

Machine Learning

Week 11: Probabilistic Machine Learning (Part 1)

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Learning Objectives

After successfully completing this, you will be able to ...

- Discuss the motivation for handling uncertainty in ML
- Distinguish between prior and conditional probability
- Demonstrate understanding of how to use the axioms of probability and Bayes' rule
- Describe and apply the Naïve Bayes classifier to inductive learning problems
- Show how Bayesian Networks represent influence and independence of variables
- Discuss how BNs can be used for classification & data exploration.



Structure of Videos for Probabilistic ML Topic

Week 11

- Topic Part 1A: Review of Probability Basics
- Topic Part 1B: Reasoning with Bayes' Rule

Week 12

- Topic Part 2A: Probabilistic Classifiers
- Topic Part 2B: Bayesian Networks



Part 1A: Review of Probability Basics

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Why Consider Uncertainty? (1)

• In a deterministic domain, is there uncertainty?

- What are the sources of uncertainty?
 - Incomplete knowledge: lack of relevant facts, partial observations, inaccurate measurements, incomplete domain theory ...
 - Inability to process: too complex to use all possible relevant data in computations, or to consider all possible exceptions and qualifications

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Why Consider Uncertainty? (2)

Example: Going to airport – will *t* minutes be enough? Problems:

- incomplete observations (road state, other drivers' plans, etc.)
- noisy sensors (traffic reports)
- uncertainty in action outcomes (flat tyre, etc.)
- immense complexity of modeling traffic

Therefore, purely logical approach either:

- Risks falsehood:"90 minutes will get me there on time", or
- Leads to conclusions that are too weak for decision making:
 "90 minutes will get me there on time, if there's no accident, and it doesn't rain, and my car doesn't break down ..."
 "24 hours will get me there on time" but requires very long wait





Techniques for Handling Uncertainty

Default or Nonmonotonic logic:

- Assume car does not have flat tyre
- Assume 90 minutes is OK unless contradicted by evidence

Issues: What assumptions are reasonable?

How should contradiction be handled?

Rules with Certainty Factors:

- 90 minutes | $\rightarrow_{0.3}$ get there on time (ie 30% certainty)
- Sprinkler | → _{0.99} WetGrass
- WetGrass | → _{0.7} Rain

Issues: Problems with combination: Sprinkler causes rain?

Probability:

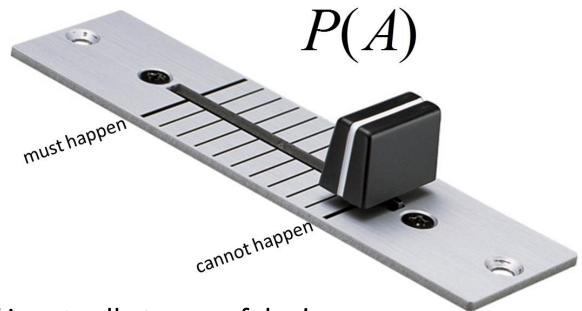
- Model agent's degree of belief
- Given the available evidence,
 90 minutes will get me there on time with probability 0.4



Review of Probability (1)

Probability: a way of summarising uncertainties

 $0 \le P(s) \le 1$: level of belief in truth of statement



Important:

- Statement itself is actually true or false!
- Our beliefs may change when we observe new evidence



Review of Probability (2)

How do we assess probabilities?

- Statistical data, general rules, logical considerations, or combination of evidence
- Although probabilities are personal,
 they must still be reasonable and rational

Example:

Pick a card ...

Before looking: $P(Card = Q \checkmark) = 1/52$

After looking: $P(Card = Q \forall) = 0 \text{ or } 1$



Review: Probability Notation (1)

We will consider discrete random variables:

- Random variable: cannot directly control its value, we can just observe it
- Boolean-valued random variable: denotes an event, with some degree of uncertainty as to whether it occurs:

```
Cavity: <true, false>
P(Cavity=true) is also written as P(cavity)
P(Cavity=false) is also written as P(¬cavity)
```

 General case of discrete random variable: values in domain are mutually exclusive and exhaustive ExamResult: <a, b, c, d, fail>

