Image Separation with Side Information: A Connected Auto-Encoders Based Approach

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• Non-invasive and Non-destructive: macro X-ray fluorescence (MA-XRF) scanning and hyperspectral imaging ...

• Challenging tasks: crack detection, material identification, brush stroke style analysis, canvas pattern or stretcher bar removal automated canvas weave analysis, and improved visualization of concealed features or under-drawing.

- X-ray images: Provide insights into an artists technique and working methods, for example revealing the paintings stratigraphy and information about the painting support or even some indication of the pigments used.
- X-ray images: However, the X-ray image of a painting particularly those with design changes, areas of damage, hidden paintings, or paintings on both the front and reverse sides of the support will inevitably contain a mix or blend of these various features, making it difficult for experts to interpret.

The propose:

- 1. First, self-supervised learning, connected auto-encoders that extract features from the RGB images in order to (a) reproduce both of the original RGB images, (b) reconstruct the associated separated X-ray images, and (c) regenerate the mixed X-ray image.
- 2. Second, tune these auto-encoders based on the use of a composite loss function involving reconstruction losses, energy losses and dis-correlation losses.

The propose:

3. Third, analysis of the effect of various hyperparameters associated with our separation method on performance.

4. Finally, we apply to a real dataset, showcasing state-of-the-art results over competing methods. The dataset relates to images taken from the double-sided wing panels of the Ghent Altarpiece

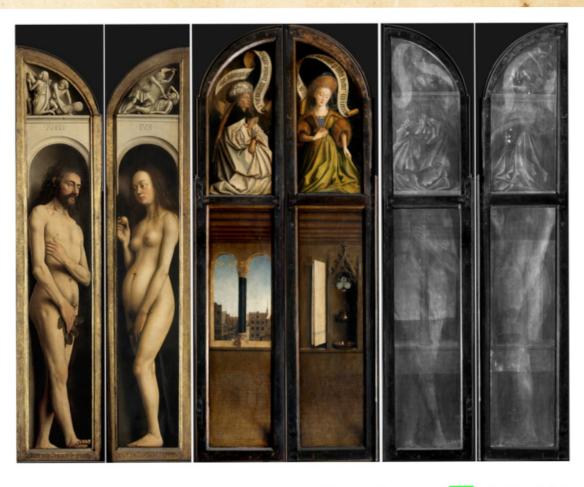


Fig. 1. Two double-sided panels from the *Ghent Altarpiece* [51]: (left) visible RGB image of the front side, (centre) visible RGB image of the back side, (right) mixed X-ray image.

II. PROBLEM FORMULATION

• **Goal:** Separate the mixed X-ray image into two components where one component would contain features associated with the image on the front panel and the rear panel.

• **Methodology:** Dividing these images into several smaller patches that overlap with respect to the vertical and horizontal dimensions of the image.

II. PROBLEM FORMULATION

• **Linear mixing assumption:** x denotes a mixed X-ray image patch and let x1 and x2 separated X-ray image patches corresponding to the front and rear.

$$x \approx x_1 + x_2$$
.

• **Further** assume that there is a mapping F that is approximately able to convert an image patch in the RGB domain into an image patch in the X-ray.

$$x \approx \mathcal{F}(r_1) + \mathcal{F}(r_2).$$

Where mapping function F has been modelled via a 7-layer (CNN).

II. PROBLEM FORMULATION

• Minimizing the error between the sum of the two separated X-ray image patches and the original mixed X-ray image patch:

