

Convergence_Diffusion_FV5_SQUARE

January 26, 2019

```
In [15]: from IPython.display import display, Markdown
with open('DiffusionProblemOnSquare.md', 'r') as file1:
    DiffusionProblemOnSquare = file1.read()
with open('DescriptionFV5DiffusionProblem.md', 'r') as file2:
    DescriptionFV5DiffusionProblem = file2.read()
with open('CodeFV5DiffusionProblem.md', 'r') as file3:
    CodeFV5DiffusionProblem = file3.read()
```

1 FV5 scheme for a Diffusion equation

```
In [16]: display(Markdown(DiffusionProblemOnSquare))
```

1.1 The Diffusion problem on the square

We consider the following diffusion problem with Dirichlet boundary conditions

$$\begin{cases} -(\partial_{xx}u + K\partial_{yy}u) = f \text{ on } \Omega \\ u = 0 \text{ on } \partial\Omega \end{cases}$$

on the square domain $\Omega = [0, 1] \times [0, 1]$ with

$$f = (1 + K)\pi^2 \sin(\pi x) \sin(\pi y).$$

The unique solution of the problem is

$$u = \sin(\pi x) \sin(\pi y).$$

The Diffusion equation can be written in a matrix form

$$-\nabla \cdot (D \vec{\nabla} u) = f$$

and the associated diffusion matrix is

$$D = \begin{pmatrix} 1 & 0 \\ 0 & K \end{pmatrix}$$

We are interested in case where $K \gg 1$. In the following numerical results we take the value $K = 10^4$.

```
In [17]: display(Markdown(DescriptionFV5DiffusionProblem))
```

1.2 The FV5 scheme for the Diffusion equation

The domain Ω is decomposed into cells C_i .

$|C_i|$ is the measure of the cell C_i .

f_{ij} is the interface between two cells C_i and C_j .

\vec{n}_{ij} is the normal vector to the interface between two cells C_i and C_j .

s_{ij} is the measure of the interface f_{ij} .

d_{ij} is the distance between the centers of mass of the two cells C_i and C_j .

The discrete Diffusion problem is

$$-\frac{1}{|C_i|} \sum s_{ij} F_{ij} = f_i,$$

where u_i is the approximation of u in the cell C_i ,

f_i is the approximation of f in the cell C_i ,

F_{ij} is a numerical approximation of the outward normal diffusion flux from cell i to cell j .

In the case of the scheme FV5, the flux formula are

$$F_{ij} = \frac{u_j - u_i}{d_{ij}} \vec{n}_{ij} D \vec{n}_{ij},$$

for two cells i and j inside the domain,

and

$$F_{boundary} = \frac{u(x_f) - u_i}{d_{if}} \vec{n}_{if} D \vec{n}_{if},$$

for a boundary face with center x_f , inner cell i , outer normal vector \vec{n}_{if} and distance between face and cell centers d_{if}

In [18]: `display(Markdown(CodeFV5PoissonProblem))`

1.3 The script

```
#Discrétisation du second membre et extraction du nb max de voisins d'une cellule
#=====
my_RHSfield = cdmath.Field("RHS_field", cdmath.CELLS, my_mesh, 1)
maxNbNeighbours=0#This is to determine the number of non zero coefficients in the sparse finite

for i in range(nbCells):
    Ci = my_mesh.getCell(i)
    x = Ci.x()
    y = Ci.y()

    my_RHSfield[i]=2*pi*pi*sin(pi*x)*sin(pi*y)#mettre la fonction definie au second membre de l
    # compute maximum number of neighbours
    maxNbNeighbours= max(1+Ci.getNumberOfFaces(),maxNbNeighbours)

# Construction de la matrice et du vecteur second membre du système linéaire
#=====
Rigidite=cdmath.SparseMatrixPetsc(nbCells,nbCells,maxNbNeighbours)# warning : third argument is
```

```

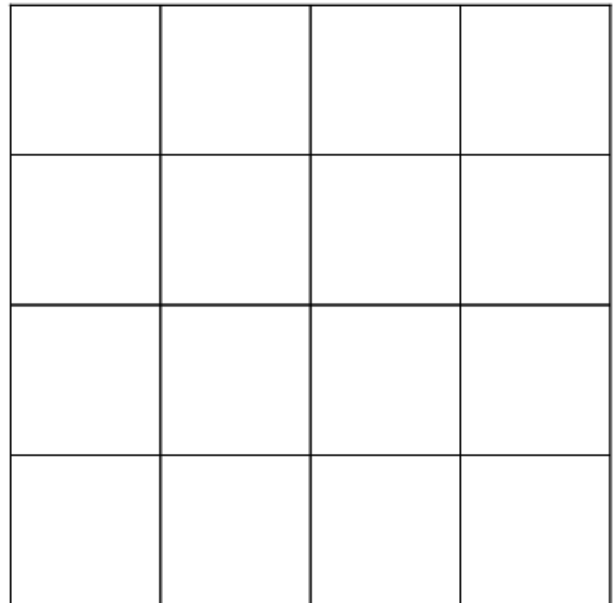
RHS=cdmath.Vector(nbCells)
normal=cdmath.Vector(dim)
#Parcours des cellules du domaine
for i in range(nbCells):
    RHS[i]=my_RHSfield[i] #la valeur moyenne du second membre f dans la cellule i
    Ci=my_mesh.getCell(i)
    for j in range(Ci.getNumberOfFaces()):# parcours des faces voisines
        Fj=my_mesh.getFace(Ci.getFaceId(j))
            for idim in range(dim) :
                normal[idim] = Ci.getNormalVector(j, idim);#normale sortante
    if not Fj.isBorder():
        k=Fj.getCellId(0)
        if k==i :
            k=Fj.getCellId(1)
        Ck=my_mesh.getCell(k)
        distance=Ci.getBarryCenter().distance(Ck.getBarryCenter())
        coeff=Fj.getMeasure()/Ci.getMeasure()/distance*(normal[0]*normal[0] + K*normal[1]*no
        Rigidite.setValue(i,k,-coeff) # terme extradiagonal
    else:
        coeff=Fj.getMeasure()/Ci.getMeasure()/Ci.getBarryCenter().distance(Fj.getBarryCenter
        #For the particular case where the mesh boundary does not coincide with the domain b
        x=Fj.getBarryCenter().x()
        y=Fj.getBarryCenter().y()
        RHS[i]+=coeff*sin(pi*x)*sin(pi*y)#mettre ici la condition limite du problème de Dirich
        Rigidite.addValue(i,i,coeff) # terme diagonal

# Résolution du système linéaire
#=====
LS=cdmath.LinearSolver(Rigidite,RHS,500,1.E-6,"GMRES","ILU")
SolSyst=LS.solve()

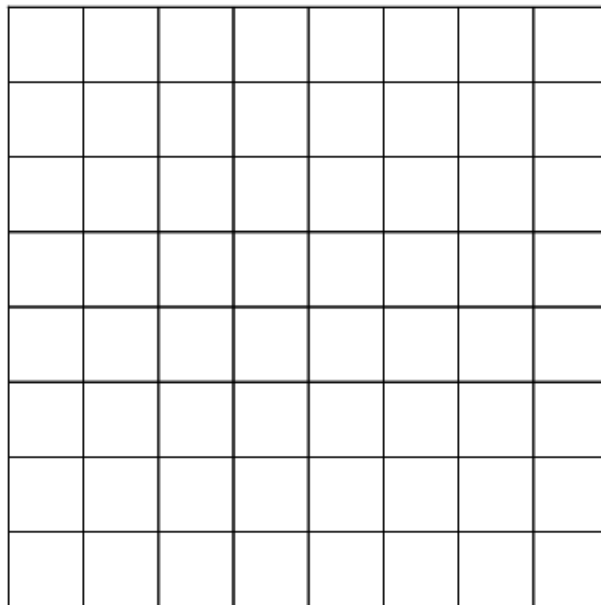
# Automatic postprocessing : save 2D picture and plot diagonal data
#=====
PV_routines.Save_PV_data_to_picture_file("my_ResultField_0.vtu","ResultField",'CELLS',"my_Result
diag_data=VTK_routines.Extract_field_data_over_line_to_numpyArray(my_ResultField,[0,1,0],[1,0,0]
plt.plot(curv_abs, diag_data, label= str(nbCells)+ ' cells mesh')
plt.savefig("FV5_on_square_PlotOverDiagonalLine.png")

```

1.4 Regular grid

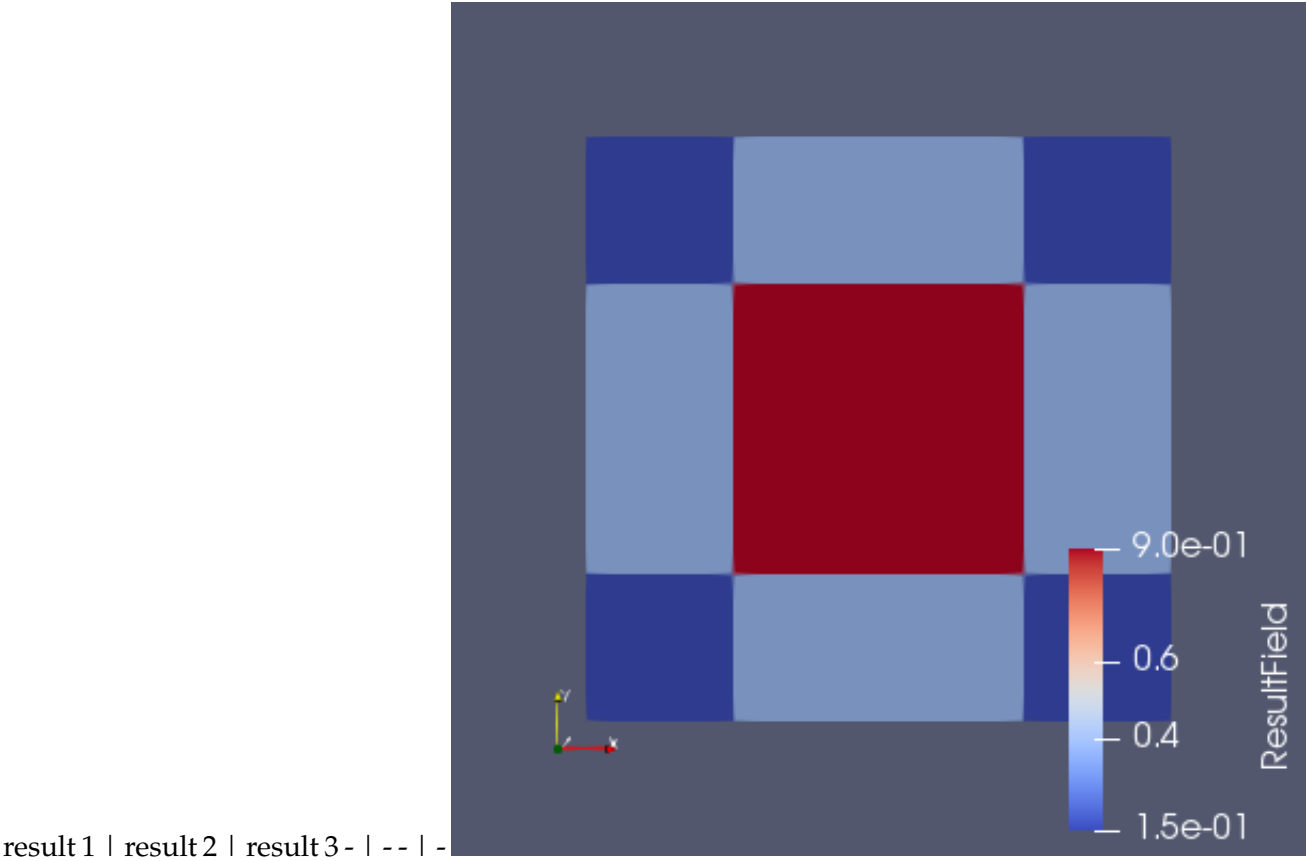
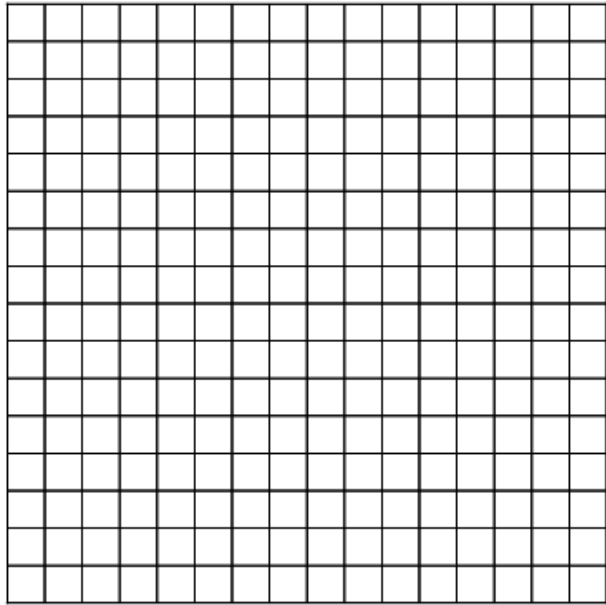


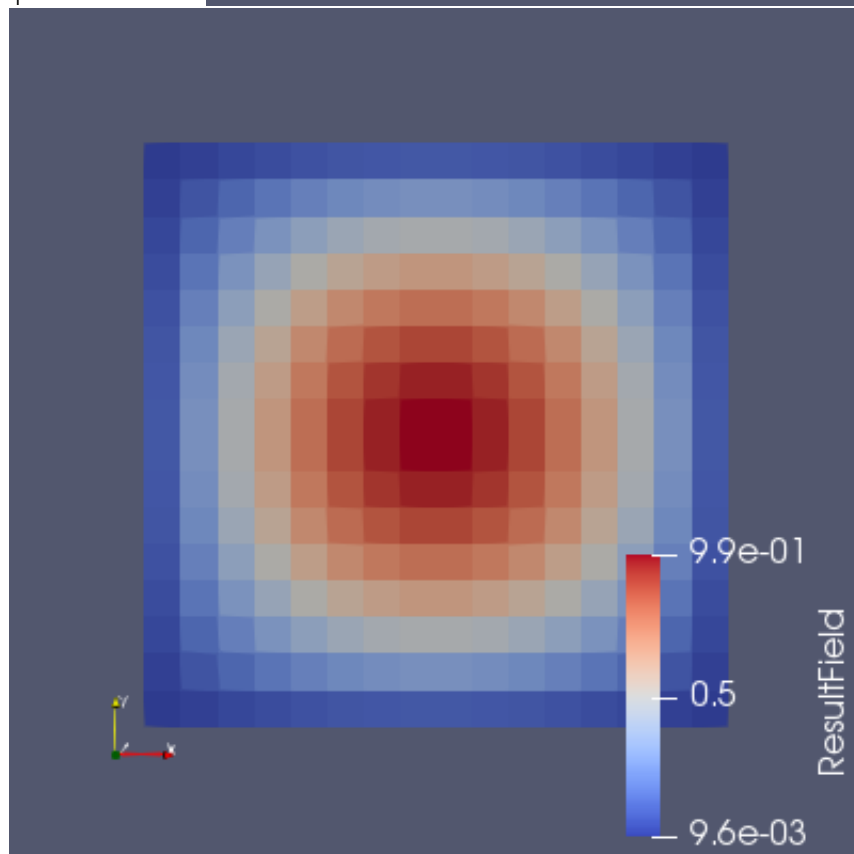
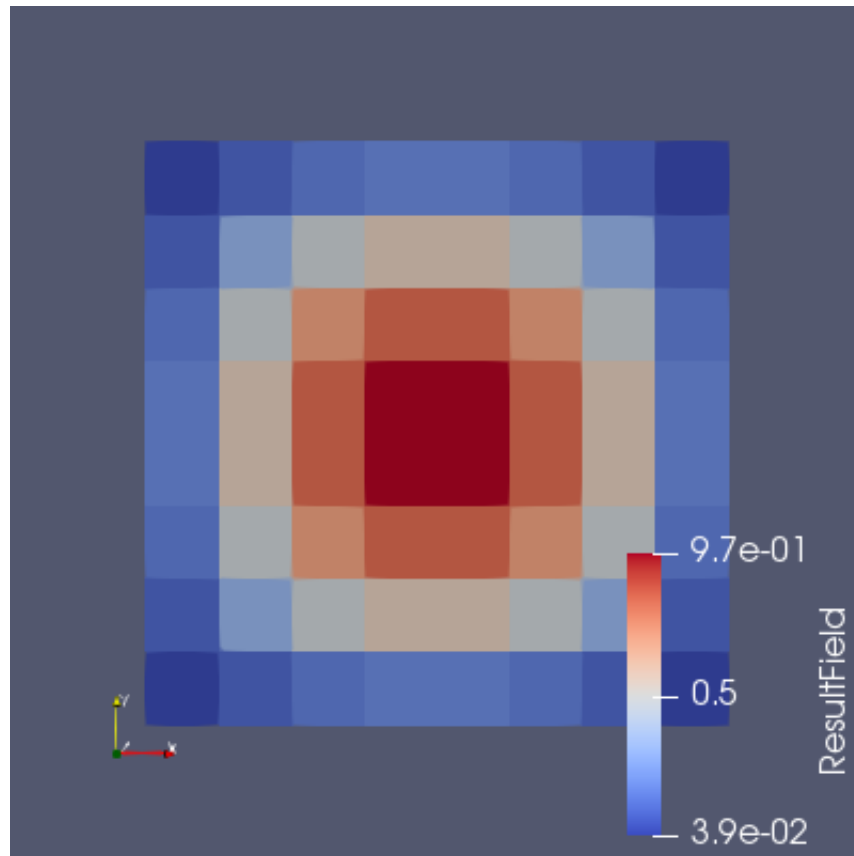
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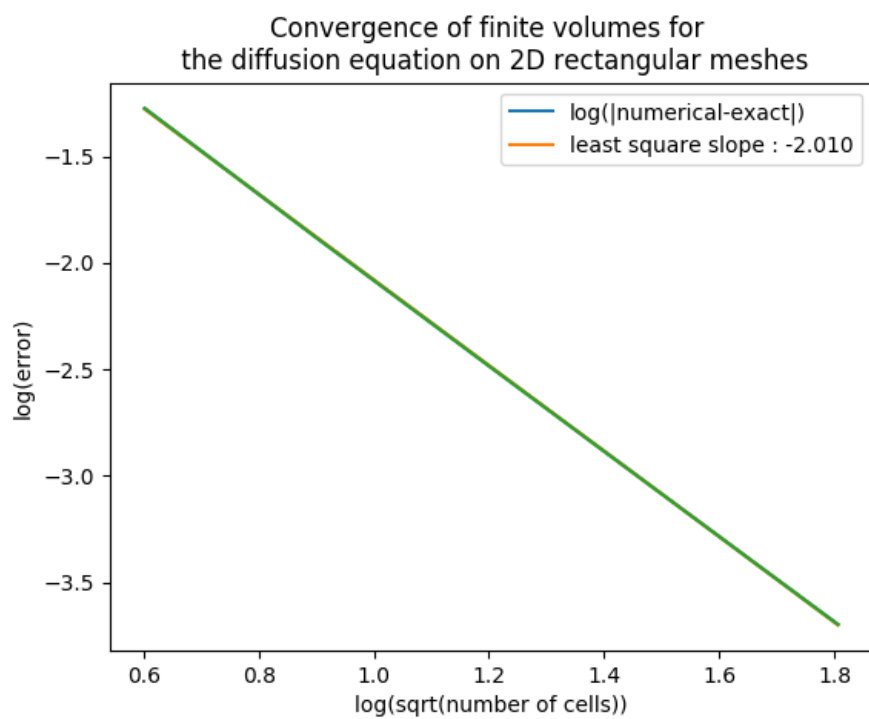


