

Dynamic regression models: Introduction

EC 361–001

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Materials

Required readings:

- Hyndman & Athanasopoulos, ch. 7
 - sections 7.1—7.5.
- Hyndman & Athanasopoulos, ch. 10
 - section 10.1.

Motivation

Motivation

After studying **ARIMA** models, we have seen that we *can* (and *should*, when possible) include **information from past observations of a series** for modeling/forecasting purposes.

However, one **limitation** of such models is that they do not allow for the inclusion of **exogenous factors**.

By **exogenous** factors we mean including other **explanatory variables** that may be relevant to model and forecast a variable's behavior over time.

To this end, we turn our attention to **dynamic regression models**.

Time-series regression models

Time-series regression models

When applied to *time series data*, a **regression model** looks like the following:

$$y_t = \beta_0 + \beta_1 x_{1t} + \beta_2 x_{2t} + \cdots + \beta_k x_{kt} + \varepsilon_t$$

In words, the **dependent** variable y_t is a **linear function** of k **predictor/independent** variables, as well of a **stochastic** error term (ε_t), which is assumed to be **white noise** and **uncorrelated** with the RHS variables.

However, when it comes to time series data, **residual autocorrelation** is a common *issue*.

To *overcome* that issue, one *alternative* is to incorporate such serial correlation into our residuals through **ARIMA modeling**.

The basics

The basics

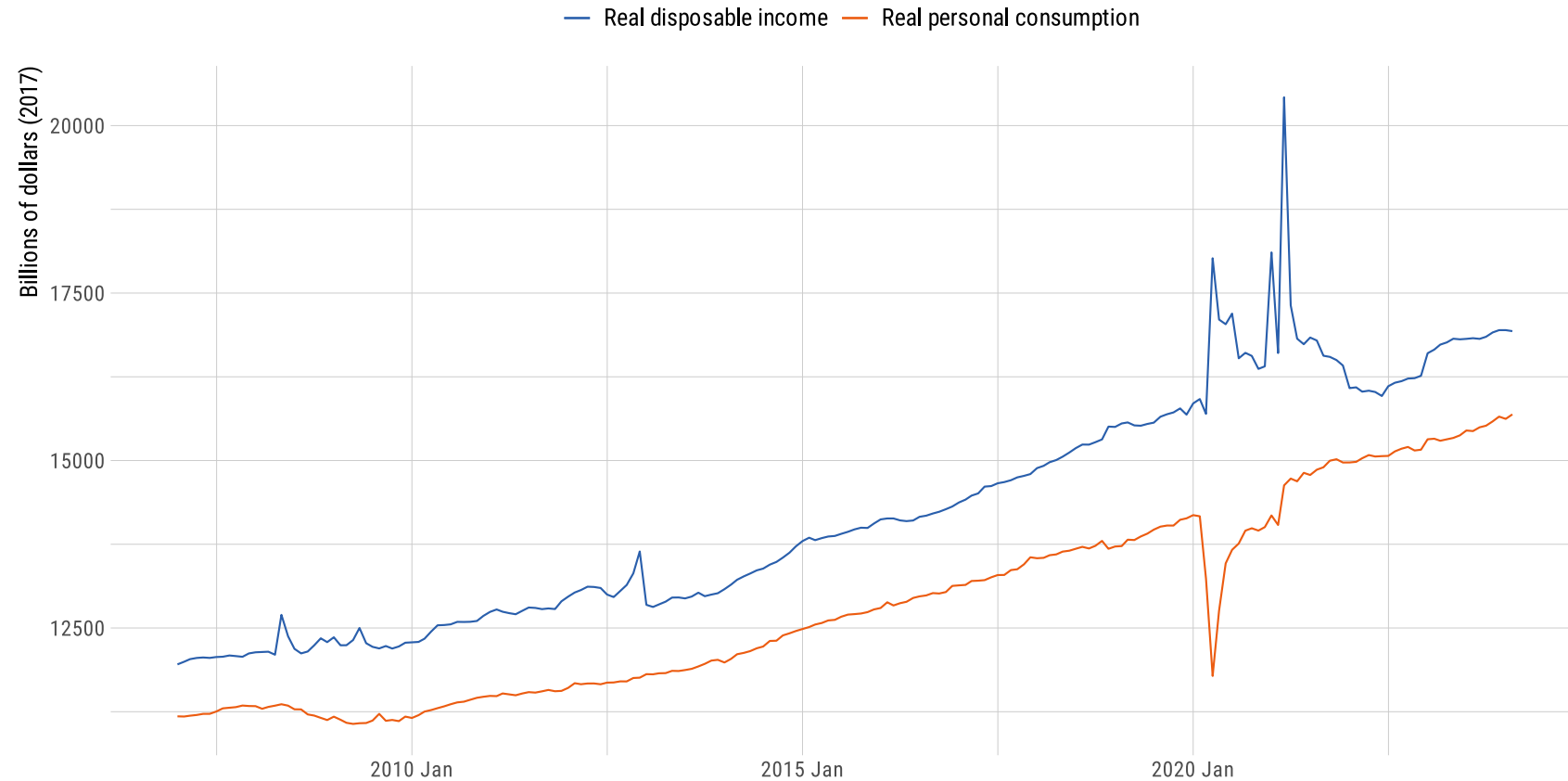
Starting from a **simple regression model**:

$$\text{Consumption}_t = \beta_0 + \beta_1 \text{Disposable Income}_t + \varepsilon_t$$

