

Top Two Algorithms Revisited

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Section 1

Motivation

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Goal: Identify the item having the highest averaged return.

Applications:

- A/B testing for online marketing,
- phase II/III of clinical trials,
- crop-management tasks.



Statistical model

Frequent distributions: parametric, e.g. Bernoulli or Gaussian.

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Nature is bounded:

☞ Bounded distributions

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Crop-management

Simulator of crop yield:

- 30 years of historical field data for 42 different plants and soil conditions,
- model complex biophysical processes.

Case study:

- maize fields with Sub-Saharan soil conditions,
- fixed fertilization policy,
- identify the best planting date.

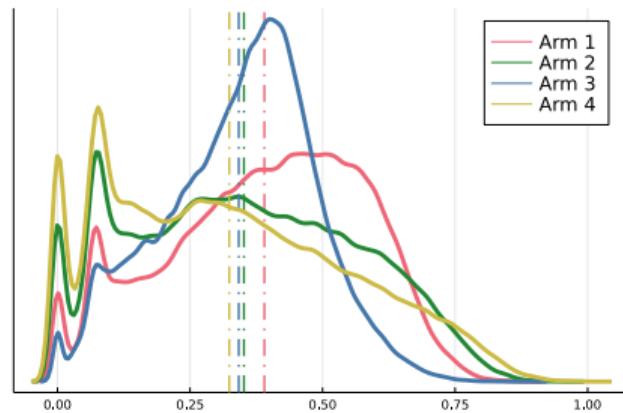


Figure: Decision Support System for Agrotechnology Transfer

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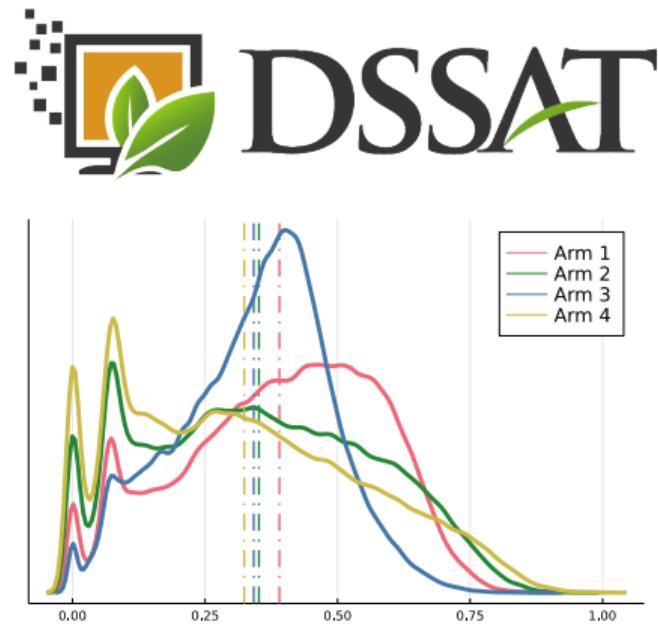


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Section 2

Problem statement

Stochastic multi-armed bandits

K arms, F_i cdf of arm i with mean $m(F_i) := \mathbb{E}_{X \sim F_i}[X]$.

At time n , pull $I_n \in [K]$ and observe $X_{n,I_n} \sim F_{I_n}$.

Distributions \mathcal{F} with set of possible means \mathcal{I} :

- bounded in $[0, B]$,
- sub-exponential single parameter exponential families (SPEF, e.g. Bernoulli, Gaussian with known variance, etc).

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Best-arm identification (BAI)

Goal: identify the best arm $i^* = \arg \max_i m(F_i)$ with confidence δ .

- sampling rule, $I_n \in [K]$,
- recommendation rule, $\hat{i}_n \in [K]$,
- stopping rule, τ_δ .

