

```
1 from machine import Pin
2 from XRPLib.encoded_motor import EncodedMotor
3 import time
4
5
6
7 LED = Pin("LED", Pin.OUT)
8
9 LED.value(1)
10
11 motor = EncodedMotor.get_default_encoded_motor(4)
12 motor.set_effort(1)
13 time.sleep(5)
14 motor.set_effort(0)
15
```