Concurrent programming

Mutual Exclusion

Companion slides for
The Art of Multiprocessor Programming
by Maurice Herlihy, Nir Shavit, Victor Luchangco,
and Michael Spear

Modified by Piotr Witkowski



- We will clarify our understanding of mutual exclusion
- We will also show you how to reason about various properties in an asynchronous concurrent setting



In his 1965 paper E. W. Dijkstra wrote:

"Given in this paper is a solution to a problem which, to the knowledge of the author, has been an open question since at least 1962, irrespective of the solvability. [...] Although the setting of the problem might seem somewhat academic at first, the author trusts that anyone familiar with the logical problems that arise in computer coupling will appreciate the significance of the fact that this problem indeed can be solved."



- Formal problem definitions
- Solutions for 2 threads
- Solutions for n threads
- Fair solutions
- Inherent costs

Warning

- You will never use these protocols
 - Get over it
- You are advised to understand them
 - The same issues show up everywhere
 - Except hidden and more complex

Why is Concurrent Programming so Hard?

- Try preparing a seven-course banquet
 - By yourself
 - With one friend
 - With twenty-seven friends …
- Before we can talk about programs
 - Need a language
 - Describing time and concurrency

Time

 "Absolute, true and mathematical time, of itself and from its own nature, flows equably without relation to anything external." (Isaac Newton, 1689)

 "Time is what keeps everything from happening at once." (Ray Cummings, 1922)

time

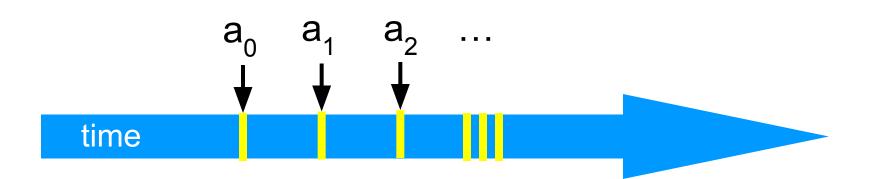
Events

- An event a₀ of thread A is
 - Instantaneous
 - No simultaneous events (break ties)



Threads

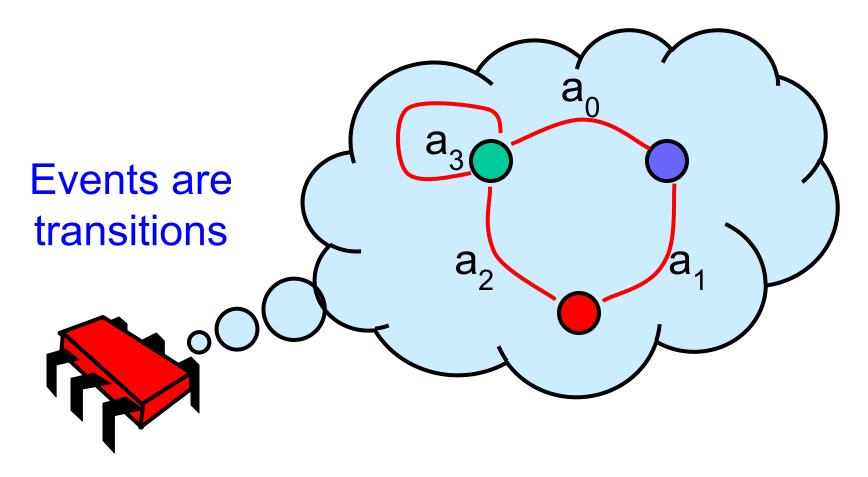
- A thread A is (formally) a sequence a₀,
 a₁, ... of events
 - "Trace" model
 - Notation: a₀ → a₁ indicates order



Example Thread Events

- Assign to shared variable
- Assign to local variable
- Invoke method
- Return from method
- Lots of other things

Threads are State Machines



States

- Thread State
 - Program counter
 - Local variables
- System state
 - Object fields (shared variables)
 - Union of thread states

Concurrency

Thread A

time

Concurrency

Thread AtimeThread Btime

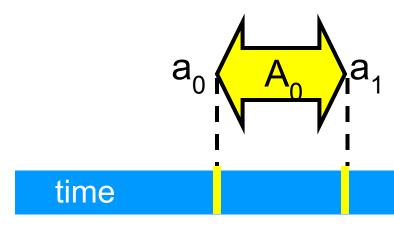
Interleavings

- Events of two or more threads
 - Interleaved
 - Not necessarily independent (why?)

