

# Macroeconomics I

University of Tokyo

## Lecture 7

# Dynamic Programming III: Practical DP

*LS, Chapter 4*

Julen Esteban-Pretel

National Graduate Institute for Policy Studies

# Deterministic Problem

- Household's consumption/saving problem (sequential formulation).

$$\begin{aligned}
 \text{(S.P.)} \quad & \max_{\{c_t, a_{t+1}\}_{t=0}^{\infty}} \sum_{t=0}^{\infty} \beta^t u(c_t), \quad 0 < \beta < 1, \\
 \text{s.t.} \quad & a_{t+1} = (1 + r)a_t + w - c_t, \\
 & c_t \geq 0, \quad a_{t+1} \geq 0. \quad \text{for } t \geq 0
 \end{aligned} \tag{7.1}$$

where  $c_t$  is consumption in  $t$ ,  
 $a_t$  are assets holdings in  $t$ ,  
 $r$  is the 1-period return on the asset,  
 $w$  is income.

- Assume  $u(\cdot)$  is strictly concave.
- No solution without  $a_{t+1} \geq 0$ .
- Assume  $\beta \leq \frac{1}{1+r}$ . Otherwise there may not be a solution for some  $u(\cdot)$ .  
 (i.e., no solution if  $\beta \geq \frac{1}{1+r}$  and  $u(c) = c^\gamma$ ).

# Bellman Equation

- The Bellman equation for the previous problem is:

$$\begin{aligned}
 \text{(D.P.)} \quad v(a) &= \max_{a'} \left\{ u[(1+r)a + w - a'] + \beta v(a') \right\}, \\
 \text{s.t. } 0 &\leq a' \leq (1+r)a + w.
 \end{aligned} \tag{7.2}$$

- *State variable*:  $a$  (current asset holdings).
- *Control variable*:  $a'$  (next period's asset holdings).
- We will compute the value function by discretizing the state space for  $a$ .
- Let  $\mathcal{A} = (\bar{a}_1, \dots, \bar{a}_n)$  be a finite set.
- The value function can be represented as an  $n$ -dimensional vector  $\underset{(n \times 1)}{v}$ .  
Its  $i$ -th element is  $v_i$ . So  $v_i = v(\bar{a}_i)$ .

$$v = \begin{bmatrix} v_1 \\ \vdots \\ v_i \\ \vdots \\ v_n \end{bmatrix} = \begin{bmatrix} v(\bar{a}_1) \\ \vdots \\ v(\bar{a}_i) \\ \vdots \\ v(\bar{a}_n) \end{bmatrix}.$$

# Bellman Equation with Discretized State Space

- Restating the Bellman equation:

$$v(a) = \max_{a'} \left\{ u[(1+r)a + w - a'] + \beta v(a') \right\}, \quad (7.3)$$

- With  $\mathcal{A} = (\bar{a}_1, \dots, \bar{a}_n)$ , the Bellman equation becomes

$$v_i = \max_{h \in \{1, 2, \dots, n\}} \{ u[(1+r)\bar{a}_i + w - \bar{a}_h] + \beta v_h \}, \quad i = 1, 2, \dots, n. \quad (7.4)$$

where  $i$  is the index for current asset holdings,  
 $h$  is the index for next period's asset holdings.

- Let  $R_{ih} \equiv u[(1+r)\bar{a}_i + w - \bar{a}_h]$ , and  $\mathbf{v}_{(n \times 1)}$  be the vector whose  $i$ -th element is  $v_i$ .

$$v_i = \max \left\{ \begin{matrix} R_{i,\bullet} \\ (1 \times n) \end{matrix} + \beta \begin{matrix} \mathbf{v}' \\ (1 \times n) \end{matrix} \right\}, \quad i = 1, 2, \dots, n. \quad (7.5)$$

where “max” is the “largest element”, and  $R_{i,\bullet} = (R_{i1}, R_{i2}, \dots, R_{in})$ .

