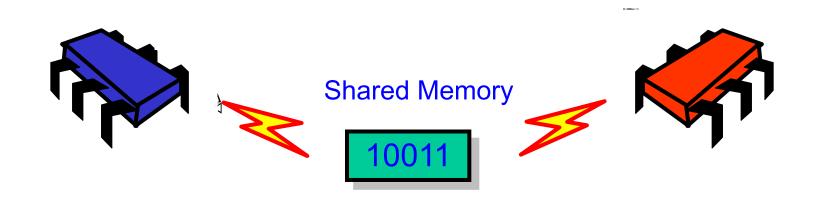
Concurrent programming The Relative Power of Synchronization Operations

Companion slides for
The Art of Multiprocessor Programming
by Maurice Herlihy, Nir Shavit, Victor Luchangco,
and Michael Spear

Modified by Piotr Witkowski

Shared-Memory Computability



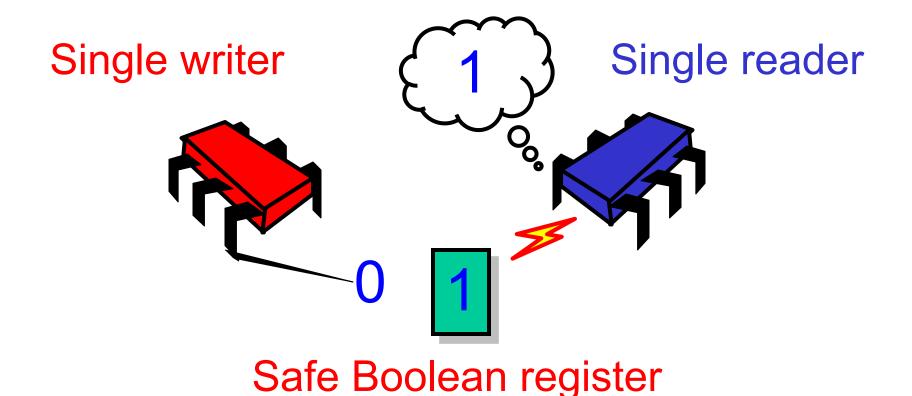
- Mathematical model of concurrent computation
- What is (and is not) concurrently computable
- Efficiency (mostly) irrelevant

Wait-Free Implementation

- Every method call completes in finite number of steps
- Implies no mutual exclusion

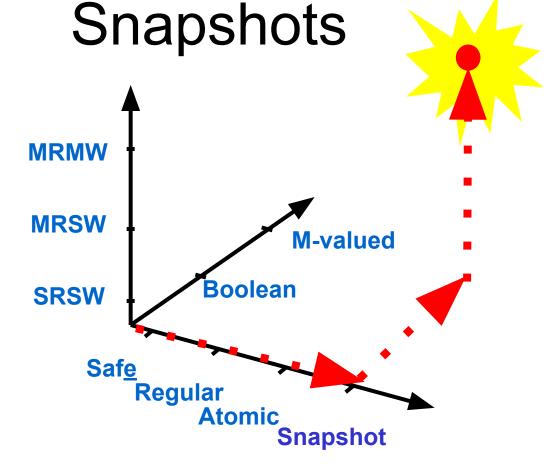


From Weakest Register



Art of Multiprocessor Programming

All the way to a Wait-free Implementation of Atomic



Rationale for wait-freedom

 We wanted atomic registers to implement mutual exclusion

Rationale for wait-freedom

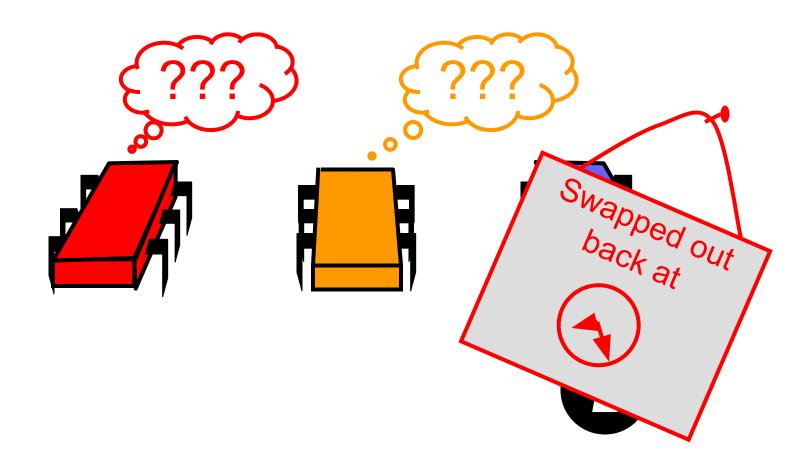
- We wanted atomic registers to implement mutual exclusion
- So we couldn't use mutual exclusion to implement atomic registers

Rationale for wait-freedom

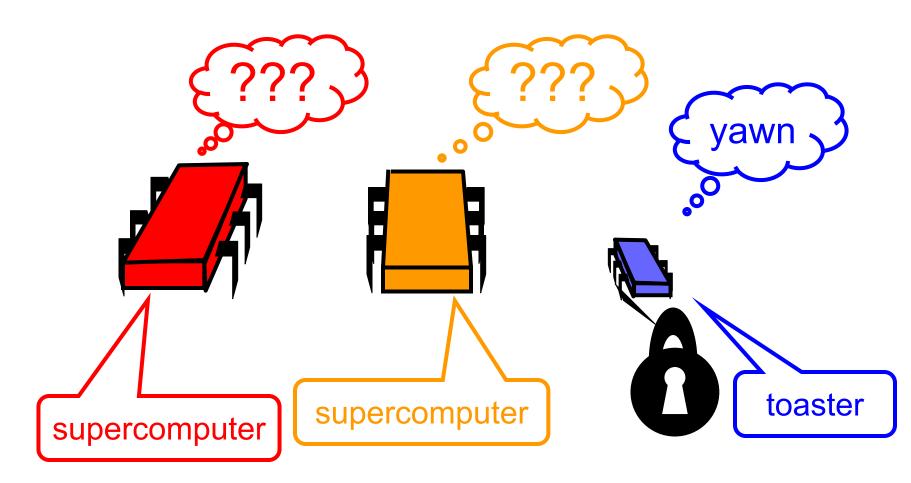
- We wanted atomic registers to implement mutual exclusion
- So we couldn't use mutual exclusion to implement atomic registers
- But wait, there's more!

Why is Mutual Exclusion so wrong?

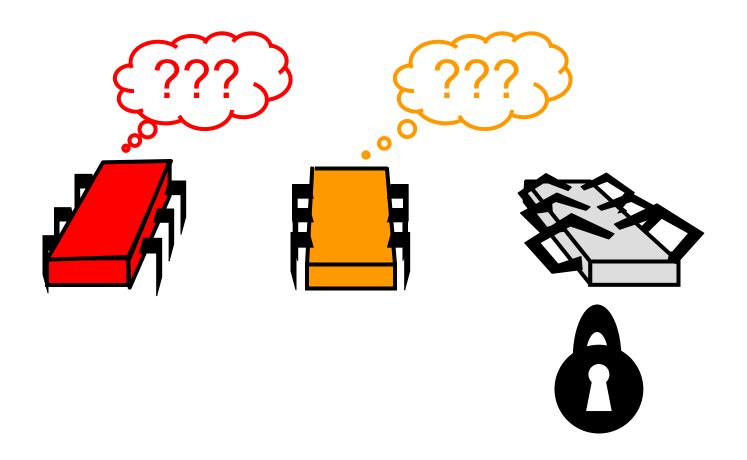
Asynchronous Interrupts



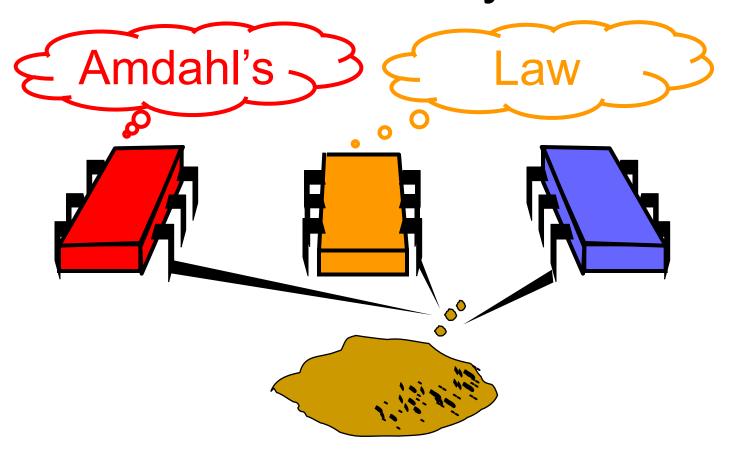
Heterogeneous Processors



Fault-tolerance



Machine Level Instruction Granularity



 Wait-Free synchronization might be a good idea in principle

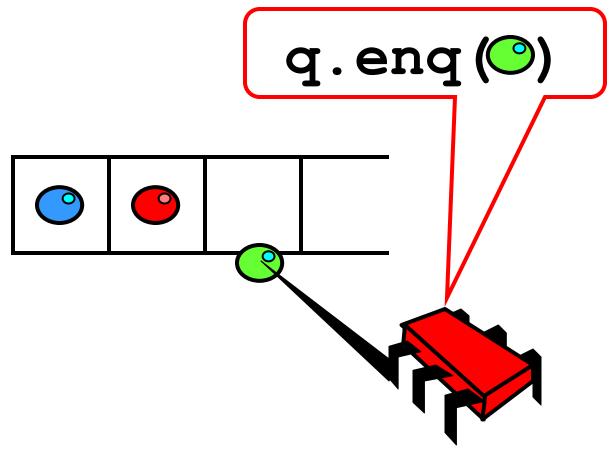
- Wait-Free synchronization might be a good idea in principle
- But how do you do it ...

- Wait-Free synchronization might be a good idea in principle
- But how do you do it ...
 - Systematically?

- Wait-Free synchronization might be a good idea in principle
- But how do you do it ...
 - Systematically?
 - Correctly?

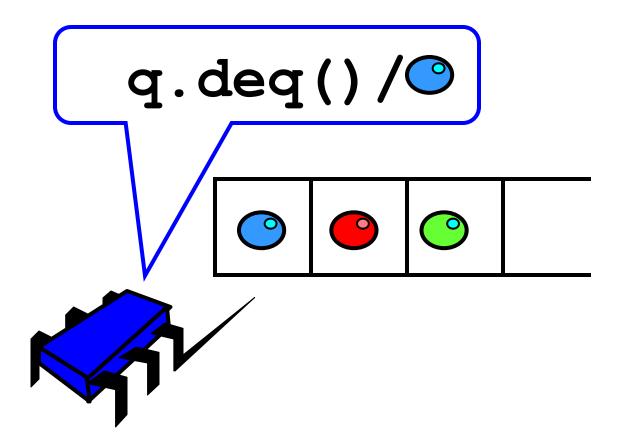
- Wait-Free synchronization might be a good idea in principle
- But how do you do it ...
 - Systematically?
 - Correctly?
 - Efficiently?

