

FV5 scheme for Poisson equation

The Poisson problem on the square

We consider the following Poisson problem with Dirichlet boundary conditions

$$\begin{cases} -\Delta u = f \text{ on } \Omega \\ u = 0 \text{ on } \partial\Omega \end{cases}$$

on the square domain $\Omega = [0, 1] \times [0, 1]$ with

$$f = 2\pi^2 \sin(\pi x) \sin(\pi y).$$

The unique solution of the problem is

$$u = -\sin(\pi x) \sin(\pi y).$$

The Poisson equation is a particular case of the diffusion problem

$$-\nabla \cdot (K \vec{\nabla} u) = f$$

and the associated diffusion flux is

$$F(u) = K \vec{\nabla} u.$$

The FV5 scheme for the Laplace equation

The domain Ω is decomposed into cells C_i .

$|C_i|$ is the measure of the cell C_i .

f_{ij} is the interface between two cells C_i and C_j .

s_{ij} is the measure of the interface f_{ij} .

d_{ij} is the distance between the centers of mass of the two cells C_i and C_j .

The discrete Poisson problem is

$$-\frac{1}{|C_i|} \sum s_{ij} F_{ij} = f_i,$$

where u_i is the approximation of u in the cell C_i ,

f_i is the approximation of f in the cell C_i ,

F_{ij} is a numerical approximation of the outward normal diffusion flux from cell i to cell j .

In the case of the scheme FV5, we use the formula

$$F_{ij} = \frac{u_j - u_i}{d_{ij}}.$$

The script


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#Discrétisation du second membre et extraction du nb max de voisins d'une cellule
#=====
==
my_RHSfield = cdmath.Field("RHS_field", cdmath.CELLS, my_mesh, 1)
maxNbNeighbours=0#This is to determine the number of non zero coefficients in the sparse finite element rigidity matrix

for i in range(nbCells):
    Ci = my_mesh.getCell(i)
    x = Ci.x()
    y = Ci.y()

    my_RHSfield[i]=2*pi*pi*sin(pi*x)*sin(pi*y)#mettre la fonction definie au second membre de l'edp
    # compute maximum number of neighbours
    maxNbNeighbours= max(1+Ci.getNumberOfFaces(),maxNbNeighbours)

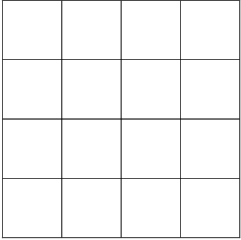
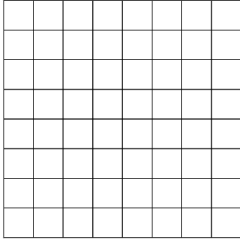
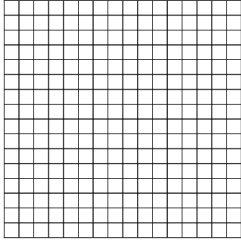
# Construction de la matrice et du vecteur second membre du système linéaire
#=====
Rigidite=cdmath.SparseMatrixPetsc(nbCells,nbCells,maxNbNeighbours)# warning : the third argument is max number of non zero coefficients per line of the matrix
RHS=cdmath.Vector(nbCells)
#Parcours des cellules du domaine
for i in range(nbCells):
    RHS[i]=my_RHSfield[i] #la valeur moyenne du second membre f dans la cellule i
    Ci=my_mesh.getCell(i)
    for j in range(Ci.getNumberOfFaces()):# parcours des faces voisines
        Fj=my_mesh.getFace(Ci.getFaceId(j))
        if not Fj.isBorder():
            k=Fj.getCellId(0)
            if k==i :
                k=Fj.getCellId(1)
            Ck=my_mesh.getCell(k)
            distance=Ci.getBarryCenter().distance(Ck.getBarryCenter())
            coeff=Fj.getMeasure()/Ci.getMeasure()/distance
            Rigidite.setValue(i,k,-coeff) # terme extradiagonal
        else:
            coeff=Fj.getMeasure()/Ci.getMeasure()/Ci.getBarryCenter().distance(Fj.getBarryCenter())
            Rigidite.addValue(i,i,coeff) # terme diagonal

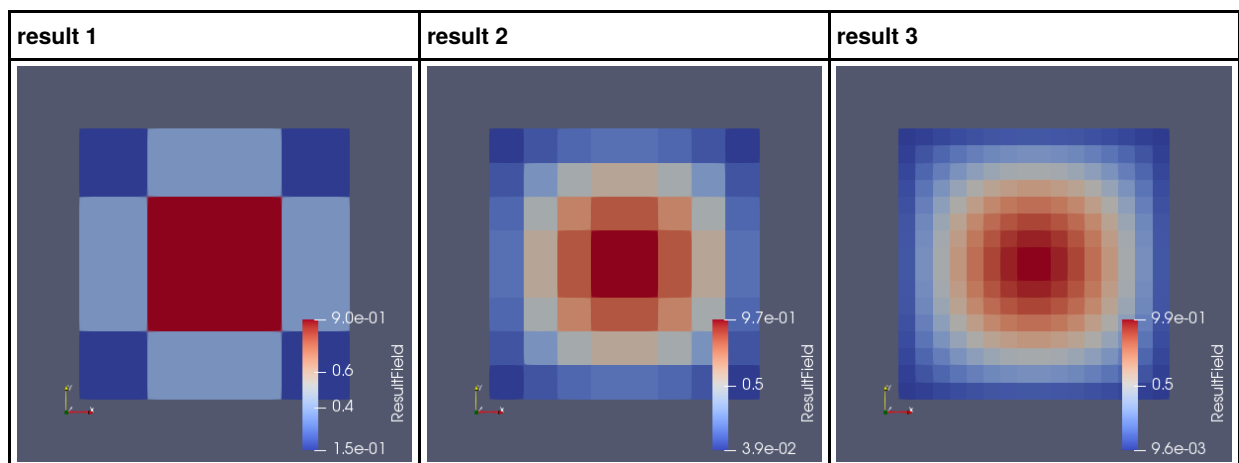
# Résolution du système linéaire
#=====
LS=cdmath.LinearSolver(Rigidite,RHS,500,1.E-6,"GMRES","ILU")
SolSyst=LS.solve()

