Interior Penalty Functions

- Barrier Functions
- A Problem and a Solution

Initial Steps

A second type of penalty function begins with an initial point inside the feasible region, which is why these procedures are called interior penalty functions or "barrier methods".

Before beginning, all constraints must be converted into (expression) ≤ 0 form.

This method will not work with equality constraints.

Barrier Functions

The simplest interior penalty function, called an "inverse barrier function", involves writing a barrier function for each constraint $g_i(x) \le 0$ as follows:

$$B(x) = -\frac{1}{g_j(x)}$$

This procedure has two effects:

- The negative sign changes the constraint from a negative number (≤ 0) to a positive.
- The fraction ensures that as g_j(x) approaches the constraint boundary at 0, the barrier function gets infinitely large.

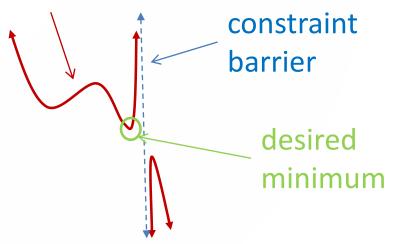
Therefore, this barrier creates a positive number that approaches infinity as x nears the boundary.

Problems with Barriers

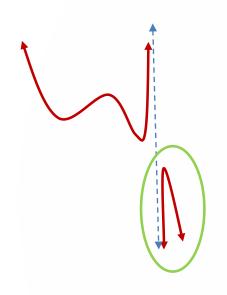
As with exterior penalty functions, the inverse barrier method causes some graphical problems. Because it involves an inverse function 1/g(x), it creates an asymptotic graph:

objective function T(x)

As long as we stay on the left side of the barrier, the method will work.



Problems with Barriers



If the initial point ever moves outside the boundary, however, the method will fail, because outside the constraint (in this case, the right side of the graph) the other side of the function will come into play.

The values here are lower, so a minimization program will pick them up and run with them, even though they violate the constraint.

The Solution: r, again!

As with exterior penalty functions, part of the solution is to include a multiplier, in this case 1/r. We will begin with r = 1 and gradually increase r by factors of 10.

This has the effect of successively reducing the penalty. In the beginning the penalty is large, preventing the minimum point from crossing the barrier of the constraint. This barrier is so effective that the minimum point will not be very accurate.

As the penalty gets smaller, the minimum point will approach closer to the boundary.

Writing the Penalty Function

Using our previous example,

minimize f(x) = 100/x

subject to $x \le 5$

we will first convert the constraint to $x - 5 \le 0$, then write the barrier function:

$$B(x) = -\frac{1}{x-5}$$

and then the modified objective function:

minimize T(x) =
$$\frac{100}{x} + \frac{1}{r} \cdot \frac{-1}{x-5}$$

Final Steps

Finally, we will choose a point within the feasible region as our starting point.

From there, we can use a step minimizer to minimize the function with r = 1; then, using that answer as the next starting point, minimize again with r = 10, and so on.

Minimize

$$T(x) = \frac{100}{x} + \frac{1}{r} \cdot \frac{-1}{x-5}$$
 with $r = 1$ from starting point $x = 2$.

Repeat for r = 10

$$r = 100$$

 $r = 1000$ and
 $r = 10,000$.

Write a program or "for" loop that will increase the value of r and decrease the initial step size of your minimizer.

Use your program to minimize

$$f(x) = (x - 12)^2$$

subject to $x \le 10$

Use an interior penalty function to minimize $f(x) = 0.8x^2 - 2^x$

subject to $x \le 4$.

- a) Start with r = 1 and initial point 2, then 3.
- b) Then, use r = 10 and initial point 2, then 3.
- c) Reference graphs of f(x) and T(x). What is the correct answer? What happened?

Final Comments

The difficulties on problem 3 bring up an interesting point: penalty methods are not just plug-and-play! There are many variables involved, including:

- the initial value of r
- how fast r grows
- the initial value of x
- the step size in the minimizer

In an actual problem, these variables are tried in different combinations, and typically both interior and exterior methods are used.

Minimize the function

$$f(x) = \frac{x^3}{10} + 12\sin(x) + 1.7^{-x} - x^2$$

subject to $-7 \le x \le 11$. (note: this is two constraints!)

- a) Run a variety of feasible starting points through an interior penalty function.
- b) Run one infeasible point from each side in an exterior penalty function.
- c) This should yield five candidates for the global minimum including the endpoints. Test each candidate in f(x) to find the minimum value.