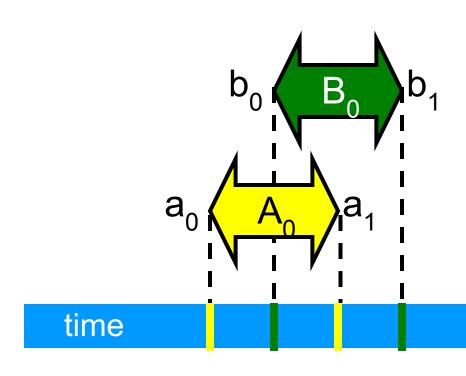
time

Intervals

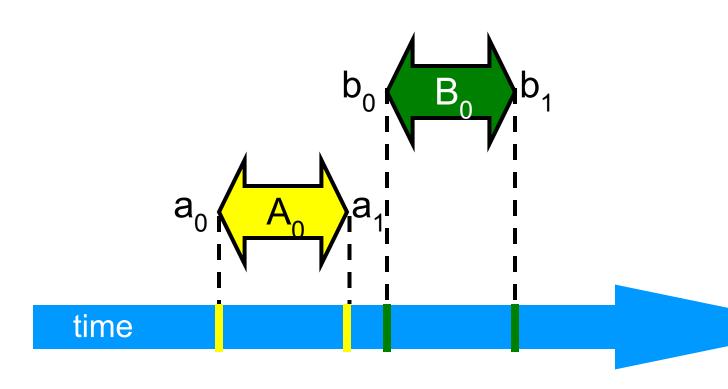
- An interval $A_0 = (a_0, a_1)$ is
 - Time between events a₀ and a₁



Intervals may Overlap

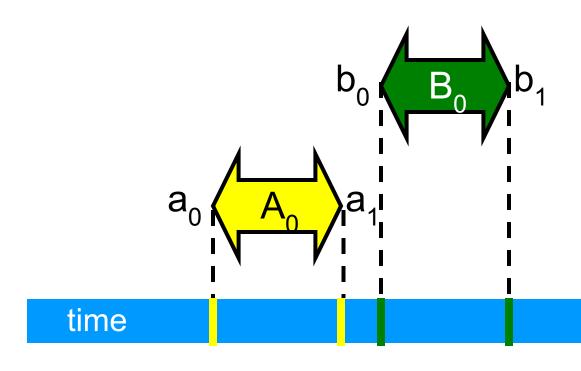


Intervals may be Disjoint

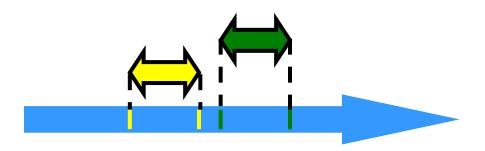


Precedence

Interval A₀ precedes interval B₀

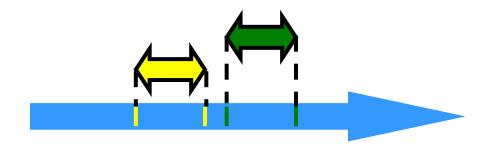


Precedence



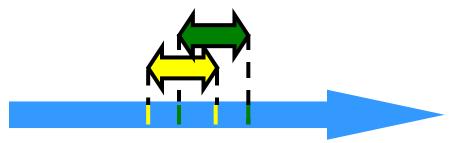
- Notation: A₀ → B₀
- Formally,
 - End event of A₀ before start event of B₀
 - Also called "happens before" or "precedes"

Precedence Ordering



- Remark: A₀ → B₀ is just like saying
 - $-1066 AD \rightarrow 1492 AD$
 - Middle Ages → Renaissance,
- Oh wait,
 - what about this week vs this month?

