

Learning Agent

Introduction

Masayu Leylia Khodra
IF-ITB



http://mmp.kaist.ac.kr/ra_machine_learning.html

Kuliah Sebelumnya

■ Percepts used to get solution (acting)

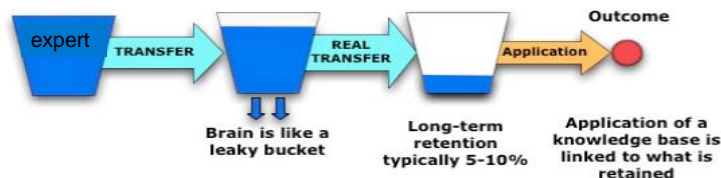
- Problem Solving Agent
 - Design: formulate problem → search solution → execute
- Knowledge-based Agent
 - Design: knowledge base + inference engine
 - Manual knowledge acquisition: elicitation + representation

MLK/IF-ITB/2010

3

Knowledge Acquisition Bottleneck

- Knowledge elicitation:
 - slow speed
 - Inability of expert to express the knowledge they possess
- Knowledge representation: **knowledge mismatch**
 - Perbedaan struktur pengetahuan pakar dan struktur pengetahuan program



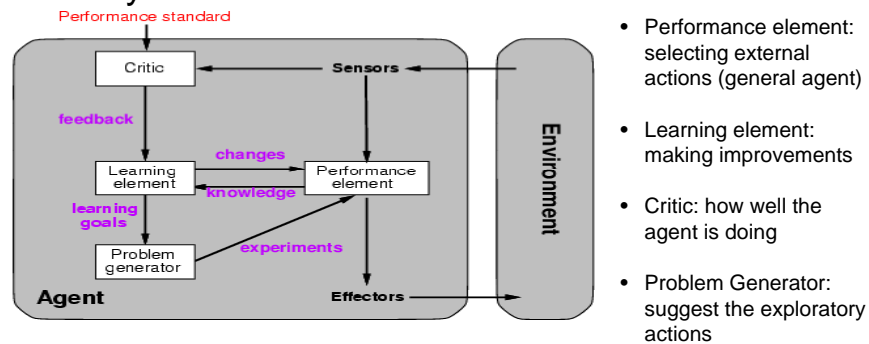
<http://www.profoundlearning.com/Content/EducationSolutions/educationKnowledgeTransfer.html>

MLK/IF-ITB/2010

4

Automatic Knowledge Acquisition

- Learning from observations
- Percepts also used for improving the agent's ability to act in the future



MLK/IF-ITB/2010

5

Learning from observations

- Learning: **changes** in the system that are **adaptive** in the sense that they enable the system to do the task or tasks drawn from the same population **more efficiently** and **more effectively** the next time.
 - Kemampuan yang penting agar dapat beroperasi pada lingkungan yang tidak diketahui → **lazy designers**
 - Berguna sebagai metode pembangunan sistem
 - Mengubah mekanisme pengambilan keputusan untuk memperbaiki performansi

MLK/IF-ITB/2010

6

Design of A Learning Element

- Which components of the performance element are to be learned
 - Type of performance element: reflex agent, logical agent, knowledge-based agent, ...
 - Component to be learned → learning goal
- What feedback is available to learn these components → supervised, unsupervised, reinforcement
- What representation is used for the components → learning algorithm
- Availability of prior knowledge

MLK/IF-ITB/2010

7

Learning Type

- **Supervised learning:**
 - Diberikan: set of example, correct answers for each example (example label) → I/O pairs
 - Prediksi output dari input baru
- **Unsupervised learning:**
 - Diberikan: set of example, no labeling
 - Kelompokkan example ke “natural” clusters
- **Reinforcement learning:**
 - Agen: observasi → aksi {rewarded/punished}
 - Pilih aksi dgn memaksimalkan reward

MLK/IF-ITB/2010

8

Taxi Driver Agent



<http://www.gettyimages.com/detail/83988175/Stone>

- Brake decision: mapping condition-action rule
 - $f: \text{states} \rightarrow \text{boolean}$ (brake or not brake)
- Buses recognition: Infer the world from percepts
 - $f: \text{images} \rightarrow \text{boolean}$
- Good/bad traffic day recognition
- Desirable/undesirable behavior recognition from tip indication

MLK/IF-ITB/2010

9

Taxi Driver Agent: Feedback

- | | |
|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <ul style="list-style-type: none"> ■ Brake decision: <ul style="list-style-type: none"> □ Direct mapping: states \rightarrow boolean □ Feedback: instructor shouts □ Design: supervised learning ■ Buses recognition by seeing many camera images: <ul style="list-style-type: none"> □ Infer bus properties: image \rightarrow boolean □ Feedback: labeling bus images □ Design: supervised learning | <ul style="list-style-type: none"> ■ Good/bad traffic day recognition <ul style="list-style-type: none"> □ Develop own concepts □ No feedback □ Design: unsupervised learning ■ Behavior recognition by tip indication <ul style="list-style-type: none"> □ Feedback: tip from customer at the end of journey □ Design: reinforcement learning |
|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|

MLK/IF-ITB/2010

10

Supervised vs Unsupervised Learning ?

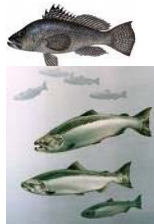


Supervised Learning

Fish Packing Plant

- Input:

- sea bass:
- Salmon

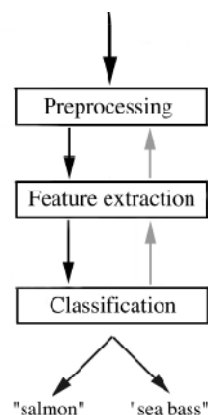


- Goal: automate sorting incoming fish on conveyor belt

MLK/IF-ITB/2010

13

Agent Pemisah Ikan



- Comp. of PE: fish classification
- Feedback: labeling fish
- Klasifikasi: model klasifikasi
 - Hasil supervised learning

MLK/IF-ITB/2010

14

Supervised Learning

- Learn a function from training data
- Input: training-set $\langle \text{data}, \text{label} \rangle \rightarrow \langle x, f(x) \rangle$
- Fungsi target learning: f
- Problem: find a **hypothesis** h s.t $h \approx f$
- Process: inductive learning
- Output: h (class description)
- Usage: classify unseen data based on class description

MLK/IF-ITB/2010

15

Data Set (Examples)

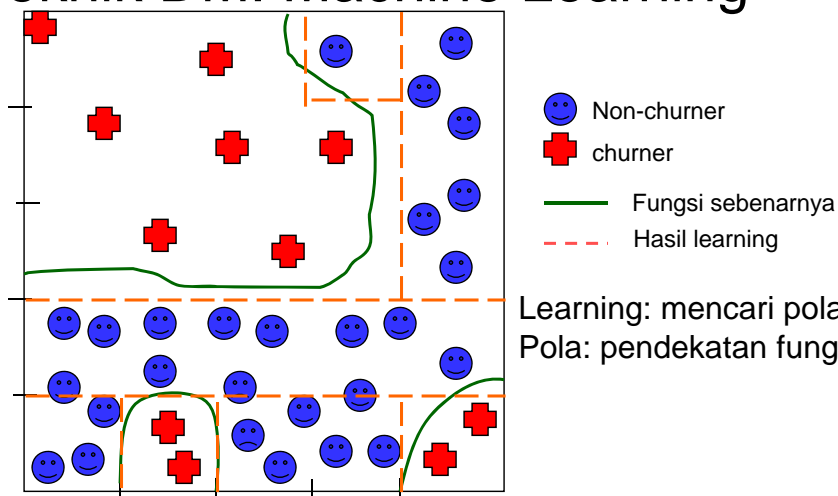
- Attribute-based representations
- Examples described by **attribute values**

Case	Age	Prescription	Astigmatism	Tear Production	Lens
1	young	myope	not astigmatic	reduced	none
2	young	myope	not astigmatic	normal	soft
3	young	myope	astigmatic	reduced	none
4	young	myope	astigmatic	normal	hard
5	young	hypermetrope	not astigmatic	reduced	none
6	young	hypermetrope	not astigmatic	normal	soft
7	young	hypermetrope	astigmatic	reduced	none
8	young	hypermetrope	astigmatic	normal	hard
9	pre-presbyopic	myope	not astigmatic	reduced	none
10	pre-presbyopic	myope	not astigmatic	normal	soft
11	pre-presbyopic	myope	astigmatic	reduced	none
12	pre-presbyopic	myope	astigmatic	normal	hard
13	pre-presbyopic	hypermetrope	not astigmatic	reduced	none
14	pre-presbyopic	hypermetrope	not astigmatic	normal	soft
15	pre-presbyopic	hypermetrope	astigmatic	reduced	none
16	pre-presbyopic	hypermetrope	astigmatic	normal	none
17	presbyopic	myope	not astigmatic	reduced	none
18	presbyopic	myope	not astigmatic	normal	none
19	presbyopic	myope	astigmatic	reduced	none
20	presbyopic	myope	astigmatic	normal	hard
21	presbyopic	hypermetrope	not astigmatic	reduced	none
22	presbyopic	hypermetrope	not astigmatic	normal	soft
23	presbyopic	hypermetrope	astigmatic	reduced	none
24	presbyopic	hypermetrope	astigmatic	normal	none

