block name 1

## 1. Linear dynamical systems

## Linear

Let:

 $\cdot$  ( $\mathbb{R}^n$ , f) euclidean functional dynamical system

Then,  $(\mathbb{R}^n, f)$  is linear if:

- $\cdot \exists A \in \mathcal{M}_{n \times n}(\mathbb{R}):$ 
  - $\cdot \ \forall \ x \in \mathbb{R}^n$ :
    - f(x) = Ax

## Invariant curve

Let:

- $\cdot\,\gamma$  differentiable curve
- $p \in \mathbb{R}^n$

Then,  $\gamma$  is invariant if:

- ·  $\forall x \in \gamma *$ :
  - $\cdot o(x) \subset \gamma *$

Then,  $\gamma$  is converges to  $p{\rm if:}$ 

- ·  $\forall x \in \gamma *$ :
  - $\cdot o(x) \xrightarrow{n} p$