The basics

U.S. real personal consumption and real disposable income

01/2007-02/2024

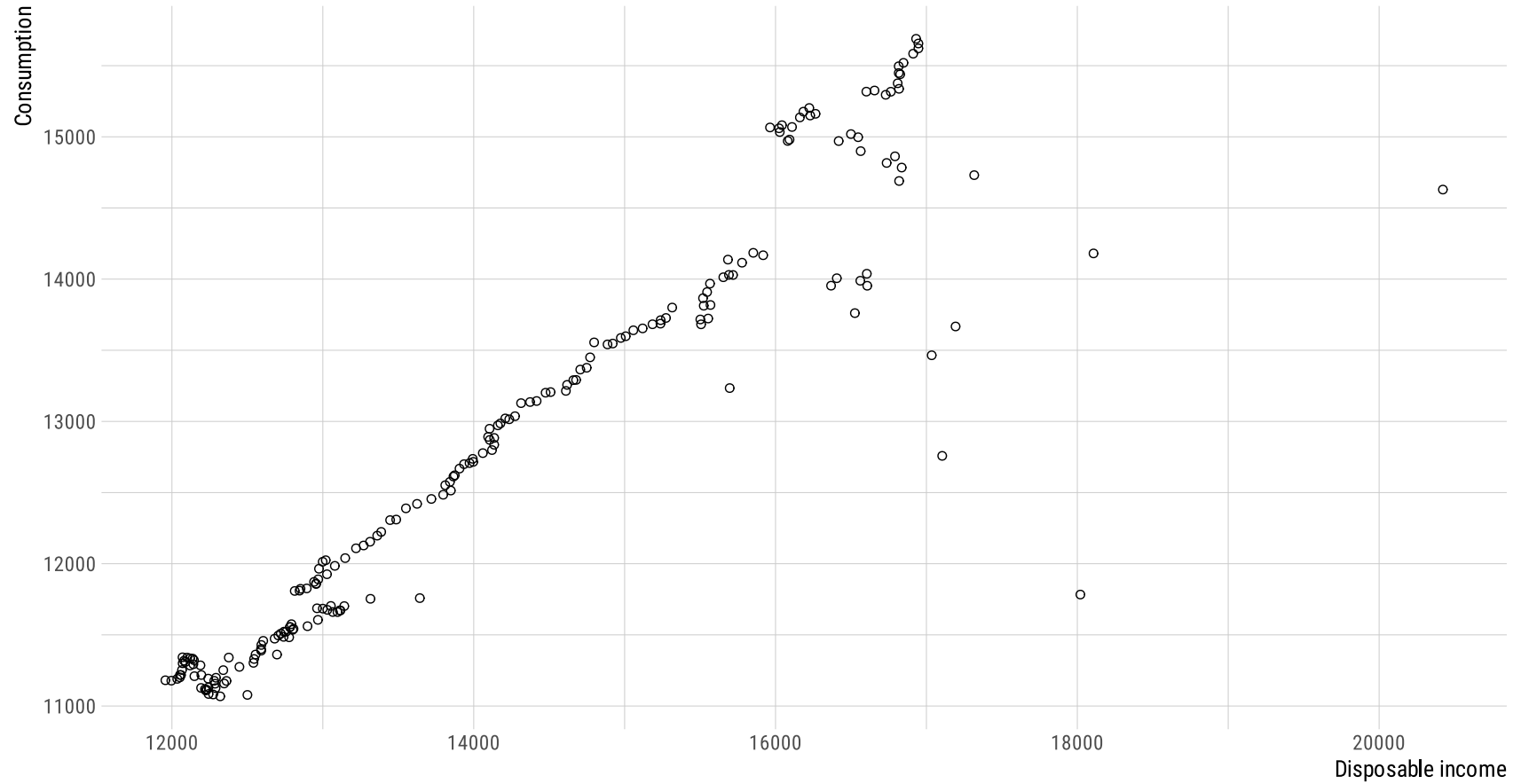


Source: U.S. Bureau of Economic Analysis (BEA).

The basics

U.S. real personal consumption and real disposable income

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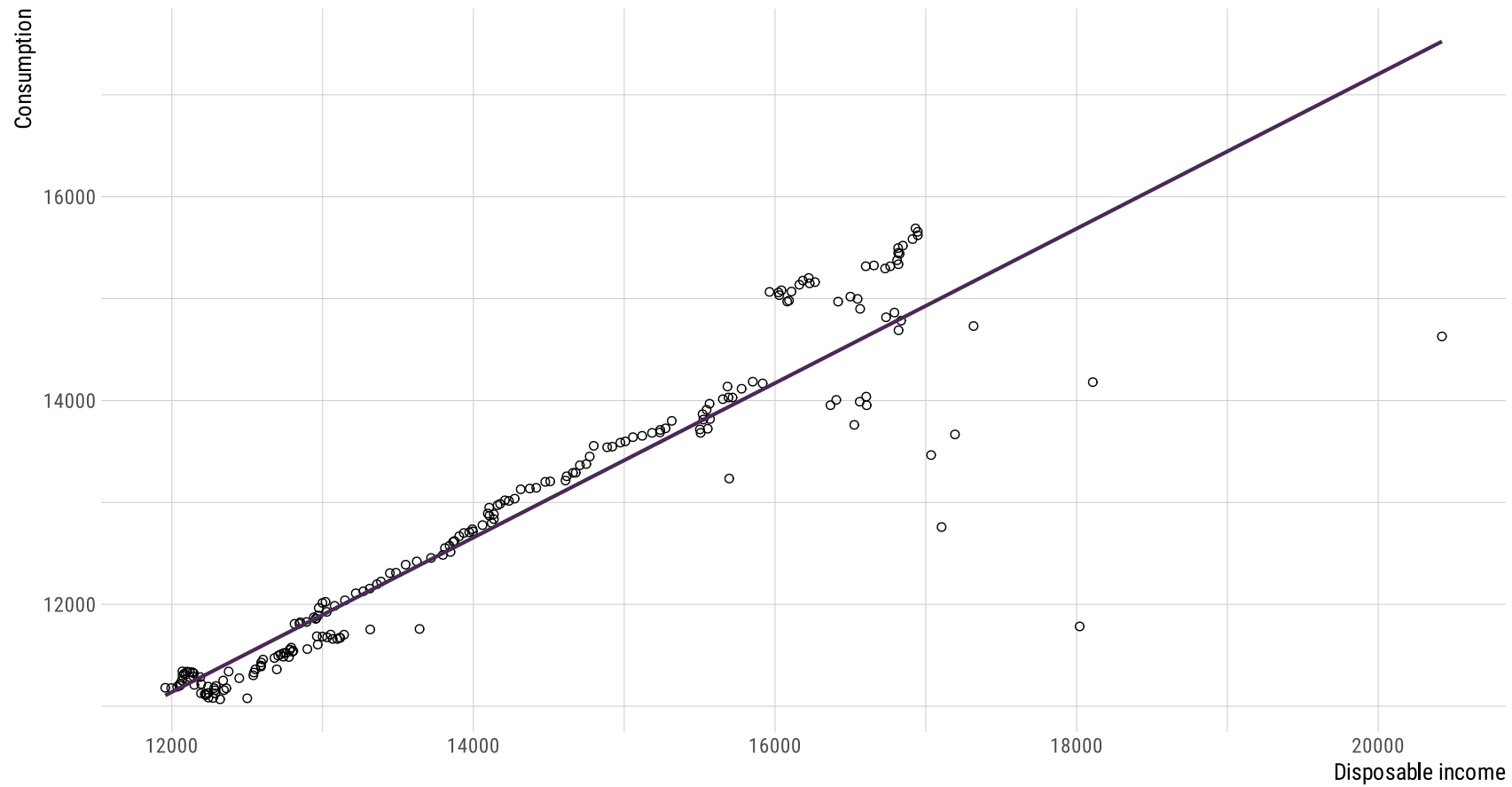


Source: U.S. Bureau of Economic Analysis (BEA).

The basics

U.S. real personal consumption and real disposable income

01/2007-02/2024



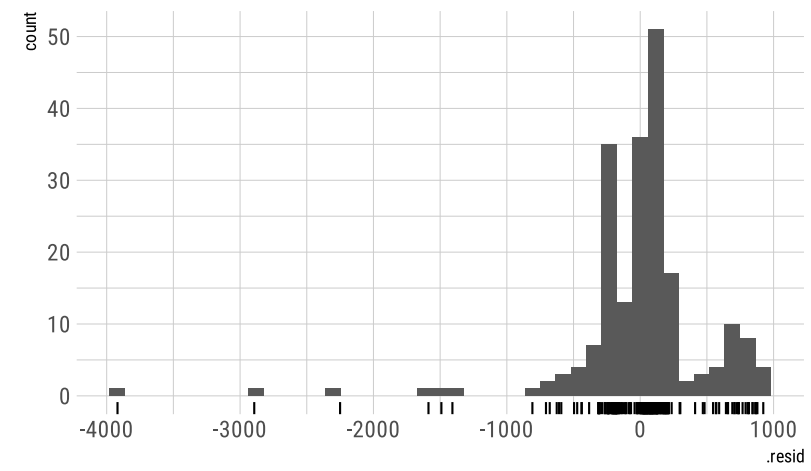
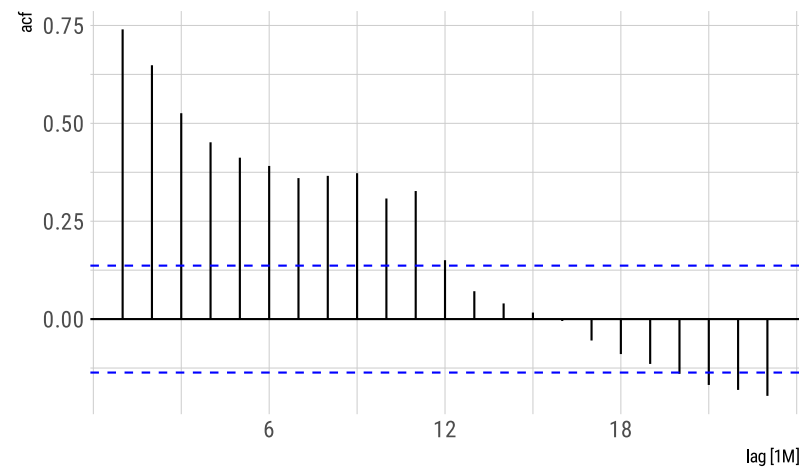
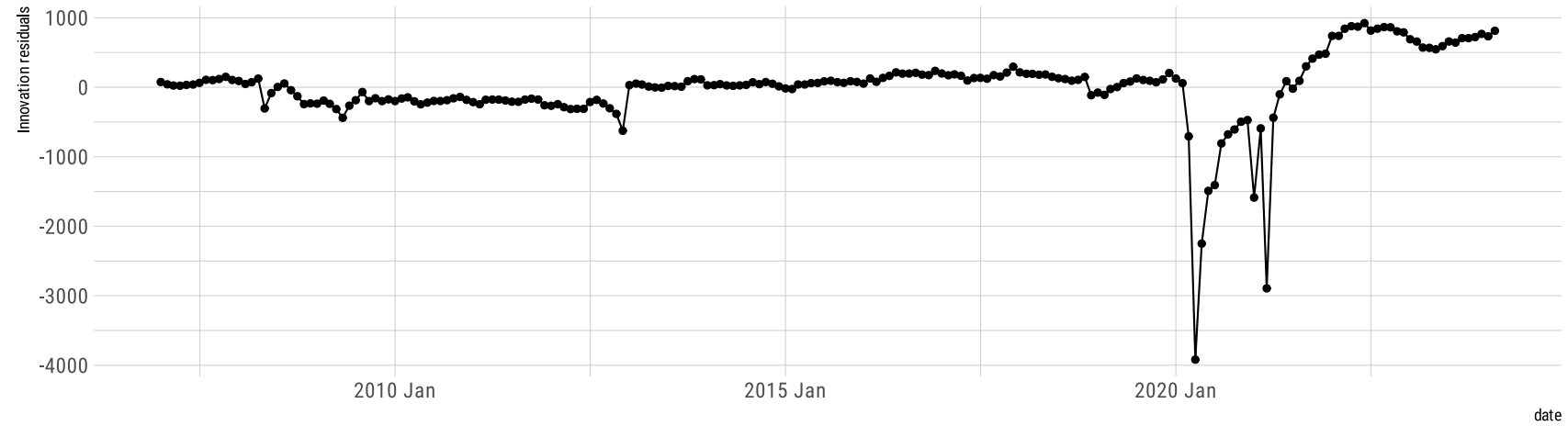
Source: U.S. Bureau of Economic Analysis (BEA).

