

Convergence_Poisson_FV5_SQUARE

January 26, 2019

```
In [6]: from IPython.display import display, Markdown
with open('PoissonProblemOnSquare.md', 'r') as file1:
    PoissonProblemOnSquare = file1.read()
with open('DescriptionFV5PoissonProblem.md', 'r') as file2:
    DescriptionFV5PoissonProblem = file2.read()
with open('CodeFV5PoissonProblem.md', 'r') as file3:
    CodeFV5PoissonProblem = file3.read()
with open('BibliographyFV5.md', 'r') as file4:
    BibliographyFV5=file4.read()
```

1 FV5 scheme for Poisson equation

```
In [7]: display(Markdown(PoissonProblemOnSquare))
```

1.1 The Poisson problem on the square

We consider the following Poisson problem with Dirichlet boundary conditions

$$\begin{cases} -\Delta u = f \text{ on } \Omega \\ u = 0 \text{ on } \partial\Omega \end{cases}$$

on the square domain $\Omega = [0, 1] \times [0, 1]$ with

$$f = 2\pi^2 \sin(\pi x) \sin(\pi y).$$

The unique solution of the problem is

$$u = \sin(\pi x) \sin(\pi y).$$

The Poisson equation is a particular case of the diffusion problem

$$-\nabla \cdot (D \vec{\nabla} u) = f$$

and the associated diffusion flux is

$$F(u) = D \nabla u,$$

where D is the diffusion matrix.

We investigate the particular case where D is the identity matrix.

```
In [8]: display(Markdown(BibliographyFV5))
```

1.2 Some bibliographical remarks

- Order 1 convergence on triangular meshes
R. Herbin, An error estimate for a four point finite volume scheme for the convection-diffusion equation on a triangular mesh, Num. Meth. P.D.E., 165-173, 1995.
- On triangular meshes, the FV5 scheme order is 2 provided
 - the center of the circumscribed circle is used instead of the center of mass in each cell
 - the Delaunay conditions are satisfied (no neighboring cell is included in the circumscribed circle of an arbitrary cell)
- Non convergence on highly deformed meshes
K. Domelevo, P. Omnes, A finite volume method for the Laplace equation on almost arbitrary 2D grids, Mathematical Modelling and Numerical Analysis, 2005
- The scheme is order 1 if the mesh is conforming except on a line
J. Droniou, C. Le Potier, Construction and Convergence Study of Schemes Preserving the Elliptic Local Maximum Principle, SIAM Journal on Numerical Analysis, 2011
- The scheme is order 2 if Delaunay type conditions, $f \in H^1$ and meshes are generated from an initial mesh either by subdivisions, symmetry or translation
J. Droniou, Improved L^2 estimate for gradient schemes and super-convergence of the TPFA finite volume scheme, 2018
- It is possible to converge with order 1 on the gradient, but only order 1 on the function ie there is no equivalent of the Aubin-Nitsche lemma in the finite volume context
P. Omnes, Error estimates for a finite volume method for the Laplace equation in dimension one through discrete Green functions. International Journal on Finite Volumes 6(1), 18p., electronic only, 2009

In [9] : `display(Markdown(DescriptionFV5PoissonProblem))`

1.3 The FV5 scheme for the Laplace equation

The domain Ω is decomposed into cells C_i .

$|C_i|$ is the measure of the cell C_i .

f_{ij} is the interface between two cells C_i and C_j .

s_{ij} is the measure of the interface f_{ij} .

d_{ij} is the distance between the centers of mass of the two cells C_i and C_j .

The discrete Poisson problem is

$$-\frac{1}{|C_i|} \sum s_{ij} F_{ij} = f_i,$$

where u_i is the approximation of u in the cell C_i ,

f_i is the approximation of f in the cell C_i ,

F_{ij} is a numerical approximation of the outward normal diffusion flux from cell i to cell j .

In the case of the scheme FV5, the flux formula are

$$F_{ij} = \frac{u_j - u_i}{d_{ij}},$$

for two cells i and j inside the domain,
and

$$F_{boundary} = \frac{u(x_f) - u_i}{d_{if}},$$

for a boundary face with center x_f , inner cell i and distance between face and cell centers d_{if}

In [10]: display(Markdown(CodeFV5PoissonProblem))

1.4 The script

```
#Discrétisation du second membre et extraction du nb max de voisins d'une cellule
=====
my_RHSfield = cdmath.Field("RHS_field", cdmath.CELLS, my_mesh, 1)
maxNbNeighbours=0#This is to determine the number of non zero coefficients in the sparse finite

for i in range(nbCells):
    Ci = my_mesh.getCell(i)
    x = Ci.x()
    y = Ci.y()

    my_RHSfield[i]=2*pi*pi*sin(pi*x)*sin(pi*y)#mettre la fonction definie au second membre de l
    # compute maximum number of neighbours
    maxNbNeighbours= max(1+Ci.getNumberOfFaces(),maxNbNeighbours)

# Construction de la matrice et du vecteur second membre du système linéaire
=====
Rigidite=cdmath.SparseMatrixPetsc(nbCells,nbCells,maxNbNeighbours)# warning : third argument is
RHS=cdmath.Vector(nbCells)
#Parcours des cellules du domaine
for i in range(nbCells):
    RHS[i]=my_RHSfield[i] #la valeur moyenne du second membre f dans la cellule i
    Ci=my_mesh.getCell(i)
    for j in range(Ci.getNumberOfFaces()):# parcours des faces voisines
        Fj=my_mesh.getFace(Ci.getFaceId(j))
        if not Fj.isBorder():
            k=Fj.getCellId(0)
            if k==i :
                k=Fj.getCellId(1)
            Ck=my_mesh.getCell(k)
            distance=Ci.getBarryCenter().distance(Ck.getBarryCenter())
            coeff=Fj.getMeasure()/Ci.getMeasure()/distance
            Rigidite.setValue(i,k,-coeff) # terme extradiagonal
        else:
            coeff=Fj.getMeasure()/Ci.getMeasure()/Ci.getBarryCenter().distance(Fj.getBarryCenter)
            #For the particular case where the mesh boundary does not coincide with the domain b
            x=Fj.getBarryCenter().x()
            y=Fj.getBarryCenter().y()
            RHS[i]+=coeff*sin(pi*x)*sin(pi*y)#mettre ici la condition limite du problème de Dirichlet
```

```

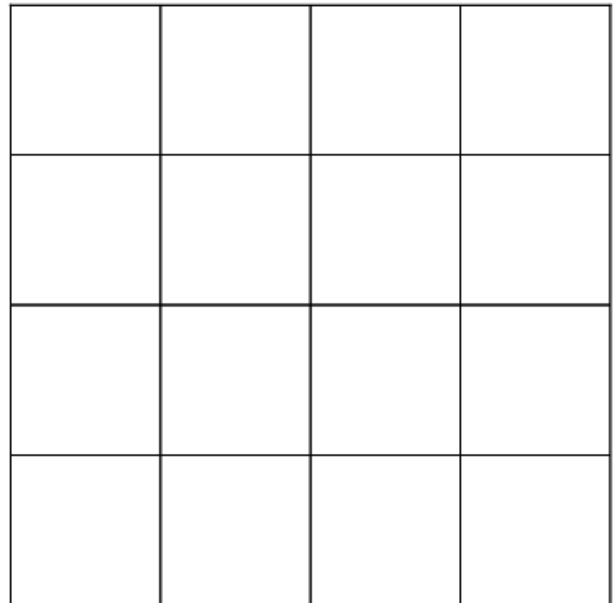
Rigidite.addValue(i,i,coeff) # terme diagonal

# Résolution du système linéaire
#=====
LS=cdmath.LinearSolver(Rigidite,RHS,500,1.E-6,"GMRES","ILU")
SolSyst=LS.solve()

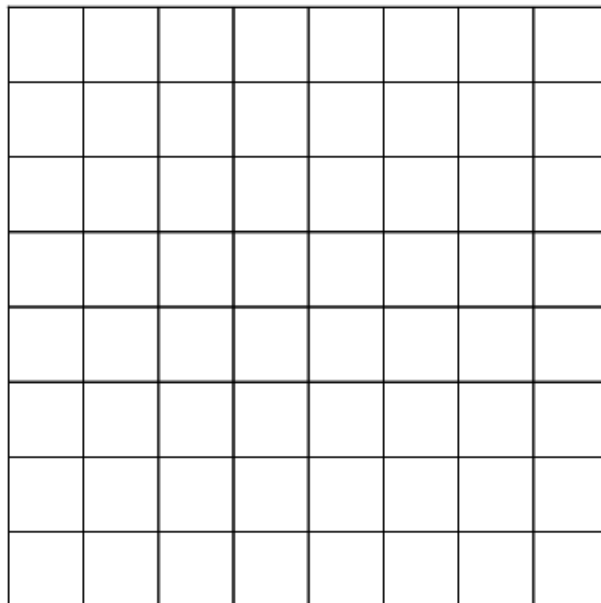
# Automatic postprocessing : save 2D picture and plot diagonal data
#=====
PV_routines.Save_PV_data_to_picture_file("my_ResultField_0.vtu","ResultField",'CELLS',"my_ResultField_0.vtu")
diag_data=VTK_routines.Extract_field_data_over_line_to_numpyArray(my_ResultField,[0,1,0],[1,0,0])
plt.plot(curv_abs, diag_data, label= str(nbCells)+ ' cells mesh')
plt.savefig("FV5_on_square_PlotOverDiagonalLine.png")

```

1.5 Regular grid

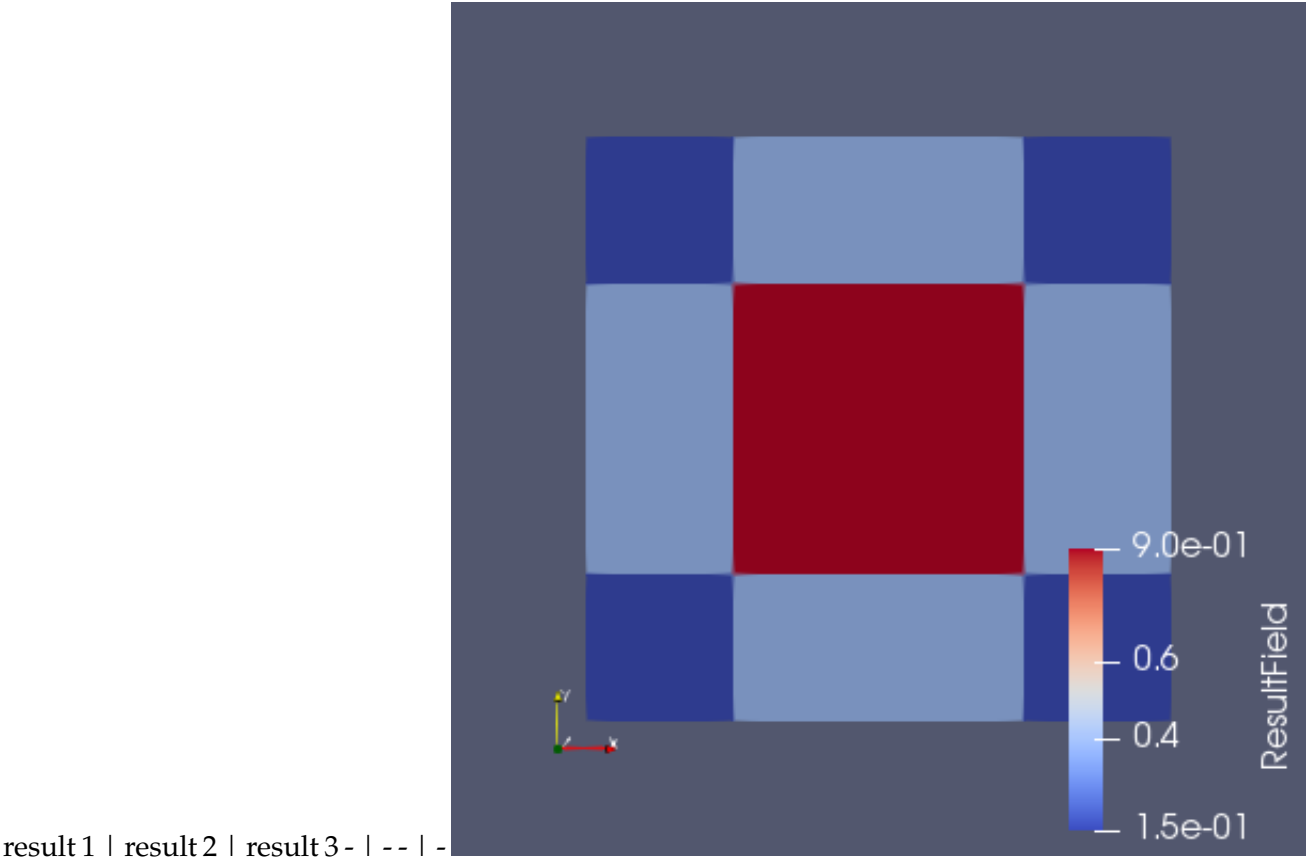
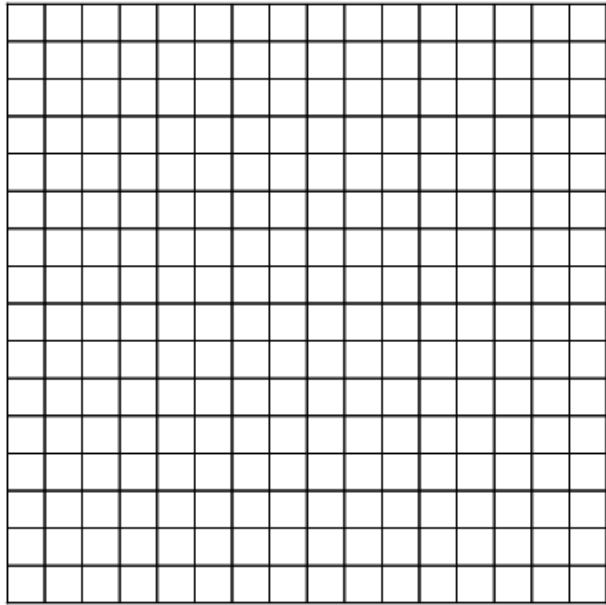