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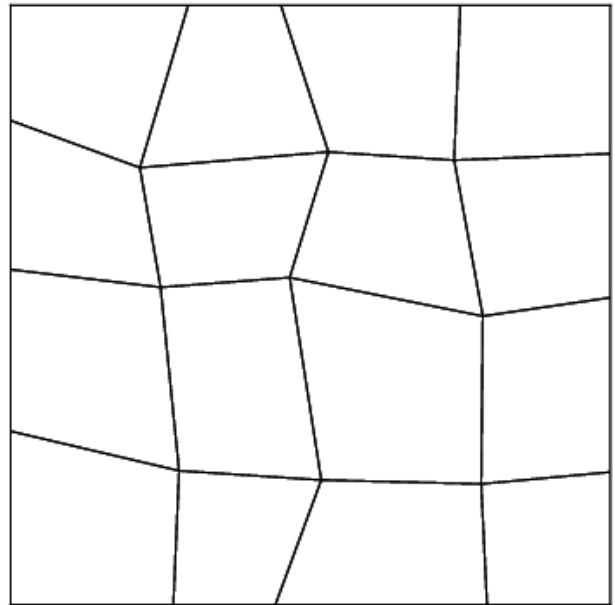
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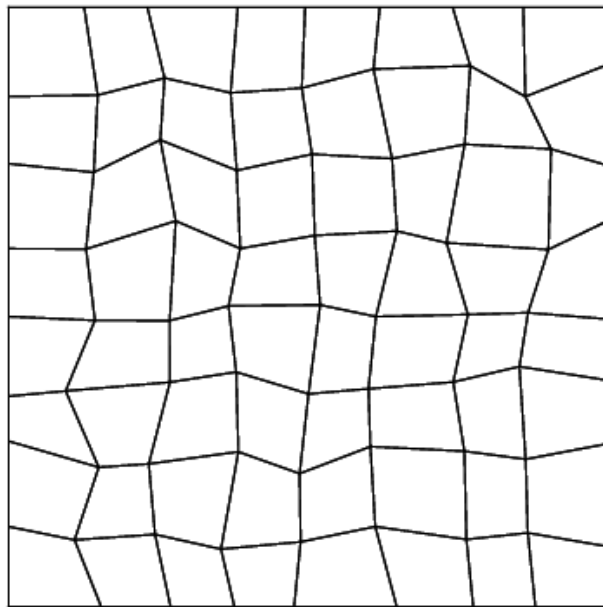




1.5 Deformed quadrangles

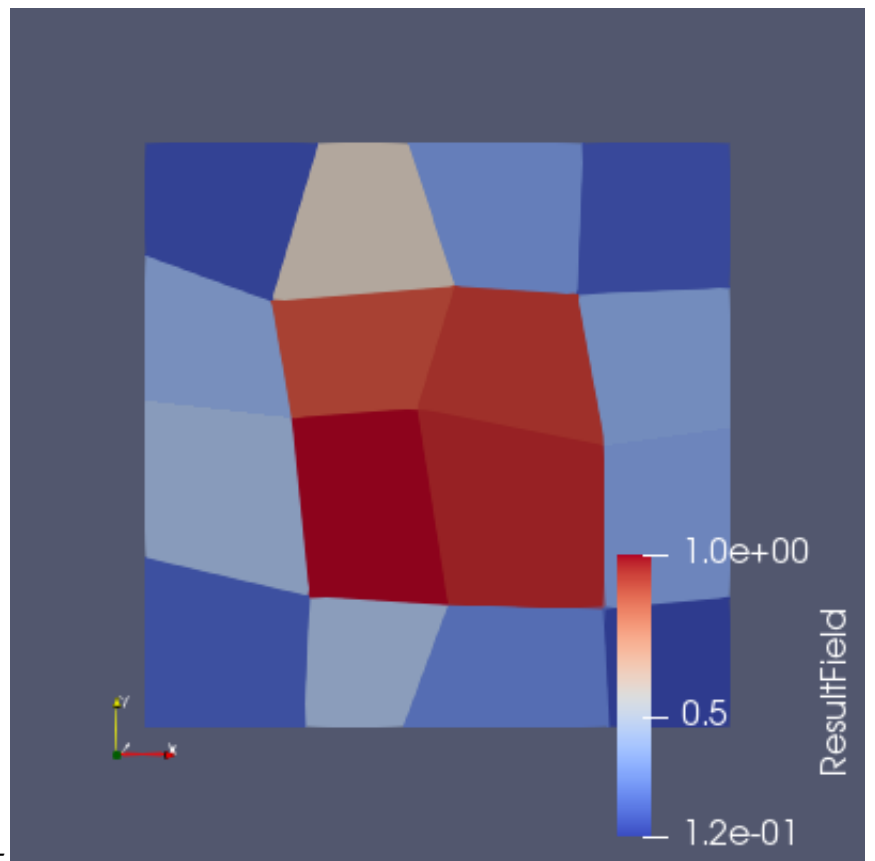
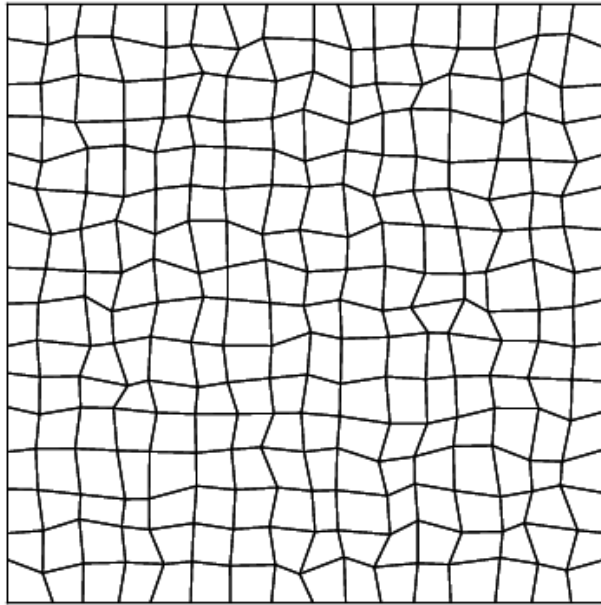


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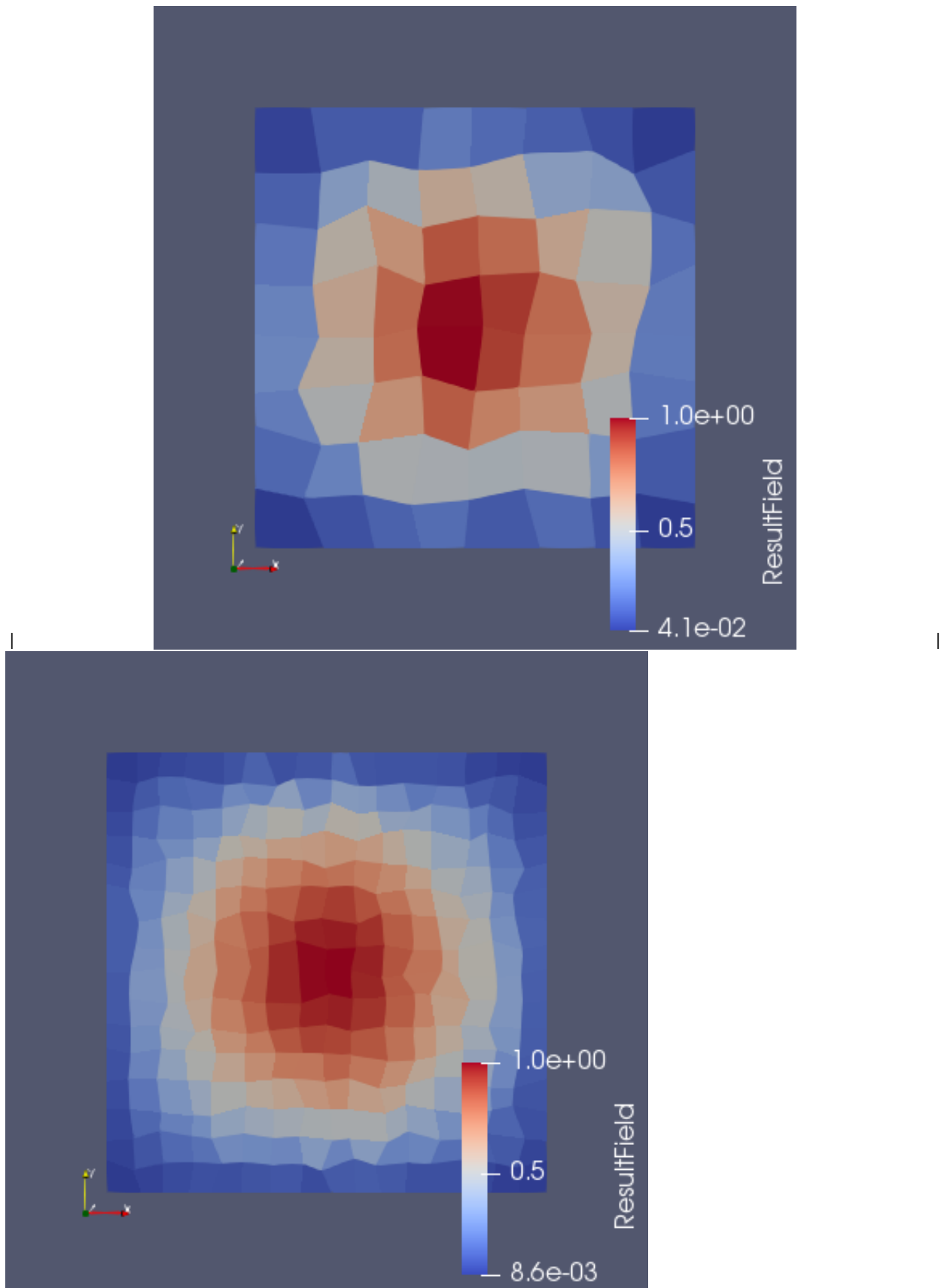


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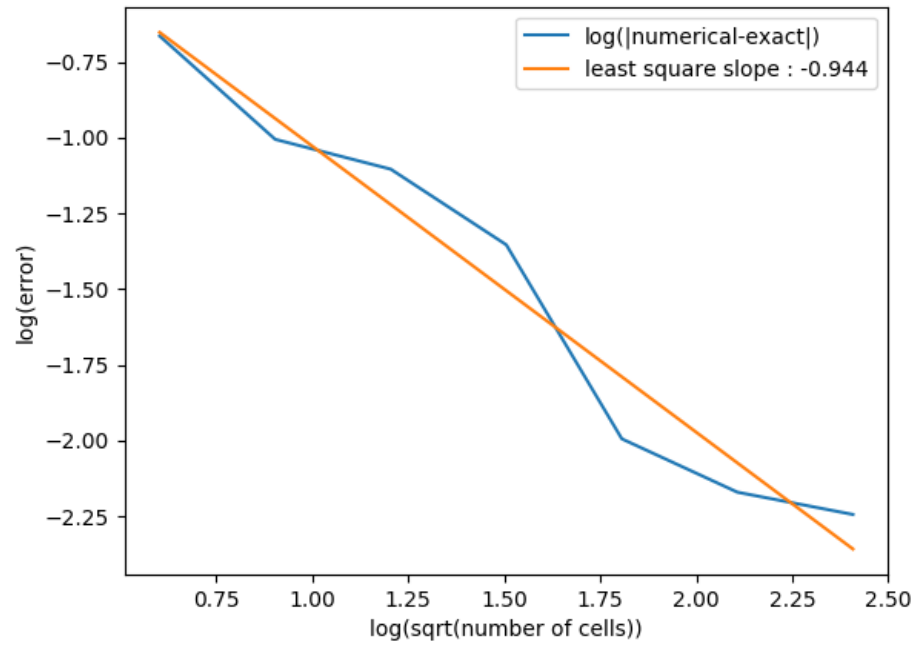
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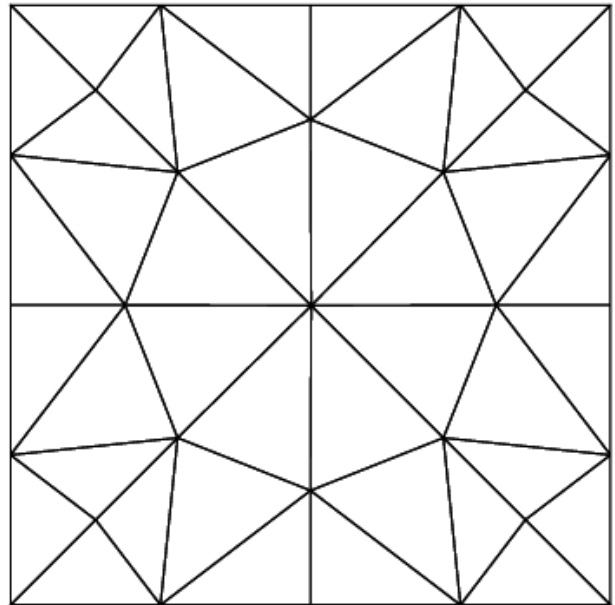
result 1 | result 2 | result 3 - | - - | -