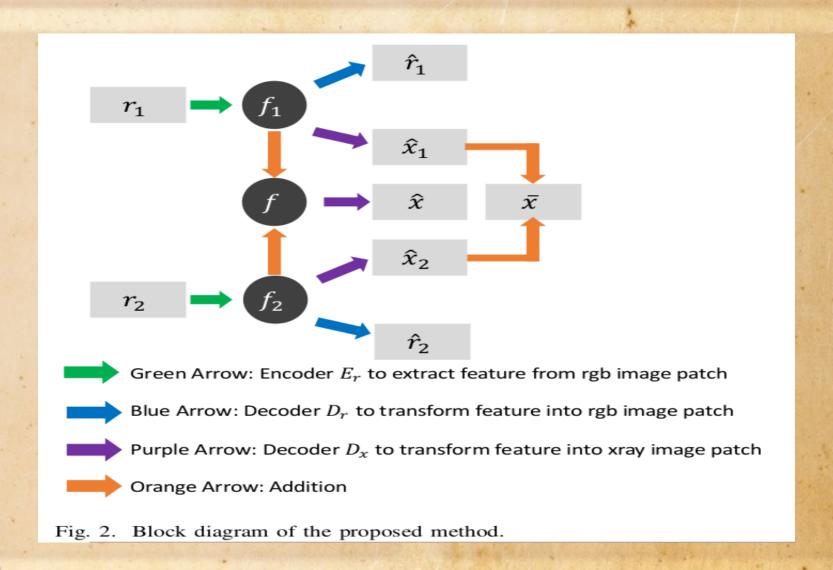
$$\min_{\mathcal{F}} \|x - \mathcal{F}(r_1) - \mathcal{F}(r_2)\|_F.$$

where || . || denotes the Frobenius norm.

• **Problem:** lack of constraints on the structure of x1 and x2, the individual X-ray images obtained using the can be highly related to the corresponding RGB images.

A. Connected auto-encoder structure

- Approach is based on the use of auto-encoders.
 - 1. **Encoder Er** is used to extract features f1 and f2 from the RGB image patches r1 and r2.
 - 2. **Decoder Dr** is used to convert the features f1 and f2 onto an estimate of the RGB image patches r1 and r2.
 - 3. **Decoder Dx** is also used to convert the features f1, f2 and f onto an estimate of the X-ray image patches $\hat{x}1$, $\hat{x}2$, and \hat{x} respectively, where f denotes a feature vector associated with the mixed X-ray image patch x;
 - 4. **One 'addition' process** is used in the feature and X-ray domain to get another version of the mixed X-ray $\bar{x} = \hat{x}1 + \hat{x}2$ and the corresponding feature map f = f1 + f2.



A. Connected auto-encoder structure

- **Shared-Features Assumption**: For a certain pair of X-ray image patch x1 and its corresponding RGB image patch r1, one postulates there is some **latent feature vector** f1 such that x1 = Dx(f1) and r1 = Er(f1) (rear panel, as well).
- **Linear-Feature Assumption:** The feature map f associated with a mixed X-ray patch x corresponds to the sum of the feature map f1 associated with X-ray image of patch x1 and feature map f2 associated with X-ray image of patch x2. The feature map can be used to reconstruct \hat{x} , Dx; i.e., $\hat{x} = Dx(f)$.

• B.

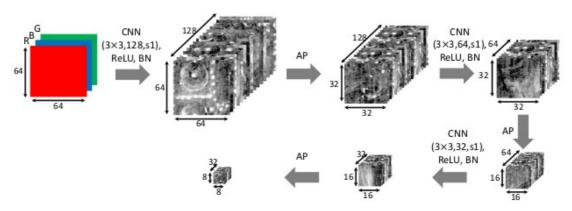


Fig. 3. Encoder E_r is modelled as 3-layer 2-dimensional CNNs , wherein each CNN layer is followed by batch normalization (BN), ReLU activation as well as average pooling (AP) layers.

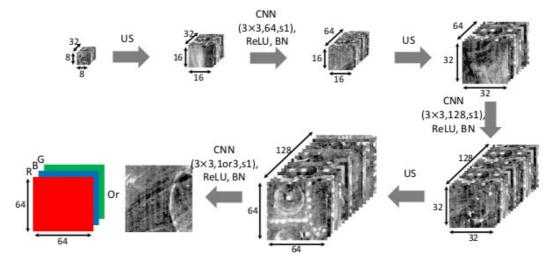


Fig. 4. Decoders D_x and D_r are modelled as 3-layer CNNs, wherein each CNN layer is followed by batch normalization (BN), ReLU activation as well as upsampling (US) layers.