P(ExamResult=a) = 0.2, ... P(ExamResult) = <0.2, 0.3, 0.3, 0.15, 0.05>



Review: Probability Notation (2)

Probabilities of Values in a Domain Sum to 1

Provided they are mutually exclusive and exhaustive:

```
P(Elvis=alive) = .01; P(Elvis=dead) =.99
```

Elementary proposition:

- Constructed by assigning a value to a random variable:
- Example 1: Weather = sunny
- Example 2: Cavity = false



Review: Probability Notation (3)

Complex proposition:

- Formed from elementary propositions and logical operators
- Example: Weather = sunny ∨ Cavity = false

Logical operators and notations used to represent them:

AND: $a \wedge b$ (mnemonic: similar shape to an A)

OR: $a \vee b$

NOT: ¬a



Review: Probability Notation (4)

Atomic event: complete specification of state of the 'world'

- World: environment/scenario about which we are reasoning
- E.g.: if world consists of just two Boolean variables, Anna_Here and Bob_Here, There are 4 distinct atomic events:

```
Anna_Here = false \land Bob_Here = false
Anna_Here = false \land Bob_Here = true
Anna_Here = true \land Bob_Here = false
Anna_Here = true \land Bob_Here = true
```

Atomic events are mutually exclusive and exhaustive:
 only one is true; their probabilities sum to 1



Review: Axioms of Probability (1)

- 1. Probability of any proposition is between 0 and 1: $0 \le P(a) \le 1$
- Necessarily true propositions have probability 1; necessarily false propositions have probability 0: P(false) = 0, P(true) = 1
- 3. Probability of a disjunction $(a \lor b)$ is: $P(a \lor b) = P(a) + P(b) - P(a \land b)$ (Sum Rule)

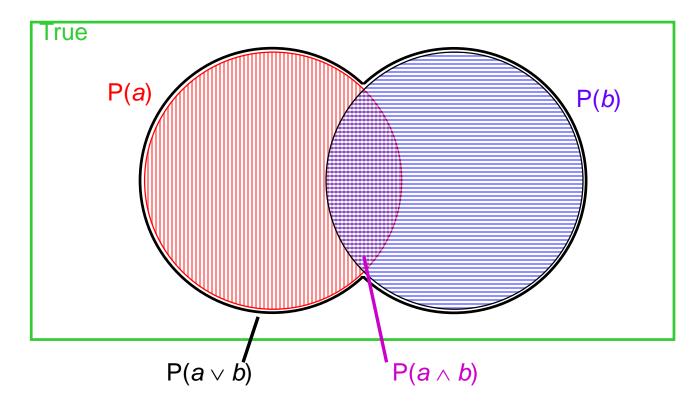




Review: Axioms of Probability (2)

Illustration of Sum Rule:

$$P(a \lor b) = P(a) + P(b) - P(a \land b)$$





Unconditional and Conditional Probability

Unconditional Probability:

- P(a) = degree of belief in proposition**a**in*absence*of any other information
- Also known as **prior probability**:
 Belief *prior* to arrival of any new information
- Specified as a probability distribution:
 P(ExamResult) = <0.2, 0.3, 0.3, 0.15, 0.05>
 P(Anna_Here=true) = .98, P(Anna_Here=false) = .02

Conditional Probability:

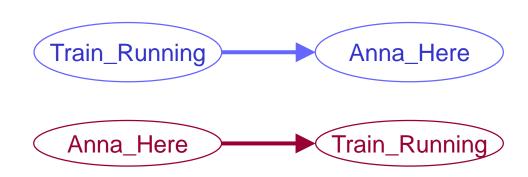
- Also known as posterior probability: Belief post arrival of new information
- Probability is conditioned by other evidence
- P(Anna_Here=false | Train_Running=false) = 0.8
 "Prob. That Anna is NOT Here is 0.8, given that all you know is that the Train is NOT running."



Conditional Probability Graphically ...

Train_Running and Anna_Here interact

- Knowing about **Train_Running** gives us evidence about **Anna_Here**
- Or vice versa



Diagrams are easiest to understand if we think about causality in drawing them:

- Which causes which?
- Hidden causes?



