1. One-dimensional discrete dynamical systems

Dynamical system

Let:

- $\cdot\,M$ manifold
- $\cdot T$ monoid

$$\cdot \phi : M \times T \to M$$

Then, (M, T, ϕ) is a dynamical system if:

 $\cdot \quad \forall \ x \in X$:

$$\phi(x,0) = 0$$

 $\forall t_1, t_2 \in T$:

$$\phi(\phi(x,t_1),t_2) = \phi(x,t_1+t_2)$$

Dimension

Let:

 $\cdot \left(M,T,\phi \right)$ dynamical system

We name dimension of (M, T, ϕ) to:

$$\cdot \dim(M)$$

We denote:

 $\cdot dim(M) = n : (M, T, \phi)$ n-D dynamical system

Discrete & Continuous

Let:

 $\cdot (M, T, \phi)$ dynamical system

Then, (M, T, ϕ) is discrete if:

$$T \stackrel{\subseteq}{\sim} \mathbb{N}$$

Then, (M, T, ϕ) is continuous if:

$$T \subset \mathbb{R} \setminus T$$
 open

Defined by a function

Let:

 $\cdot (M, T, \phi)$ dynamical system

$$f: M \to M$$

Then, (M, T, ϕ) is a dynamical system defined by f if:

$$\cdot T$$
 = \mathbb{N}

$$\begin{array}{cccc} \phi : M \times \mathbb{N} & \longrightarrow & M \\ (x,n) & \longmapsto & f^n(x) \end{array}$$

We denote:

 (M, T, ϕ) dynamical system defined by $f: (M, \mathbb{N}, f)$

\mathbf{Orbit}

Let:

 (M, \mathbb{N}, f) functional dynamical system

$$\cdot x \in M$$

We name orbit of x to:

$$\cdot \{f^n(x)\}_{n \in \mathbb{N}}$$

We denote:

 $\cdot o(x)$

n-periodic point

Let:

 $\cdot \left(M, \mathbb{N}, f \right)$ functional dynamical system

 $\cdot x \in M$

 $\cdot n \in \mathbb{N}$

Then, x is a n-periodic point if:

$$f^n(x) = x$$

 $\cdot \quad \forall \ n' \in \mathbb{N} \quad \mathbf{n}' < n$:

$$f^{n'}(x) \neq x$$

We denote:

 $\cdot n = 1 : x \text{ fixed point}$

Attractive & Repulsive

Let:

 (M, \mathbb{N}, f) metrical dynamical system

 $\cdot x \in M$ m-periodic point

Then, x is attractive if:

 $\cdot \exists \mathcal{U} \subset M \text{ open } :$

 $\forall y \in \mathcal{U}$:

 $\exists N \in \mathbb{N}$:

 $\forall n \in \mathbb{N} \mid_{\mathbf{n}} n \geq N$:

$$f^{nm}(y) \in \mathcal{U}$$

Then, x is repulsive if:

 $\cdot \quad \forall \ \mathcal{U} \subset M \quad \mathbf{u} \ x \in \mathcal{U}$:

 $\forall y \in \mathcal{U}$:

 $\exists \ N \in \mathbb{N}$:

 $\forall n \in \mathbb{N} \mid_{\mathbf{n}} n \geq N$:

 $f^{nm}(x)\notin\mathcal{U}$

Attraction set

Let:

 $\cdot (M, \mathbb{N}, f)$ dynamical system

 $\cdot x \in M$ attractive m-periodic point

 $\cdot o(x)$ orbit of x

We name attraction set of x to:

$$\{y \in M \mid \exists x' \in o(x) : f^{nm}(y) \xrightarrow{n} x'\}$$

We denote:

 $\cdot A(x)$

Neutral point

Let:

 (M, \mathbb{N}, f) differentiable dynamical system

 $\cdot x \in M$

Then, x is a neutral point if:

$$f'(x) \in \{-1, 1\}$$

Feeble attractive & repulsive points

Let:

 $(M, \mathbb{N}, f) \mathcal{C}^3$ dynamical system

 $\cdot x \in M$

Then, x is feeble attractive point if:

- f'(x) = 1
- f''(x) = 0
- f'''(x) > 0

Then, x is feeble repulsive point if:

- f'(x) = 1
- f''(x) = 0
- f'''(x) < 0

Multiplier

Let:

 $(M, \mathbb{N}, f)\mathcal{C}^1$ dynamical system

 $\cdot x \in M$

We name multiplier of x to:

 $\cdot f'(x)$

Logistic

Let:

$$f: \mathbb{R} \to \mathbb{R}$$

 $\cdot (M, T, \phi)$ dynamical system defined by f

Then, (M, T, ϕ) is a logistic dynamical system if:

· $\exists a \in \mathbb{R}$:

$$\begin{array}{ccc}
f : \mathbb{R} & \longrightarrow & \mathbb{R} \\
x & \longmapsto & ax(1-x)
\end{array}$$

Chaos

Let:

$$f: \mathbb{R} \to \mathbb{R}$$

 $\cdot \left(M,T,\phi \right)$ dynamical system defined by f

Then, (M, T, ϕ) is chaotic if:

- $\cdot Fix(f)$ dense in \mathbb{R}
- $\cdot \quad \exists \ x \in \mathbb{R}$:

$$o(x)$$
 dense in \mathbb{R}

 $\cdot f$ sensibility of x_0

Sarkovskii's order

We name Sarkovskii's order to:

 $\cdot naming$

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We denote:

 $\cdot property : notation$

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