

Aiyagari_diffusion

November 18, 2021

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[1]: globals().clear()

import numpy as np
from numpy.core.fromnumeric import transpose
from scipy import sparse
import matplotlib.pyplot as plt
from scipy.linalg import block_diag
#np.set_printoptions(formatter={'float': lambda x: "{0:0.4f}".format(x)})
#np.set_printoptions(precision=3)

# ----- #
#                                     Parameters                                     #
# ----- #

alpha = 0.35#1/3,
beta  = 1.05**(-1/4)
rho   = 0.05#1-
delta = 0.1
gamma = 2
phi   = -1
Delta = 1000
Na=100 #100
Nz=40 #40

# Grid of assets
a_max = 30
a_min = phi
a_grid = np.array(np.linspace(a_min,a_max,num=Na) )
da = a_grid[2]-a_grid[1]

AA = np.tile(a_grid, (Nz,1)).T
#A = np.tile(a_grid.reshape(-1,1), (1,Nz))

# Grid of productivity shock
z_min = 0.5 # Range z
z_max = 1.5
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z_grid = np.array(np.linspace(z_min,z_max,num=Nz) )
dz = z_grid[2] - z_grid[1]
dz2 = dz**2
ZZ = np.tile(z_grid, (Na,1))

# ----- #
# Ornstein-Uhlenbeck process:  $dX_t = (X - X_t)dt + dW_t$  #
# ----- #
muz_bar = 1;      # mean O-U process (in levels). This parameter has to be
    ↳adjusted to ensure that the mean of z (truncated gaussian) is 1.
sigmaz = 0.10;    # sigma O-U
thetaz = 0.3

muz = thetaz*(muz_bar - z_grid) #DRIFT (FROM ITO'S LEMMA)
varz = np.repeat(sigmaz**2,Nz)  #VARIANCE (FROM ITO'S LEMMA)

# ----- #
# Derivatives #
# ----- #
# Convert       $V = u(c) + a V_a + \_z V_z + (1/2) \^2 V_{zz}$ 
# into          $V = u(c) + a D_a V + \_z D_z V + (1/2) \^2 D_{zz} V$ 
# and iterate over  $V_{\{n+1\}} = u(c_n(V_n)) [ - a D_a - \_z D_z - (1/2) \^2 D_{zz} ]^{-1}$ 

#Derivatives on z:  $(\_z D_z + (1/2) \^2 D_{zz}) * V$ 

#First Derivative
D_z = np.zeros((Nz,Nz))
for j in range(1,Nz-1):
    if muz[j] >= 0: #OJO con el >=, pq no estoy seguro
        D_z[j,j]   = muz[j] * (-1)/dz
        D_z[j,j+1] = muz[j] * 1/dz
    elif muz[j] < 0:
        D_z[j,j]   = muz[j] * 1/dz
        D_z[j,j-1] = muz[j] * (-1)/dz

if muz[0] >= 0:
    D_z[0,0]   = muz[0] * (-1)/dz
    D_z[0,0+1] = muz[0] * 1/dz
elif muz[0] < 0:
    D_z[0,0]   = muz[0] * 1/dz

if muz[Nz-1] >= 0:
    D_z[Nz-1,Nz-1] = muz[0] * (-1)/dz
elif muz[Nz-1] < 0:
    D_z[Nz-1,Nz-1] = muz[Nz-1] * 1/dz

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D_z[Nz-1,Nz-2] = muz[Nz-1] * (-1)/dz

#Second Derivative
D_zz = np.zeros((Nz,Nz))
for j in range(1,Nz-1):
    D_zz[j,j] = (varz[j]/2)* (-2)/dz**2
    D_zz[j,j+1] = (varz[j]/2)* 1/dz**2
    D_zz[j,j-1] = (varz[j]/2)* 1/dz**2

D_zz[0,0] = (varz[0]/2)* (-2/dz**2) /2
D_zz[0,0+1] = (varz[0]/2)* (1/dz**2)

D_zz[Nz-1,Nz-1] = (varz[Nz-1]/2)* (-2/dz**2) /2
D_zz[Nz-1,Nz-2] = (varz[Nz-1]/2)* (1/dz**2)
DZ = D_z + D_zz

#expanding on a-dimension
Aswitch = np.kron(DZ,np.identity(Na))

