block name 1

1. One-dimensional discrete dynamical systems

Dynamical system

Let:

- $\cdot\,M$ manifold
- $\cdot T$ monoid

$$\cdot \phi : M \times T \to M$$

Then, (M, T, ϕ) is a dynamical system if:

 $\cdot \quad \forall \ x \in X$:

$$\phi(x,0) = 0$$

 $\forall t_1, t_2 \in T$:

$$\phi(\phi(x,t_1),t_2) = \phi(x,t_1+t_2)$$

Dimension

Let:

 $\cdot \left(M,T,\phi \right)$ dynamical system

We name dimension of (M, T, ϕ) to:

$$\cdot \dim(M)$$

We denote:

$$\cdot \dim(M) = n \,:\, (M,T,\phi)$$
n-D dynamical system

block name 3

Discrete & Continuous

Let:

 $\cdot (M, T, \phi)$ dynamical system

Then, (M, T, ϕ) is discrete if:

 $\cdot \, T \stackrel{\scriptscriptstyle \subset}{\scriptscriptstyle \sim} \, \mathbb{N}$

Then, (M, T, ϕ) is continuous if:

 $T \subset \mathbb{R} \setminus T$ open