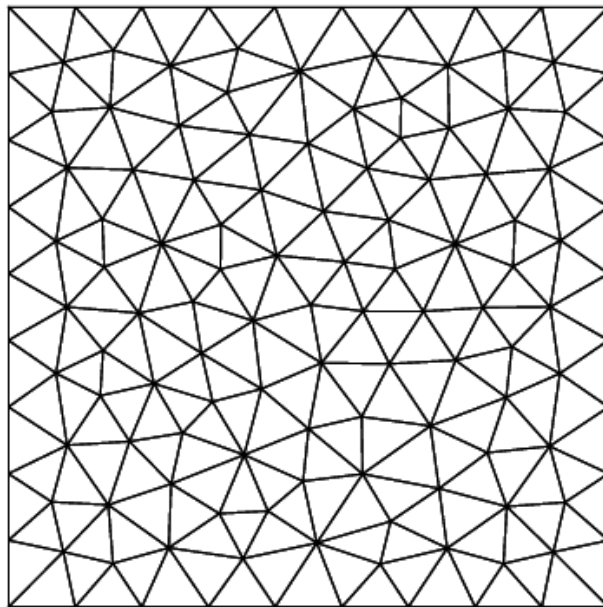
Convergence of finite volumes
for the diffusion equation on a 2D deformed quadrangles meshes



1.6 Delaunay triangular meshes

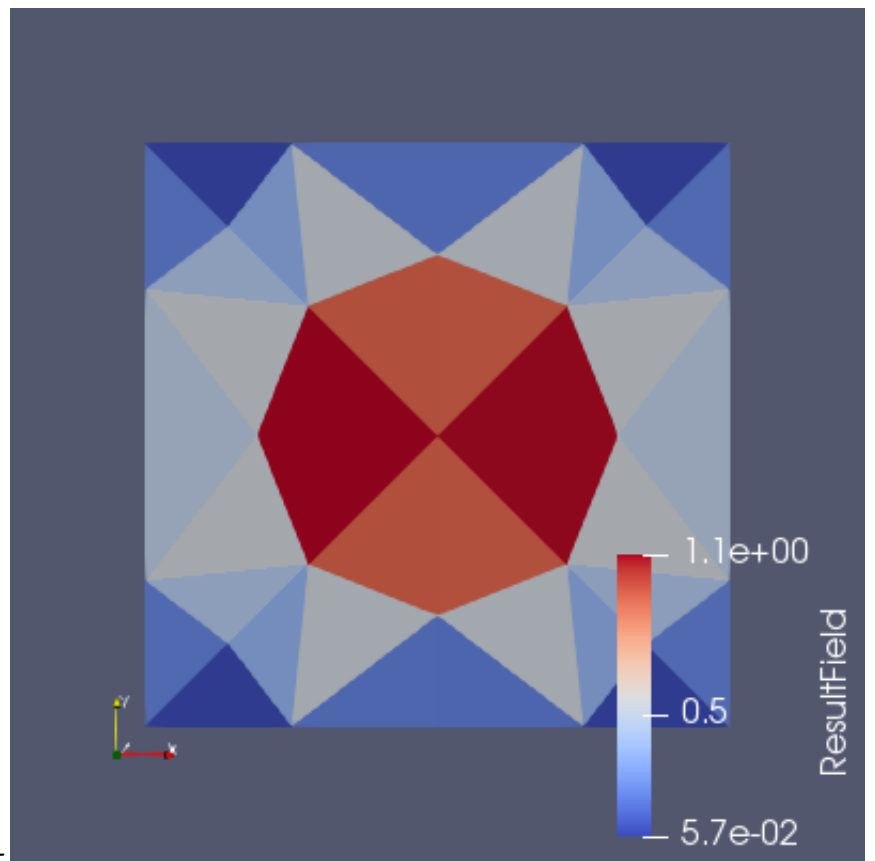
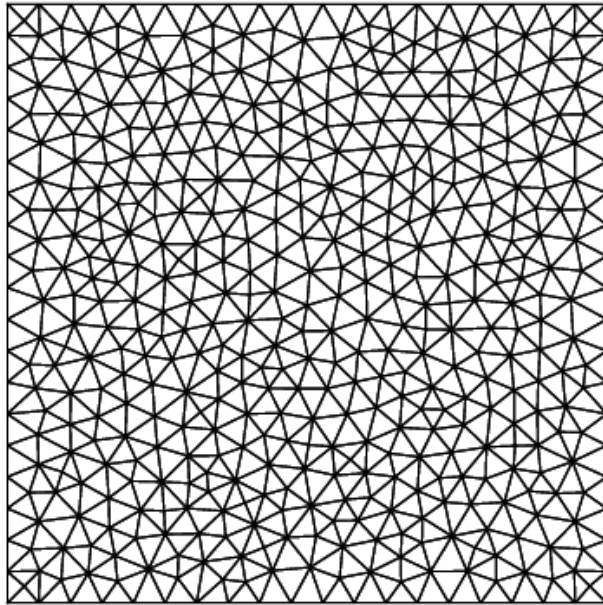


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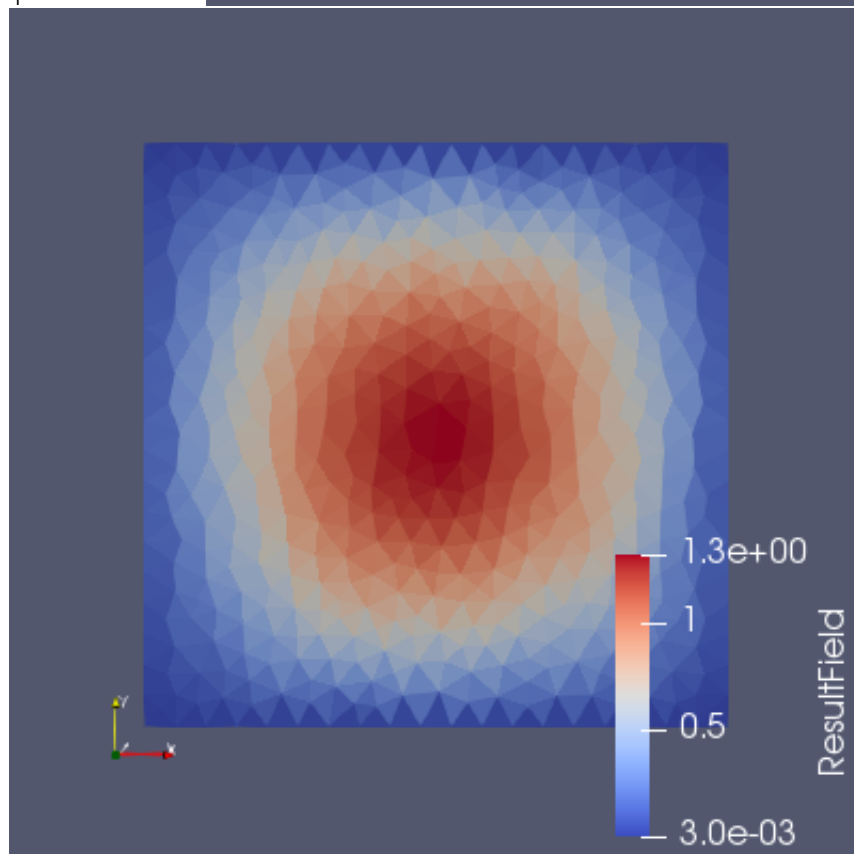
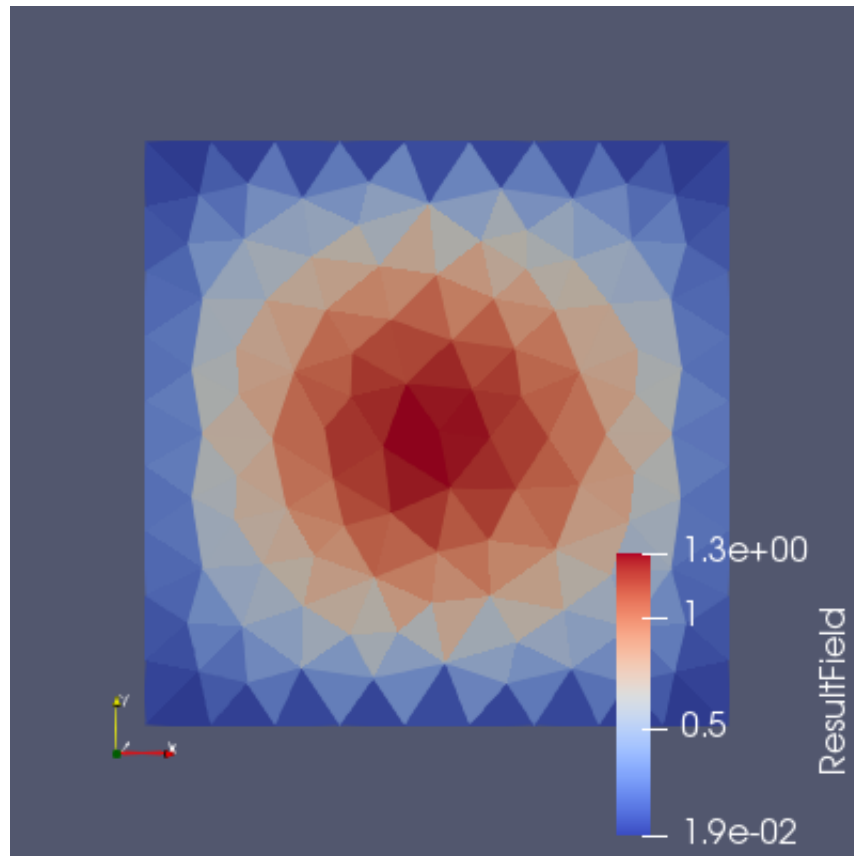


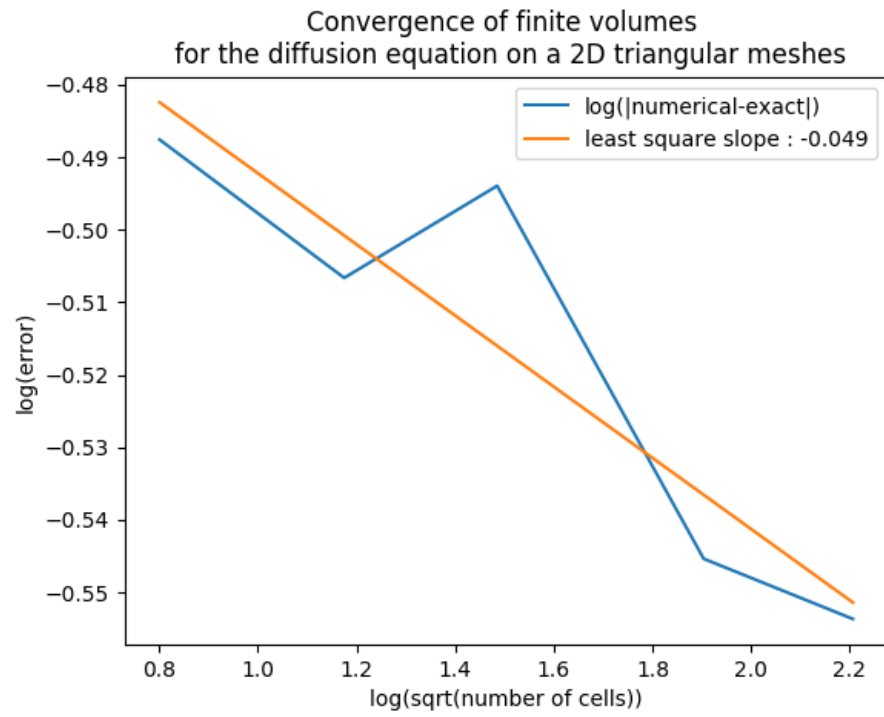
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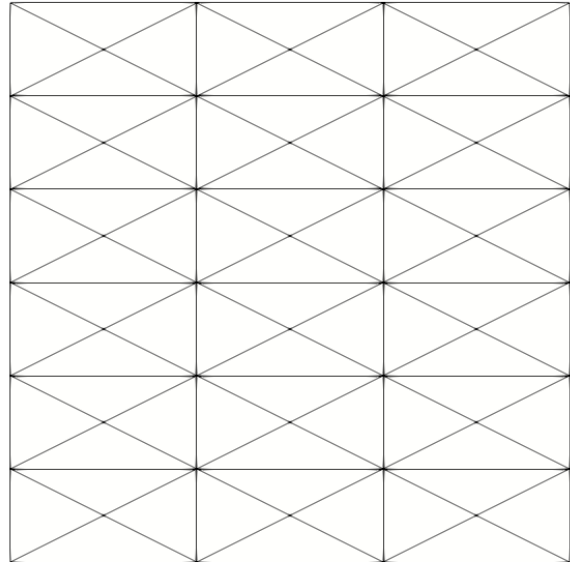


result 1 | result 2 | result 3 - | - - | -

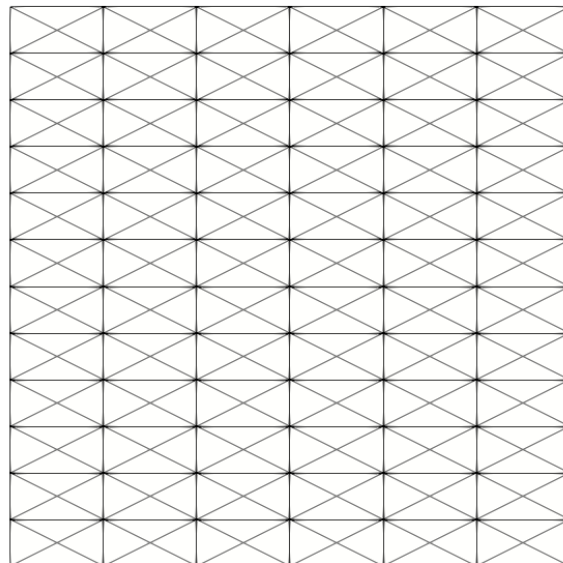




1.7 Cross triangle meshes (from a $(n, 2n)$ rectangular grid)

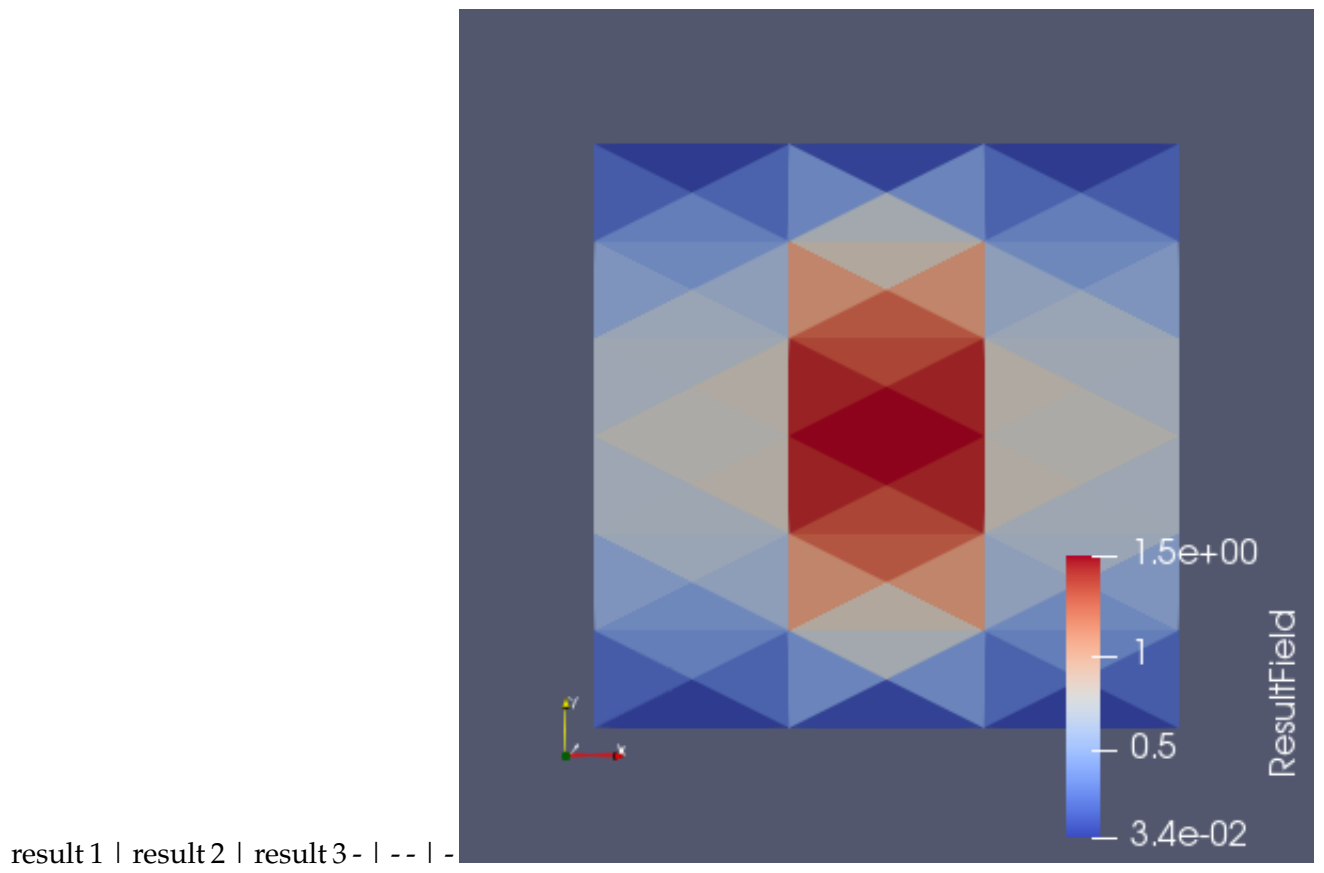
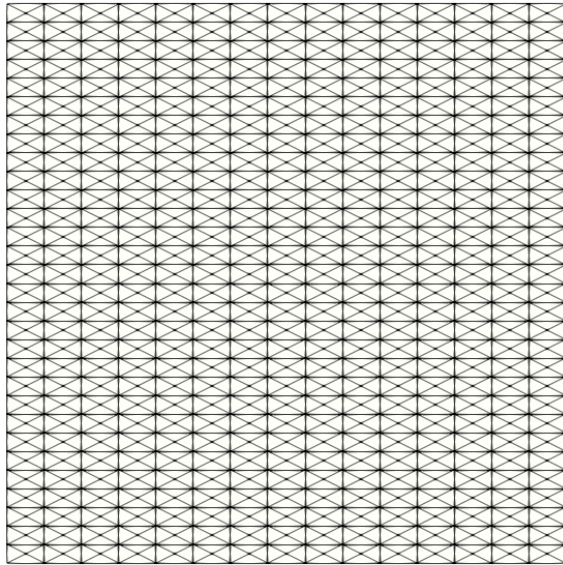