Joint Probability Distribution

For a set of random variables, joint probability distribution gives probability of every **atomic event** on those variables

- For n Boolean variables, size is 2^n (exponential in no. of variables)
- Later: represent more compactly because of independence
- P(Weather, Tennis): 4 × 2 matrix of values:

	Weather = sunny	Weather = rain	Weather = cloudy	Weather = snow
Tennis = true	0.144	0.02	0.016	0.02
Tennis = false	0.576	0.08	0.064	0.08



A Real-Life Joint Probability Distribution ...



The joint probabilities are as follows, per our Deluxe model.

D Senate + D House: 18%

D Senate + R House: <1%

R Senate + D House: 68%

R Senate + R House: 14%

So still better than a 30% chance that *either* the House or the Senate will result in an upset tonight. Pretty exciting!



Independence

New evidence may be irrelevant:

```
P(Anna_Here=false | Train_Running=False, Exam_Result=a) = P(Anna_Here=false | Train_Running=False)
```

= 0.8

This indicates independence between variables:

- Exam_Result independent of Anna_Here
- Also known as absolute independence
- Diagram: no arc

Such simplifications very important

- Can greatly reduce the number of combinations we need to consider

Anna_Here

Exam_Result

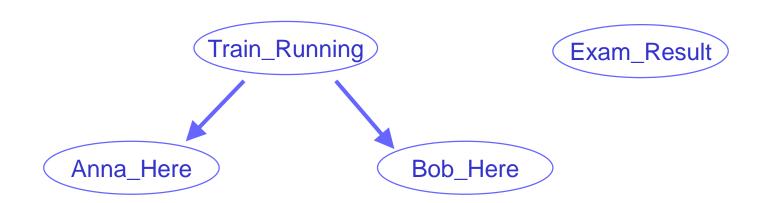


Conditional Independence (1)

Conditional Independence is different from absolute independence

- Anna and Bob both take the train, so if Anna is not here,
 it is more likely that Bob is not here
- Bob being here is **not completely independent** of Anna being here;
 they are both dependent on the Train running
- Anna_Here conditionally independent of Bob_Here given Train_Running

Graphically:



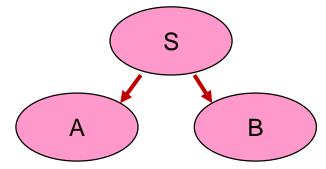
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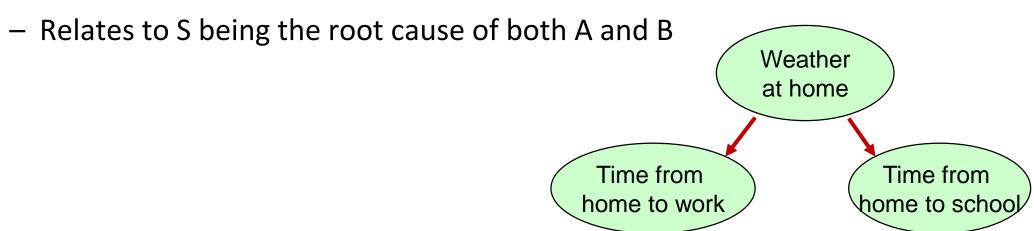
Conditional Independence (2)

Note also:

- We say that A and B are *d-separated* by S (D=directional)
- If we know value of S, then knowing value of A does not give us any additional information about value of B



 However, in the absence of information about the separating variable S, knowing A does give us information about B



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Probability Formulae (1)

Absolute Independence:

 If two variables are independent, the probability of both happening is the product of their individual probabilities

$$P(A \land B) = P(A) P(B) \Leftrightarrow A \text{ independent of } B$$

– Example:

```
P(Suit=♥) = 1/4. P(Value=Q) = 1/13. P(Suit=♥ ∧ Value=Q) = 1/52.
```

Conditional Independence:

– If A is conditionally independent of B given X:

 $P(A \land B \mid X) = P(A \mid X) P(B \mid X) \Leftrightarrow A cond. indep. of B given X$

If X is known, knowledge of A's value will not affect opinion of B's value, so can apply same rule as for absolute independence



Probability Formulae (2)