In R, the `{fable}` package handles linear regression through the `TSLM()` function.

```
dat_ts >
  model(reg = TSLM(cons ~ inc)) >
  report()
```

```
#> Series: cons
#> Model: TSLM
#>
#> Residuals:
#>      Min       1Q   Median       3Q      Max
#> -3918.8  -180.9    48.7   153.5   922.6
#>
#> Coefficients:
#>              Estimate Std. Error t value Pr(>|t|)
#> (Intercept) 2.044e+03  3.087e+02   6.622 3.08e-10 ***
#> inc          7.579e-01  2.154e-02  35.191  < 2e-16 ***
#> ---
#> Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
#>
#> Residual standard error: 535.2 on 204 degrees of freedom
#> Multiple R-squared:  0.8586,    Adjusted R-squared:  0.8579
#> F-statistic: 1238 on 1 and 204 DF, p-value: < 2.22e-16
```

```
reg_fit ▷ gg_tsresiduals()
```



The basics

Are the residuals **white noise**?

```
reg_fit >
  augment() >
  features(.innov, ljung_box, lag = 10)
```

```
#> # A tibble: 1 × 3
#>   .model lb_stat lb_pvalue
#>   <chr>    <dbl>    <dbl>
#> 1 reg      481.        0
```

Useful predictors

Useful predictors

When a time series shows **trend** and/or **seasonality**, one good *first step* may be **explicitly** incorporating these features on a regression's right-hand side.

A **linear trend** may be modeled in the following way:

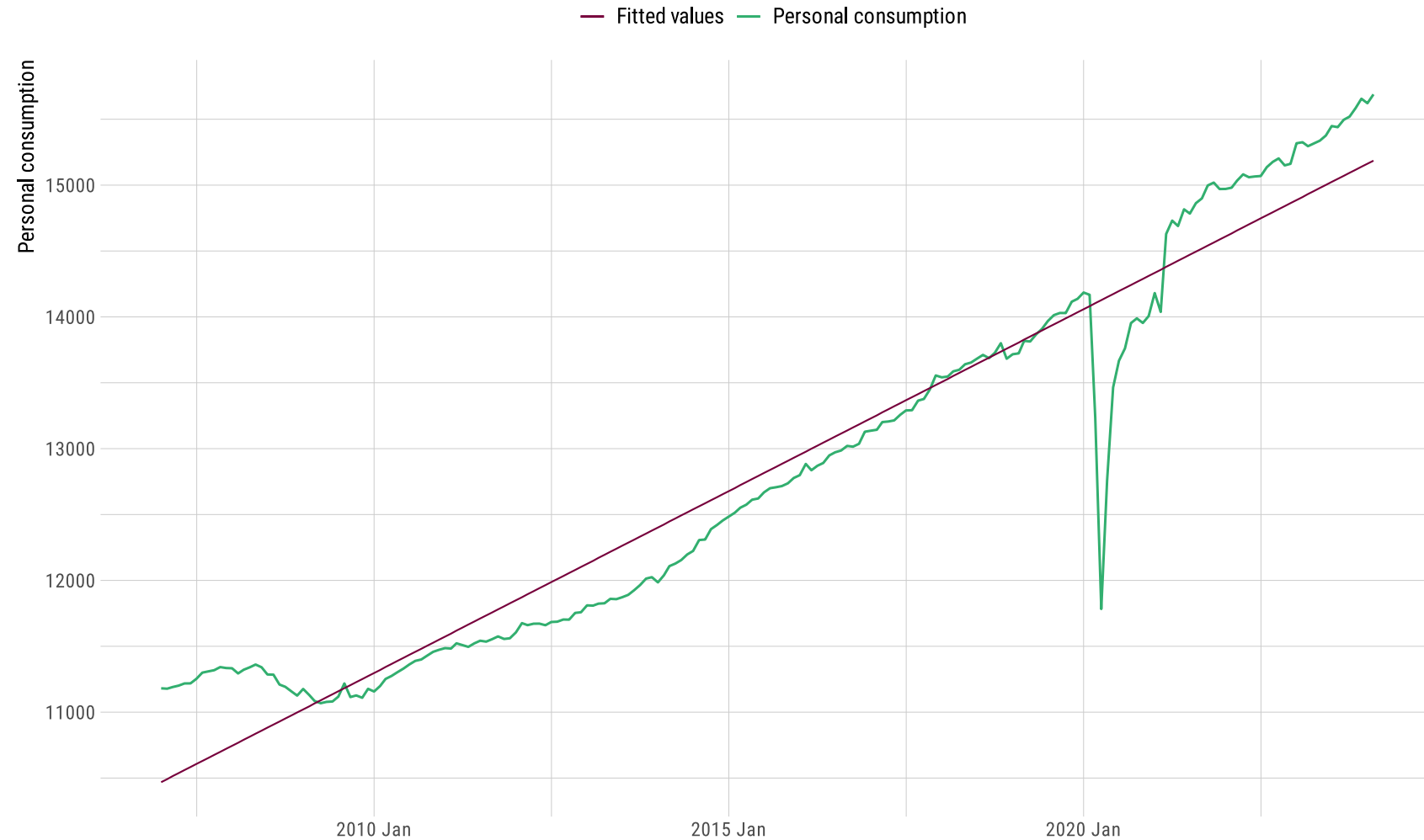
$$y_t = \beta_0 + \beta_1 t + \varepsilon_t$$

where $t = 1, 2, \dots, T$.


```
dat_ts ▷  
  model(reg_trend = TSLM(cons ~ trend())) ▷  
  report()
```

```
#> Series: cons  
#> Model: TSLM  
#>  
#> Residuals:  
#>      Min      1Q   Median      3Q      Max  
#> -2343.74 -195.48  -77.25   311.25   712.36  
#>  
#> Coefficients:  
#>              Estimate Std. Error t value Pr(>|t|)  
#> (Intercept) 10445.63      51.32   203.52  <2e-16 ***  
#> trend()      23.01       0.43    53.51  <2e-16 ***  
#> ---  
#> Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1  
#>  
#> Residual standard error: 367 on 204 degrees of freedom  
#> Multiple R-squared:  0.9335,    Adjusted R-squared:  0.9332  
#> F-statistic:  2864 on 1 and 204 DF, p-value: < 2.22e-16
```

