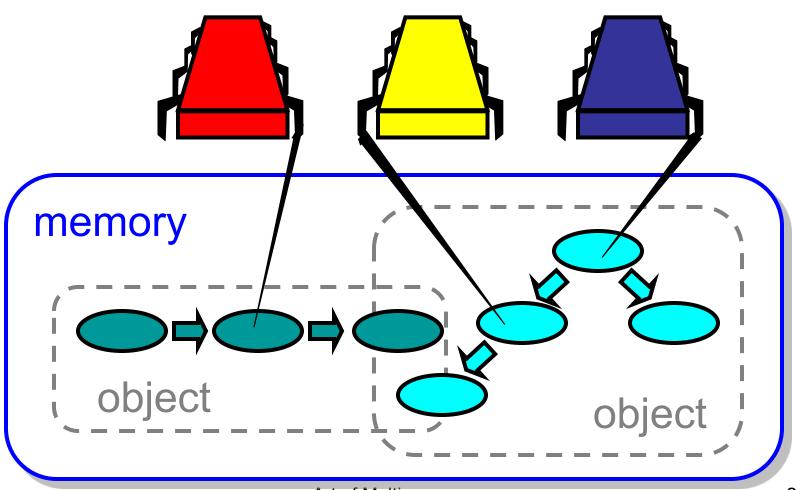
Concurrent programming

Concurrent objects

Companion slides for
The Art of Multiprocessor Programming
by Maurice Herlihy, Nir Shavit, Victor Luchangco,
and Michael Spear

Modified by Piotr Witkowski

Concurrent Computation



Objectivism

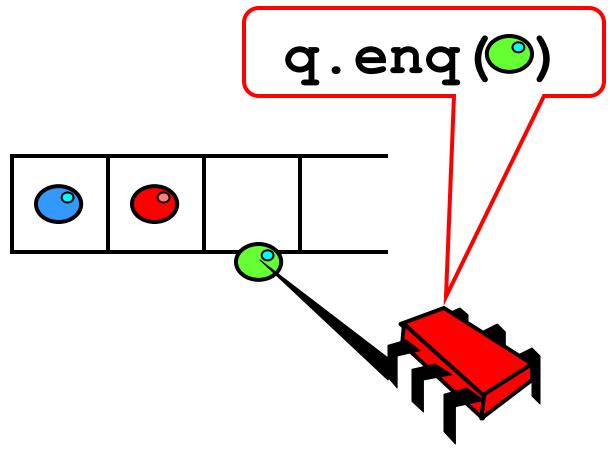
- What is a concurrent object?
 - How do we describe one?
 - How do we implement one?
 - How do we tell if we're right?

Objectivism

- What is a concurrent object?
 - How do we describe one?

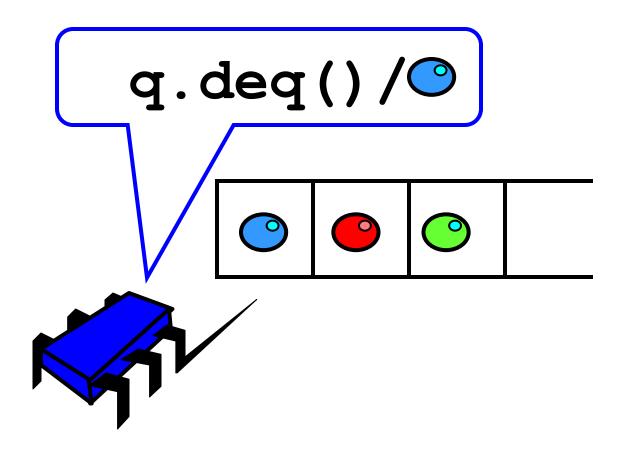
– How do we tell if we're right?

FIFO Queue: Enqueue Method

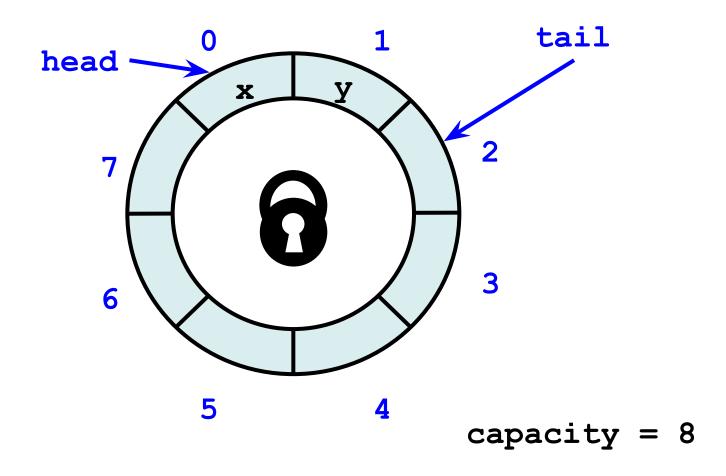


Art of Multiprocessor Programming

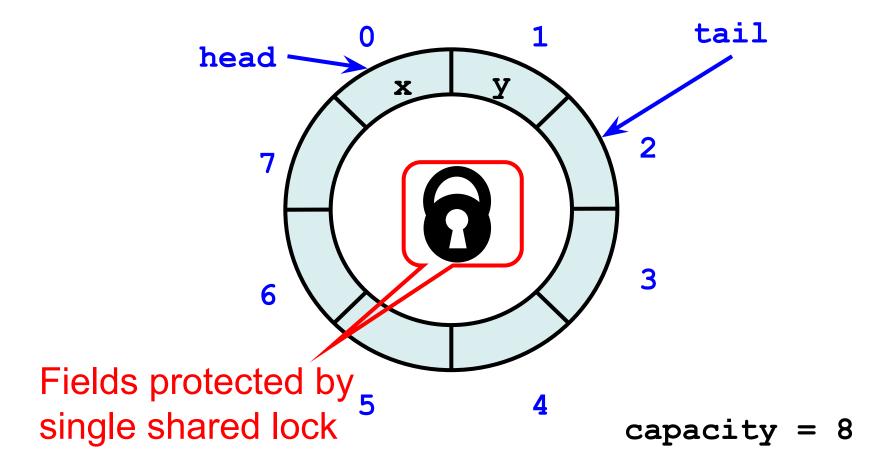
FIFO Queue: Dequeue Method



Lock-Based Queue



Lock-Based Queue



A Lock-Based Queue

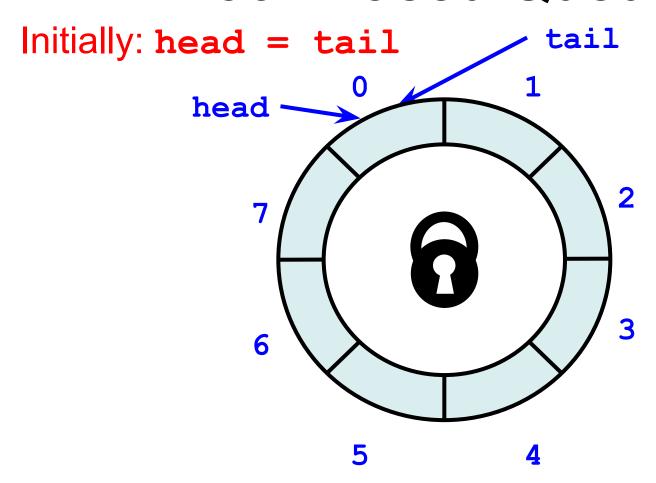
```
class LockBasedQueue<T> {
  int head, tail;
  T[] items;
  Lock lock;
  public LockBasedQueue(int capacity) {
    head = 0; tail = 0;
    lock = new ReentrantLock();
    items = (T[]) new Object[capacity];
}
```

A Lock-Based Queue

```
class LockBasedQueue<T> {
   int head, tail;
   T[] items;
   Lock lock;
   public LockBasedQueue(int capacity) {
     head = 0 \ tail = 0;
     lock = new ReentrantLock();
     items = (T[]) new Object[capacity];
}
```

Fields protected by single shared lock

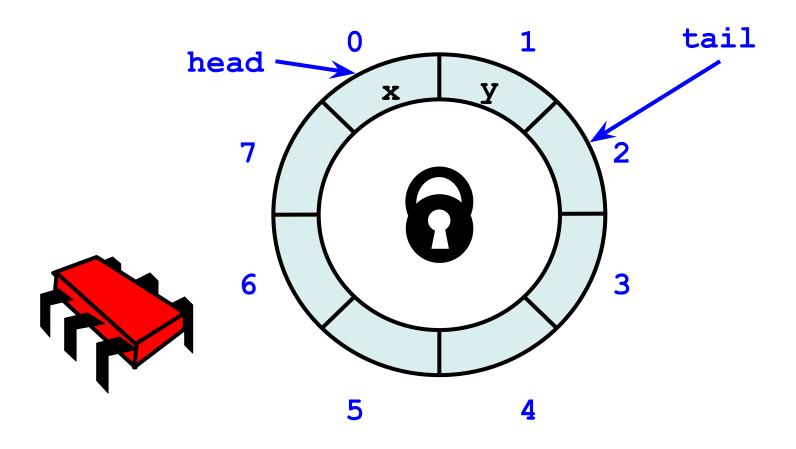
Lock-Based Queue



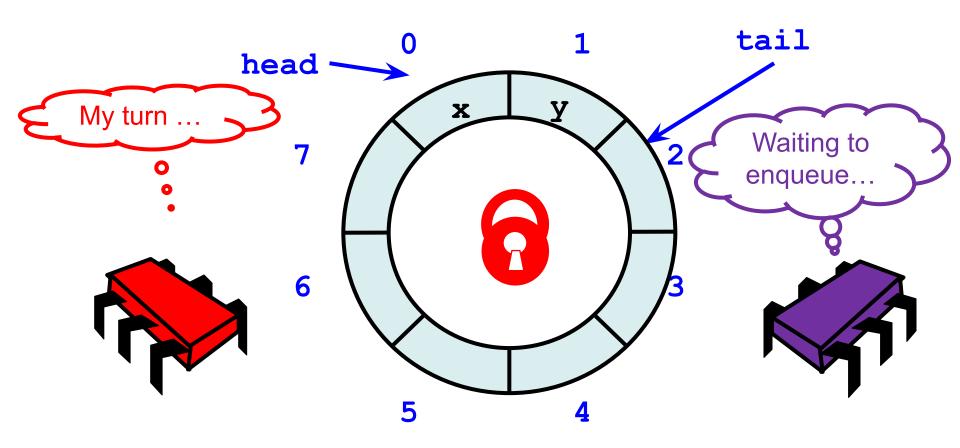
A Lock-Based Queue

```
head
                                          tail
                            capacity-1
class LockBasedQueue<T> {
  int head, tail;
  T[] items;
  Lock lock;
  public LockBasedQueue(int capacity) {
    head = 0; tail = 0;
    lock = new ReentrantLock();
    items = (T[]) new Object[capacity];
                    Initially head = tail
```

Lock-Based deq()



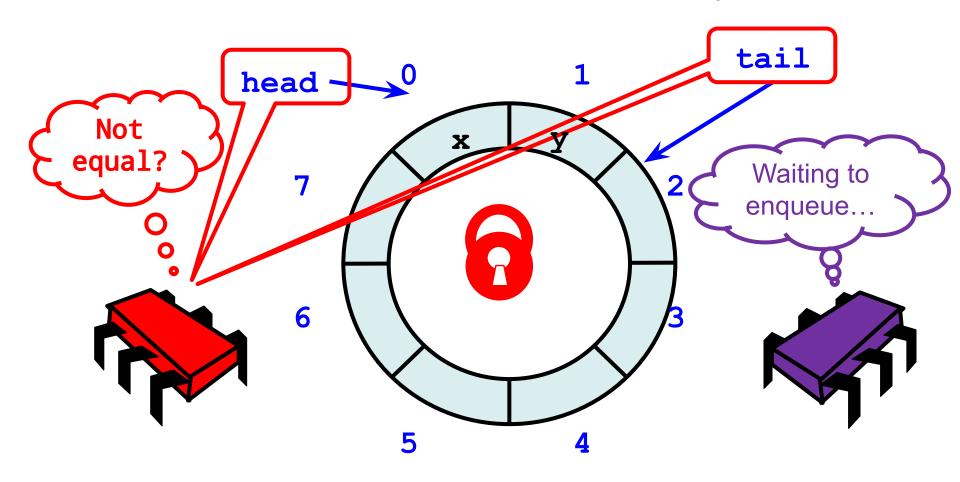
Acquire Lock



Implementation: deq()

```
public T deg() throws EmptyException {
  lock.lock();
                                  Acquire lock at
                                   method start
    if (tail == head)
       throw new EmptyException();
    T x = items[head % items.length];
    head++;
    return x;
                                                  tail
                                       head
  } finally {
                                    capacity-1
    lock.unlock();
```

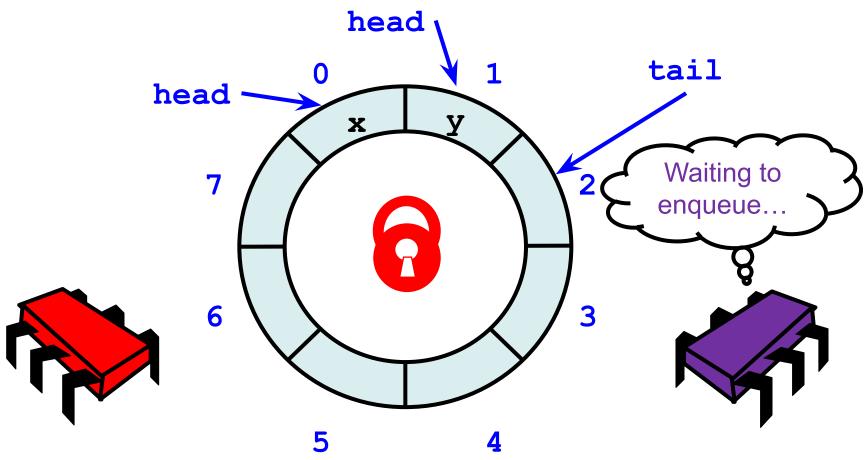
Check if Non-Empty



Implementation: deq()

```
public T deq() throws EmptyException {
  lock.lock();
  trv
    if (tail == head)
       throw new EmptyException();
                         items /length];
    T x = items[head]
    head++;
    return x;
                                          head
                                                    tail
  } finally {
                                      capacity-1
    lock.unlock();
             If queue empty
             throw exception
```