MLK/IF-ITB/2010

16

Teknik DM: Machine Learning



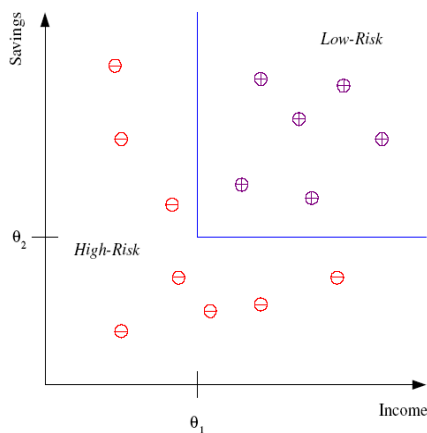
Learning: mencari pola
Pola: pendekatan fungsi

17

MLK/Churn Prediction

Credit Scoring

- Differentiating between **low-risk** and **high-risk** customers from their *income* and *savings*



Discriminant: IF *income* > θ_1 AND *savings* > θ_2

THEN **low-risk** ELSE **high-risk**

Based on Lecture Notes for E Alpaydin
2004 Introduction to Machine Learning
© The MIT Press (V1.1)

18

Inductive learning

Learn suatu fungsi dari contoh

An **example** is a pair $(x, f(x))$; f is the **target function**

Case	Age	Prescription	Astigmatism	Tear Production	Lens
1	young	myope	not astigmatic	reduced	none

x
 $f(x)$

Problem: find a **hypothesis** h such that $h \approx f$

This is a highly simplified model of real learning:

- ☐ Ignores prior knowledge
- ☐ Assumes examples are given)

MLK/IF-ITB/2010

19

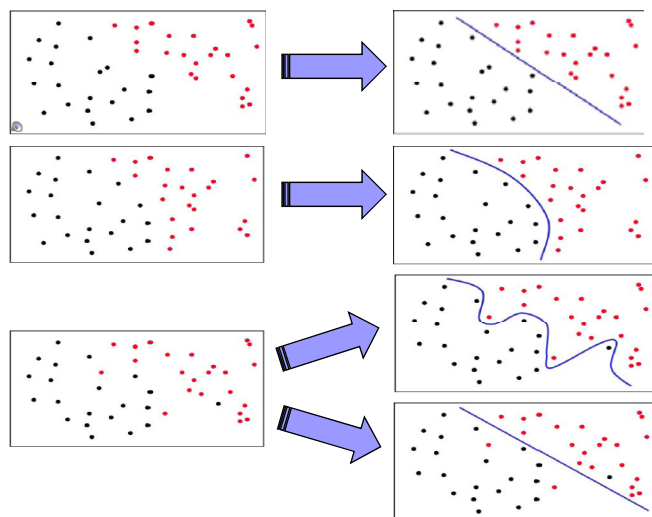
Inductive learning method

- Construct/adjust h to agree with f on training set
- (h is **consistent** if it agrees with f on all examples)
- Contoh: **curve fitting**

