Convergence_Poisson_FV5_SQUARE

November 13, 2018

```
In [1]: from IPython.display import display, Markdown
    with open('PoissonProblemOnSquare.md', 'r') as file1:
        PoissonProblemOnSquare = file1.read()
    with open('DescriptionFV5PoissonProblem.md', 'r') as file2:
        DescriptionFV5PoissonProblem = file2.read()
    with open('CodeFV5PoissonProblem.md', 'r') as file3:
        CodeFV5PoissonProblem = file3.read()
    with open('BibliographyFV5.md', 'r') as file4:
        BibliographyFV5=file4.read()
```

1 FV5 scheme for Poisson equation

In [2]: display(Markdown(PoissonProblemOnSquare))

1.1 The Poisson problem on the square

We consider the following Poisson problem with Dirichlet boundary conditions

$$\begin{cases} -\Delta u = f \text{ on } \Omega \\ u = 0 \text{ on } \partial \Omega \end{cases}$$

on the square domain $\Omega = [0,1] \times [0,1]$ with

$$f = 2\pi^2 sin(\pi x) sin(\pi y).$$

The unique solution of the problem is

$$u = \sin(\pi x)\sin(\pi y).$$

The Poisson equation is a particular case of the diffusion problem

$$-\nabla \cdot (K\vec{\nabla}u) = f$$

and the associated diffusion flux is

$$F(u) = K\nabla u$$
.

We are in the particular case where K = 1.

In [3]: display(Markdown(BibliographyFV5))

1.2 Some bibliographical remarks

- Order 1 convergence on triangular meshes R. Herbin, An error estimate for a four point finite volume scheme for the convection-diffusion equation on a triangular mesh, Num. Meth. P.D.E., 165-173, 1995.
- On triangular meshes, the FV5 scheme order is 2 provided
 - the center of the circumscribed circle is used instead of the center of mass in each cell
 - the Delaunay conditions are satisfied (no neighboring cell is included in the circumscribed circle of an arbitrary cell)
- Non convergence on highly deformed meshes
 K. Domelevo, P. Omnes, A finite volume method for the Laplace equation on almost arbitrary 2D grids, Mathematical Modelling and Numerical Analysis, 2005
- The scheme is order 1 if the mesh is conforming except on a line J. Droniou, C. Le Potier, Construction and Convergence Study of Schemes Preserving the Elliptic Local Maximum Principle, SIAM Journal on Numerical Analysis, 2011
- The scheme is order 2 if Delaunay type conditions, f ∈ H¹ and meshes are generated from an initial mesh either by subdivisions, symmetry or translation
 J. Droniou, Improved L^2 estimate for gradient schemes and super-convergence of the TPFA finite volume scheme, 2018
- It is possible to converge with order 1 on the gradient, but only order 1 on the function ie there is no equivalent of the Aubin-Nitsche lemma in the finite volume context *P. Omnes, Error estimates for a finite volume method for the Laplace equation in dimension one through discrete Green functions. International Journal on Finite Volumes 6(1), 18p., electronic only, 2009*

In [4]: display(Markdown(DescriptionFV5PoissonProblem))

1.3 The FV5 scheme for the Laplace equation

The domain Ω is decomposed into cells C_i .

 $|C_i|$ is the measure of the cell C_i .

 f_{ii} is the interface between two cells C_i and C_i .

 s_{ij} is the measure of the interface f_{ij} .

 d_{ij} is the distance between the centers of mass of the two cells C_i and C_j .

The discrete Poisson problem is

$$-\frac{1}{|C_i|}\sum s_{ij}F_{ij}=f_i,$$

where u_i is the approximation of u in the cell C_i ,

 f_i is the approximation of f in the cell C_i ,

 F_{ij} is a numerical approximation of the outward normal diffusion flux from cell i to cell j. In the case of the scheme FV5, the flux formula are

$$F_{ij}=\frac{u_j-u_i}{d_{ij}},$$

for two cells i and j inside the domain, and

$$F_{boundary} = \frac{u(x_f) - u_i}{d_{if}},$$

for a boundary face with center x_f , inner cell i and distance between face and cell centers d_{if}

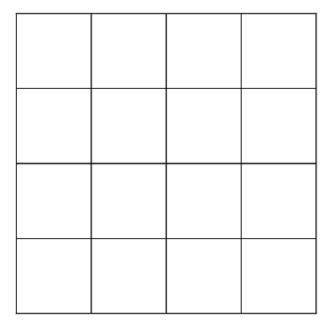
In [5]: display(Markdown(CodeFV5PoissonProblem))