C. Learning Algorithm

1.
$$L_1 = ||r_1 - \hat{r}_1||_F + ||r_2 - \hat{r}_2||_F.$$

2.
$$L_2 = \|x - \hat{x}\|_F ,$$
 where $\hat{x} = D_x(E_r(r_1) + E_r(r_2)).$

3.
$$L_3 = \|x - \bar{x}\|_F \,,$$
 where $\bar{x} = \hat{x}_1 + \hat{x}_2 = D_x(E_r(r_1)) + D_x(E_r(r_2)).$

C. Learning Algorithm

(Problems)

We have also noted that these individual losses by themselves do not entirely promote reasonable results in view of the fact that:

- 1) It is possible to obtain degenerate results such as $\hat{x}_1 \approx x$ and $\hat{x}_2 \approx 0$ or $\hat{x}_1 \approx 0$ and $\hat{x}_2 \approx x$ by using these loss functions alone.
- It is also possible to obtain results where a portion of the content of the X-ray image from one side appears in the X-ray image of the other side (and vice versa).

C. Learning Algorithm

4.
$$L_4 = \|\hat{x}_1\|_F^2 + \|\hat{x}_2\|_F^2$$
.

$$L_5 = C^2(f_1, f_2), \tag{8}$$

where $C(f_1, f_2)$ denotes the Pearson correlation coefficient between f_1 and f_2 given by

$$C(f_1, f_2) = \frac{\sum (f_{v1} - \mu_1)(f_{v2} - \mu_2)}{\sqrt{\sum (f_{v1} - \mu_1)^2 \sum (f_{v2} - \mu_2)^2}}.$$
 (9)

C. Learning Algorithm

$$L_{total} = L_1 + \lambda_1 \cdot L_2 + \lambda_2 \cdot L_3 + \lambda_3 \cdot L_4 + \lambda_4 \cdot L_5,$$

Where $\lambda 1$, $\lambda 2$, $\lambda 3$ and $\lambda 4$ are the hyper-parameters corresponding to the losses L2, L3, L4 and L5, respectively.

Stochastic gradient descent (SGD) algorithm with the ADAM optimization strategy with learning rate 0.0001.

A. Datasets

• Ghent Altarpiece by Hubert and Jan van Eyck. This large, complex 15th-century polyptych altarpiece comprises a series of panels including panels with a composition on both sides that we use to showcase the performance of our algorithm on real mixed X-ray data.



A. Datasets

• Kitchen Scene with Christ in the House of Martha andn Mary by Diego Velzquez. This one-sided canvas painting was used to showcase the performance of algorithm on synthetically mixed X-ray data.





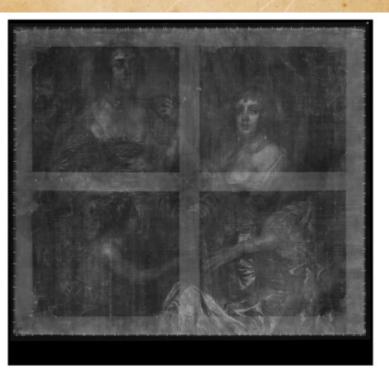
(a)



A. Datasets

• Lady Elizabeth Thimbelby and Dorothy, Viscountess Andover by Anthony Van Dyck. This canvas painting, also one-sided.





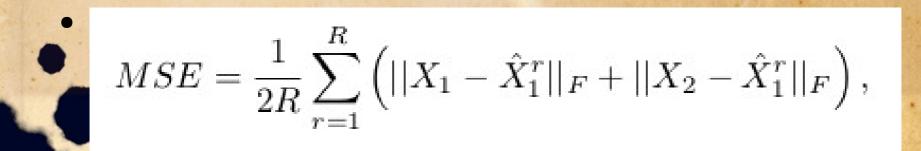
(a)

(b)

B. Hyper-parameter Selection Protocol

- First, we report results for the optimal values for the hyper-parameters $\lambda 1$ and $\lambda 2$ with the hyper-parameters $\lambda 3$ and $\lambda 4$ set to be equal to zero.
- Second, we report the results for the optimal values for the hyper-parameters $\lambda 3$ and $\lambda 4$ with the hyper- parameters $\lambda 1$ and $\lambda 2$ set to be equal to their optimal values from the first optimization step.
- $\lambda 1 \in [0, 10], \lambda 2 \in [0, 10], \lambda 3 \in [1, 10] \text{ and } \lambda 4 \in [0.1, 0.5]$ in steps of 0.2, 0.2, 0.2 and 0.02, respectively.

- C. Experiments with Synthetically Mixed X-ray Data
- Experiment set-up (Lady Elizabeth Thimbelby and Dorothy): Each such image is of size 1100 × 1100 pixels. These images were then further divided into patches of size 64×64 pixels with 56 pixels overlap (both in the horizontal and vertical direction), resulting in 11,236 patches.
- Random initialization.

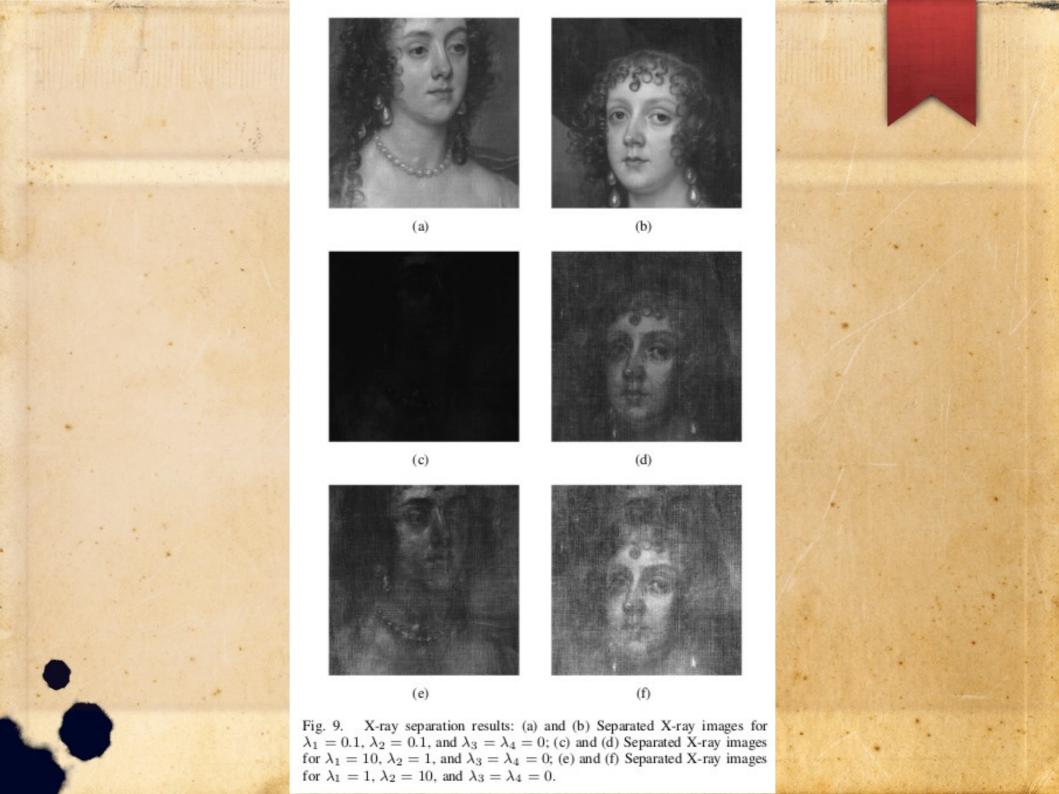


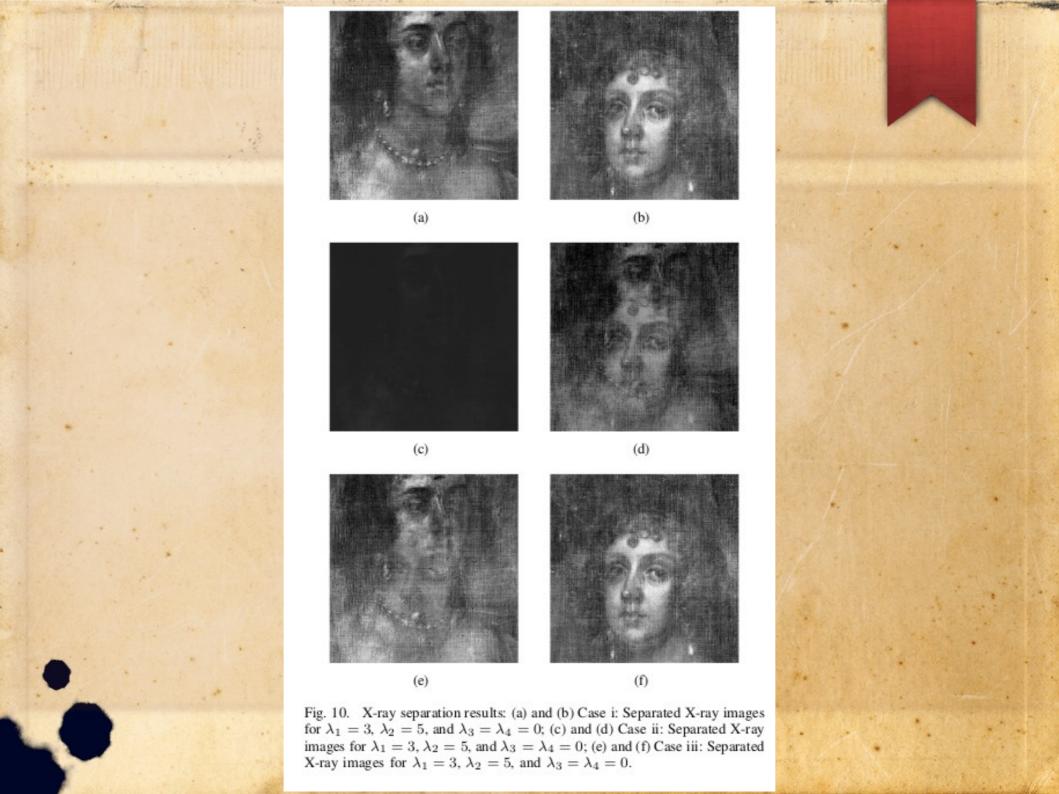
C. Experiments with Synthetically Mixed X-ray Data



Fig. 7. Images used for hyper-parameter selection. (a). First RGB image. (b). Second RGB image. (c). X-ray image corresponding to first RGB image. (d). X-ray image corresponding to second RGB image. (e). Synthetically mixed X-ray image.