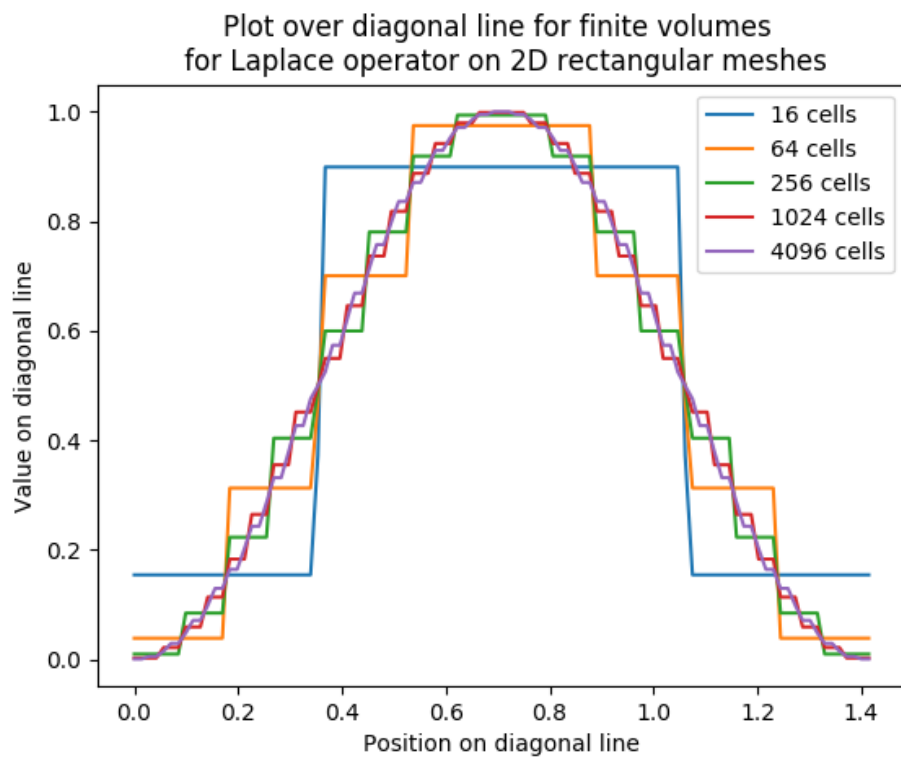
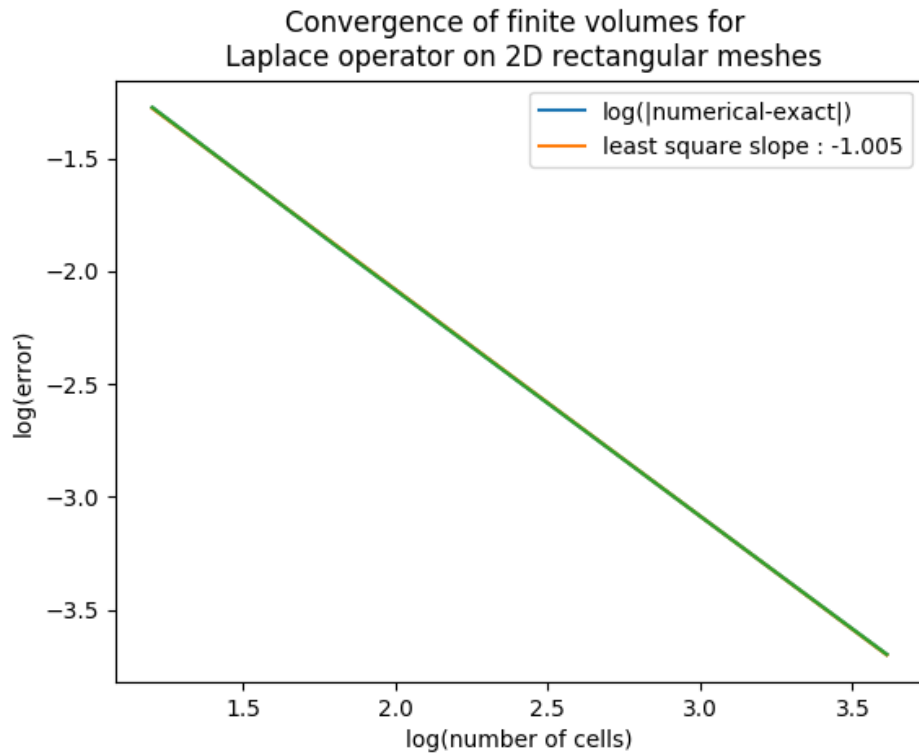
# Automatic postprocessing : save 2D picture and plot diagonal data
#=====
diag_data=VTK_routines.Extract_field_data_over_line_to_numpyArray(my_ResultField,[0,1,0],[1,0,0], resolution)
plt.legend()
plt.xlabel('Position on diagonal line')
plt.ylabel('Value on diagonal line')
if len(sys.argv) >1 :