Objective: Minimize $\mathbb{E}_{\mathbf{F}}[\tau_\delta]$ for δ -correct algorithms

$$\mathbb{P}_{\mathbf{F}}[\tau_\delta < +\infty, \hat{i}_{\tau_\delta} \neq i^*] \leq \delta .$$

? What is the best one could achieve ? Agrawal et al. (2020)

☞ For all δ -correct algorithm, for all $\mathbf{F} \in \mathcal{F}^K$,

$$\mathbb{E}_{\mathbf{F}}[\tau_\delta] \geq T^*(\mathbf{F}) \log(1/(2.4\delta)) .$$

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Characteristic time

$$T^*(\mathbf{F})^{-1} := \sup_{w \in \Delta_K} \min_{i \neq i^*} \inf_{u \in \mathcal{I}} \left\{ w_{i^*} \mathcal{K}_{\text{inf}}^-(F_{i^*}, u) + w_i \mathcal{K}_{\text{inf}}^+(F_i, u) \right\} ,$$

Δ_K simplex, $\mathcal{K}_{\text{inf}}^\pm(F, u) := \inf \{ \text{KL}(F, G) \mid G \in \mathcal{F}, m(G) \gtrless u \}$.

? How can we reach the lower bound $T^*(\mathbf{F})$?

☞ Empirical sampling proportions converging towards maximizer.

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Asymptotic β -optimality

Sub-class of algorithms: β proportion of samples to the best arm.

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What is the best one could achieve ? Russo (2016)

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achieved for a unique β -optimal allocation w^β when i^* is unique.

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How does it relate to asymptotic optimality ?

☞ $T^*(\mathbf{F}) = \min_{\beta \in (0,1)} T_\beta^*(\mathbf{F})$ and $T_{1/2}^*(\mathbf{F}) \leq 2T^*(\mathbf{F})$.

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Contributions

- ① Generic and modular analysis of Top Two algorithms.
- ② Asymptotically β -optimal instances (bounded and SPEF).
- ③ Competitive performance on a real-world non-parametric task.

Related work

Top Two (TT) algorithms for Gaussians:

- Russo (2016), TPPS and TTS (Probability/Thompson Sampling),
- Qin et al. (2017), TTEI (Expected Improvement),
- Shang et al. (2020), T3C (Transportation Cost).

Other BAI algorithms:

- Kalyanakrishnan et al. (2012), (kl)-LUCB algorithm for bounded distributions,
- Agrawal et al. (2020), Track-and-Stop for heavy-tailed distributions,
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Section 3

Top Two algorithms

Stopping-recommendation pair

? Which arm should we recommend ?

$$\hat{i}_n = \arg \max_i \mu_{n,i} \quad \text{with} \quad \mu_{n,i} = m(F_{n,i}),$$

$$N_{n,i} = \sum_{t \in [n]} \mathbb{1}(I_t = i) \text{ and } F_{n,i} = \frac{1}{N_{n,i}} \sum_{t \in [n]} \delta_{X_{t,I_t}} \mathbb{1}(I_t = i).$$

? How to stop to obtain δ -correct algorithm ?

☞ calibrated GLR stopping rule

$$\tau_\delta = \inf \left\{ n \in \mathbb{N} \mid \min_{j \neq \hat{i}_n} W_n(\hat{i}_n, j) > \beta(n, \delta) \right\}, \quad (1)$$

where the empirical transportation cost between arms (i, j) is

$$W_n(i, j) = \inf_{x \in \mathcal{X}} [N_{n,i} \mathcal{K}_{\inf}^-(F_{n,i}, x) + N_{n,j} \mathcal{K}_{\inf}^+(F_{n,j}, x)].$$

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Sampling rule

? How should we pull arms with the β constraint ?

☞ **Top Two sampling rule** with fixed β !

- 1: Choose a **leader** $B_n \in [K]$
- 2: $U \sim \mathcal{U}([0, 1])$
- 3: **if** $U < \beta$ **then**
- 4: $I_n = B_n$
- 5: **else**
- 6: Choose a **challenger** $C_n \in [K] \setminus \{B_n\}$
- 7: $I_n = C_n$
- 8: **end if**
- 9: **Output:** next arm to sample I_n

Choices of leader

Empirical Best (**EB**), deterministic,

$$B_n^{\text{EB}} \in \arg \max_{i \in [K]} \mu_{n-1,i} .$$

Thompson Sampling (**TS**), randomized with a sampler Π_n on \mathcal{I}^K ,

$$B_n^{\text{TS}} \in \arg \max_{i \in [K]} \theta_i \quad \text{where} \quad \theta \sim \Pi_{n-1} .$$

Choices of challenger given leader B_n

Transportation Cost (**TC**), deterministic,

$$C_n^{\text{TC}} \in \arg \min_{j \neq B_n} W_{n-1}(B_n, j) .$$

Transportation Cost Improved (**TCI**), deterministic,

$$C_n^{\text{TCI}} \in \arg \min_{j \neq B_n} W_{n-1}(B_n, j) + \log N_{n-1,j} .$$

Re-Sampling (**RS**), randomized, repeat $\theta \sim \Pi_{n-1}$ until

$$C_n^{\text{RS}} \in \arg \max_{i \in [K]} \theta_i \not\ni B_n .$$

Novelties

Six instances denoted by β -[leader]-[challenger].