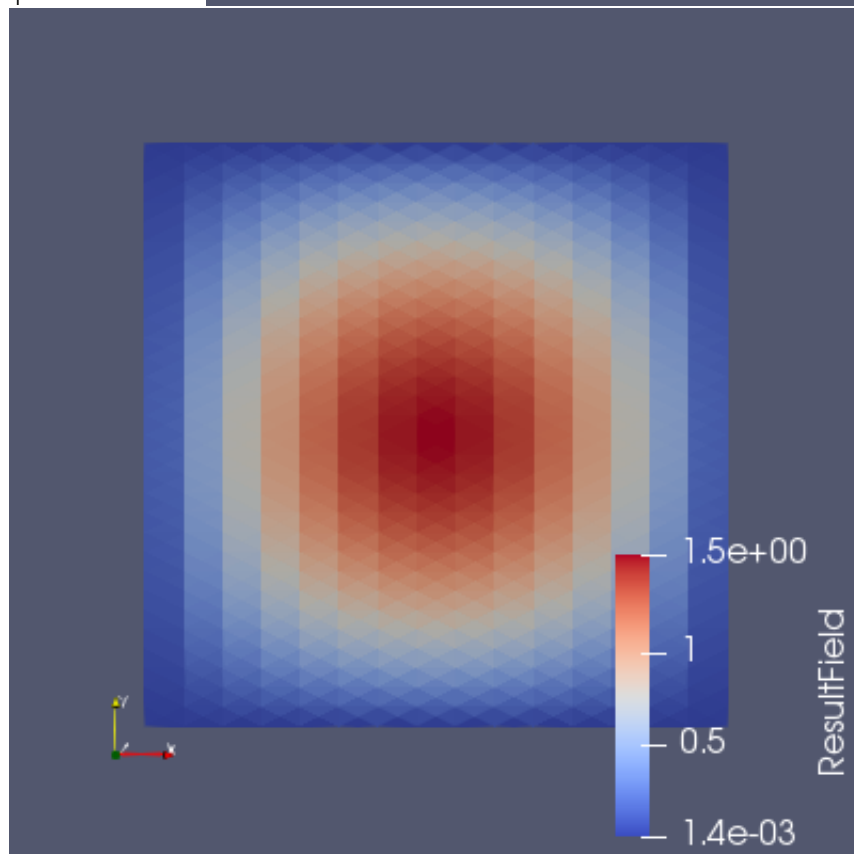
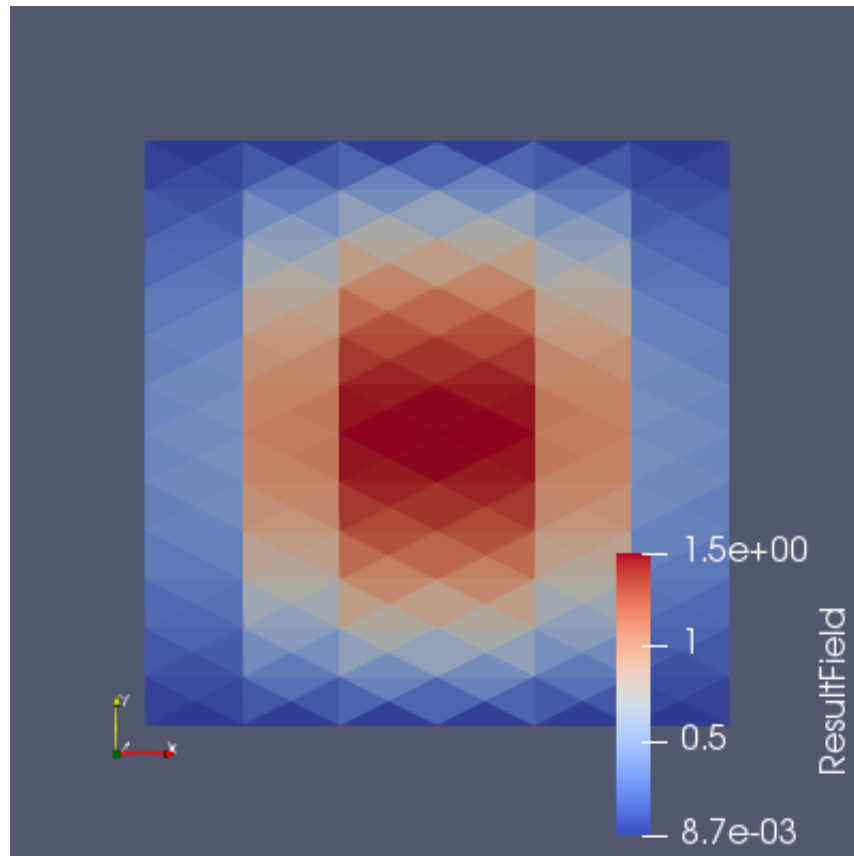
mesh 1 | mesh 2 | mesh 3 - | - | -

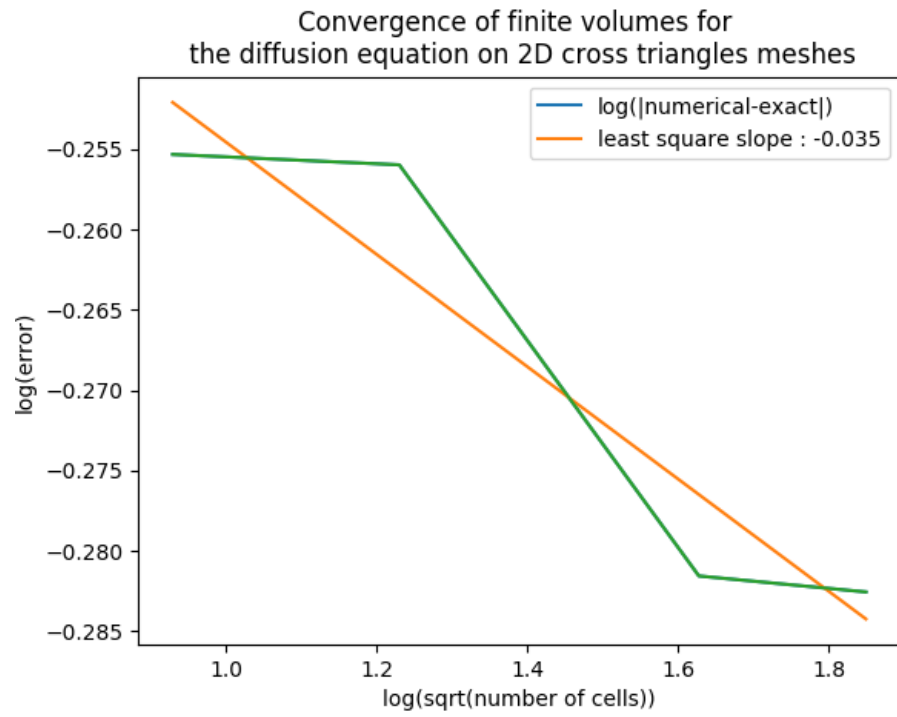


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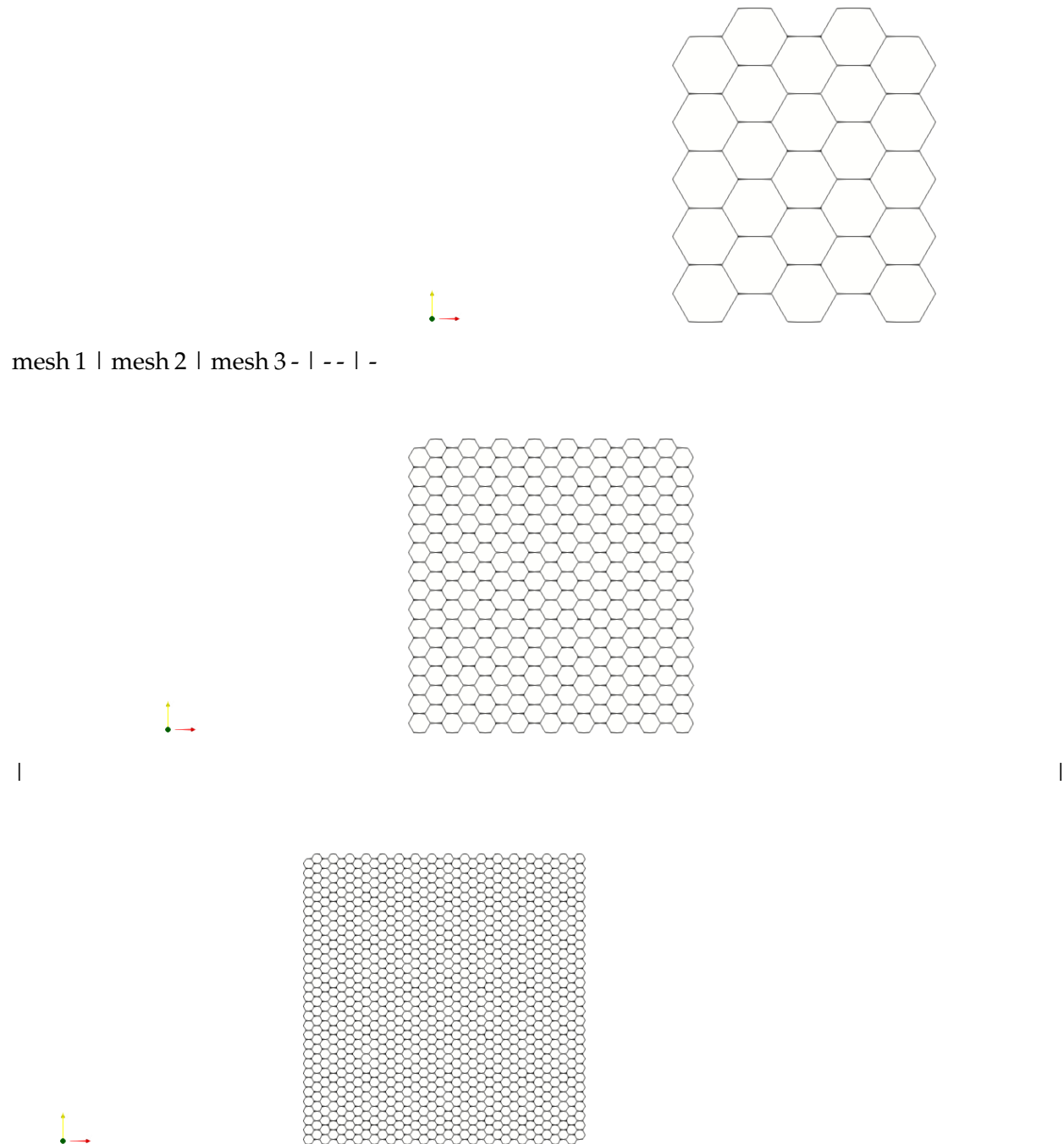
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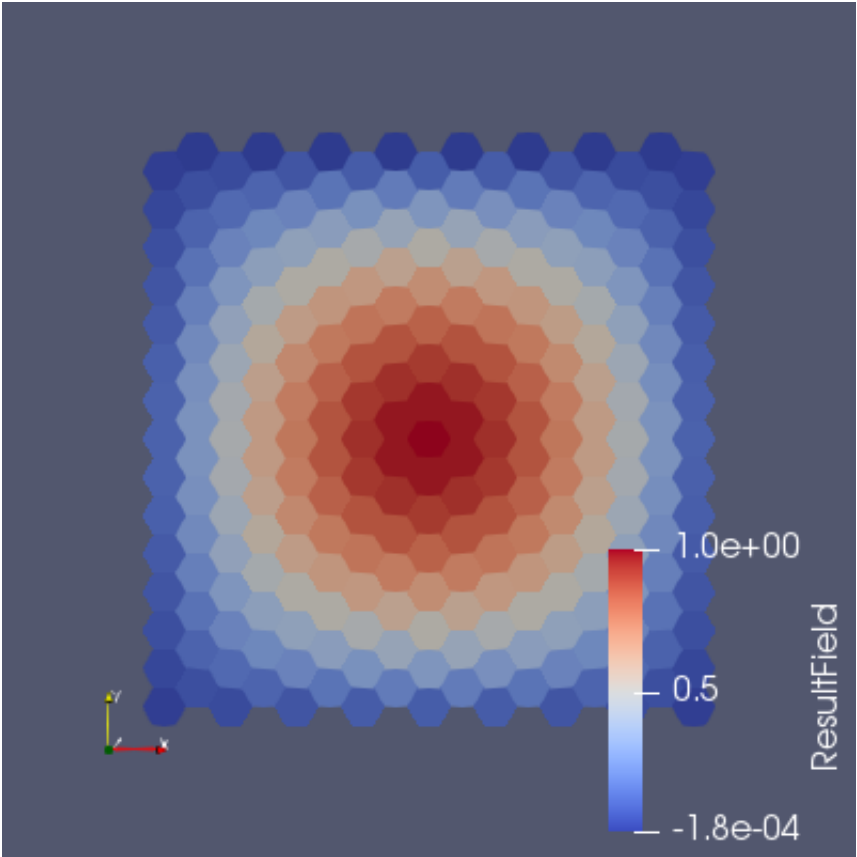
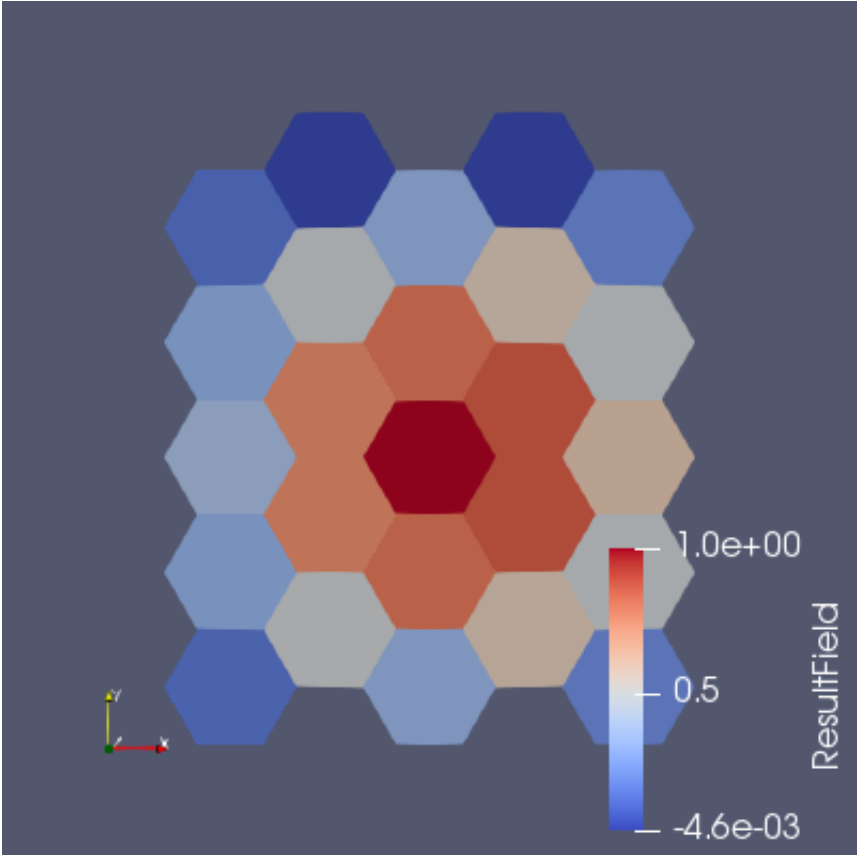