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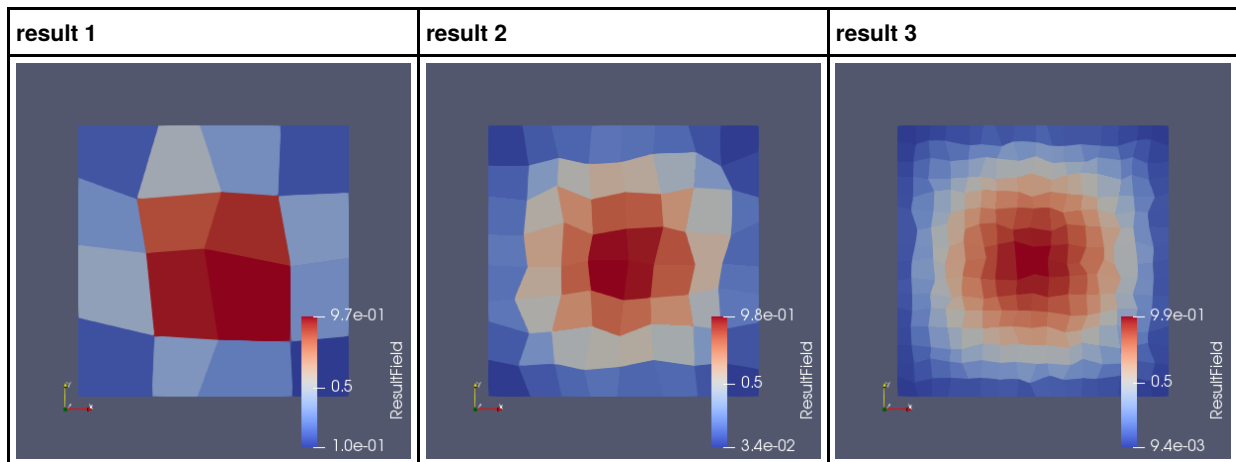
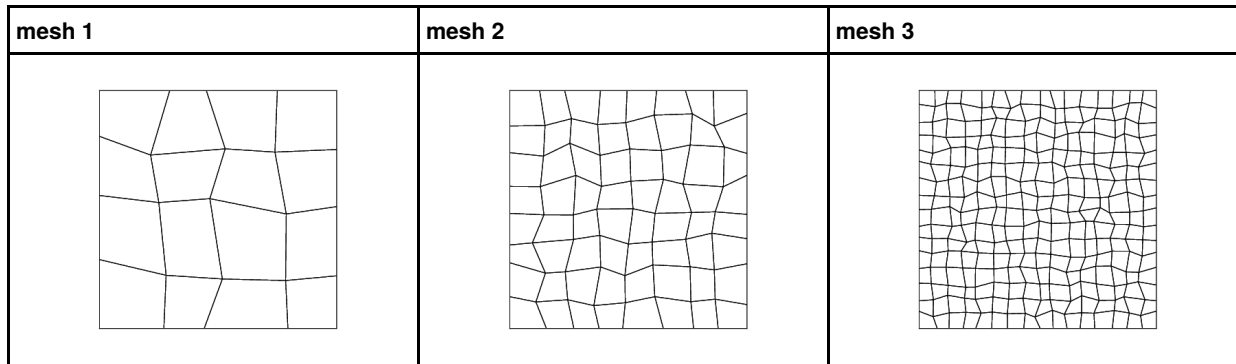
Regular grid

mesh 1	mesh 2	mesh 3
		

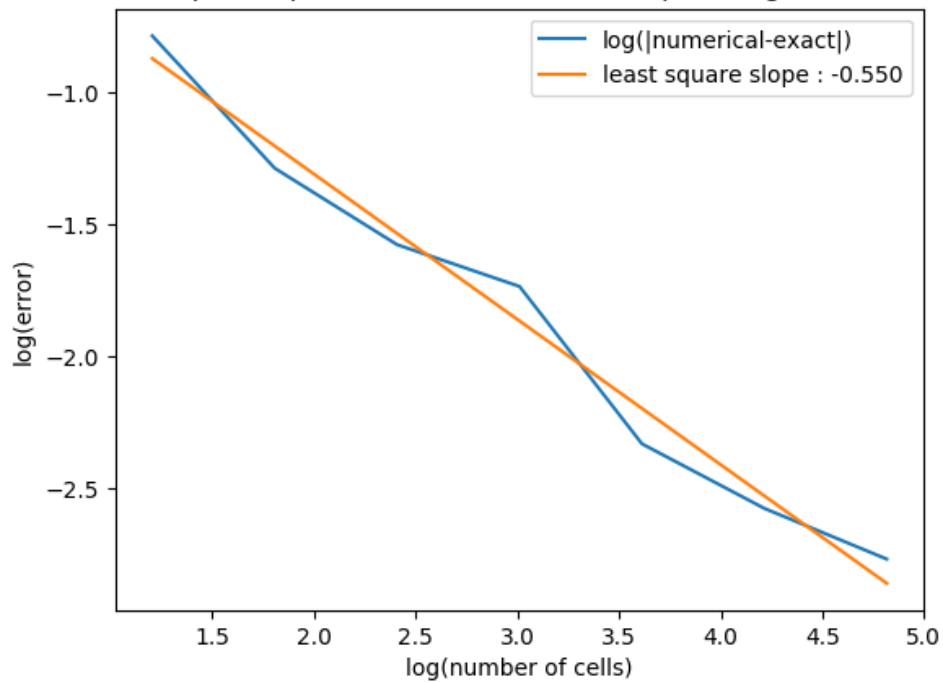




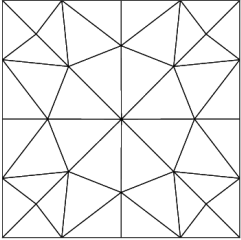
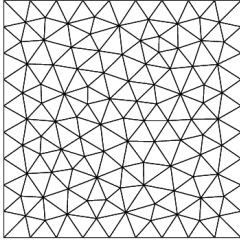
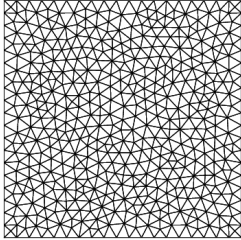
Deformed quadrangles