Literature:

- TTTS and T3C corresponds to β -TS-RS and β -TS-TC.
- β -optimality for Gaussian distributions.

Novelties:

- Fully deterministic instances are possible with the EB leader.
- The TCI challenger is more stable than the TC one by penalizing over-sampled challengers.
- Dirichlet sampler for BAI with bounded distributions.
- Bounded distributions and SPEF of sub-exponential distributions.

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Section 4

Bounded distributions

Deterministic instances

Threshold ensuring δ -correctness of the stopping rule (1)

$$\beta(n, \delta) = \log(1/\delta) + 2 \log(1 + n/2) + 2 + \log(K - 1). \quad (2)$$

Computing transportation costs between arm i and arm j :

$$N_{n,i} \mathcal{K}_{\inf}^+(F_{n,i}, x) = \sup_{\lambda \in [0,1]} \sum_{t \in [N_{n,i}]} \log \left(1 - \lambda \frac{X_{t,i} - x}{B - x} \right).$$

Randomized instances

? How to design a sampler over $(0, B)^K$? [Riou and Honda \(2020\)](#)

☞ **Dirichlet sampler:** $\Pi_n = \bigtimes_{i \in [K]} \Pi_{n,i}$ where $\Pi_{n,i}$ uses the empirical cdf $F_{n,i}$ augmented by $\{0, B\}$. The sampler $\Pi_{n,i}$ returns

$$\sum_{t \in [N_{n,i}]} w_t X_{t,i} + B w_{N_{n,i}+1} \quad \text{with} \quad \boldsymbol{w} \sim \text{Dir}(\mathbf{1}_{N_{n,i}+2}).$$

Sample complexity upper bound

Theorem

Combining the stopping rule (1) with threshold (2) and a Top Two algorithm with $\beta \in (0, 1)$, instantiated with any pair of leader/challenger introduced above, yields a δ -correct algorithm which is asymptotically β -optimal for all $\mathbf{F} \in \mathcal{F}^K$ with $m(\mathbf{F}) \in (0, B)^K$ and $\Delta_{\min} := \min_{i \neq j} |m(F_i) - m(F_j)| > 0$.

Distinct means:

- Uncommon, used for sufficient exploration of Top Two algorithms.
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Comparing instances

Limitations:

- For large n , the RS challenger is computationally costly and the TS leader is expensive.
- β -EB-TC is too greedy and lacks robustness for moderate regime.

Advantages:

- The EB leader is computationally efficient and the TC(I) challengers are not costlier than computing the stopping rule.
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Section 5

Modular sample complexity analysis

Reaching asymptotic β -optimality

- ? How can we reach asymptotic β -optimality ?
- ☞ Empirical proportions converging towards maximizer w^β .

Convergence time T_β^ε defined as

$$T_\beta^\varepsilon := \inf \left\{ T \geq 1 \mid \forall n \geq T, \max_{i \in [K]} \left| \frac{N_{n,i}}{n} - w_i^\beta \right| \leq \varepsilon \right\} .$$

For any sampling rule, there exists $\varepsilon_0(\mathbf{F}) > 0$,

$$\forall \varepsilon \in (0, \varepsilon_0(\mathbf{F})], \mathbb{E}_{\mathbf{F}}[T_\beta^\varepsilon] < +\infty \implies \limsup_{\delta \rightarrow 0} \frac{\mathbb{E}_{\mathbf{F}}[\tau_\delta]}{\log(1/\delta)} \leq T_\beta^*(\mathbf{F}) .$$

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Proving $\mathbb{E}_F[T_\beta^\varepsilon] < +\infty$

① **Sufficient exploration:** for n large enough,

$$\min_{i \in [K]} N_{n,i} \geq \sqrt{n/K} .$$

☞ Combining properties of the leader and challenger.

