## Math 1152 Lecture Notes

July 22, 2022

## 1 Last time

Parametric equations parametrize an equation in variables  $x, y, \cdots$  by making explicit the parameter(s)  $t, s, \cdots$  on which the variables depend. This makes it easy to see, for instance, that a curve like

$$\gamma(t) = \begin{cases} x(t) = t^2 + \sin(t) \\ y(t) = t^3 + \cos(t) \end{cases}$$

is one-dimensional.

The idea of making explicit some hidden parameters which underly relationships between multiple variables is also a thing which shows up, in a different form, in statistics.

# 2 Calculus and parametric equations

Suppose that  $\gamma(t)=(x(t),y(t))$ . To talk about limits, we want to be able to talk about how close  $\gamma(t)$  and  $\gamma(s)$  are. Given two points in the plane, their distance is given by the distance formula, so we define

$$|\gamma(t) - \gamma(s)| = \sqrt{|x(t) - x(s)|^2 + |y(t) - y(s)|^2}.$$

Then we can say

$$\lim_{t \to s} \gamma(t) = \left(\lim_{t \to s} x(t), \lim_{t \to s} y(t)\right)$$

not as a definition, but as a theorem, with our definition of limit being that

 $\lim_{t\to s} \gamma(t) = L$  if for every  $\epsilon > 0$ , there is a  $\delta = \delta(\epsilon) > 0$  so that

$$|\gamma(t) - L| < \epsilon$$

whenever

$$|t-s| < \delta$$
.

**Theorem 1.** If  $\lim_{t\to s} x(t) = a$  and  $\lim_{t\to s} y(t) = b$ , then

$$\lim_{t\to s}\gamma(t)=(a,b).$$

## ${\bf Continuity}$

We define continuity as usual:  $\gamma$  is continuous at s if  $\lim_{t\to s} \gamma(t) = \gamma(s)$ .

**Exercise 1.** Explain why  $\gamma=(x,y)$  is continuous if and only if x and y are continuous.

 ${\bf Question} \ {\bf 1.} \ {\bf Are \ there \ so-called}$  "space-filling" curves?

#### **Derivatives**

Here's an attempt at a definition of derivative for a parametrized curve  $\gamma$ :

$$\gamma'(t) = \lim_{h \to 0} \frac{\gamma(t+h) - \gamma(t)}{h}.$$

In order for this to work, we have just one problem : we need to know about operations of addition (or subtraction) between curves and multiplying (or rather, dividing) them by real numbers.

#### Vectors

A Vector Space is a set, X, endowed with a binary operation, +, and an identity element, 0, such that for any  $u, v, w \in V$ 

- 1. 0 + v = v
- 2. u + v = v + u
- 3. (u+v) + w = u + (v+w)

together with an operation  $\cdot : \mathbb{R} \cdot V \to V$  satisfying that for any real numbers (called **scalars**), a, b,

- 4.  $1 \cdot v = v$
- 5.  $a \cdot (b \cdot v) = (ab) \cdot v$
- 6.  $v + (-1) \cdot v = 0$
- 7.  $a \cdot v + b \cdot v = (a+b) \cdot v$ .

Elements of a vector space are called **vectors**.

**Exercise 2.**  $\mathbb{R}^2$  is a vector space. So is  $\mathbb{R}$ . So are the polynomials of degree less than any fixed d. So is the space of all continuous functions.

So lets reinterpret our parametrized curve  $\gamma$  as mapping  $\mathbb R$  into the vector space  $\mathbb R^2.$  Then

$$\gamma'(t) = \lim_{h \to 0} \frac{\gamma(t+h) - \gamma(t)}{h}$$

makes sense, and we can see that it is just

$$\gamma'(t) = \lim_{h \to 0} \frac{(x(t+h) - x(t), y(t+h) - y(t))}{h}$$

$$= \lim_{h \to 0} \left( \frac{x(t+h) - x(t)}{h}, \frac{y(t+h) - y(t)}{h} \right)$$

$$= (x'(t), y'(t)).$$

Geometrically, this also matches what we want from the derivative:

**Exercise 3.** Find the equation for the tangent lines to the curve  $\gamma(t) = (\cos(t), \sin(t))$ .

3 Lengths of curves, revisited