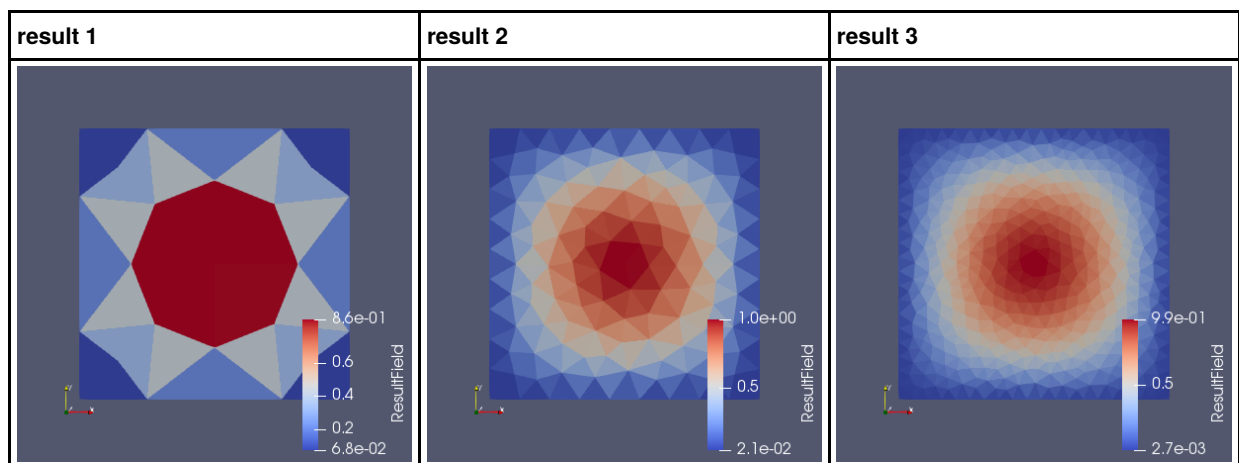


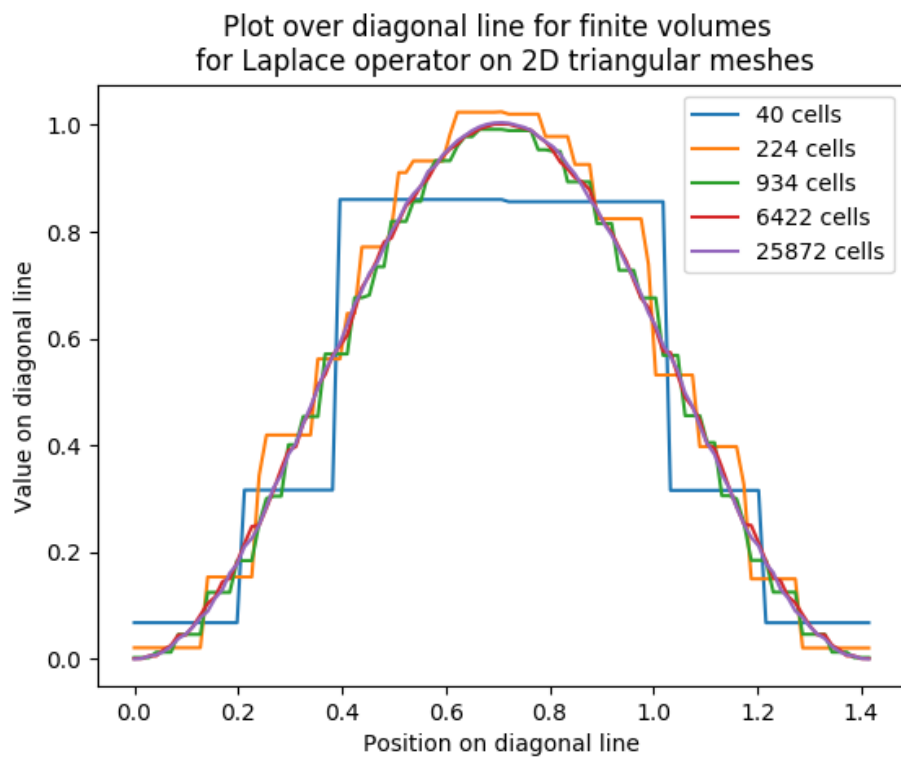
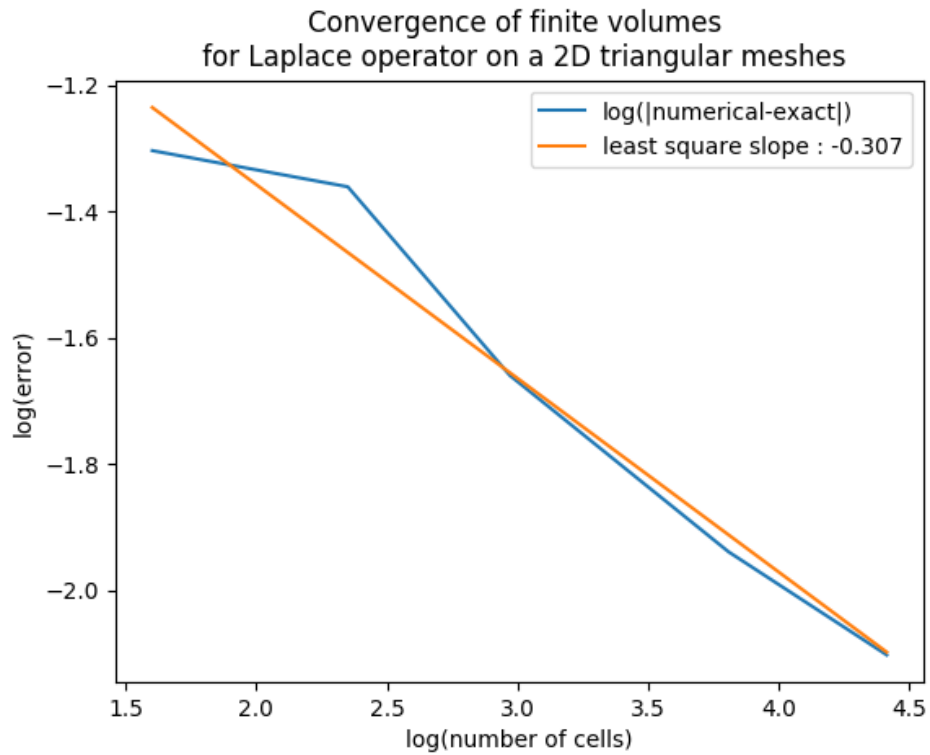
Convergence of finite volumes
for Laplace operator on a 2D deformed quadrangles meshes