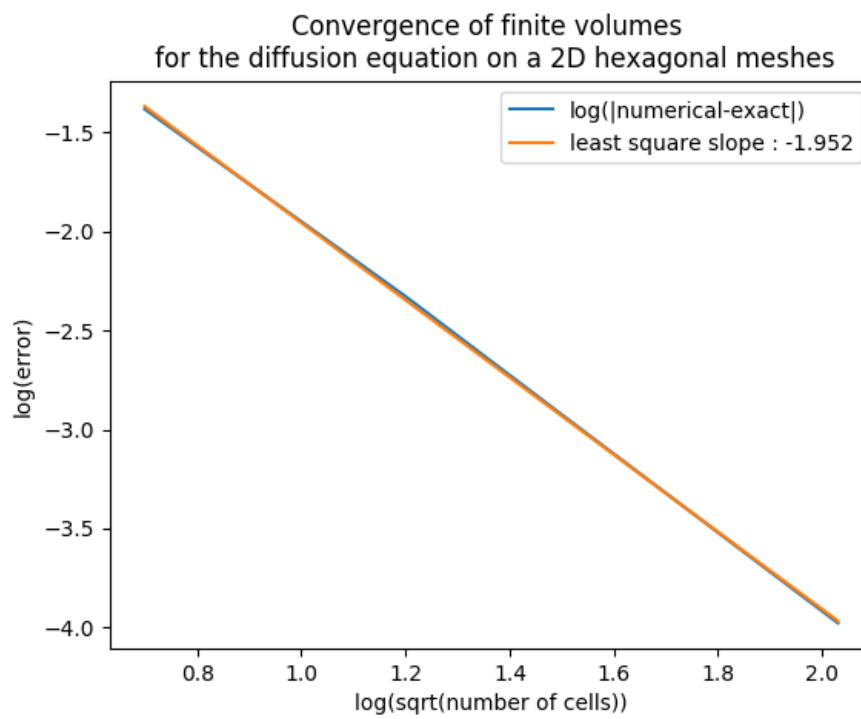
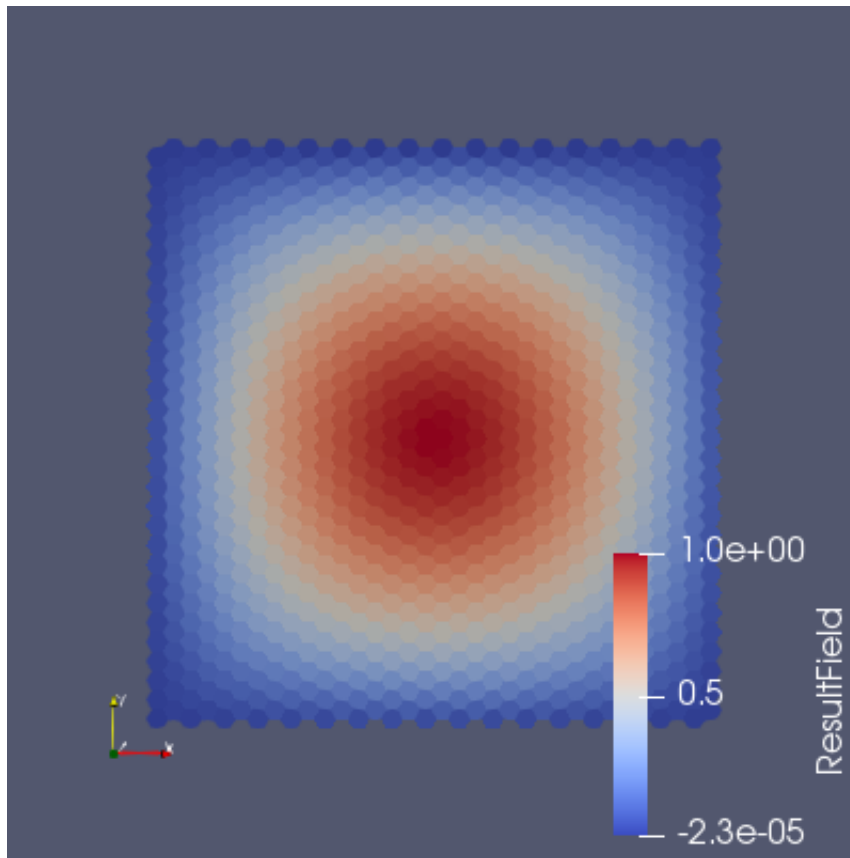


1.8 Hexagonal meshes

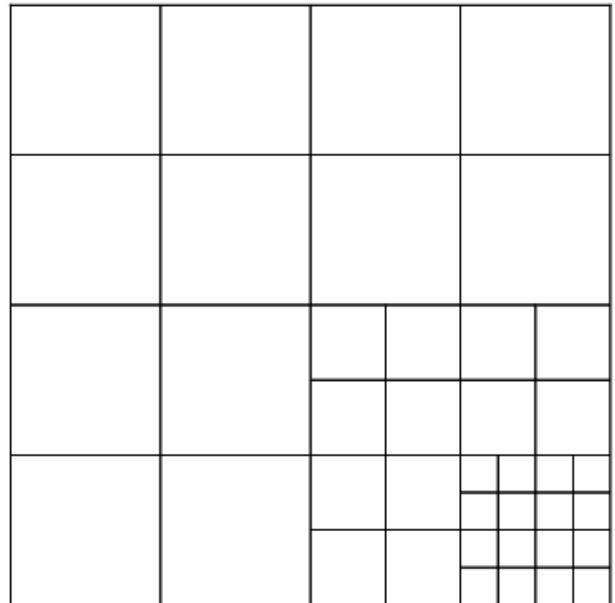


result 1 | result 2 | result 3 - | - - | -

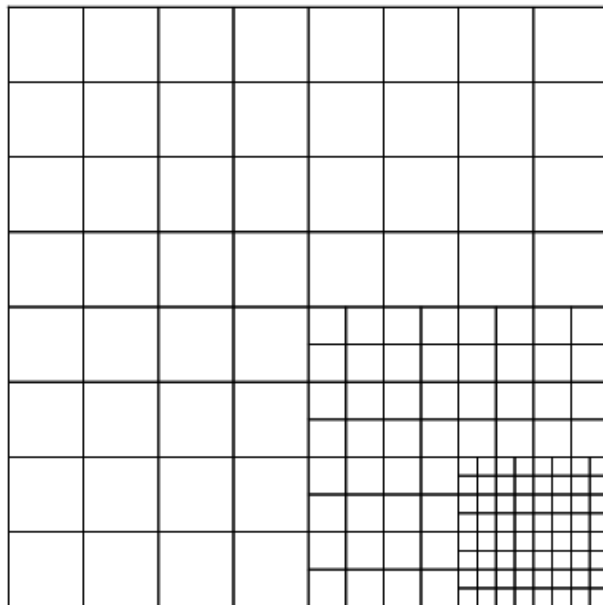




1.9 Locally refined meshes

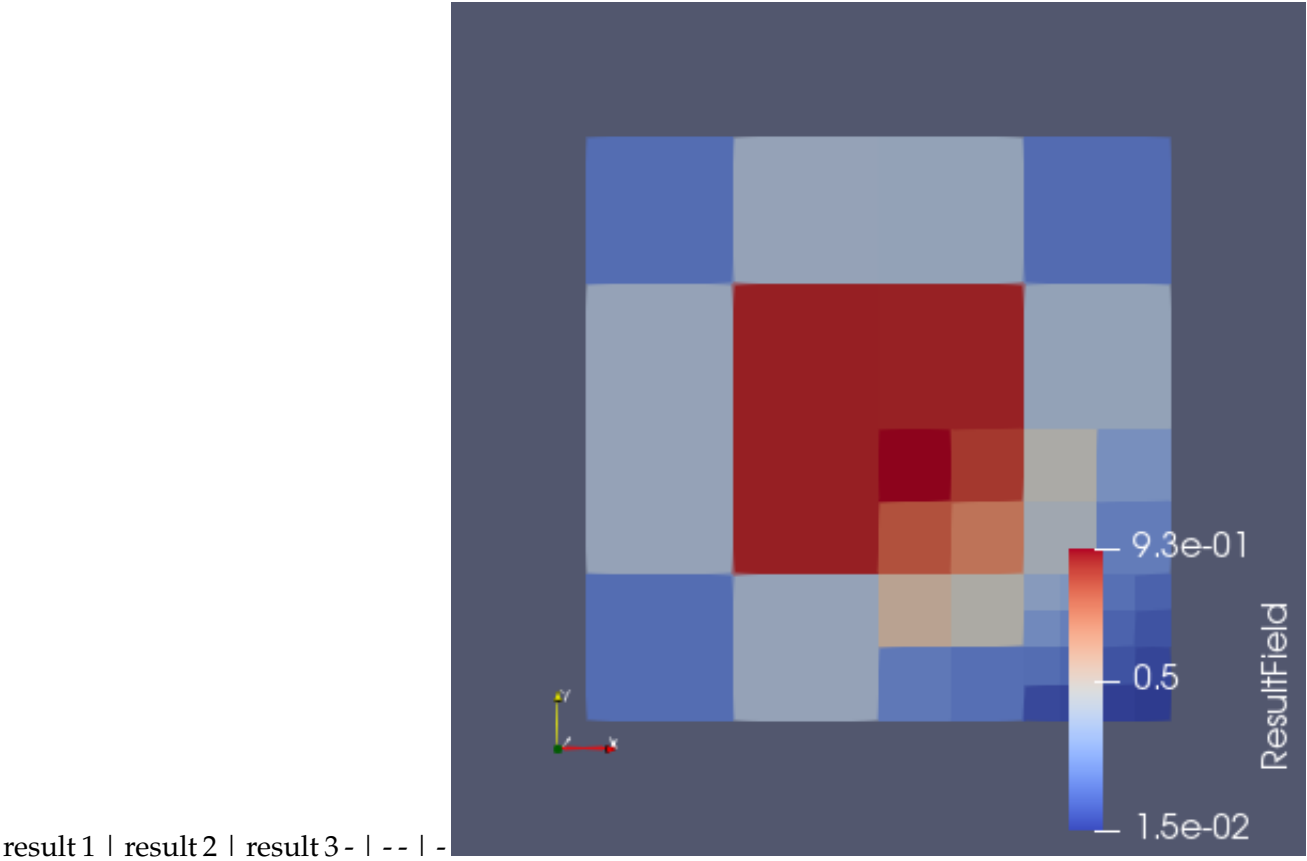
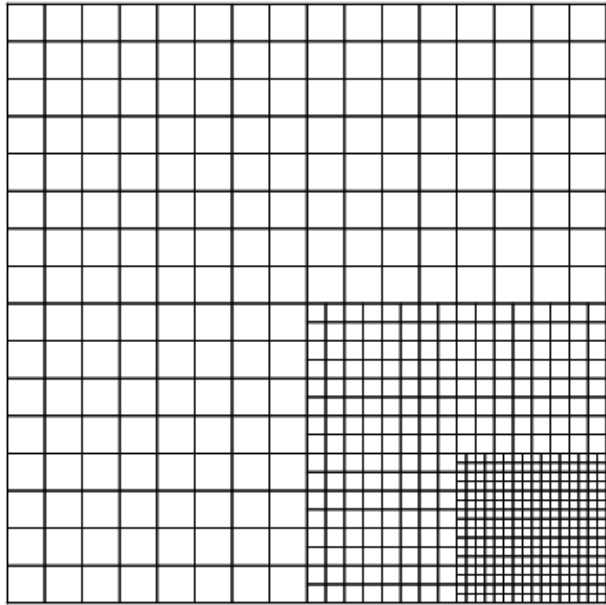


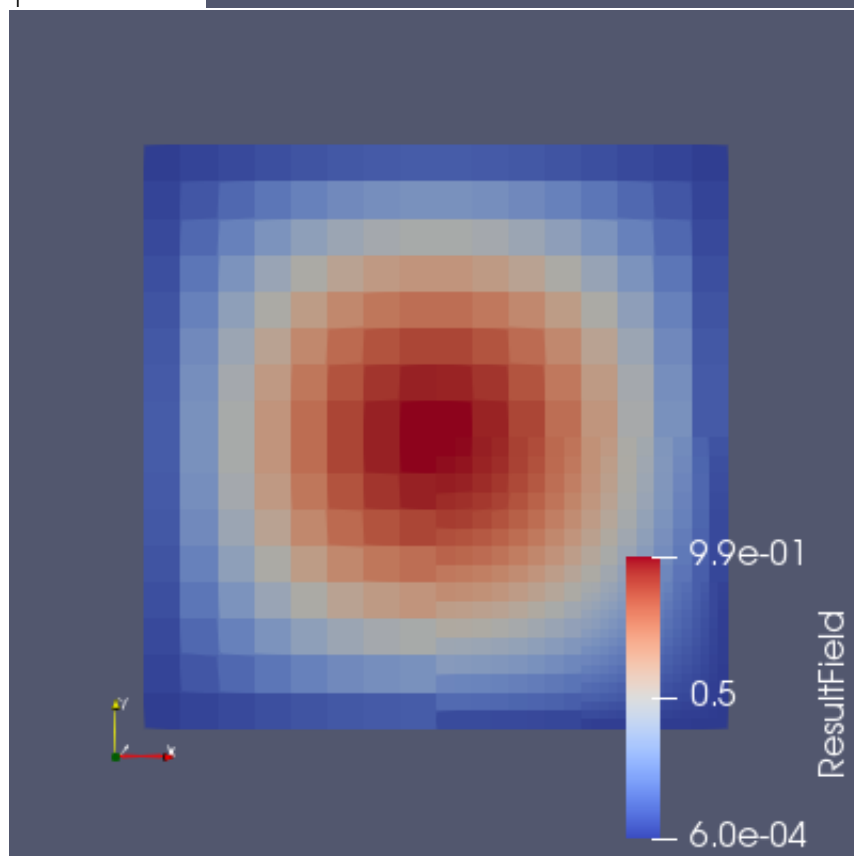
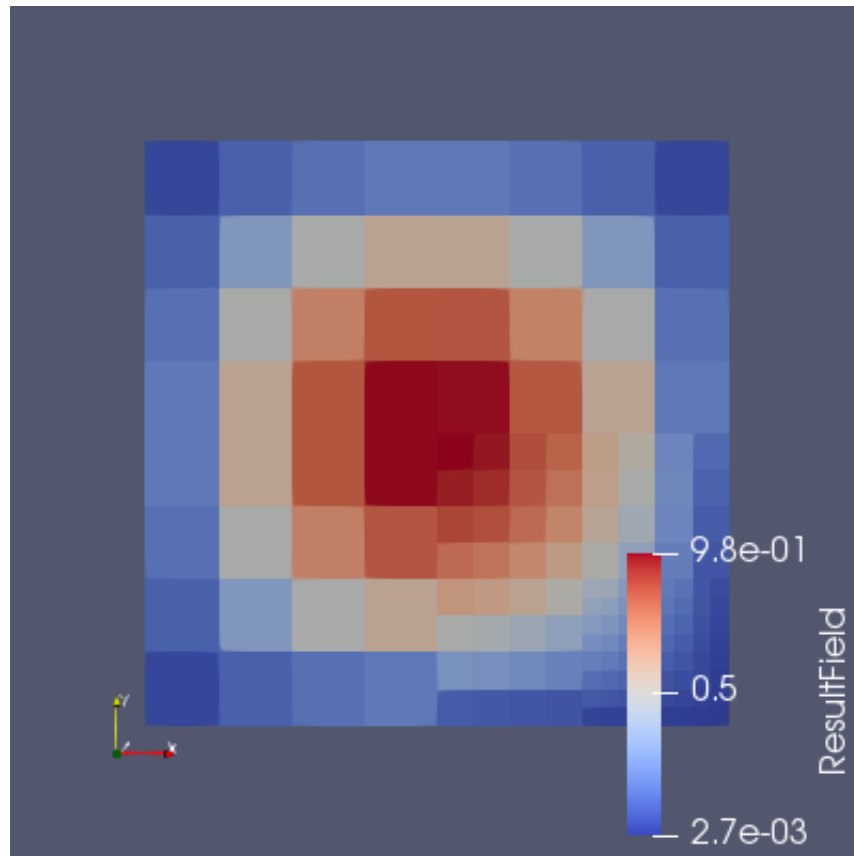
mesh 1 | mesh 2 | mesh 3 - | - - | -