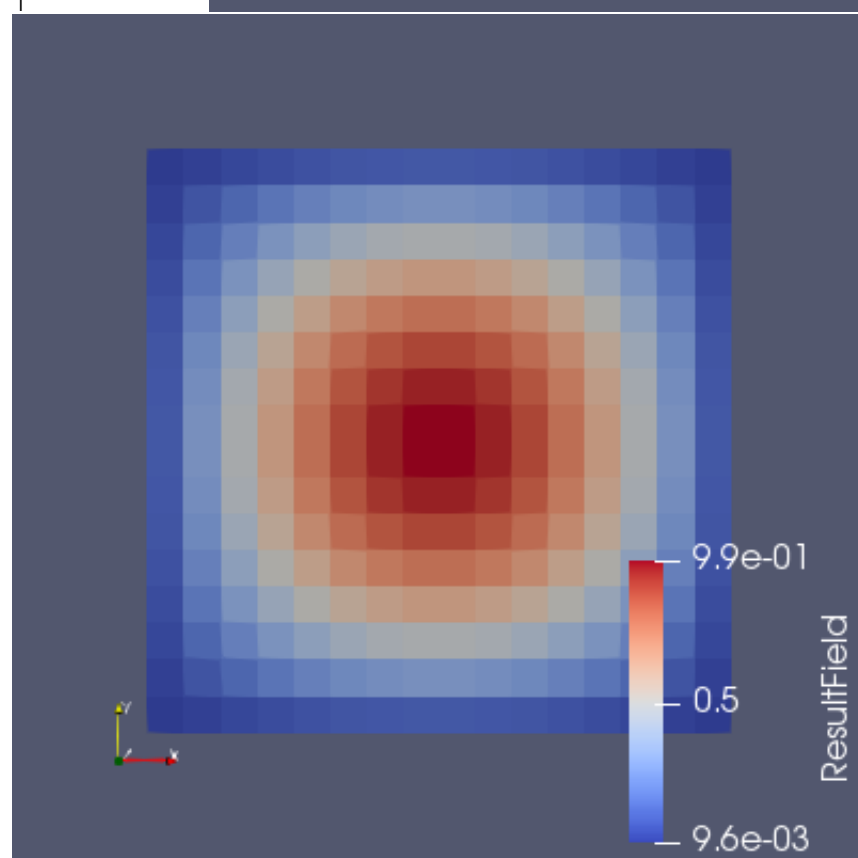
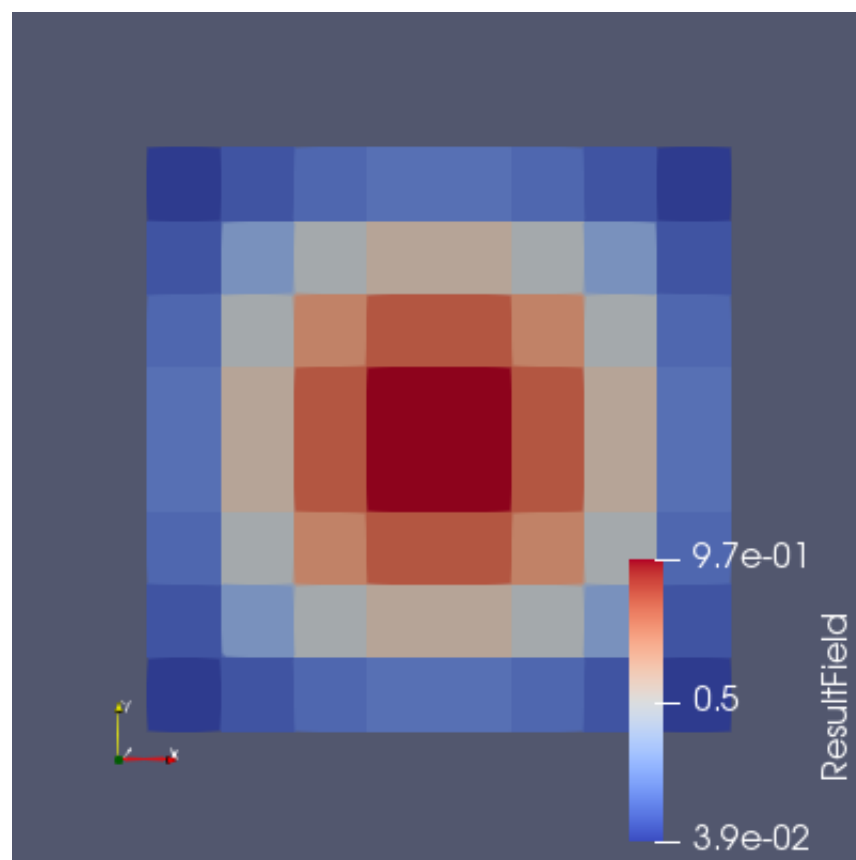
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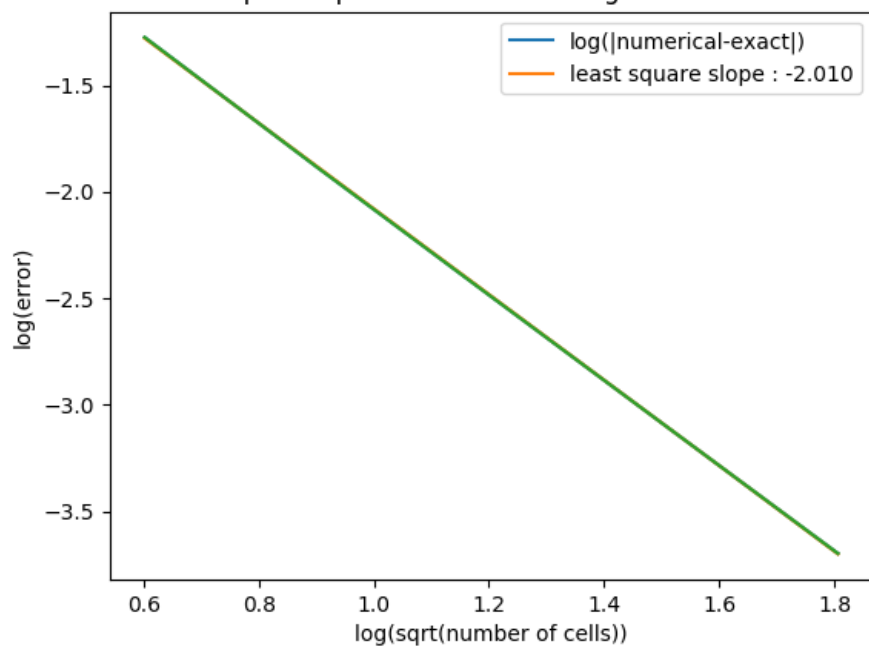
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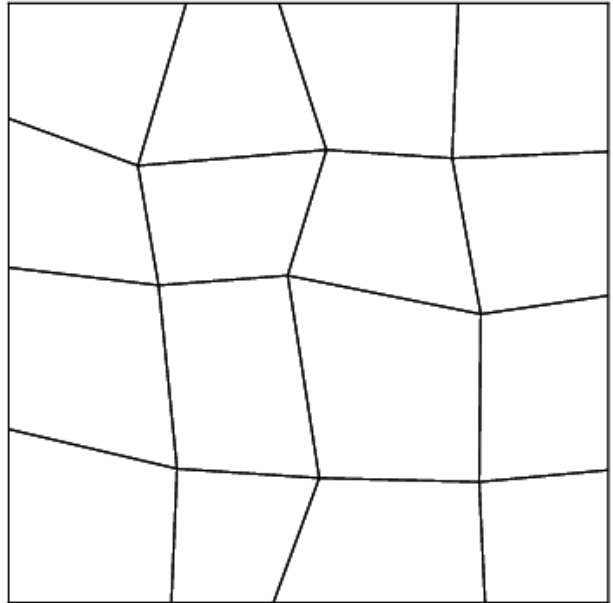




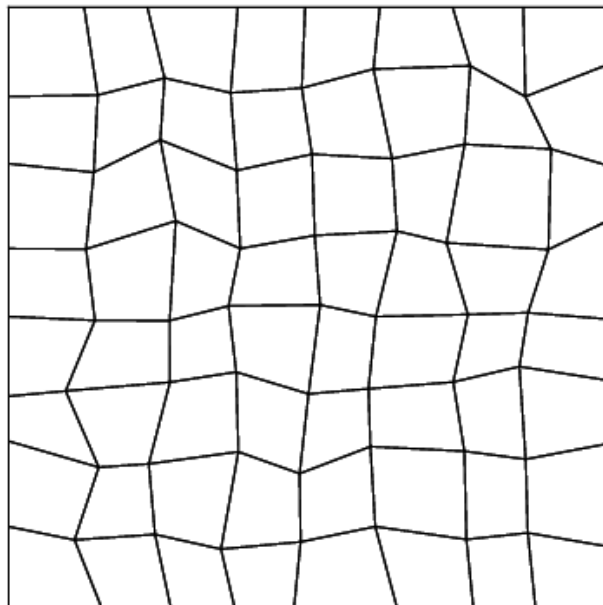
Convergence of finite volumes for
Laplace operator on 2D rectangular meshes



1.6 Deformed quadrangles

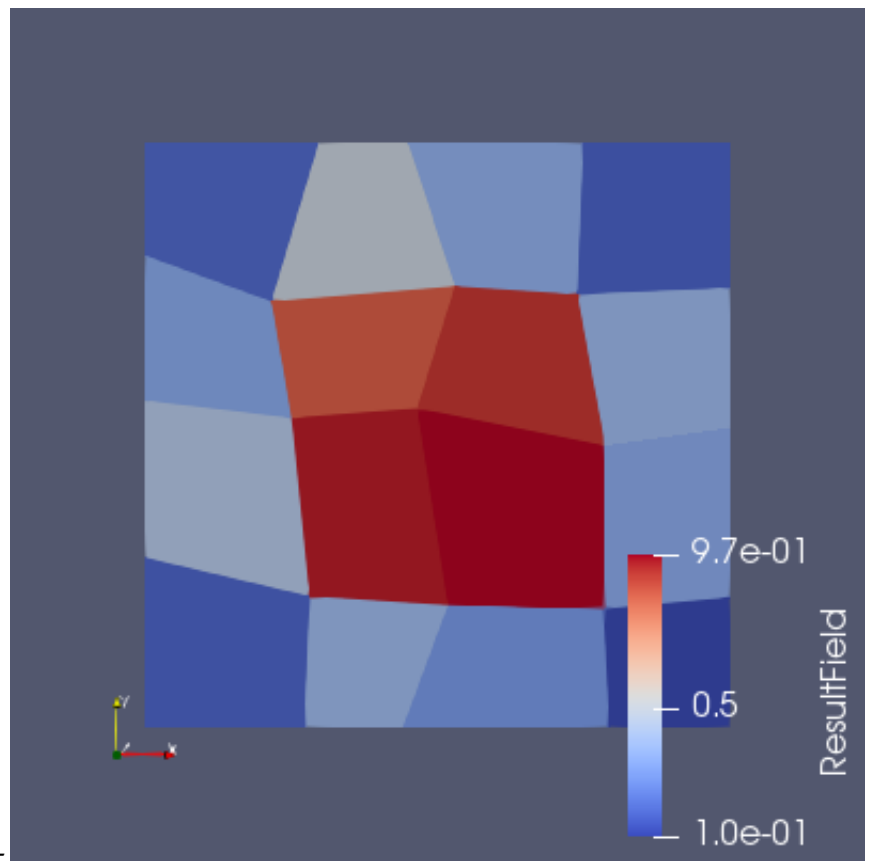
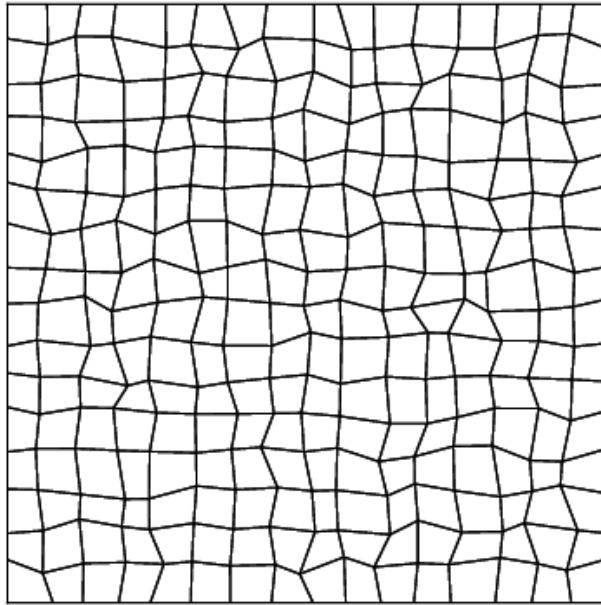


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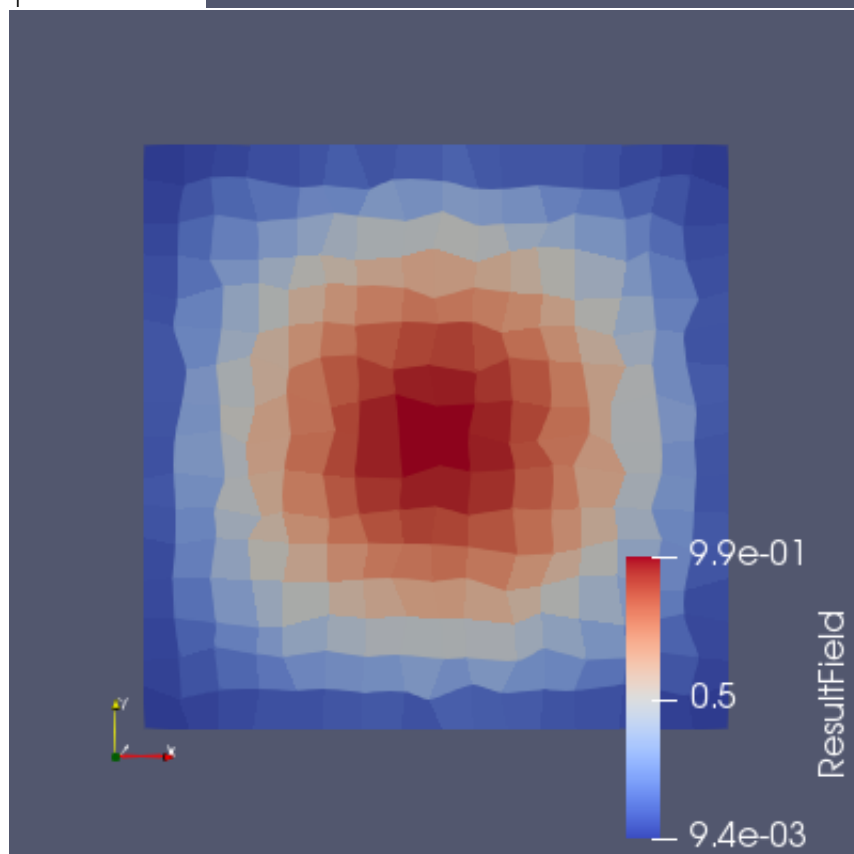
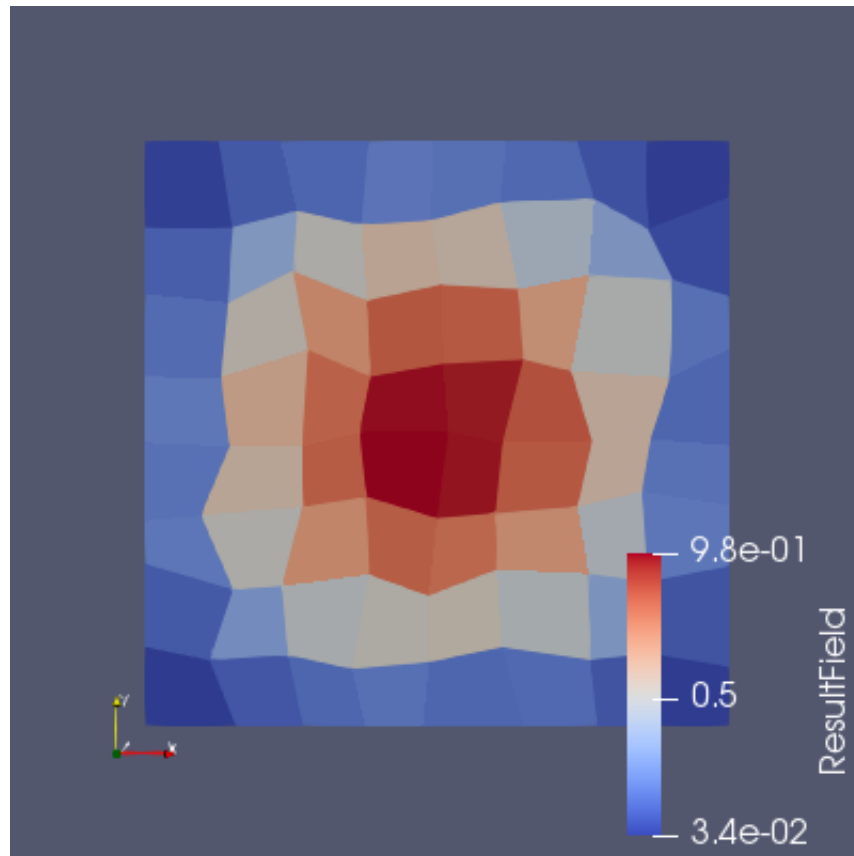


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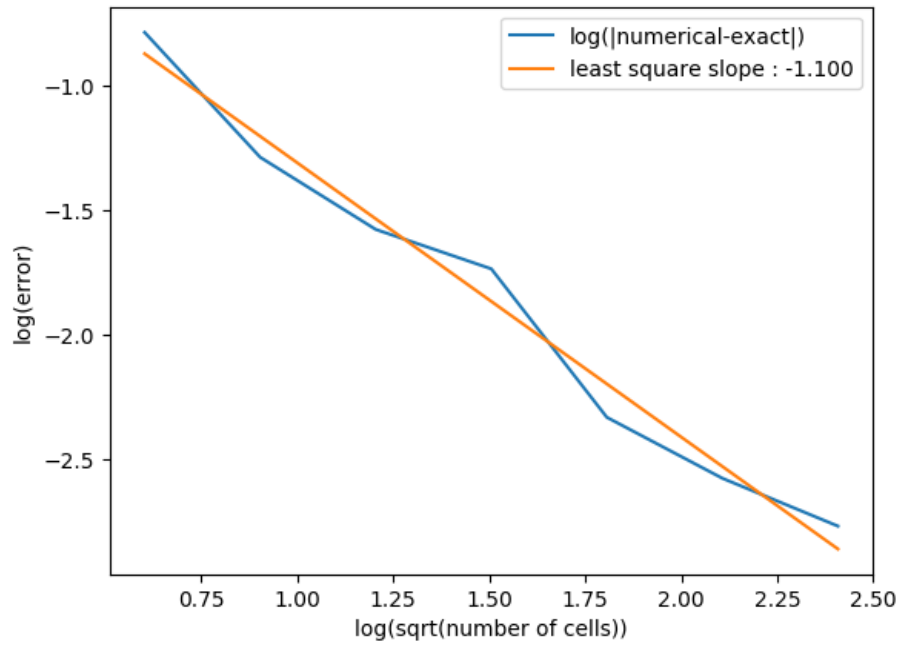
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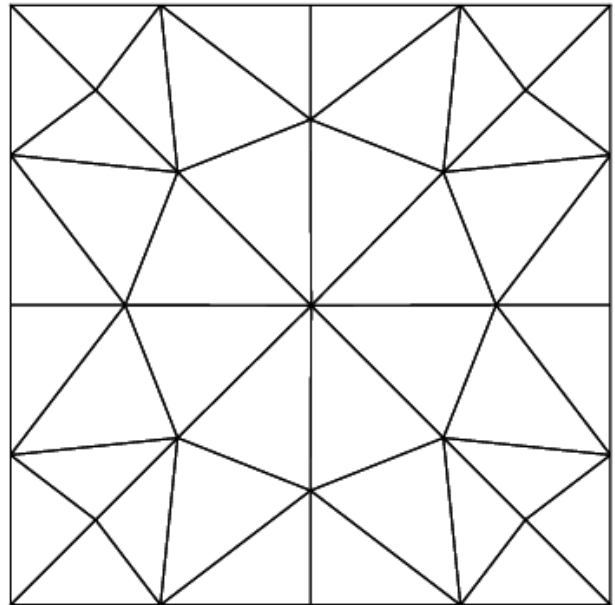
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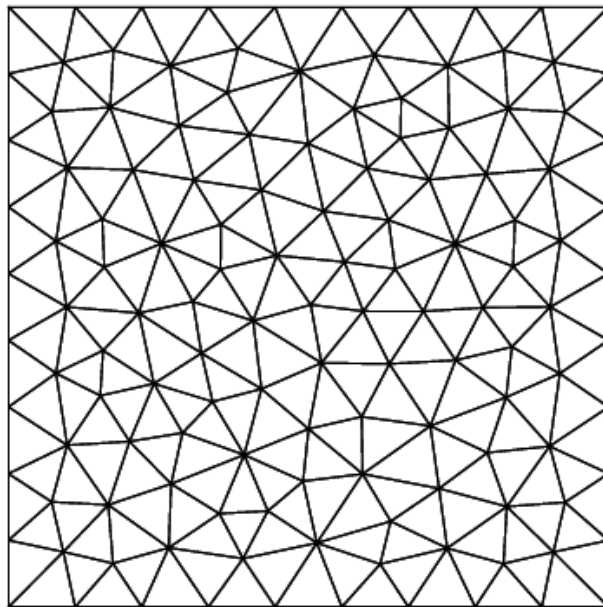
Convergence of finite volumes
for Laplace operator on a 2D deformed quadrangles meshes