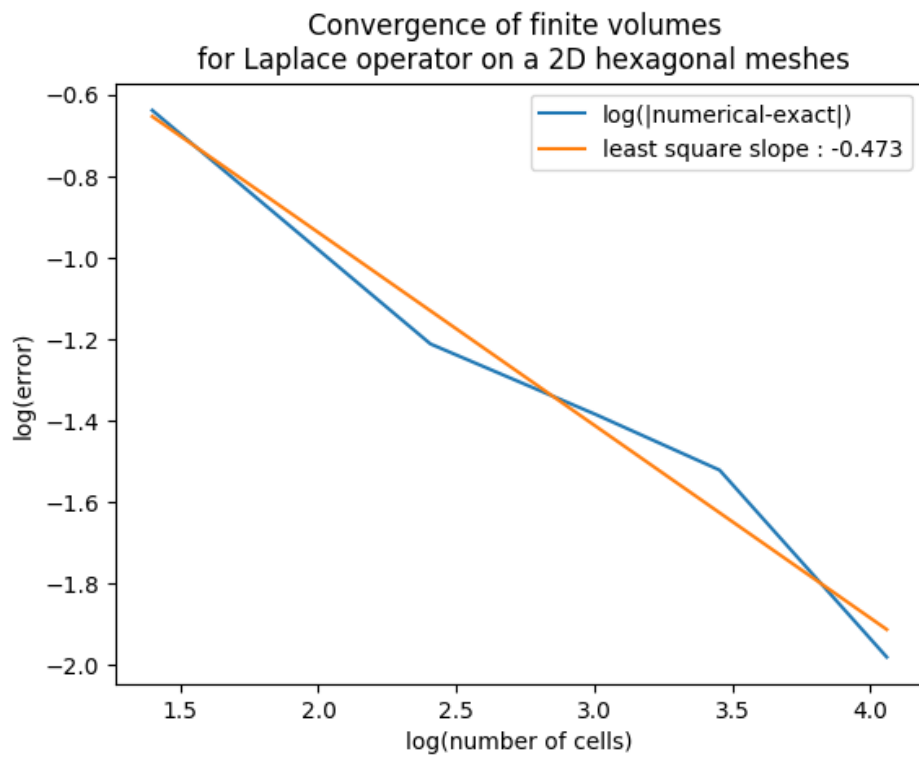
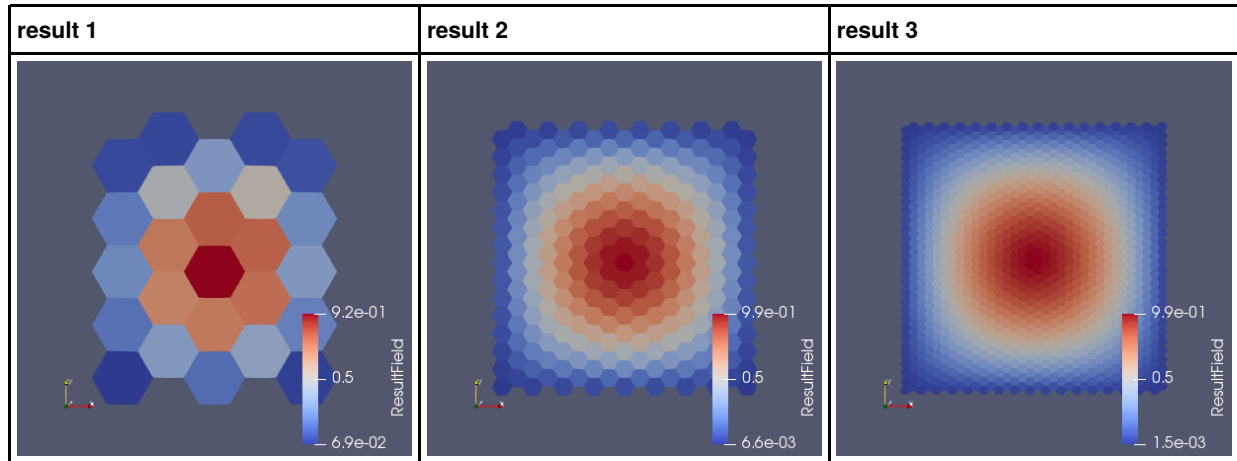
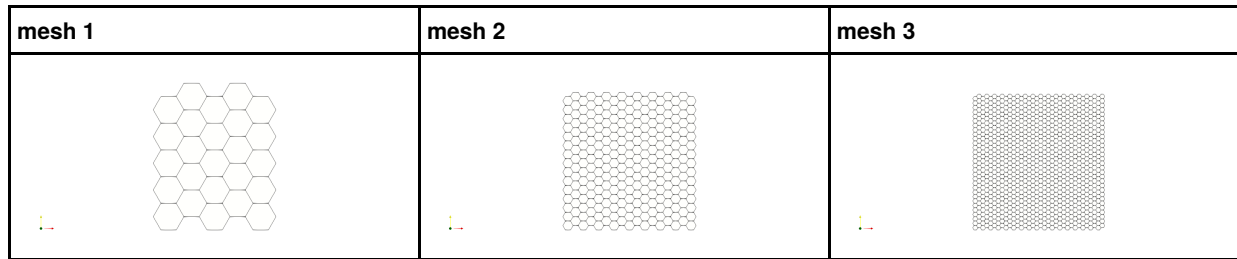
Triangular meshes

