Convergence_Poisson_FV5_SQUARE_brickwall

October 21, 2018

1 FV5 scheme for Poisson equation on brick wall meshes

1.1 The Poisson problem on the square

We consider the following Poisson problem with Dirichlet boundary conditions

$$\begin{cases} -\Delta u = f \text{ on } \Omega \\ u = 0 \text{ on } \partial \Omega \end{cases}$$

on the square domain $\Omega = [0,1] \times [0,1]$ with

$$f = 2\pi^2 sin(\pi x) sin(\pi y).$$

The unique solution of the problem is

$$u = sin(\pi x)sin(\pi y).$$

The Poisson equation is a particular case of the diffusion problem

$$-\nabla \cdot (K\vec{\nabla}u) = f$$

and the associated diffusion flux is

$$F(u) = K\nabla u$$
.

1.2 The FV5 scheme for the Laplace equation

The domain Ω is decomposed into cells C_i .

 $|C_i|$ is the measure of the cell C_i .

 f_{ij} is the interface between two cells C_i and C_j .

 s_{ij} is the measure of the interface f_{ij} .

 d_{ij} is the distance between the centers of mass of the two cells C_i and C_j .

The discrete Poisson problem is

$$-\frac{1}{|C_i|}\sum s_{ij}F_{ij}=f_i,$$

where u_i is the approximation of u in the cell C_i ,

 f_i is the approximation of f in the cell C_i ,

 F_{ij} is a numerical approximation of the outward normal diffusion flux from cell i to cell j. In the case of the scheme FV5, we use the formula

$$F_{ij} = \frac{u_j - u_i}{d_{ij}}.$$

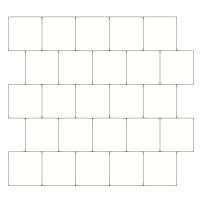
1.3 The script

SolSyst=LS.solve()

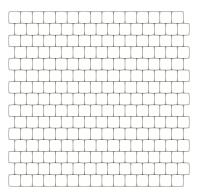
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#Discrétisation du second membre et extraction du nb max de voisins d'une cellule
#-----
my_RHSfield = cdmath.Field("RHS_field", cdmath.CELLS, my_mesh, 1)
maxNbNeighbours=0#This is to determine the number of non zero coefficients in the sparse finite
for i in range(nbCells):
   Ci = my_mesh.getCell(i)
   x = Ci.x()
   y = Ci.y()
   my_RHSfield[i]=2*pi*pi*sin(pi*x)*sin(pi*y)#mettre la fonction definie au second membre de l
   # compute maximum number of neighbours
   maxNbNeighbours= max(1+Ci.getNumberOfFaces(), maxNbNeighbours)
# Construction de la matrice et du vecteur second membre du système linéaire
#-----
Rigidite=cdmath.SparseMatrixPetsc(nbCells,nbCells,maxNbNeighbours)# warning : third argument is
RHS=cdmath.Vector(nbCells)
#Parcours des cellules du domaine
for i in range(nbCells):
   RHS[i]=my_RHSfield[i] #la valeur moyenne du second membre f dans la cellule i
   Ci=my_mesh.getCell(i)
   for j in range(Ci.getNumberOfFaces()): # parcours des faces voisinnes
       Fj=my_mesh.getFace(Ci.getFaceId(j))
       if not Fj.isBorder():
          k=Fj.getCellId(0)
          if k==i:
              k=Fj.getCellId(1)
          Ck=my_mesh.getCell(k)
          distance=Ci.getBarryCenter().distance(Ck.getBarryCenter())
          coeff=Fj.getMeasure()/Ci.getMeasure()/distance
          Rigidite.setValue(i,k,-coeff) # terme extradiagonal
       else:
          coeff=Fj.getMeasure()/Ci.getMeasure()/Ci.getBarryCenter().distance(Fj.getBarryCenter
       Rigidite.addValue(i,i,coeff) # terme diagonal
       #For the particular case where the mesh boundary does not coincide with the domain bound
          x=Fj.getBarryCenter().x()
          y=Fj.getBarryCenter().y()
          RHS[i]+=coeff*sin(pi*x)*sin(pi*y)#mettre ici la condition limite du problème de Dire
# Résolution du système linéaire
LS=cdmath.LinearSolver(Rigidite,RHS,500,1.E-6,"GMRES","ILU")
```

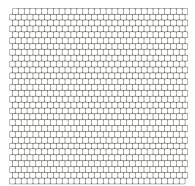
1.4 Numerical results on a triangular mesh

1.4.1 Meshes



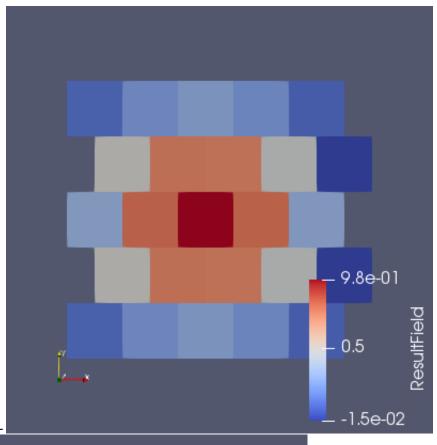
mesh 1 | mesh 2 | mesh 3 - | - - | -



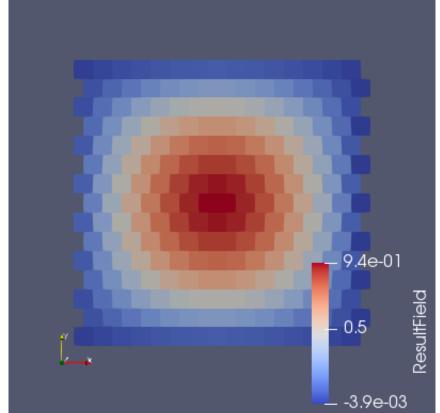


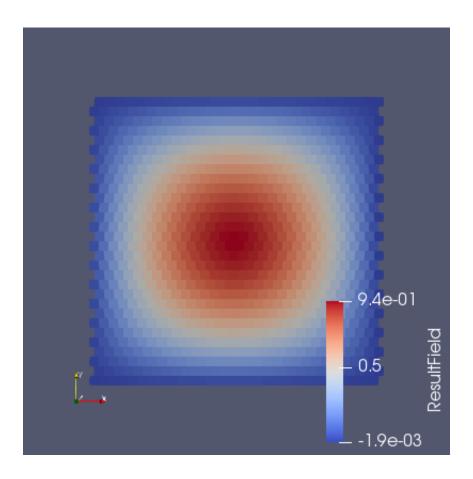
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1.4.2 Numerical results



 $result \, 1 \mid result \, \underline{2 \mid result \, 3 \text{------}}$





1.4.3 Convergence curves

Convergence of finite volumes for Laplace operator on a 2D brickwall meshes