Product Rule (conjunctions):

$$P(A \wedge B) = P(A \mid B) P(B) = P(B \mid A) P(A)$$

Example:

$$P(N | storm) = 0.6, P(storm) = 0.01$$

=> $P(N \land storm) = 0.006$

If lightning occurs in 60% of storms, and a storm occurs 1% of the time, then lightning and storm together occur 0.6% of the time

Conditional Probability of two propositions:

$$P(a | b) = P(a \land b) / P(b), for P(b) > 0$$



Probability Formulae (3)

Theorem of Total Probability:

- If domain of A is $< a_1, a_2, ..., a_n >$, then:

$$P(B) = \sum_{n} P(B|a_i) P(a_i)$$

$$P(N) = P(N \mid storm) P(storm) + P(N \mid \neg storm) P(\neg storm)$$

Total probability of lightning occurring = prob. of it *with* a storm + prob. of it *without* a storm

Bayes' Rule:

$$P(B \mid A) = P(A \mid B) P(B) / P(A)$$

- Follows from Product Rule
- Allows us to reason about causes when we have observed effects



Part 1B: Reasoning with Bayes' Rule

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Reasoning with Bayes' Rule

Bayes' Rule:

$$P(b | a) = P(a | b) P(b) / P(a)$$

Easily derived from Product Rule:

$$P(a \land b) = P(a \mid b) P(b) = P(b \mid a) P(a)$$

Divide by P(a): $P(a \mid b) P(b) / P(a) = P(b \mid a)$



Probably not the Rev. Thomas Bayes 1702-1761

Applies to variables as well as propositions:

$$P(B \mid A) = \frac{P(A \mid B) P(B)}{P(A)}$$

What's the point?

Allows us to reason about an **unobserved cause** (B) when we have observed the **effect** (A)





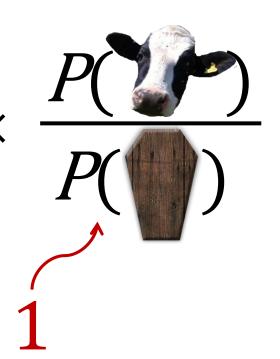


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= P(causes)



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$$= P(\text{causes}) \times P(\text{constant})$$



$$= P(\underbrace{causes}) \times P(\underbrace{)}$$

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A disease affects 1 in 1000 people

A Person Tests +

Test is 99% accurate

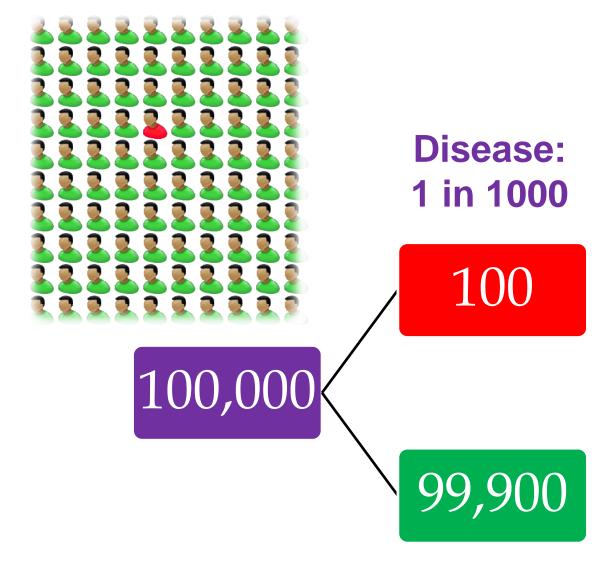
Probably have it?

Probably don't?