FIFO Queue: Enqueue Method



Art of Multiprocessor Programming

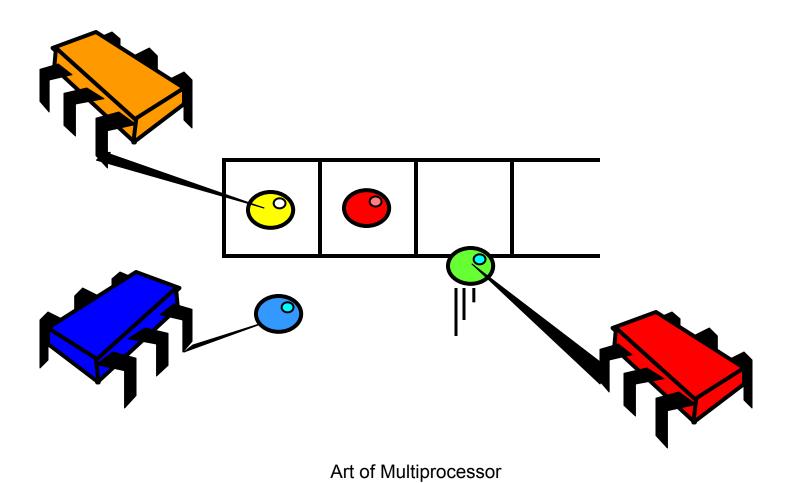
FIFO Queue: Dequeue Method



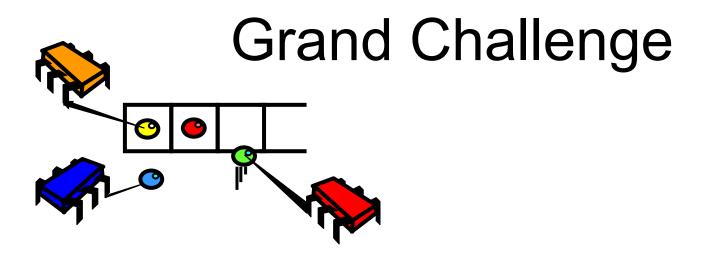
Two-Thread Wait-Free Queue

```
head
                                            tail
public class WaitFreeQueue {
 int head = 0, tail = 0;
                                 capacity-1
 Item[QSIZE] items;
 public void enq(Item x) {
  while (tail-head == QSIZE) {};
  items[tail % QSIZE] = x; tail++;
 public Item deq() {
  while (tail-head == 0) {}
  Item item = items[head % QSIZE];
  head++; return item;
}}
```

What About Multiple Dequeuers?



Programming



Implement a FIFO queue

- Implement a FIFO queue
 - Wait-free

- Implement a FIFO queue
 - Wait-free
 - Linearizable

- Implement a FIFO queue
 - Wait-free
 - Linearizable
 - From atomic read-write registers

- Implement a FIFO queue
 - Wait-free
 - Linearizable
 - From atomic read-write registers
 - Multiple dequeuers

Only new aspect

- Implement a FIFO queue
 - Wait-free
 - Linearizable
 - From atomic read-write registers
 - Multiple dequeuers

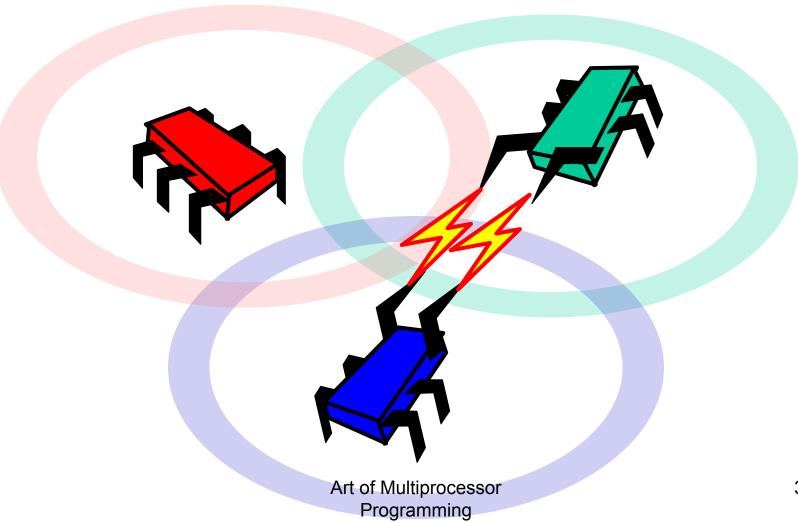
Puzzle

While you are ruminating on the grand challenge ...

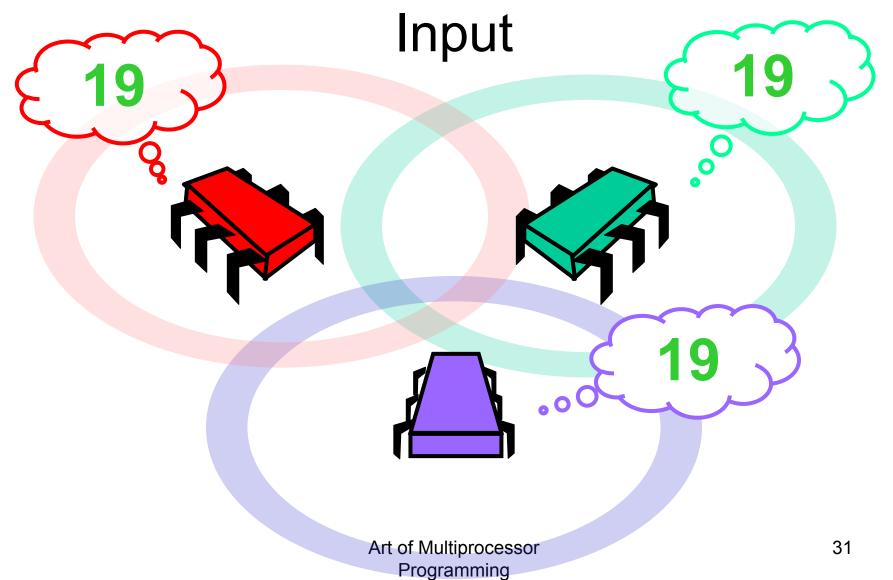
We will give you another puzzle ...

Consensus!

They Communicate



They Agree on One Thread's



Formally: Consensus

- Consistent:
 - all threads decide the same value

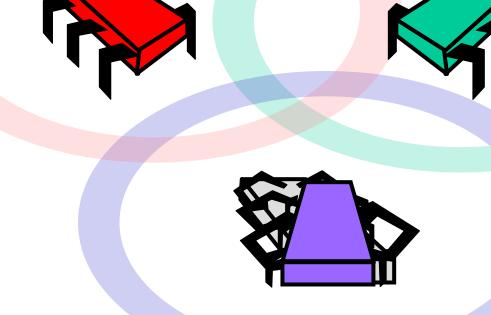
Formally: Consensus

- Consistent:
 - all threads decide the same value
- Valid:
 - the common decision value is some thread's input

No Wait-Free Implementation of Consensus using Registers

Art of Multiprocessor

Programming



Formally

- Theorem
 - There is no wait-free implementation of n-thread consensus from read-write registers

Formally

- Theorem
 - There is no wait-free implementation of n-thread consensus from read-write registers
- Implication
 - Asynchronous computability different from Turing computability

Proof Strategy

```
Assume otherwise ...

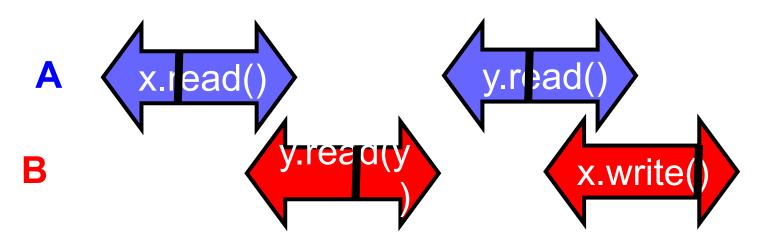
Reason about the properties of any such protocol ...

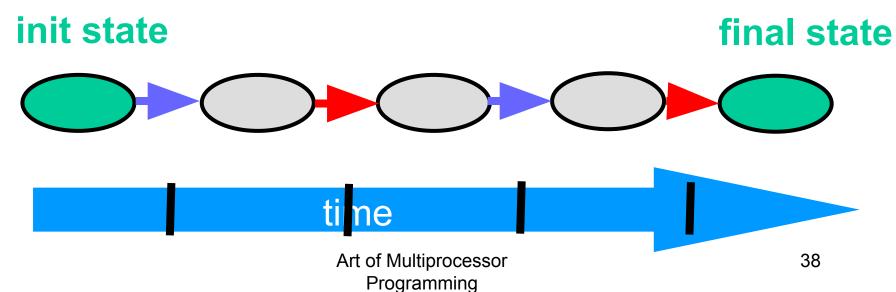
Derive a contradiction

Quod
Erat
Demonstrandum
```

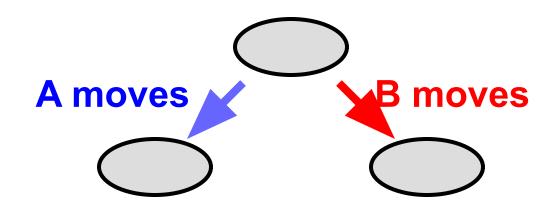
Enough to consider binary consensus and *n*=2