1.7 Delaunay triangular meshes

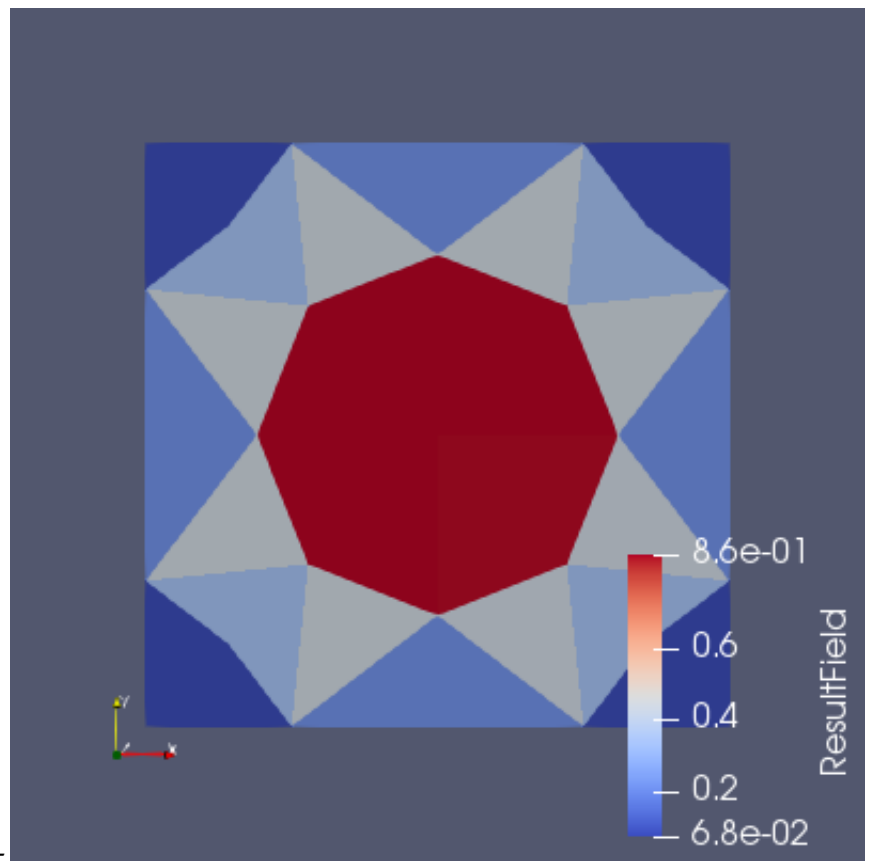
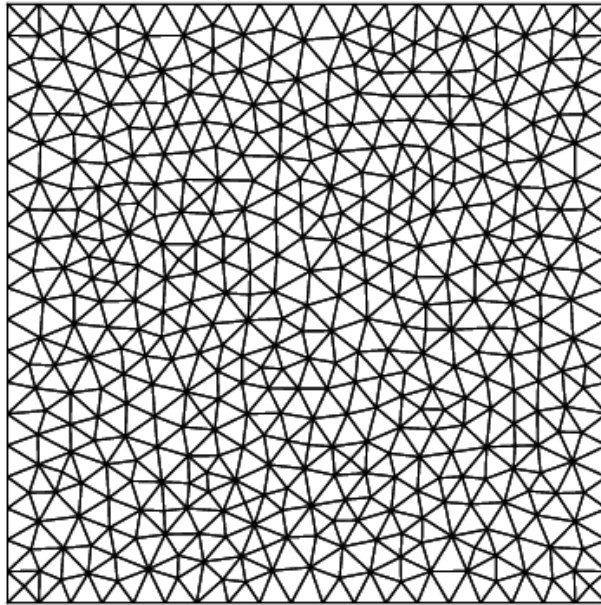


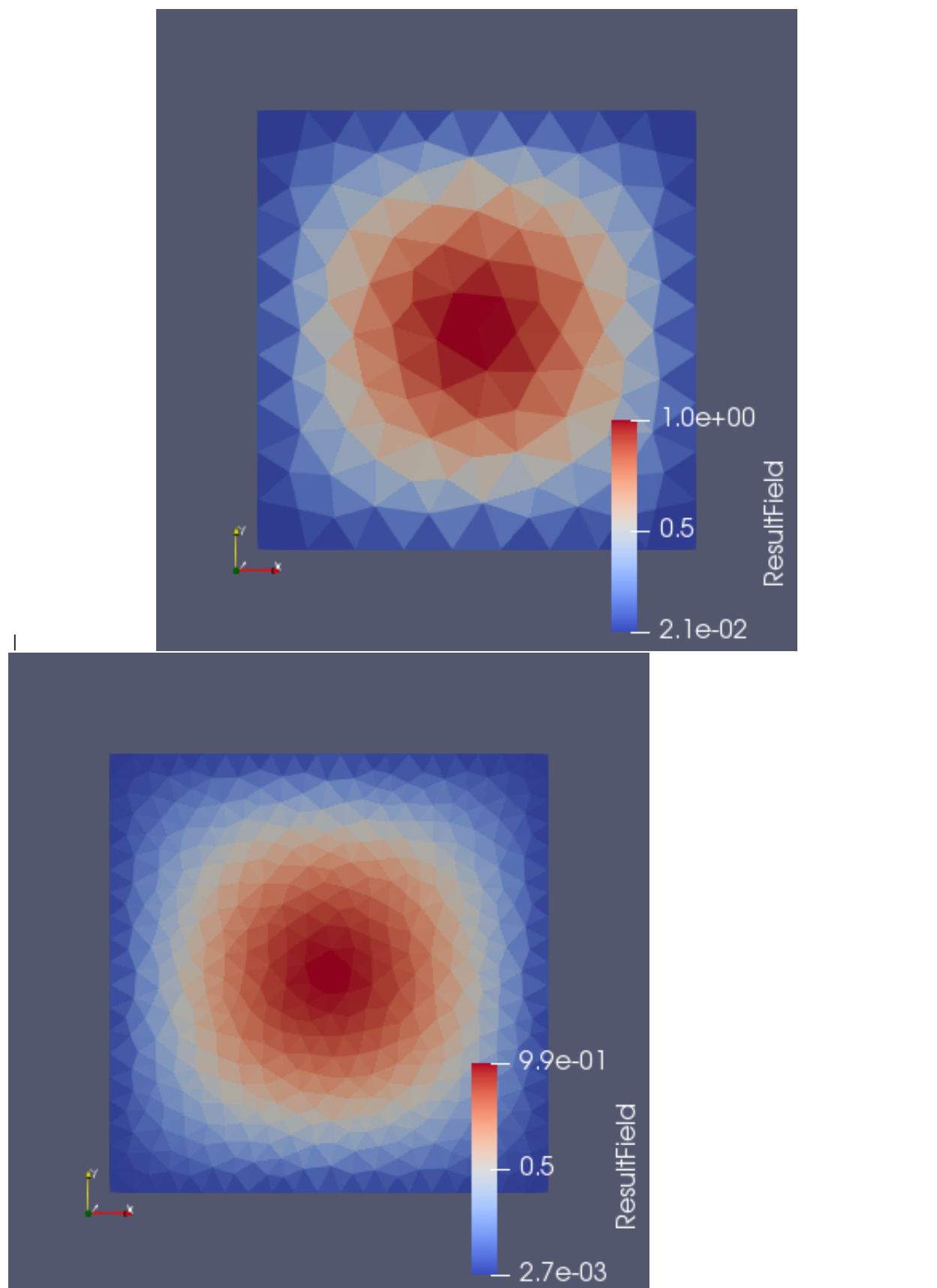
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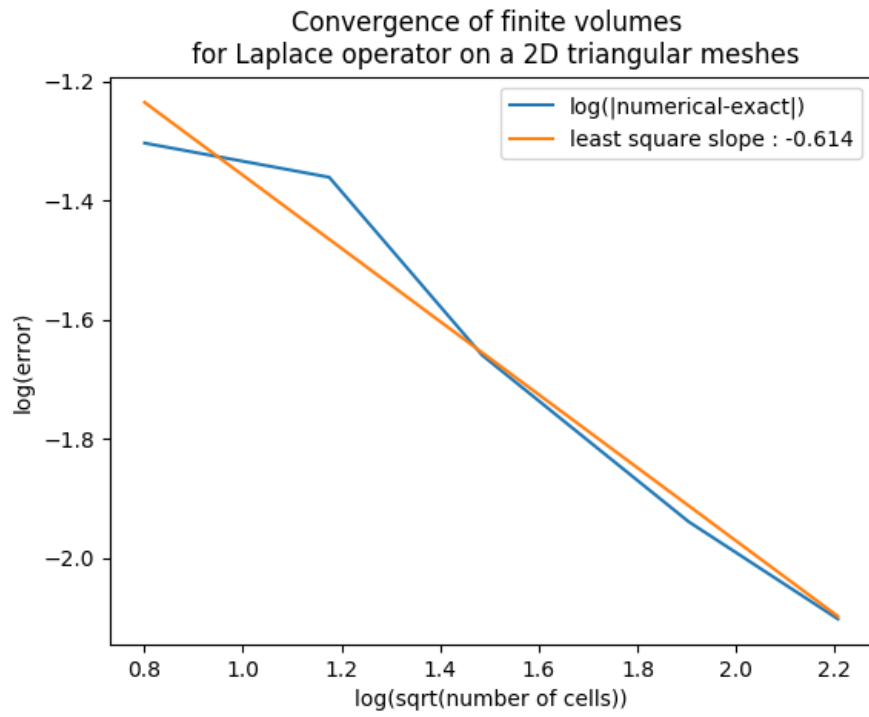


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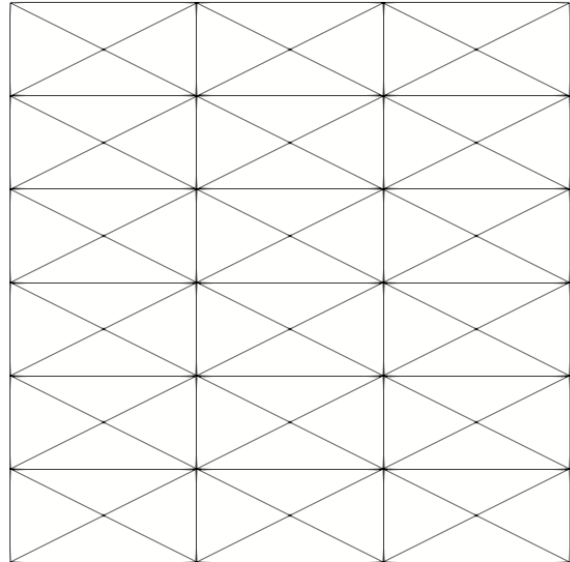
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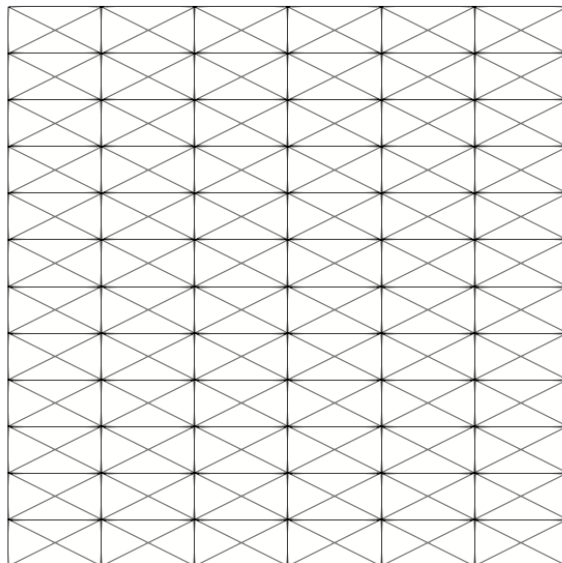




1.8 Cross triangle meshes (from a $(n, 2n)$ rectangular grid)

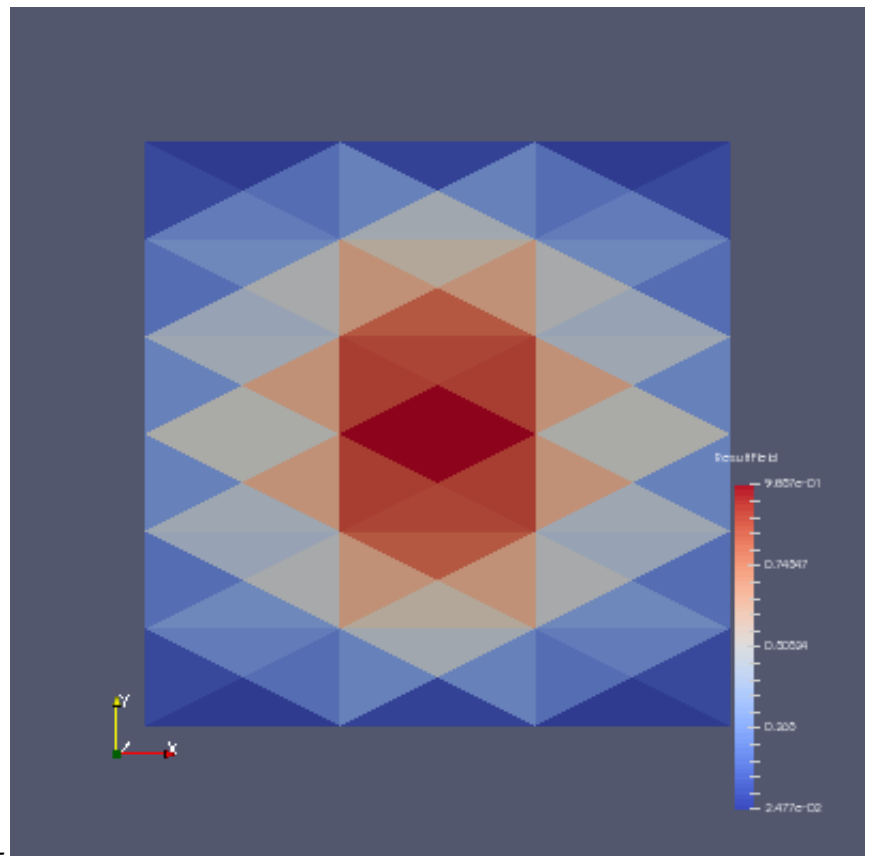
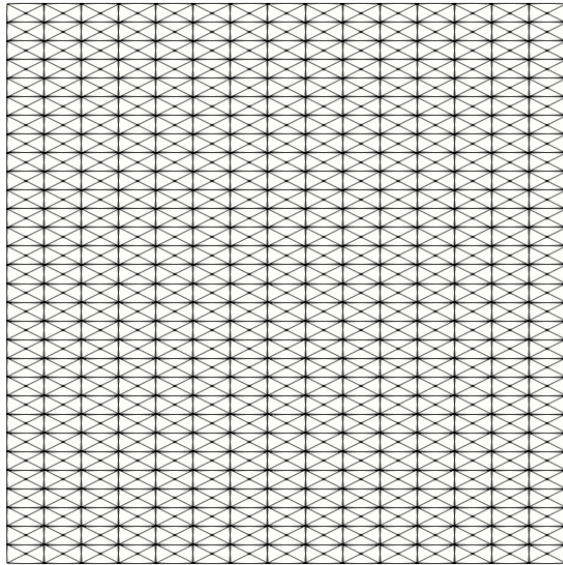