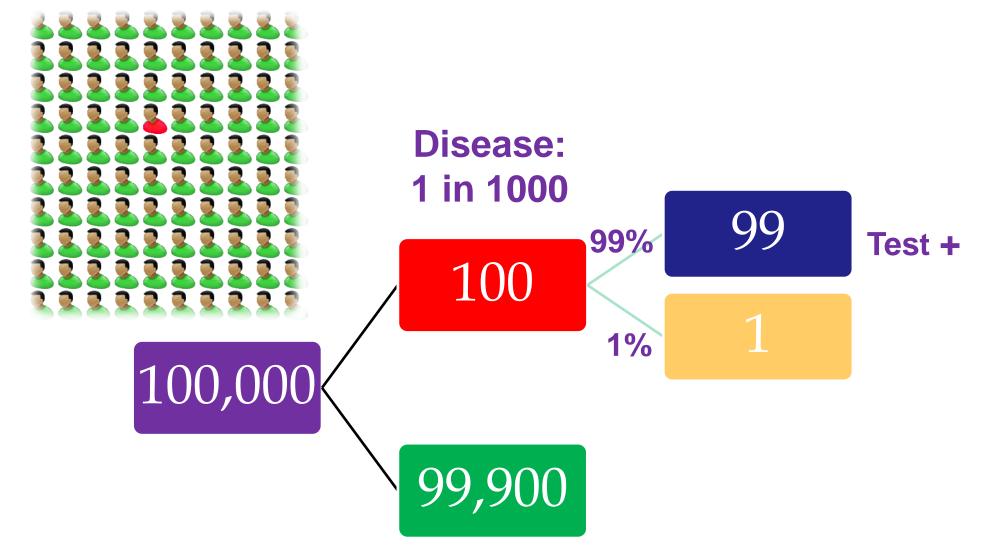
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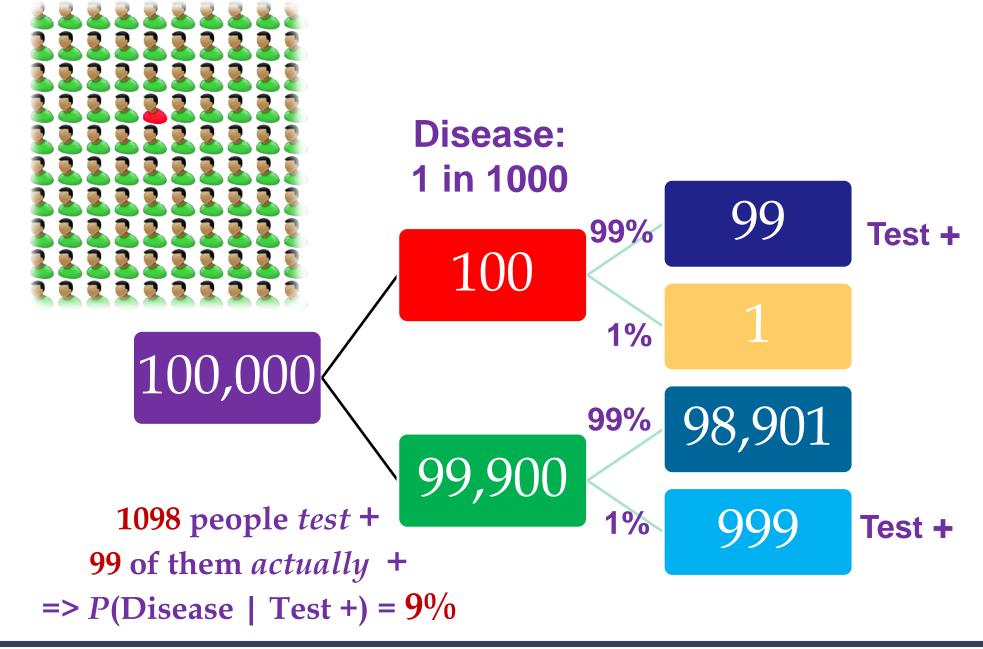
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Bayes' Rule: Example

Patient has sore throat: caused by influenza?

- P(sore_throat | flu) = 0.75
 75% probability of a patient with flu having a sore throat, based on experience of patients with flu
- P(sore_throat) = 0.1:
 1 in 10 patients have sore throat, based on observations at the surgery
- P(flu) = 0.02:1 in 50 patients have flu
- => P(flu | sore_throat) = $.75 \times .02 / .1 = 0.15$ 15% probability based on this evidence



Bayes' Rule with Normalisation (1)

Alternative formulation of Bayes' Rule

- Avoid needing to know prior probability of evidence:
 In this example, P(sore_throat)
- Instead, compute posterior probability for each value of query variable, and normalise:

```
P(flu \mid sore\_th) = P(sore\_th \mid flu) \times P(flu) / P(sore\_th)
P(\neg flu \mid sore\_th) = P(sore\_th \mid \neg flu) \times P(\neg flu) / P(sore\_th)
```