1.4 The script

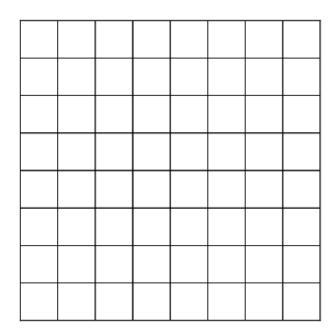
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#Discrétisation du second membre et extraction du nb max de voisins d'une cellule
#-----
my_RHSfield = cdmath.Field("RHS_field", cdmath.CELLS, my_mesh, 1)
maxNbNeighbours=0#This is to determine the number of non zero coefficients in the sparse finite
for i in range(nbCells):
   Ci = my_mesh.getCell(i)
   x = Ci.x()
   y = Ci.y()
   my_RHSfield[i]=2*pi*pi*sin(pi*x)*sin(pi*y)#mettre la fonction definie au second membre de l
   # compute maximum number of neighbours
   maxNbNeighbours= max(1+Ci.getNumberOfFaces(),maxNbNeighbours)
# Construction de la matrice et du vecteur second membre du système linéaire
#-----
Rigidite=cdmath.SparseMatrixPetsc(nbCells,nbCells,maxNbNeighbours) # warning : third argument is
RHS=cdmath.Vector(nbCells)
#Parcours des cellules du domaine
for i in range(nbCells):
   RHS[i]=my_RHSfield[i] #la valeur moyenne du second membre f dans la cellule i
   Ci=my_mesh.getCell(i)
   for j in range(Ci.getNumberOfFaces()): # parcours des faces voisinnes
       Fj=my_mesh.getFace(Ci.getFaceId(j))
       if not Fj.isBorder():
           k=Fj.getCellId(0)
           if k==i:
              k=Fj.getCellId(1)
           Ck=my_mesh.getCell(k)
           distance=Ci.getBarryCenter().distance(Ck.getBarryCenter())
           coeff=Fj.getMeasure()/Ci.getMeasure()/distance
           Rigidite.setValue(i,k,-coeff) # terme extradiagonal
           coeff=Fj.getMeasure()/Ci.getMeasure()/Ci.getBarryCenter().distance(Fj.getBarryCenter
           #For the particular case where the mesh boundary does not coincide with the domain t
           x=Fj.getBarryCenter().x()
           y=Fj.getBarryCenter().y()
           RHS[i]+=coeff*sin(pi*x)*sin(pi*y) #mettre ici la condition limite du problème de Diri
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Rigidite.addValue(i,i,coeff) # terme diagonal

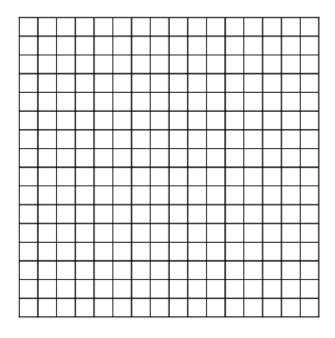
1.5 Regular grid

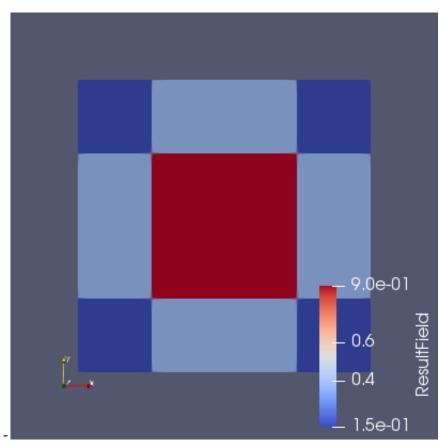


mesh 1 | mesh 2 | mesh 3 - | - - | -

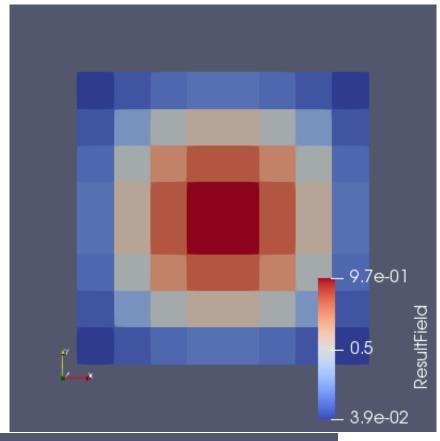


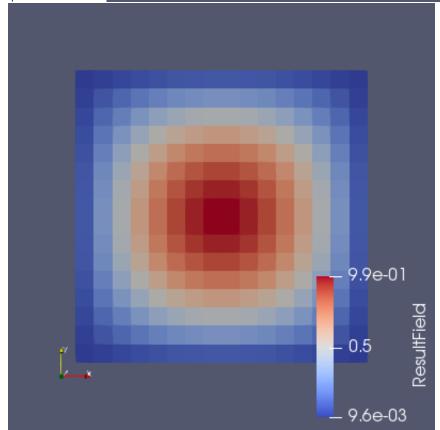
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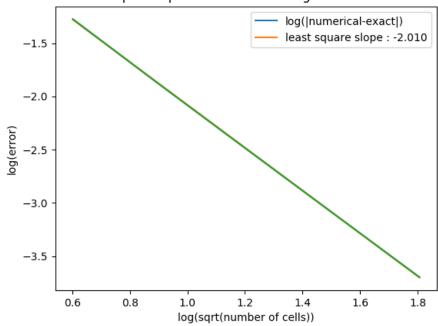


result 1 | result 2 | result 3 - | - - | -

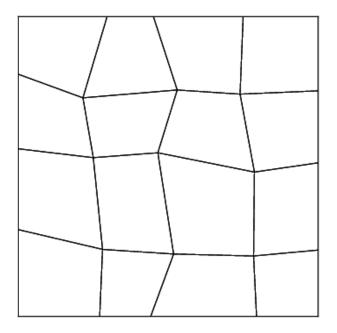




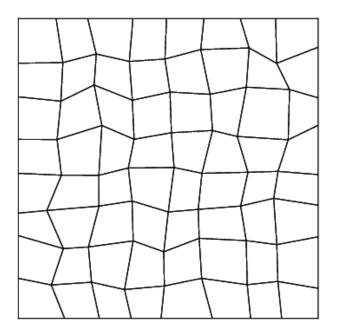
Convergence of finite volumes for Laplace operator on 2D rectangular meshes