Useful predictors



Useful predictors

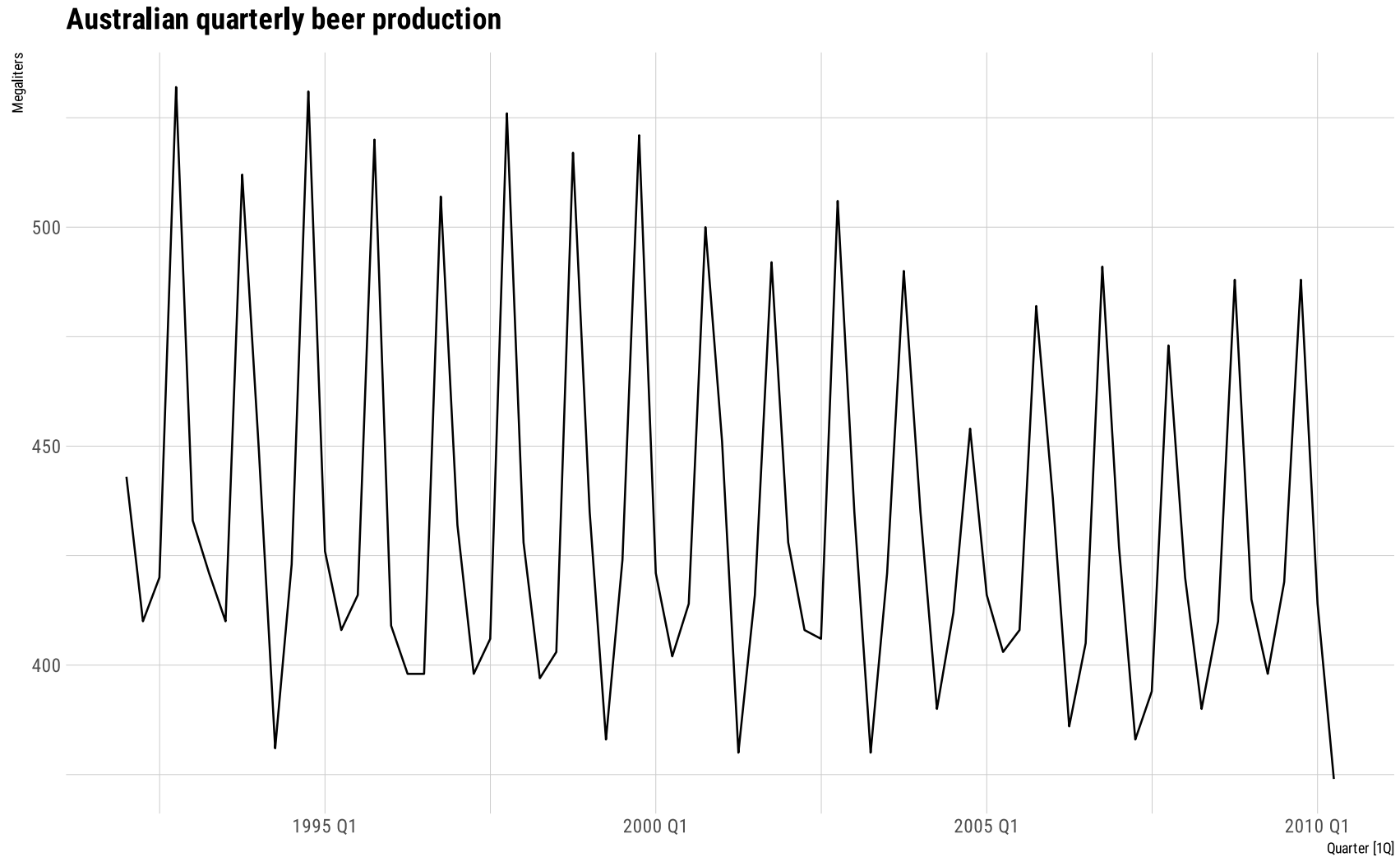
Seasonality can be easily handled with the use of **dummy (binary)** variables.

The idea is to **encode** specific seasonal periods with either 1 or 0 values.

- In **R**, the `TSLM()` function takes care of seasonal dummies for us.

In terms of **interpretation**, each of the coefficients associated with the dummy variables is a measure of the effect of *that category* **relative to** the *omitted* category.

Useful predictors



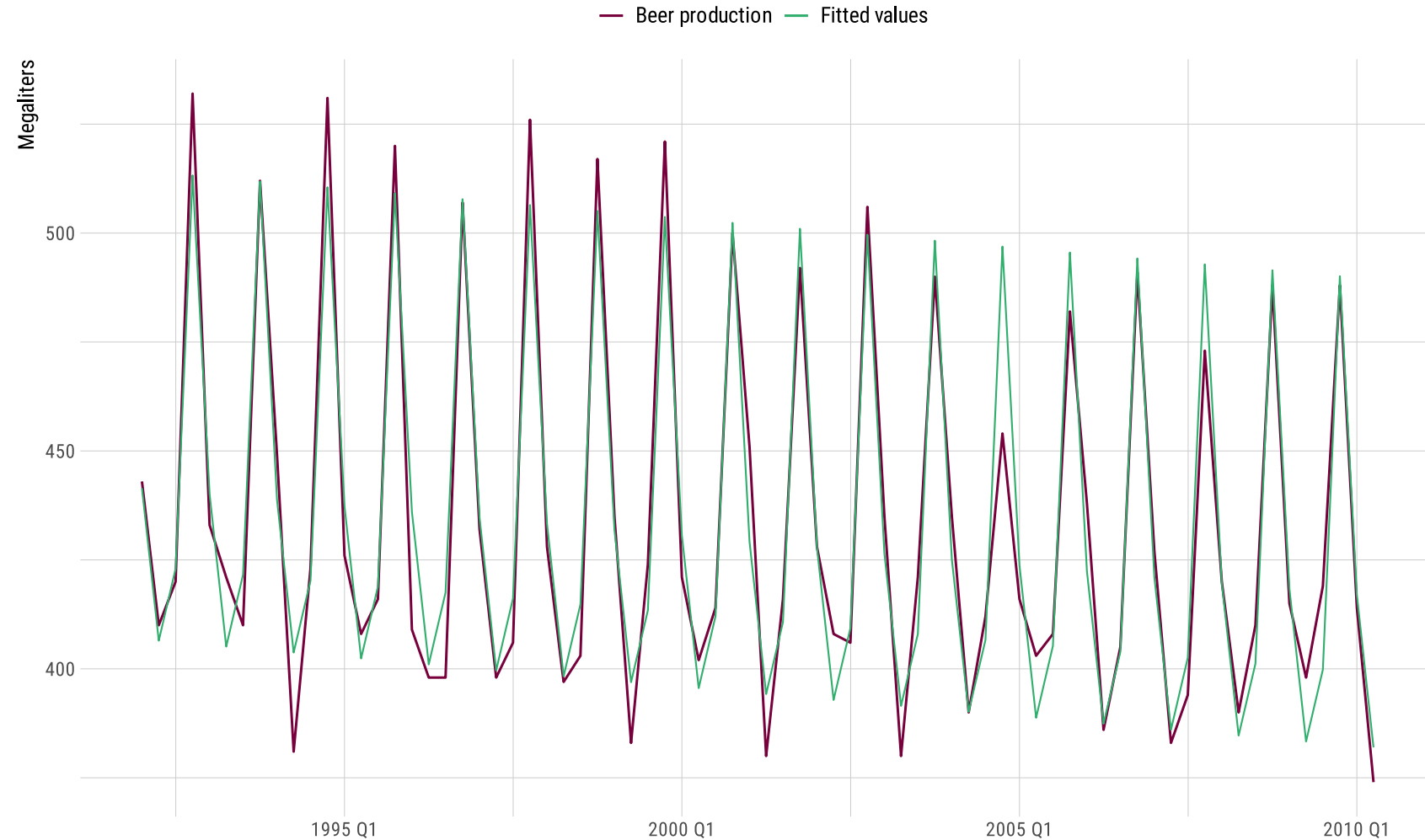
```
recent_production ▷  
  model(reg_season = TSLM(Beer ~ season())) ▷  
  report()
```

```
#> Series: Beer  
#> Model: TSLM  
#>  
#> Residuals:  
#>      Min      1Q   Median      3Q      Max  
#> -47.6667 -10.4167  -0.2997   8.7449  30.3333  
#>  
#> Coefficients:  
#>              Estimate Std. Error t value Pr(>|t|)  
#> (Intercept)    429.211      3.271  131.234 < 2e-16 ***  
#> season()year2  -35.000      4.625   -7.567 1.14e-10 ***  
#> season()year3  -17.822      4.689   -3.801 0.000305 ***  
#> season()year4   72.456      4.689   15.452 < 2e-16 ***  
#> ---  
#> Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1  
#>  
#> Residual standard error: 14.26 on 70 degrees of freedom  
#> Multiple R-squared:  0.8957,    Adjusted R-squared:  0.8912  
#> F-statistic: 200.3 on 3 and 70 DF, p-value: < 2.22e-16
```

```
recent_production ▷  
  model(reg_season = TSLM(Beer ~ trend() + season())) ▷  
  report()
```

```
#> Series: Beer  
#> Model: TSLM  
#>  
#> Residuals:  
#>      Min      1Q   Median      3Q      Max  
#> -42.9029  -7.5995  -0.4594   7.9908  21.7895  
#>  
#> Coefficients:  
#>              Estimate Std. Error t value Pr(>|t|)  
#> (Intercept)   441.80044    3.73353  118.333 < 2e-16 ***  
#> trend()       -0.34027    0.06657   -5.111 2.73e-06 ***  
#> season()year2 -34.65973    3.96832   -8.734 9.10e-13 ***  
#> season()year3 -17.82164    4.02249   -4.430 3.45e-05 ***  
#> season()year4  72.79641    4.02305   18.095 < 2e-16 ***  
#> ---  
#> Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1  
#>  
#> Residual standard error: 12.23 on 69 degrees of freedom  
#> Multiple R-squared:  0.9243,    Adjusted R-squared:  0.9199  
#> F-statistic: 210.7 on 4 and 69 DF, p-value: < 2.22e-16
```