② Convergence of $\frac{N_n}{n}$ towards w^β under sufficient exploration.

Let $\psi_{n,i} := \mathbb{P}_{|(n-1)}[I_n = i]$ and $\Psi_{n,i} := \sum_{t \in [n]} \psi_{t,i}$,

☞ $(N_{n,i} - \Psi_{n,i})/\sqrt{n}$ are sub-Gaussian random variables.

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Convergence towards w^β : leader's property

$$\psi_{n,i} = \beta \mathbb{P}_{|(n-1)}[B_n = i] + (1 - \beta) \sum_{j \neq i} \mathbb{P}_{|(n-1)}[B_n = j] \mathbb{P}_{|(n-1)}[C_n = i | B_n = j].$$

For all $M \in \mathbb{N}$,

$$\left| \frac{\Psi_{n,i^*}}{n} - \beta \right| \leq \frac{M-1}{n} + \frac{1}{n} \sum_{t=M}^n \mathbb{P}_{|(t-1)}[B_t \neq i^*].$$

Good leader: for n large enough,

$$\mathbb{P}_{|n}[B_{n+1} \neq i^*] \leq g(n) =_{+\infty} o(n^{-\alpha}).$$

Convergence towards w^β : challenger's property

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For all $M \in \mathbb{N}$ and all $i \neq i^*$,

$$\frac{\Psi_{n,i}}{n} \leq \frac{M-1}{n} + \frac{1}{n} \sum_{t=M}^n \mathbb{P}_{|(t-1)}[B_t \neq i^*] + \frac{1}{n} \sum_{t=M}^n \mathbb{P}_{|(t-1)}[C_t = i | B_t = i^*].$$

Good challenger: for n large enough and all $i \neq i^*$,

$$\frac{\Psi_{n,i}}{n} \geq w_i^\beta + \varepsilon \Rightarrow \mathbb{P}_{|n}[C_{n+1} = i | B_{n+1} = i^*] \leq h(n) =_{+\infty} o(n^{-\alpha}),$$

Section 6

Experiments

Experimental setup

Moderate regime, $\delta = 0.01$. Top Two algorithms with $\beta = \frac{1}{2}$.

Examples:

- Real-world non-parametric crop-management task,
- Random Bernoulli instances.

Benchmarks:

- KL-LUCB, “fixed” oracle and uniform sampling.
- Heuristics: \mathcal{K}_{inf} -DKM and \mathcal{K}_{inf} -LUCB.

Crop-management problem

DSSAT: yield (observation) depending on the planting date (arm).

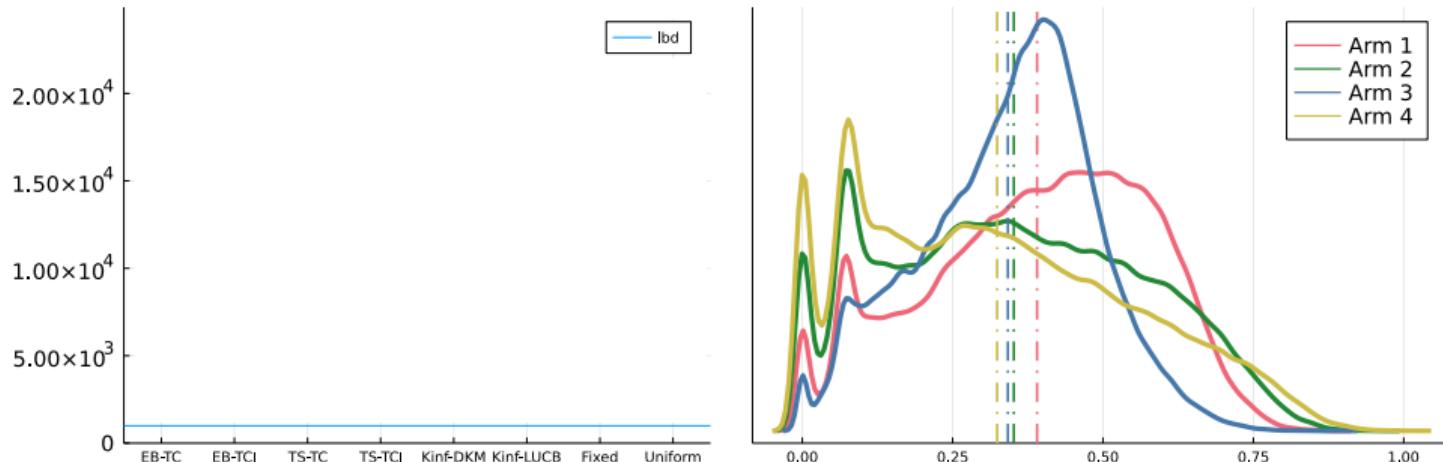


Figure: Empirical stopping time (a) on scaled DSSAT instances with their density and mean (b). Lower bound is $T^*(F) \log(1/\delta)$.