Precedence Ordering



- Never true that A → A
- If A → B then not true that B → A
- If $A \rightarrow B \& B \rightarrow C$ then $A \rightarrow C$
- Funny thing: A →B & B →A might both be false!

Partial Orders

(review)

- Irreflexive:
 - Never true that A → A
- Antisymmetric:
 - If A→ B then not true that B → A
- Transitive:
 - If $A \rightarrow B \& B \rightarrow C$ then $A \rightarrow C$

Total Orders

(review)

- Also
 - Irreflexive
 - Antisymmetric
 - Transitive
- Except that for every distinct A, B,
 - Either $A \rightarrow B$ or $B \rightarrow A$

Repeated Events

```
while (mumble) {
   a<sub>0</sub>; a<sub>1</sub>;
                                 k-th occurrence of
                                         event a<sub>n</sub>
                              k-th occurrence of
                              interval A_0 = (a_0, a_1)
                        Art of Multiprocessor
                                                            25
                          Programming
```

Implementing a Counter

```
public class Counter {
   private long value;

public long getAndIncrement() {
    temp = value;
   value = temp + 1;
    return temp;
}

Make these steps
indivisible using locks
```

Locks (Mutual Exclusion)

```
public interface Lock {
  public void lock();
  public void unlock();
}
```

Locks (Mutual Exclusion)

```
public interface Lock {

public void lock();

public void unlock();
}
```

Locks (Mutual Exclusion)

```
public interface Lock {

public void lock();

public void unlock();

release lock
```

```
public class Counter {
  private long value;
  private Lock lock;
  public long getAndIncrement() {
   lock.lock();
   try {
    int temp = value;
    value = value + 1;
   } finally {
     lock.unlock();
   return temp;
  } }
```

```
public class Counter {
  private long value;
  private Lock lock;
  public long getAndIncrement() {
   lock.lock();
                               acquire Lock
    int temp = value;
    value = value + 1;
   } finally {
     lock.unlock();
   return temp;
  }}
```

```
public class Counter {
  private long value;
  private Lock lock;
  public long getAndIncrement() {
   lock.lock();
   try {
    int temp = value;
    value = value + 1;
     finally {
                               Release lock
     lock.unlock();
                             (no matter what)
   return temp;
```

```
public class Counter {
  private long value;
  private Lock lock;
  public long getAndIncrement() {
   lock.lock();
   try {
    int temp = value;
                                          critical section
    value = value + 1;
     lock.unlock();
   return temp;
  } }
```

Let CS_i^k be thread i's k-th critical section execution

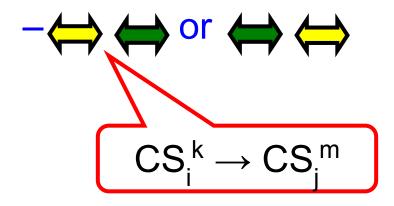
- Let CS_i^k be thread i's k-th critical section execution
- And CS_j^m be thread j's m-th critical section execution

- Let CS_i^k be thread i's k-th critical section execution
- And CS_i^m be j's m-th execution
- Then either



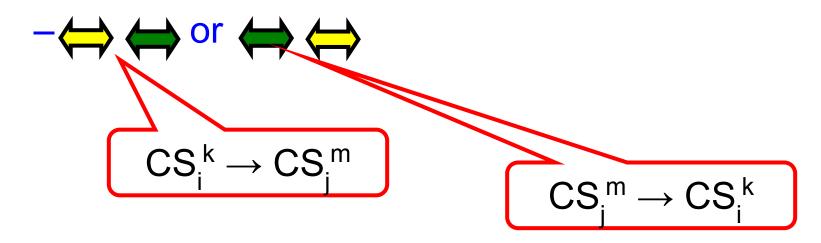
Mutual Exclusion

- Let CS_i^k be thread i's k-th critical section execution
- And CS_i^m be j's m-th execution
- Then either