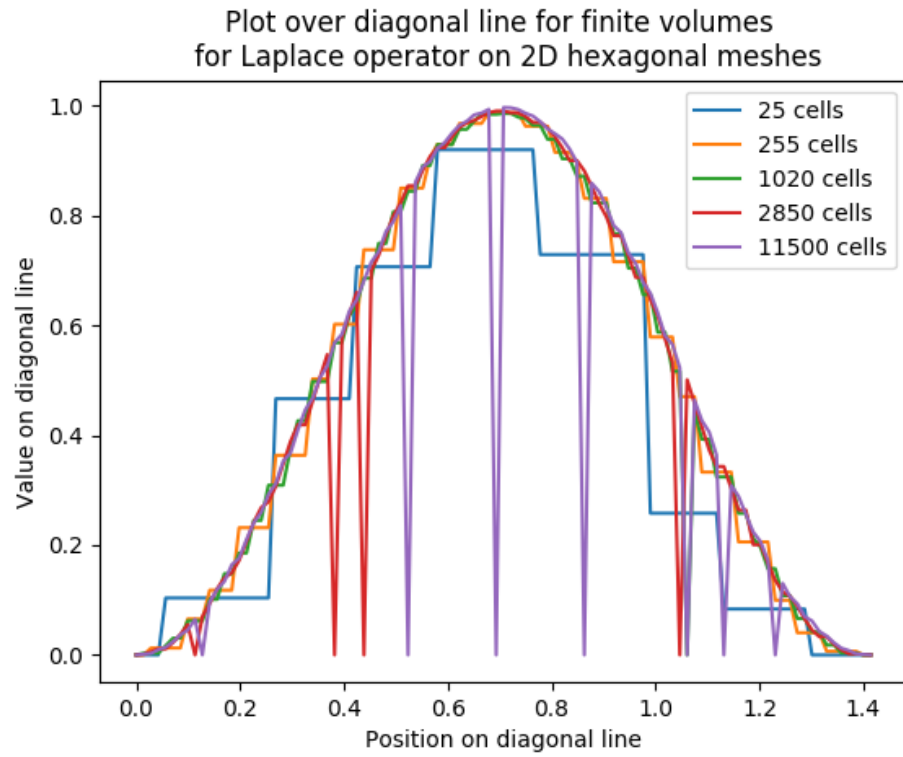
mesh 1	mesh 2	mesh 3
		



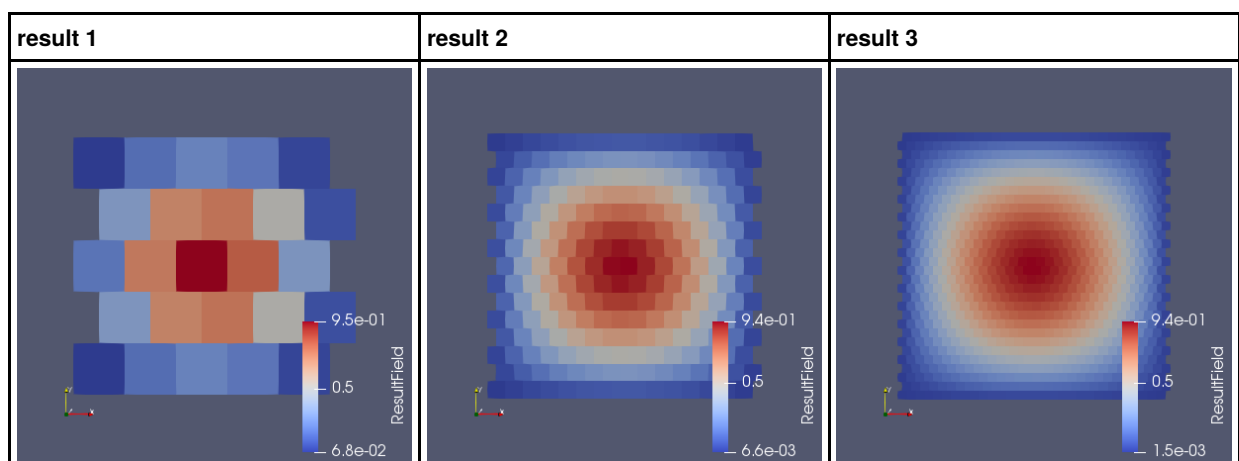
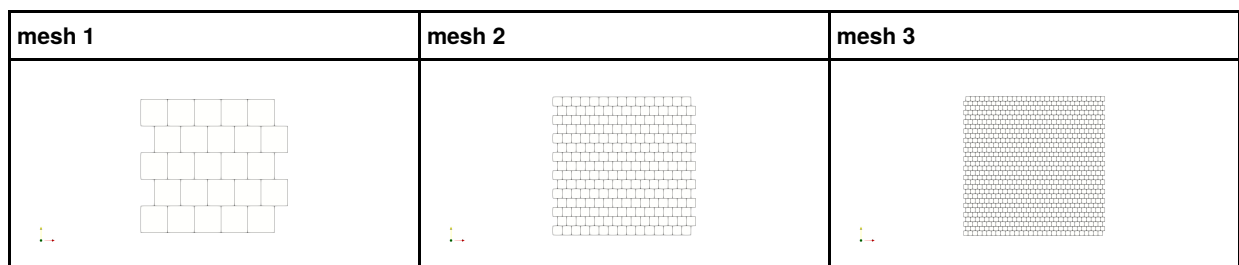


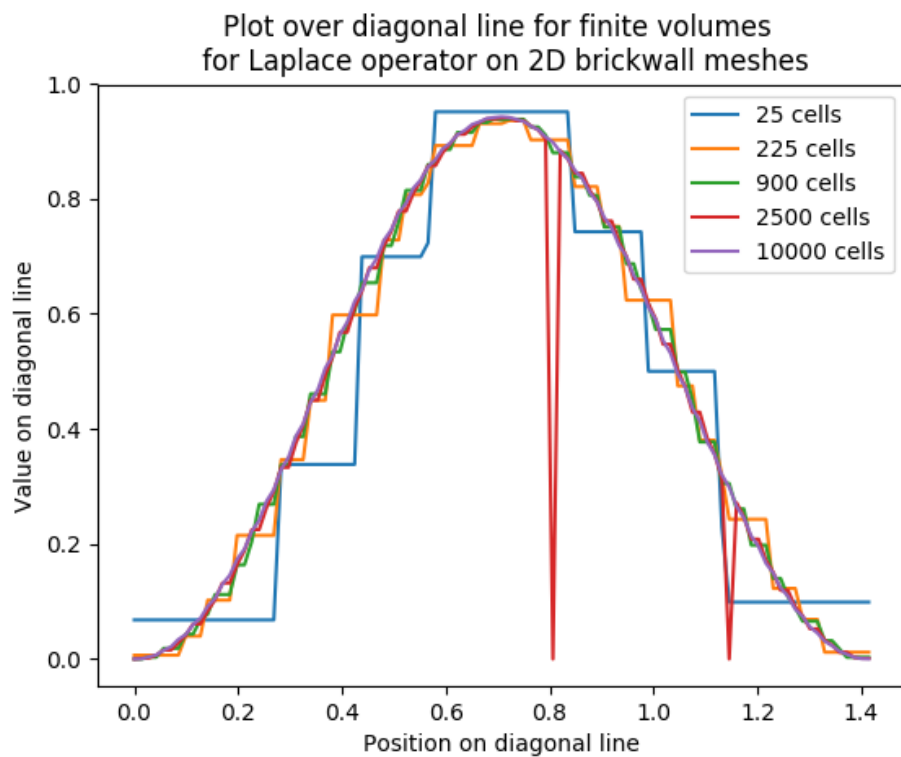
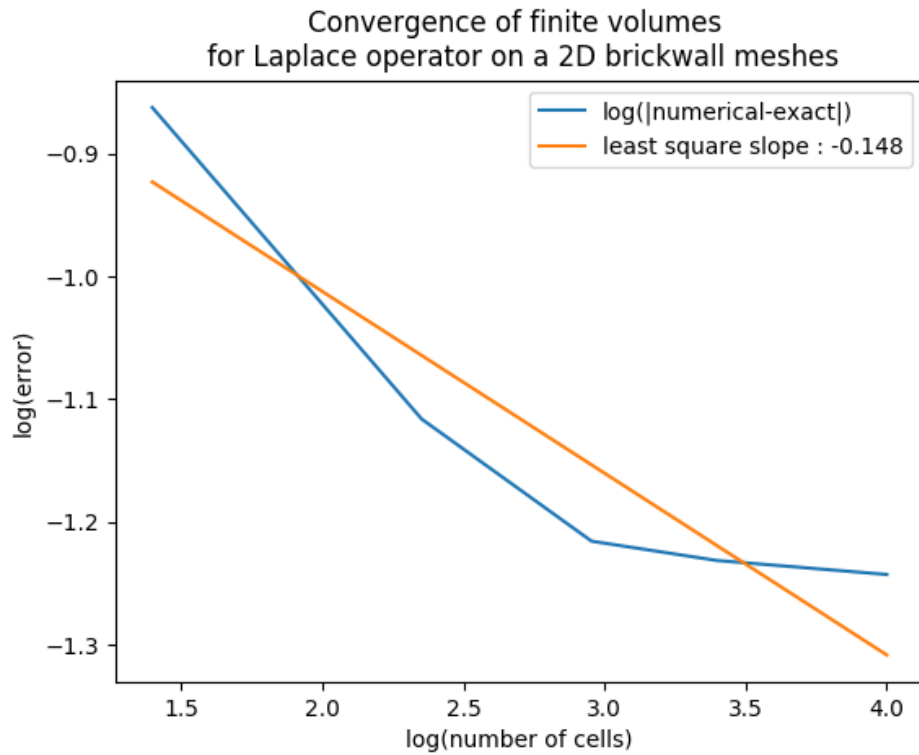
Hexagonal meshes