Modify the Queue



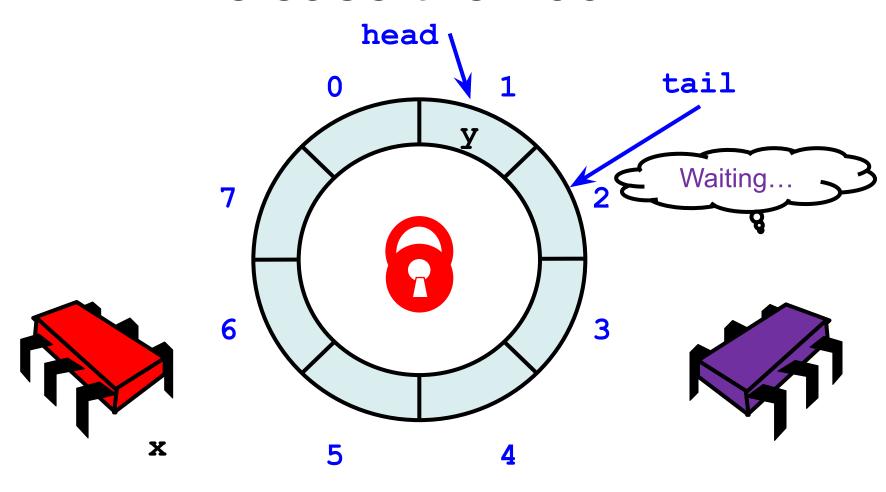
Implementation: deq()

```
public T deq() throws EmptyException {
  lock.lock();
  try {
    if (tail == head)
       throw new EmptyException():
    T x = items[head % items.length];
    head++;
                                         head
                                                   tail
    return x;
    finally {
                                      capacity-1
    lock.unlock();
             Queue not empty?
      Remove item and update head
```

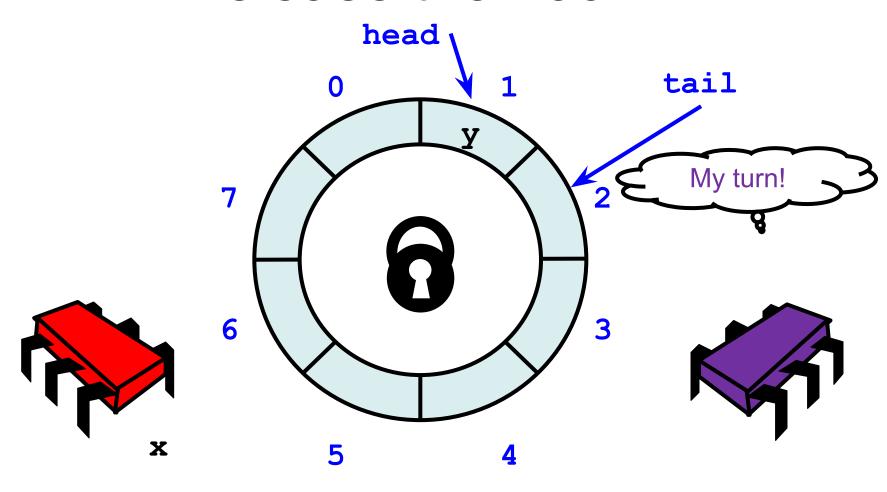
Implementation: deq()

```
public T deq() throws EmptyException {
  lock.lock();
  try {
    if (tail == head)
       throw new EmptyException();
    T x = items[head % items.length];
    head++:
    return x;
                                          head
                                                     tail
    finally
                                      capacity-1
    lock.unlock();
              Return result
```

Release the Lock



Release the Lock



Implementation: deq()

```
public T deq() throws EmptyException {
  lock.lock();
  try {
    if (tail == head)
       throw new EmptyException();
    T x = items[head % items.length];
    head++;
                                        head
                                                   tail
    return x;
                                     capacity-1
    finally {
    lock.unlock();
            Release lock no
```

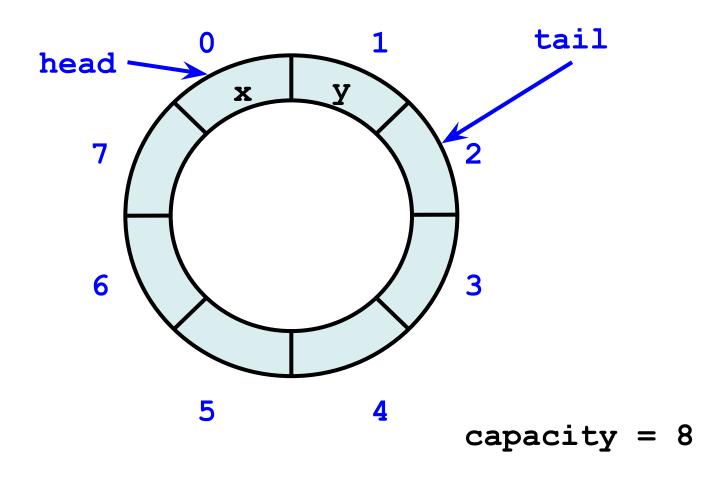
matter what!

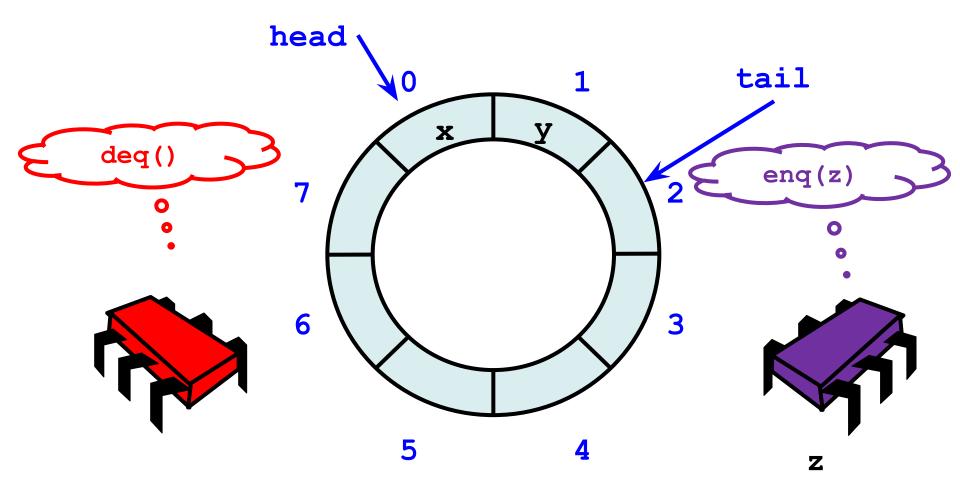
Implementation: deq()

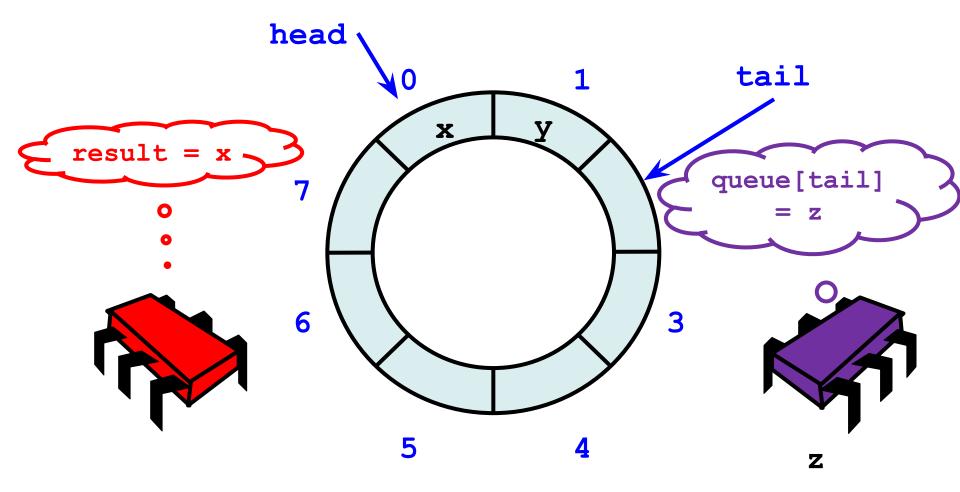
```
public T deq() throws EmptyException {
  lock.lock();
  try {
    if (tail == head)
       throw new EmptyException();
    T x = items[head % items.length];
                   modifications are mutually exclusive...
    head++;
                  Should be correct because
    return x;
  } finally {
    lock.unlock();
```

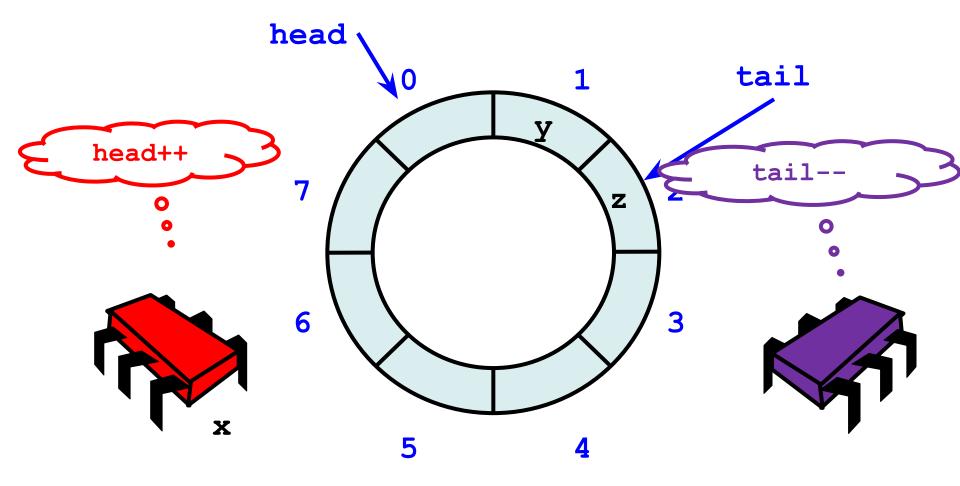
Now consider the following implementation

- The same thing without mutual exclusion
- For simplicity, only two threads
 - One thread enq only
 - The other deq only









```
head
                                                   tail
public class WaitFreeQueue {
                                     capacity-1
  int head = 0, tail = 0;
  items = (T[]) new Object[capacity];
  public void enq(Item x) {
    if (tail-head == capacity) throw
          new FullException();
    items[tail % capacity] = x; tail++
  public Item deq() {
     if (tail == head) throw
                                   No lock needed
         new EmptyException();
     Item item = items[head % capacity]; head++;
     return item;
                   Art of Multiprocessor
                                                   30
                     Programming
```

```
public T deq() throws EmptyException {
   lock.lock();
   try {
    T x = items[headefine "correct" when head++; do we define not mutually return How do we are not mutually finally
                modifications are not mutually exclusive?
      finall
       lock.un
```

What is a Concurrent Queue?

- Need a way to specify a concurrent queue object
- Need a way to prove that an algorithm implements the object's specification
- Lets talk about object specifications ...



Correctness and Progress

- In a concurrent setting, we need to specify both the safety and the liveness properties of an object
- Need a way to define
 - when an implementation is correct
 - the conditions under which it guarantees progress

Lets begin with correctness



Sequential Objects

- Each object has a state
 - Usually given by a set of fields
 - Queue example: sequence of items
- Each object has a set of methods
 - Only way to manipulate state
 - Queue example: enq and deq methods



Sequential Specifications

- If (precondition)
 - the object is in such-and-such a state
 - before you call the method,
- Then (postcondition)
 - the method will return a particular value
 - or throw a particular exception.
- and (postcondition, con't)
 - the object will be in some other state
 - when the method returns,



Pre and PostConditions for Dequeue

- Precondition:
 - Queue is non-empty
- Postcondition:
 - Returns first item in queue
- Postcondition:
 - Removes first item in queue



Pre and PostConditions for Dequeue

- Precondition:
 - Queue is empty
- Postcondition:
 - Throws Empty exception
- Postcondition:
 - Queue state unchanged



Why Sequential Specifications Totally Rock

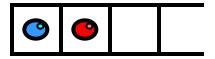
- Interactions among methods captured by side-effects on object state
 - State meaningful between method calls
- Documentation size linear in number of methods
 - Each method described in isolation
- Can add new methods
 - Without changing descriptions of old methods



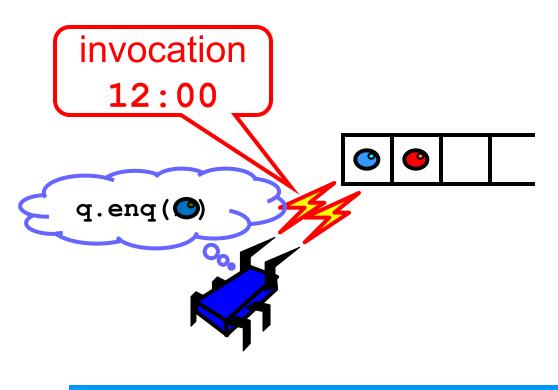
What About Concurrent Specifications?

- Methods?
- Documentation?
- Adding new methods?

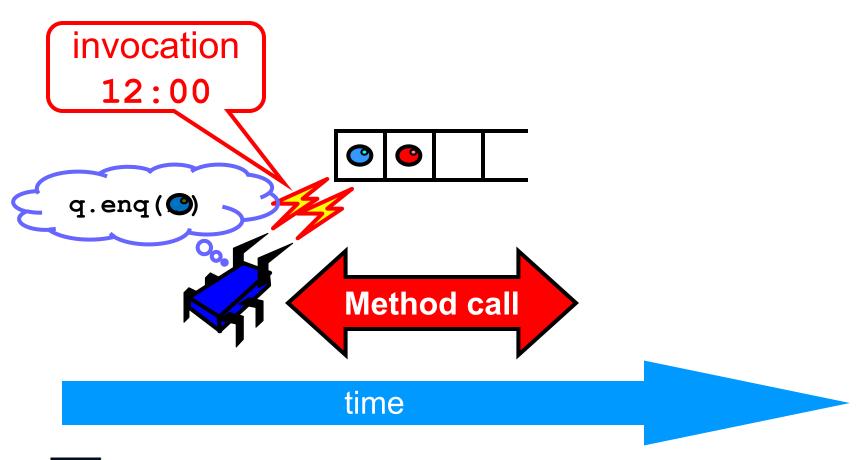




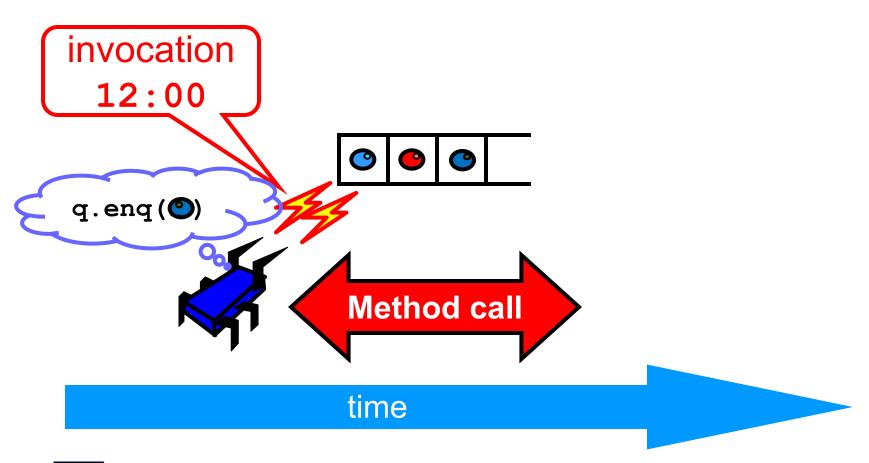




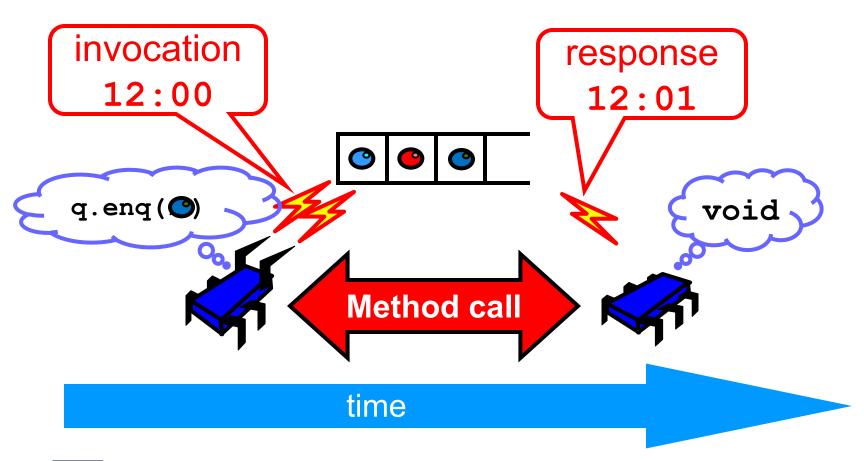








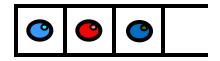




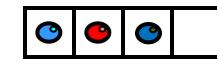


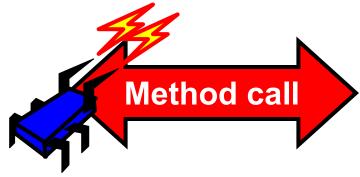
- Sequential
 - Methods take time? Who knew?
- Concurrent
 - Method call is not an event
 - Method call is an interval.



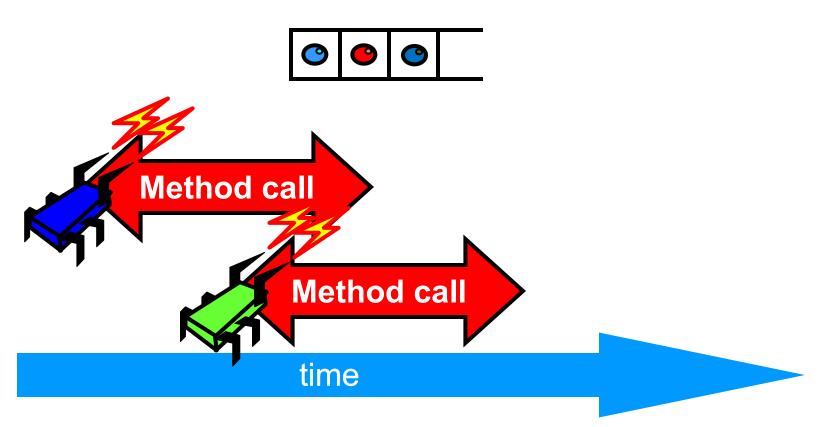




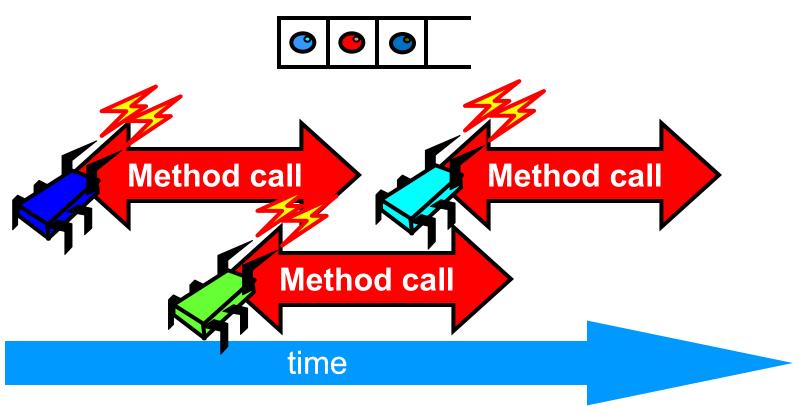














- Sequential:
 - Object needs meaningful state only between method calls
- Concurrent
 - Because method calls overlap, object might never be between method calls



- Sequential:
 - Each method described in isolation
- Concurrent
 - Must characterize all possible interactions with concurrent calls
 - What if two enq() calls overlap?
 - Two deq() calls? enq() and deq()? ...



Sequential:

Can add new methods without affecting older methods

Concurrent:

 Everything can potentially interact with everything else



- Sequential:
 - Can add new methods without affecting older methods
- Concurrent:

Everything can potentially interact with everything else



The Big Question

- What does it mean for a concurrent object to be correct?
 - What is a concurrent FIFO queue?
 - FIFO means strict temporal order
 - Concurrent means ambiguous temporal order



Intuitively...

```
public T deq() throws EmptyException {
  lock.lock();
  try {
    if (tail == head)
       throw new EmptyException();
    T x = items[head % items.length];
    head++;
    return x;
  } finally {
    lock.unlock();
```



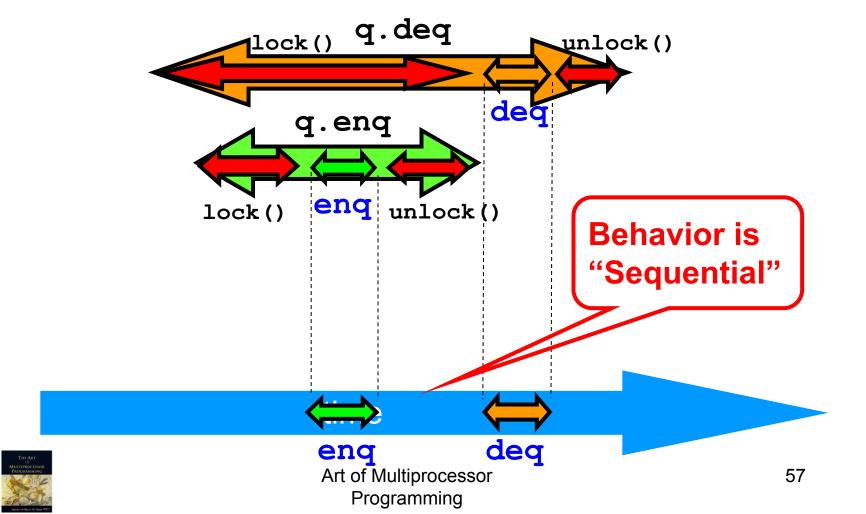
Intuitively...

```
public T dea() throws EmptyException {
  lock.lock();
    if (tail
                head)
       throw New EmptyException();
    T x = items[head % items.length];
   head++;
    return x;
                        All queue modifications
    finally 4
    lock.unlock();
                         are mutually exclusive
```



1.24...:4:...

Lets capture the idea of describing the concurrent via the sequential



Linearizability

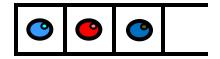
- Each method should
 - "take effect"
 - Instantaneously
 - Between invocation and response events
- Object is correct if this "sequential" behavior is correct
- Any such concurrent object is
 - Linearizable™



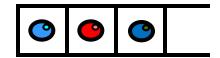
Is it really about the object?

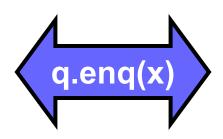
- Each method should
 - "take effect"
 - Instantaneously
 - Between invocation and response events
- Sounds like a property of an execution...
- A linearizable object: one all of whose possible executions are linearizable



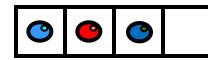


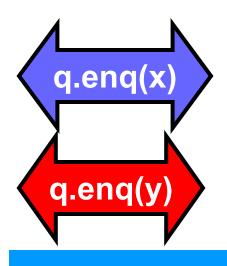




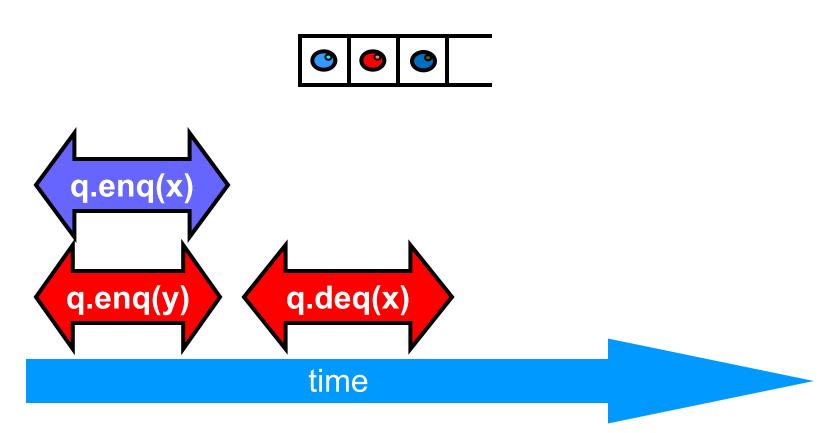






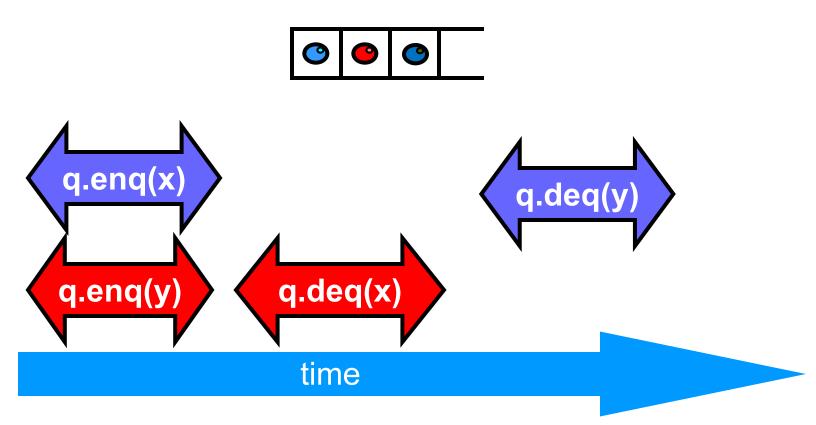




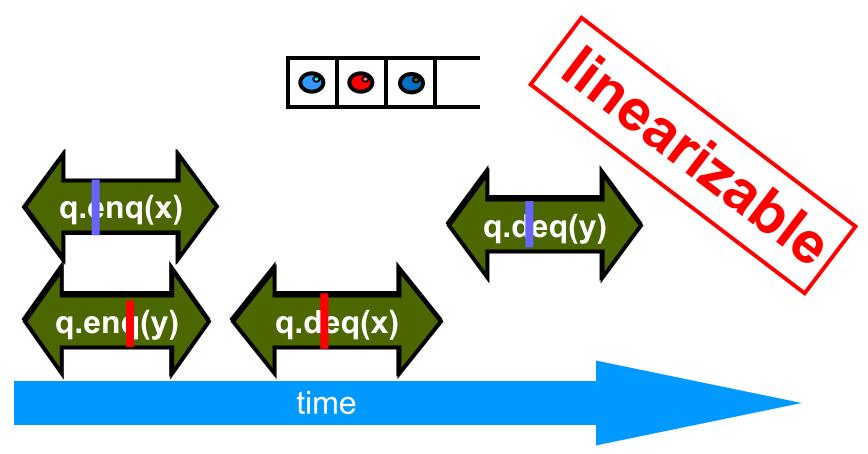




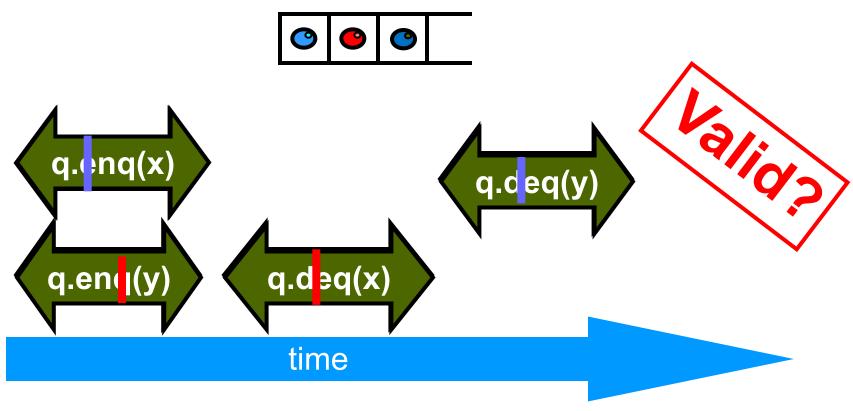




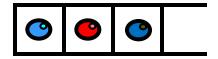




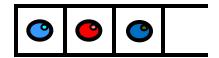


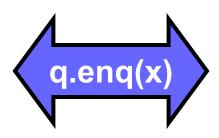




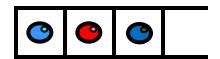


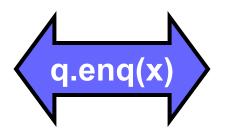


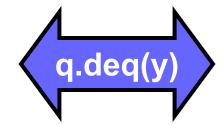






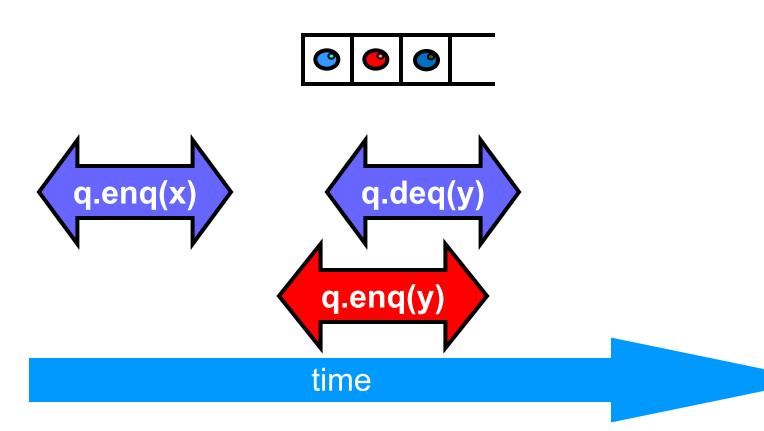






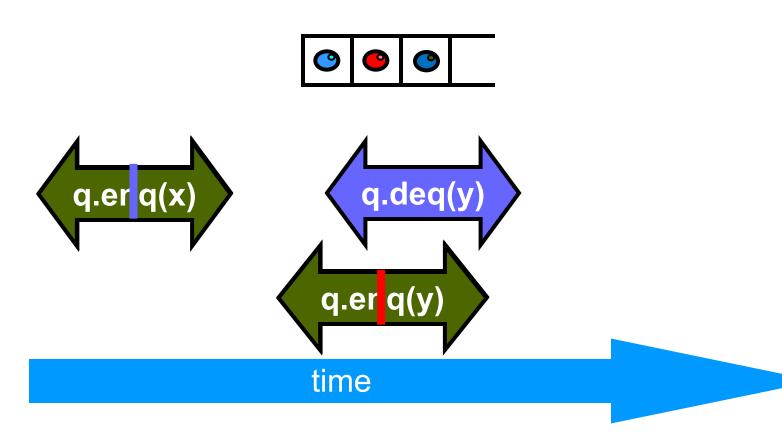






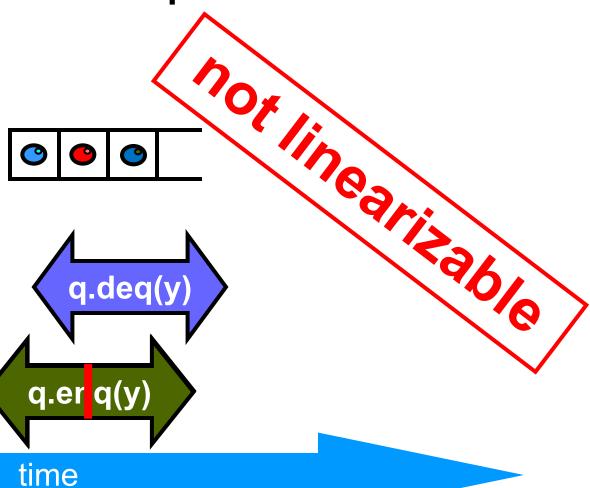






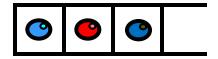






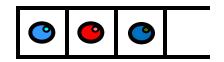


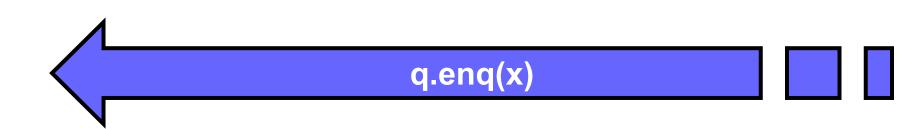
q.er q(x)



time



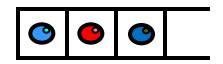


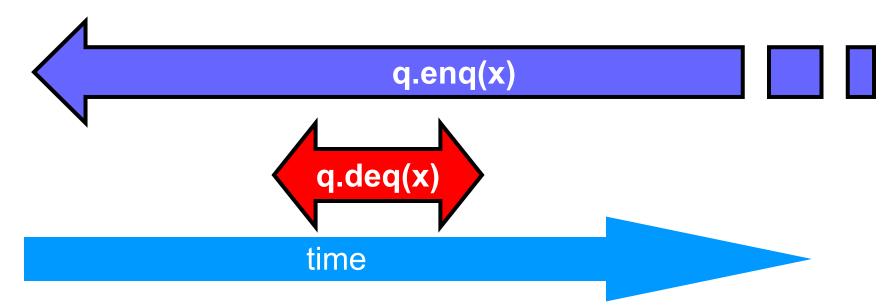


time



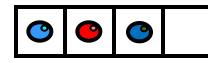


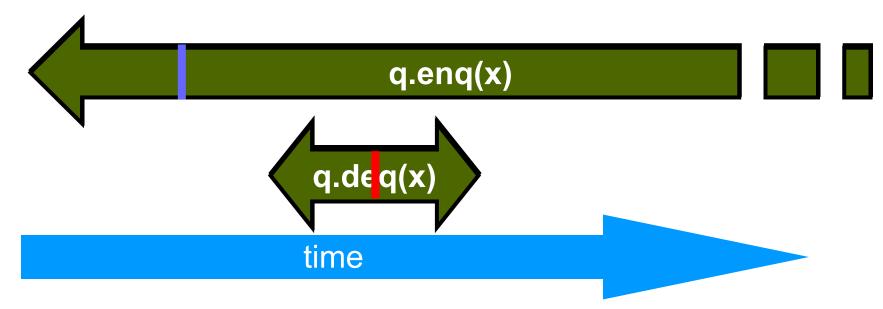






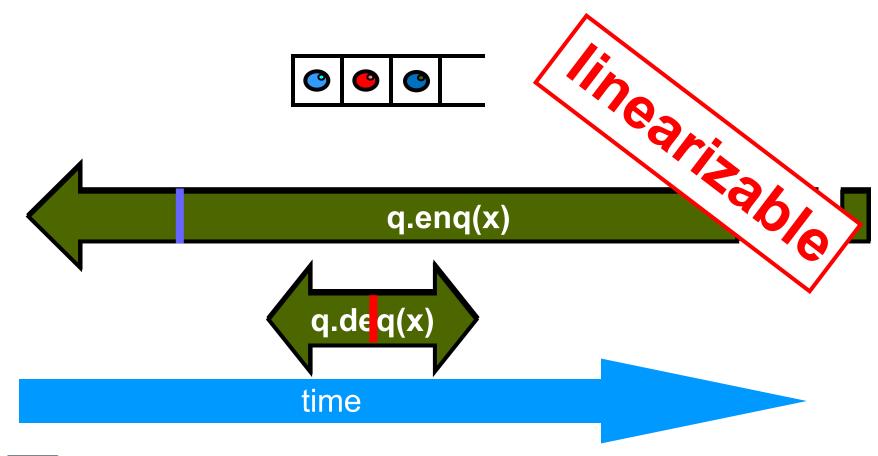




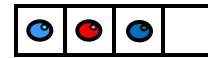


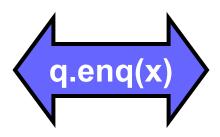






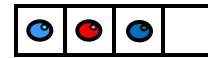


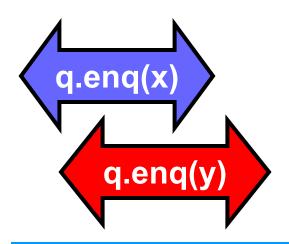




time

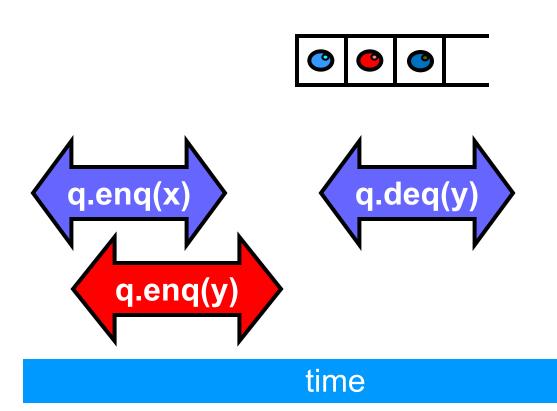






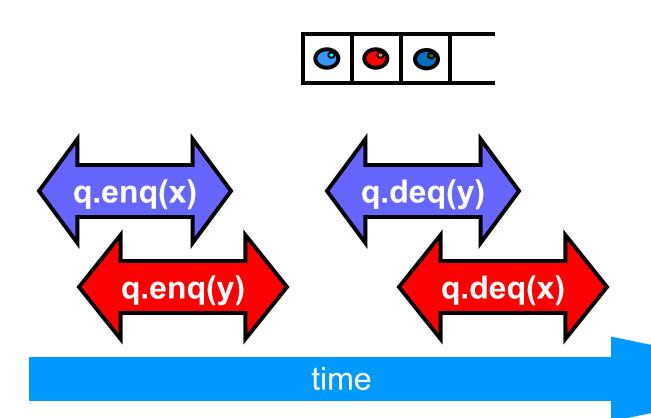
time



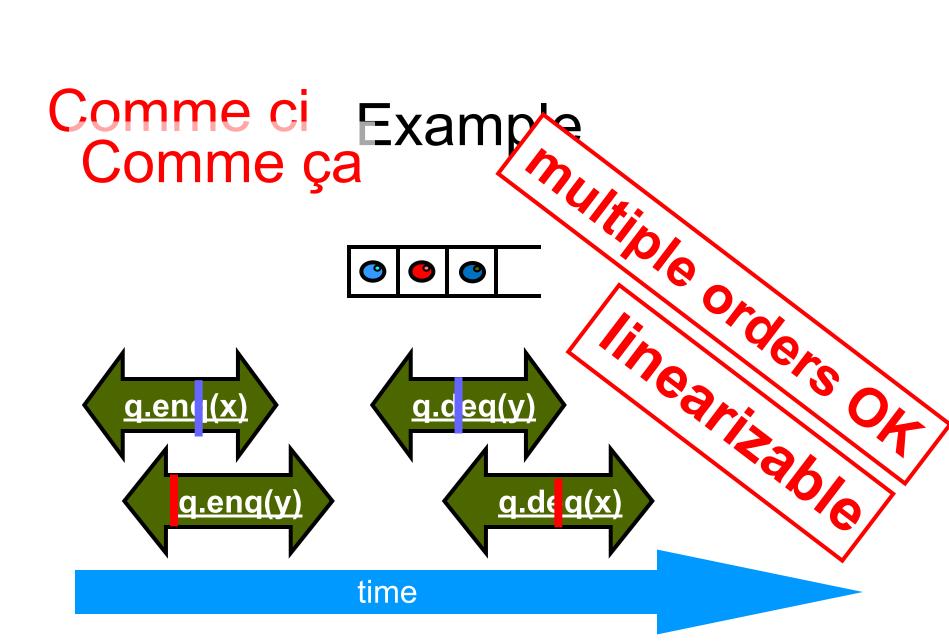




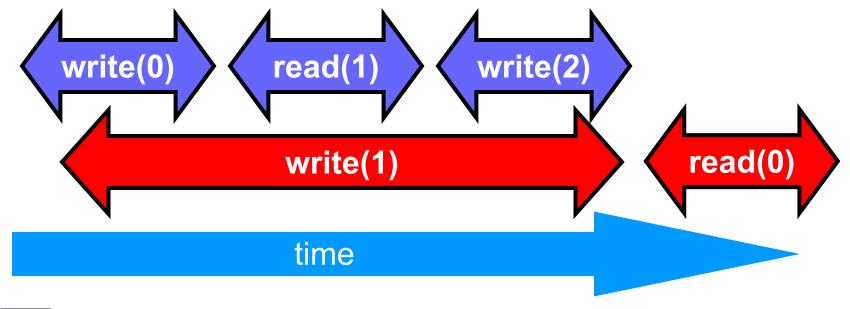




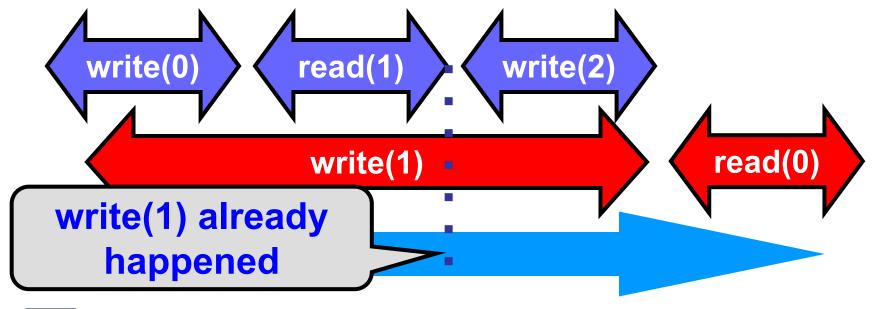




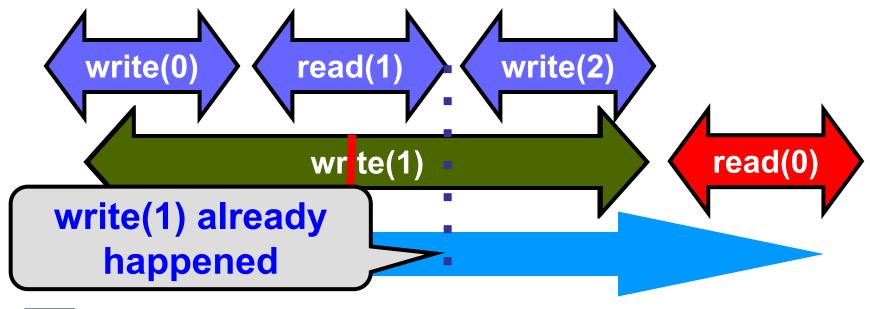




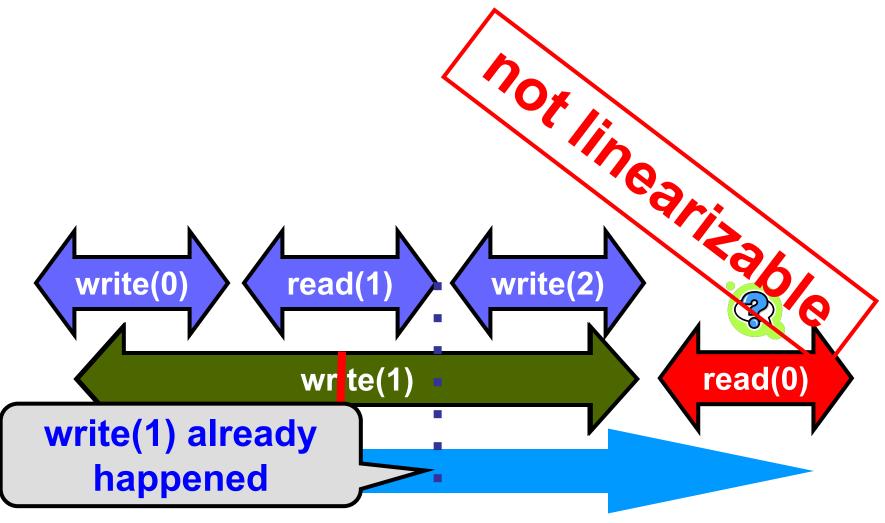




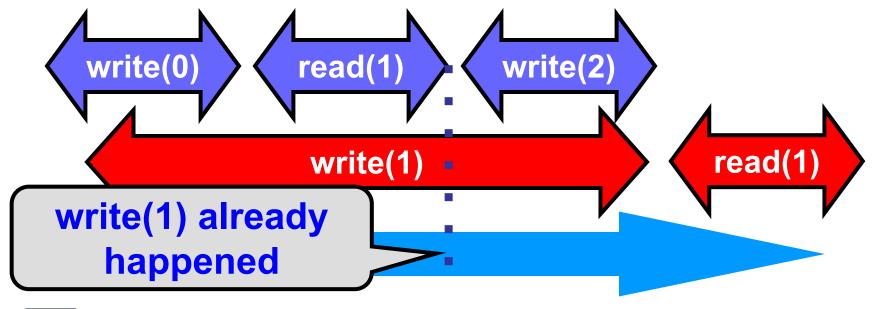




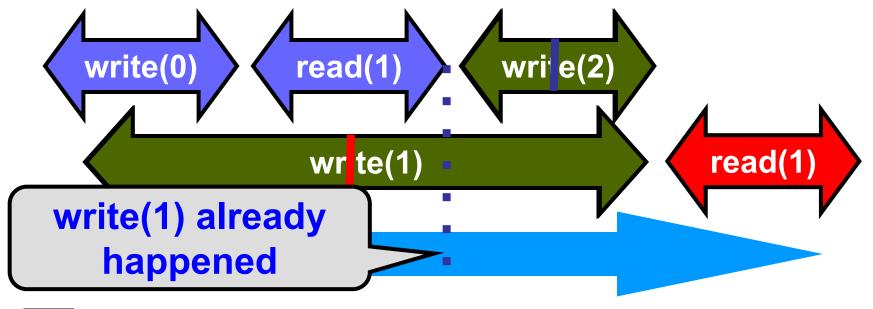




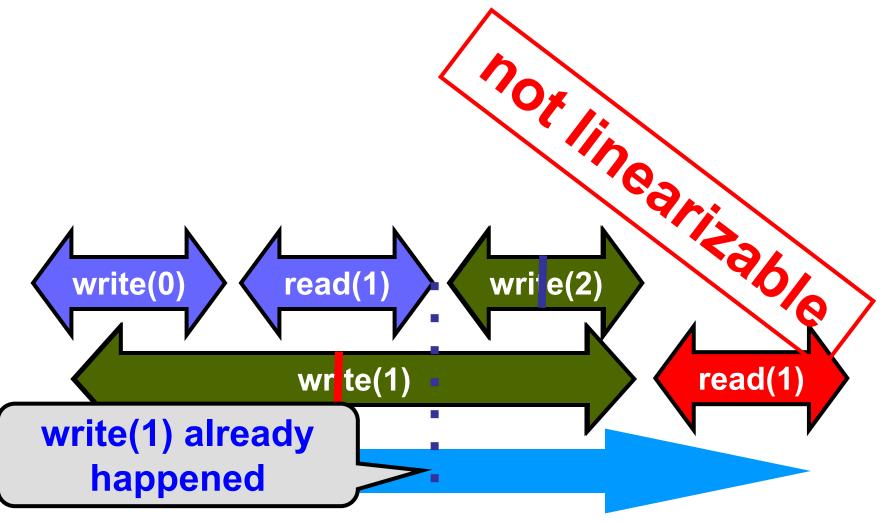




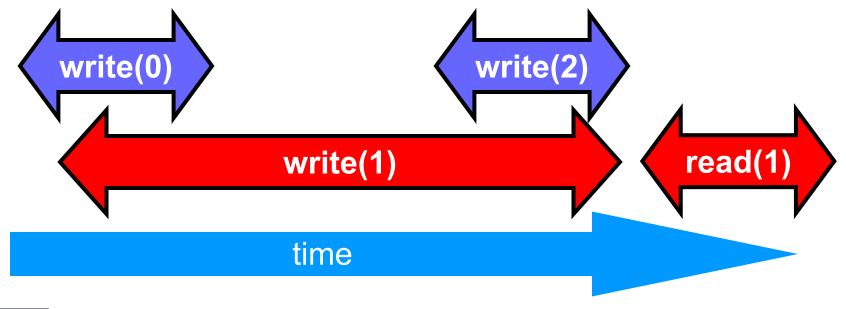




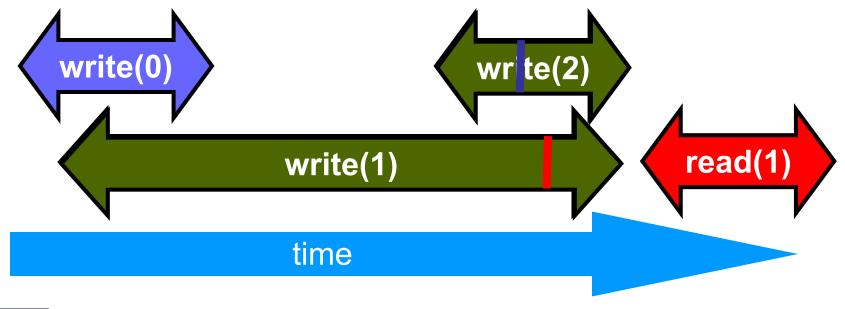




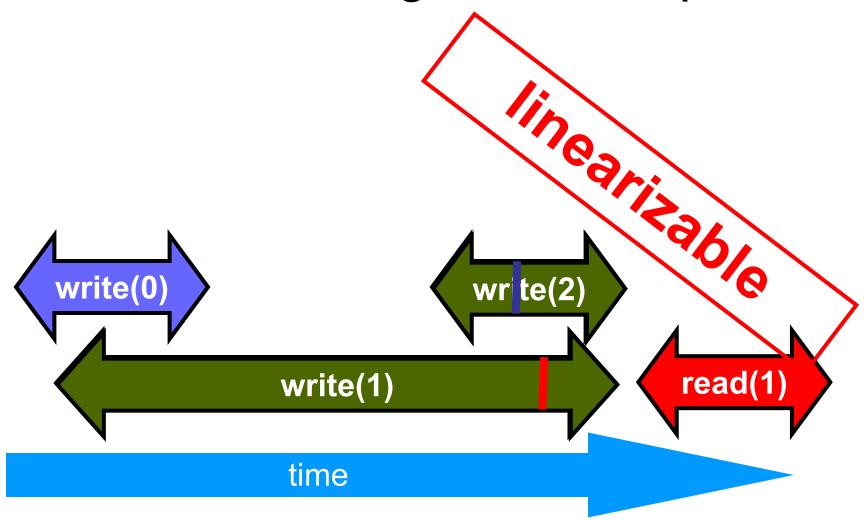














Talking About Executions

- Why?
 - Can't we specify the linearization point of each operation without describing an execution?
- Not Always
 - In some cases, linearization point depends on the execution



Formal Model of Executions

- Define precisely what we mean
 - Ambiguity is bad when intuition is weak
- Allow reasoning
 - Formal
 - But mostly informal
 - In the long run, actually more important
 - Ask me why!



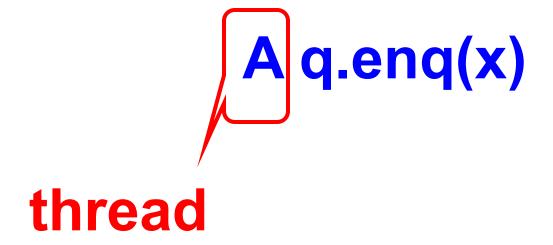
Split Method Calls into Two Events

- Invocation
 - method name & args
 - -q.enq(x)
- Response
 - result or exception
 - q.enq(x) returns void
 - -q.deq() returns x
 - -q.deq() throws empty

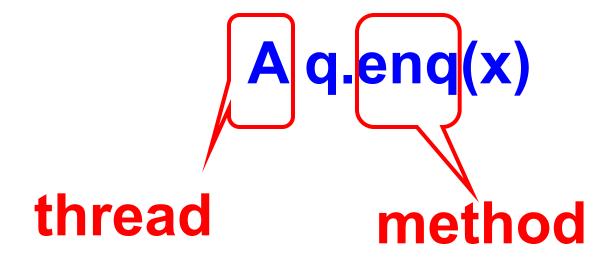


A q.enq(x)

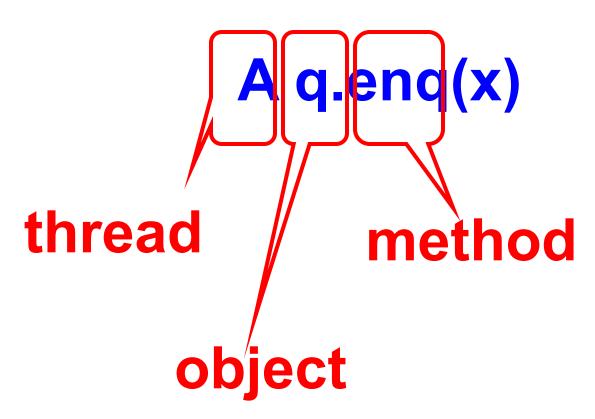




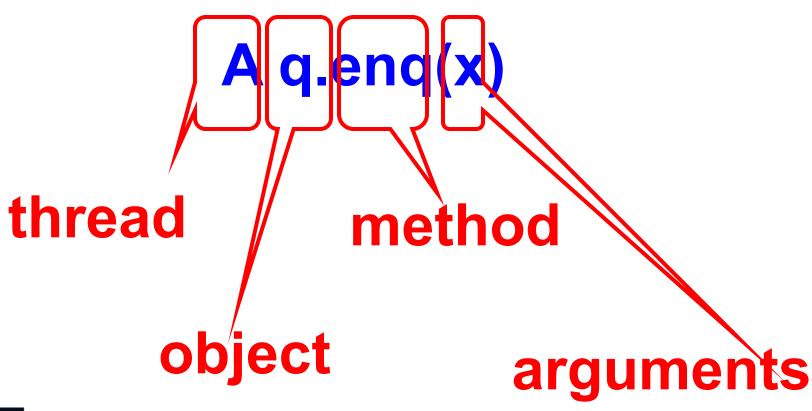








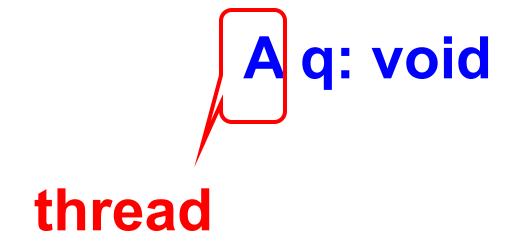




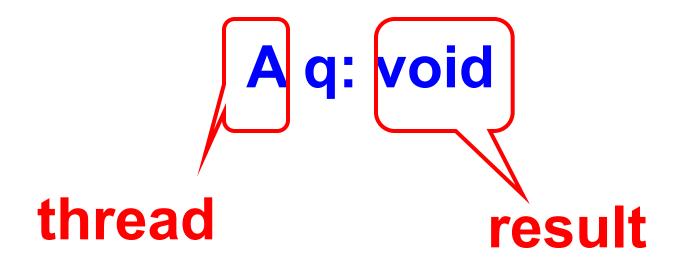


A q: void

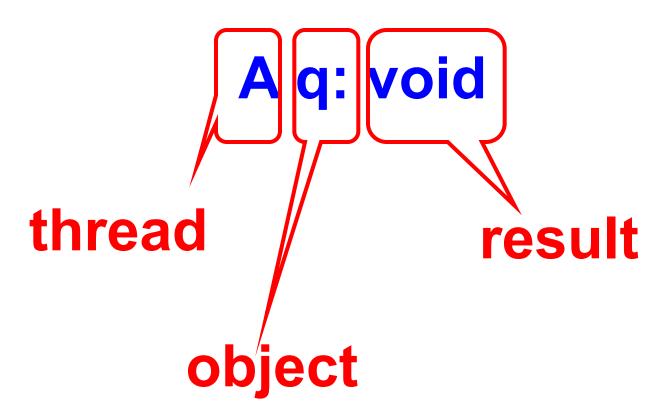




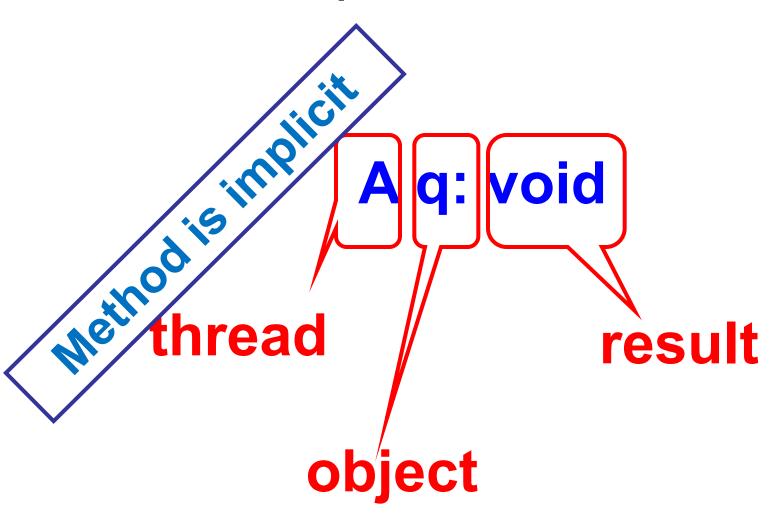




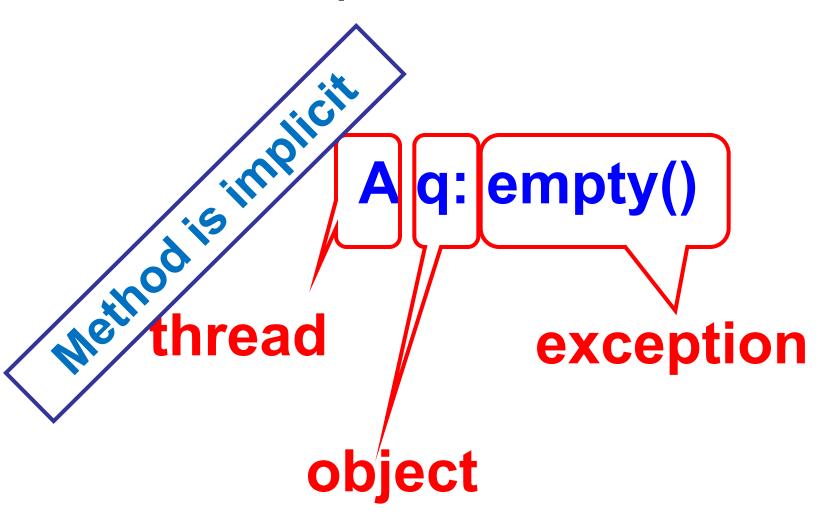














History - Describing an Execution

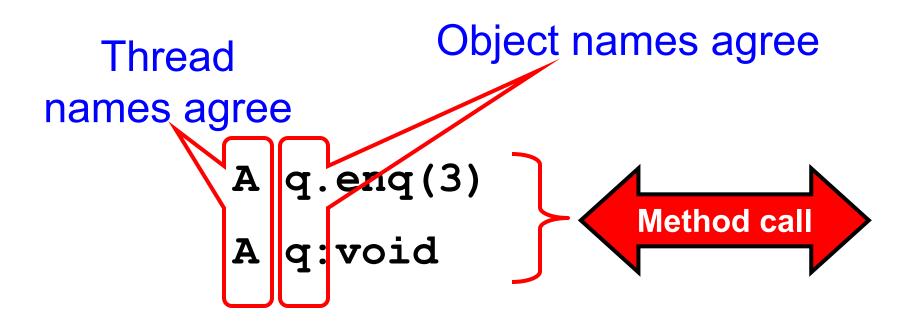
```
A q.enq(3)
A q:void
A q.enq(5)
H = B p.enq(4)
B p:void
B q.deq()
B q:3
```

Sequence of invocations and responses



Definition

Invocation & response match if





Object Projections

```
A q.enq(3)
A q:void
H = B p.enq(4)
B p:void
B q.deq()
B q:3
```



Object Projections

```
A q.enq(3)
```

A q:void

$$H|q =$$

B q.deq()

B q:3



Thread Projections

```
A q.enq(3)
A q:void
H = B p.enq(4)
B p:void
B q.deq()
B q:3
```



Thread Projections

```
H|B = B p.enq(4)
B p:void
B q.deq()
B q:3
```



```
A q.enq(3)
A q:void
A q.enq(5)
H = B p.enq(4)
B p:void
B q.deq() An invocation is pending if it has no matching respnse
```



```
A q.enq(3)
A q:void
A q.enq(5)
H = B p.enq(4)
B p:void
B q.deq() May or may not
B q:3 have taken effect
```



```
A q.enq(3)
A q:void
A q.enq(5)
H = B p.enq(4)
B p:void
B q.deq() discard pending
B q:3 invocations
```



```
A q.enq(3)
A q:void

Complete(H) = B p.enq(4)
B p:void
B q.deq()
B q:3
```



```
A q.enq(3)
A q:void
B p.enq(4)
B p:void
B q.deq()
B q:3
A q:enq(5)
```



```
match
A q.enq(3)
A q:void
B p.enq(4)
B p:void
B q.deq()
B q:3
A q:enq(5)
```

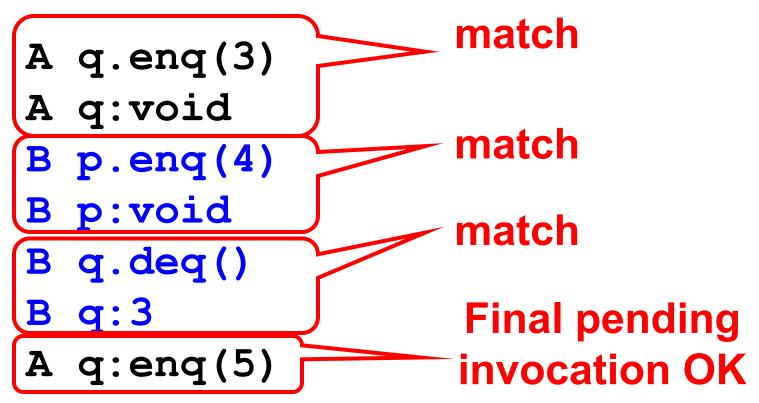


```
match
A q.enq(3)
 q:void
                  match
 p.enq(4)
  p:void
B q.deq()
 q:3
A q:enq(5)
```

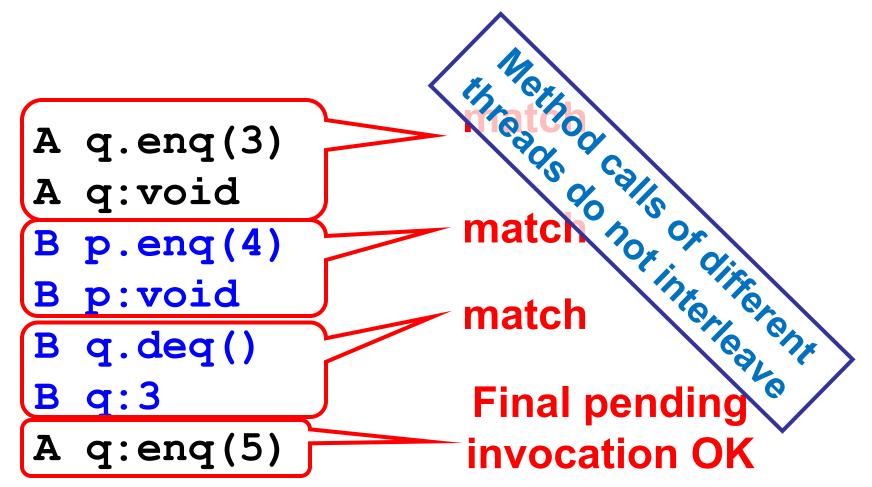


```
match
A q.enq(3)
 q:void
                   match
 p.enq(4)
  p:void
                   match
 q.deq()
A q:enq(5)
```











Well-Formed Histories

```
A q.enq(3)
B p.enq(4)
B p:void
B q.deq()
A q:void
B q:3
```



Well-Formed Histories

Per-thread projections sequential

```
A q.enq(3)
B p.enq(4)
B p:void
B q.deq()
A q:void
B q:3
```

```
B p.enq(4)
H|B= B p:void
B q.deq()
B q:3
```



Well-Formed Histories

Per-thread projections sequential

```
A q.enq(3)
```

B
$$p.enq(4)$$

$$H= B q.deq()$$



Equivalent Histories

```
Threads see the same H A = G A
thing in both H B = G B
```

```
A q.enq(3)
B p.enq(4)
```

```
A q.enq(3)
A q:void
B p.enq(4)
B p:void
B q.deq()
B q:3
```



Sequential Specifications

- A sequential specification is some way of telling whether a
 - Single-thread, single-object history
 - Is legal
- For example:
 - Pre and post-conditions
 - But plenty of other techniques exist ...



Legal Histories

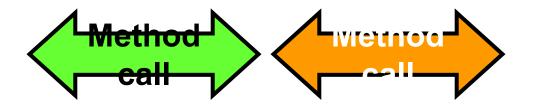
- A sequential (multi-object) history H is legal if
 - For every object x
 - H|x is in the sequential spec for x



Precedence

```
A q.enq(3)
B p.enq(4)
B p.void
A q:void
B q.deq()
B q:3
```

A method call precedes another if response event precedes invocation event

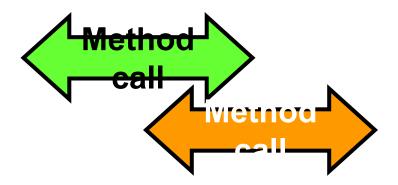




Non-Precedence

```
A q.enq(3)
B p.enq(4)
B p.void
B q.deq()
A q:void
B q:3
```

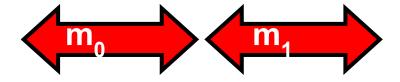
Some method calls overlap one another





Notation

- Given
 - History H
 - method executions m₀ and m₁ in H
- We say $m_0 \rightarrow_H m_1$, if
 - m₀ precedes m₁
- Relation $m_0 \rightarrow_H m_1$ is a



- Partial order
- Total order if H is sequential



Linearizability

- History H is *linearizable* if it can be extended to G by
 - Appending zero or more responses to pending invocations
 - Discarding other pending invocations
- So that G is equivalent to
 - Legal sequential history S
 - where $\rightarrow_{\mathbf{G}} \subset \rightarrow_{\mathbf{S}}$

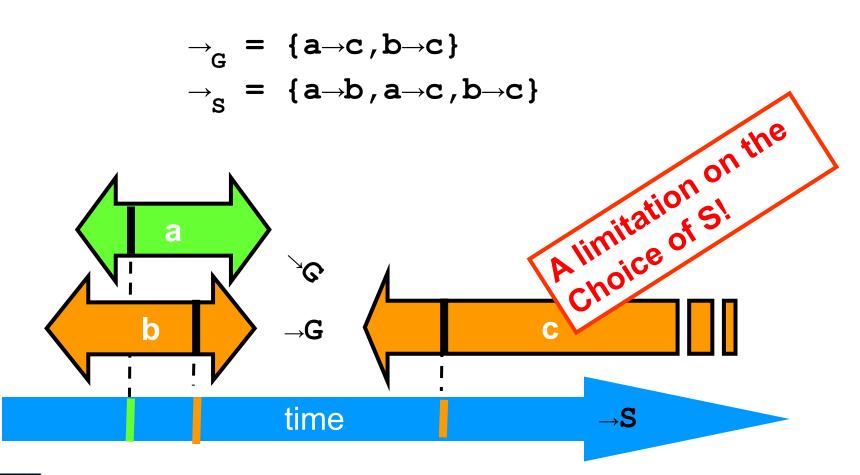


Remarks

- Some pending invocations
 - Took effect, so keep them
 - Discard the rest
- Condition $\rightarrow_{\mathbf{G}} \subset \rightarrow_{\mathbf{S}}$
 - Means that S respects "real-time order" of G

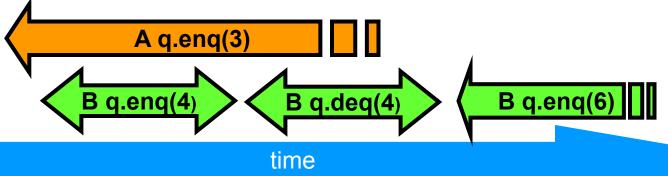


Ensuring $\rightarrow_{\mathbf{G}} \subset \rightarrow_{\mathbf{S}}$





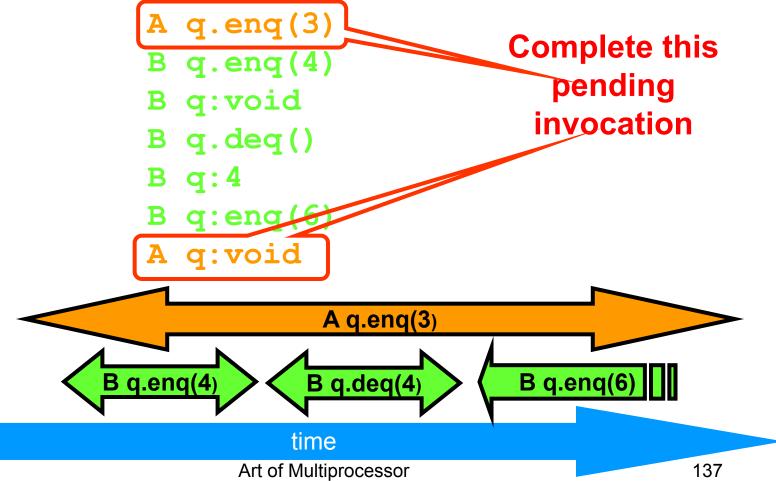
```
A q.enq(3)
B q.enq(4)
B q:void
B q.deq()
B q:4
B q:enq(6)
```



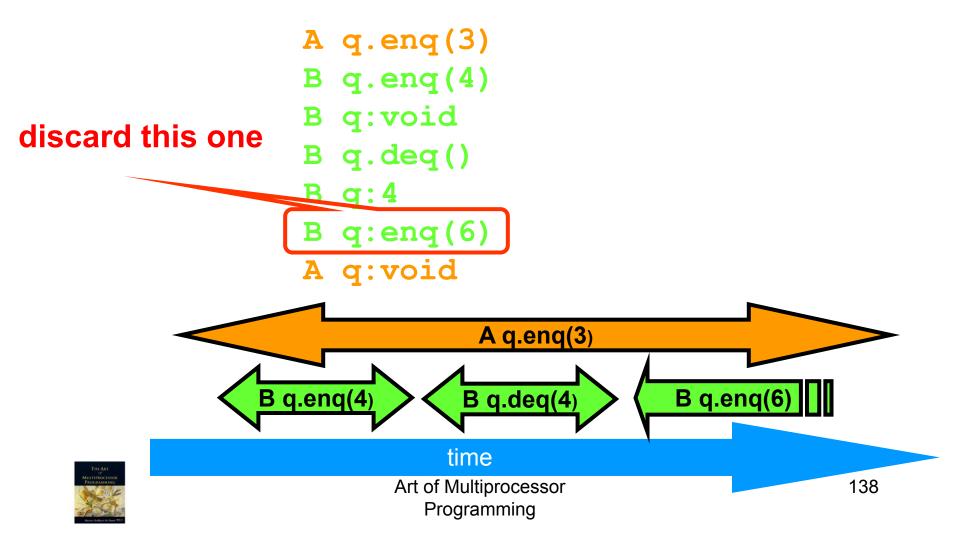


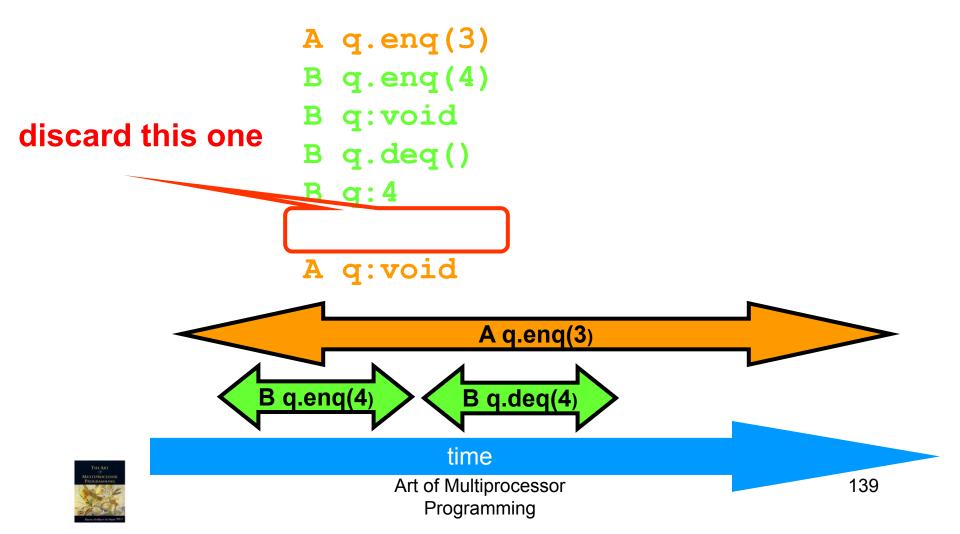
```
q.enq(3)
                              Complete this
      q.enq(4)
                                 pending
      q:void
                                invocation
   B q.deq()
   B q:4
   B q:enq(6)
  A q.enq(3)
B q.enq(4)
               B q.deq(3)
                               B q.enq(6)
              time
                                            136
          Art of Multiprocessor
```



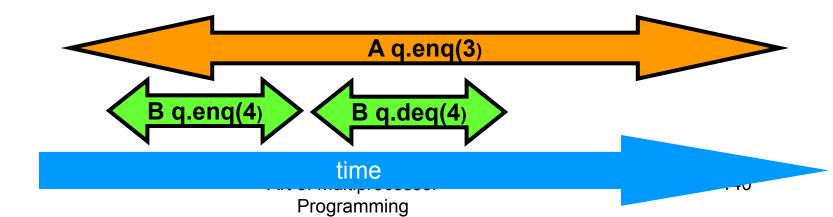






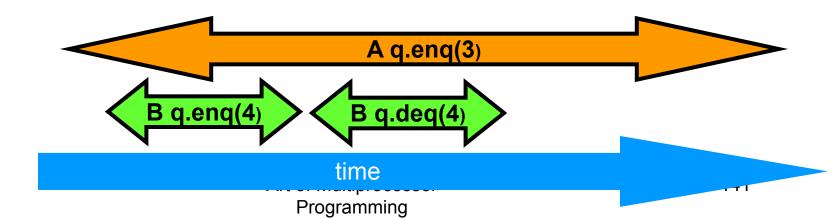


```
A q.enq(3)
B q.enq(4)
B q:void
B q.deq()
B q:4
A q:void
```





```
A q.enq(3)
B q.enq(4)
B q.enq(4)
B q:void
A q.enq(3)
B q.deq()
A q:void
B q:4
B q.deq()
A q:void
B q:4
B q:4
```





```
Equivalent sequential history
                          Bq.enq(4)
A q.enq(3)
Bq.enq(4)
                          B q:void
                          A q.enq(3)
 q:void
                          A q:void
B q.deq()
                          B q.deq()
B q:4
A q:void
                          B q:4
                     A q.enq(3)
                   B q. deq(4)
       B q.er q(4)
```

time

Programming



Concurrency

- How much concurrency does linearizability allow?
- When must a method invocation block?



Concurrency

- Focus on total methods
 - Defined in every state
- Example:
 - deq() that throws Empty exception
 - Versus deq() that waits ...
- Why?
 - Otherwise, blocking unrelated to synchronization



Concurrency

- Question: When does linearizability require a method invocation to block?
- Answer: never.
- Linearizability is non-blocking



Non-Blocking Theorem

If method invocation

```
A q.inv(...)
```

is pending in history H, then there exists a response

```
A q:res(...)
```

such that

```
H + A q:res(...)
```

is linearizable



Proof

- Pick linearization S of H
- If S already contains
 - Invocation A q.inv(...) and response,
 - Then we are done.
- Otherwise, pick a response such that
 - -S + A q.inv(...) + A q:res(...)
 - Possible because object is total.



Composability Theorem

- History H is linearizable if and only if
 - For every object x
 - H|x is linearizable
- We care about objects only!
 - (Materialism?)



Why Does Composability Matter?

- Modularity
- Can prove linearizability of objects in isolation
- Can compose independently-implemented objects



Reasoning About Linearizability: Locking

```
public T deq() throws EmptyException {
  lock.lock();
                                                    tail
                                         head
  try {
    if (tail == head)
                                     capacity-1
       throw new EmptyException();
    T x = items[head % items.length];
    head++;
    return x;
  } finally {
    lock.unlock();
```



Reasoning About Linearizability: Locking

```
public T deq() throws EmptyException {
  lock.lock();
                                                   tail
                                        head
  try {
    if (tail == head)
                                    capacity-1
       throw new EmptyException();
    T x = items[head % items.length]
    head++;
    return x;
    finally (
                            Linearization points
    lock.unlock();
                            are when locks are
                                  released
```



More Reasoning: Wait-free

```
public class WaitFreeQueue {
                                       head
                                                 tail
                                   capacity-1
  int head = 0, tail = 0;
  items = (T[]) new Object[capacity];
  public void enq(Item x) {
    if (tail-head == capacity) throw
         new FullException();
    items[tail % capacity] = x; tail++;
  public Item deq() {
     if (tail == head) throw
         new EmptyException();
     Item item = items[head % capacity]; head++;
     return item;
```

More Reasoning: Wait-free

```
public clas
                   tFreeQueue {
                           Linearization order is
and only one decillener
                           order head and tail
                              fields modified
                 enq(Item x) {
               -head == capacity) throw
           new FullException();
      tems[tail % capacity] = x;
   public Item deq() {
       if (tail == head) throw
           new EmptyException();
       Item item = items[head % capacity];
       return item;
                     Art of Multiprocessor
                                                    153
                       Programming
```

Strategy

- Identify one atomic step where method "happens"
 - Critical section
 - Machine instruction
- Doesn't always work
 - Might need to define several different steps for a given method



Linearizability: Summary

- Powerful specification tool for shared objects
- Allows us to capture the notion of objects being "atomic"
- Don't leave home without it



Alternative: Sequential Consistency

- History H is Sequentially Consistent if it can be extended to G by
 - Appending zero or more responses to pending invocations
 - Discarding other pending invocations
- So that G is equivalent to a
 - Legal sequential history S

Differs from linearizability

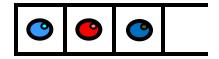




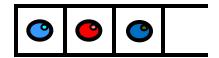
Sequential Consistency

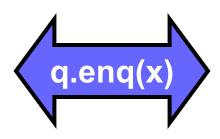
- No need to preserve real-time order
 - Cannot re-order operations done by the same thread
 - Can re-order non-overlapping operations done by different threads
- Often used to describe multiprocessor memory architectures



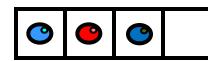


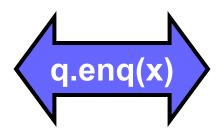


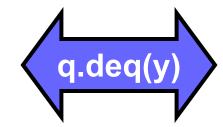






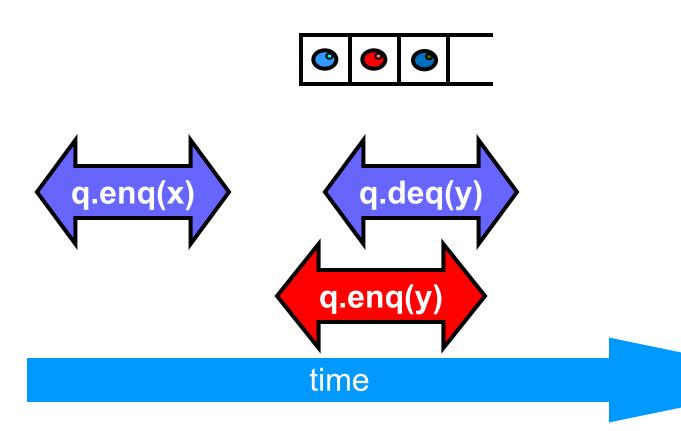






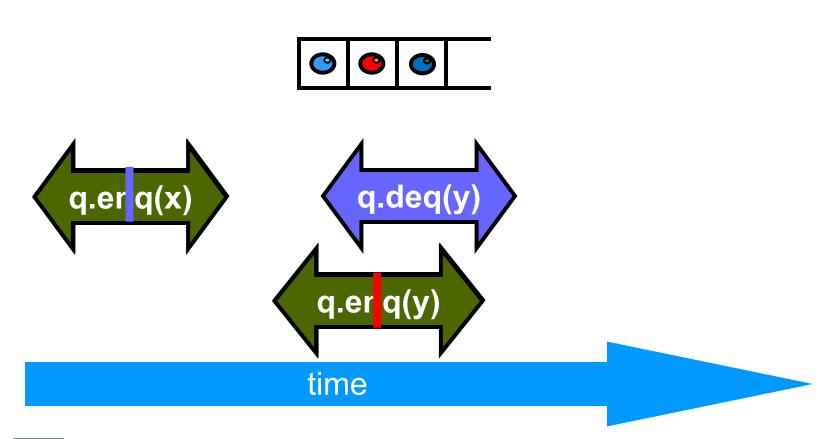






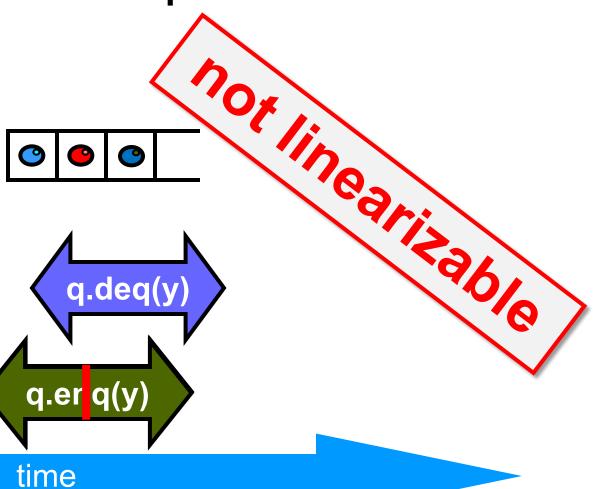






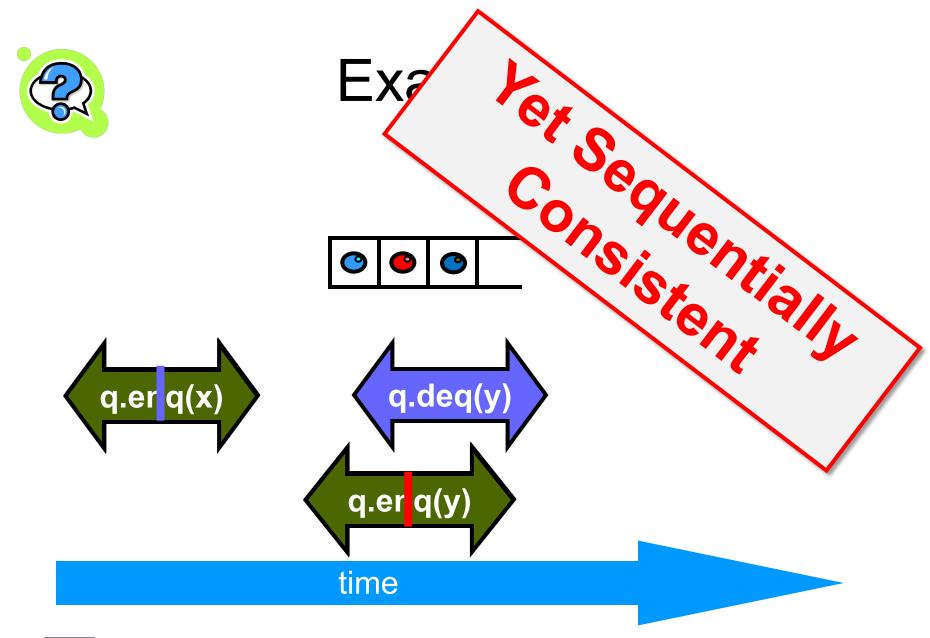








q.erq(x)



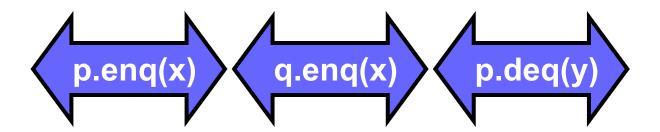


Theorem

Sequential Consistency is not composable

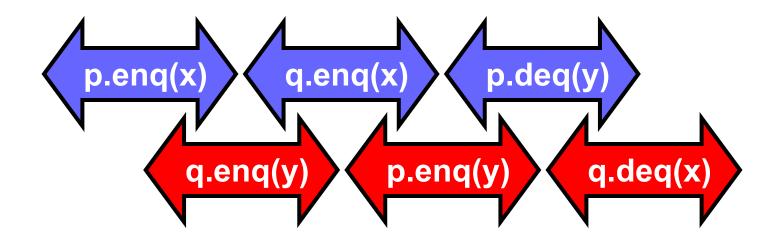


FIFO Queue Example



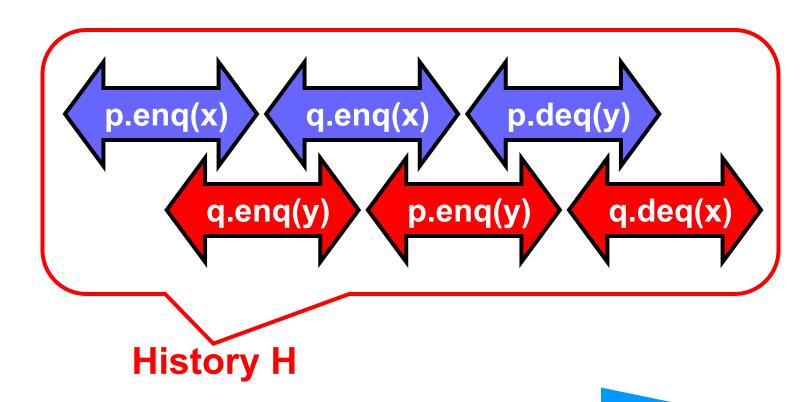


FIFO Queue Example



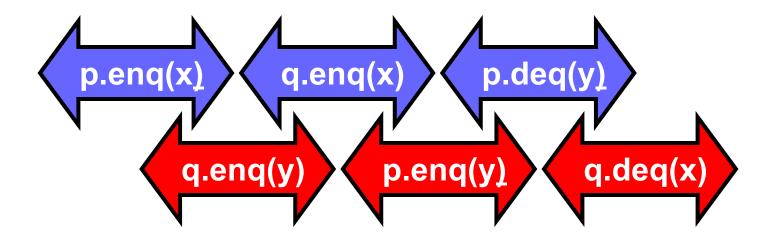


FIFO Queue Example



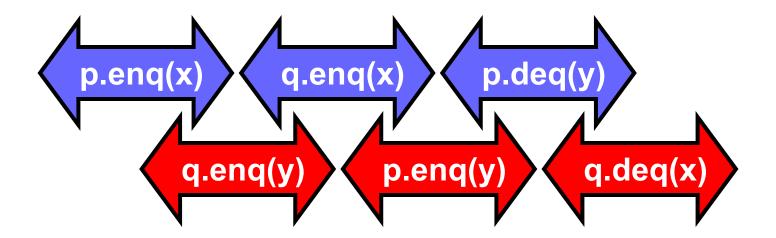


H|p Sequentially Consistent



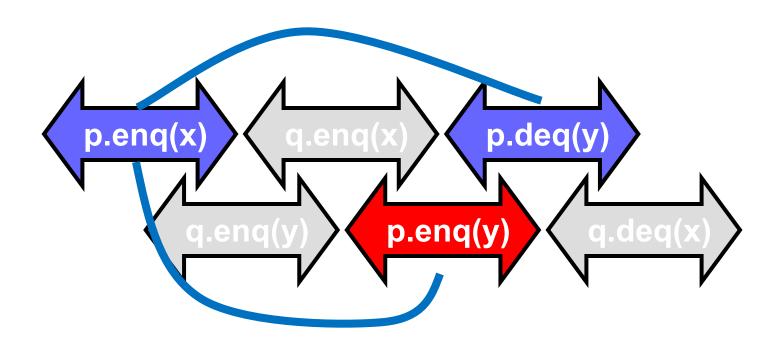


H|q Sequentially Consistent



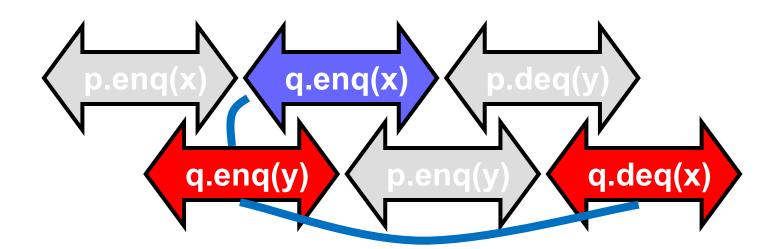


Ordering imposed by p



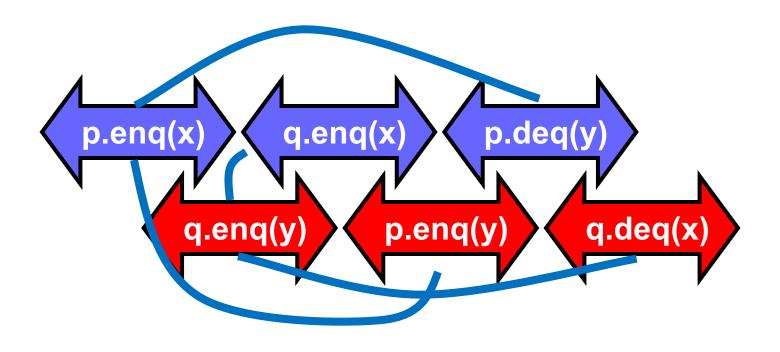


Ordering imposed by q



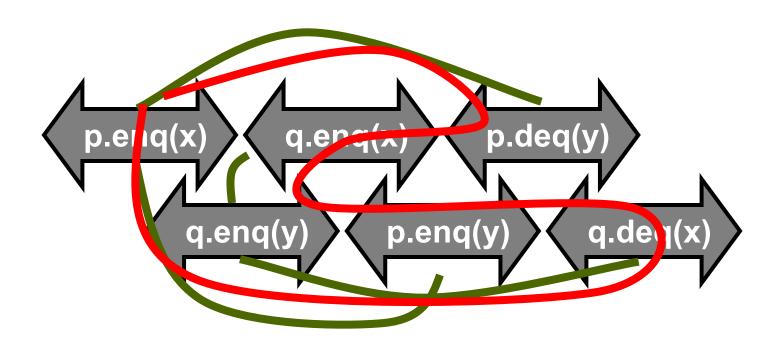


Ordering imposed by both





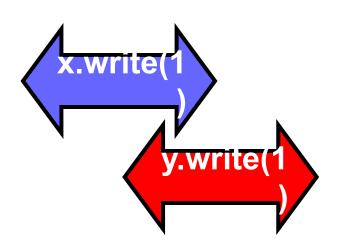
Combining orders

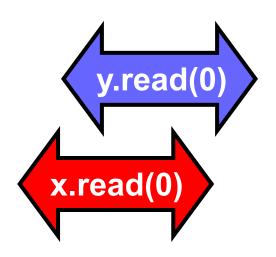


Fact

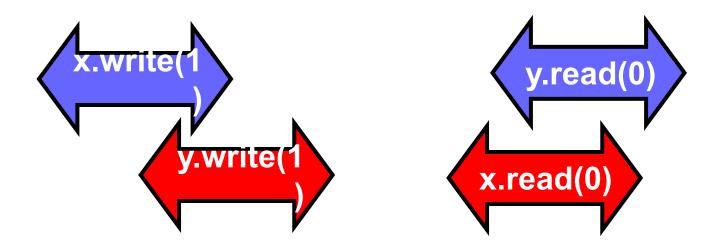
- Most hardware architectures don't support sequential consistency
- Because they think it's too strong
- Here's another story





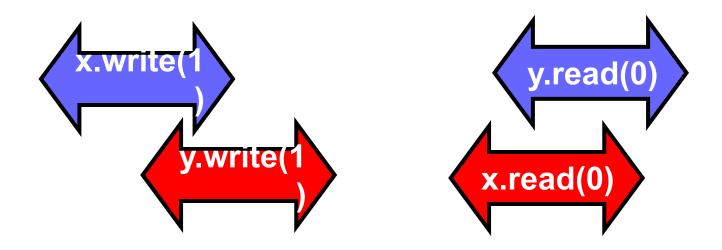






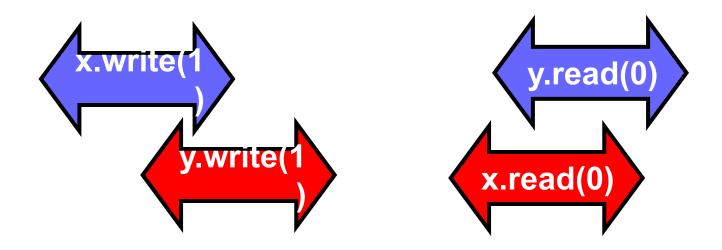
- Each thread's view is sequentially consistent
 - It went first





- Entire history isn't sequentially consistent
 - Can't both go first





- Is this behavior really so wrong?
 - We can argue either way ...



Opinion: It's Wrong

- This pattern
 - Write mine, read yours
- Is exactly the flag principle
 - Beloved of Alice and Bob
 - Heart of mutual exclusion
 - Peterson
 - · Bakery, etc.
- It's non-negotiable!



Peterson's Algorithm

```
public void lock() {
  flag[i] = true;
  victim = i;
  while (flag[j] && victim == i) {};
}
public void unlock() {
  flag[i] = false;
}
```

Crux of Peterson Proof

- (1) write_B(flag[B]=true) \rightarrow
- (3) write_B(victim=B) \rightarrow
- (2) write_A(victim=A) \rightarrow read_A(flag[B]) \rightarrow read_A(victim)

Crux of Peterson Proof

```
    (1) write<sub>B</sub>(flag[B]=true)→
    (3) write<sub>B</sub>(victim=B)→
    (2) write<sub>A</sub>(victim=A)—read<sub>A</sub>(flag[B]) → read<sub>A</sub>(victim)
```

Observation: proof relied on fact that if a location is stored, a later load by some thread will return this or a later stored value.

Opinion: But It Feels So Right ...

- Many hardware architects think that sequential consistency is too strong
- Too expensive to implement in modern hardware
- OK if flag principle
 - violated by default
 - Honored by explicit request



Hardware Consistancy

Initially, a = b = 0.

Processor O

mov 1, a ;Store mov b, %ebx ;Load

Processor 1

mov 1, b ;Store mov a, %eax ;Load

What are the final possible values of %eax and %ebx after both processors have executed?

Sequential consistency implies that no execution ends with %eax= %ebx = 0

Hardware Consistency

- No modern-day processor implements sequential consistency.
- Hardware actively reorders instructions.
- Compilers may reorder instructions, too.
- Why?
- Because most of performance is derived from a single thread's unsynchronized execution of code.

Instruction Reordering

```
mov 1, a ;Store mov b, %ebx ;Load mov 1, a ;Store
```

Program Order

Execution Order

- Q. Why might the hardware or compiler decide to reorder these instructions?
- A. To obtain higher performance by covering load latency *instruction-level* parallelism.

Slide used with permission of Charles E. Leiserson

Instruction Reordering

mov 1, a ;Store mov b, %ebx ;Load

mov b, %ebx ;Load mov 1, a ;Store

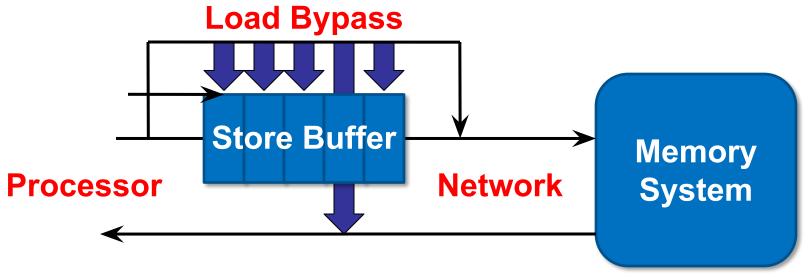
Program Order

Execution Order

- Q. When is it safe for the hardware or compiler to perform this reordering?
- A. When $a \neq b$.
- A'. And there's no concurrency.

Slide used with permission of Charles E. Leiserson

Hardware Reordering



- Processor can issue stores faster than the network can handle them ⇒ store buffer.
- Loads take priority, bypassing the store buffer.
- Except if a load address matches an address in the store buffer, the store buffer returns the result.

X86: Memory Consistency

Thread's Code



- Loads are not reordered with loads.
- 2. Stores are *not* reordered with stores.
- 3. Stores are *not* reordered with prior loads.
- 4. A load *may* be reordered with a prior store to a different location but *not* with a prior store to the same location.
- 5. Stores to the same location respect a global total order.

X86: Memory Consistency

Threa d's

Code Stor Stor **E**oa dda **Stor** 9Bor **E6a** d₃a dda

- Loads are *not* reordered with loads.
- 2. Stores are not reordered with stores.
- 3. **Total Store Ordering** r (TSO)...weaker than rior
- 4. sequential consistency

mur a prior store to the same location.

Stores to the same location respect a OK! global total order.

D

Memory Barriers (Fences)

- A memory barrier (or memory fence) is a hardware action that enforces an ordering constraint between the instructions before and after the fence.
- A memory barrier can be issued explicitly as an instruction (x86: mfence)
- The typical cost of a memory fence is comparable to that of an L2-cache access.

X86: Memory Consistency

Threa d's

```
Code
Stor
9 dor
Eoa
ddad
2tor
geor
Barrier
Loa
d<sub>3</sub>a
d<del>d</del>a
```

- 1. Loads are *not* reordered with loads.
- 2. Sto Total Store Ordering +
- 3. Sto properly placed memory barriers = sequential
 - A lo consistency

location.

5. Stores to the same location respect a global total order.

Memory Barriers

- Explicit Synchronization
- Memory barrier will
 - Flush write buffer
 - Bring caches up to date
- Compilers often do this for you
 - Entering and leaving critical sections



Volatile Variables

- In Java, can ask compiler to keep a variable up-to-date by declaring it volatile
- Adds a memory barrier after each store
- Inhibits reordering, removing from loops, & other "compiler optimizations"
- Will talk about it in detail in later lectures



Summary: Real-World

- Hardware weaker than sequential consistency
- Can get sequential consistency at a price
- Linearizability better fit for high-level software



Linearizability

- Linearizability
 - Operation takes effect instantaneously between invocation and response
 - Uses sequential specification, locality implies composablity



Summary: Correctness

- Sequential Consistency
 - Not composable
 - Harder to work with
 - Good way to think about hardware models
- We will use linearizability as our consistency condition in the remainder of this course unless stated otherwise



Progress

- We saw an implementation whose methods were lock-based (deadlock-free)
- We saw an implementation whose methods did not use locks (lock-free)
- How do they relate?



Progress Conditions

- Deadlock-free: some thread trying to acquire the lock eventually succeeds.
- Starvation-free: every thread trying to acquire the lock eventually succeeds.
- Lock-free: some thread calling a method eventually returns.
- Wait-free: every thread calling a method eventually returns.



Progress Conditions

Non-Blocking

Blocking

Everyone makes progress

Someone makes progress

Wait-free	Starvation-free
Lock-free	Deadlock-free



Summary

 We will look at *linearizable blocking* and non-blocking implementations of objects.





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