Useful predictors



Useful predictors

```
recent_production ▷  
  model(reg_season = TSLM(Beer ~ trend() + season())) ▷  
  augment() ▷  
  features(.innov, ljung_box, lag = 2 * 4)
```

```
#> # A tibble: 1 × 3  
#>   .model    lb_stat lb_pvalue  
#>   <chr>      <dbl>    <dbl>  
#> 1 reg_season    10.4      0.240
```

Are residuals **white noise**?

Useful predictors

An alternative way of **modeling seasonality** is to incorporate **Fourier terms**.

These are *sine* and *cosine* terms used to approximate **periodic functions**.

As time series show *periodic* behavior, Fourier terms are well-suited for **seasonal series**.

If m is the seasonal period, then the first few Fourier terms are given by

$$\begin{aligned}x_{1,t} &= \sin\left(\frac{2\pi t}{m}\right), x_{2,t} = \cos\left(\frac{2\pi t}{m}\right), x_{3,t} = \sin\left(\frac{4\pi t}{m}\right), \\x_{4,t} &= \cos\left(\frac{4\pi t}{m}\right), x_{5,t} = \sin\left(\frac{6\pi t}{m}\right), x_{6,t} = \cos\left(\frac{6\pi t}{m}\right),\end{aligned}$$

Useful predictors

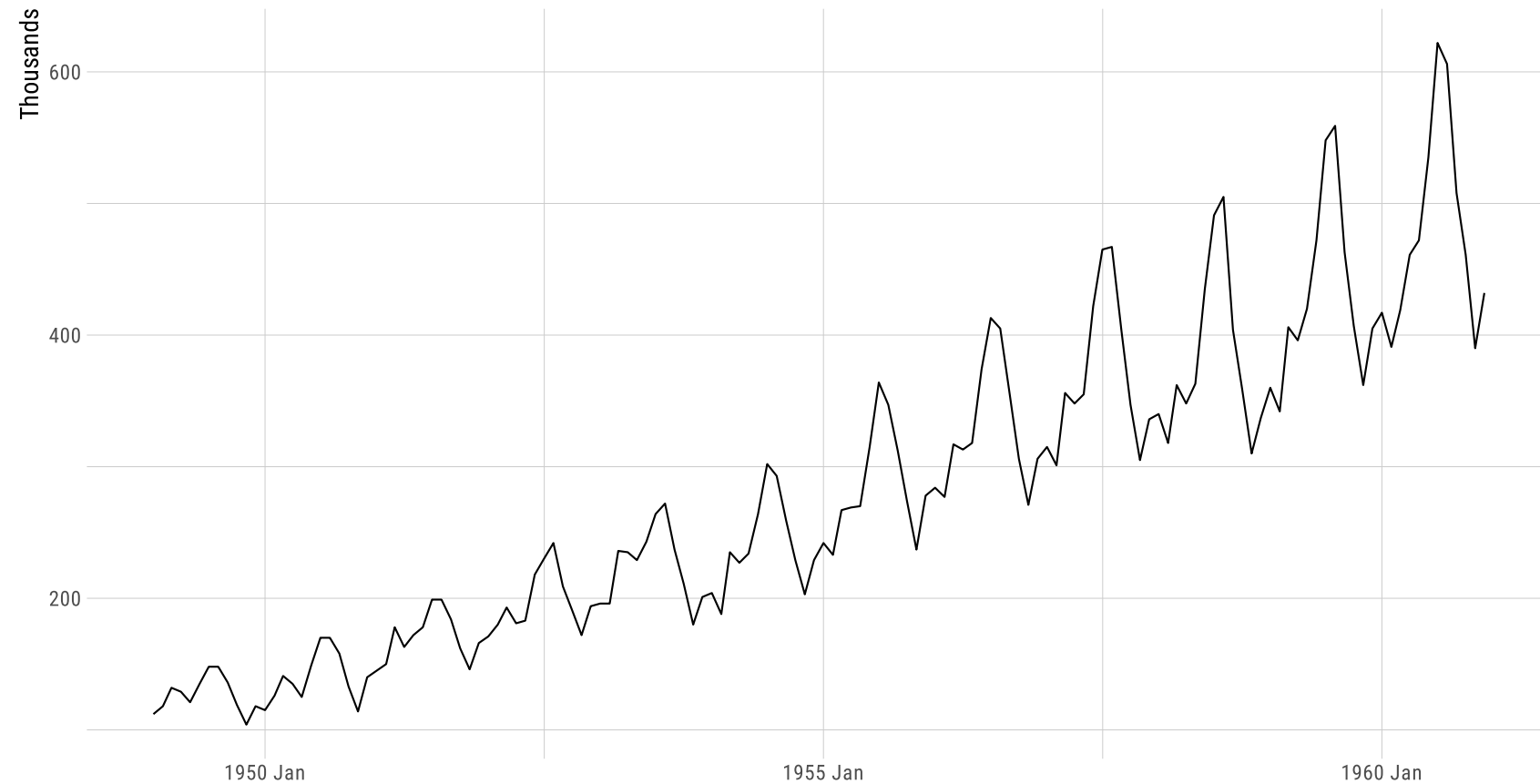
The **maximum** number of Fourier terms allowed is given by $K = m/2$, where m is the number of seasonal periods in a year.

A regression model containing Fourier terms is often called a **harmonic regression**.