Crop-management problem

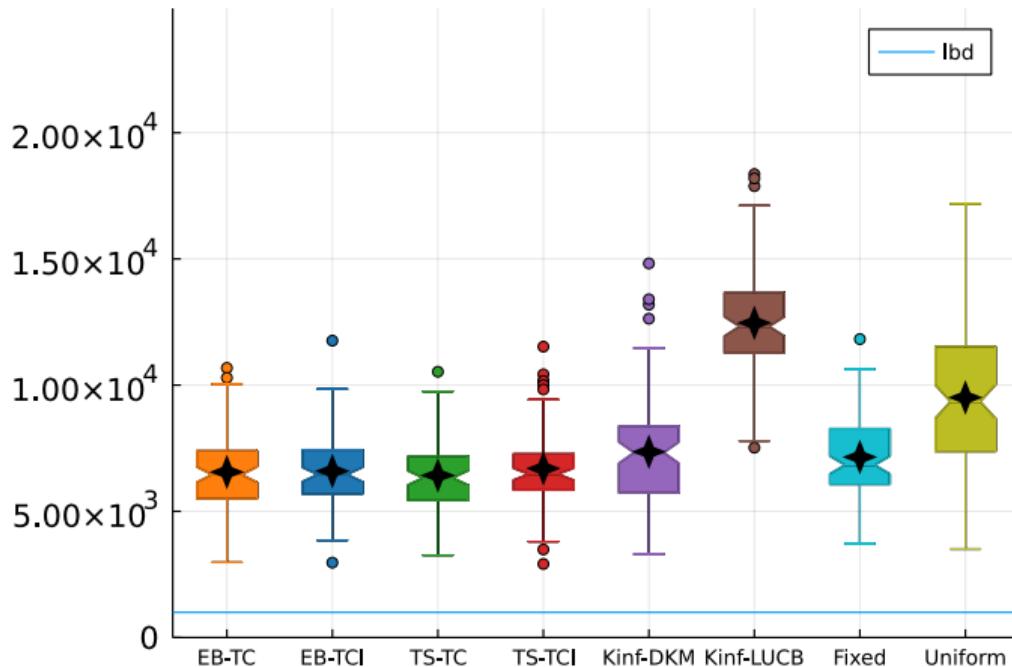


Figure: Empirical stopping time on scaled DSSAT instances. Lower bound is $T^*(F) \log(1/\delta)$. “stars” equal means.