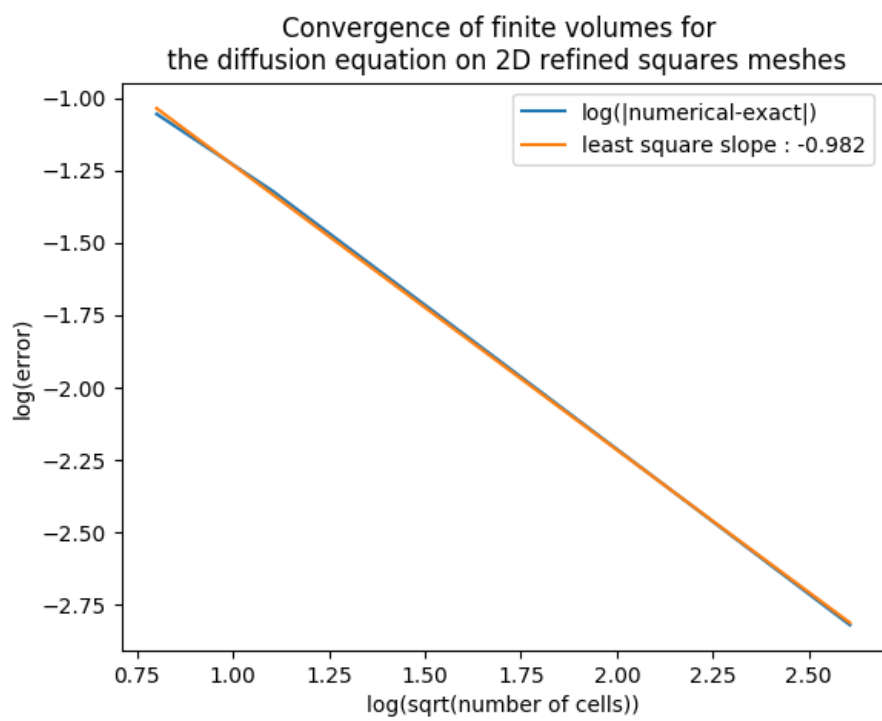


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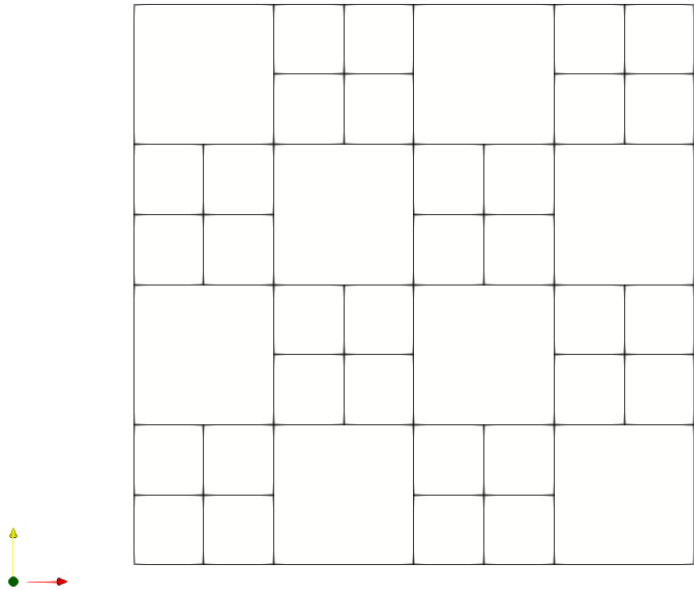
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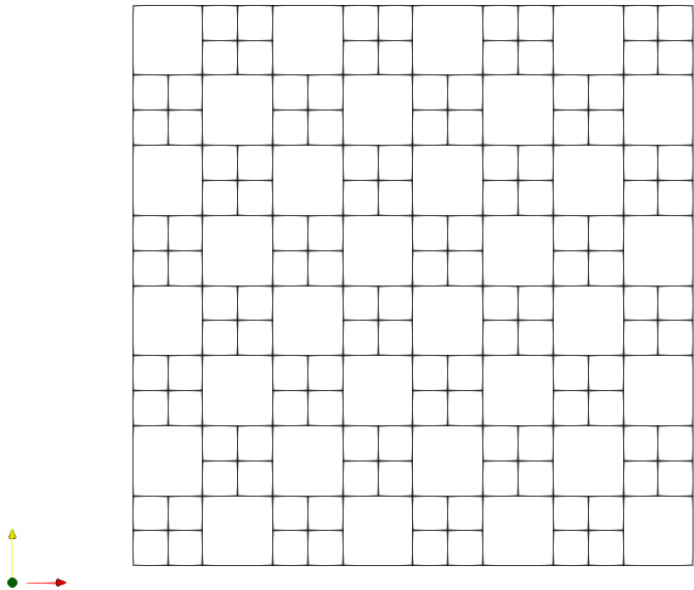




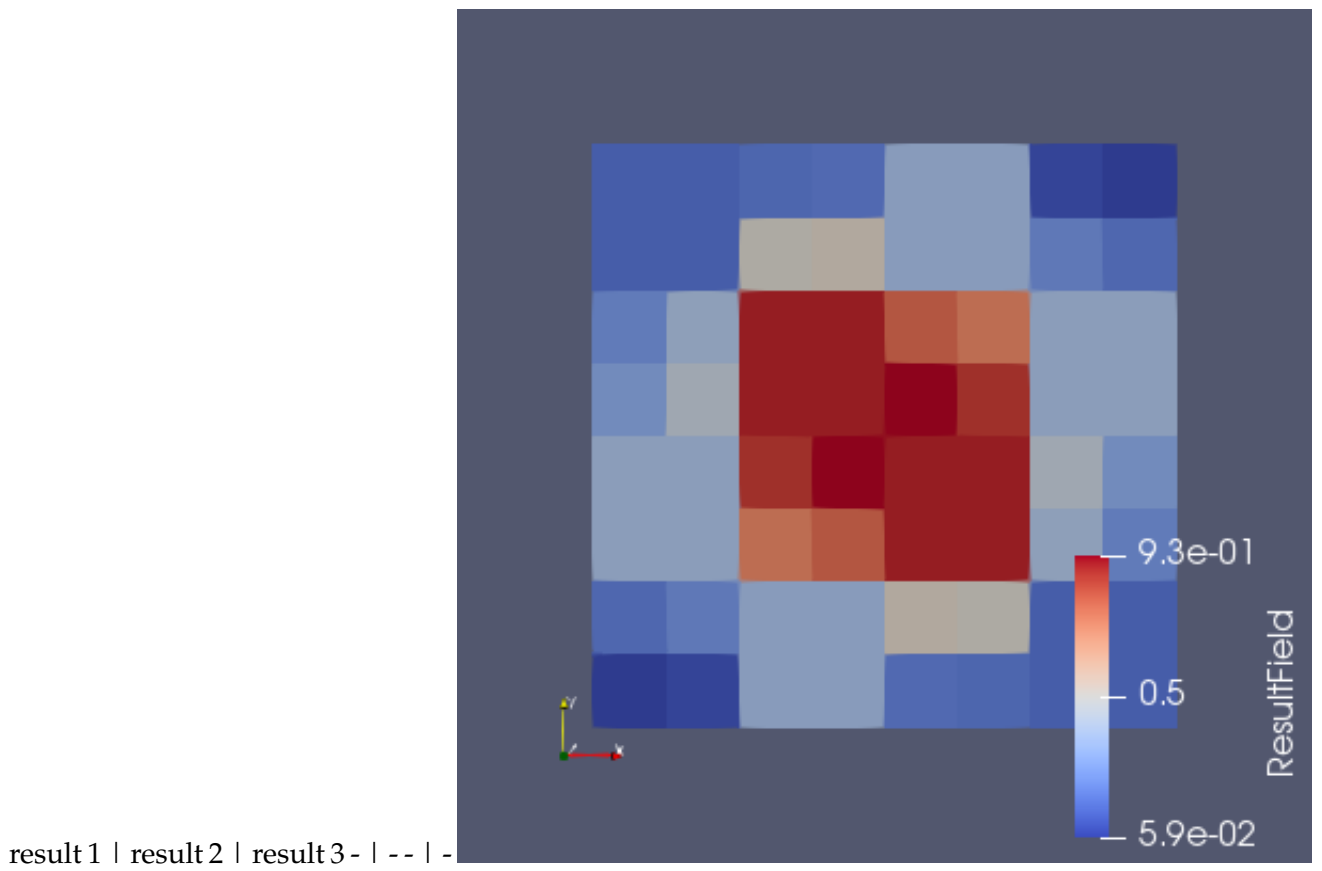
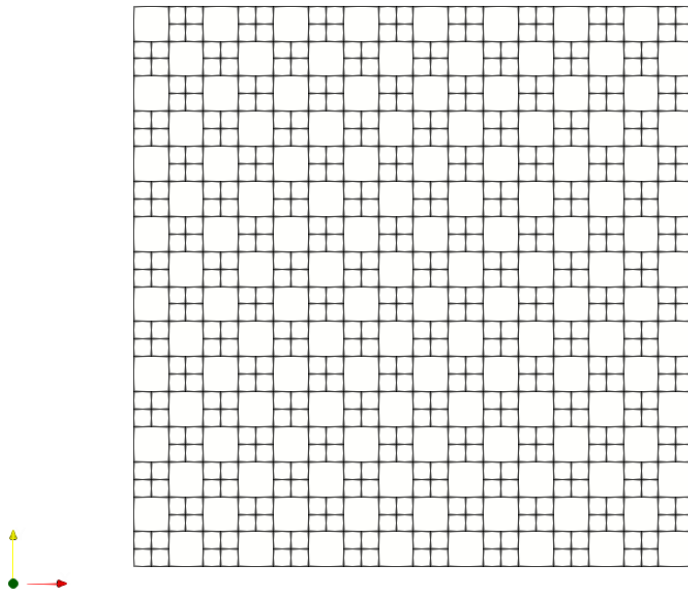
1.10 Checkerboard meshes

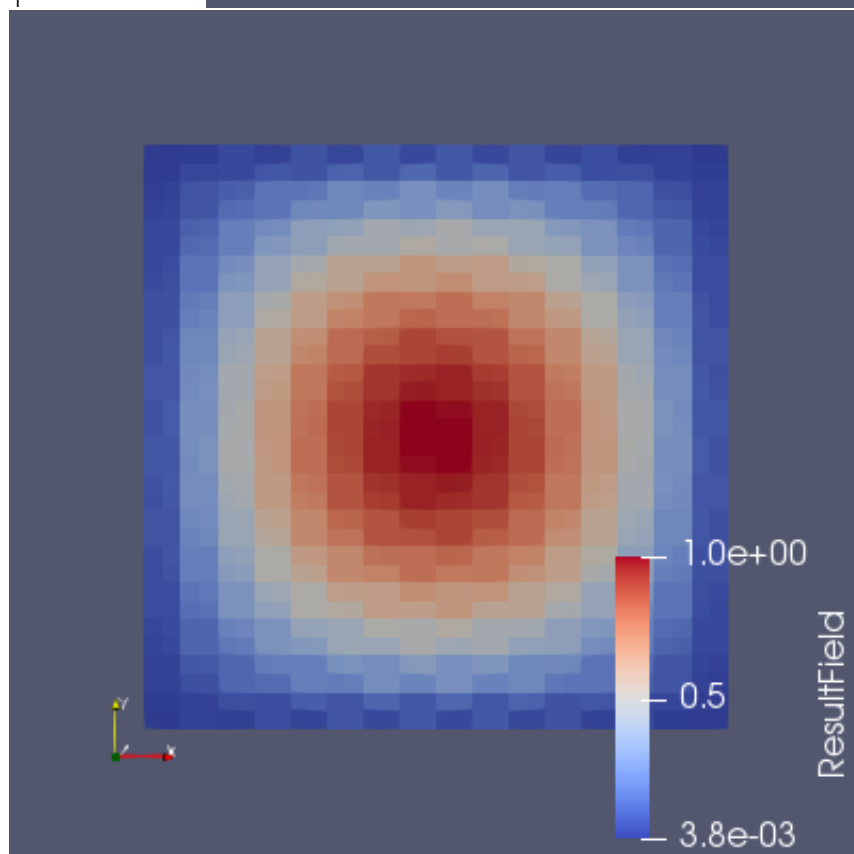
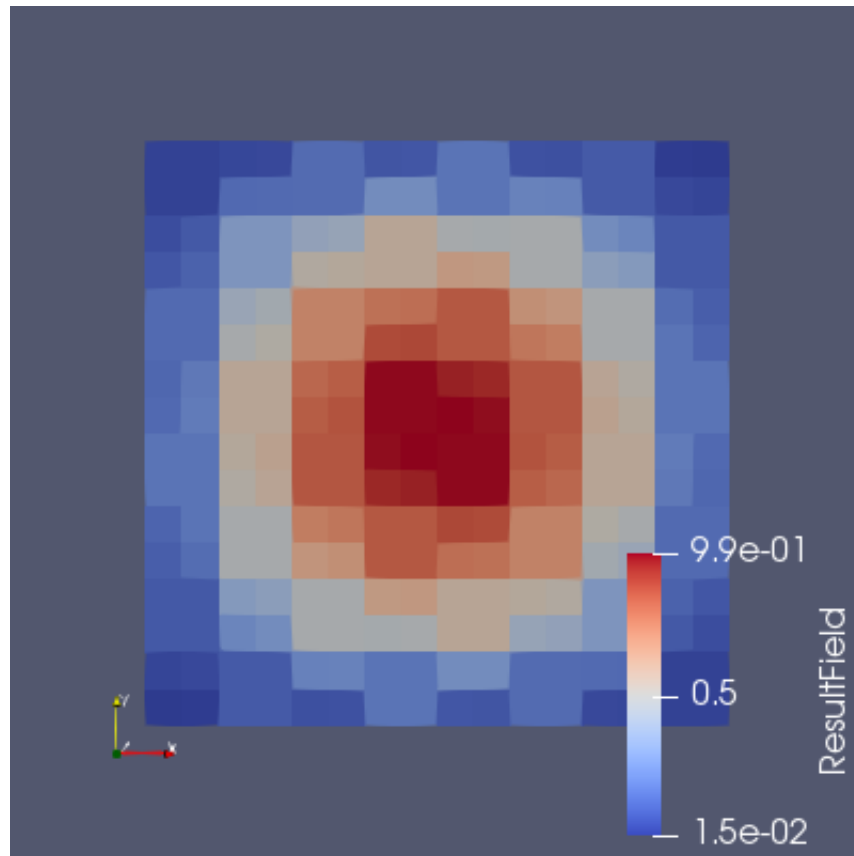


