

# Block I

# Definitions

**1. Discrete dynamical systems**
**Dynamical system**

Let:

·  $M$  manifold

·  $(T, +)$  monoid

·  $\phi : T \times M \rightarrow M$

Then,  $(M, T, \phi)$  is a dynamical system if:

·  $\forall x \in X:$

·  $\phi(x, 0) = x$

·  $\forall t_1, t_2 \in T:$

·  $\phi(\phi(x, t_1), t_2) = \phi(x, t_1 + t_2)$

**Discrete**

Let:

·  $(M, T, \phi)$  dynamical system

Then,  $(M, T, \phi)$  is discrete if:

·  $T \simeq \mathbb{N}$

## Dimension

Let:

·  $(M, T, \phi)$  dynamical system

We name dimension of  $(M, T, \phi)$  to:

$\dim(M)$

We denote:

·  $\dim(M) = n : (M, T, \phi)$  n-D

## Functional

Let:

·  $(M, T, \phi)$  discrete dynamical system

Then,  $(M, T, \phi)$  is functional if:

·  $T \subset \mathbb{N}$

·  $\exists f : M \rightarrow M:$

·  $\forall (t, x) \in T \times M:$

·  $\phi(t, x) = f^t(x)$

We denote:

·  $T = \mathbb{N} : (M, f)$  functional discrete dynamical system

·  $f \in \mathcal{C}^n(M) : (M, f) \in \mathcal{C}^n$

**Orbit**

Let:

·  $(M, f)$  functional discrete dynamical system

·  $x \in M$

We name orbit of  $x$  to:

$$\{f^n(x)\}_{n \in \mathbb{N}}$$

We denote:

·  $o(x)$

**Periodicity**

Let:

·  $(M, f)$  functional discrete dynamical system

·  $x \in M$

·  $m \in \mathbb{N}$

Then,  $x$  is a period  $m$  point if:

$$\cdot f^m(x) = x$$

We denote:

·  $\{x \in M \mid x \text{ period } 1 \text{ point} \} : \text{Fix}(f)$

## Stability

Let:

·  $(\mathbb{R}^n, f)$  functional dynamical system

·  $p \in \mathbb{R}^n$  period  $m$  point

Then,  $p$  is stable for  $f$  if:

·  $\forall \varepsilon \in \mathbb{R}^+$ :

·  $\exists \delta \in \mathbb{R}^+$ :

·  $\forall x \in B(p, \delta)$ :

·  $\forall n \in \mathbb{N}$ :

·  $f^{nm}(x) \in B(p, \varepsilon)$

Then,  $p$  is unstable if:

·  $p$  not stable

Then,  $p$  is attractive for  $f$  if:

·  $p$  stable

·  $\exists \varepsilon \in \mathbb{R}^+$ :

·  $\forall x \in B(p, \varepsilon)$ :

·  $f^{nm}(x) \xrightarrow{n} p$

Then,  $p$  is repulsive if:

·  $p$  attractive by  $f^{-1}$

**Attraction set**

Let:

- $(M, f)$  functional discrete dynamical system
- $x \in M$  attractive m-periodic point
- $o(x)$  orbit of  $x$

We name attraction set of  $o(x)$  to:

$$\{y \in M \mid \exists x' \in o(x) : f^{nm}(y) \xrightarrow{n} x'\}$$

We denote:

$$\cdot A(o(x))$$

**Multiplier**

Let:

- $(M, f)$   $\mathcal{C}^1$  functional discrete dynamical system
- $x \in M$

We name multiplier of  $x$  to:

$$m(x) = f'(x)$$

We denote:

- $|m(x)| = 1$  :  $x$  neutral point
- $|m(x)| = 1 \wedge f''(x) = 0$  :  $x$  feeble point

## Character

Let:

$\cdot (M, f)$  functional discrete dynamical system

We name fixed point character to:

$$\begin{array}{rcl} f : \text{Fix}(f) & \longrightarrow & \{-2, -1, 0, 1, 2\} \\ x & \longmapsto & \begin{cases} +2 & x \text{ repulsive} \\ +1 & x \text{ unstable} \\ 0 & * \\ -1 & x \text{ stable} \\ -2 & x \text{ attractive} \end{cases} \end{array}$$

We denote:

$$\cdot f : \chi_f$$

## Topological equivalence

Let:

$\cdot (M, f_1), (M, f_2)$  functional discrete dynamical systems

Then,  $(M, \mathbb{N}, f_1)$  is topologically equivalent to  $(M, \mathbb{N}, f_2)$  if:

$$\begin{array}{l} \cdot \text{Fix}(f_1) = \text{Fix}(f_2) \\ \cdot \forall x \in \text{Fix}(f_1): \\ \cdot \chi_{f_1}(x) = \chi_{f_2}(x) \end{array}$$