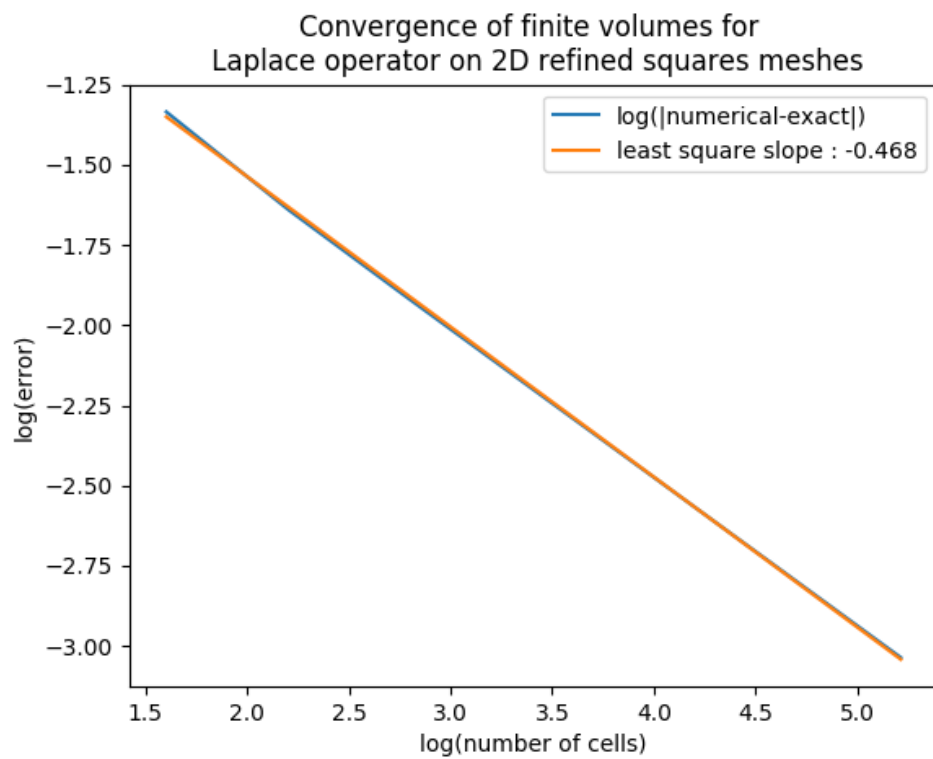
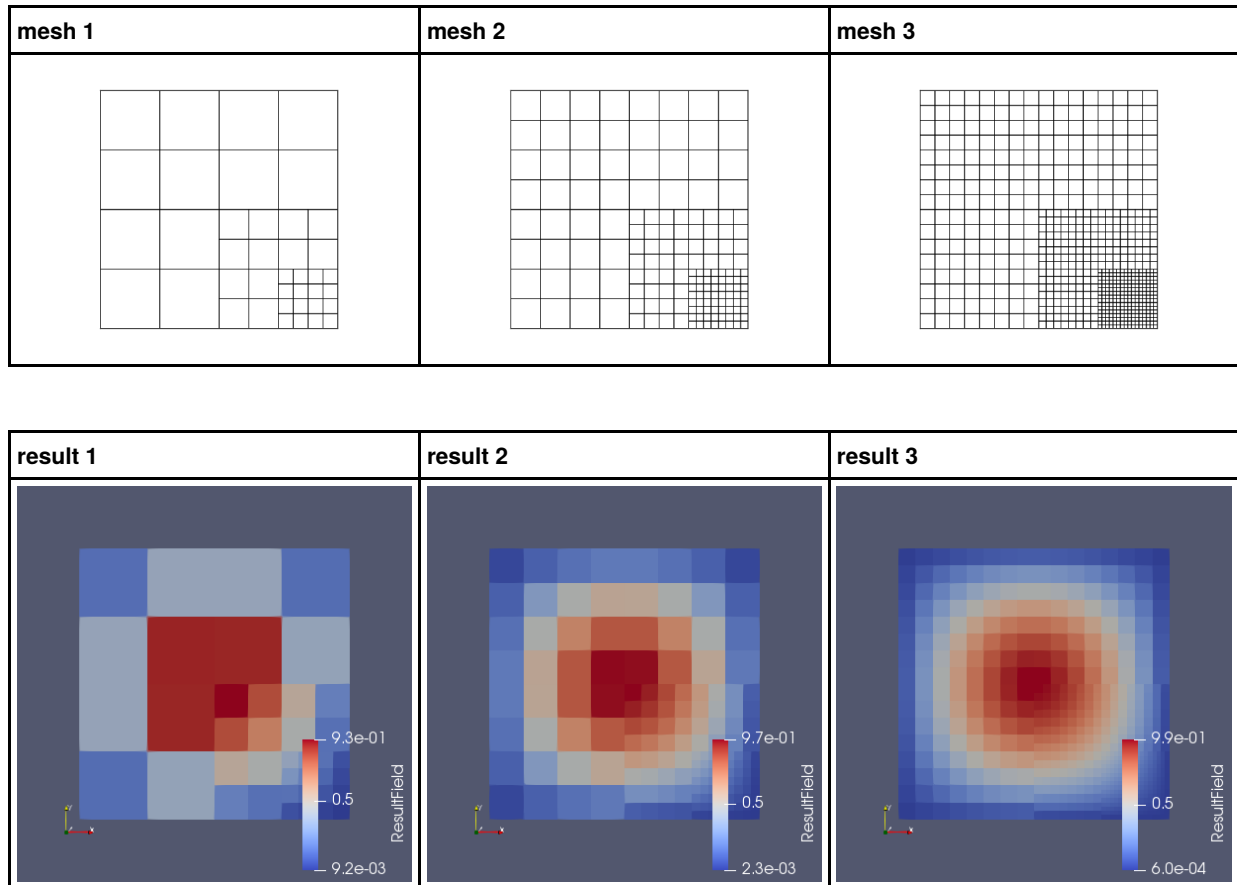