Useful predictors

International airline passengers

Jan 1949 – Dec 1960

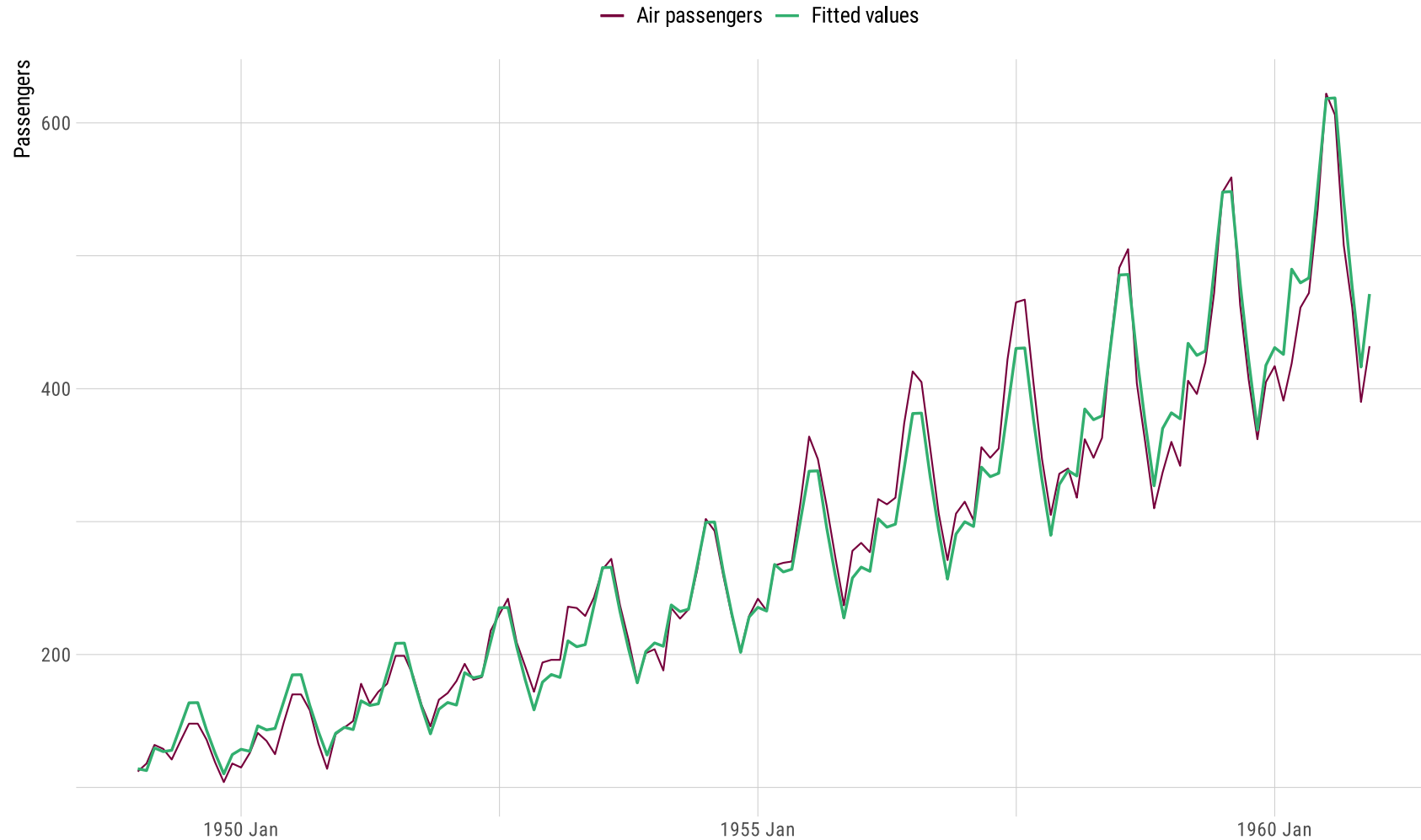


Source: Brown (1962).

```
air_ts >
  model(reg = TSLM(log(passengers) ~ trend() + season())) >
  report()
```

```
#> Series: passengers
#> Model: TSLM
#> Transformation: log(passengers)
#>
#> Residuals:
#>      Min       1Q   Median       3Q      Max
#> -0.156370 -0.041016  0.003677  0.044069  0.132324
#>
#> Coefficients:
#>              Estimate Std. Error t value Pr(>|t|)
#> (Intercept)   4.7267804   0.0188935 250.180 < 2e-16 ***
#> trend()        0.0100688   0.0001193  84.399 < 2e-16 ***
#> season()year2 -0.0220548   0.0242109  -0.911  0.36400
#> season()year3  0.1081723   0.0242118   4.468 1.69e-05 ***
#> season()year4  0.0769034   0.0242132   3.176  0.00186 **
#> season()year5  0.0745308   0.0242153   3.078  0.00254 **
#> season()year6  0.1966770   0.0242179   8.121 2.98e-13 ***
#> season()year7  0.3006193   0.0242212  12.411 < 2e-16 ***
#> season()year8  0.2913245   0.0242250  12.026 < 2e-16 ***
#> season()year9  0.1466899   0.0242294   6.054 1.39e-08 ***
#> season()year10 0.0085316   0.0242344   0.352  0.72537
#> season()year11 -0.1351861   0.0242400  -5.577 1.34e-07 ***
#> season()year12 -0.0213211   0.0242461  -0.879  0.38082
#> ---
#> Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
#>
#> Residual standard error: 0.0593 on 131 degrees of freedom
#> Multiple R-squared:  0.9835,    Adjusted R-squared:  0.982
#> F-statistic: 649.4 on 12 and 131 DF, p-value: < 2.22e-16
```

Useful predictors



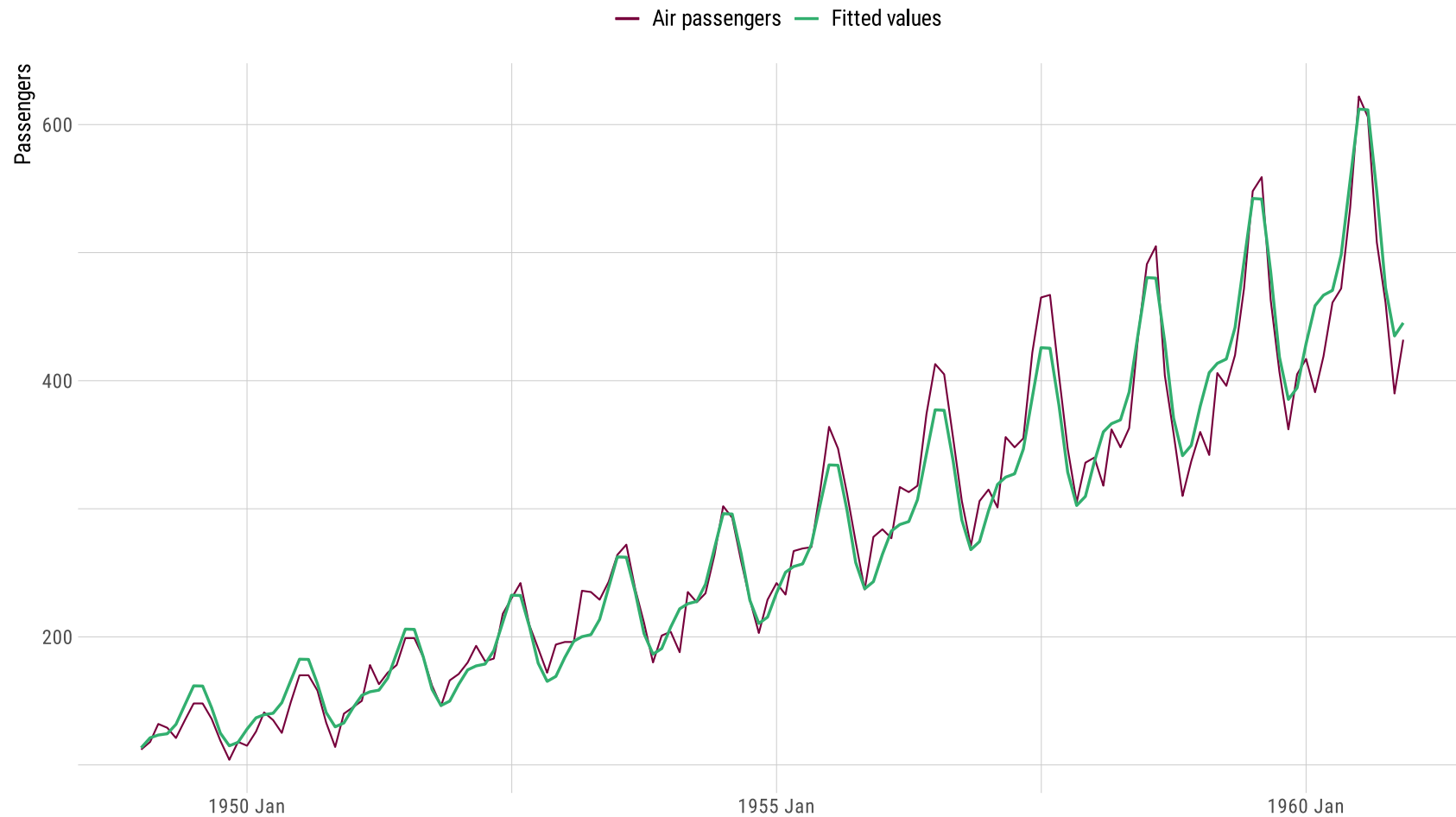
Useful predictors

```
air_ts >
  model(reg = TSLM(log(passengers) ~ trend() + fourier(K = 2))) >
  report()
```

```
#> Series: passengers
#> Model: TSLM
#> Transformation: log(passengers)
#>
#> Residuals:
#>      Min       1Q   Median       3Q      Max
#> -0.172892 -0.040363  0.002417  0.046796  0.164906
#>
#> Coefficients:
#>              Estimate Std. Error t value Pr(>|t|)
#> (Intercept)      4.8112150   0.0114209  421.262 < 2e-16 ***
#> trend()           0.0100822   0.0001368   73.725 < 2e-16 ***
#> fourier(K = 2)C1_12 -0.1474737   0.0080184  -18.392 < 2e-16 ***
#> fourier(K = 2)S1_12  0.0282074   0.0080334    3.511 0.000603 ***
#> fourier(K = 2)C2_12  0.0567457   0.0080184    7.077 6.79e-11 ***
#> fourier(K = 2)S2_12  0.0591195   0.0080207    7.371 1.41e-11 ***
#> ---
#> Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
#>
#> Residual standard error: 0.06803 on 138 degrees of freedom
#> Multiple R-squared:  0.9771,    Adjusted R-squared:  0.9763
#> F-statistic: 1177 on 5 and 138 DF, p-value: < 2.22e-16
```