#Derivative on a
#First Derivative
D_af = np.zeros((Na,Na))
D_ab = np.zeros((Na,Na))

for j in range(0,Na-1):
    D_af[j,j] = -1/da
    D_af[j,j+1] = 1/da
D_af[Na-1,Na-1] = -1

for j in range(1,Na):
    D_ab[j,j] = 1/da
    D_ab[j,j-1] = -1/da
D_ab[0,0] = 1

# ----- #
#                               Initial Values                               #
# ----- #

def utility(c):
    if gamma!=1:
        u = (c**(1-gamma)) / (1-gamma)
    else:
        u = np.log(c)
    return u

def price_r(K):
    r = alpha * K**( alpha-1) - delta

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    return r

def price_w(K):
    w = (1-alpha) * K**alpha
    return w

def consumption(dV):
    '''
        FOC:
        du/dc = dv/da
        c^(1/gamma) = dv/da
        c= (dv/da)^(-1/gamma)
    '''
    c = dV**(-1/gamma)
    return c

c = np.zeros((Na,Nz))
K = 3.8
r = price_r(K)
w = price_w(K)

V0 = utility( w*ZZ + r*AA) /rho

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[2]: # ----- #
#                                     MAIN LOOP                                     #
# ----- #

#HJB iter
iterHJB=0
maxiterHJB=1000
tolHJB = 1e-6
convHJB = 1000

#FKE iter
iterFKE=0
maxiterFKE=120
tolFKE= 1e-5
convFKE = 100
relax=0.99

for iterFKE in range(0,maxiterFKE):
    print("Iteration Num " + str(iterFKE))
    # '''
    # HAMILTON-JACOBI-BELLMAN EQUATION
    # '''
    for iterHJB in range(0,maxiterFKE):
        V1 = V0

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V_af = np.matmul(D_af,V1) ; V_af[Na-1,:] = (w*z_grid +
↪r*a_grid[Na-1])**(- gamma)
V_ab = np.matmul(D_ab,V1) ; V_ab[0 ,:] = (w*z_grid +
↪r*a_grid[0])**(- gamma)

Ind_concave = V_ab > V_af #indicator whether value function is
↪concave (problems arise if this is not the case)

#forward
c_f = consumption(V_af)
s_f = w*ZZ + r*AA - c_f
I_f = s_f>0

#backward
c_b = consumption(V_ab)
s_b = w*ZZ + r*AA - c_b
I_b = s_b<0

#complement (equals zero in steady state)
c_0 = w*ZZ + r*AA
V_a0= c_0**(-gamma)
I_0 = (1 - I_f - I_b)

#Upwind scheme
V_a = V_af*I_f + V_ab*I_b + V_a0*I_0 #important to include third
↪term (complement)

c = V_a**(-1/gamma)
u = utility(c)
s = s_f*I_f + s_b*I_b #Drift

# Derivative on a-dimension (it is a matrix for every z-state)
DA_aux = np.zeros((Nz,Na,Na))
for j in range(0,Nz):
    for i in range(0,Na):

        #FIRST VALUE
        if i == 0:
            if s[0,j] >= 0:
                DA_aux[j,0,0] = s[0,j] * (-1)/da
                DA_aux[j,0,1] = s[0,j] * 1/da
            elif s[0,j] < 0:
                DA_aux[j,0,0] = s[0,j] * 1/da

        #LAST VALUE
        elif i == Na-1:

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        if s[Na-1,j] >= 0:
            DA_aux[j,Na-1,Na-1] = s[Na-1,j] * (-1)/da
        elif s[Na-1,j] < 0:
            DA_aux[j,Na-1,Na-1] = s[Na-1,j] * (1)/da
            DA_aux[j,Na-1,Na-2] = s[Na-1,j] * (-1)/da
    #CENTER
    else:
        if s[i,j] >= 0:
            DA_aux[j,i,i] = s[i,j] * (-1)/da
            DA_aux[j,i,i+1] = s[i,j] * 1/da
        elif s[i,j] < 0:
            DA_aux[j,i,i] = s[i,j] * 1/da
            DA_aux[j,i,i-1] = s[i,j] * (-1)/da

#np.set_printoptions(precision=5)
#DA_aux
DA=block_diag(*DA_aux)

#Solve the system:
# '''
# (v_{n+1} - v_n)/Delta + rho * v_{n+1} = u_n + A_n*v_{n+1}
# can be expressed as
# X_n * v_{n+1} = y_n
# where
# X_n = (1/Delta + rho)*I - A_n
# y_n = u_n + (1/Delta)*v_n
# then
# v_{n+1} = X_n \ y_n
# '''
A = DA + Aswitch
X = (1/Delta+rho) * np.eye(Na*Nz) - A

u_stacked =u.reshape((Na*Nz,1),order='F')
V1_stacked=V1.reshape((Na*Nz,1),order='F')
y = u_stacked + V1_stacked/Delta

V_stacked = np.matmul(np.linalg.inv(X),y)

V1 = V_stacked.reshape((Na,Nz),order='F')

#convergence criterionwhile
convHJB = np.amax(np.abs(V1-V0))
#print(convHJB)

#update
V0 = V1

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        #iterHJB += 1
        if convHJB < tolHJB:
            break