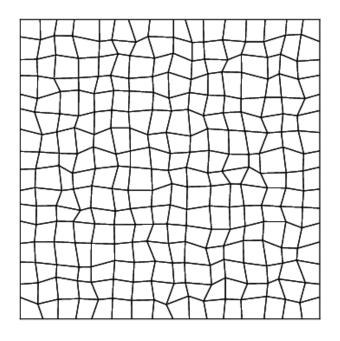


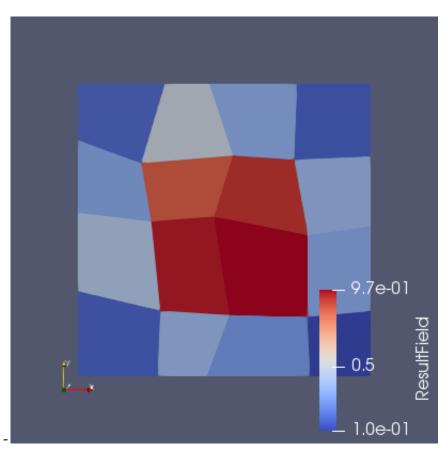
1.6 Deformed quadrangles



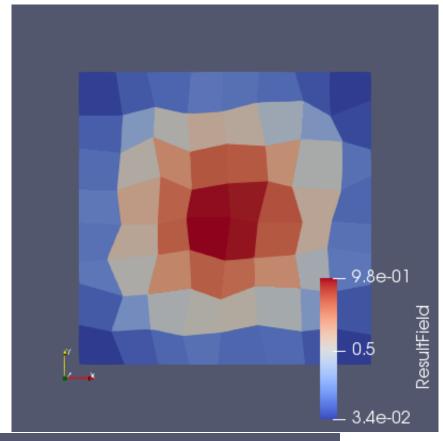
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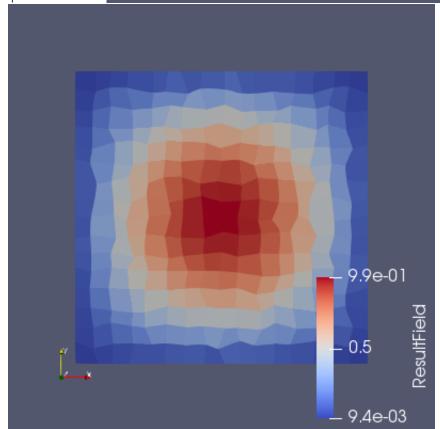


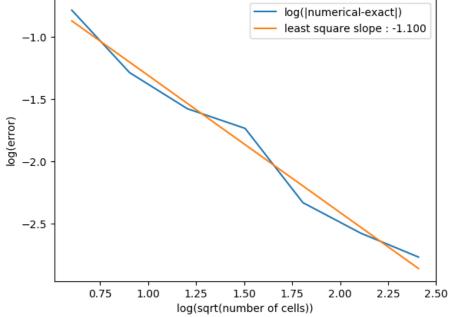




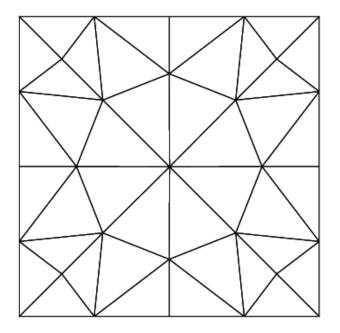
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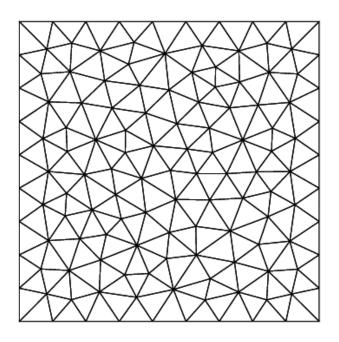


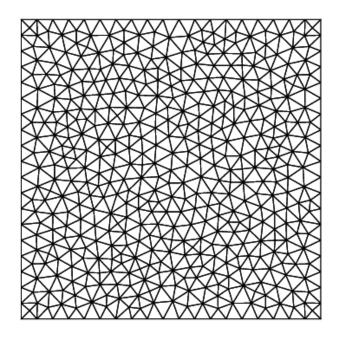


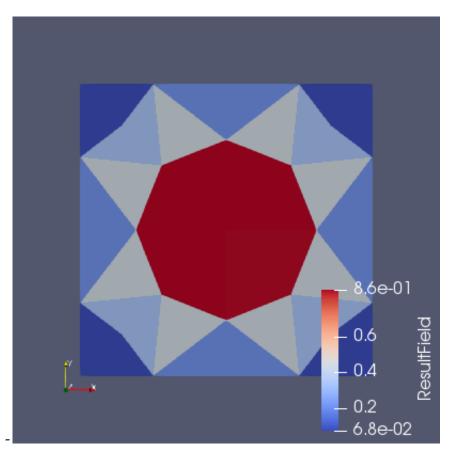
1.7 Delaunay triangular meshes



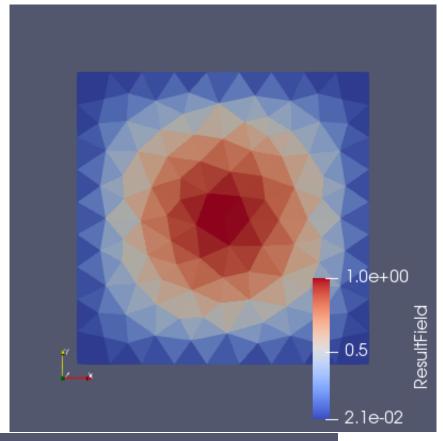
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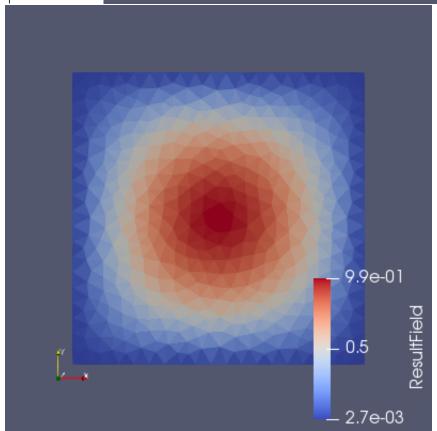