MLK/IF-ITB/2010

20

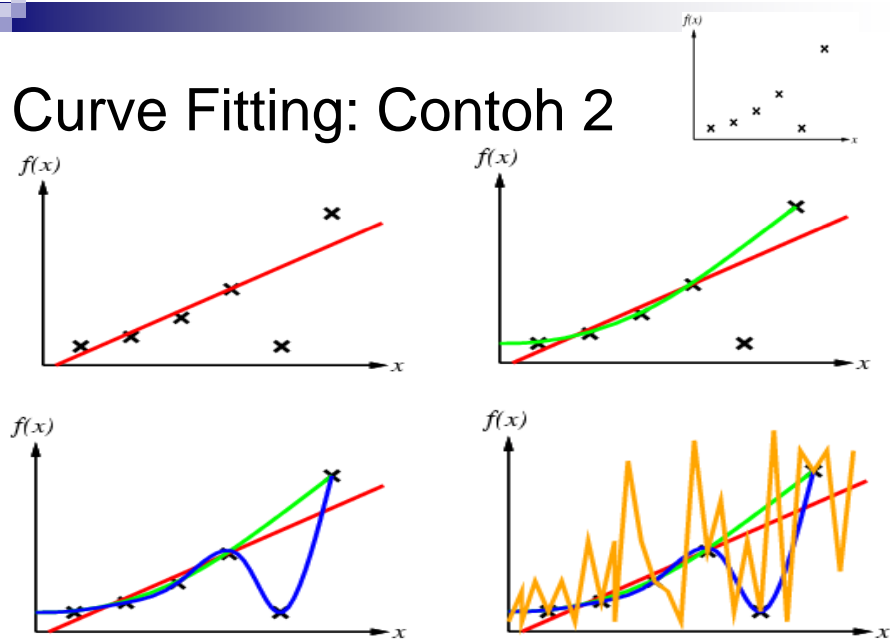
Curve Fitting: Contoh 1



MLK/IF-ITB/2010

21

Curve Fitting: Contoh 2



MLK/IF-ITB/2010

22

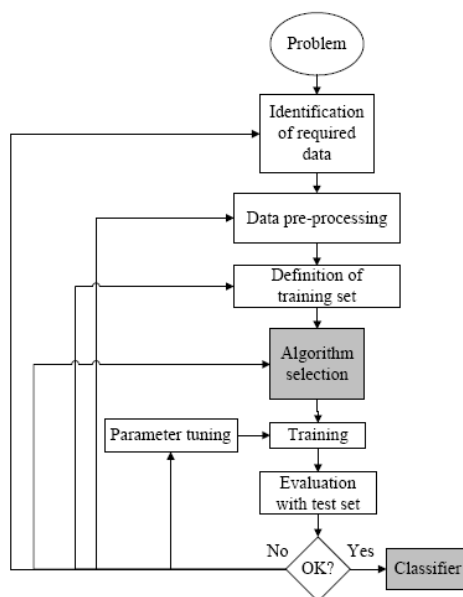
Inductive learning method

- Construct/adjust h to agree with f on training set
- (h is **consistent** if it agrees with f on all examples)
- **Ockham's razor:**
 - Pilih hipotesis yang paling sederhana yang konsisten dengan data

MLK/IF-ITB/2010

23

Supervised Learning Process

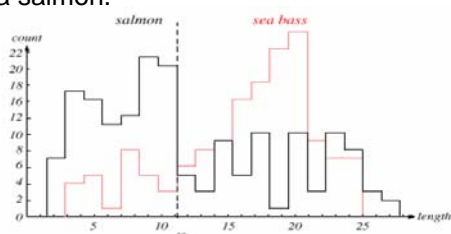


MLK/IF-ITB/2010

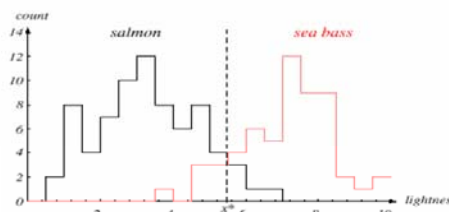
24

1 feature: Threshold Value

A sea bass is generally longer than a salmon.



Lightness is better feature to classify the fish.

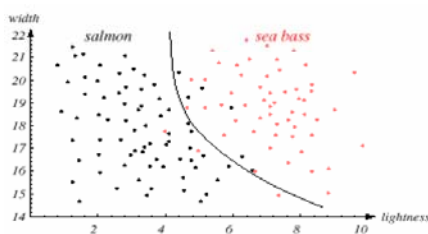
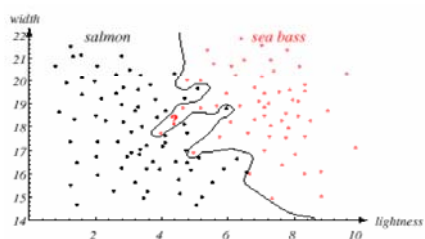


Poor performance
→ length is a poor feature

MLK/IF-ITB/2010

25

>1 Features: Decision Boundary



- Features: width, lightness
- Ideal decision boundary: 100% training accuracy
- Aim of classifier designing is to correctly classify novel input
- Need good generalization for future patterns
- Testing accuracy vs training accuracy

MLK/IF-ITB/2010

26

Applications for Supervised Learning

Given: Training examples $(\mathbf{x}; f(\mathbf{x}))$ for some unknown function f

Find: A good approximation to f .