# '''
# FOKKER - PLANCK EQUATION
# '''

# A'g = 0
np.set_printoptions(precision=5)
TA= np.transpose(A)

#OPT1: use built-in eigenvalues
# eigvals, eigvecs =np.linalg.eig( TA )
# eigvals.real
# eigvecs.real
# TA @ eigvecs[:,0]
# np.matmul(TA,eigvecs[:,0] )
# gg = eigvecs.real[:,0] / np.sum(eigvecs.real[:,0])
# g=gg.reshape((Na,Nz))

#OPT2: fix one value
i_fix = 0
b_aux = np.zeros((Na*Nz,1))
b_aux[i_fix,0] = .1

row_aux= np.zeros((1,Na*Nz))
row_aux[0,i_fix] = 1

TA[i_fix,:] = row_aux
gg = np.linalg.inv(TA) @ b_aux

#normalization
g_sum= np.sum(gg)*da*dz
g= (gg/g_sum).reshape((Na,Nz),order='F')

#Update Agg Capital
S = np.sum(g.T @ a_grid *da*dz)

#Update prices
K = relax*K + (1-relax)*S
r=price_r(K)
w=price_w(K)

convFKE = np.abs(K-S)
print(convFKE)

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if convFKE < tolFKE:
    break

```

```

Iteration Num 0
2.316079316403469
Iteration Num 1
1.7382314294225973
Iteration Num 2
1.0878035475202692
Iteration Num 3
0.5169197418657103
Iteration Num 4
0.17920023513989491
Iteration Num 5
0.04906847189125374
Iteration Num 6
0.012152953007054101
Iteration Num 7
0.0029058364321081775
Iteration Num 8
0.0006891112046956138
Iteration Num 9
0.00017119673531551527
Iteration Num 10
3.442318822832746e-05
Iteration Num 11
2.8148219677781583e-05
Iteration Num 12
3.0434289546299453e-06

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[47]: # -----#
#                                     PLOT DISTRIBUTION                                     #
# -----#

from matplotlib import cm
from matplotlib.ticker import LinearLocator
from matplotlib.pyplot import figure

#figure(figsize=(8, 6), dpi=80)

#Savings policy function
SS = w*ZZ + r*AA - c

fig = plt.figure(figsize=(12, 8), dpi=1200)

ax1=fig.add_subplot(121,projection='3d')
ax1.plot_surface(AA, ZZ , SS, cmap=cm.jet, linewidth=0, antialiased=False)

```



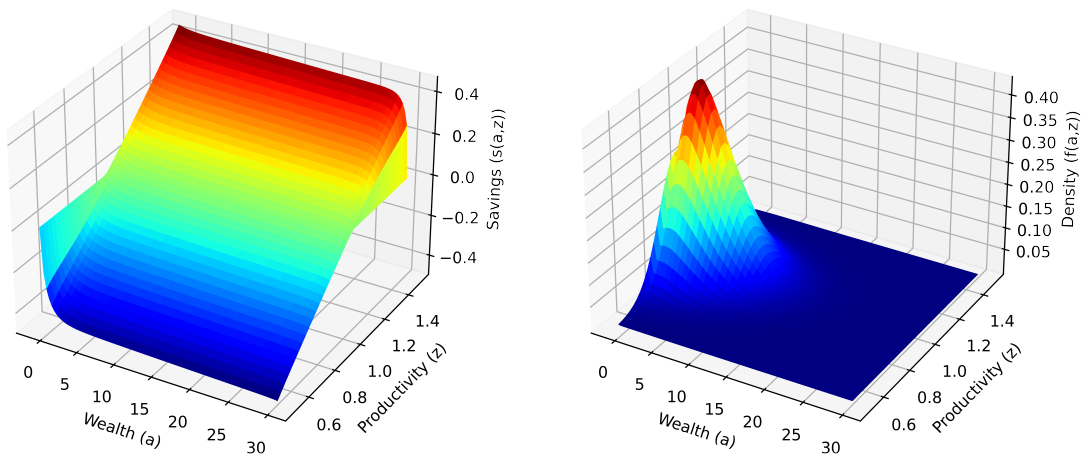
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ax1.set_xlabel('Wealth (a)')
ax1.set_ylabel('Productivity (z)')
ax1.set_zlabel('Savings (s(a,z))')
#ax1.view_init(elev=45., azim=25)}

#Wealth distribution
ax2=fig.add_subplot(122,projection='3d')
ax2.plot_surface(AA, ZZ , g, cmap=cm.jet, linewidth=0, antialiased=False)
ax2.set_xlabel('Wealth (a)')
ax2.set_ylabel('Productivity (z)')
ax2.set_zlabel('Density (f(a,z))')
#ax2.view_init(elev=45., azim=25)

plt.show()
plt.tight_layout()
fig.savefig('aiyagari_difussion.svg', format='svg', dpi=1200)

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<Figure size 432x288 with 0 Axes>