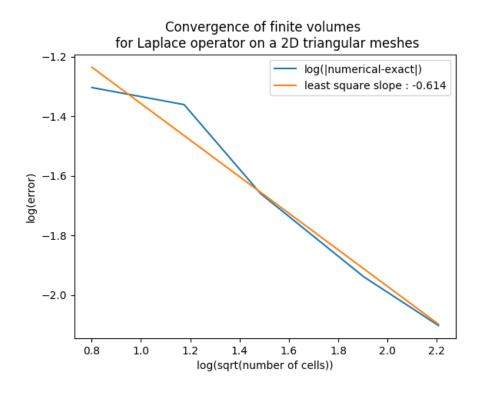




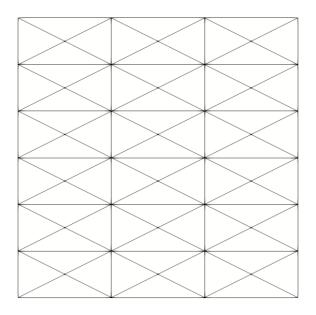
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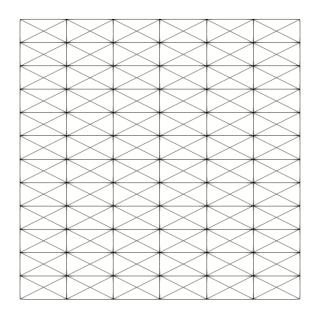


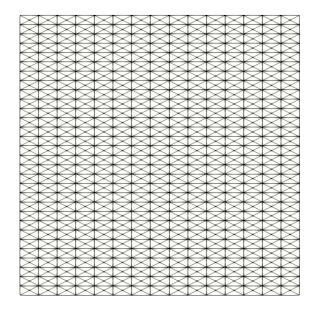


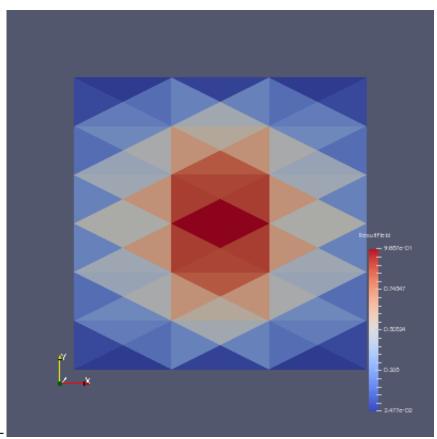
1.8 Cross triangle meshes (from a (n,2n) rectangular grid)



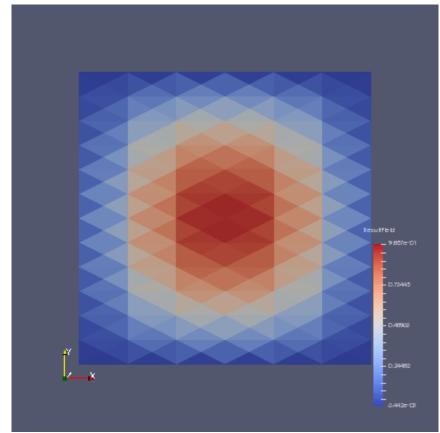
 $mesh \, 1 \mid mesh \, 2 \mid mesh \, 3 \text{-} \mid \text{--} \mid \text{-}$

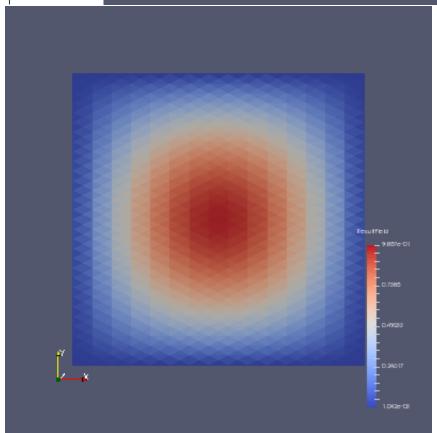


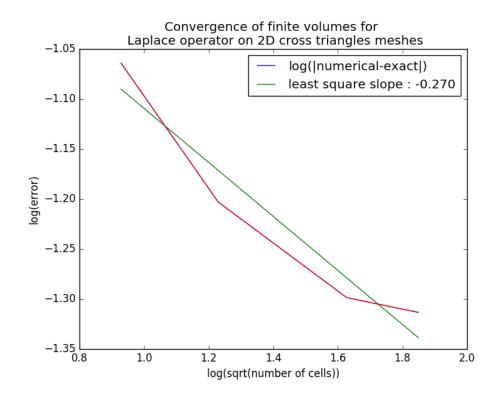




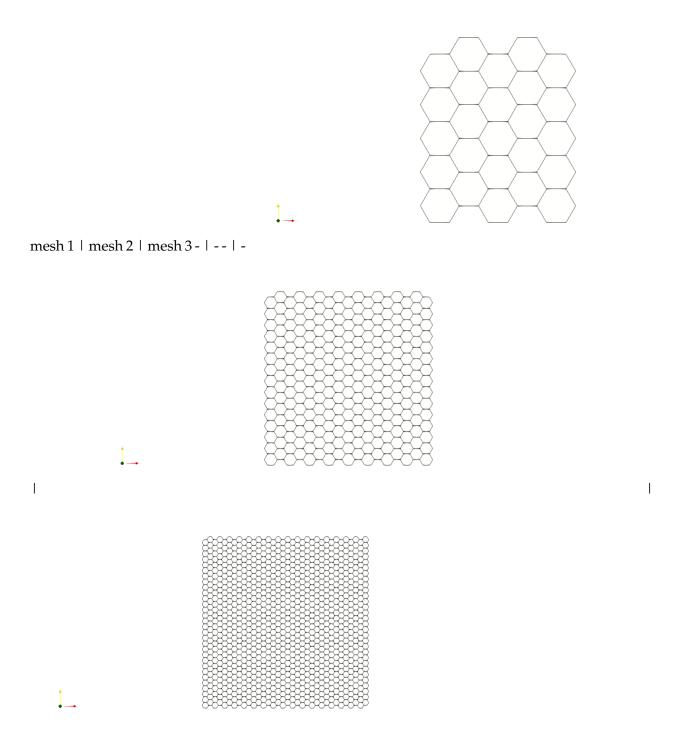
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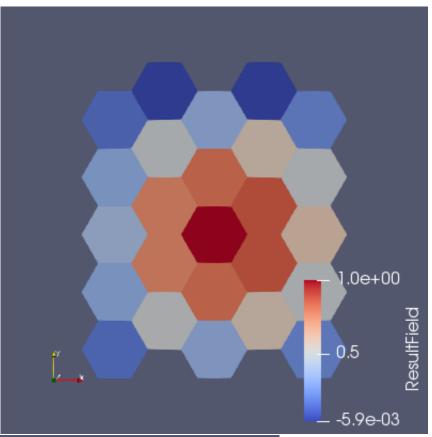




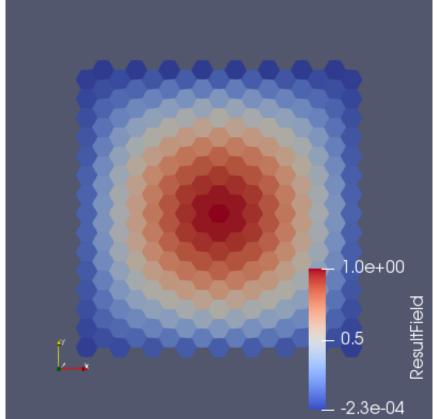


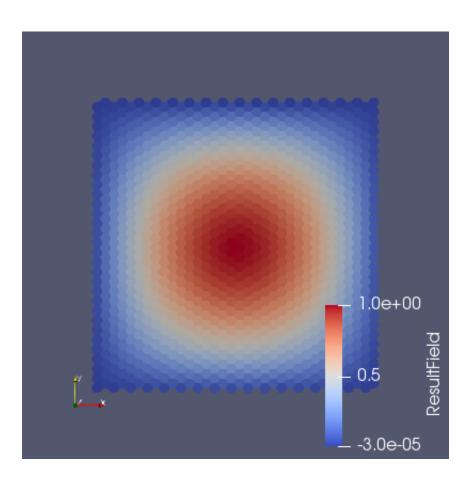
1.9 Hexagonal meshes



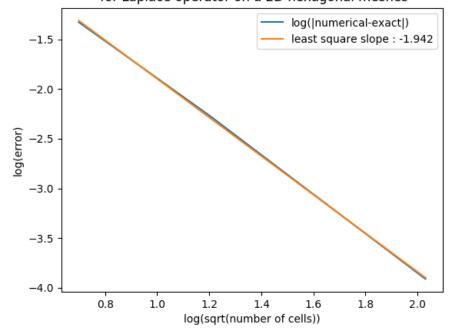




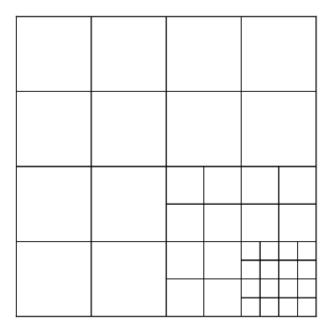




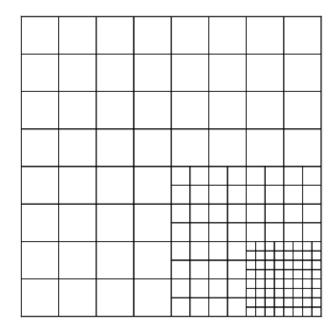
Convergence of finite volumes for Laplace operator on a 2D hexagonal meshes