Protocol Histories as State Transitions



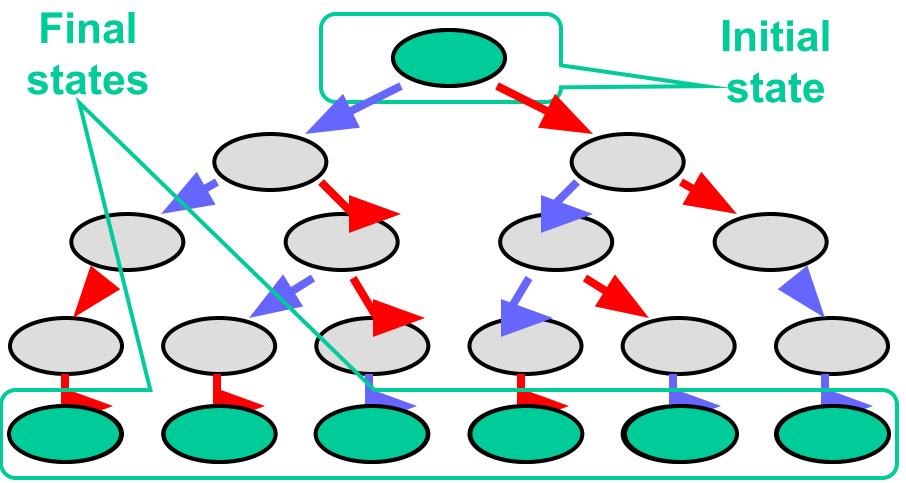


Wait-Free Computation

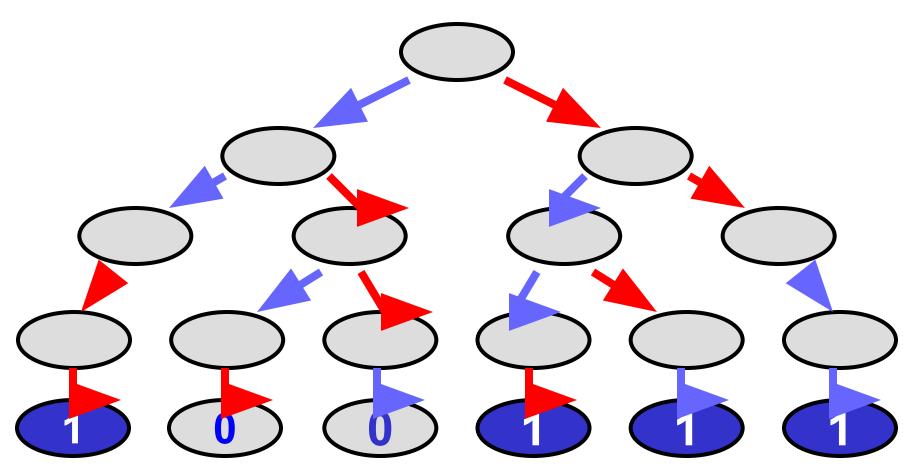


- Either A or B "moves"
- Moving means
 - Register read
 - Register write

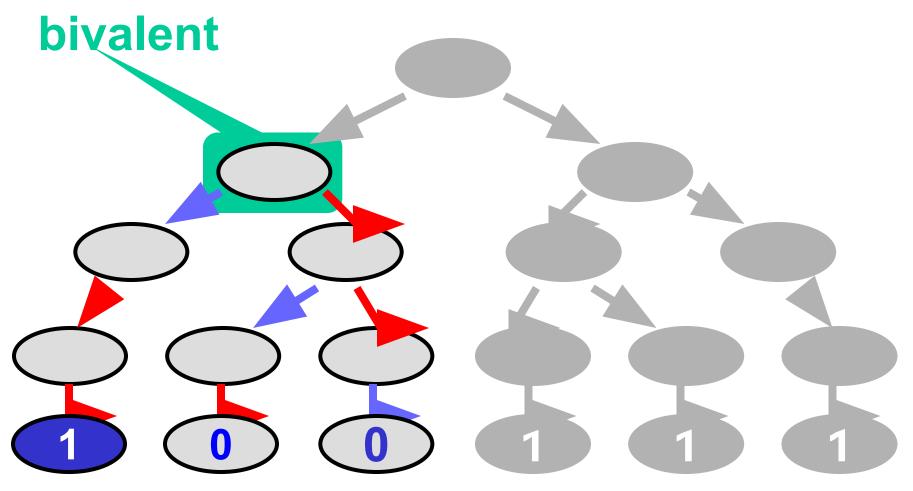
The Two-Move Tree



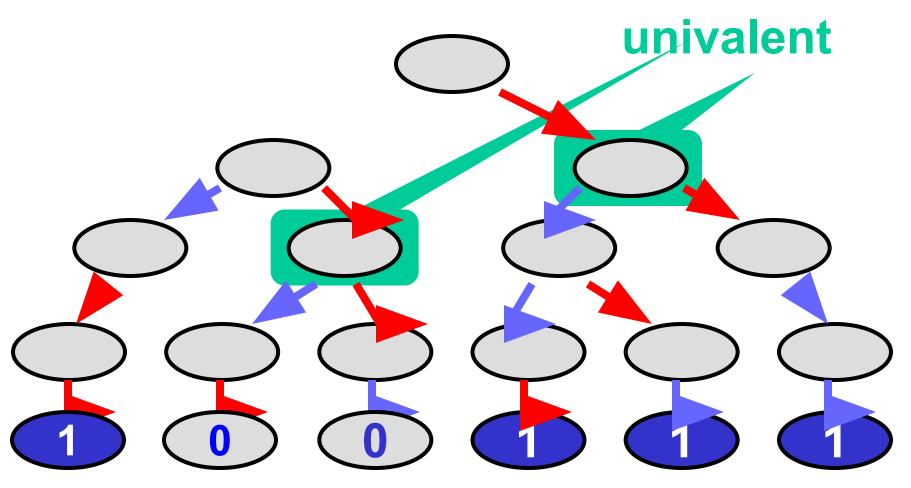
Decision Values



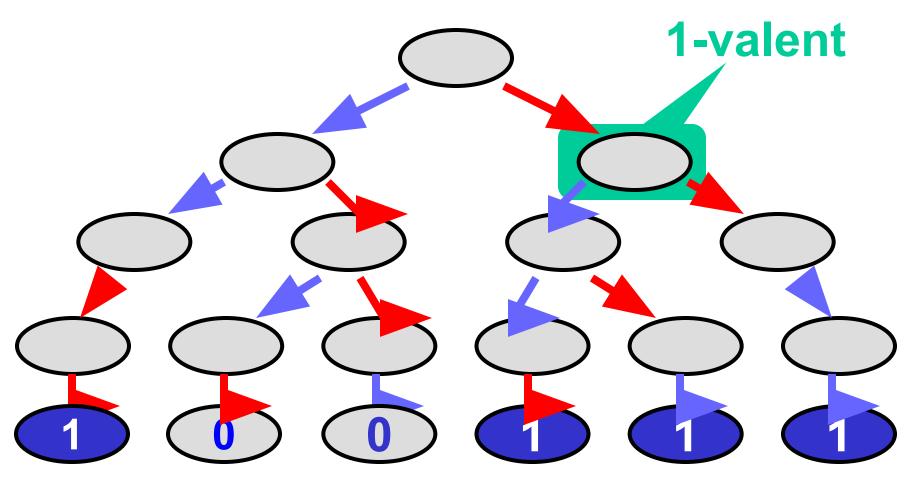
Bivalent: Both Possible



Univalent: Single Value Possible



x-valent: x Only Possible Decision



Wait-free computation is a tree

- Wait-free computation is a tree
- Bivalent system states
 - Outcome not fixed

- Wait-free computation is a tree
- Bivalent system states
 - Outcome not fixed
- Univalent states
 - Outcome is fixed
 - May not be "known" yet

- Wait-free computation is a tree
- Bivalent system states
 - Outcome not fixed
- Univalent states
 - Outcome is fixed
 - May not be "known" yet
- 1-Valent and 0-Valent states

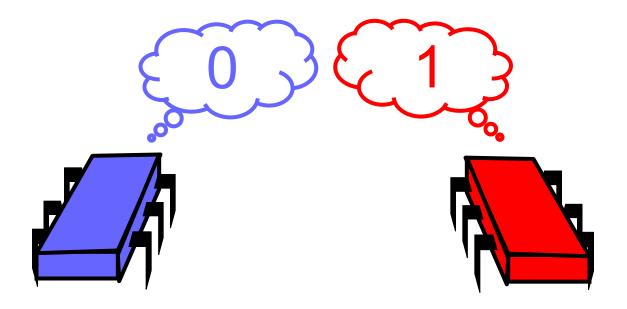
Some initial state is bivalent

- Some initial state is bivalent
- Outcome depends on
 - Chance
 - Whim of the scheduler

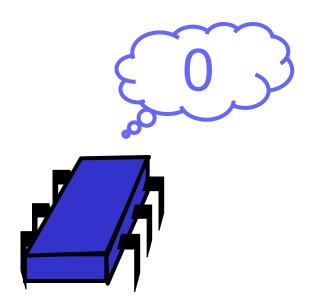
- Some initial state is bivalent
- Outcome depends on
 - Chance
 - Whim of the scheduler
- Multicore gods procrastinate ...

- Some initial state is bivalent
- Outcome depends on
 - Chance
 - Whim of the scheduler
- Multicore gods procrastinate
- Let's prove it

What if inputs differ?