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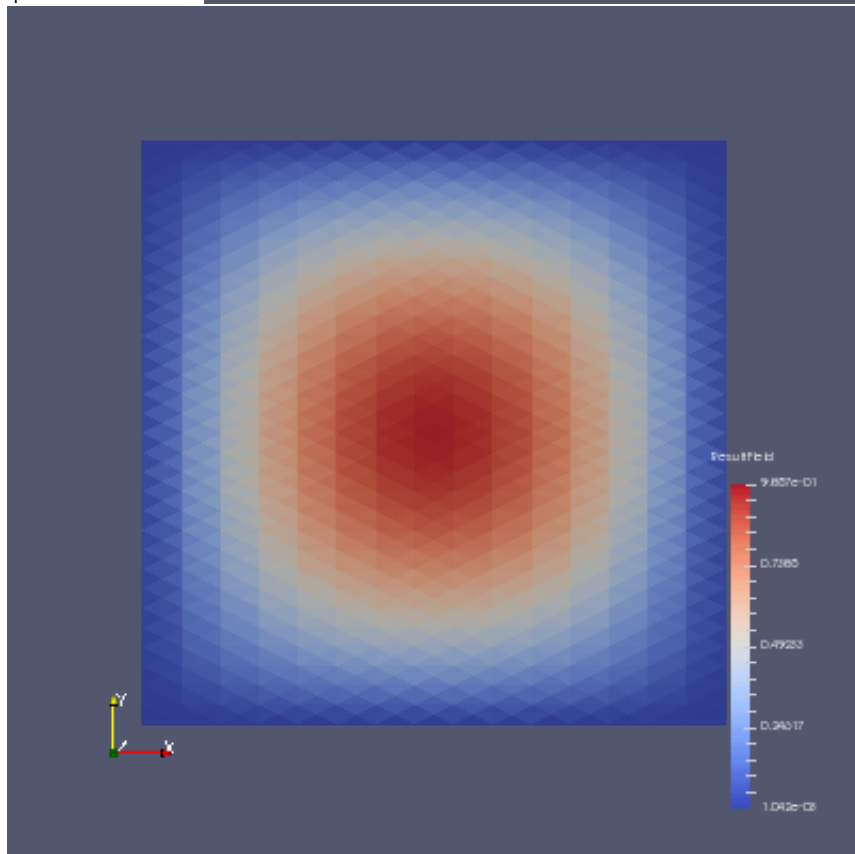
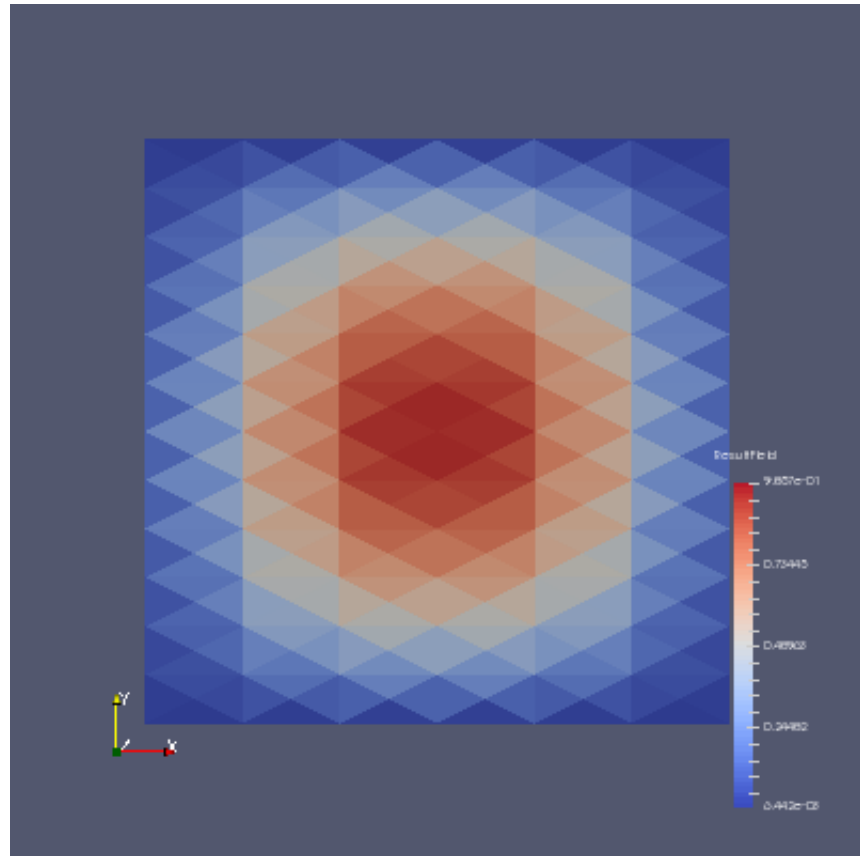


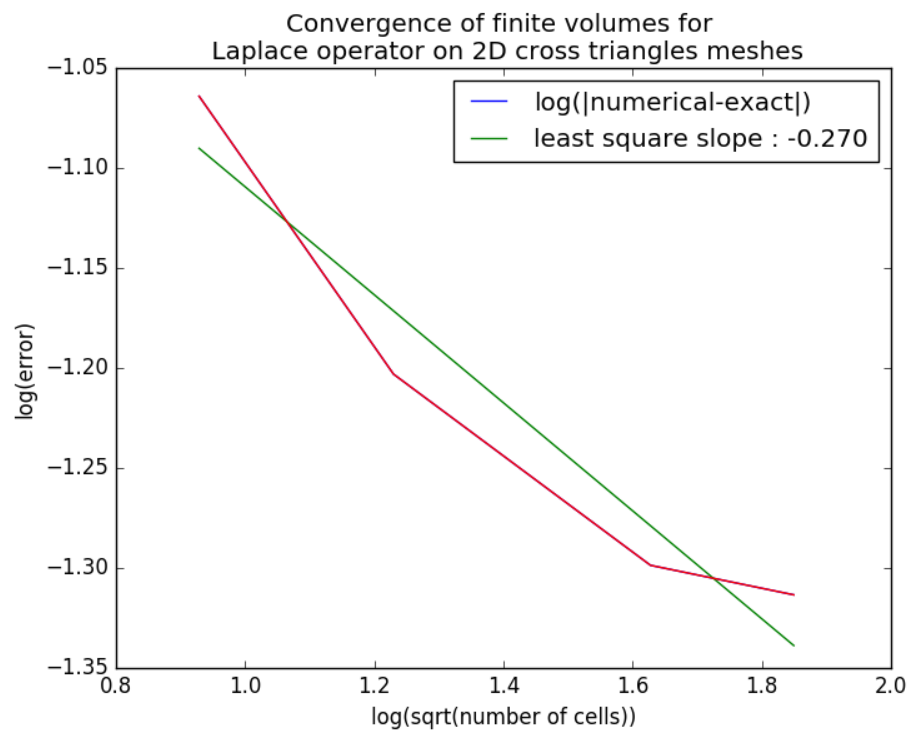
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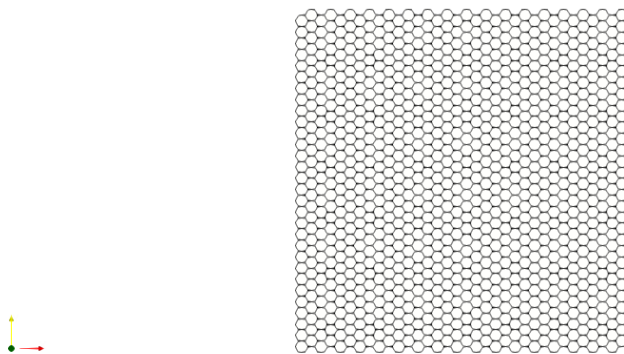
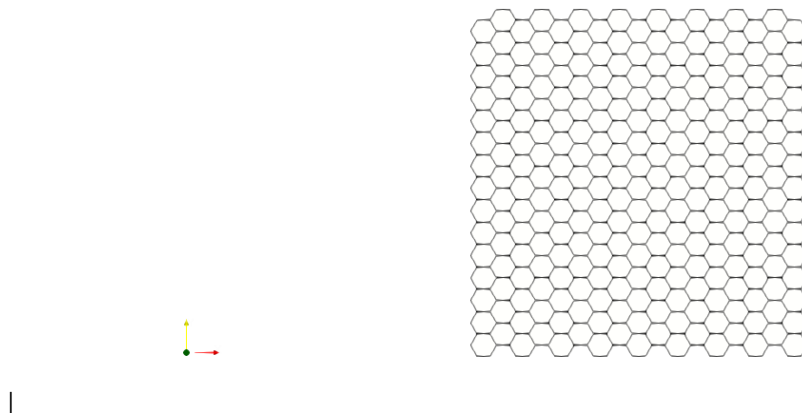
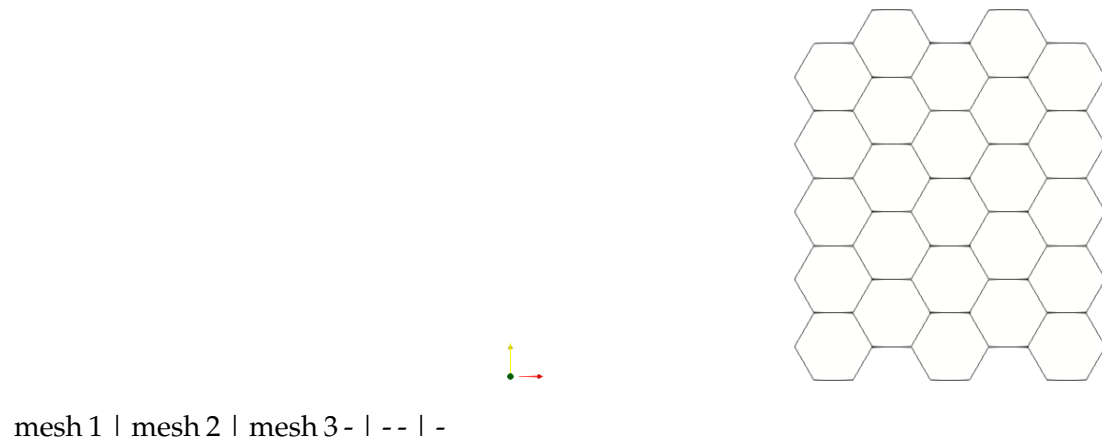


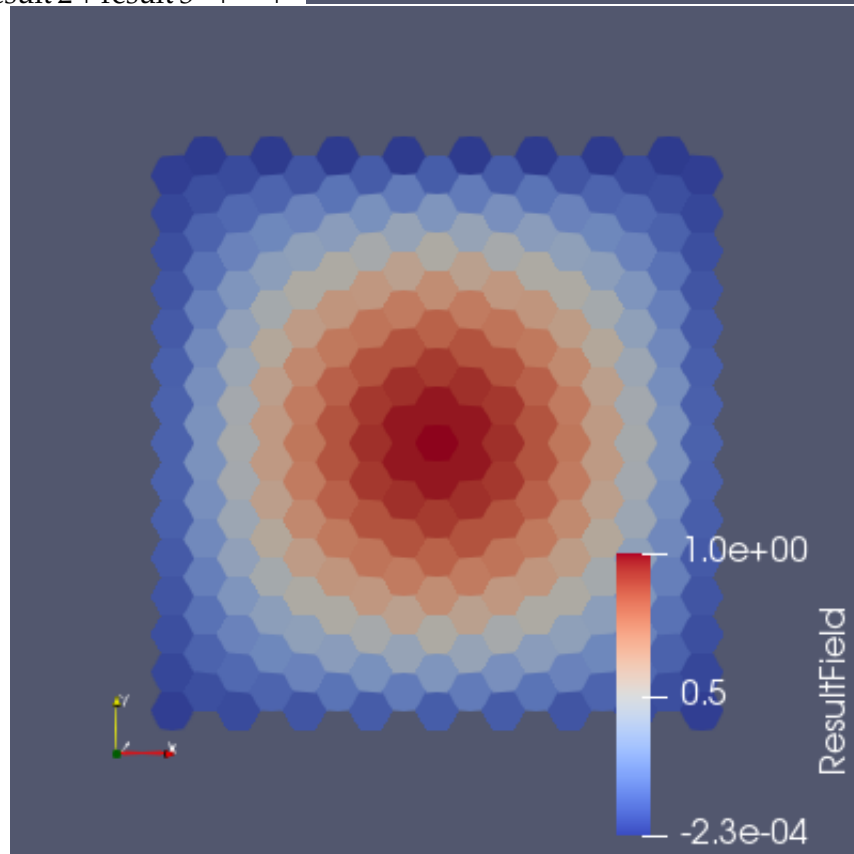
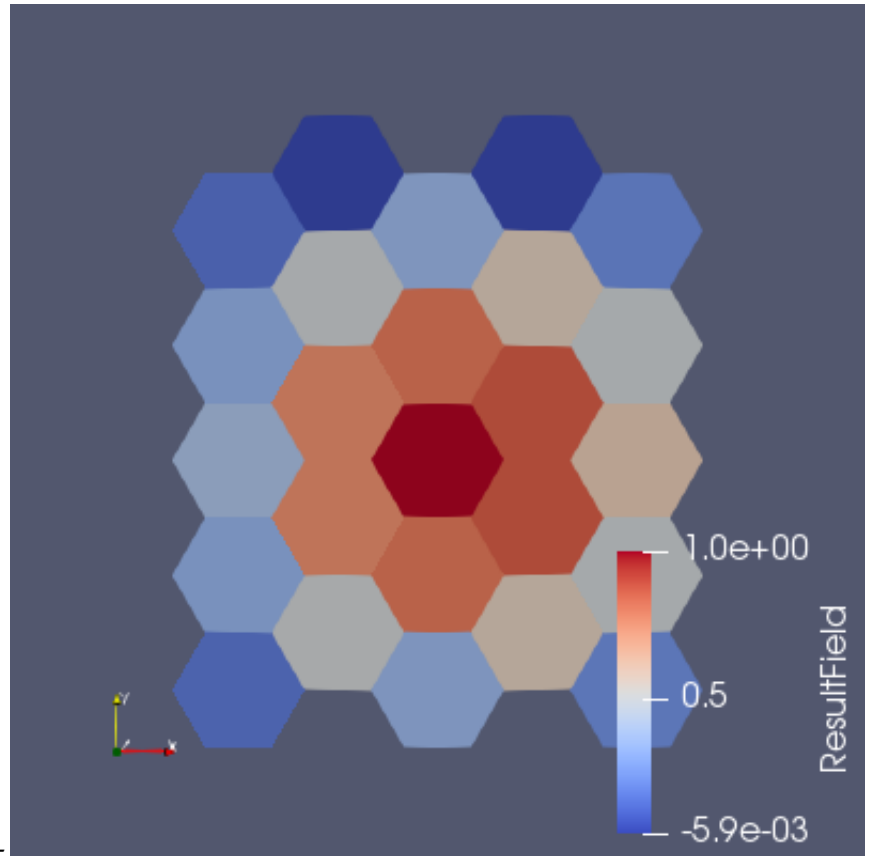
result 1 | result 2 | result 3 - | - - | -