- C. Experiments with Synthetically Mixed X-ray Data
- Experiment set-up (Kitchen Scene with Christ in the House of Martha andn Mary) The images which are of size 1000 × 1000 pixels were divided into patches of size 64 × 64 pixels with 56 pixels overlap (both in the horizontal and vertical direction), resulting in 13,924 patches.

C. Experiments with Synthetically Mixed X-ray Data

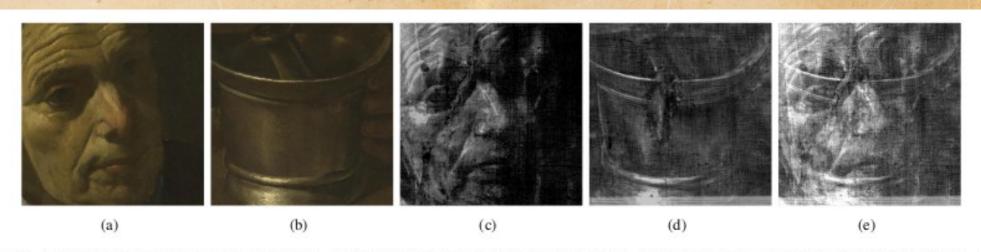


Fig. 13. Images used for synthetic data experiments. (a). First RGB image. (b). Second RGB image. (c). X-ray image corresponding to first RGB image. (d). X-ray image corresponding to second RGB image. (e). Synthetically mixed X-ray image.