Mutual Exclusion

- Let CS_i^k be thread i's k-th critical section execution
- And CS_i^m be j's m-th execution
- Then either



Deadlock-Free



- If some thread calls lock()
 - And never returns
 - Then other threads must complete lock()
 and unlock() calls infinitely often
- System as a whole makes progress
 - Even if individuals starve

Starvation-Free



- If some thread calls lock()
 - It will eventually return
- Individual threads make progress

Two-Thread vs *n*-Thread Solutions

- 2-thread solutions first
 - Illustrate most basic ideas
 - Fits on one slide
- Then n-thread solutions

Two-Thread Conventions

```
class ... implements Lock {
    ...
    // thread-local index, 0 or 1
    public void lock() {
        int i = ThreadID.get();
        int j = 1 - i;
    ...
    }
}
```

Two-Thread Conventions

```
class ... implements Lock {
    ...
    // thread-local index, 0 or 1
    public void lock() {
        int i = ThreadID.get();
        int j = 1 - i;
        ...
    }
}
```

Henceforth: i is current thread, j is other thread

```
class LockOne implements Lock {
  private boolean[] flag = new boolean[2];
  public void lock() {
    flag[i] = true;
    while (flag[j]) {}
}
```

```
class LockOne implements Lock {
private boolean[] flag = new boolean[2];
public void lock() {
  flag[i] = true;
  while (flag[j]) {}
}
Each thread has flag
```

```
class LockOne implements Lock {
  private boolean[] flag = new boolean[2];
  public void lock() {
    flag[i] = true;
    while (flag[j]) {}
    Set my flag
}
```

```
class LockOne implements Lock {
private boolean[] flag = new boolean[2];
public void lock() {
  flag[i] = true;
  while (flag[j]) {}
}
```

Wait for other flag to become false

LockOne Satisfies Mutual Exclusion

- Assume CS_A^j overlaps CS_B^k
- Consider each thread's last
 - $-(j^{th} \text{ and } k^{th}) \text{ read and write } \dots$
 - in lock() before entering
- Derive a contradiction

From the Code

write_A(flag[A]=true) →
 read_A(flag[B]==false) →CS_A

write_B(flag[B]=true) → read_B(flag[A]==false) → CS_B

```
class LockOne implements Lock {
    ...
public void lock() {
    flag[i] = true;
    while (flag[j]) {}
}
```

From the Assumption

read_A(flag[B]==false) →
 write_B(flag[B]=true)

read_B(flag[A]==false) →
 write_A(flag[A]=true)

Assumptions:

- read_∆(flag[B]==false) → write_B(flag[B]=true)
- read_B(flag[A]==false) → write_A(flag[A]=true)

From the code

- write_∆(flag[A]=true) → read_∆(flag[B]==false)
- $write_B(flag[B]=true) \rightarrow read_B(flag[A]==false)$

- Assumptions:
 - read_∆(flag[B]==false) → write_B(flag[B]=true)
 - read_B(flag[A]==false) → write_A(flag[A]=true)
- From the code

 - write $_{A}(flag[A]=true) \rightarrow read_{A}(flag[B]==false)$ write $_{B}(flag[B]=true) \rightarrow read_{B}(flag[A]==false)$

- Assumptions:
 - read_∆(flag[B]==false) → write_B(flag[B]=true)
 - _read_B(flag[A]==false) → write_A(flag[A]=true)
- From the code
 - $write_{A}(flag[A]=true) \rightarrow read_{A}(flag[B]==false)$
 - write_B(flag[B]=true) → read_B(flag[A]==false)

Assumptions:

