

Grade Sheet for a Thesis or Report

Type of Thesis or Course: Motion Planning for Autonomous Vehicles (WS 2017/18)

Advisor:

Submission:

Student:

Evaluator:

	Poor	Fair	Average	Good	Excellent
A) Written report					
Organization	5	4	3	2	1
Logical structure, consistency					
Clarity, comprehensibility					
Content	5	4	3	2	1
Scientific (well defined, accurate, relevant)					
Clear description of logic/methods					
Critical evaluation, concise discussion					
Literature	5	4	3	2	1
Related work: well researched, discussed					
Solid understanding					
Writing skills	5	4	3	2	1
Language: prose, grammar, spelling					
Figures: informative, appealing					
B) Practical work					
Motivation and amount of work	5	4	3	2	1
Independency					
Effort					
Originality and creativity	5	4	3	2	1
Initiative and own contribution					
Novelty					
Quality of work (e.g. software)	5	4	3	2	1
High quality					
Detailed and traceable documentation					
Utilization of results	5	4	3	2	1
Useful for research project					
Reproducibility					

Overall grade: