So, we have $2m$ from the triangles due to the clauses and $3m$ from the edges between all pair $(x_i, \neg x_i)$.

Reciprocally, if we have a cut of size $\geqslant 5m$.

If we have no pair $(x_i, \neg x_i)$ on the same size, we have a valid assignment.

If there is a such pair, we can move one of them on the opposite side without decreasing the size of the cut. Let n_i the number of edges between x_i and $\neg x_i$. We note a the number of edges which x_i is an extremity and which the other is in the opposite side. We note b the number of edges between b and a vertex of the opposite size. We know that $a + b \leqslant 2n_i$. If we move x_i in the opposite size, the cut gains $n_i - a$ edges. If $\neg x_i$ go to the opposite side, it gains $n_i - b$. $\max(n_i - a, n_i - b) \geqslant 0$, so we can move one of these vertices to the opposite side without decreasing the size of the cut. We redo this transformation until we reach a cut of the first case (at most m times).

We proved that $NAE-3-SAT \leqslant_p$ MaxCut.

Moreover, MaxCut is in NP. Indeed, a witness is the list of the vertices of S (or $\overline{S}$). The size is actually polynomial with respect of the size of G and we can check the solution in a polynomial time : we check easily that the cut has a size $\geqslant k$ in a quadratic time.

So, MaxCut $\in$ NP.

2 Reductions

3 Difference of NP problems

Proposition 1. ExactIndSet *is in DP.*

Proof. Let A be the set of all pairs (G, k) such that G has an independent set of size at least k, and let B be the set of all pairs (G, k) such G has a independent set of size at least $k + 1$. Then ExactIndSet $= A \setminus B$ and A is in NP and B is in NP. Hence by definition of DP, ExactIndSet is in DP. $\square$

Proposition 2. $\forall L \in DP$, *L is polynomial-time reducible to* ExactIndSet.

Proof.

Lemma 3. IndSet $\geqslant_p 3 - SAT$

Proof. Suppose we have an instance F of $3 - SAT$ problem where $F = \bigwedge_{i=1}^{m} C_i$ where C_i is the disjunction of 3 variables. We note $x_1, \ldots, x_n$ the variables. We create the graph G as follows:

- For each variable in each clause, create a vertex, which we will label with the name of the variable. Therefore there may be multiple vertexs with the label x_i or $\neg x_i$, if these variables appear in multiple clauses.
- For each clause, add an edge between the three vertices corresponding the variables from that clause.
- For all i, add an edge between every pair of vertexs with one is labelled with x_i and the other labelled with x_i.

There is a independent set of size m in G if and only if F is satisfiable. □

We note that this reduction from $3 - SAT$ to IndSet took an instance φ of $3 - SAT$ consisting of m clauses each of three literals and produced a graph G_φ with $3m$ vertexs such that if φ is satisfiable then the largest independent set in G has m vertexs, and if G is unsatisfiable then the largest independent set of G has at most $m - 1$ vertices.

Now suppose that A is in DP. We want to show that $A \leqslant_p$ ExactIndSet. By definition of DP, $A = L_1 \setminus L_2$ for $(L_1, L_2) \in NP^2$. Since $3 - SAT$ is NP-complete, there are polytime functions f_1 , f_2 such that for $i = 1\,, 2$ and for all $x \in \{0,1\}^\star$ we have $x \in L_i \Leftrightarrow f_i(x) \in 3SAT$. Hence for each fixed $x \in \{0,1\}^\star$, setting $\varphi_i = f_i(x)$, we have $x \in L_i \Leftrightarrow \varphi_i$ is satisfiable Thus from the above reduction to IndSet, there is a polytime function which takes x to a pair of graphs G_1, G_2 such that if m_i is the number of clauses in φ_i, then for $i = 1\,, 2$, no independent set in G_i has more than m_i vertices, and $x \in L_i \Leftrightarrow$ the largest independent set in G_i has size m_i.

Now we use the notation$G \sqcup H$ for the disjoint union of graphs G and H. That is, the vertices in $G \sqcup H$ are the disjoint union of those in G and H, and similarly for the edges. Now let $G_1' = G_1 \sqcup G_1$ Then a maximum independent set in G_1' is the union of maximum independent sets in the two copies of G_1. Thus $x \in L_1 \Rightarrow$ maximum independent set of G_1' is $2m_1$ and $x \in \overline{L_1} \Rightarrow$ maximum independent set of G_1' is $\leqslant 2m_1 - 2$. Now define G_2' so that its vertices are those of G_2 together with $m_2 - 1$ new vertices, and the edges consist of those of G_2 together with an edge from each of the new vertices to every vertex of G_2. Then we have designed $G'2$ so that no independent set can contain both vertices of G_2 and new vertices, so $x \in L_2 \Rightarrow$ maximum independent set of G_2' is m_2, $x \in \overline{L_2} \Rightarrow$ maximum independent set of G_2' is $m_2 - 1$. Now let $G_3 = G_1' \sqcup G_2'$ and let $k = 2m_1 + m_2 - 1$. To finish the proof that $A \leqslant_p DP$, it suffices to show that

Lemma 4.

$$x \in A \Leftrightarrow (G_3, k) \in DP$$

($\Rightarrow$): Suppose $x \in A$. Then by (2)$x \in L_1 \cap L_2$, so by (3) and (6) we conclude the maximum independent set of $G_3 = G_1' \sqcup G_2'$ is $2m_1 + m_2 - 1 = k$.

($\Leftarrow$): Suppose $x \notin A$. There are three cases:

- $x \in L_1 \cap L_2 \Rightarrow maxindset(G_3) = 2m_1 + m_2 > k$.
- $x \in L_1 \cap L_2 \Rightarrow maxindset(G_3) \leqslant 2m_1 + m_2 - 2 < k$
- $x \in L_1 \cap L_2 \Rightarrow maxindset(G_2) = 2m_1 + m_2 - 3 < k$

□

Theorem 5. ExactIndSet *is* DP*-complete.*

Proof. ExactIndSet is in DP (proposition 1) and it is DP-hard (proposition 2). □

4 Classes with exponential resources

We name BOUNDEDHALT the language of 3-tuples $\langle M, x, k\rangle$ where the machine M halts on input x in k steps.

Theorem 1. BOUNDEDHALT *is* EXP*-complete.*

Proof.

Lemma 2. BOUNDEDHALT $\in$ EXP.

Proof. Let $\langle M, x, k\rangle$ an instance of BOUNDEDHALT.

We simulate M on x for k steps and accepts if and only if M halts and rejects otherwise. The running time is $m^{\mathcal{O}(1)}$. Let $n = |\langle \alpha, x, k\rangle| \geqslant \log k$. Therefore, the running time $\leqslant m^c = 2^{c \log m} \leqslant 2^{cn}$. $\square$

Lemma 3. BOUNDEDHALT *is* EXP*-hard.*

Proof. For each language $\mathcal{L} \in$ EXP, we need to give polytime reduction from $\mathcal{L}$ to BOUNDEDHALT. For a given language $\mathcal{L} \in$ EXP, we know there is a TURING MACHINE $M_{\mathcal{L}}$ that decides A in time $g(n) \leqslant 2^{n^k}$ for a $c \in \mathbb{N}$.

Let f such that $f(w) = \langle M_{\mathcal{L}}, w, m\rangle$ where $m = 2^{|w|^c}$.

f is polytime computable and $w \in \mathcal{L} \Rightarrow \langle M_{\mathcal{L}}, w, m\rangle \in$ BOUNDEDHALT and $w \notin \mathcal{L} \Rightarrow \langle M_{\mathcal{L}}, w, m\rangle \notin$ BOUNDEDHALT $\square$

BOUNDEDHALT is in EXP (lemma 2) and it is EXP-hard (lemma 3). $\square$

Theorem 4.

$$\mathrm{L} = \mathrm{P} \Rightarrow \mathrm{PSPACE} = \mathrm{EXP}$$

Proof. Take an arbitrary $\mathcal{L} \in$ EXP, decided by a TURING machine in time 2^{n^c}.

Let $L_{pad} := \left\{ x\diamondsuit^{2^{|x|^c}} \mid x \in \mathcal{L} \right\}$. We have $L_{pad} \in$ P and, by the assumption P = L, we found that $L_{pad} \in$ L. So, there is some TURING machine M_0 deciding L_{pad} in space $\log n$. M_0 can be used to decide L: on input x, simulate M_0 on the padded input $x\diamondsuit^{2^{|x|^c}}$ accept if and only if M_0 accepts.

The space we used on input x ($|x| = n$) is the space used by M_0 on the padded input $x\diamondsuit^{2^{|x|^c}}$ of size $n + 2^{n^c}$, which is at most $\log\left(2^{n^c+1}\right) = n^c + 1$, a polynomial. Hence, we have that $\mathcal{L} \in$ PSPACE.

If we actually write the padded input $x\diamondsuit^{2^{|x|^c}}$ on the work tape, this would make the space usage exponential in n. But, we don't need to write entirely this padded input. We know what it looks like to the right of x. So we can simulate M_0 on the virtual padded input $x\diamondsuit^{2^{|x|^c}}$ by using a counter which tells the position on the tape of M_0. If M_0 enquires about the position to the right of x, we respond with the symbol $\diamondsuit$ (or the blank, if M_0 goes to the right of the entire padded input). Since the counter can assume the value at most 2^{n^c}, we need at most n^c bits for the counter. Thus, this new TURING machine uses space at most polynomial in n. $\square$

5 Downward self-reducibility

6 Space hierarchy theorem

7 Polynomial hierarchy