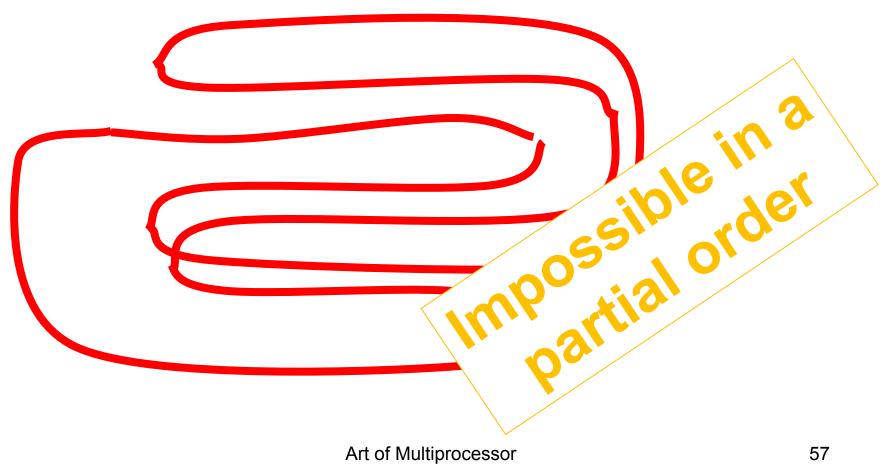
```
    read<sub>A</sub>(flag[B]==false) → write<sub>B</sub>(flag[B]=true)
    read<sub>B</sub>(flag[A]==false) → write<sub>A</sub>(flag[A]=true)
    From the code
    write<sub>A</sub>(flag[A]=true) → read<sub>A</sub>(flag[B]==false)
    write<sub>B</sub>(flag[B]=true) → read<sub>B</sub>(flag[A]==false)
```

```
    read<sub>∆</sub>(flag[B]==false) → write<sub>B</sub>(flag[B]=true)

   _ read<sub>B</sub>(flag[A]==false) → write<sub>A</sub>(fla<mark>g A</mark>]=true)
• From the code • • •
     – write<sub>Δ</sub>(flag[A]=true) → read<sub>Δ</sub>(flag[B]==false)
     – write<sub>B</sub>(flag[B]=true) → read<sub>B</sub>(flag[A]==false)
```

- Assumptions.
 - read_(flag[B]==false) write_g(flag[B]=true)
 - _ read_p(flag[A]==false) → write_A(flag A]=true)
- From the code
 - write_A(flag[A]=true) → read_A(flag[F]==false)
 - write_B(flag[B]=true) → read_B(flag[A]==false)

Cycle!



Programming

Deadlock Freedom

- LockOne Fails deadlock-freedom
 - Concurrent execution can deadlock

```
flag[i] = true; flag[j] = true;
while (flag[j]){} while (flag[i]){}
```

Sequential executions OK

```
public class LockTwo implements Lock {
  private int victim;
  public void lock() {
    victim = i;
    while (victim == i) {};
  }
  public void unlock() {}
}
```

```
public class LockTwo implements Lock {
  private int victim;
  public void lock() {
    victim = i;
    while (victim == i) {};

  public void unlock() {}
}
```

```
public class Lock2 implements Lock {
  private int victim;
  public void lock() {
    victim = i;
    while (victim == i) {};
  }

public void unlock() {}
```

LockTwo Claims

- Satisfies mutual exclusion
 - If thread i in CS
 - Then victim == j
 - Cannot be both 0 and 1
- Not deadlock free
 - Sequential execution deadlocks
 - Concurrent execution does not

```
public void LockTwo() {
  victim = i;
  while (victim == i) {};
}
```

```
public void lock() {
  flag[i] = true;
  victim = i;
  while (flag[j] && victim == i) {};
}
public void unlock() {
  flag[i] = false;
}
```

Announce I'm

```
public void lock() {
  flag[i] = true;
  victim = i;
  while (flag[j] && victim == i) {};
}
public void unlock() {
  flag[i] = false;
}
```

```
Announce I'm
                           interested
public void loc
 flag[i] = true;
                           Defer to other
 victim = i;
 while (flag[j] && victim == i) {};
public void unlock() {
 flag[i] = false;
```

```
Announce I'm
                            interested
 flag[i]
         = true;
                             Defer to other
 victim
while (flag[j] && victim == i)
public void unlock()
                         Wait while other
 flag[i] = false;
                         interested & I'm
                            the victim
```

```
Announce I'm
                            interested
 flag[i]
           true;
                             Defer to other
 victim
while (flag[j] && victim == i)
public void unlock()
                         Wait while other
 flag[i] = false;
                         interested & I'm
          No longer
                            the victim
          interested
```

Mutual Exclusion

(1) write_B(Flag[B]=true) \rightarrow write_B(victim=B)

```
public void lock() {
  flag[i] = true;
  victim = i;
  while (flag[j] && victim == i) {};
}
```

From the Code

Also from the Code

(2) write_A(victim=A) \rightarrow read_A(flag[B]) \rightarrow read_A(victim)

```
public void lock() {
  flag[i] = true:
  victim = i;
  while (flag[j] && victim == i) {};
}
```

Assumption

(3) write_B(victim=B) \rightarrow write_A(victim=A)

W.L.O.G. assume A is the last thread to write **victim**

Combining Observations

- (1) write_B(flag[B]=true) \rightarrow write_B(victim=B)
- (3) write_B(victim=B) \rightarrow write_A(victim=A)
- (2) write_A(victim=A) \rightarrow read_A(flag[B]) \rightarrow read_A(victim)

Combining Observations

- (1) write_B(flag[B]=true) \rightarrow
- (3) write_B(victim=B) \rightarrow
- (2) write_A(victim=A) \rightarrow read_A(flag[B]) \rightarrow read_A(victim)

Combining Observations

```
(1) write<sub>B</sub>(flag[B]=true)→
(3) write<sub>B</sub>(victim=B)\rightarrow
(2) write (victim = A) \rightarrow read_{\Delta}(flag[B])
     → read<sub>Δ</sub>(victim)
           A read flag[B] == true and victim == A, so it
```

could not have entered the CS (QED)

Deadlock Free

```
public void lock() {
    ...
    while (flag[j] && victim == i) {};
```

- Thread blocked
 - only at while loop
 - only if other's flag is true
 - only if it is the victim
- Solo: other's flag is false
- Both: one or the other not the victim

Starvation Free

 Thread i blocked only if j repeatedly re-enters so that

```
flag[j] == true and
victim == i
```

- When j re-enters
 - it sets victim to j.
 - So i gets in

```
public void lock() {
   flag[i] = true;
   victim = i;
   while (flag[j] && victim == i) {};
}

public void unlock() {
   flag[i] = false;
}
```

Bounded Waiting

- Want stronger fairness guarantees
- Thread not "overtaken" too much
- If A starts before B, then A enters before B?
- But what does "start" mean?
- Need to adjust definitions

Bounded Waiting

- Divide lock() method into 2 parts:
 - Doorway interval:
 - Written D_A
 - always finishes in finite steps
 - Waiting interval:
 - Written W_A
 - may take unbounded steps

r-Bounded Waiting

For threads A and B:

$$-\text{ If }D_{A}^{k} \to D_{B}^{j}$$

- A's k-th doorway precedes B's j-th doorway
- Then $CS_A^k \rightarrow CS_B^{j+r}$
 - A's k-th critical section precedes B's j+r-th critical section
 - B cannot overtake A more than r times
- First-come-first-served → r = 0

What is "r" for Peterson's Algorithm?

```
public void lock() {
  flag[i] = true;
  victim = i;
  while (flag[j] && victim == i) {};
}
public void unlock() {
  flag[i] = false;
}
```