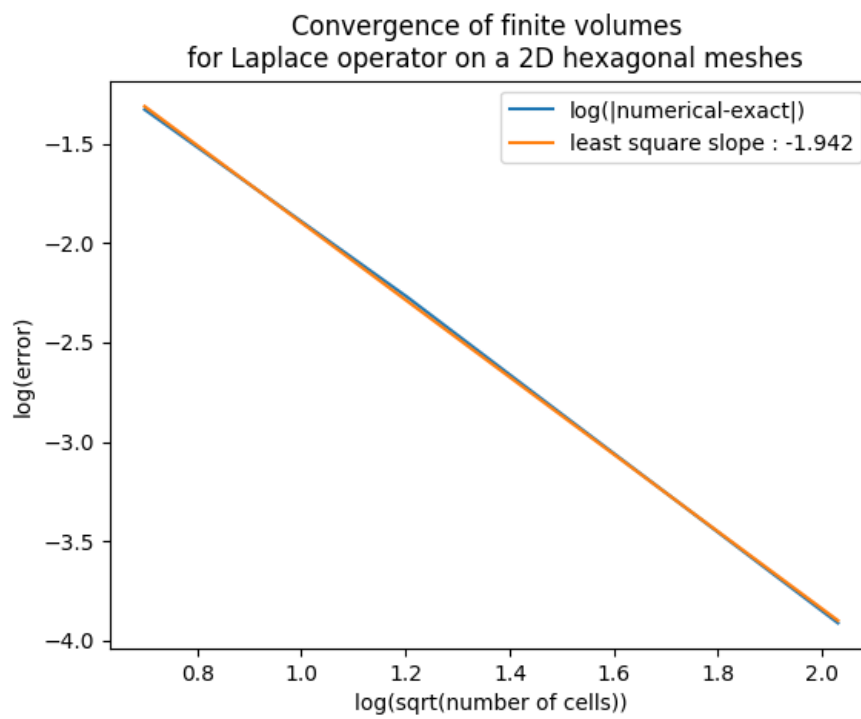
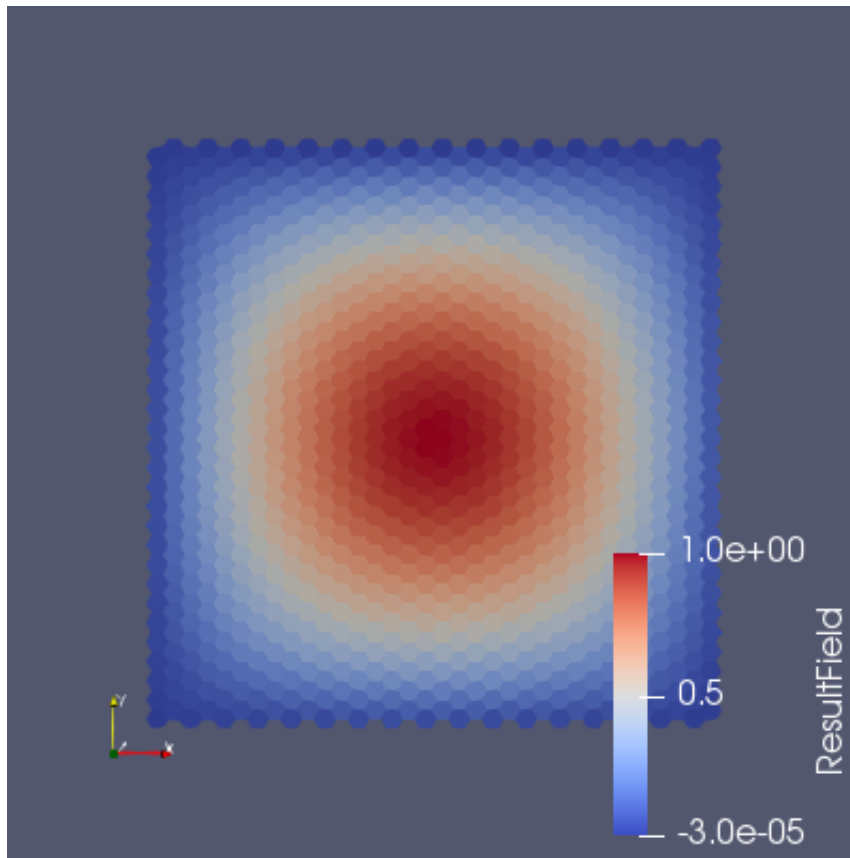




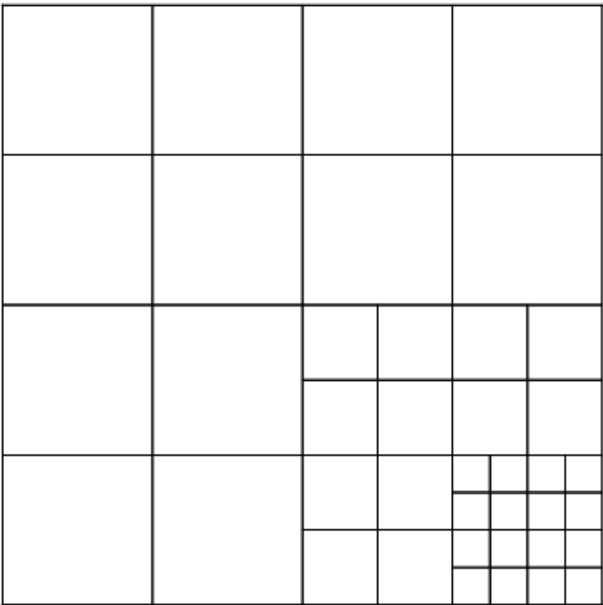
1.9 Hexagonal meshes



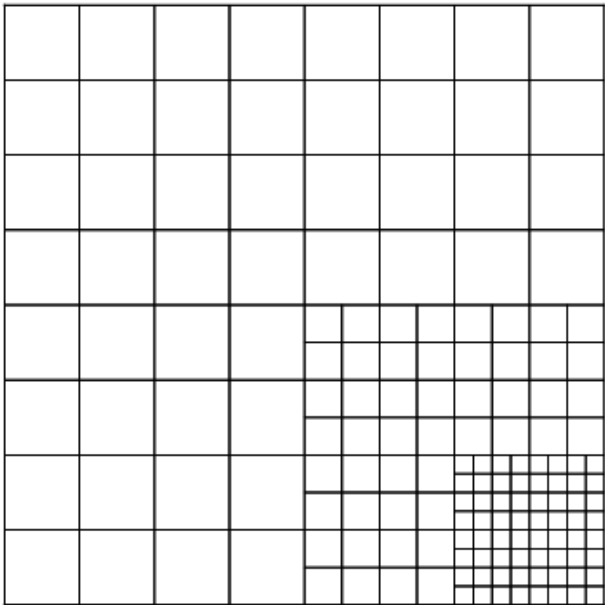




1.10 Locally refined meshes

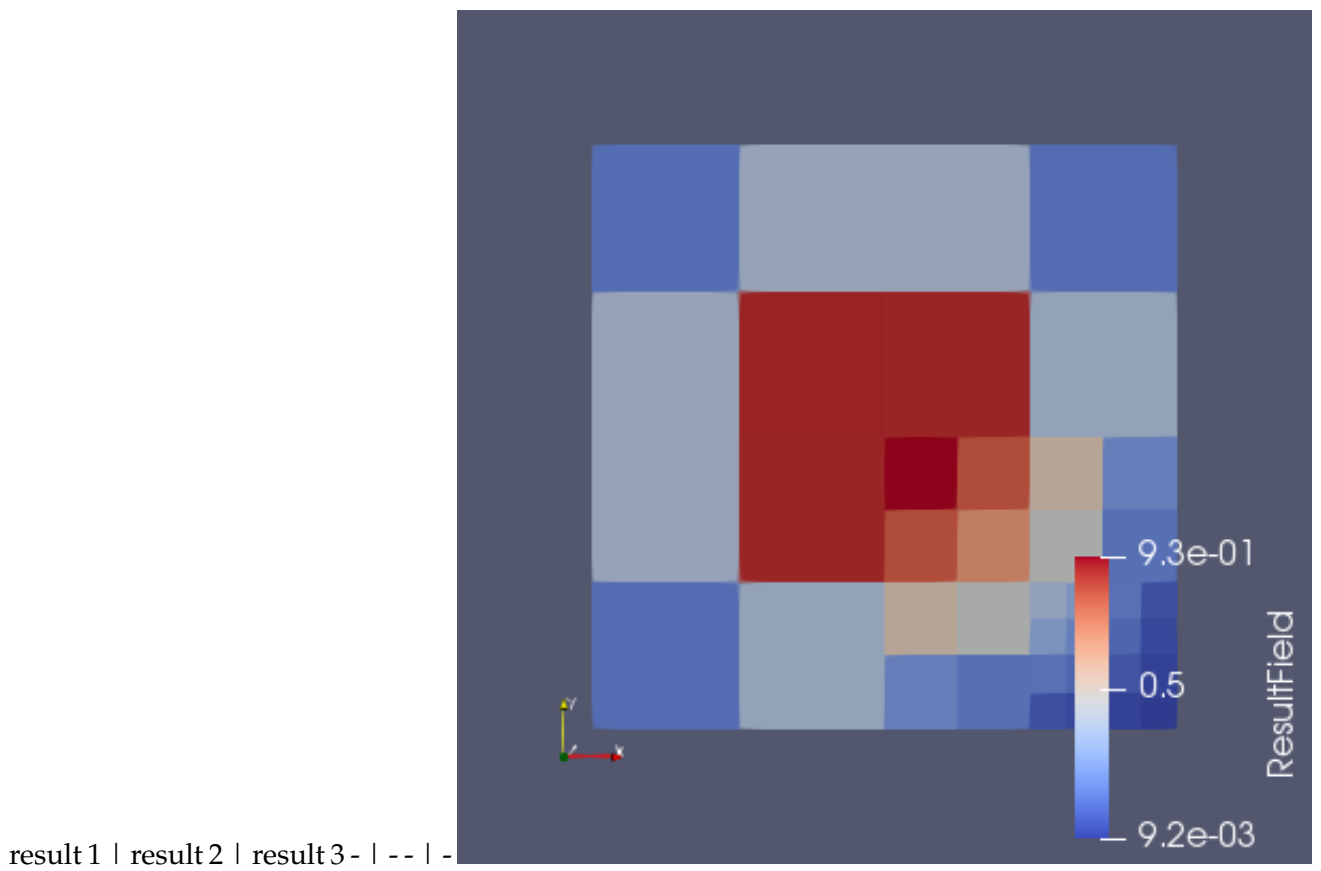
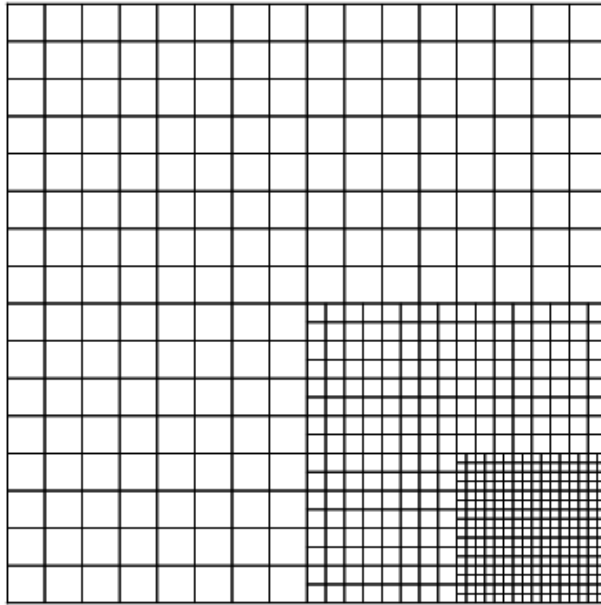


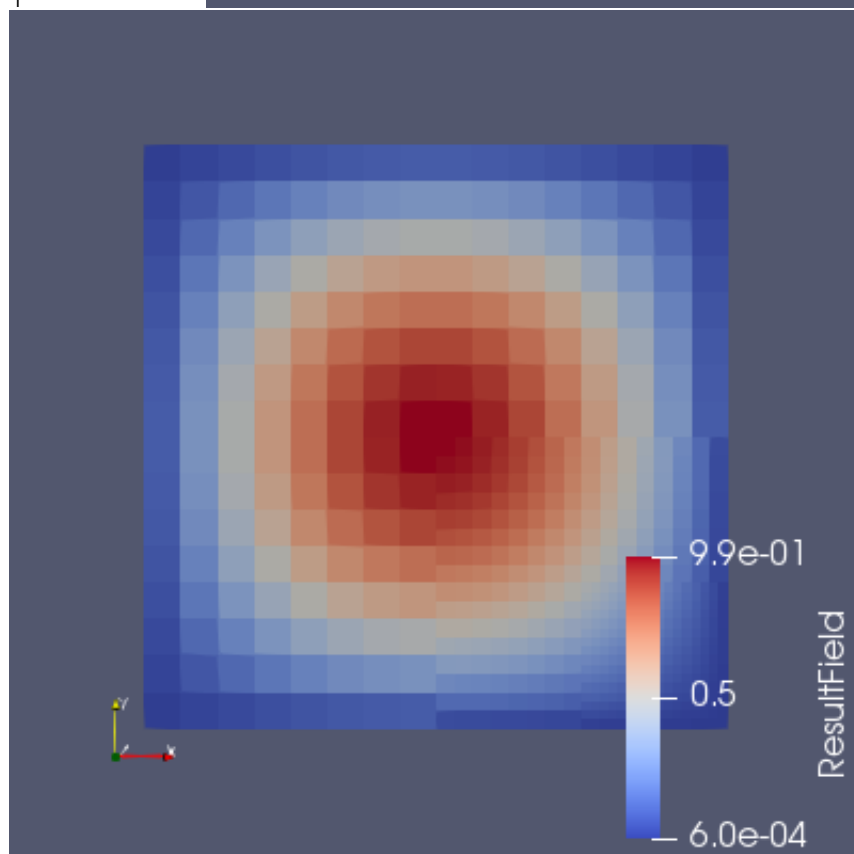
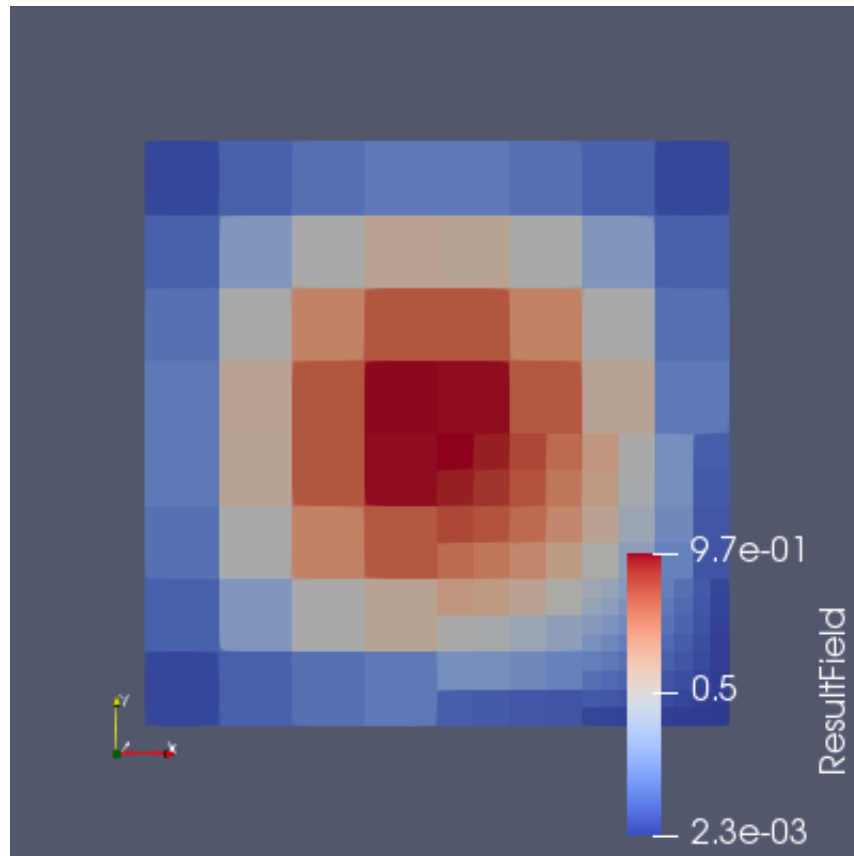
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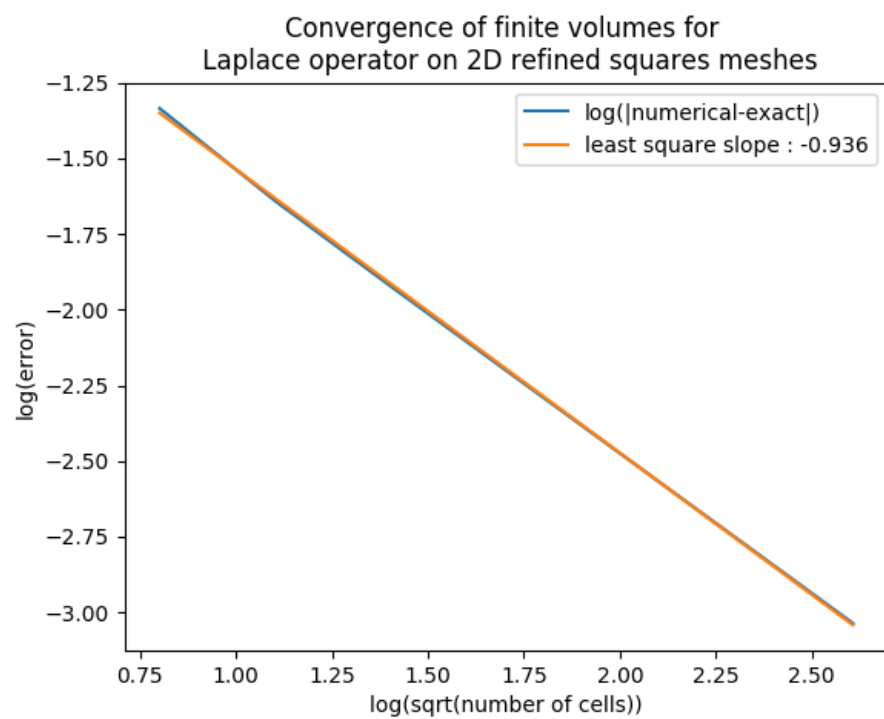