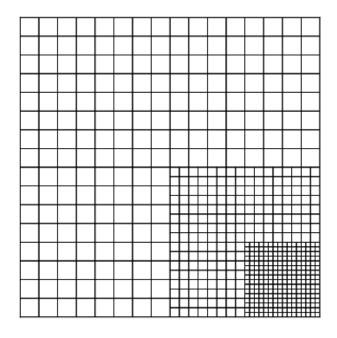


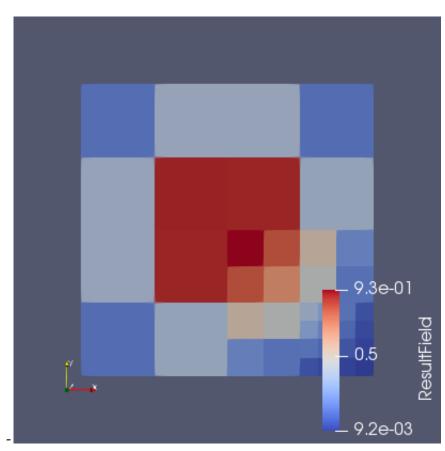
1.10 Locally refined meshes



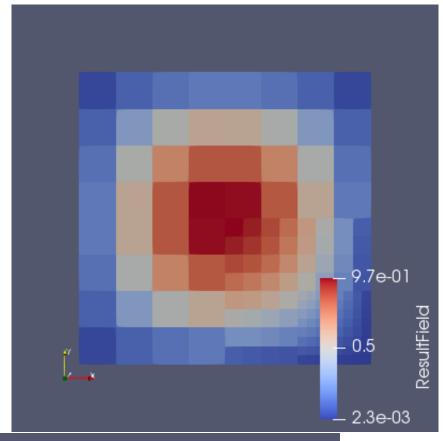
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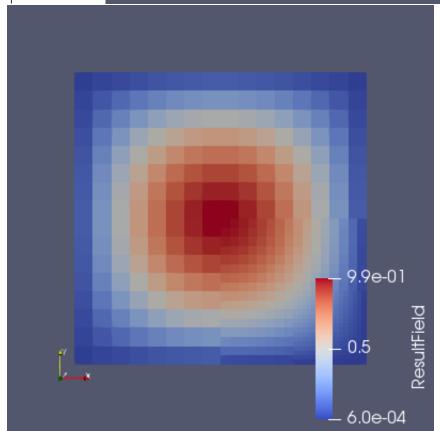


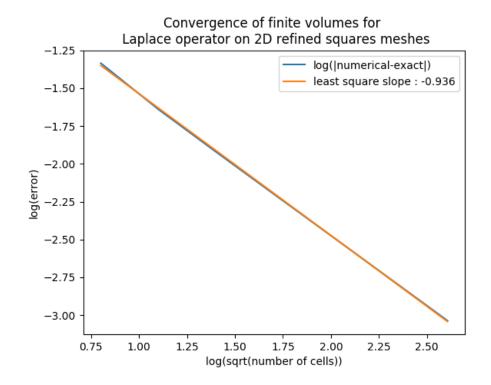




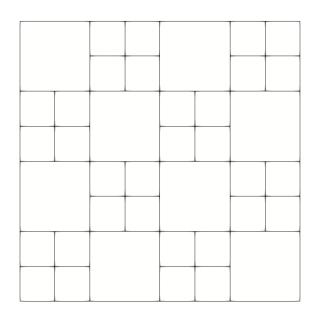
result 1 | result 2 | result 3 - | - - | -



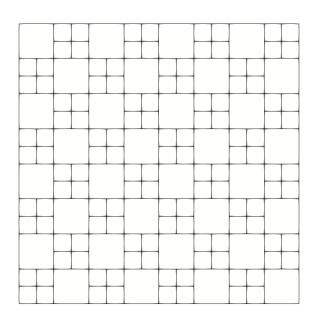


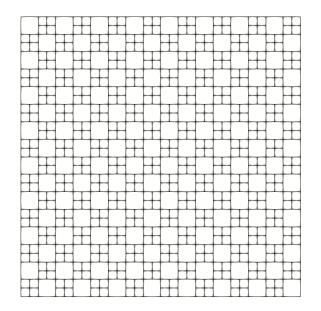


1.11 Checkerboard meshes

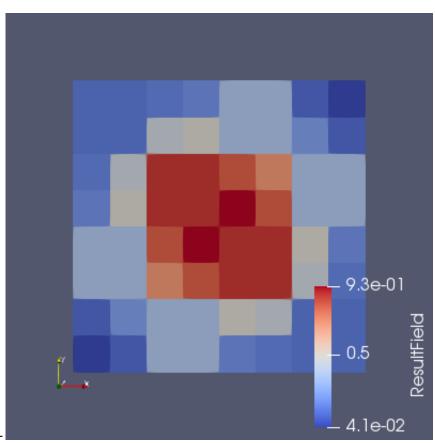


mesh 1 | mesh 2 | mesh 3 - | -- | -

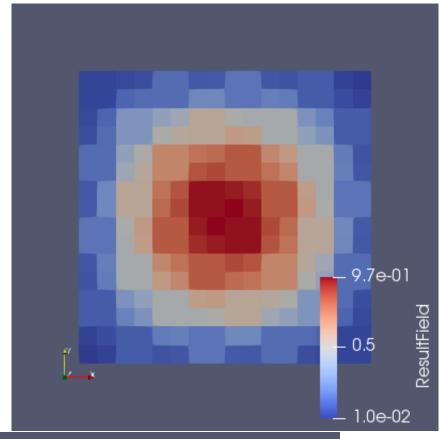


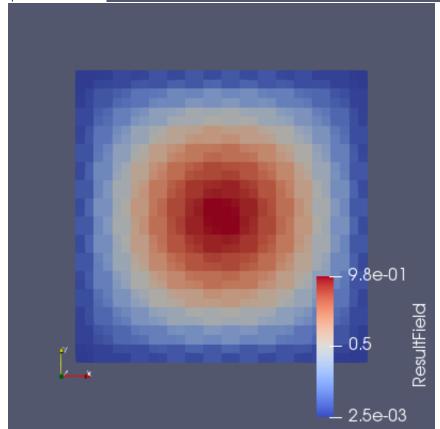


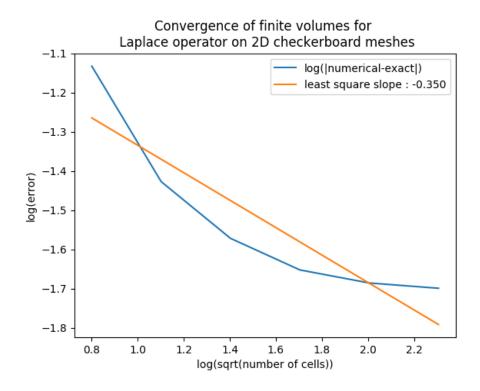




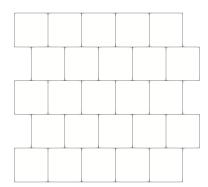
result 1 | result 2 | result 3 - | - - | -