Answer: r = 0

First-Come-First-Served

For threads A and B:

$$- \text{ If } D_A^{k} \rightarrow D_B^{j}$$

A's k-th doorway precedes B's j-th doorway

$$- \ Then \ CS_A^{\ k} \rightarrow CS_B^{\ j}$$

- A's k-th critical section precedes B's j-th critical section
- B cannot overtake A

- Provides First-Come-First-Served for n threads
- How?
 - Take a "number"
 - Wait until lower numbers have been served
- Lexicographic order
 - -(a,i) > (b,j)
 - If a > b, or a = b and i > j

```
class Bakery implements Lock {
  boolean[] flag;
   Label[] label;
 public Bakery (int n) {
    flag = new boolean[n];
    label = new Label[n];
    for (int i = 0; i < n; i++) {
       flag[i] = false; label[i] = 0;
```

```
class Bakery implements Lock {
  boolean[] flag;
   Label[] label;
                             0
 public Bakery (int n)
    flag = new boolean[n];
    label = new Label[n];
    for (int i = 0; i < n; i++)
       flag[i] = false; label[i]
```

```
class Bakery implements Lock {
    ...

public void lock! {
    flag[i] = true;
    label[i] = max(label[0], ..., label[n-1])+1;
    while ( label[i], i) > (label[k], k));
}
```

Take increasing

... whose (label,i) in lexicographic order is lower

```
class Bakery implements Lock {
    ...

public void unlock() {
    flag[i] = false;
}
}
```

```
class Bakery implements Lock {
    No longer interested

public void unlock {
    flag[i] = false;
}

labels are always increasing
```

No Deadlock

- There is always one thread with earliest label
- Ties are impossible (why?)

First-Come-First-Served

- If $D_{\Delta} \rightarrow D_{R}$ then
 - A's label is smaller
- And:
 - write_A(label[A]) →
 - read_R(label[A]) →
 - write_B(label[B]) → read_B(flag[A])
- So B sees
 - smaller label for A
 - locked out while flag[A] is true

- Suppose A and B in CS together
- Suppose A has earlier label
- When B entered, it must have seen
 - flag[A] is false, or
 - label[A] > label[B]

- Labels are strictly increasing so
- B must have seen flag[A] == false

- Labels are strictly increasing so
- B must have seen flag[A] == false
- Labeling_B → read_B(flag[A]) → write_A(flag[A]) → Labeling_A

- Labels are strictly increasing so
- B must have seen flag[A] == false
- Labeling_B → read_B(flag[A]) → write_A(flag[A]) → Labeling_A
- Which contradicts the assumption that A has an earlier label

Bakery Y2³²K Bug

Bakery Y2³²K Bug

Does Overflow Actually Matter?

- Yes
 - Y2K
 - 18 January 2038 (Unix time_t rollover)
 - 16-bit counters
- No
 - 64-bit counters
- Maybe
 - 32-bit counters

Deep Philosophical Question

- The Bakery Algorithm is
 - Succinct,
 - Elegant, and
 - Fair.
- Q: So why isn't it practical?
- A: Well, you have to read N distinct variables

Shared Memory

- Shared read/write memory locations called Registers (historical reasons)
- Come in different flavors
 - Multi-Reader-Single-Writer (flag[])
 - Multi-Reader-Multi-Writer (victim[])
 - Not that interesting: SRMW and SRSW

Theorem

At least N MRSW (multi-reader/single-writer) registers are needed to solve deadlock-free mutual exclusion.

N registers such as flag[]...

Summary of Lecture

- In the 1960's several incorrect solutions to starvation-free mutual exclusion using RW-registers were published...
- Today we know how to solve FIFO N thread mutual exclusion using 2N RW-Registers

Summary of Lecture

- N RW-Registers inefficient
 - But mathematically required ...
- Need stronger hardware operations
 - that do not have the "covering problem"
- In later lectures understand what these operations are...



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