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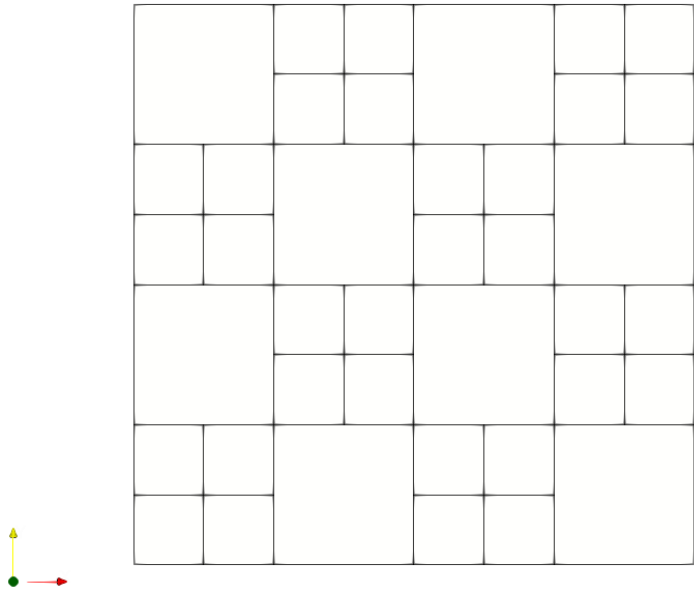
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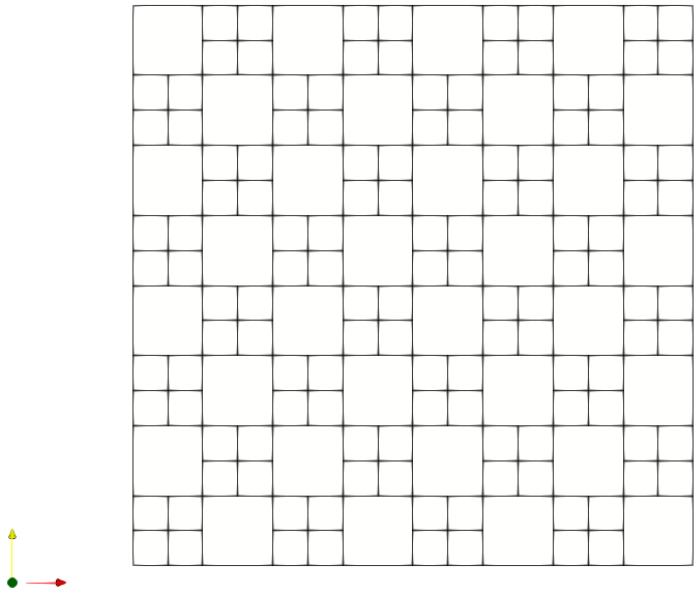




1.11 Checkerboard meshes

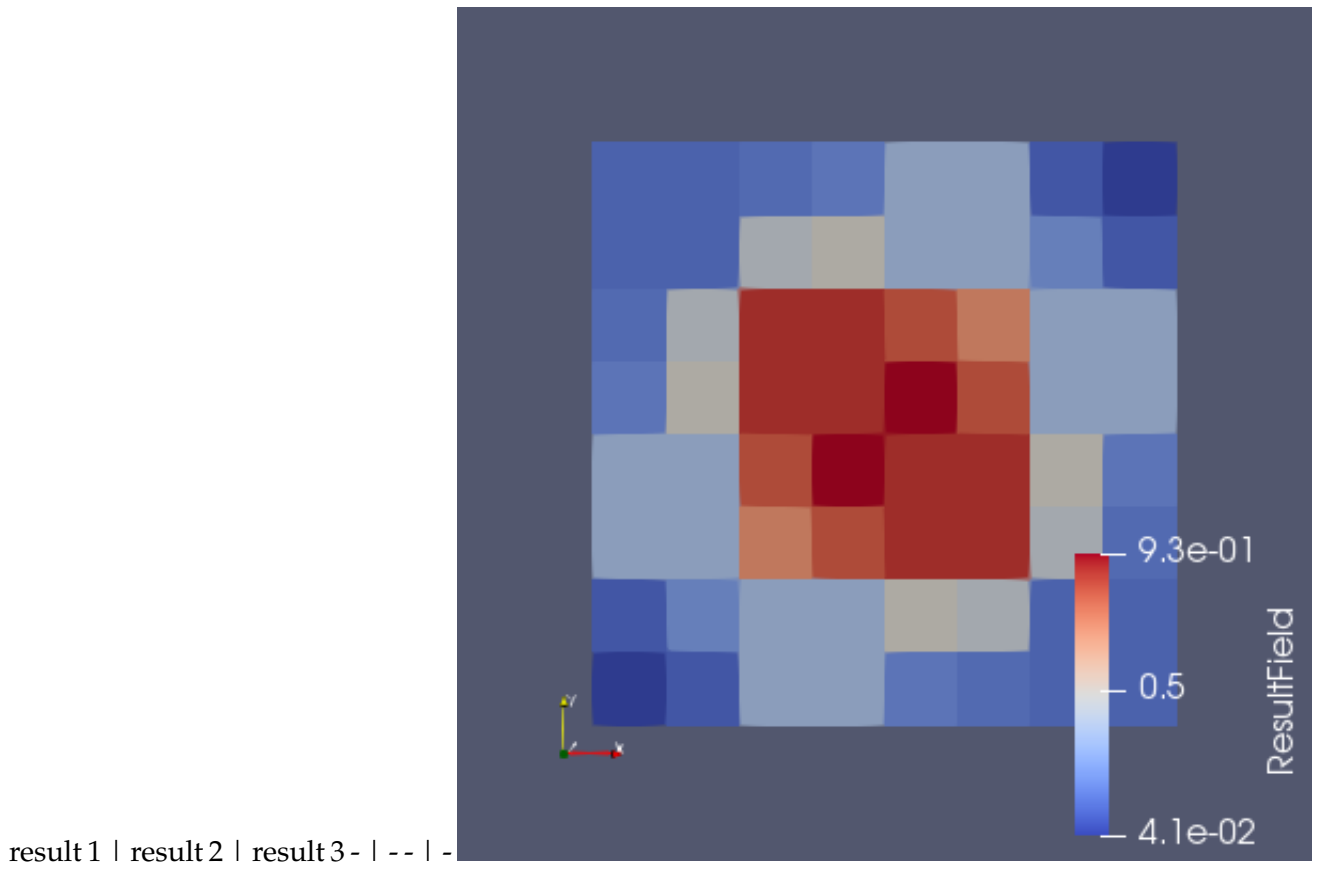
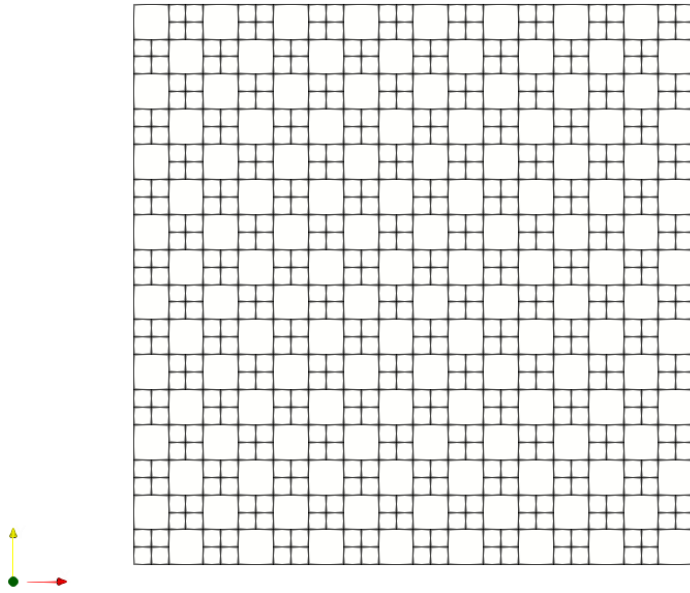


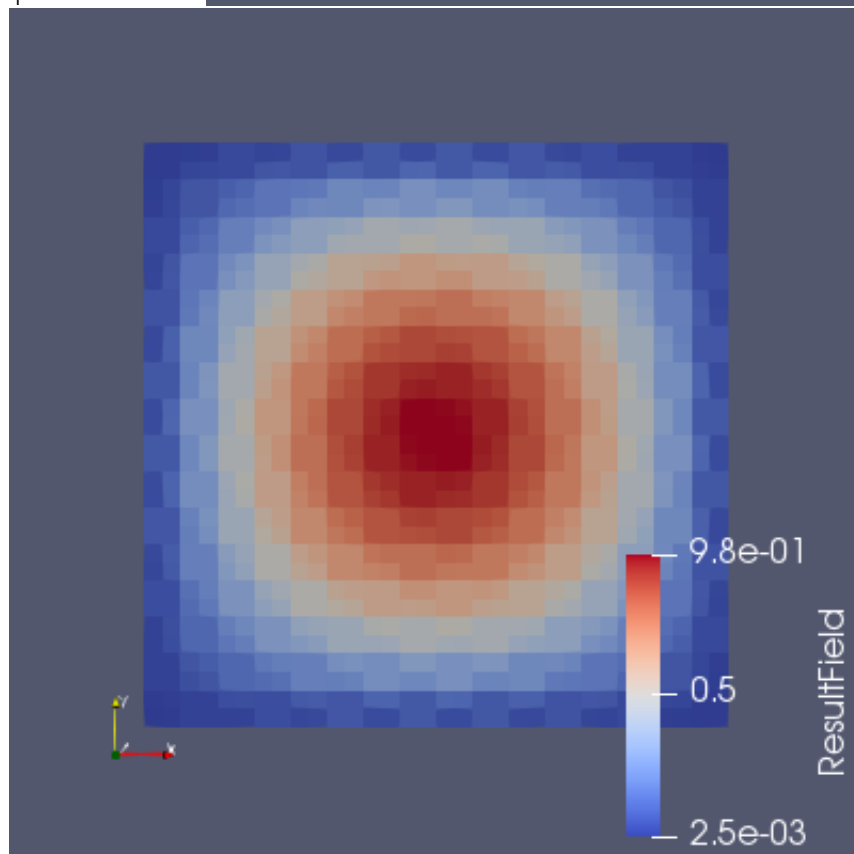
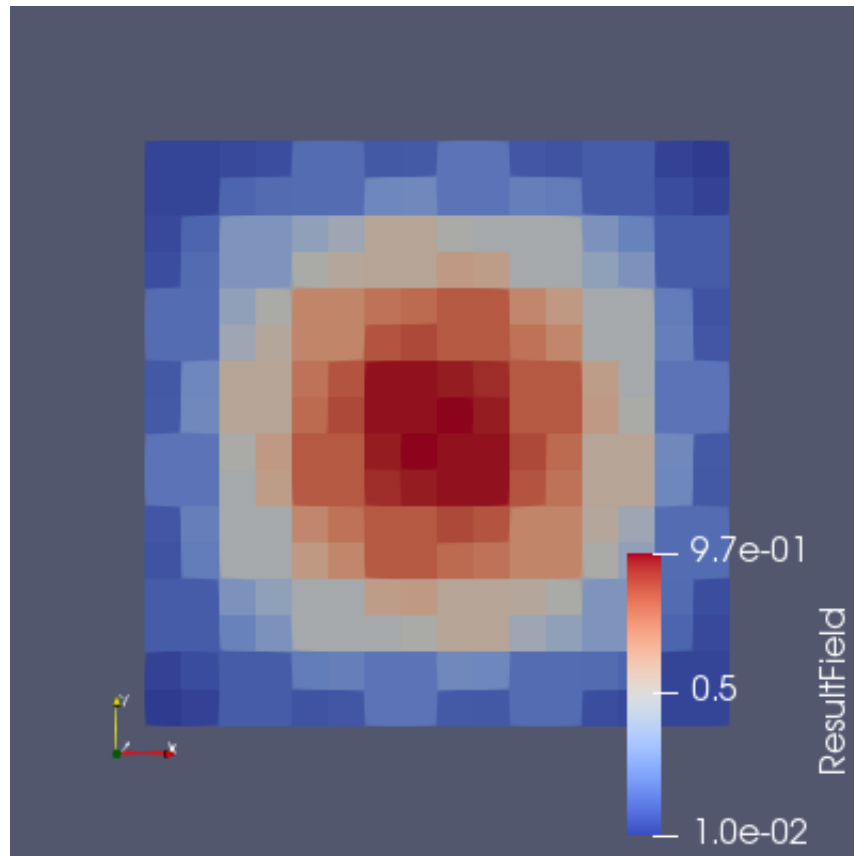
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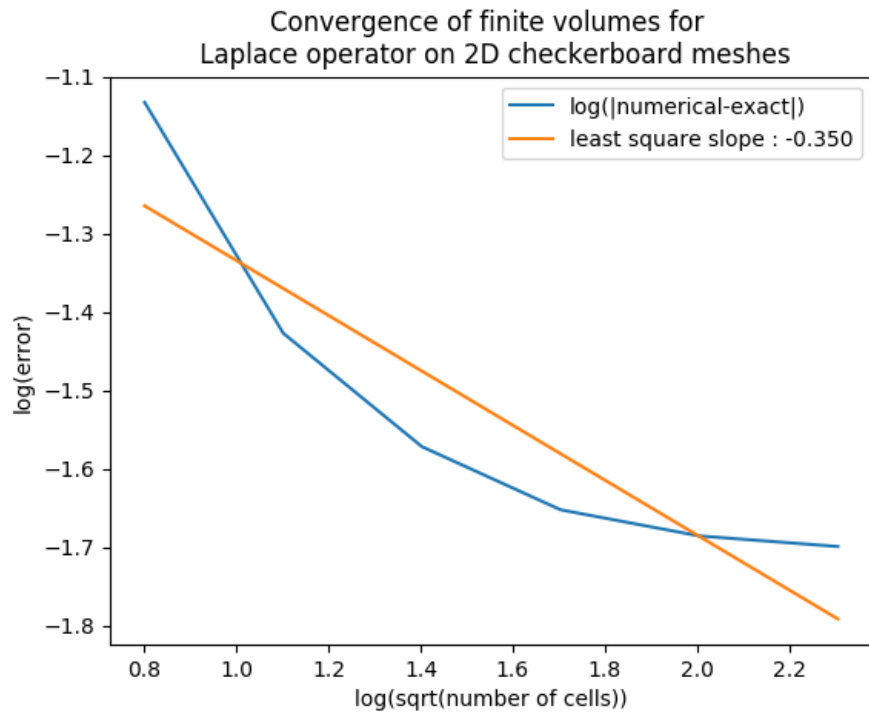


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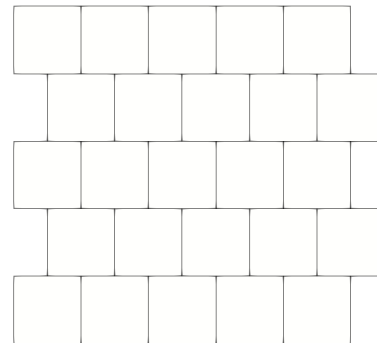
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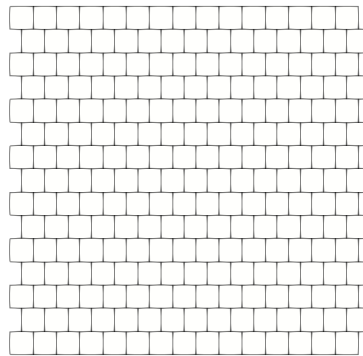