Bayes' Rule with Normalisation (2)

Some observations:

- The probabilities P(flu | ...) and P(¬flu | ...) must sum to 1
- Both times we are dividing by same term, P(sore_th), so we can eliminate it by normalising
 P(flu | ...) and P(¬flu | ...)
- Probability of not having flu is easily found: $P(\neg flu) = 1 P(flu)$



Bayes' Rule with Normalisation (3)

Applying this to the Influenza example:

```
    Use α to denote the normalisation constant
        (this will be equal to 1/P(sore_th))
    P(flu | sore_th) = α ×P(sore_th | flu) ×P(flu)
    P(¬flu | sore_th) = α ×P(sore_th | ¬flu) ×P(¬flu)
```

– We already have:

```
P(sore_throat | flu) = 0.75, P(flu) = 0.02
P(\neg flu) = 1 - P(flu) = 0.98
```

In this case, we also need to know P(sore_th | ¬flu),
 probability of having a sore throat when you don't have flu:
 From observations at the surgery, this is 0.087

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Bayes' Rule with Normalisation (4)

Can then calculate:

```
P(flu | sore_th) = \alpha \times 0.75 \times 0.02 = \alpha 0.015
P(¬flu | sore_th) = \alpha \times 0.087 \times 0.98 = \alpha 0.08526
```

To eliminate α , normalise the numbers (sum is 0.10026):

```
P(flu | sore_th) = 0.015 / 0.10026 = 0.15 (as before)
P(\negflu | sore_th) = 0.08526 / 0.10026 = 0.85
```

General form of Bayes' Rule with Normalisation:

```
P(Y \mid X) = \alpha P(X \mid Y) P(Y)
```

where α is constant to make P(Y|X) entries sum to 1



Bayes' Rule with Normalisation (5)

General form of Bayes' Rule with Normalisation:

$$P(Y \mid X) = \alpha P(X \mid Y) P(Y)$$
 where α is normalisation constant

The Product Rule that we saw earlier states that:

$$P(X \wedge Y) = P(X \mid Y) P(Y)$$

If we combine both equations, we see that:

$$P(Y \mid X) = \alpha P(X \land Y)$$

Therefore, to calculate the probability of **X given Y**, we can calculate probability of **X and Y** and normalise result to get the final answer.



Bayes' Rule: Discussion

Why not just measure P(flu | sore_throat)?

 This diagnostic probability could be assessed from observations, as the other values are

Rationale: causal probabilities are more robust

- If there's a flu outbreak, P(flu) will increase
- P(flu | sore_throat) is difficult to re-assess directly:
 counts from before outbreak will not be applicable
- However, P(flu) can be measured again andP(sore_throat | flu) is unchanged
- From Bayes' Rule, see that P(flu | sore_throat) should increase proportionately with P(flu)

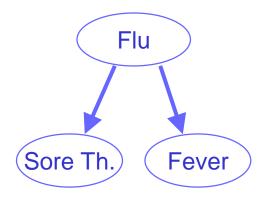


Bayes' Rule: Combining Evidence

Suppose patient also has fever: effect on reasoning?

P(flu | sore_th \land fever) = α P(sore_th \land fever | flu) P(flu)

Problem: To apply Bayes' Rule directly, need
 joint probability: sore_th \(\triangle \) fever



Observation: sore_th conditionally independent of fever given flu

- Can use Conditional Independence formula
 P(A \(\times \) B \(\times \) X) = P(A \(\times \) X)
- Therefore, only need individual conditional probabilities:
 P(flu | sore_th ∧ fever) = α P(sore_th | flu) P(fever | flu) P(flu)
- Just calculate both using Bayes' Rule and multiply them.



Bayesian Updating

Bayes' Rule can be applied iteratively, for sequential testing

Flu example can operate in this way:
 Initially, have prior probability of flu: P(flu)

Then, check whether patient has sore throat and compute

P(flu | sore_th) by applying Bayes' Rule to update P(flu)

Then, check whether patient has a fever and compute

P(flu | sore_th ∧ fever) by applying Bayes' Rule to P(flu)

 It is easy to check that this gives the same result in the case where we assume sore_th and fever are independent

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