Random Bernoulli instances

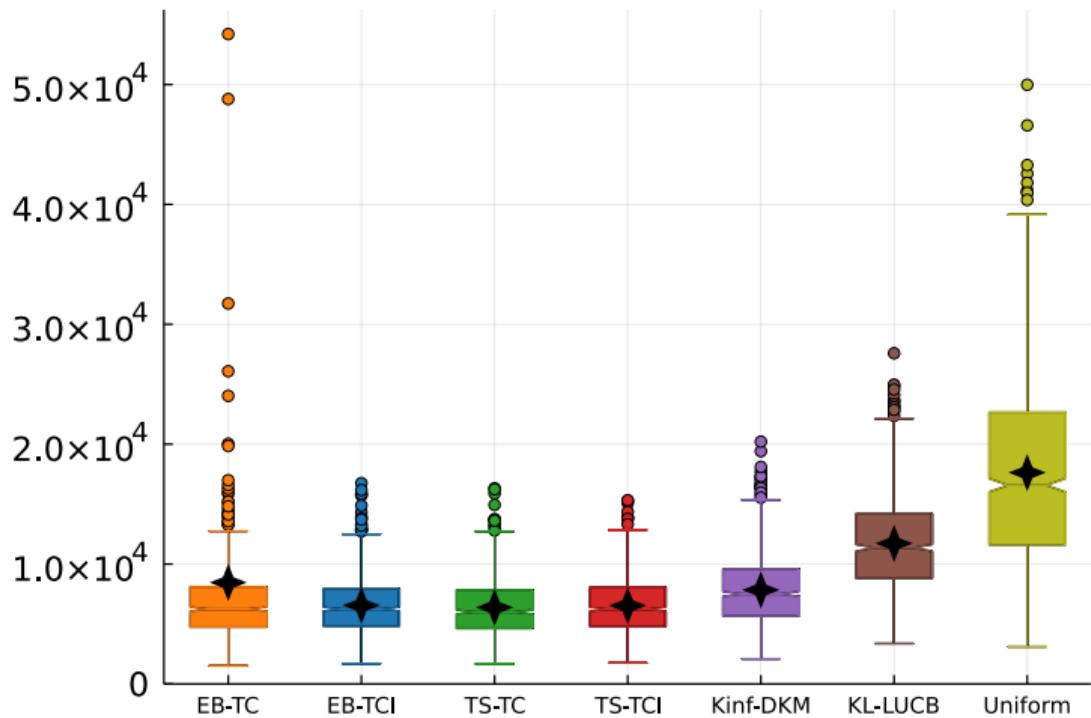


Figure: Empirical stopping time on random Bernoulli instances with $K = 10$.

Conclusion

Contributions:

- ① Generic and modular analysis of Top Two algorithms.
- ② Asymptotically β -optimal instances (bounded and SPEF).
- ③ Competitive performance on a real-world non-parametric task.

Future work and open problems:

- Adaptive Top Two algorithms.
- Guarantees when $\Delta_{\min} = 0$.
- Fixed-budget setting.



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References

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Questions ?

Appendix

Distinct means

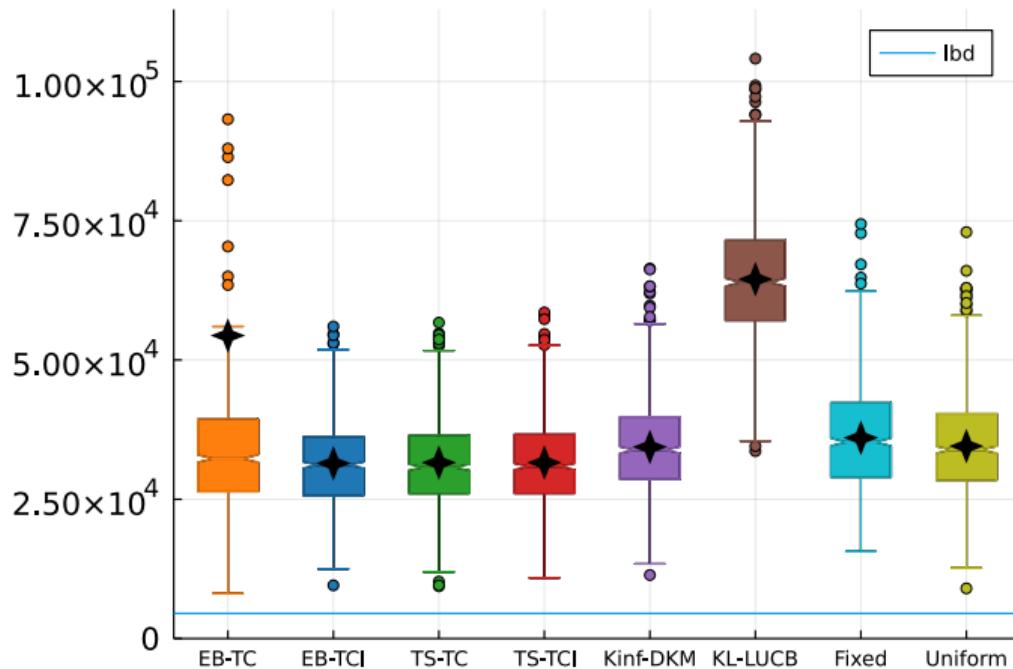


Figure: Empirical stopping time on Bernoulli instance $\mu = (0.5, 0.45, 0.45)$.