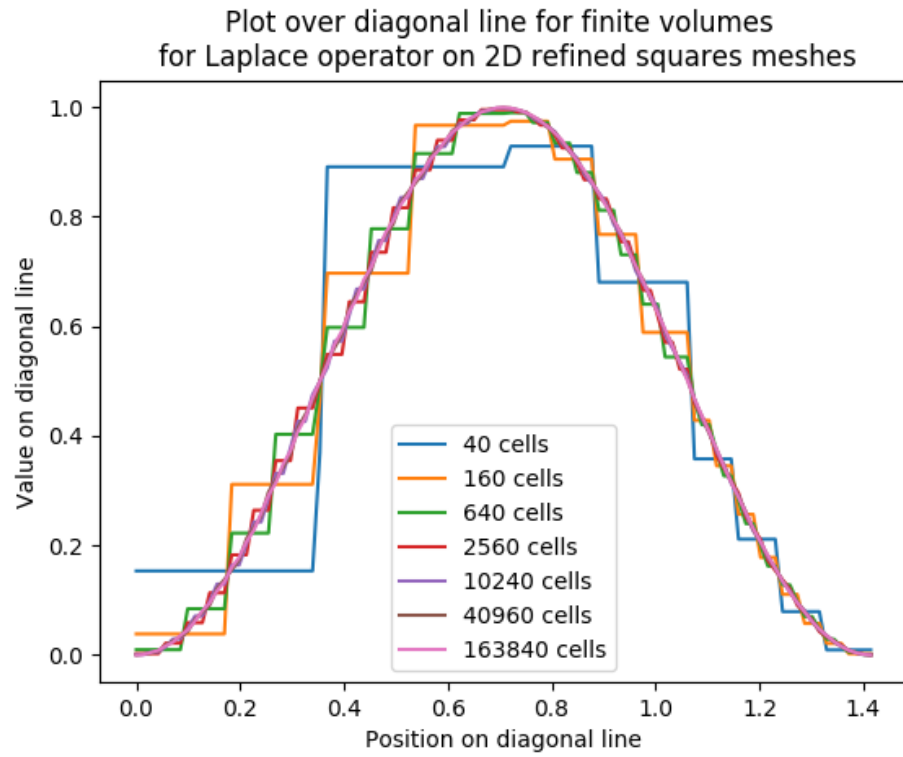
Brick wall meshes



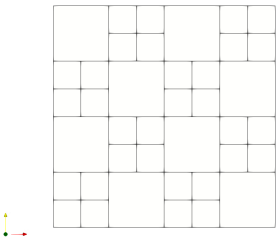
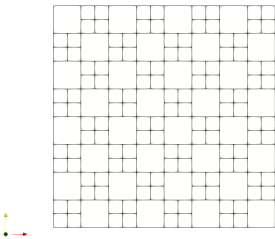
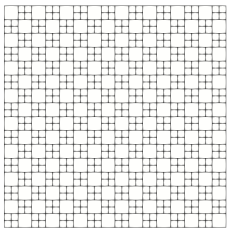


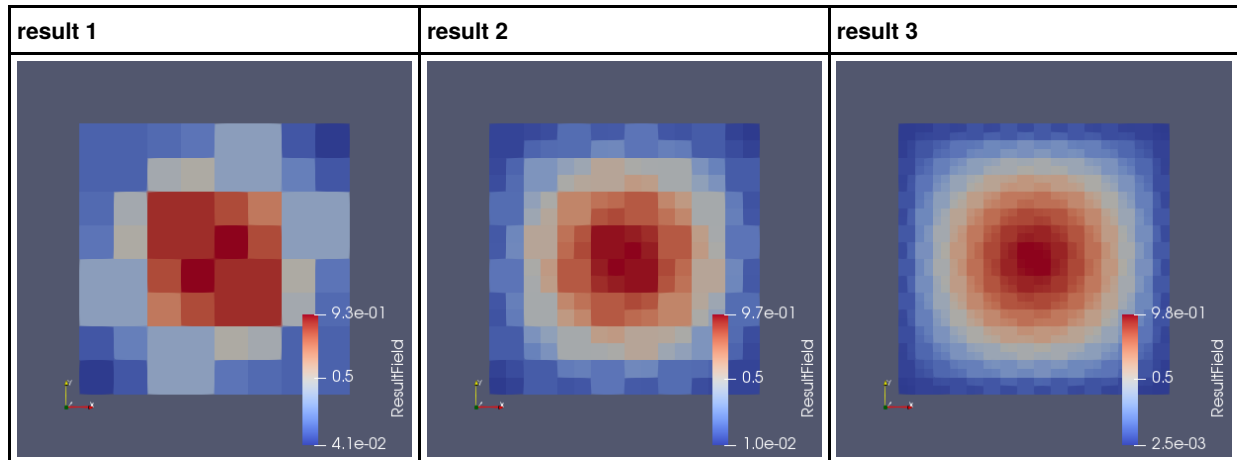
Locally refined meshes





Checkerboard meshes

mesh 1	mesh 2	mesh 3
		



Convergence of finite volumes for Laplace operator on a 2D checkerboard mes