C. Experiments with Synthetically Mixed X-ray Data

• Best results: $\lambda 1 = 3$, $\lambda 2 = 5$, $\lambda 3 = 2$, and $\lambda 4 = 0.3$.

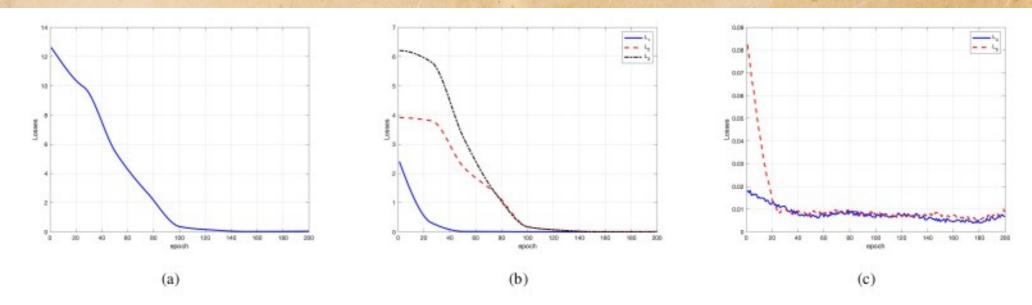


Fig. 14. Losses vs. number of epochs on synthetic data. (a). Ltotal. (b). L1, L2 and L3. (c). L4 and L5.



Fig. 15. Reconstructed images vs. number of epochs on synthetic data experiments. Columns 1 to 7 correspond to reconstructed result under 1st, 4th, 10th, 50th, 100th, 150th and 200th epoch, respectively. Rows 1 to 2 correspond to the reconstructed RGB images. Rows 3 to 4 correspond to the reconstructed X-ray images.

D. Experiments with Real Mixed X-ray Data

- **Set-up:** In this experiment, we use a small area of size1000 × 1000 pixels from the Ghent Altarpiece. The previous procedure was again followed: the two RGB images and the corresponding mixed X-ray image were divided into patches of size 64×64 pixels with 56 pixels overlap (both in the horizontal and vertical direction), resulting in 13,924 patches.
- Once again, hyper-parameter values $\lambda 1 = 3$, $\lambda 2 = 5$, $\lambda 3 = 2$, and $\lambda 4 = 0.3$.

D. Experiments with Real Mixed X-ray Data

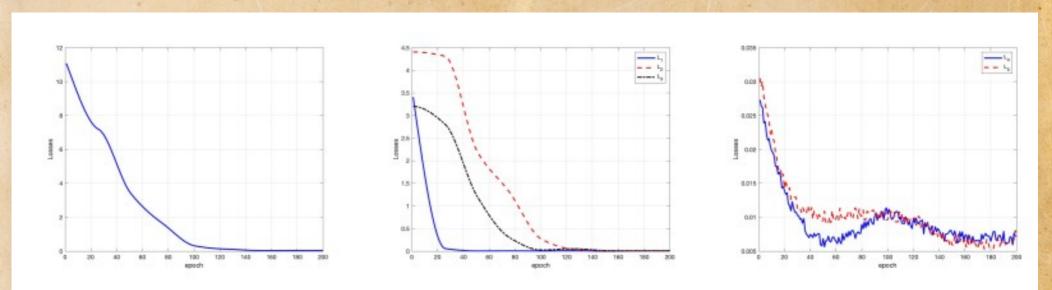


Fig. 18. Losses vs. number of epochs on real data experiments. (a). Ltotal. (b). L1, L2 and L3. (a). L4 and L5.



Fig. 19. Reconstructed images vs. number of epochs on real data experiments. Columns 1 to 7 correspond to reconstructed result under 1st, 4th, 10th, 50th, 100th, 150th and 200th epoch, respectively. Rows 1 to 2 correspond to the reconstructed RGB images. Rows 3 to 4 correspond to the reconstructed X-ray images.

V. CONCLUSION

- Improvement the utility of X-ray images in studying and conserving artworks.
- This approach allows image separation without the need for labelled data.
- The results from this image separation also maintain features of the support, such as wood grain and canvas weave, that are not readily apparent in the RGB images



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