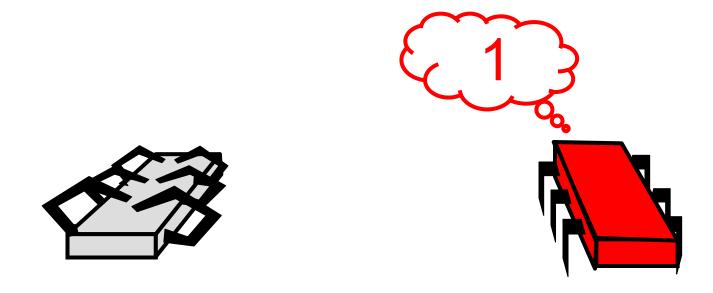
Must Decide 0





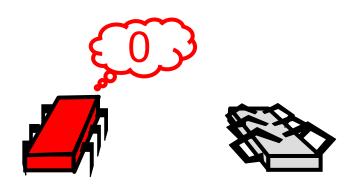
In this solo execution by A

Must Decide 1

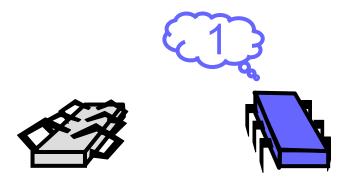


In this solo execution by B

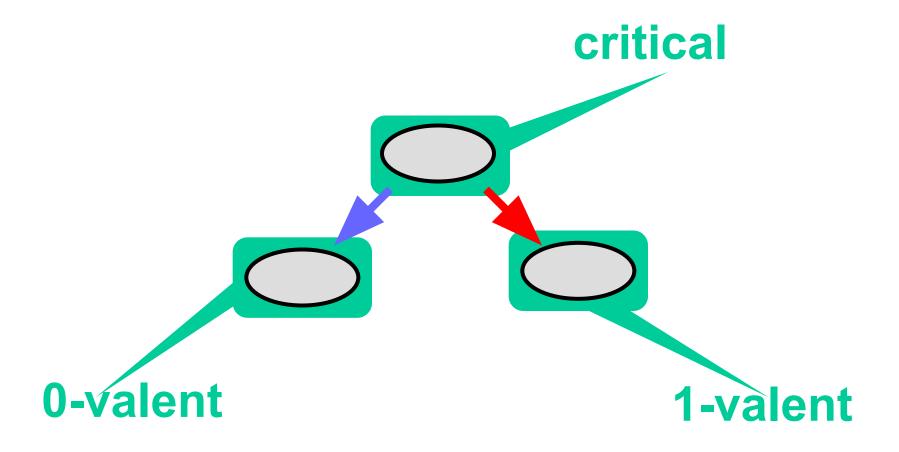
Mixed Initial State Bivalent



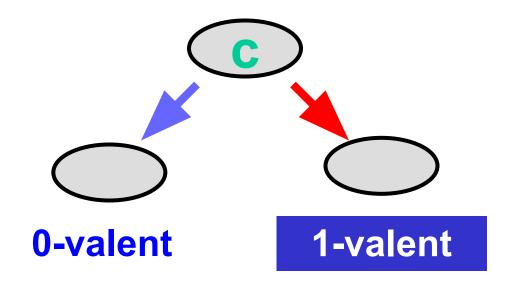




Solo execution by B must decide 1



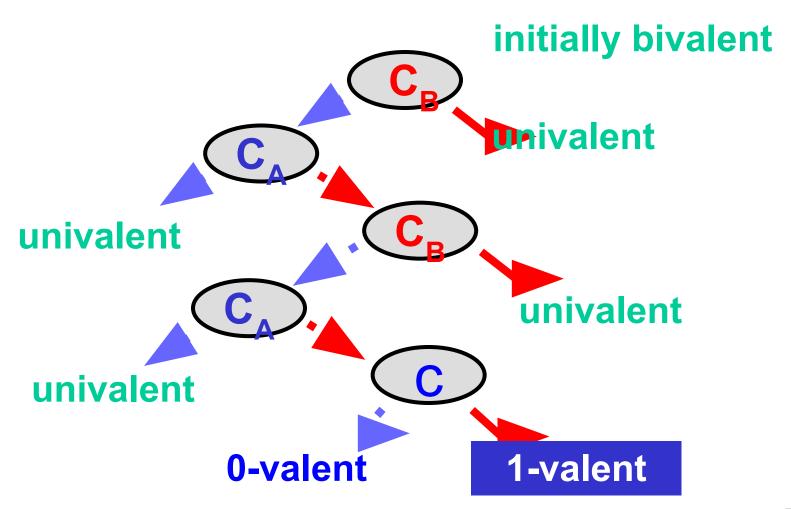
From a Critical State



If A goes first, protocol decides 0

If B goes first, protocol decides 1

Reaching Critical State



Starting from a bivalent initial state

- Starting from a bivalent initial state
- The protocol can reach a critical state

- Starting from a bivalent initial state
- The protocol can reach a critical state
 - Otherwise we could stay bivalent forever
 - And the protocol is not wait-free

Model Dependency

- So far, memory-independent!
- True for
 - Registers
 - Message-passing
 - Carrier pigeons
 - Any kind of asynchronous computation

Start from a critical state

- Start from a critical state
- Each thread fixes outcome by
 - Reading or writing ...
 - Same or different registers

- Start from a critical state
- Each thread fixes outcome by
 - Reading or writing ...
 - Same or different registers
- Leading to a 0 or 1 decision ...

- Start from a critical state
- Each thread fixes outcome by
 - Reading or writing ...
 - Same or different registers
- Leading to a 0 or 1 decision ...
- And a contradiction.

Possible Interactions

	x.read()	y.read()	x.write()	y.write()
x.read()	?	?	?	?
y.read()	?	?	?	?
x.write()	?	?	?	?
y.write()	?	?	?	?
	68			

Programming

Possible Interactions

	A reads x			
	x.read()	y.read()	x.write()	y.write()
x.read()	?	?	?	?
y.read()	?	?	?	?
x.write()	?	?	?	?
y.write()	?	?	?	?
	69			

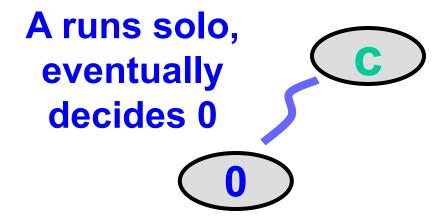
Possible Interactions

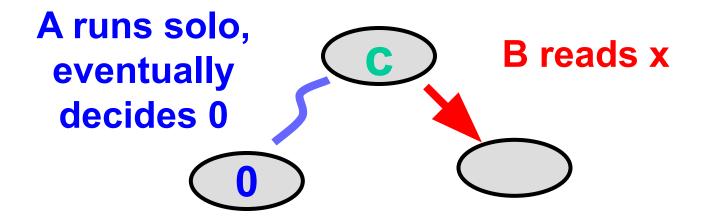
	I	A reads x		
			A	reads y
	x.read()	y.read()	x.write()	y.write()
x.read()	?	?	?	?
y.read()	?	?	?	?
x.write()	?	?	?	?
y.write()	?	?	?	?
Art of Multiprocessor Programming				

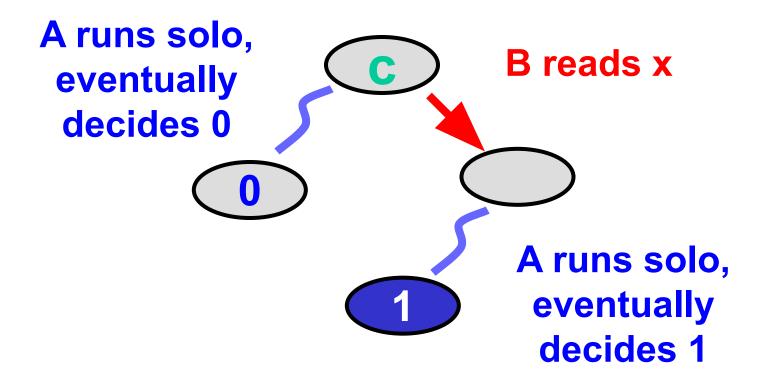
Some Thread Reads

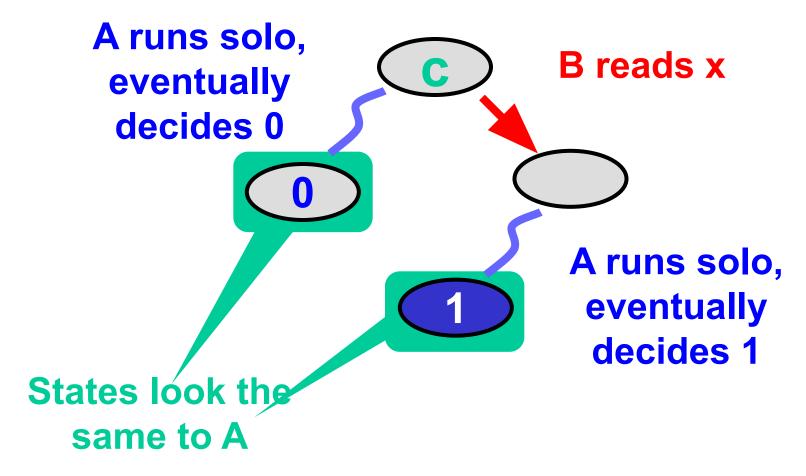


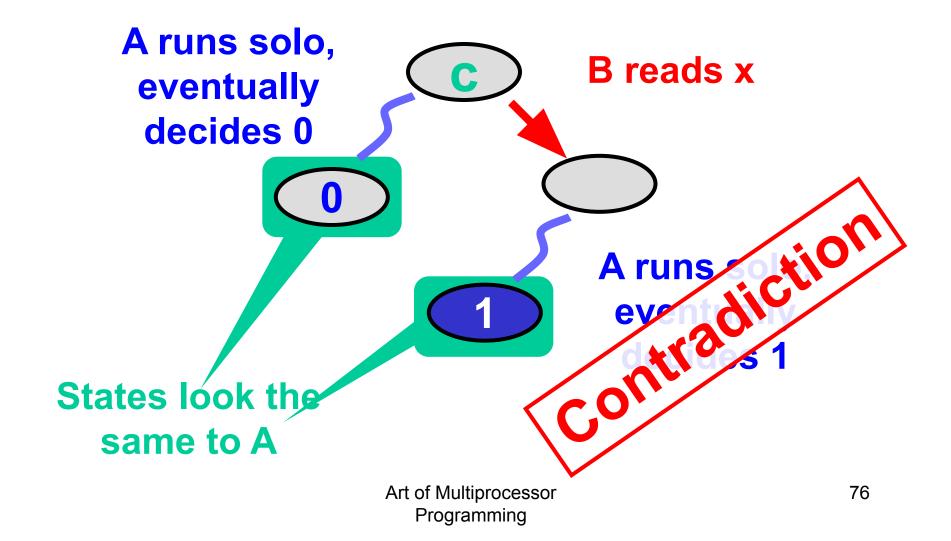
Some Thread Reads









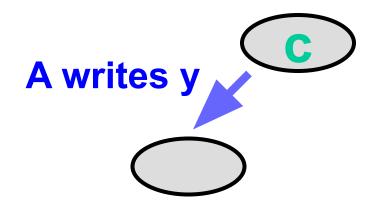


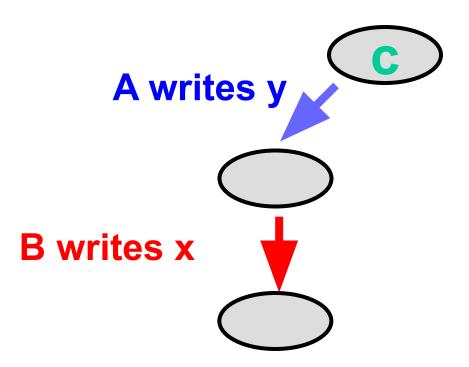
Possible Interactions

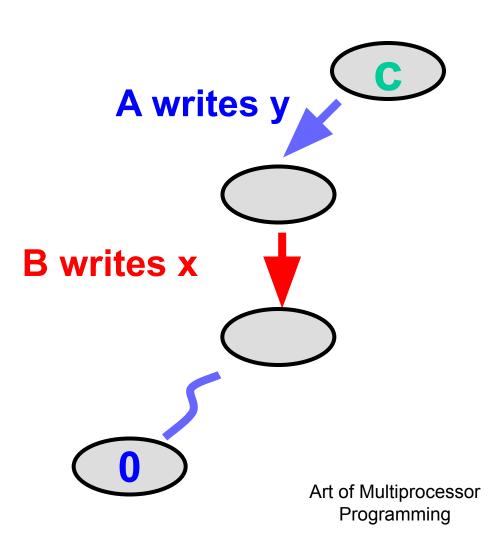
	x.read()	y.read()	x.write()	y.write()
x.read()	no	no	no	no
y.read()	no	no	no	no
x.write()	no	no	?	?
y.write()	no	no	?	?
		Art of Multiprocesso] or	77