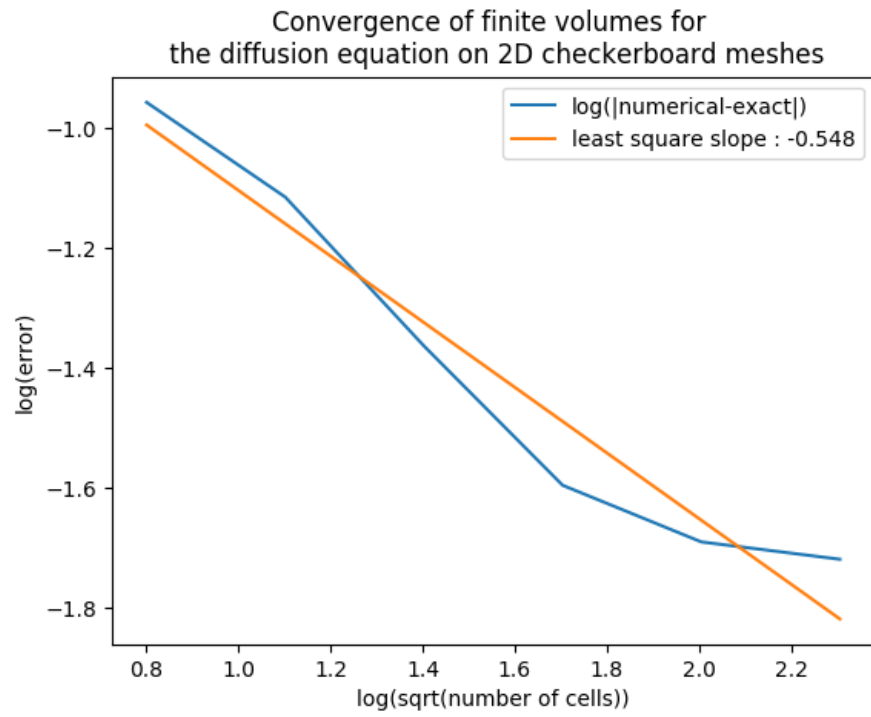
mesh 1 | mesh 2 | mesh 3 - | - - | -



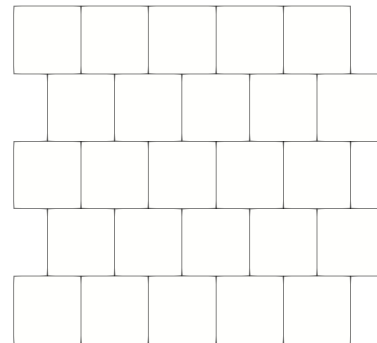
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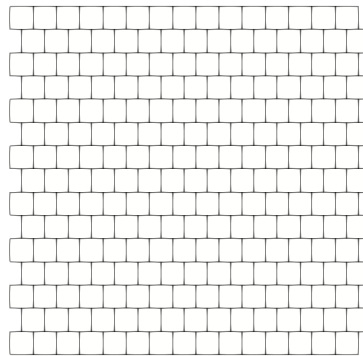




1.11 Brick wall meshes

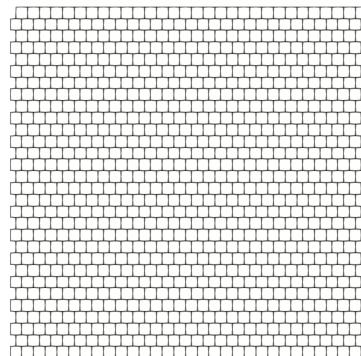


mesh 1 | mesh 2 | mesh 3 - | - - | -

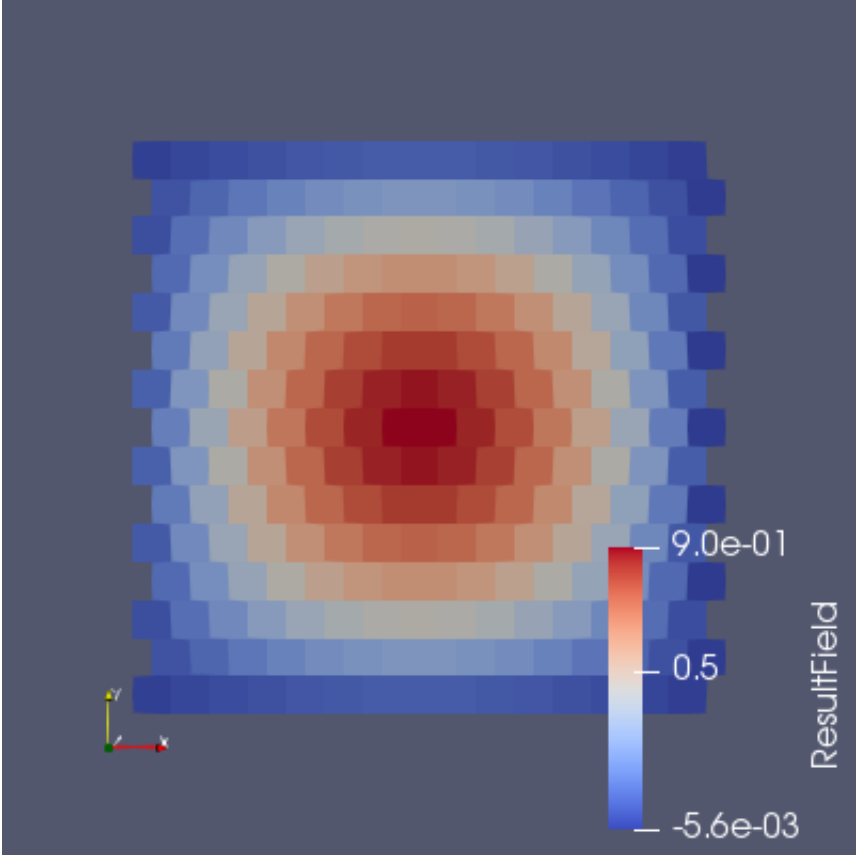
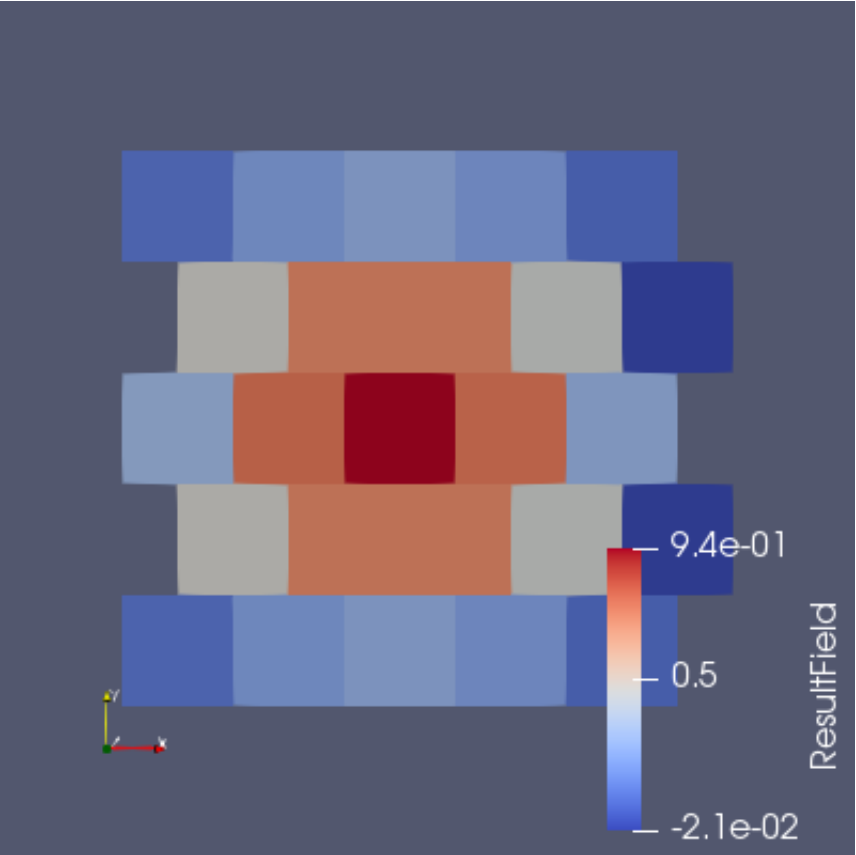


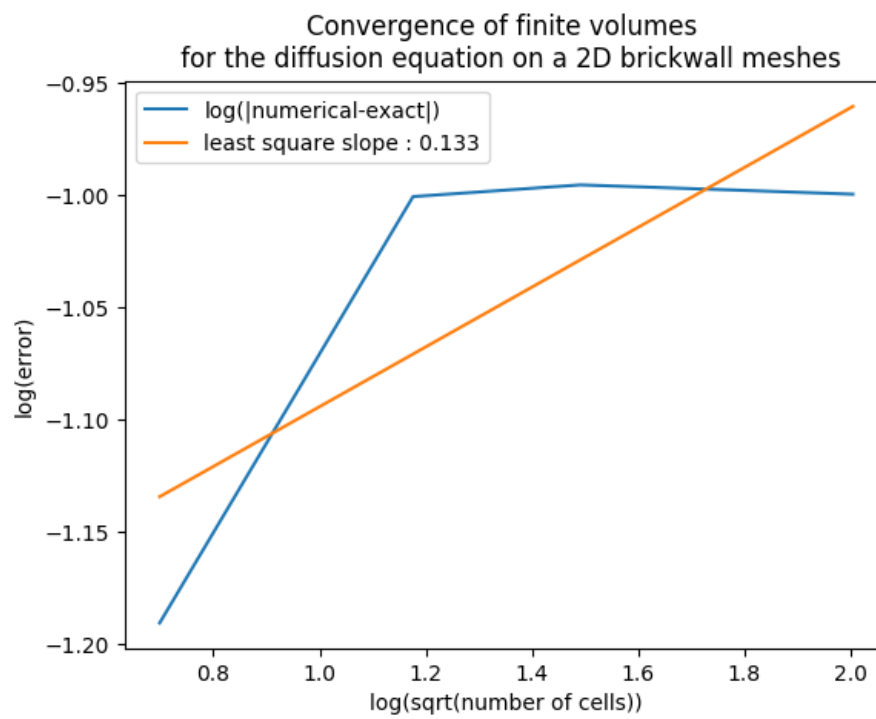
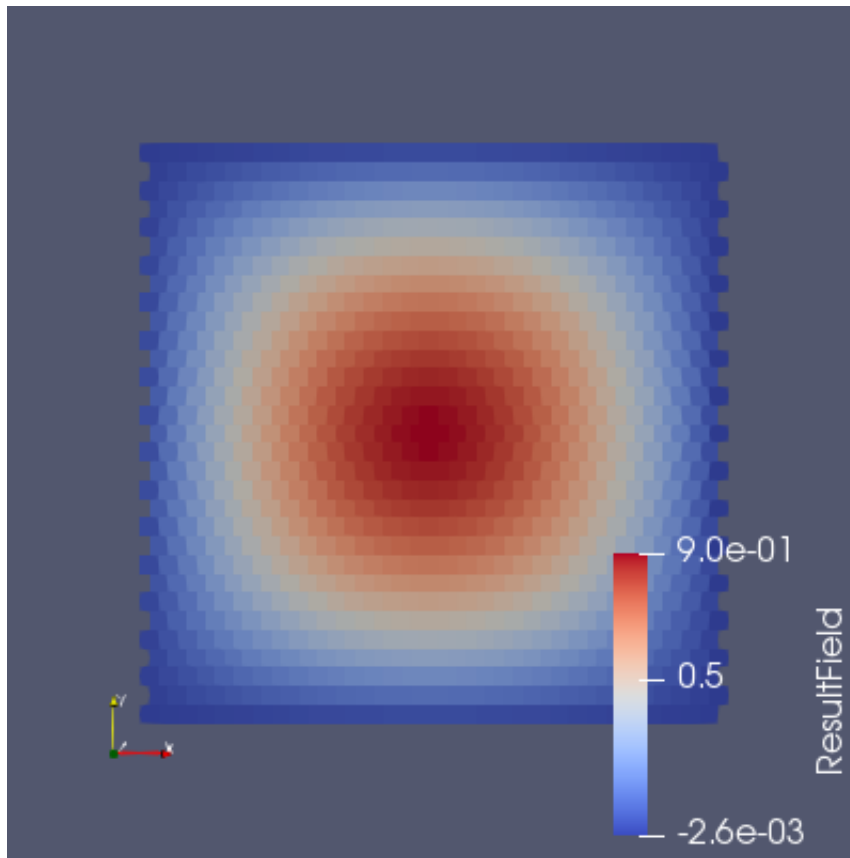
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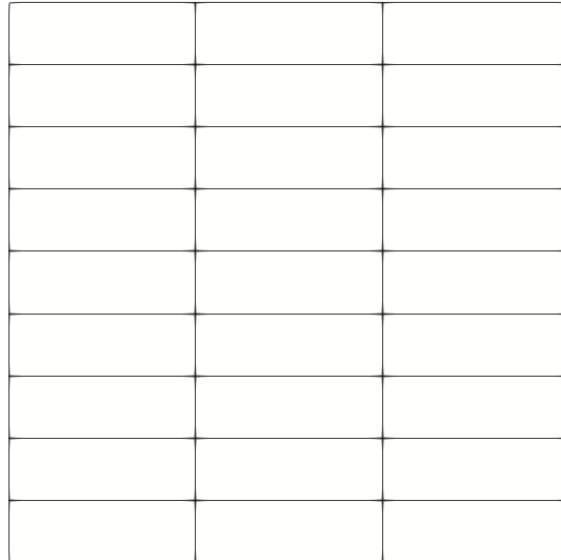


result 1 | result 2 | result 3 - | - - | -

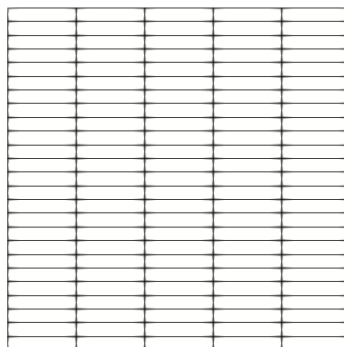




1.12 Long rectangle meshes ((n, n^2) rectangular grid)

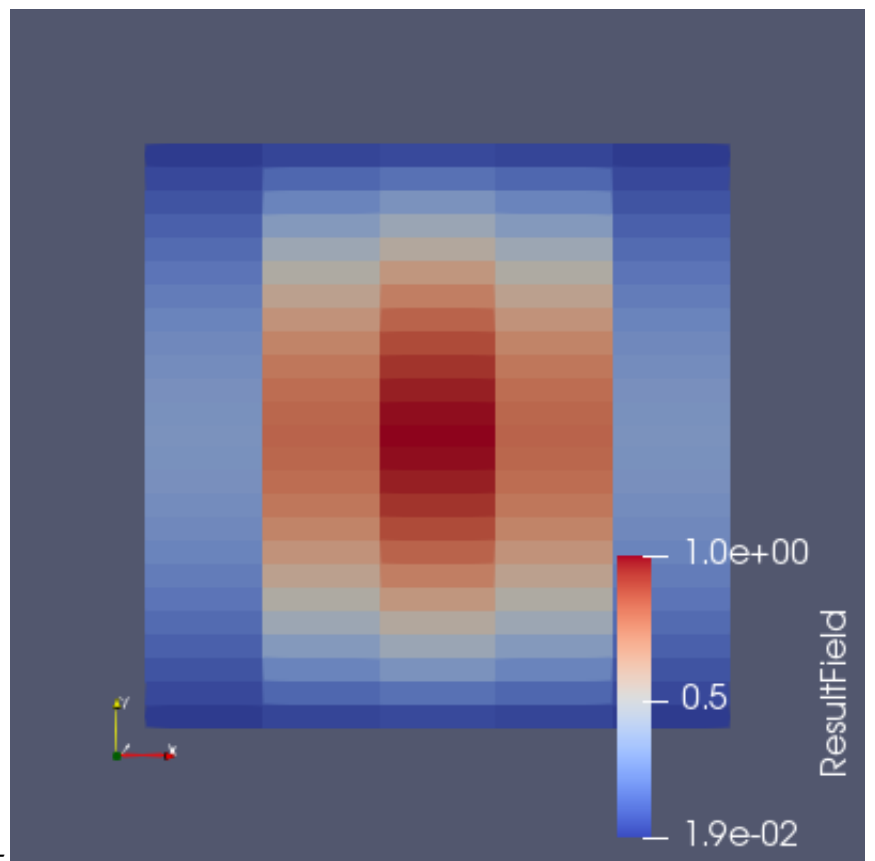
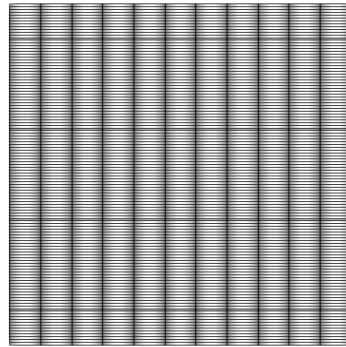