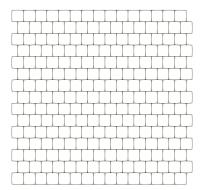




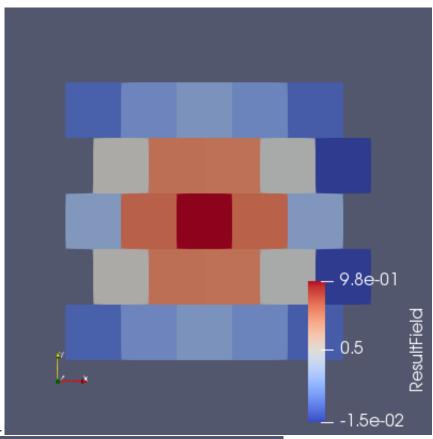
1.12 Brick wall meshes

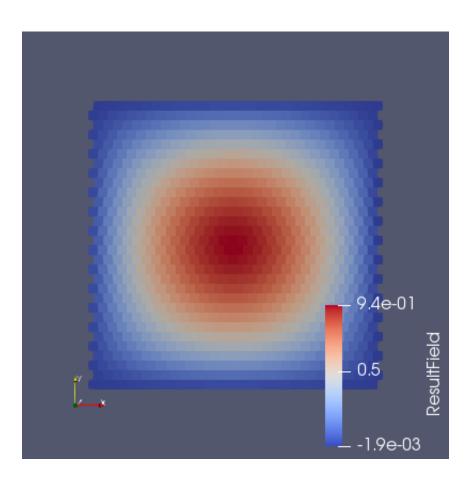


mesh 1 | mesh 2 | mesh 3 - | - - | -

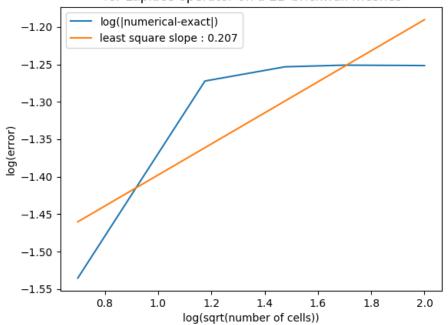


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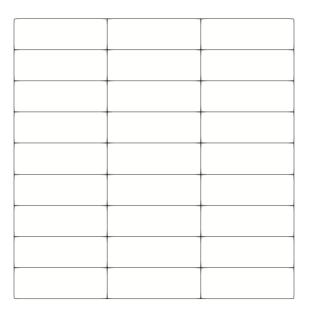




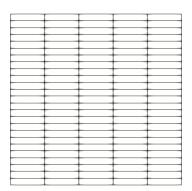
Convergence of finite volumes for Laplace operator on a 2D brickwall meshes

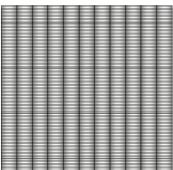


1.13 Long rectangle meshes ((n, n^2) rectangular grid)

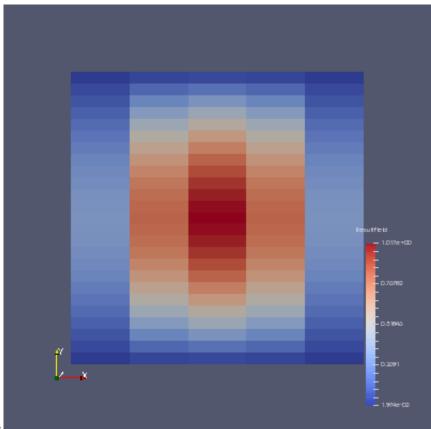


mesh 1 | mesh 2 - | --

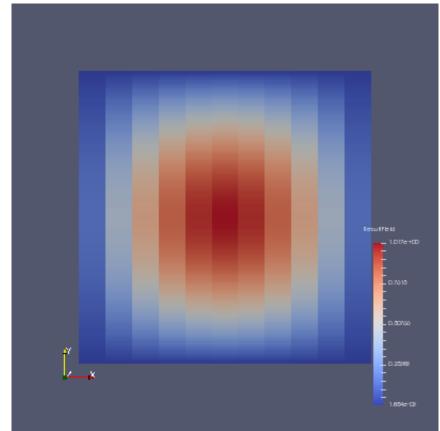


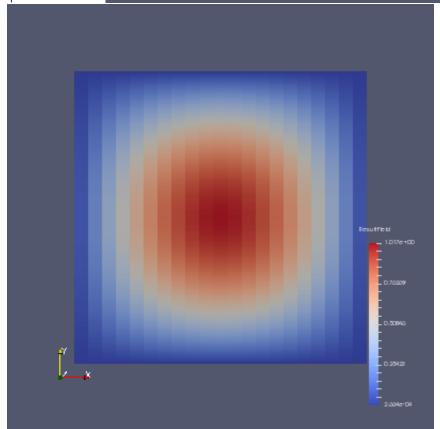


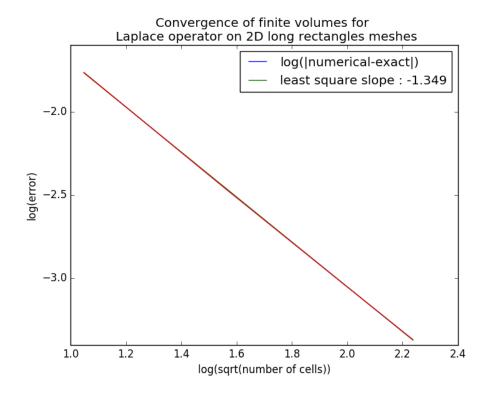
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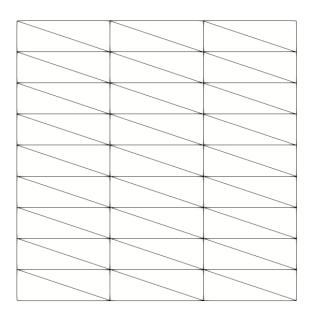
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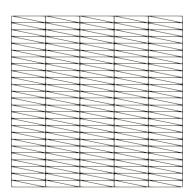