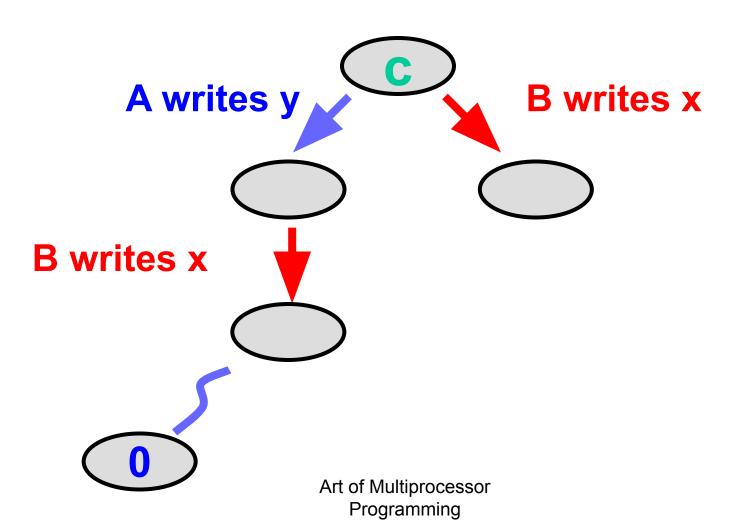
Programming

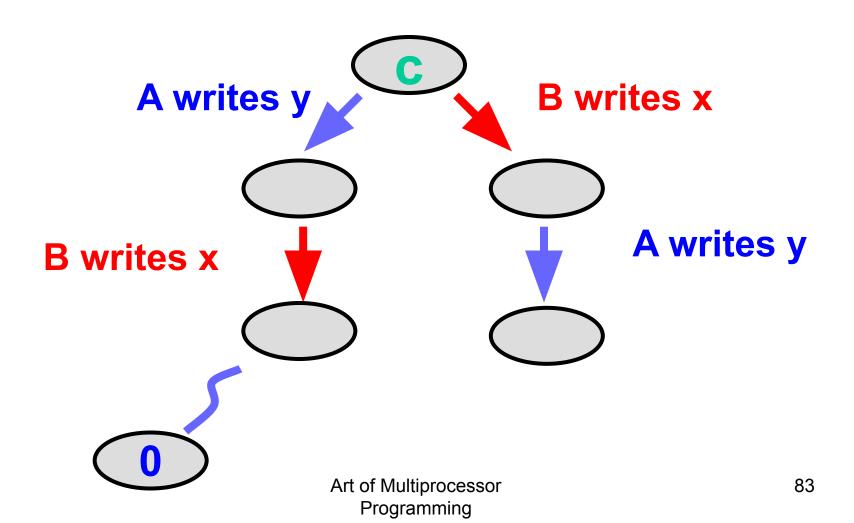


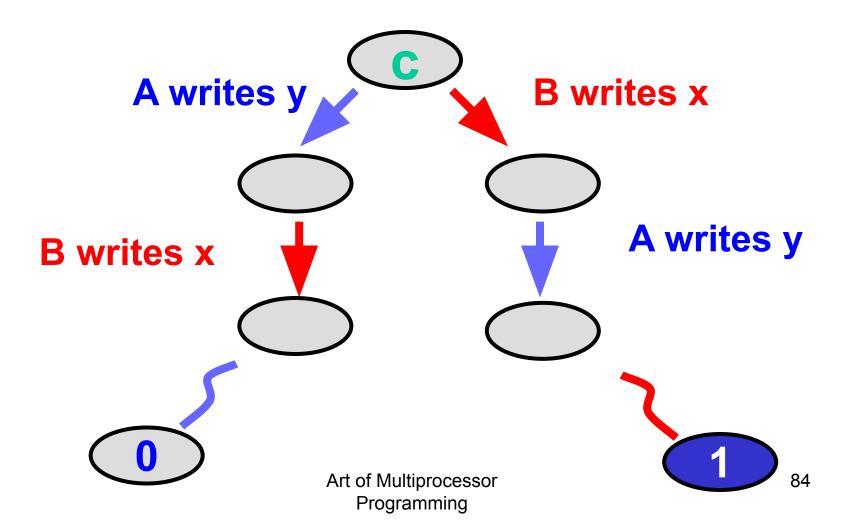


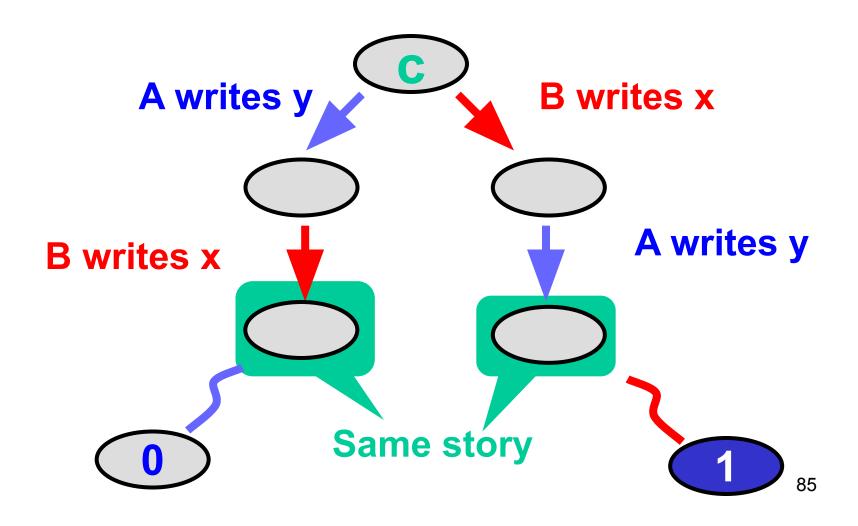


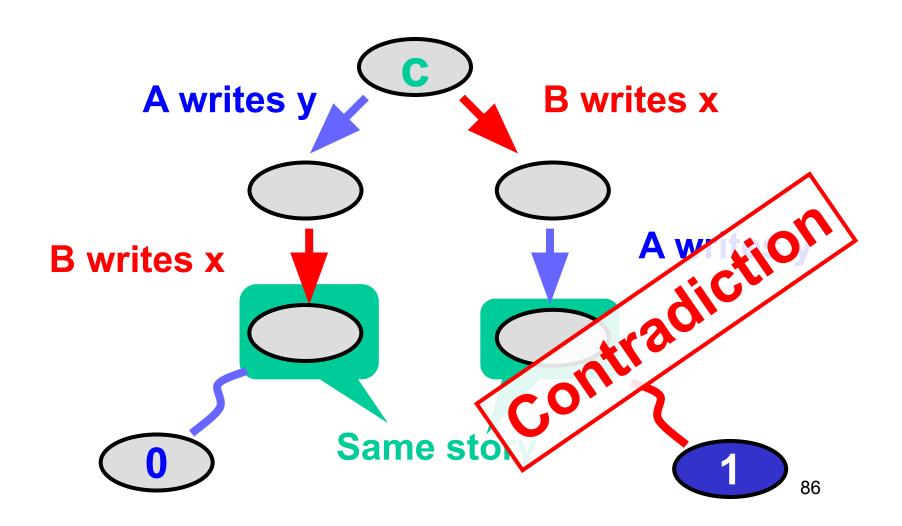










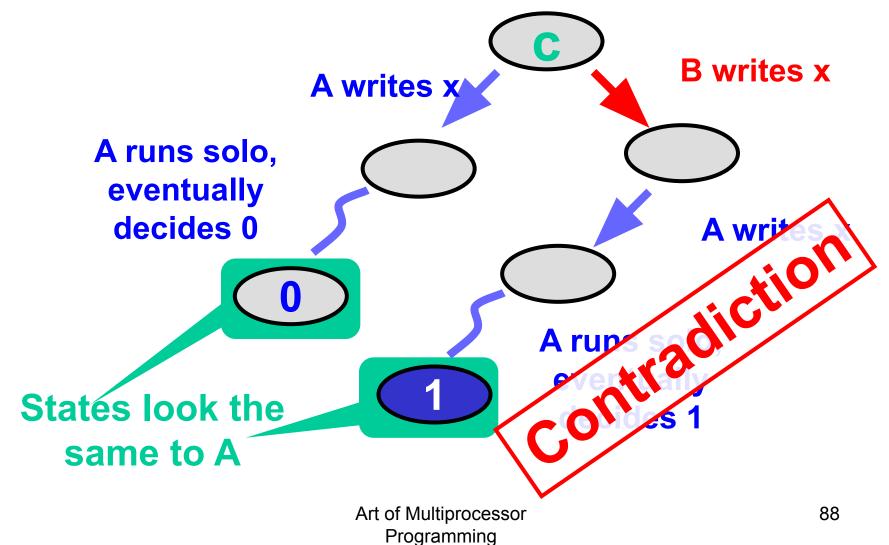


Possible Interactions

	x.read()	y.read()	x.write()	y.write()
x.read()	no	no	no	no
y.read()	no	no	no	no
x.write()	no	no	?	no
y.write()	no	no	no	?
	87			

Programming

Writing Same Registers



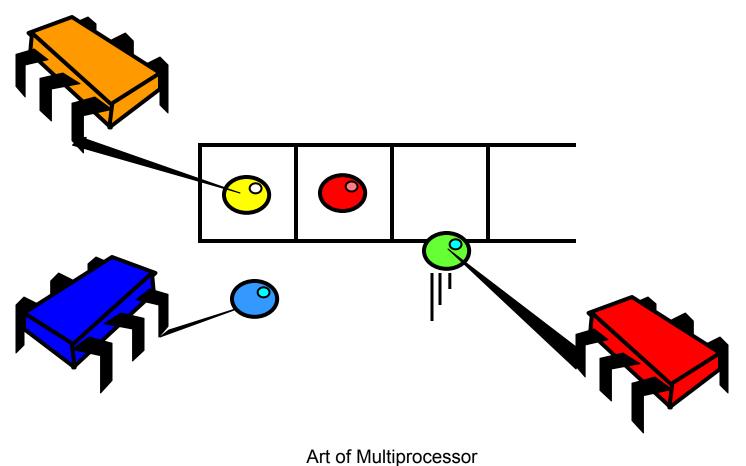
That's All, Folks!

	x.read()	y.read()	x.write()	y.write()	
x.read()	no	no	no	no	
y.read()	no	no	no	no	
x.write()	no	no	no	no	
y.write()	no	no	na C	no	
Art of Multiprocessor Programming					

Recap: Atomic Registers Can't Do Consensus

- If protocol exists
 - It has a bivalent initial state
 - Leading to a critical state
- What's up with the critical state?
 - Case analysis for each pair of methods
 - As we showed, all lead to a contradiction

What Does Consensus have to do with Concurrent Objects?



Programming

91

Consensus Object

```
public interface Consensus<T> {
  T decide(T value);
}
```

Concurrent Consensus Object

- We consider only one time objects:
 - each thread calls method only once
- Linearizable to sequential consensus object:
 - Winner's call went first

Java Jargon Watch

- Define Consensus protocol as an abstract class
- We implement some methods
- You do the rest

```
abstract class ConsensusProtocol<T>
   implements Consensus<T> {
protected T[] proposed = new T[N];
protected void propose(T value) {
 proposed[ThreadID.get()] = value;
 abstract public T decide (T value);
```

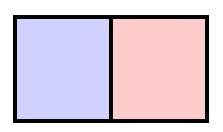
```
abstract class ConsensusProtocol<T>
   implements Consensus<T>
protected T[] proposed = new T[N];
protected void propose
 proposed[ThreadID.get
                       Each thread's
abstract public T de
                       proposed value
```

```
abstract class ConsensusProtocol<T>
   implements Consensus<T> {
protected T[] proposed = new T[N];
protected void propose(T value) {
 proposed[ThreadID.get()] = value;
abstract public T decide(T value)
                      Propose a value
```

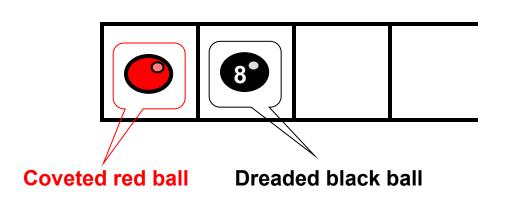
```
Decide a value: abstract method
   means subclass does the real work
protected voi
               propose(T value) {
 proposed[ThreadID.get()] = value;
abstract public T decide (T value);
```

Can a FIFO Queue Implement Consensus?