We denote:

$$\cdot (M, f_1) \sim (M, f_2)$$

**Bifurcation**

Let:

- $\{(M, f_\lambda)\}_{\lambda \in \Lambda}$  functional discrete dynamical systems
- $\lambda_0 \in \Lambda$

Then,  $\lambda_0$  is a bifurcation parameter if:

- $\forall \varepsilon \in \mathbb{R}^+$ :
- $\exists \lambda' \in B(\lambda_0, \varepsilon)$ :
- $(M, f_{\lambda'}) \not\sim (M, f_{\lambda_0})$

**Saddle-node bifurcation**

Let:

- $(M, \mathbb{N}, f_\lambda)_{\lambda \in \Lambda}$  functional discrete dynamical systems
- $\lambda_0 \in \Lambda$
- $x_0 \in M$

Then,  $\lambda_0$  is a saddle-node bifurcation value at  $x_0$  if:

- $x_0 \in \text{Fix}(f_{\lambda_0})$
- $x_0$  neutral point of  $f_{\lambda_0}$
- $\partial_\lambda f_\lambda(x_0) \neq 0$
- $\partial_{xx} f_\lambda(x_0) \neq 0$



### Pitchfork bifurcation

Let:

·  $(M, \mathbb{N}, f_\lambda)_{\lambda \in \Lambda}$  functional discrete dynamical systems

·  $\lambda_0 \in \Lambda$

·  $x_0 \in M$

Then,  $\lambda_0$  is Pitchfork bifurcation value at  $x_0$  if:

·  $x_0 \in \text{Fix}(f_{\lambda_0})$

·  $x_0$  neutral point of  $f_{\lambda_0}$

·  $\partial_\lambda f_\lambda(x_0, \lambda_0) = 0$

·  $\partial_{x^2} f_\lambda(x_0, \lambda_0) = 0$

·  $\partial_{\lambda x} f_\lambda(x_0, \lambda_0) \neq 0$

·  $\partial_{x^3} f_\lambda(x_0, \lambda_0) \neq 0$

**Period doubling bifurcation**

Let:

$$\cdot \Lambda \subset M$$

$$\cdot (M, \mathbb{N}, f_\lambda)_{\lambda \in \Lambda} \text{ functional discrete dynamical systems}$$

$$\cdot \lambda_0 \in \Lambda$$

$$\cdot x_0 \in M$$

Then,  $\lambda_0$  is Period doubling bifurcation value at  $x_0$  if:

$$\cdot \lambda_0 \text{ Pitchfork bifurcation value at } x_0 \text{ of } f^2$$

### Sarkovskii's order

We name Sarkovskii's order to:

$$\forall a, b \in \mathbb{N} \quad \begin{cases} a = 2^n a', b = 2^m b', 2^n \parallel a, 2^m \parallel b: \\ a <_s b \leftrightarrow \begin{cases} m < n & a' = b' = 1 \\ & a' = 1, b' \neq 1 \\ a' < b' & a' = b' \neq 1 \\ n < m & 1 \neq a' \neq b' \end{cases} \end{cases}$$

### Chaos

Let:

·  $(\mathbb{R}, \mathbb{N}, f)$  dynamical system

Then,  $(\mathbb{R}, \mathbb{N}, f)$  is chaotic if:

·  $\text{Fix}(f)$  dense in  $\mathbb{R}$

·  $\exists x \in \mathbb{R}$ :

·  $o(x)$  dense in  $\mathbb{R}$

·  $\forall x \in \mathbb{R}$ :

·  $\exists \varepsilon \in \mathbb{R}^+$ :

·  $\forall \delta \in \mathbb{R}^+$ :

·  $\exists \tilde{x} \in B(x, \delta)$ :

·  $\lim_n o(\tilde{x}) \notin B(\lim_n o(x), \varepsilon)$

## 2. Linear dynamical systems

### Linear

Let:

·  $(\mathbb{R}^n, f)$  euclidean functional dynamical system

Then,  $(\mathbb{R}^n, f)$  is linear if:

·  $\exists A \in \mathcal{M}_{n \times n}(\mathbb{R})$ :

·  $\forall x \in \mathbb{R}^n$ :

·  $f(x) = Ax$

**Invariant curve**

Let:

·  $\gamma$  differentiable curve

·  $p \in \mathbb{R}^n$

Then,  $\gamma$  is invariant if:

·  $\forall x \in \gamma^*:$

·  $o(x) \subset \gamma^*$

Then,  $\gamma$  is converges to  $p$  if:

·  $\forall x \in \gamma^*:$

·  $o(x) \xrightarrow{n} p$