Example Applications

- **Handwriting Recognition**
 - \mathbf{x} : Data from pen motion.
 - $f(\mathbf{x})$: Letter of the alphabet.
- **Disease diagnosis**
 - \mathbf{x} : Properties of patient (symptoms, lab tests)
 - $f(\mathbf{x})$: Disease (or maybe, recommended therapy)
- **Face recognition**
 - \mathbf{x} : Bitmap picture of person's face
 - $f(\mathbf{x})$: Name of the person.
- **Spam Detection**
 - \mathbf{x} : Email message
 - $f(\mathbf{x})$: Spam or not spam.

Based on Lecture Notes for E Alpaydin
2004 Introduction to Machine Learning
© The MIT Press (V1.1)

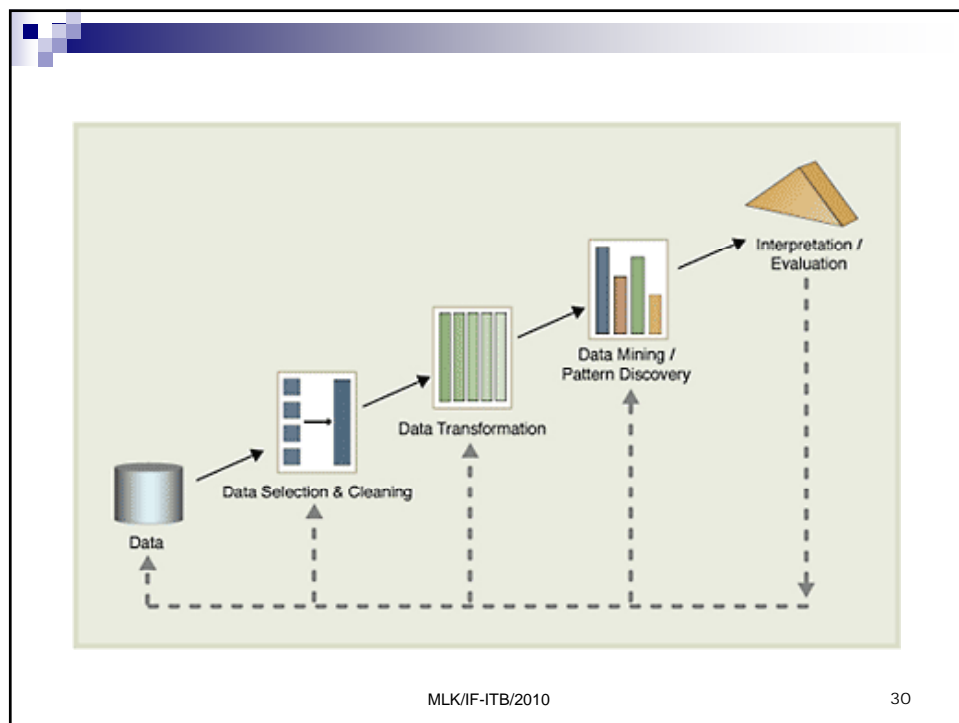
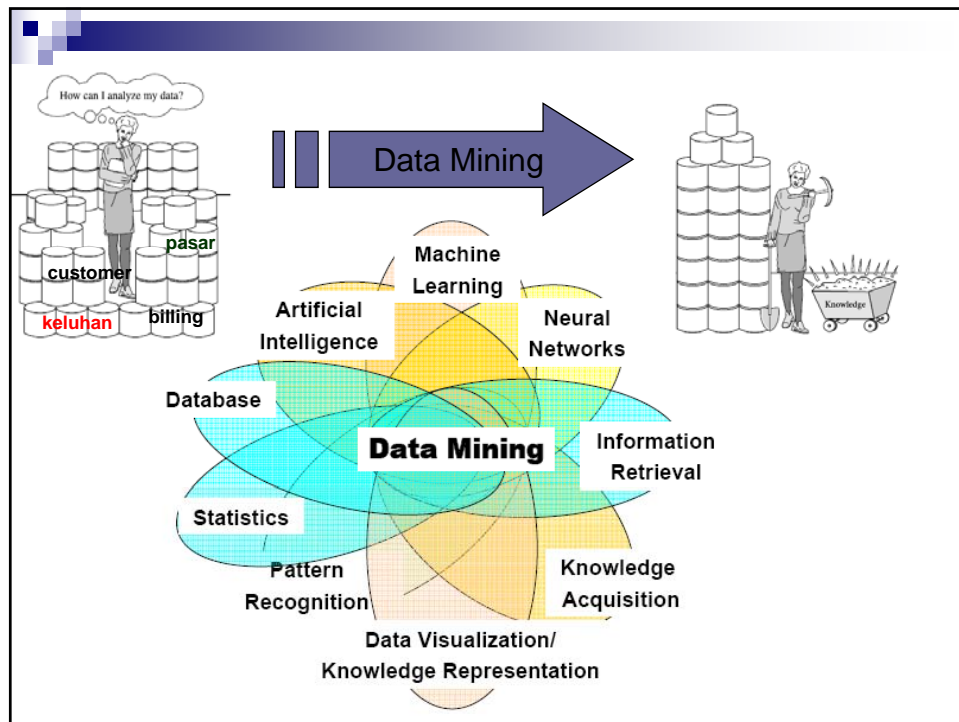
27