RS challenger

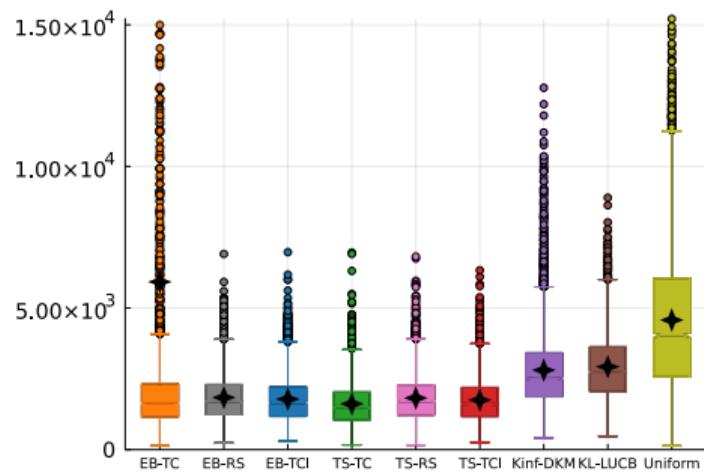
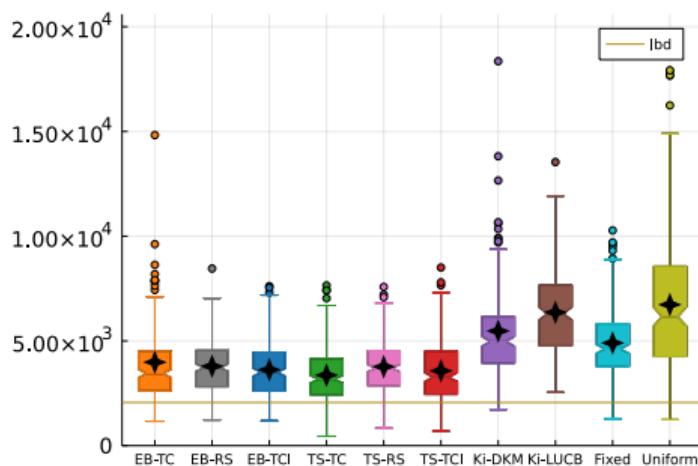


Figure: Empirical stopping time on (a) scaled DSSAT instances with $K = 6$ and (b) random Bernoulli instances with $K = 10$.

\mathcal{K}_{inf} -LUCB

$$\begin{aligned}\forall i \neq \hat{i}_n, \quad U_{n+1,i} &= \max \left\{ u \in [\mu_{n,i}, B] \mid N_{n,i} \mathcal{K}_{\text{inf}}^+(F_{n,i}, u) \leq \beta(n, \delta) \right\} , \\ L_{n+1,\hat{i}_n} &= \min \left\{ u \in [0, \mu_{n,\hat{i}_n}] \mid N_{n,\hat{i}_n} \mathcal{K}_{\text{inf}}^-(F_{n,\hat{i}_n}, u) \leq \beta(n, \delta) \right\} .\end{aligned}$$

Sampling rule: Sample $B_n = \hat{i}_n$ and $C_n \in \arg \max_{i \neq \hat{i}_n} U_{n+1,i}$

Stopping rule:

$$\tau_\delta = \inf \left\{ n \in \mathbb{N} \mid L_{n+1,\hat{i}_n} \geq \max_{j \neq \hat{i}_n} U_{n+1,j} \right\} .$$

Convergence implies optimality

$$\mathbb{E}_{\mathbf{F}}[T_{\beta}^{\varepsilon}] < +\infty \quad \implies \quad \limsup_{\delta \rightarrow 0} \frac{\mathbb{E}_{\mathbf{F}}[\tau_{\delta}]}{\log(1/\delta)} \leq T_{\beta}^{\star}(\mathbf{F}) ,$$

Up to technicalities (\mathcal{K}_{\inf} continuity and second order terms), this implication is shown by using that if $\tau_{\delta} \geq n$, then

$$\log(1/\delta) \approx_{\delta \rightarrow 0} \beta(n, \delta) \geq \min_{j \neq \hat{i}_n} W_n(\hat{i}_n, j) \approx_{n \geq T_{\beta}^{\varepsilon}} n T_{\beta}^{\star}(\mathbf{F})^{-1} .$$

It holds for bounded distributions and SPEF of sub-exponential distributions.

Drawings