Useful predictors

Using $K = 2$



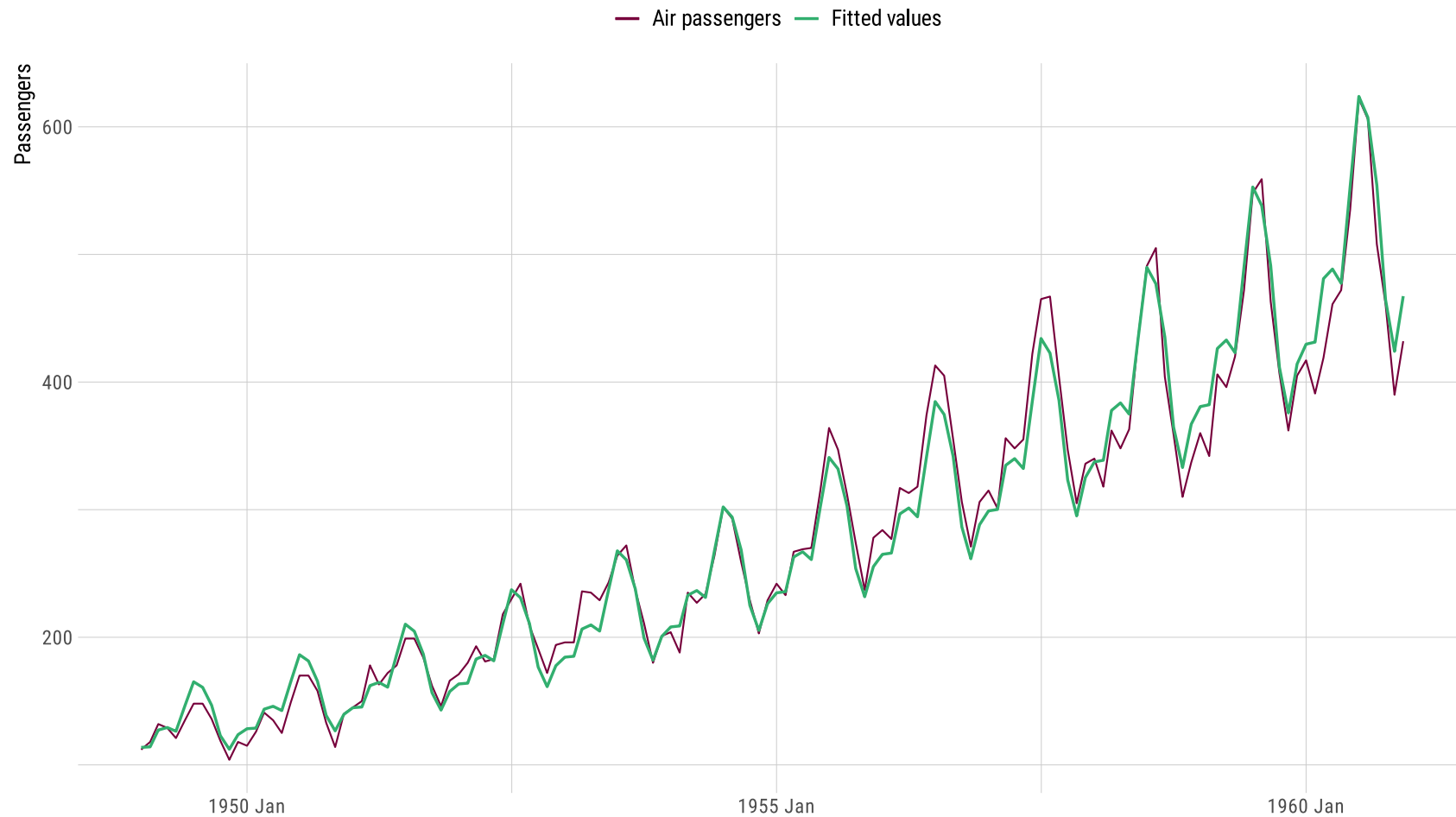
Useful predictors

```
air_ts >
  model(reg = TSLM(log(passengers) ~ trend() + fourier(K = 4))) >
  report()
```

```
#> Series: passengers
#> Model: TSLM
#> Transformation: log(passengers)
#>
#> Residuals:
#>      Min       1Q   Median       3Q      Max
#> -0.1379894 -0.0416537  0.0004086  0.0446304  0.1338178
#>
#> Coefficients:
#>              Estimate Std. Error t value Pr(>|t|)
#> (Intercept)      4.8121301   0.0102284  470.467 < 2e-16 ***
#> trend()           0.0100696   0.0001225   82.208 < 2e-16 ***
#> fourier(K = 4)C1_12 -0.1474864   0.0071785  -20.546 < 2e-16 ***
#> fourier(K = 4)S1_12  0.0281603   0.0071920    3.916 0.000143 ***
#> fourier(K = 4)C2_12  0.0567331   0.0071785    7.903 8.84e-13 ***
#> fourier(K = 4)S2_12  0.0590977   0.0071806    8.230 1.46e-13 ***
#> fourier(K = 4)C3_12 -0.0087300   0.0071785   -1.216 0.226072
#> fourier(K = 4)S3_12 -0.0272914   0.0071785   -3.802 0.000217 ***
#> fourier(K = 4)C4_12  0.0111072   0.0071785    1.547 0.124154
#> fourier(K = 4)S4_12 -0.0319853   0.0071778   -4.456 1.75e-05 ***
#> ---
#> Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
#>
#> Residual standard error: 0.0609 on 134 degrees of freedom
#> Multiple R-squared:  0.9822,    Adjusted R-squared:  0.981
#> F-statistic: 819.9 on 9 and 134 DF, p-value: < 2.22e-16
```


