

Introduction to Artificial Intelligence

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Introduction

What is AI? (Review)

1. Computational models of human behaviour? (Acting humanly)
 - ▶ Programs that behave (externally) like humans
2. Computational models of human “thought” processes? (Thinking humanly)
 - Programs that operate (internally) the way humans do
3. Computational systems that behave intelligently? (Thinking rationally)
 - What does it mean to behave intelligently?
4. Computational systems that behave rationally! (Acting rationally)
 - Later
- AI Applications: monitor ..., detect ..., schedule ...

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Agents

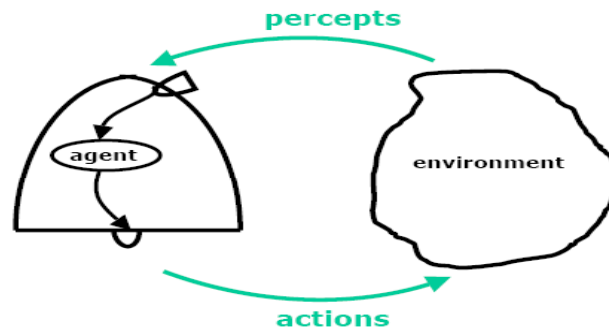
- ▶ Anything that can be viewed as **perceiving** its environment through **sensors** and **acting** upon that environment through **effectors**.
 - ▶ A robot
 - ▶ A factory
 - ▶ A web shopping program
 - ▶ ...
- ⇒ Computational agents that behave autonomously

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The Agent & the Environment

- ▶ How do we begin to formalize the problem of building an agent?
 - ▶ Make a dichotomy between the agent and the environment

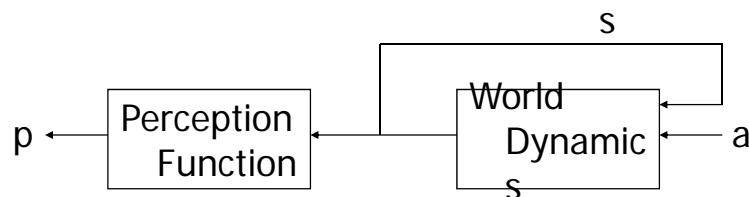


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World Model

- ▶ A – the action space
- ▶ P – the percept space
- ▶ Define:
 - ▶ S – internal state [may not be visible to agent]
 - ▶ Perception function: $S \rightarrow P$
 - ▶ World dynamics: $S \times A \rightarrow S$



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Agent Design

- ▶ U – utility function: $S \rightarrow \text{real}$ (or $S^* \rightarrow \text{real}$)
- ▶ The agent design problem: Find $P^* \rightarrow A$
 - ▶ mapping of sequences of percepts to actions
 - ▶ maximize the utility of the resulting sequences of states (each action maps from one state to next state)

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Rationality

- ▶ A rational agent takes actions it believes will achieve its goals.
 - ▶ Assume I don't like to get wet, so I bring an umbrella. Is that rational?
 - ▶ Depends on the weather forecast and whether I've heard it. If I've heard the forecast for rain (and I believe it) then bringing the umbrella is rational.
- ▶ Rationality \neq omniscience
 - ▶ Assume the most recent forecast is for rain but I did not listen to it and I did not bring my umbrella. Is that rational?
 - ▶ Yes, since I did not know about the recent forecast!
- ▶ Rationality \neq success
 - ▶ Suppose the forecast is for no rain but I bring my umbrella and I use it to defend myself against an attack. Is that rational?
 - ▶ No, although successful, it was done for the wrong reason.

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Limited Rationality

- ▶ There is a big problem with our definition of rationality ...
- ▶ The agent might not be able to compute the best action (subject to its beliefs and goals).
- ▶ So, we want to use limited rationality: “acting in the best way you can subject to the computational constraints that you have”.

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Limited Rationality (2)

- ▶ The (limited rational) agent design problem:
Find $P^* \rightarrow A$
 - ▶ mapping of sequences of percepts to actions
 - ▶ maximizes the utility of the resulting sequences of states
 - ▶ subject to our computational constraints

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Issues

- ▶ How could we possibly specify completely the domain the agent is going to work in?
 - ▶ If you expect a problem to be solved, you have to say what the problem is!
 - ▶ Specification is usually iterative: Build agent, test, modify specification
- ▶ We're going to map classes of environments and utilities to structures of programs that solve that class of problem.

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Thinking

- ▶ Is all this off-line work AI?
- ▶ Aren't the agents supposed to think?
- ▶ Why is it ever useful to think?
- ▶ If you can be endowed with an optimal table of reactions/reflexes ($P^* \rightarrow A$) why do you need to think?
- ▶ The table is too big! There are too many world states and too many sequences of percepts.
- ▶ In other domains, we'll take advantage of the fact that most things that could happen – don't. There's no reason to precompute reactions to an elephant flying in the window.

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Learning

- ▶ What if you don't know much about the environment when you start or if the environment changes?
 - ▶ Learn!
 - ▶ We're sending a robot to Mars but we don't know the coefficient of friction of the dust on the Martian surface.
 - ▶ I know a lot about the world dynamics but I have to leave a free parameter representing this coefficient of friction.
- ▶ Part of the agent's job is to use sequences of percepts to estimate the missing details in the world dynamics.
- ▶ Learning is not very different from perception, they both find out about the world based on experience.
 - ▶ Perception = short time scale (where am I?)
 - ▶ Learning = long time scale (what's the coefficient of friction?)

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THANK YOU