FIFO Consensus

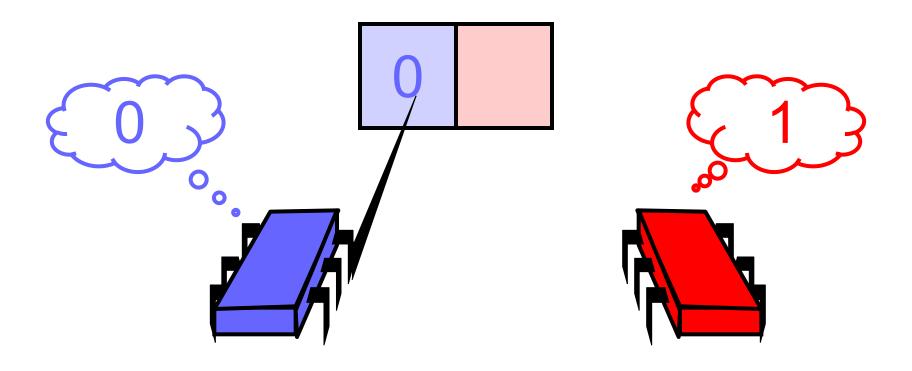


proposed array

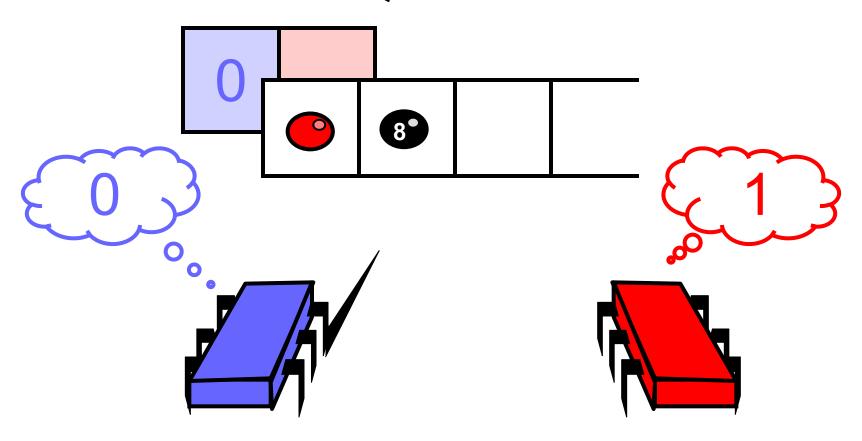


FIFO Queue with red and black balls

Protocol: Write Value to Array



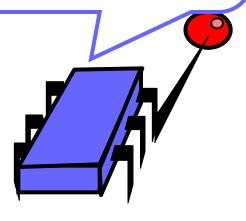
Protocol: Take Next Item from Queue

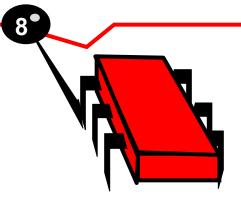


Protocol: Take Next Item from Queue

I got the coveted red ball, so I will decide my value

I got the dreaded black ball, so I will decide the other's value from the array





Consensus Using FIFO Queue

```
public class QueueConsensus<T>
  extends ConsensusProtocol<T> {
 private Queue queue;
 public QueueConsensus() {
  queue = new Queue();
  queue.enq(Ball.RED);
  queue.enq(Ball.BLACK);
```

Initialize Queue

```
public class QueueConsensus
  extends ConsensusProtocol {
 private Queue queue;
 public QueueConsensus (
  this.queue = new Queue();
  this.queue.enq(Ball.RED);
  this.queue.enq(Ball.BLACK);
```

Who Won?

```
public class QueueConsensus<T>
  extends ConsensusProtocol<T> {
 private Queue queue;
 public T decide(T value) {
  propose(value);
  Ball ball = queue.deq();
  if (ball == Ball.RED)
   return proposed[i];
  else
   return proposed[1-i];
```

Who Won?

```
public class QueueConsensus<T>
  extends ConsensusProtocol<T> {
 private Queue queue;
 public T decide(T value) {
  propose (value):
  Ball ball = queue.deq();
         II == Ball RED
   return proposed[i
  else
   return proposed[1-ij];
                          Race to dequeue
                          first queue item
```

Who Won?

```
public class QueueConsensus<T>
  extends ConsensusProtocol<T> {
 private Queue queue;
 public T decide(T value) {
  propose(value);
  Ball ball = this.queue.deq();
 if (ball == Ball.RED)
   return proposed[i];
  else
   return proposed[1-1]
                        I win if I was first
```

Who Won?

```
public class QueueConsensus<T>
  extends ConsensusProtocol<T> {
 private Queue queue;
                       Other thread wins if I
 public T decide (T valug) was second
  propose(value);
  Ball ball = this.quere.deq();
  if (ball == Ball.RE)
   return proposed[i];
  else
   return proposed[1-i];
```

Why does this Work?

- If one thread gets the red ball
- Then the other gets the black ball
- Winner decides her own value
- Loser can find winner's value in array
 - Because threads write array
 - Before dequeueing from queue

Theorem

- We can solve 2-thread consensus using only
 - A two-dequeuer queue, and
 - Some atomic registers

Implications

- Given
 - A consensus protocol from queue and registers
- Assume there exists
 - A queue implementation from atomic registers
- Substitution yields:
 - A wait-free consensus protocol from at registers

Corollary

- It is impossible to implement
 - a two-dequeuer wait-free FIFO queue
 - from read/write memory.

Consensus Numbers

- An object X has consensus number n
 - If it can be used to solve *n*-thread consensus
 - Take any number of instances of X
 - together with atomic read/write registers
 - and implement n-thread consensus
 - But not (n+1)-thread consensus

Consensus Numbers

- Theorem
 - Atomic read/write registers have consensus number 1
- Theorem
 - Multi-dequeuer FIFO queues have consensus number at least 2

Consensus Numbers Measure Synchronization Power

- Theorem
 - If you can implement X from Y
 - And X has consensus number c
 - Then Y has consensus number at least c

Synchronization Speed Limit

- Conversely
 - If X has consensus num
 - And Y has consensus no
 - Then there is no way to construct
 wait-free implementation of X by Y
- This theorem will be very useful
 - Unforeseen practical implications!

Earlier Grand Challenge

- Snapshot means
 - Write any array element
 - Read multiple array elements atomically
- What about
 - Write multiple array elements atomically
 - Scan any array elements
- Call this problem multiple assignment

Multiple Assignment Theorem

- Atomic registers cannot implement multiple assignment
- Weird or what?
 - Single write/multi read OK
 - Multi write/multi read impossible

Proof Strategy

- If we can write to 2/3 array elements
 - We can solve 2-consensus
 - Impossible with atomic registers
- Therefore
 - Cannot implement multiple assignment with atomic registers

Proof Strategy

- Take a 3-element array
 - A writes atomically to slots 0 and 1
 - B writes atomically to slots 1 and 2
 - Any thread can scan any set of locations

Double Assignment Interface

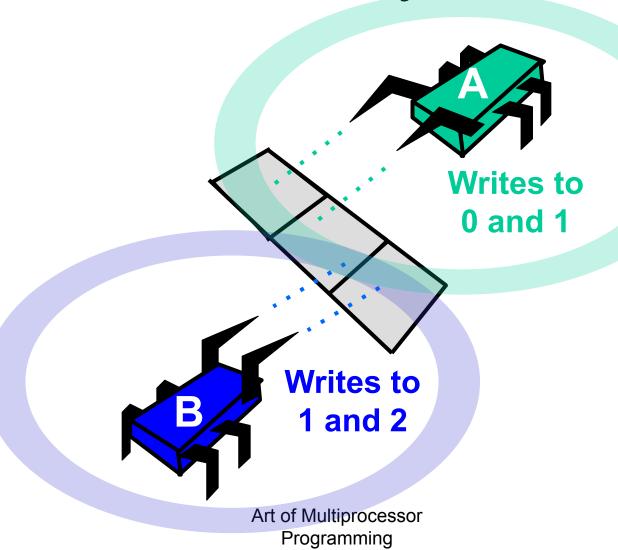
Double Assignment Interface

```
interface Assign2 {
public void assign(int i, int v,
                     int i, int v,;
       int read(int i);
   Atomically assign
   value[i_1] = v_1
   value[i_2] = v_2
```

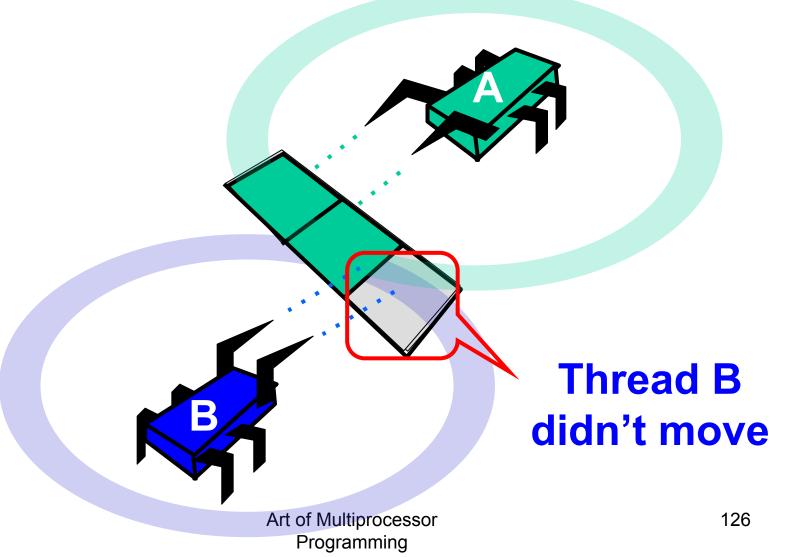
Double Assignment Interface

```
interface Assign2 {
  public void assign(int i, int v, int v, int i, int v, int v, int i, int v, int v
```