Useful predictors

Using $K = 4$



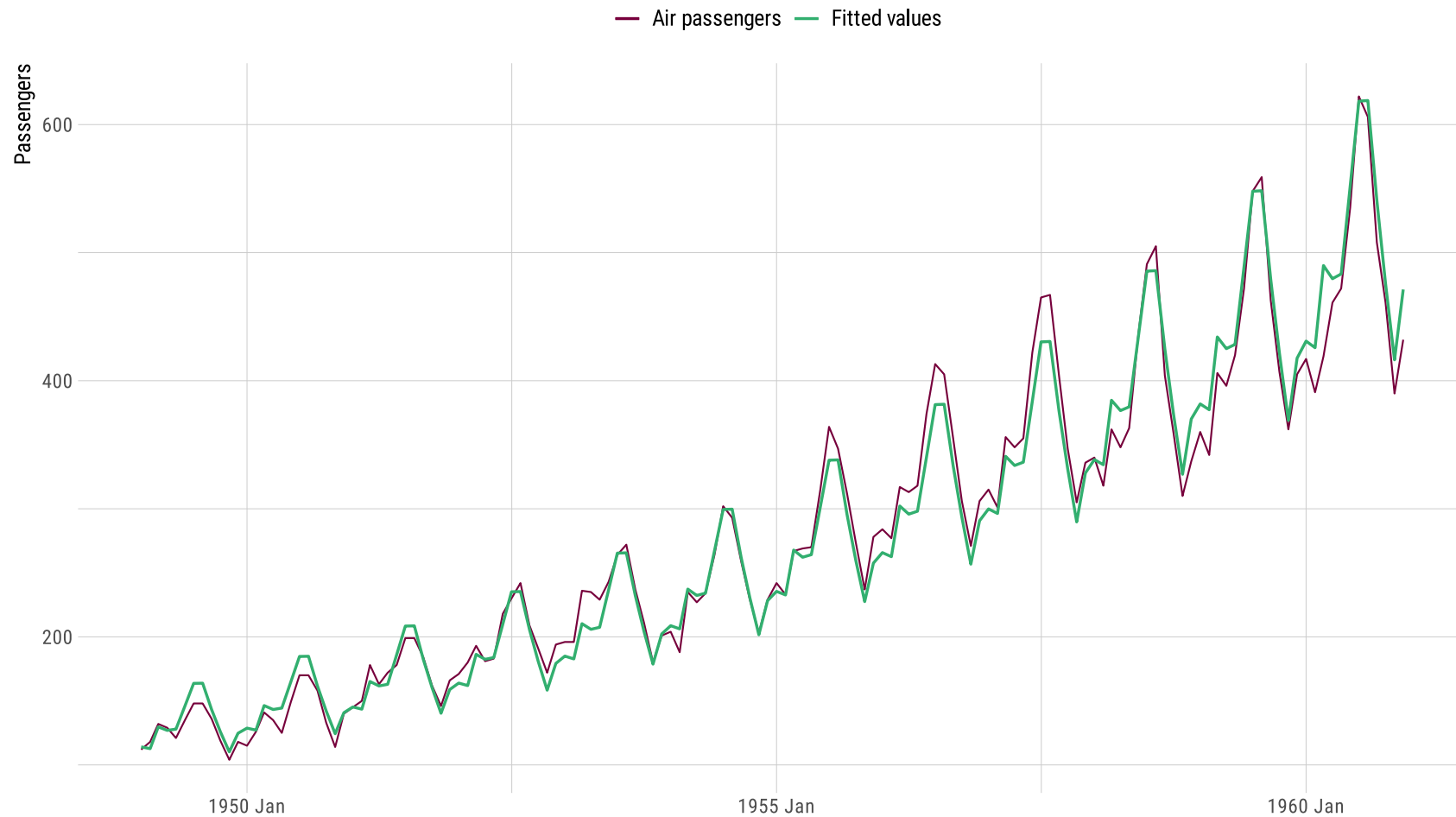
Useful predictors

```
air_ts >
  model(reg = TSLM(log(passengers) ~ trend() + fourier(K = 6))) >
  report()
```

```
#> Series: passengers
#> Model: TSLM
#> Transformation: log(passengers)
#>
#> Residuals:
#>      Min       1Q   Median       3Q      Max
#> -0.156370 -0.041016  0.003677  0.044069  0.132324
#>
#> Coefficients:
#>              Estimate Std. Error t value Pr(>|t|)
#> (Intercept)      4.8121876   0.0099616  483.076 < 2e-16 ***
#> trend()           0.0100688   0.0001193   84.399 < 2e-16 ***
#> fourier(K = 6)C1_12 -0.1474871   0.0069900  -21.100 < 2e-16 ***
#> fourier(K = 6)S1_12  0.0281573   0.0070032    4.021 9.74e-05 ***
#> fourier(K = 6)C2_12  0.0567323   0.0069900    8.116 3.06e-13 ***
#> fourier(K = 6)S2_12  0.0590963   0.0069920    8.452 4.81e-14 ***
#> fourier(K = 6)C3_12 -0.0087308   0.0069900   -1.249  0.21388
#> fourier(K = 6)S3_12 -0.0272922   0.0069900   -3.904  0.00015 ***
#> fourier(K = 6)C4_12  0.0111064   0.0069900    1.589  0.11450
#> fourier(K = 6)S4_12 -0.0319857   0.0069893   -4.576 1.09e-05 ***
#> fourier(K = 6)C5_12  0.0059083   0.0069900    0.845  0.39951
#> fourier(K = 6)S5_12 -0.0212636   0.0069891   -3.042  0.00284 **
#> fourier(K = 6)C6_12 -0.0029362   0.0049423   -0.594  0.55347
#> ---
#> Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
#>
#> Residual standard error: 0.0593 on 131 degrees of freedom
```

Useful predictors

Using $K = 6$



ARIMA errors

ARIMA errors

In case we have evidence of residual serial correlation, we may write a time-series regression model as follows:

$$y_t = \beta_0 + \beta_1 x_{1t} + \beta_2 x_{2t} + \cdots + \beta_k x_{kt} + \eta_t$$

where η_t is assumed to be **autocorrelated**, and follows an **ARIMA** process.

For instance, if η_t follows an **ARIMA(1, 1, 1)** process, it can be expressed as

$$\eta'_t = c + \phi_1 \eta'_{t-1} + \theta_1 \varepsilon_{t-1} + \varepsilon_t$$

where ε_t follows a white-noise process.

ARIMA errors

Now, the model has **two error terms**:

1. The error from the *regression model*, which we denote by η_t ; and
2. The error term from the *ARIMA* model, which we denote by ε_t .

Only ε_t is assumed to be white noise here.

ARIMA errors

Whenever a regression's **error term** shows **serial correlation**, several problems arise:

- As relevant information is left to the error term, the model is **not well specified**;
 - ***Autocorrelation is information!***
- Inference is unreliable;
 - *p-values, t-statistics* are **biased**.

Therefore, applying **Ordinary Least Squares** (OLS) estimation in models with residual autocorrelation is **problematic**.

Instead, we should **model** the autocorrelations in the residual term, so we incorporate such information into our modeling/forecasting.

ARIMA errors

An important **consideration** when estimating a regression with *ARIMA errors* is that all of the variables in the model must first be **stationary**.

Thus, running a unit-root test (such as KPSS) is **mandatory**.

One **common practice** is to difference **all** regression variables if **any** of them is *non-stationary*.

- The resulting model is then called a “*model in differences*.”

On the other hand, a “*model in levels*” denotes a regression with all included variables being stationary *without* any transformation needed.

ARIMA errors

In **R**, the `{fable}` package handles dynamic regression models with the `ARIMA()` function.

For example, the code

```
ARIMA(y ~ x + pdq(1,1,0))
```

fits a dynamic regression for y_t , controlling for one exogenous variable (x_t), assuming that the residual term η_t follows an **ARIMA(1, 1, 0)** process.

- Let us write out this model.

Next time: More on dynamic regression