

AA1 – GCED

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A brief intro to resampling methods

The big question

You fit (*train*) a model to a data sample. How “good” is this solution? Can we estimate it?

We know that computing the error on the same data used for fitting the model (i.e., the **training error**) is in general wrong, because we can make the error optimistically small (overfitting).

Instead of a fitting error, we need a **prediction error**

What do we want?

What do we want?



Good predictions!!



Can we see the future?



Nooooooo!!



What do we do instead?



We re-sample!!



Tasks we need data for

In practice we have only **one** data sample and we need to do three different tasks, which require different (actually, independent) data samples. These tasks are:

1. fit/train models to data (“calculation of the model’s parameters”)
2. if several candidate models are available, choose the most promising one (“model selection”); also choose appropriate values for hyper-parameter(s)
3. estimate the error of the selected model as honestly as possible (“error estimation”)

Predictive error estimation (3)

There is only one universal way: use a separate data sample (called a **test sample**).

There are two options:

1. Wait to have more data, and see how well the model does. Not ideal in many contexts.
2. The **holdout** method: reserve some data for this purpose, do not use it until your model is trained. Use the held-out data to test the model.

Training and model selection (1+2)

For this we have at least two options.

- 1) Use a heuristic that combines the training errors obtained with some measure of the complexity of the model; one finds methods such as AIC and BIC; the former is typically used with GLMs; the latter is used with E-M for clustering, among others

There are many drawbacks:

- ▶ it is unclear how they behave for non-linear models,
- ▶ they do not provide with an estimation of the error (just an abstract quantity), and
- ▶ are only crude approximations

... so we won't pursue them further; however, they find their place in some cases

Training and model selection (1+2) cont.

- 2) Use a resampling strategy: divide the data into parts for fitting the models (**training**) and parts for making them predict (**validation**). The general form is called **cross-validation**, of which **LOOCV** is a particular case.

The **average cross-validation error** is typically used for **model selection**.

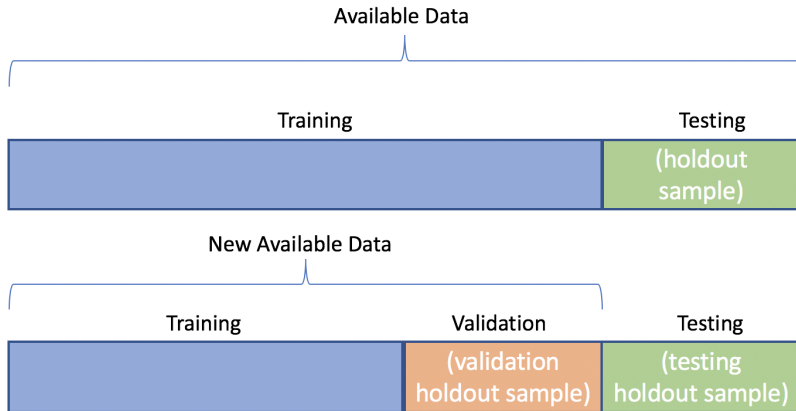
When we have selected a model, we refit it on the full data available for **learning (training + validation)** and use the final model to predict the **test** set and consequently estimate its generalization error.

Resampling strategies

We will cover the following strategies, with increasing level of sophistication:

- ▶ train/val split
- ▶ Monte-Carlo cross-validation
- ▶ k-fold cross-validation
- ▶ LOOCV (leave-one-out cross-validation)
- ▶ Iterated k-fold cross-validation

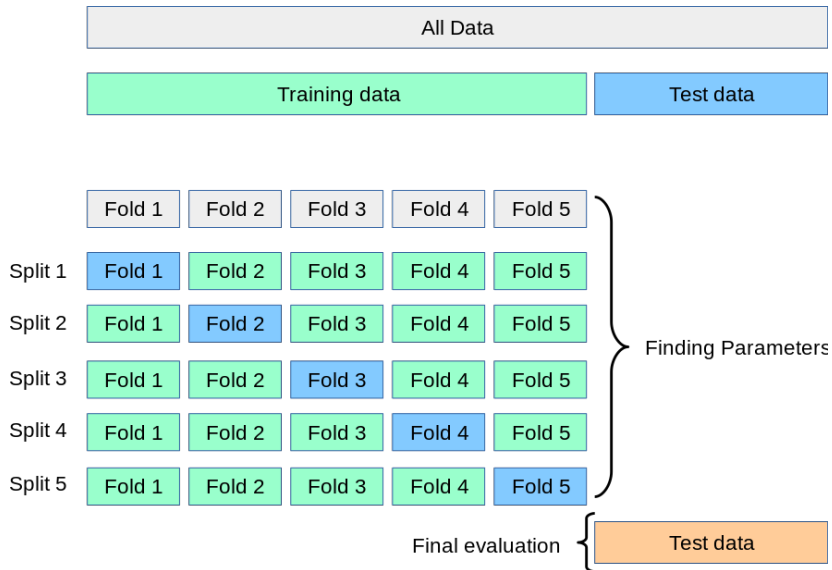
Train/Val split, Monte-Carlo cross-validation



Train/Val split, Monte-Carlo cross-validation (cont.)

- ▶ Partition should be **randomized** (care should be taken with non iid data such as time-series!)
- ▶ Ideally **stratified**
- ▶ Typical default percentages train/val/test: 50/25/25 however largely dependent on dataset dimension and learning algorithm
- ▶ **Method of choice** if lots of data are available
- ▶ Sensitive to split so in **Monte-Carlo cross-validation**, repeat process of split into training + validation several times and report average performance

k-fold cross-validation



k-fold cross-validation (cont.)

- ▶ $2 \leq k \leq n$, where n is the size of training data
- ▶ When $k = n$, then this is called *leave-one-out cross-validation* or **loocv**
- ▶ Method of choice for tuning hyper-parameters and model selection, namely: keep model + hyperparameters that minimize cross-validation error (i.e. mean error over all folds)
- ▶ Ideally **stratified**, necessarily **randomized**
- ▶ Still sensitive to partition, so if computational resources permit it, iterate cross-validation, and minimize average cross-validation error, typical values are 10x10 cross-validation
- ▶ For loocv, iteration is obviously not needed
- ▶ Popular choices are **5 cv** or **10 cv**, **10x10 cv** and **loocv**

Typical machine learning experimental protocol

1. Split data into two parts: **training** and **test** sets. *Reserve the test set and do not look at it until the end.*
2. Use resampling technique of your choice on your training set for model selection.
3. Build final model by re-training on the whole training set using optimal hyper-parameters and modelling technique from step 2.
4. Estimate error of final model on **test set** reserved in step 1.

Typical machine learning experimental protocol, visually