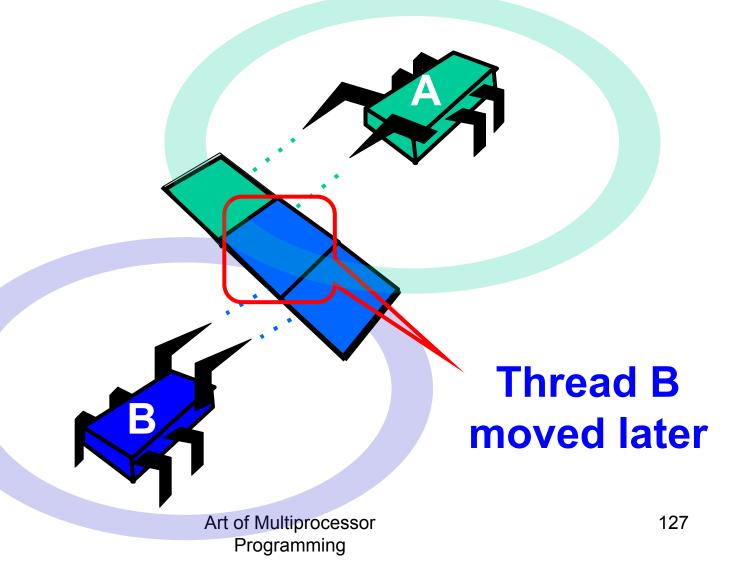
Initially



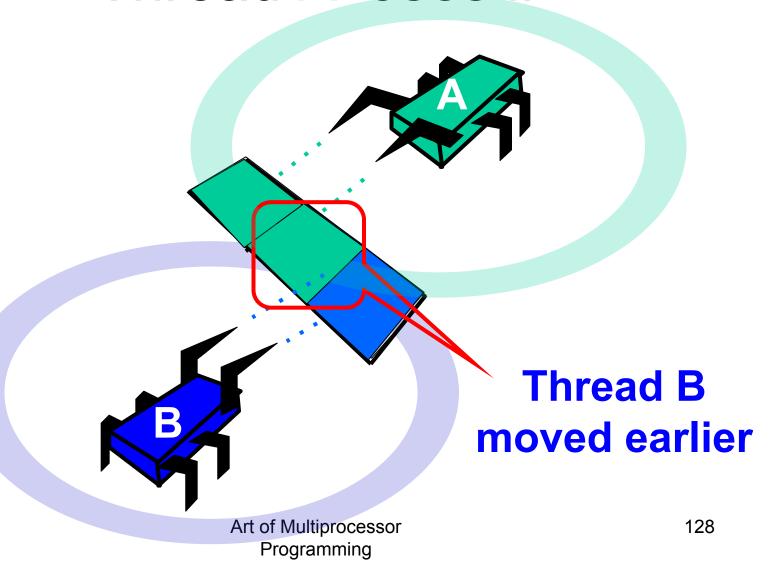
Thread A wins if



Thread A wins if



Thread A loses if



```
class MultiConsensus extends ... {
Assign2 a = new Assign2(3, EMPTY);
public T decide(T value) {
  a.assign(i, i, i+1, i);
  int other = a.read((i+2) % 3);
  if (other==EMPTY||other==a.read(1))
   return proposed[i];
  else
   return proposed[j];
  }}
```

```
class MultiConsensus extends ... {
Assign2 a = new Assign2(3, EMPTY);
public T decide(T value) {
  a.assign(i, i, i+1, i);
  int other = a.read((i+2) % 3);
  if (other==EMPTY||other==a.read(1))
   return proposed[i];
  else
   return proposed[j];
  }}
```

Extends ConsensusProtocol Decide sets j=i-1 and proposes value

```
class MultiConsensus extends
Assign2 a = new Assign2(3, EMPTY)
public T decide (T value)
 a.assign(i, i, i+1,
  int other = a.read((i+2))
  if (other==EMPTY||other==a
   return proposed[i];
  else
                              Three slots
   return proposed[j];
                              initialized to
                                EMPTY
```

```
class MultiConsensus extends ... {
Assign2 a = new Assign2(3, EMPTY);
 public T decide(T value)
  a.assign(i, i, i+1, i);
  int other = a.xead((1+2)
  if (other==EMPTY) other==a.read(1))
   return proposed[i]
  else
   return proposed[jAssign ID 0 to entries 0,1
                       (or ID 1 to entries 1,2)
```

```
class MultiConsensus extends ... {
Assign2 a = new Assign2(3, EMPTY);
public T decide(T value) {
 int other = a.read((i+2) % 3);
  if (other==EMPTY||other==a\read(1))
   return proposed[i];
  else
   return proposed[j];
                         Read the register my
                         thread didn't assign
```

```
class MultiConsensus extends
Assign2 a = new Assign2(3,
public T decide(T value)
  a.assign(i, i, i+1, i);
  int_other = a.read((i+2)
     (other==EMPTY | other==a.read(1))
   return propo
  else
                           Other thread didn't
   return proposed[j];
                             move, so I win
```

```
class MultiConsensus extends ... {
                 Assign2(3, EMPTY);
Assign2
          decide(T value) {
               i, i+1, i);
  a.ass
               a.read
         er==EMPTY | other==a.read(1))
      urn proposed[i]
  else
                        Other thread moved
   return proposed[j]; later so | win
```

```
class MultiConsensus extends ... {
Assign2 a = new Assign2(3, EMPTY);
public T decide(T value) {
  a.assign(i, i, i+1, i);
  int other = a.read((i+2) % 3);
  if (other==EMPTY||other==a.read(1))
  return proposed[i];
   return proposed[j]
                            OK, I win.
```

```
class MultiConsensus extends ... {
Assign2 a = new Assign2(3,
public T decide(T value)
  a.assign(i, i, i+1,
  int other = a.read((i+2) 6
  if (other==EMPTY||other
                               .read(1))
   return proposed[i];(1)
  else
   return proposed[j]; Other thread moved
                           first, so I lose
```

Summary

- If a thread can assign atomically to 2 out of 3 array locations
- Then we can solve 2-consensus
- Therefore
 - No wait-free multi-assignment
 - From read/write registers

Read-Modify-Write Objects

- Method call
 - Returns object's prior value x
 - Replaces x with mumble(x)

Read-Modify-Write

```
public abstract class RMWRegister {
private int value;
public int synchronized
  getAndMumble() {
    int prior = value;
    value = mumble(value);
    return prior;
```

Read-Modify-Write

```
public abstract class RMWRegister {
private int value;
public int synchronized
  getAndMumble()
   int prior = value;
    value = mumble(value);
    return prior;
                    Return prior value
```

Read-Modify-Write

```
public abstract class RMWRegister {
private int value;
public int synchronized
  getAndMumble() {
    int prior = value;
   value = mumble(value);
    return prior;
        Apply function to current value
```

RMW Everywhere!

- Most synchronization instructions
 - are RMW methods
- The rest
 - Can be trivially transformed into RMW methods

Example: Read

```
public abstract class RMWRegister {
 private int value;
  public int synchronized read() {
    int prior = value;
    value = value;
    return prior;
```

Example: Read

```
public abstract class RMW {
  private int value;
  public int synchronized read() {
    int prior = this.value;
   value = value;
    return prior
             apply f(x)=x, the
             identity function
```

Example: getAndSet

```
public abstract class RMWRegister {
private int value;
public int synchronized
   getAndSet(int v) {
  int prior = value;
  value = v;
  return prior;
```

Example: getAndSet (swap)

```
public abstract class RMWRegister {
private int value;
 public int synchronized
   getAndSet(int v) {
  int prior = value;
  value = v;
  return prior;
           f(x)=v is constant
```

getAndIncrement

```
public abstract class RMWRegister {
private int value;
public int synchronized
   getAndIncrement() {
  int prior = value;
  value = value + 1;
  return prior;
```

getAndIncrement

```
public abstract class RMWRegister {
 private int value;
 public int synchronized
   getAndIncrement() {
  int prior = value;
  value = value + 1;
  return prior;
         f(x) = x+1
```

getAndAdd

```
public abstract class RMWRegister {
private int value;
public int synchronized
   getAndAdd(int a) {
  int prior = value;
  value = value + a;
  return prior;
```

Example: getAndAdd

```
public abstract class RMWRegister {
private int value;
 public int synchronized
   getAndIncrement(int a) {
  int prior = value;
 value = value + a;
  return prior;
```

```
public abstract class CASObject {
private int value;
public boolean synchronized
   compareAndSet(int expected,
                  int update) {
  if (value==expected) {
   value = update; return true;
  return false;
  } ... }
```

```
public abstract class CASObject {
 private int value;
 public boolean synchronized
   compareAndSet(int expected,
                  int update)
     (value==expected)
                   return
 return false;
 } ... }
                If value is as expected, ...
```

```
public abstract class CASOBJECT{
 private int value;
 public boolean synchronized
   compareAndSet(int expected,
                  int update)
 if (value==expected)
 value = update return
 return false;
 } ... }
             ... replace it
```

```
public abstract class RMWRegister {
private int value;
public boolean synchronized
   compareAndSet(int expected,
                 int update) {
 if (value==expected) {
  value = update; return true;
 return false;
 } ... }
```

```
public abstract class RMWRegister {
private int value;
 public boolean synchronized
   compareAndSet(int expected,
                 int update) {
 if (value==expected) {
  value = update; return true;
return false;
                         Otherwise report
                              failure
```

Read-Modify-Write

```
public abstract class RMWRegister {
private int value;
public void synchronized
  getAndMumble() {
    int prior = value;
    value = mumble(value);
    return prior;
```

Lets characterize f(x)...

Definition

- A RMW method
 - With function mumble(x)
 - is non-trivial if there exists a value v
 - Such that $v \neq \text{mumble}(v)$

Par Example

- Identity(x) = x
 - is trivial
- getAndIncrement(x) = x+1
 - is non-trivial

Theorem

- Any non-trivial RMW object has consensus number at least 2
- No wait-free implementation of RMW registers from atomic registers
- Hardware RMW instructions not just a convenience

Reminder

- Subclasses of consensus have
 - propose(x) method
 - which just stores x into proposed[i]
 - built-in method
 - decide (object value) method
 - which determines winning value
 - customized, class-specific method

```
public class RMWConsensus
     extends ConsensusProtocol {
 private RMWRegister r = v;
public T decide(T value) {
  propose(value);
  if (r.getAndMumble() == v)
   return proposed[i];
  else
   return proposed[j];
}}
```

```
public class RMWConsensus
     extends ConsensusProtocol {
private RMWRegister r = v;
     ic T decide(T value)
  propose(value);
  if (r.getAndMumble()
   return proposed[i];
                        Initialized to v
  else
   return proposed[j];
} }
```

```
public class RMWConsensus
     extends Consensus {
                              Am I first?
 private RMWRegister r = v;
public T decide (T value)
  propose(value);
  if (r.getAndMumble() == v)
   return proposed[i];
  else
   return proposed[j];
  } }
```

```
public class RMWConsensus
     extends ConsensusProtocol {
private RMWRegister r = v;
 public T decide(T value)
                            Yes, return
  propose(value);
                           my input
  if (r.getAndMumble()
   return proposed[i];
  else
   return proposed[j];
} }
```

```
public class RMWConsensus
     extends ConsensusProtocol {
private RMWRegister r = v;
public T decide(T value) {
 propose (value);
  if (r.getAndMumble() == v)
                             No, return
   return proposed[i];
                            other's input
  else
   return proposed[j];
```

