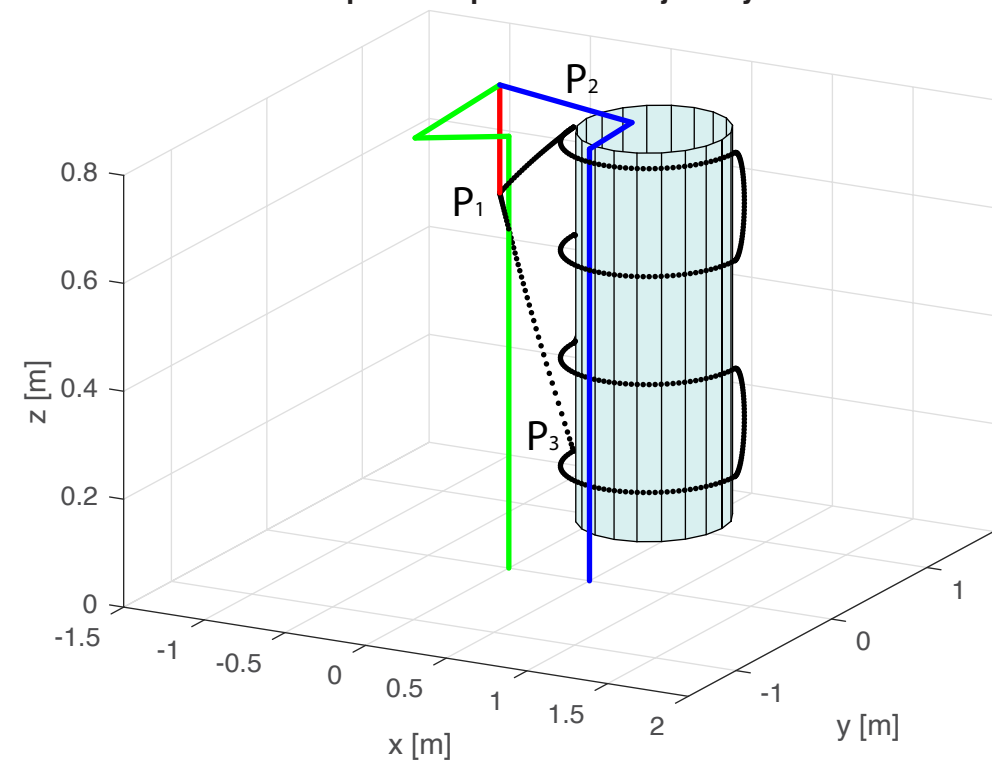
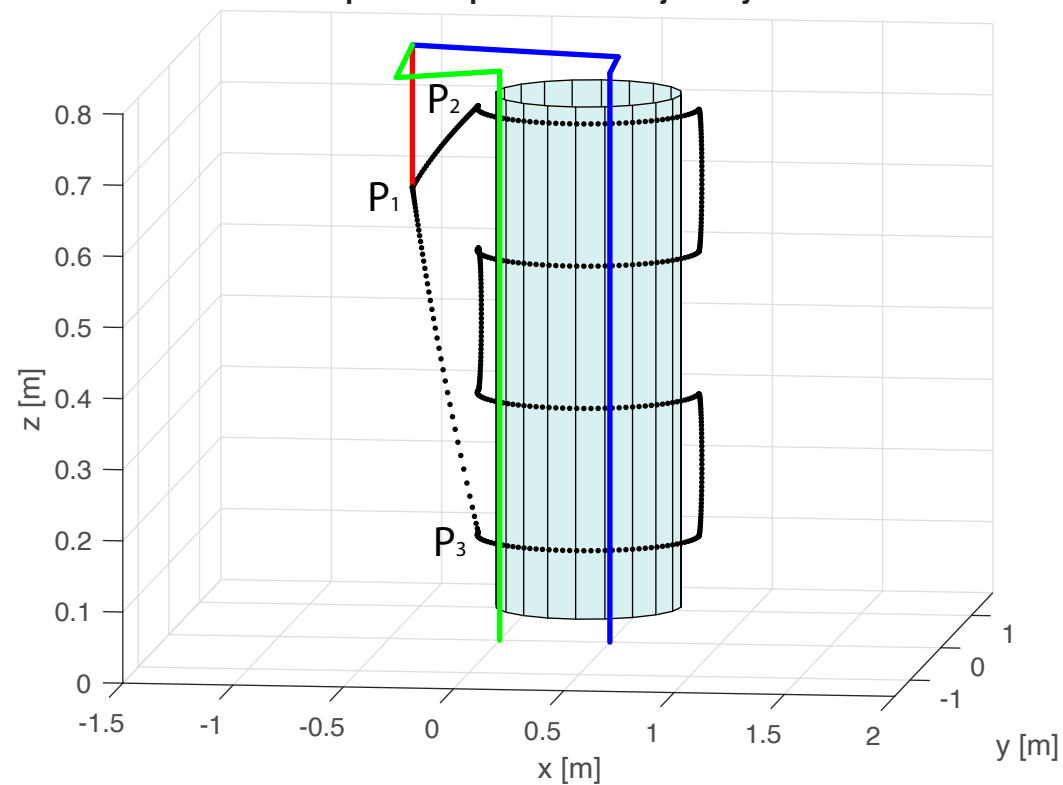


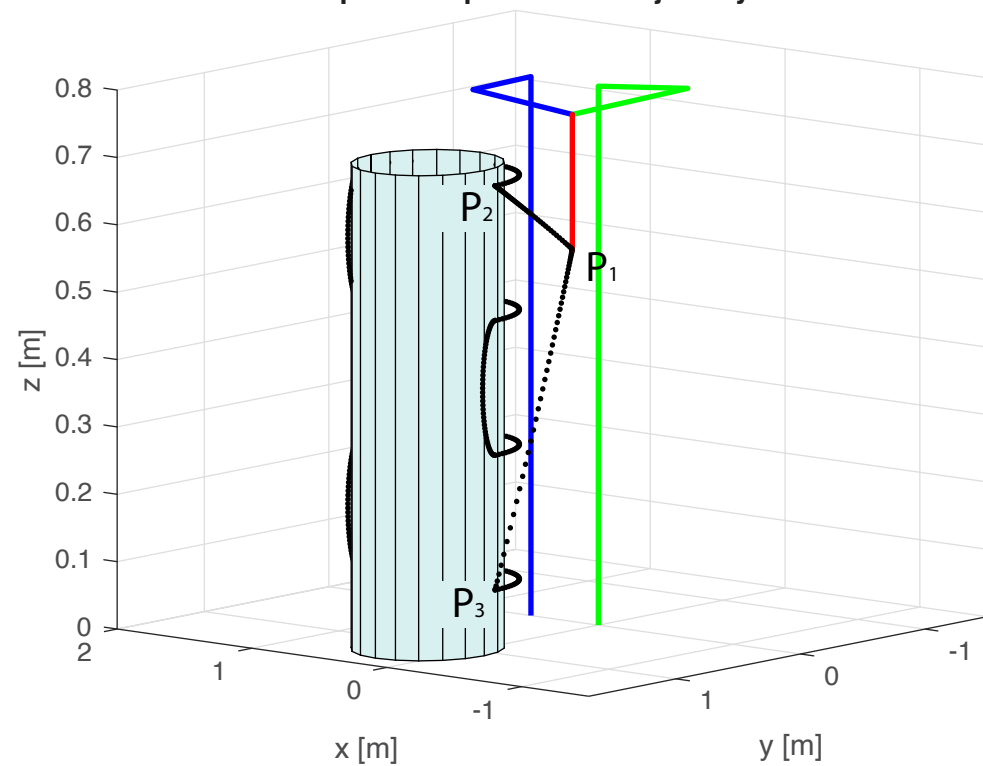
Manipulators poses and trajectory in 3D



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