Applications for Supervised Learning

- **Situations where there is no human expert**
 - \mathbf{x} : Bond graph for a new molecule.
 - $f(\mathbf{x})$: Predicted binding strength to AIDS protease molecule.
- **Situations where humans can perform the task but can't describe how they do it.**
 - \mathbf{x} : Bitmap picture of hand-written character
 - $f(\mathbf{x})$: Ascii code of the character
- **Situations where the desired function is changing frequently**
 - \mathbf{x} : Description of stock prices and trades for last 10 days.
 - $f(\mathbf{x})$: Recommended stock transactions
- **Situations where each user needs a customized function f**
 - \mathbf{x} : Incoming email message.
 - $f(\mathbf{x})$: Importance score for presenting to user (or deleting without presenting).

Based on Lecture Notes for E Alpaydin
2004 Introduction to Machine Learning
© The MIT Press (V1.1)

28



Learning Method

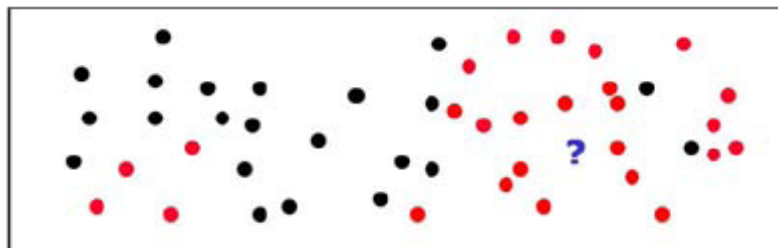
- Numeric/quantitative:
 - probabilistic classifier, linear classifier, SVM, regression, artificial neural network, Naïve Bayes
- Nonnumeric/symbolic:
 - Decision tree learning, decision rule classifier
- Example-based classifier:
 - k-Nearest Neighbor

MLK/IF-ITB/2010

31

K-Nearest Neighbor

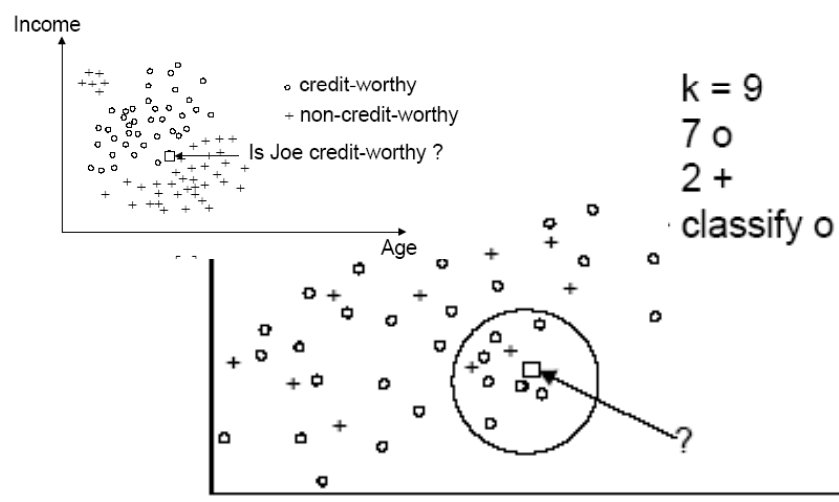
- Menyimpan semua data
- Input baru → kelas dari data terdekat



MLK/IF-ITB/2010

32

Contoh k-NN



MLK/IF-ITB/2010

33