- We have displayed
 - A two-thread consensus protocol
 - Using any non-trivial RMW object

Interfering RMW

- Let F be a set of functions such that for all f_i and f_i either
 - Commute: $f_i(f_i(v))=f_i(f_i(v))$
 - Overwrite: $f_i(f_i(v))=f_i(v)$
- Claim: Any set of RMW objects that commutes or overwrites has consensus number exactly 2

Examples

"test-and-set" getAndSet(1) f(v)=1

Overwrite
$$f_i(f_i(v))=f_i(v)$$

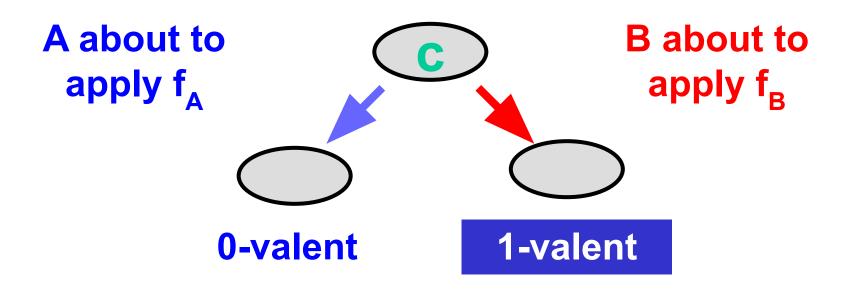
"swap" getAndSet(x) f(v,x)=x

Overwrite
$$f_i(f_i(v))=f_i(v)$$

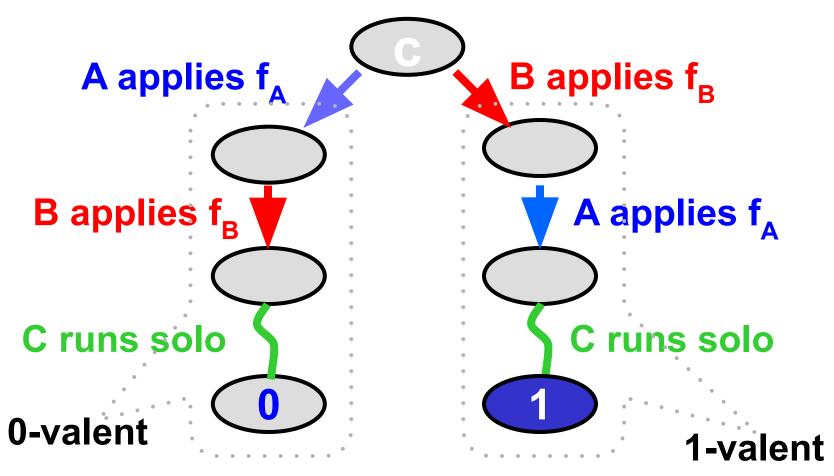
"fetch-and-inc" getAndIncrement() f(v)=v+1

Commute
$$f_i(f_j(v)) = f_j(f_i(v))$$

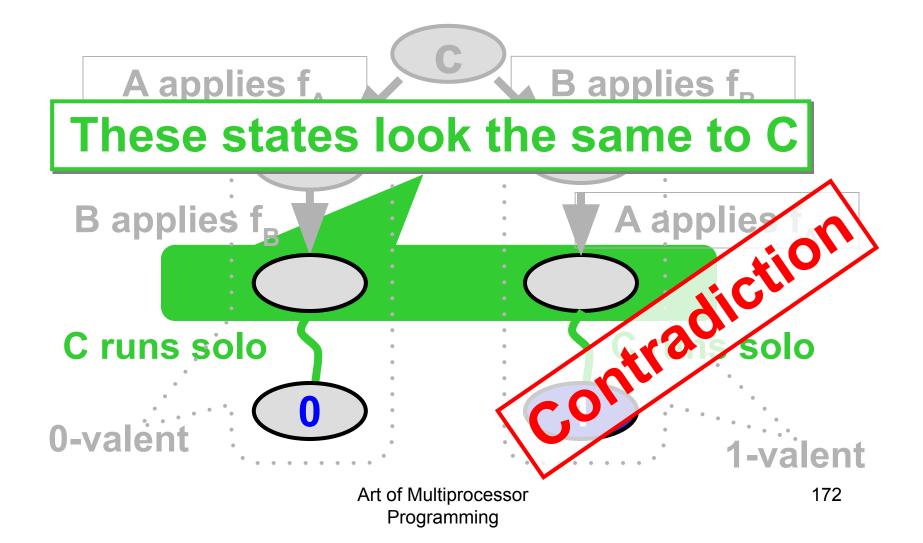
Meanwhile Back at the Critical State



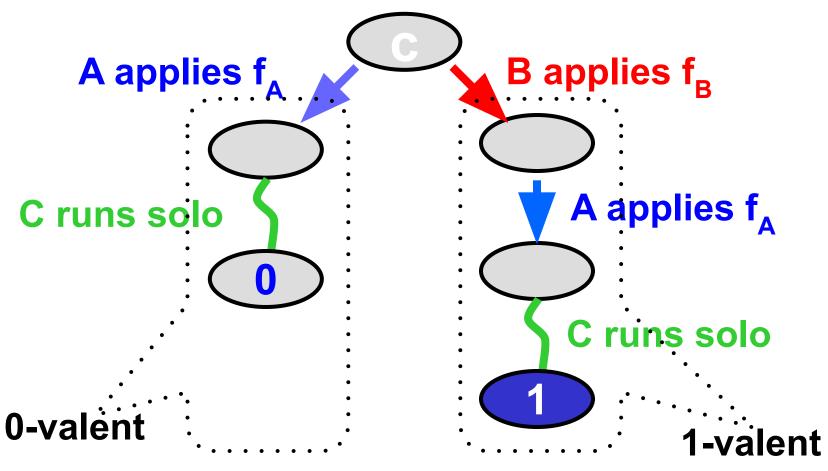
Maybe the Functions Commute



Maybe the Functions Commute

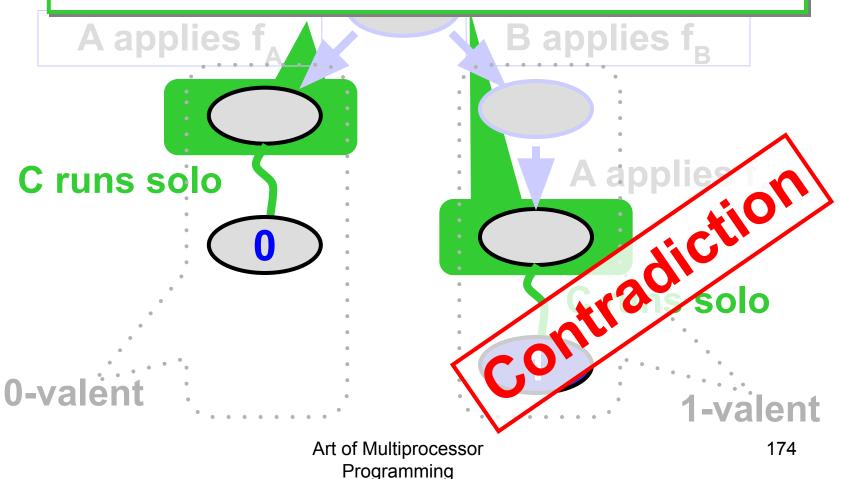


Maybe the Functions Overwrite



Maybe the Functions Overwrite

These states look the same to C



Impact

- Many early machines provided only these "weak" RMW instructions
 - Test-and-set (IBM 360)
 - Fetch-and-add (NYU Ultracomputer)
 - Swap (Original SPARCs)
- We now understand their limitations
 - But why do we want consensus anyway?

```
public abstract class RMWRegister {
private int value;
public boolean synchronized
   compareAndSet(int expected,
                 int update) {
  int prior = value;
  if (value==expected) {
   value = update; return true;
  return false;
  } ... }
```

```
public abstract class RMWRegister {
private int value;
public boolean synchronized
   compareAndSet(int expected,
                  int update)
 int prior = this.value;
 if (value==expected)
  this.value = update; return true;
return false; replace value if it's what we
                     expected, ...
```

```
public class RMWConsensus
     extends ConsensusProtocol {
private AtomicInteger r =
   new AtomicInteger(-1);
 public T decide(T value) {
 propose(value);
  r.compareAndSet(-1,i);
  return proposed[r.get()];
```

```
public class RMWConsensus
     extends ConsensusProtocol {
private AtomicInteger r =
   new AtomicInteger(-1);
 public T decide (T value
  propose (value)
  r.compareAndSet(-1)
  return proposed[r.ge
                        Initialized to -1
```

```
public class RMWConsensus
 extends ConsensusProtocol {
private AtomicInteger Y = swap in my
   new AtomicInteger (-1
 public T decide (T
  propose (value
  r.compareAndSet(-1,i);
  return proposed[r.get()];
```

```
public class RMWConsensus
 extends Consensus Protocol {
private AtomicInteger r = de winner's
   new AtomicInteger (-1) preference
 public T decide (T value)
  propose(value);
  r.compareAndSet
  return proposed[r.get()];
```

The Consensus Hierarchy

```
1 Read/Write Registers, Snapshots...
2 getAndSet, getAndIncrement, ...
∞ compareAndSet,...
```

Multiple Assignment

- Atomic k-assignment
- Solves consensus for 2k-2 threads
- Every even consensus number has an object (can be extended to odd numbers)

Lock-Freedom

- Lock-free:
 - in an infinite execution
 - infinitely often some method call finishes
- Pragmatic approach
- Implies no mutual exclusion



Lock-Free vs. Wait-free

 Wait-Free: each method call takes a finite number of steps to finish

 Lock-free: infinitely often some method call finishes







- Any wait-free implementation is lock-free.
- Lock-free is the same as wait-free if the execution is finite.

Lock-Free Implementations

- Lock-free consensus is as impossible as wait-free consensus
- All these results hold for lock-free algorithms also.

There is More: Universality

- Consensus is universal
- From *n*-thread consensus
 - Wait-free/Lock-free
 Linearizable
 n-threaded
 Implementation
 Of any sequenti
 Art of Multiprocessor

Programming



This work is licensed under a <u>Creative Commons</u> Attribution-ShareAlike 2.5 License.

You are free:

- **to Share** to copy, distribute and transmit the work
- **to Remix** to adapt the work

Under the following conditions:

- Attribution. You must attribute the work to "The Art of Multiprocessor Programming" (but not in any way that suggests that the authors endorse you or your use of the work).
- Share Alike. If you alter, transform, or build upon this work, you
 may distribute the resulting work only under the same, similar or a
 compatible license.
- For any reuse or distribution, you must make clear to others the license terms of this work. The best way to do this is with a link to
 - http://creativecommons.org/licenses/by-sa/3.0/.
- Any of the above conditions can be waived if you get permission from the copyright holder.
- Nothing in this license impairs or restricts the author's moral rights.