1.12 Brick wall meshes

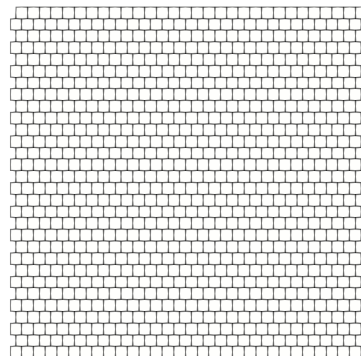


mesh 1 | mesh 2 | mesh 3 - | - - | -

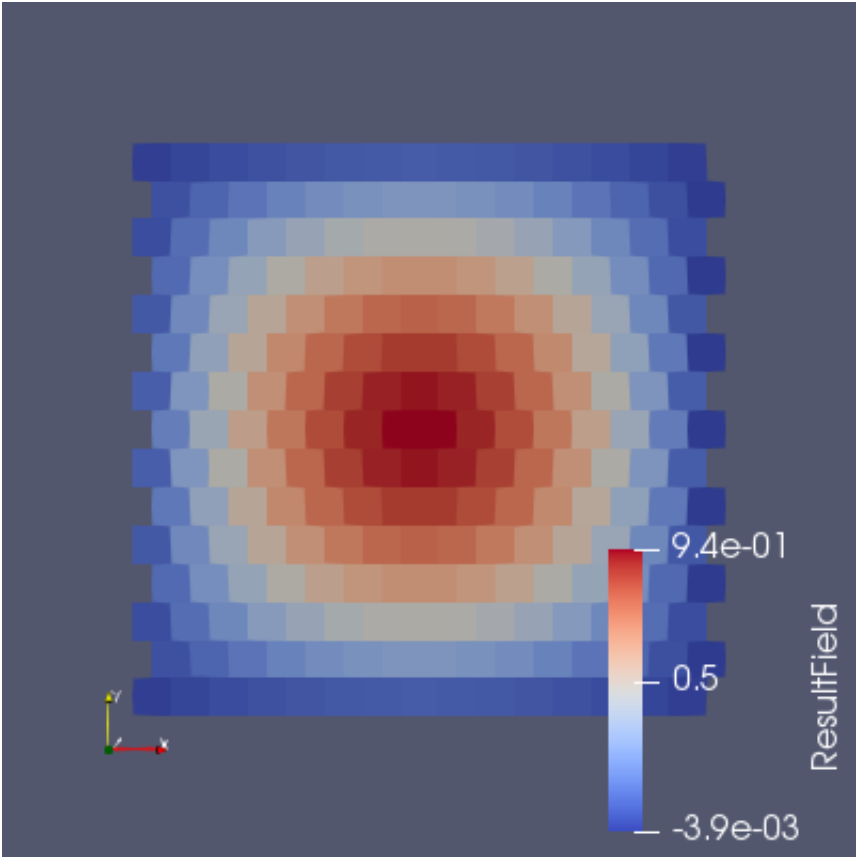
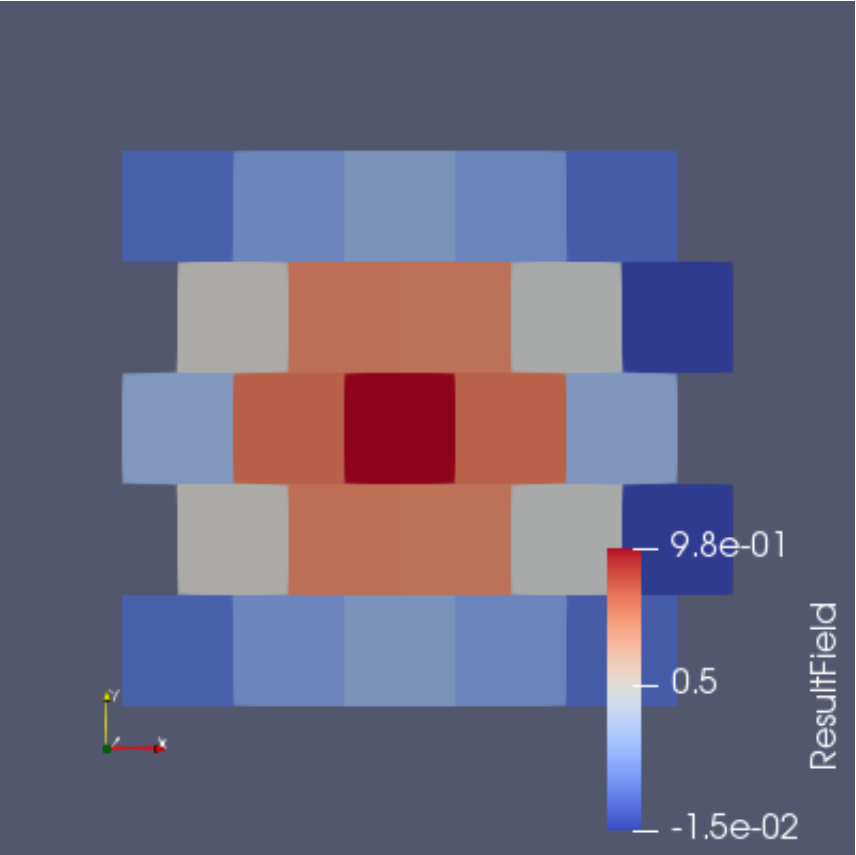


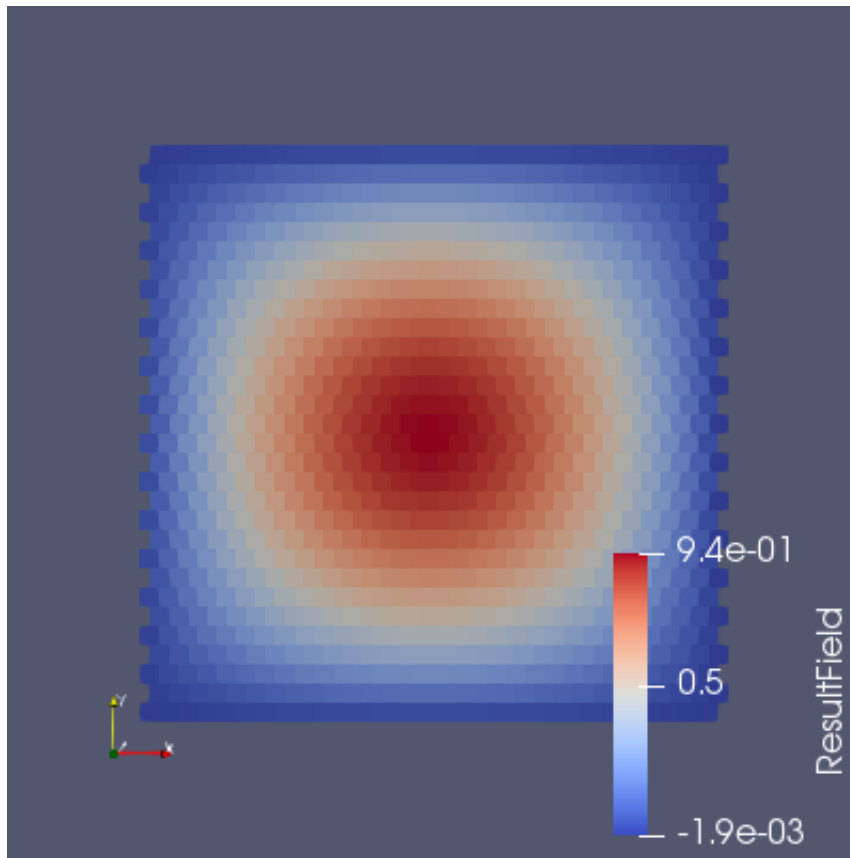
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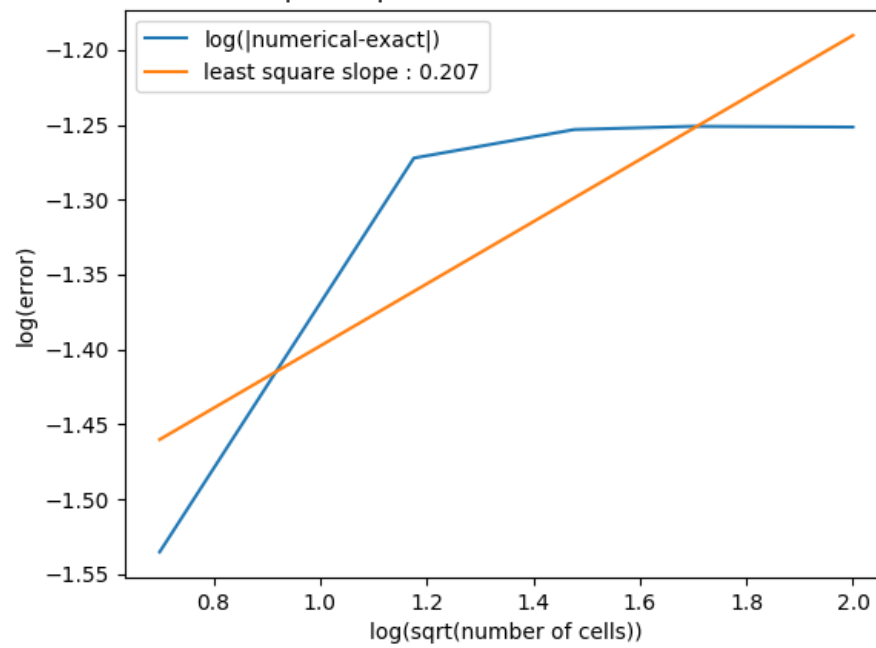


result 1 | result 2 | result 3 - | - - | -

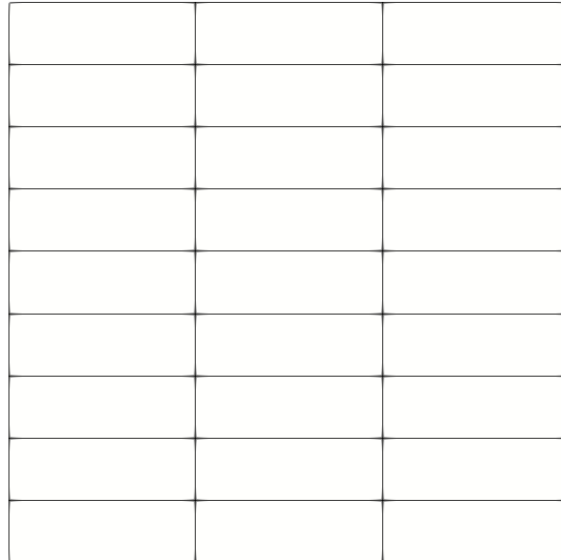




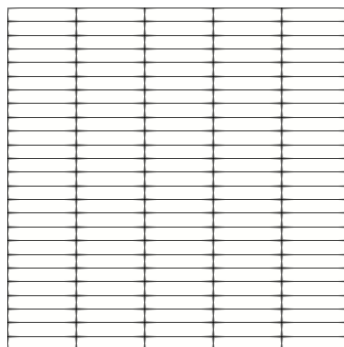
Convergence of finite volumes
for Laplace operator on a 2D brickwall meshes



1.13 Long rectangle meshes ((n, n^2) rectangular grid)

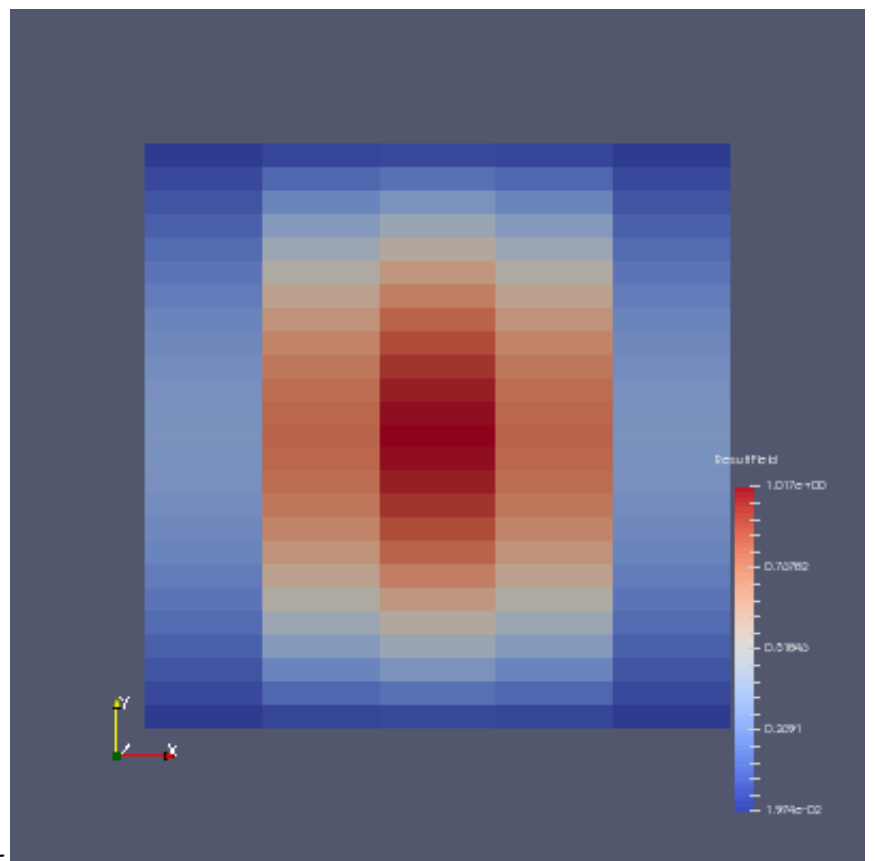
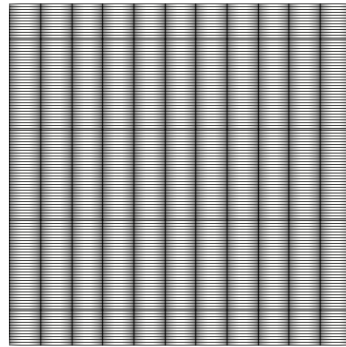


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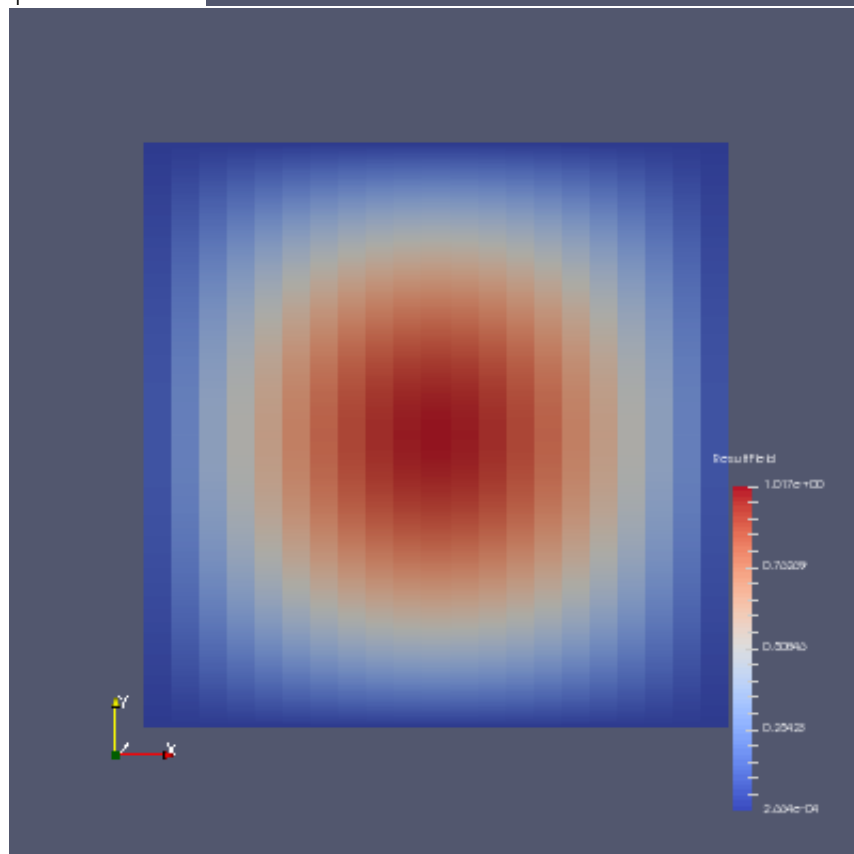
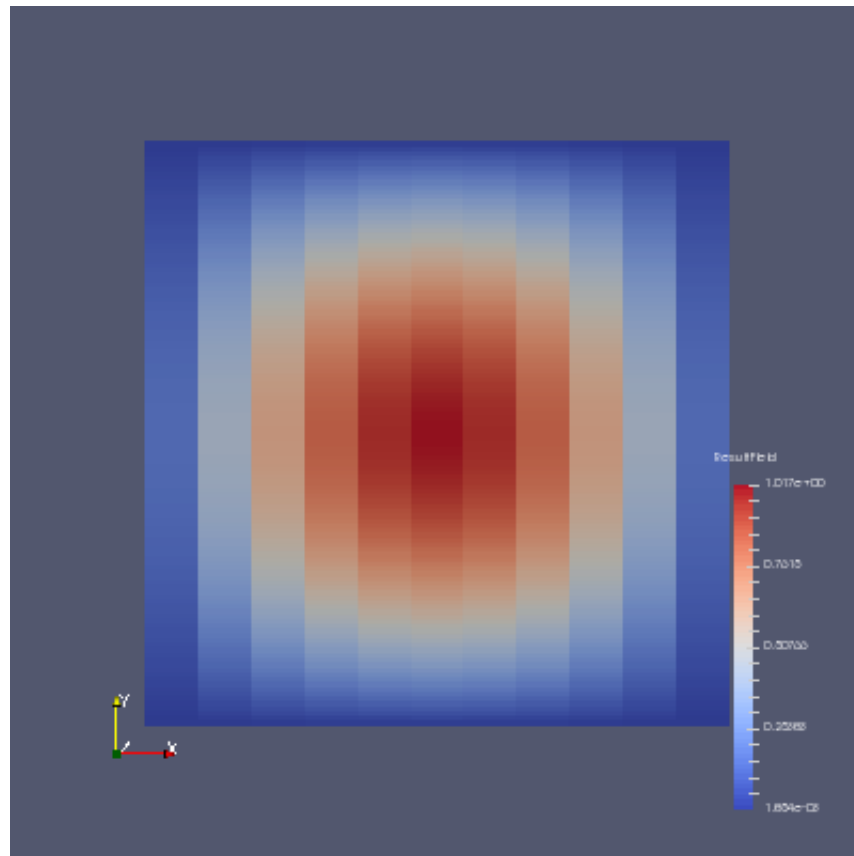