mesh 1 | mesh 2 - | - -

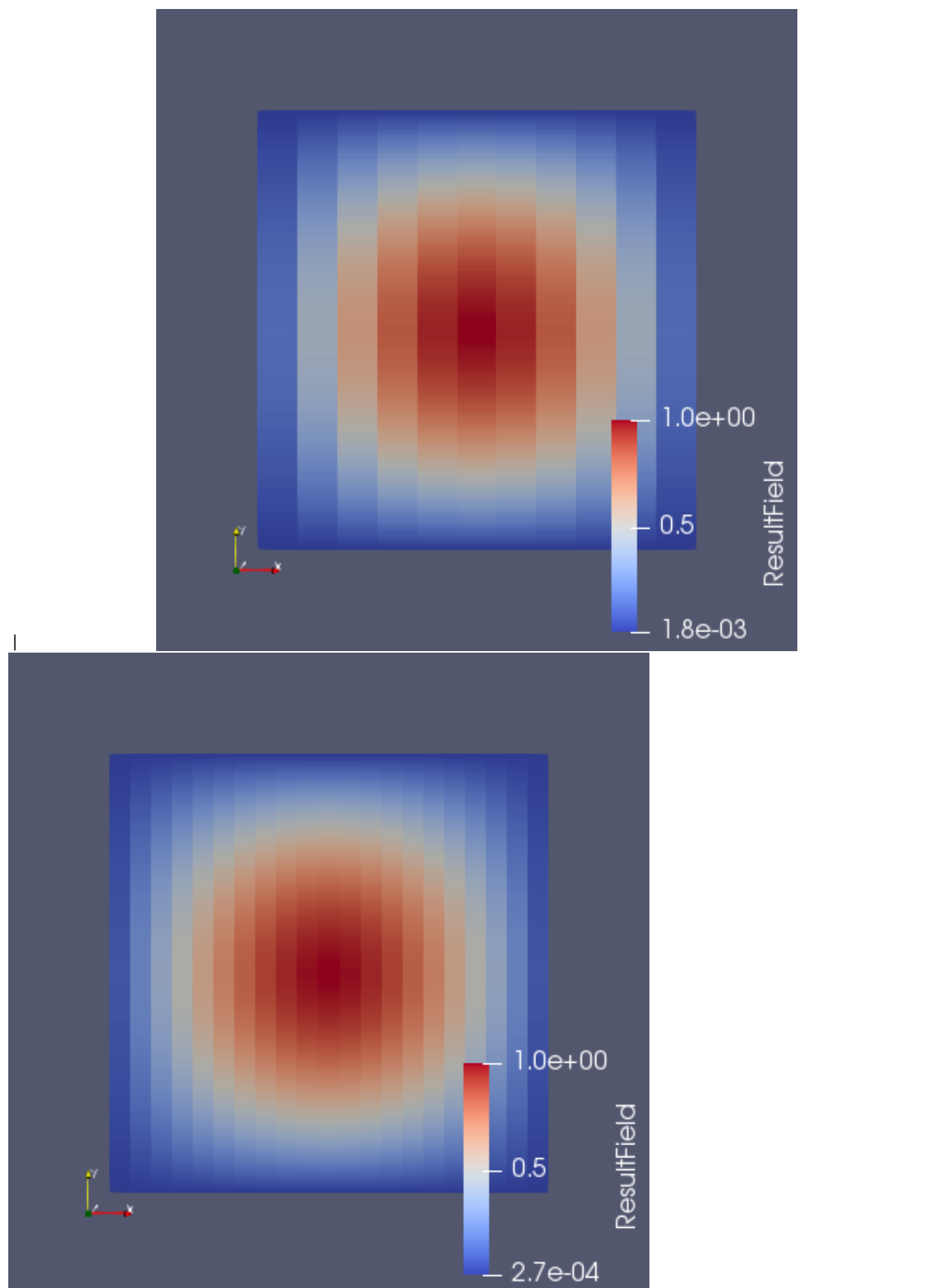


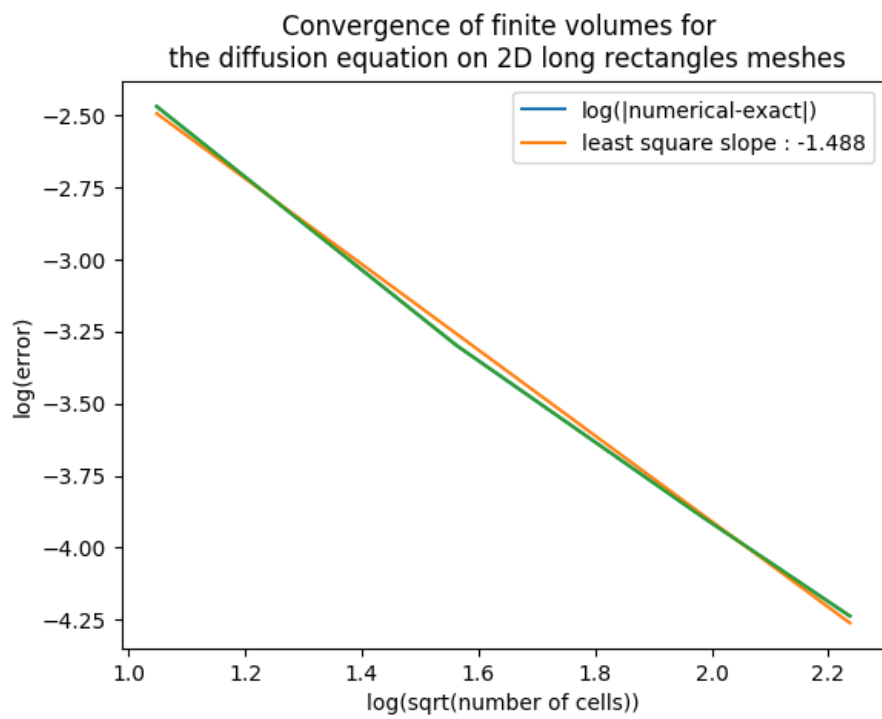
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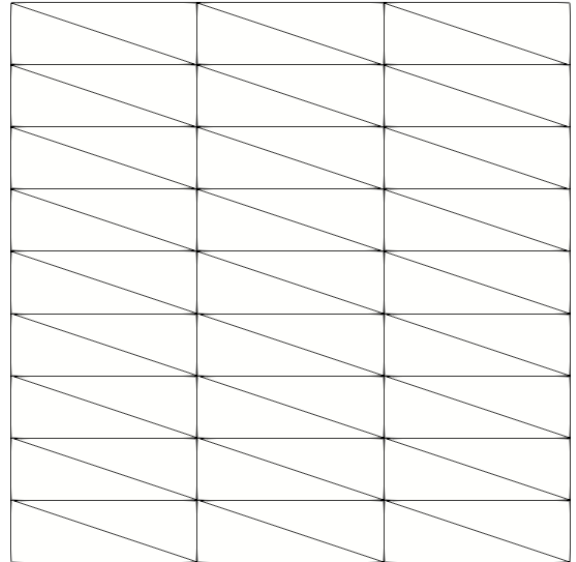


result 1 | result 2 | result 3 - | - - | -

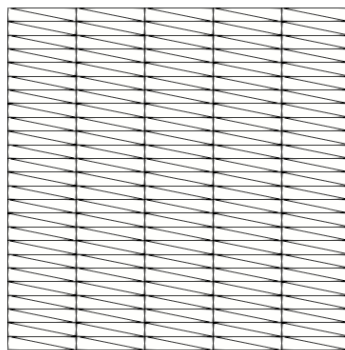




1.13 Skinny right triangle meshes (from a (n, n^2) rectangular grid)

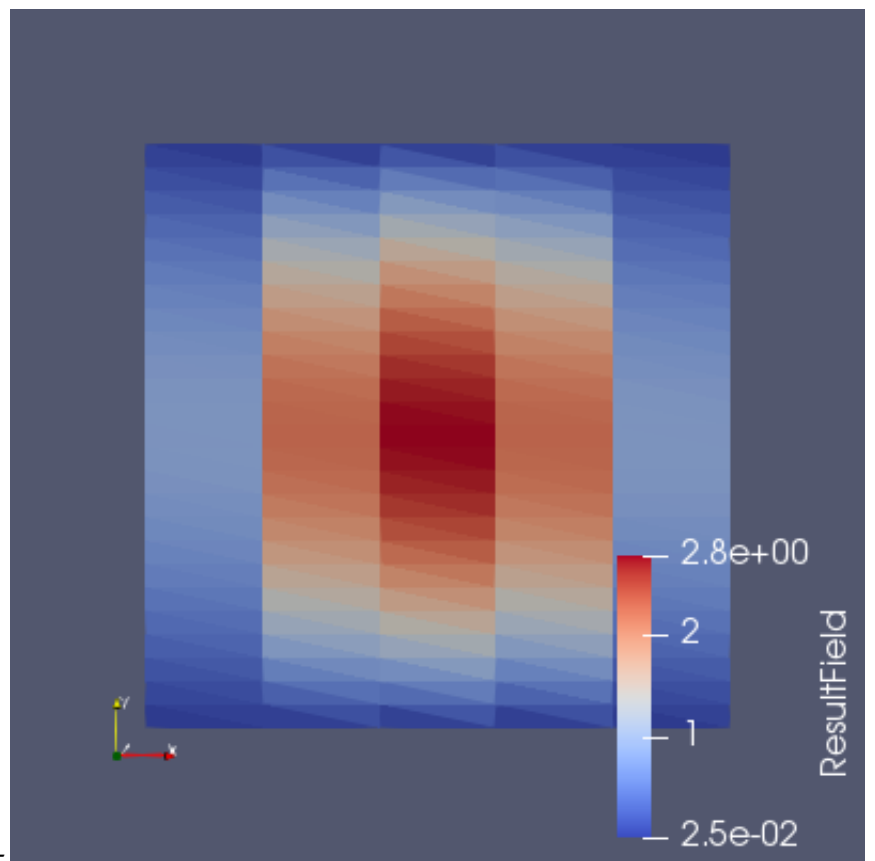
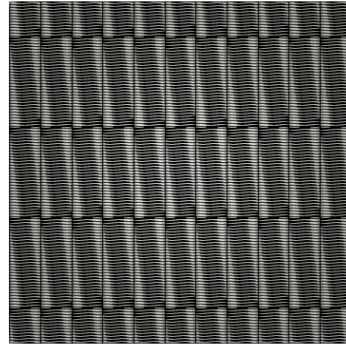


mesh 1 | mesh 2 | mesh 3 - | - - | - -

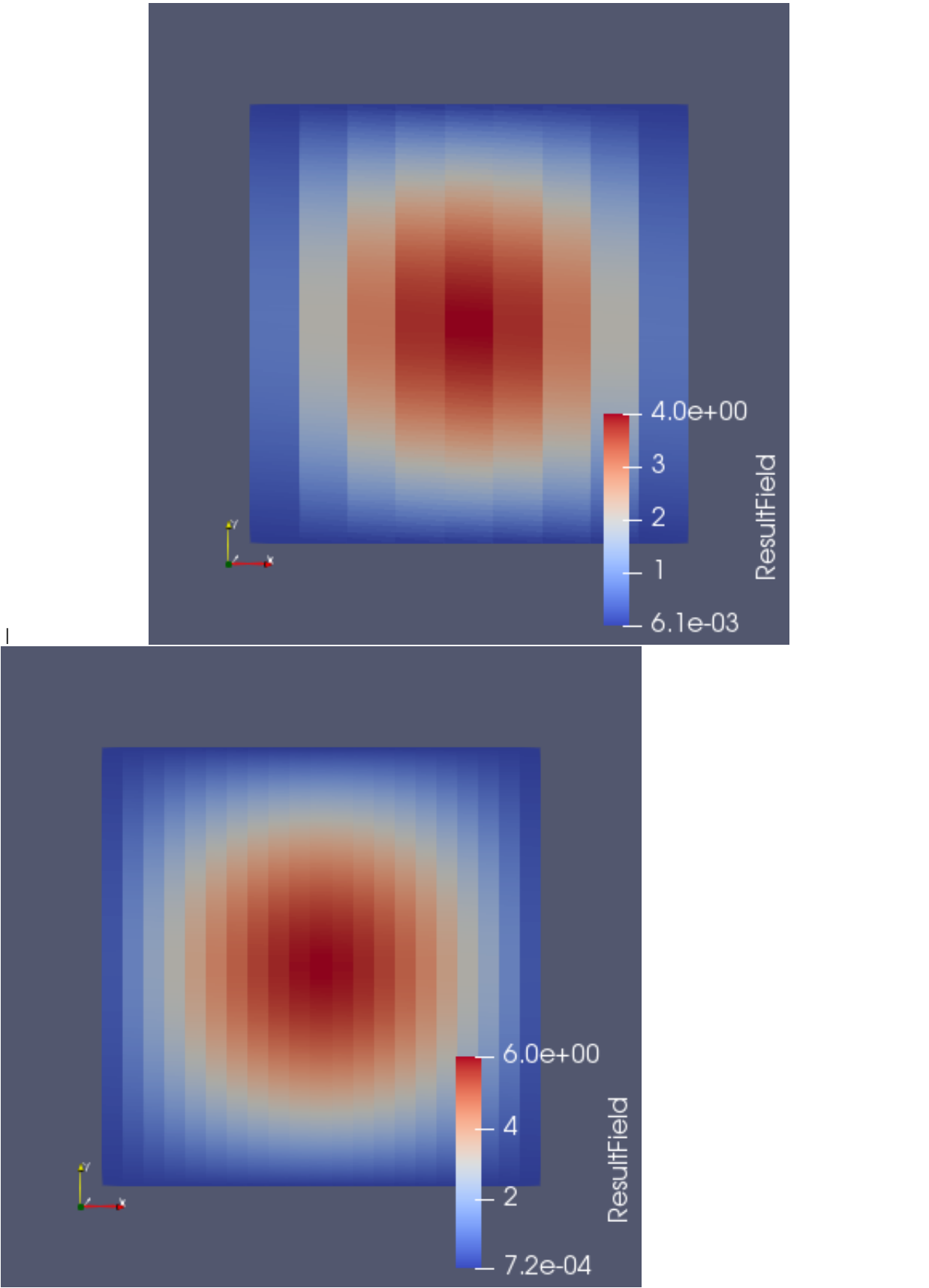


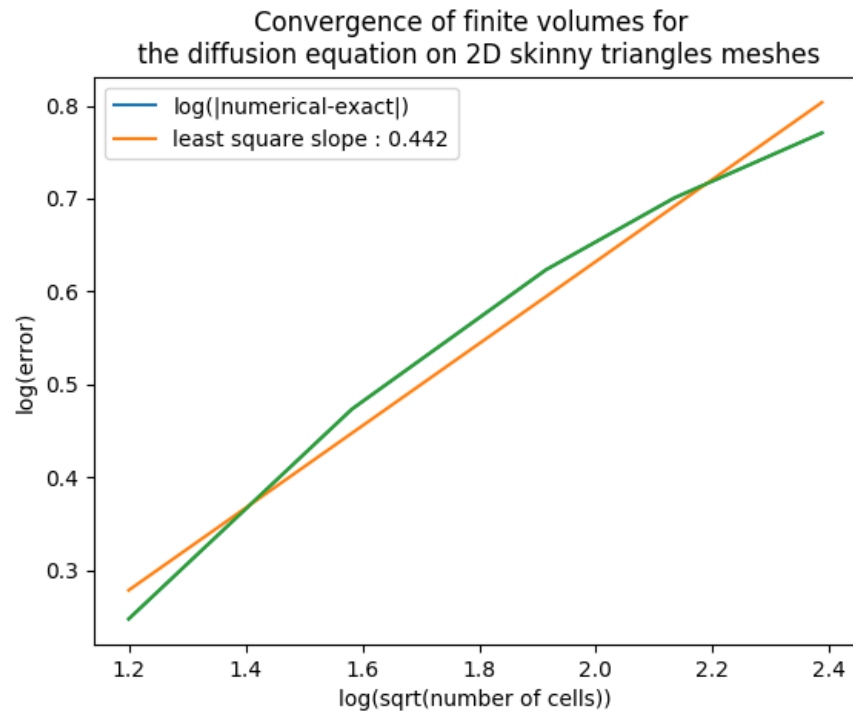
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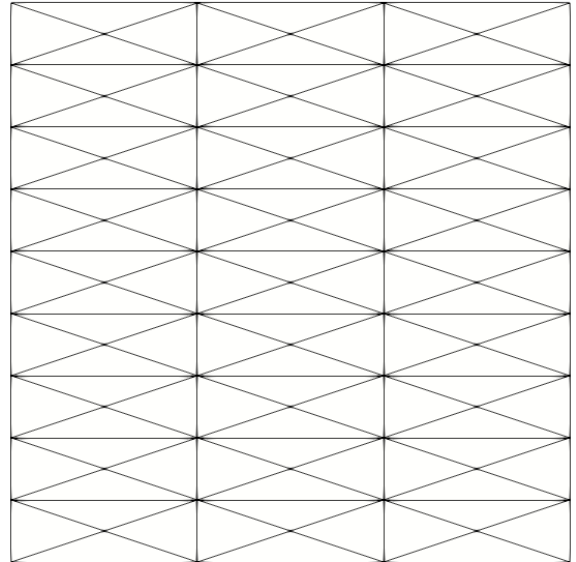


result 1 | result 2 | result 3 - | - - | -





1.14 Flat cross triangle meshes (from a (n, n^2) rectangular grid)



mesh 1 | mesh 2 | mesh 3 - | - - | - -