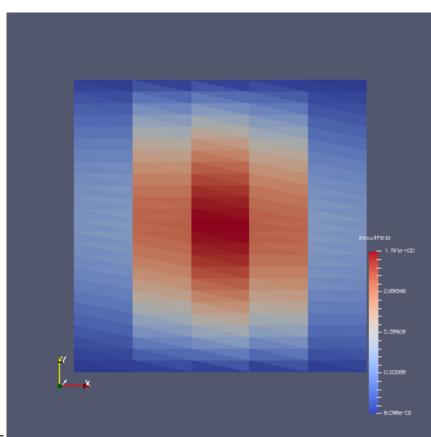
1.14 Long right triangle meshes (from a (n, n^2) rectangular grid)



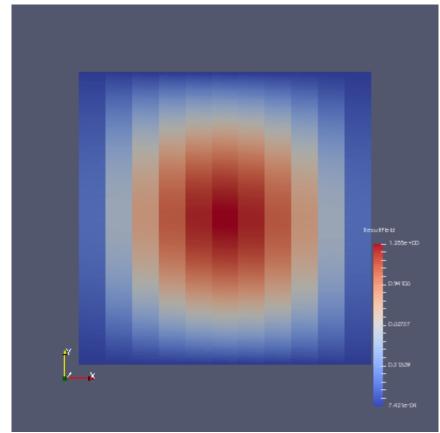
 $mesh\,1\mid mesh\,2\mid mesh\,3\,\text{-}\mid\text{--}\mid\text{--}$

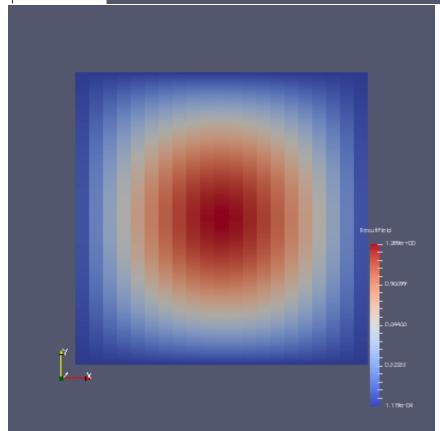


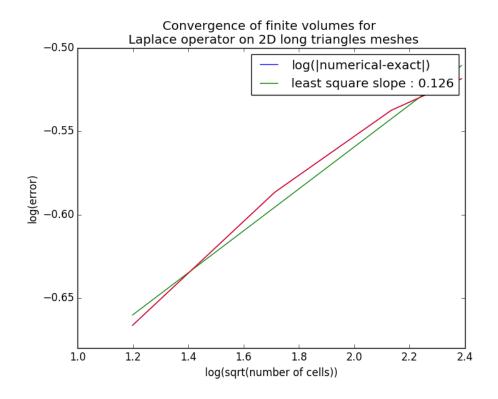




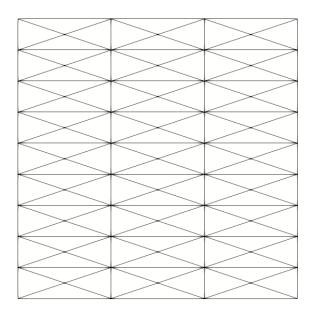
result 1 | result 2 | result 3 - | - - | -



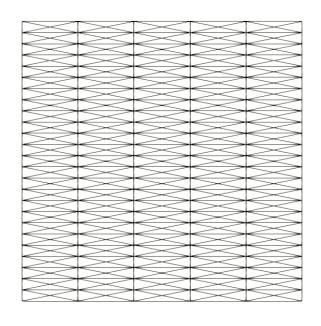


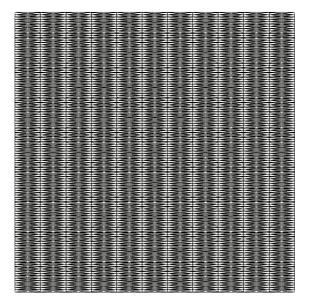


1.15 Flat cross triangle meshes (from a (n, n^2) rectangular grid)

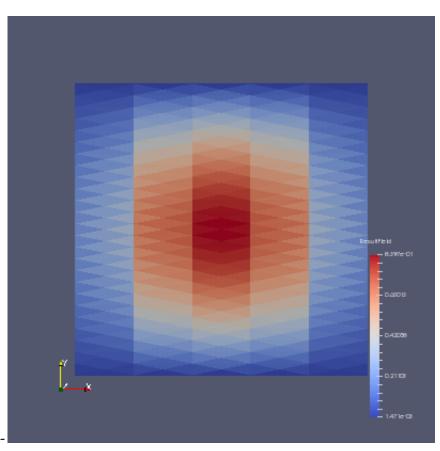


 $mesh\,1\mid mesh\,2\mid mesh\,3\,\text{-}\mid\text{--}\mid\text{--}$









result 1 | result 2 | result 3 - | -- | -