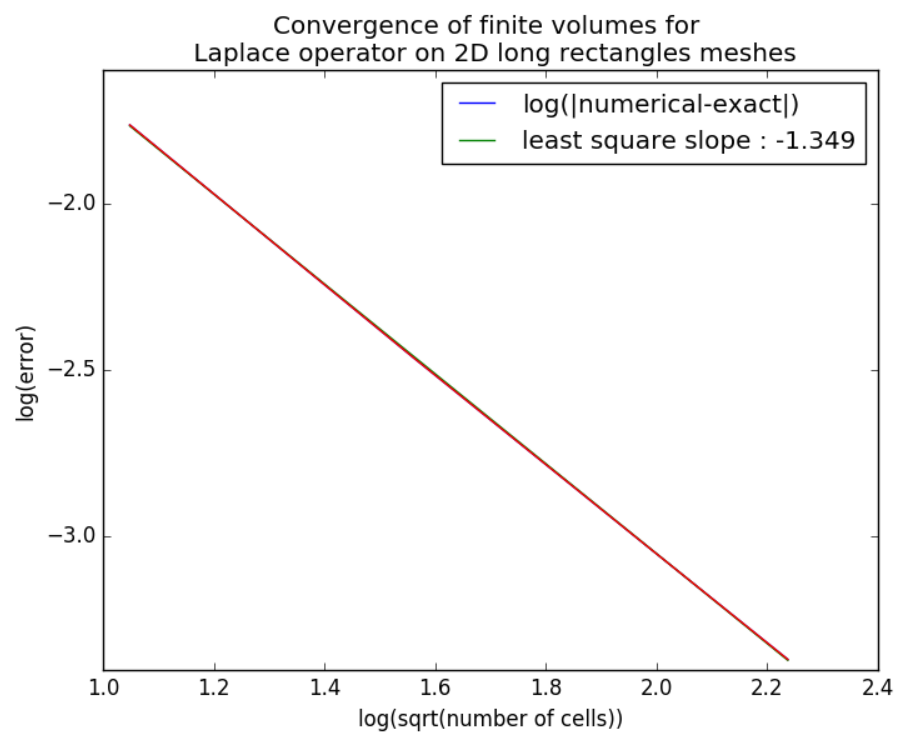
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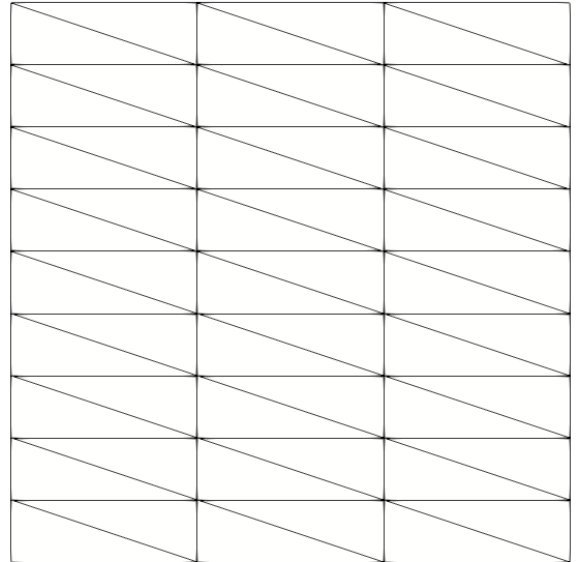


result 1 | result 2 | result 3 - | - - | -

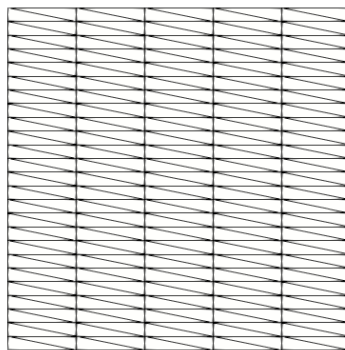




1.14 Long right triangle meshes (from a (n, n^2) rectangular grid)

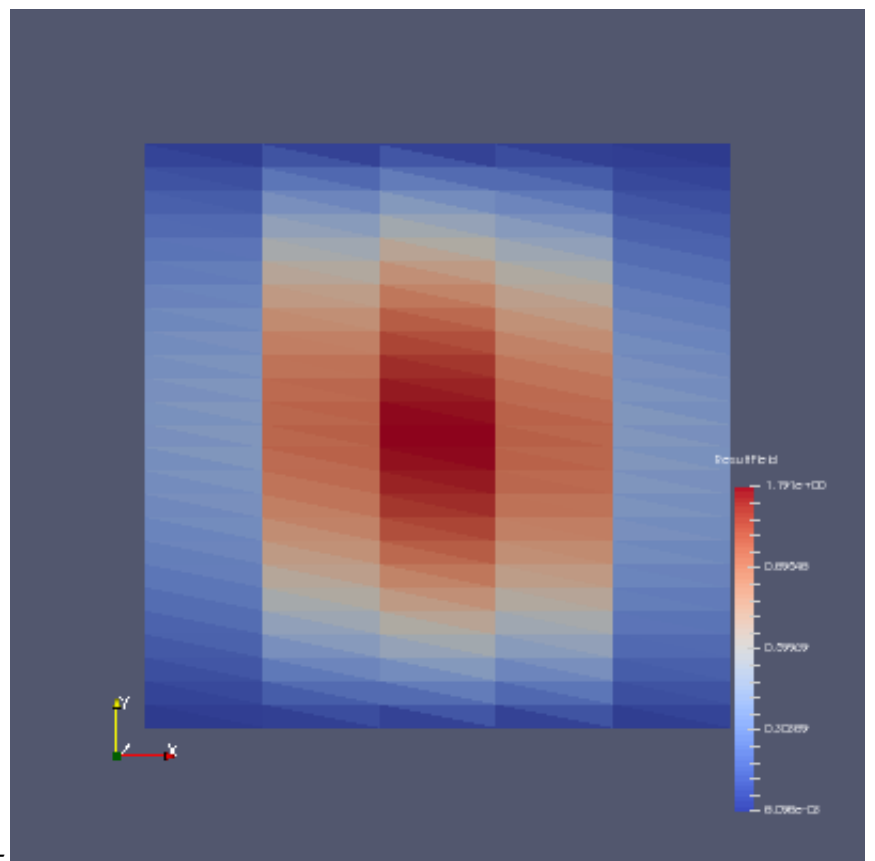
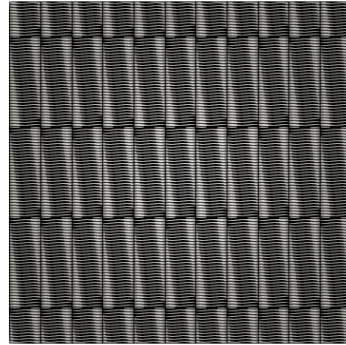


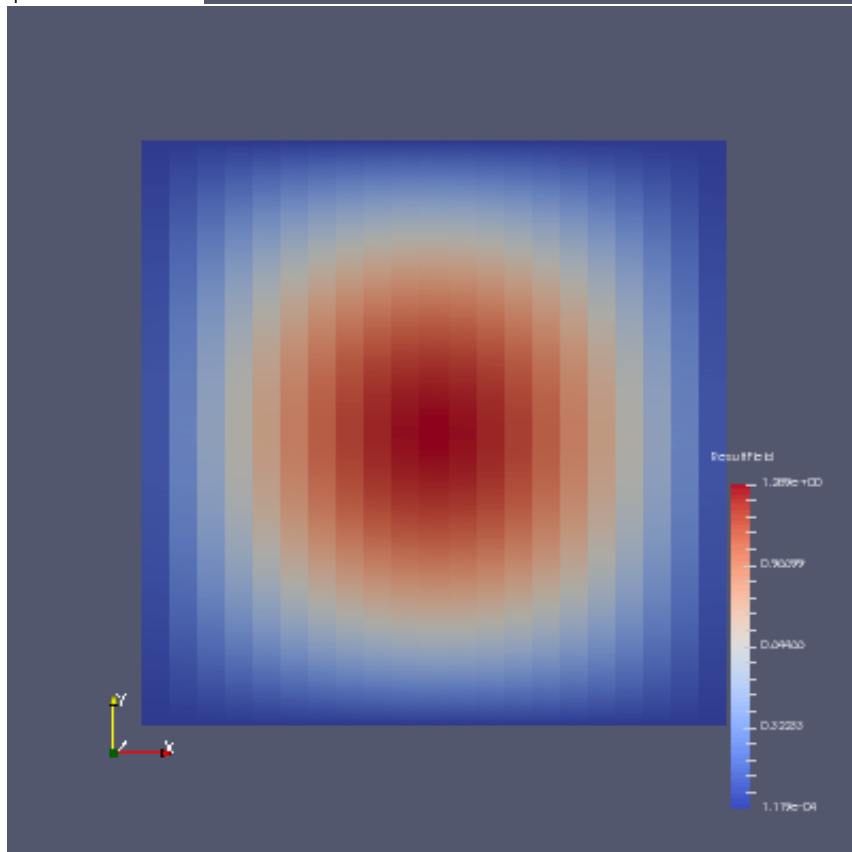
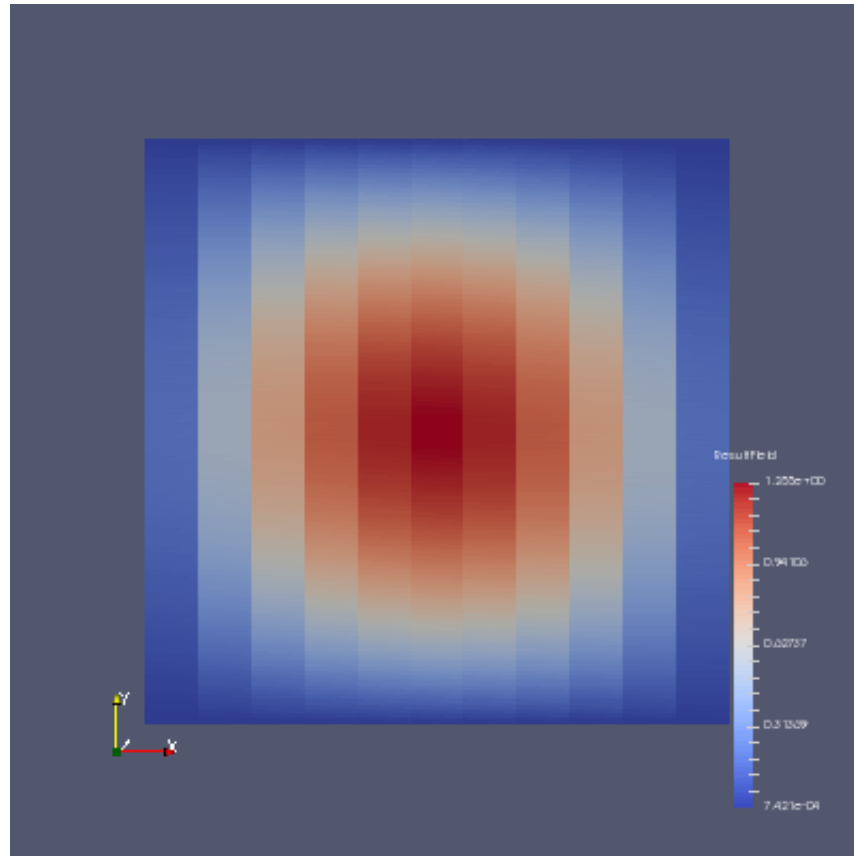
mesh 1 | mesh 2 | mesh 3 - | - - | - -

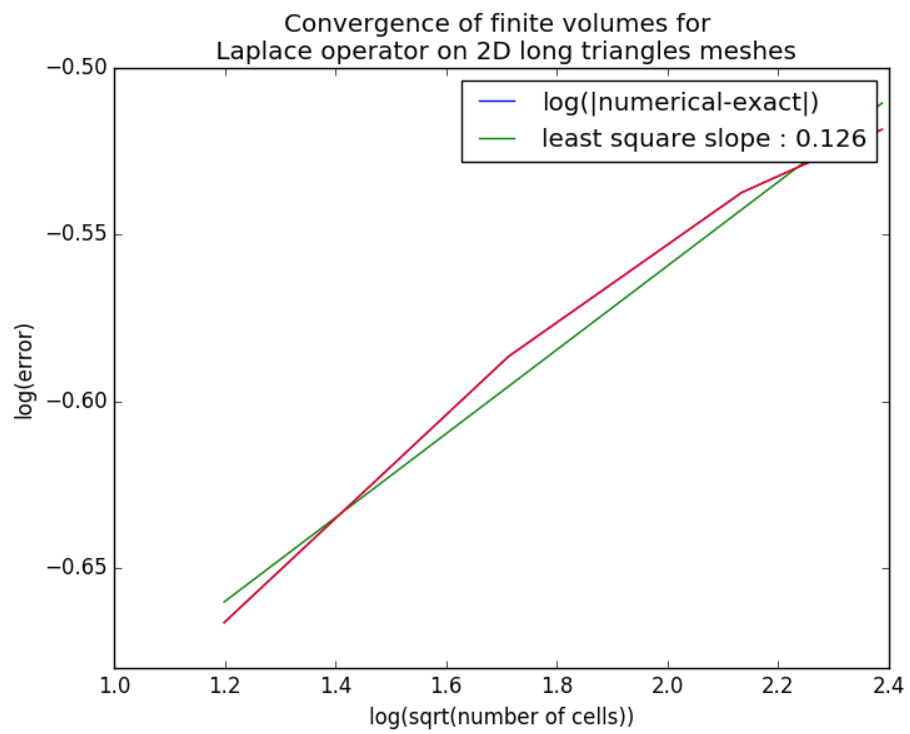


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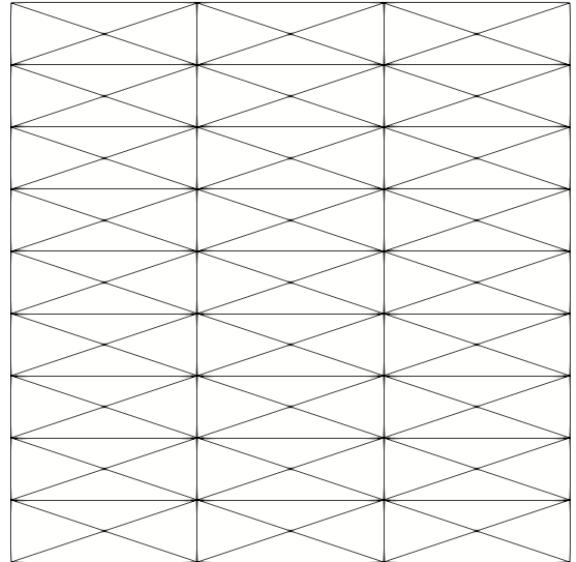
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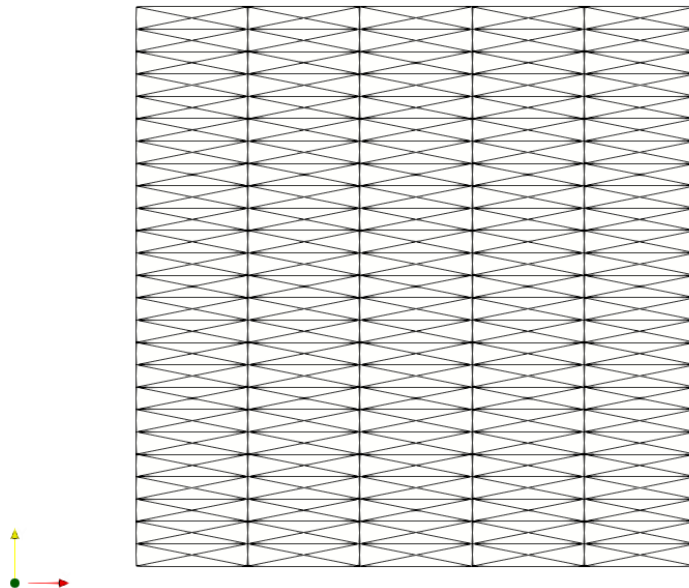


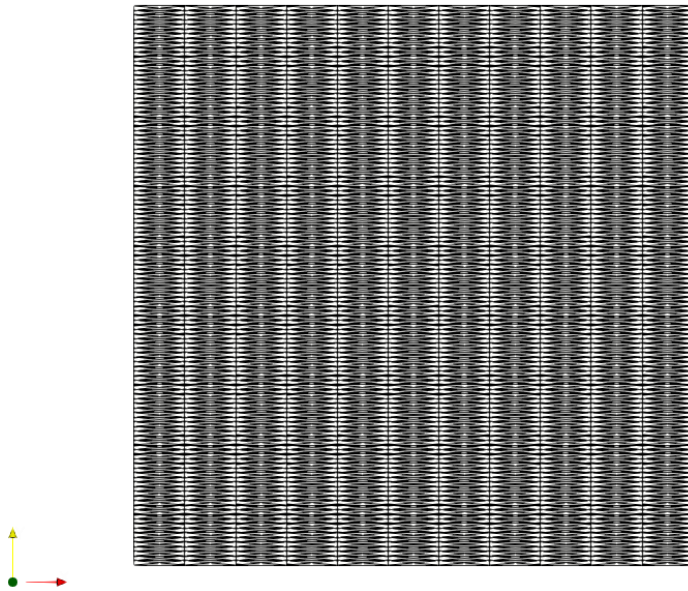


1.15 Flat cross triangle meshes (from a (n, n^2) rectangular grid)



mesh 1 | mesh 2 | mesh 3 - | - - | - -





result 1 | result 2 | result 3 - | - - | -