# Iteration on the Bellman Equation

- For each state the **Bellman equation** is:

$$v_i = \max \{ (R_{i1}, R_{i2}, \dots, R_{in}) + \beta(v_1, v_2, \dots, v_n) \}, \quad i = 1, 2, \dots, n. \quad (7.6)$$

- In **matrix notation**

$$\underset{(n \times 1)}{v} = \max \left\{ \underset{(n \times n)}{R_{\bullet, \bullet}} + \beta \underset{(n \times 1)}{1_n} \underset{(1 \times n)}{v'} \right\} \quad (7.7)$$

- This defines an **iteration** on  $\underset{(n \times 1)}{v}$  :

$$v^{(\ell+1)} = \max \left\{ R_{\bullet, \bullet} + \beta 1_n v^{(\ell)'} \right\}. \quad (7.8)$$

- Given  $v$ , the Bellman equation (7.7) defines the **policy function**, which is a mapping from current asset holdings ( $a$ ) to next period's holdings ( $a'$ ).

# Non-negativity Constraints

- Reproducing equation (7.7)

$$\underset{(n \times I)}{v} = \max \left\{ \underset{(n \times n)}{R_{\bullet, \bullet}} + \underset{(n \times I)(I \times n)}{\beta 1_n} \underset{(I \times n)}{v'} \right\} \quad (7.7)$$

- Recall that  $R_{ih} \equiv u[(I + r)\bar{a}_i + w - \bar{a}_h]$  .
- What about  $0 \leq a' \leq (I + r)a + w$ ?
  - Not including **negative numbers** in  $\mathcal{A}$  takes care of  $0 \leq a'$ .
  - The non-negativity **constraint on consumption** (i.e.,  $(I + r)a + w - a' \geq 0$ ) can be taken care of by assigning a large negative number to  $R_{ij}$  when  $(I + r)a + w - a' < 0$ .

$$v(a) = \max_{a'} \left\{ u[(1+r)a + w - a'] + \beta v(a') \right\}$$

- 1.- Discretize asset space:  $\mathcal{A} = (\bar{a}_1, \dots, \bar{a}_n)$

```
% Discretize the state space
% State variable: Assets in current period (a)
a = (0:0.05:20)'; % State space for assets
n = size(a,1); % n is the number of states for assets
```

- 2.- Choose parameter values

```
% Preference parameters
bet = 0.95; % Discount factor
sig = 1; % Degree of risk aversion in the CRRA utility function
% Technological parameters
r = 0.04; % Rate of return on assets
w = 1; % wage rate
% Iteration procedure elements
MxIt= 1000; % Maximum number of iterations
eps = 0.001; % Convergence criterium
```

- 3.- Calculate matrix of current returns  $R$ , where  $R_{ih} \equiv u[(1+r)\bar{a}_i + w - \bar{a}_h]$   
( $n \times n$ )

```
R=zeros(n,n); % Initialize the return matrix R (n by n)
% Calculate matrix of consumption (n by n) for assets states (i,h) [current,future]
C=(1+r)*a*ones(1,n)+w*ones(n,n)-ones(n,1)*a';
% Calculate matrix of current returns for each c (if cons. is neg. util = -999)
R=UtilFn(C.*(C>=0),sig).*(C>=0)-999*(C<0);
```

# Matlab Implementation - Value Function Iteration

$$v(a) = \max_{a'} \left\{ u[(1+r)a + w - a'] + \beta v(a') \right\}, \text{ or } \underset{(n \times 1)}{v} = \max \left\{ \underset{(n \times n)}{R_{\bullet, \bullet}} + \beta \underset{(n \times 1)}{1_n} \underset{(1 \times n)}{v'} \right\}$$

- **4.- Iterate** on the bellman equation until it converges:

```
V = ones(n,1); Vnew = ones(n,1); Pol = ones(n,1); % Initialize value fns, pol. fn
for l=1:MxIt; % Iterate until the max iterations has been reached
```

- **4.1.- Calculate RHS of the Bellman eq** before finding the max:  $R + \beta 1_n v'$

```
W=R+bet*ones(n,1)*V'; % Calculates RHS of Bellman eq for i and h.
```

- **4.2.- Calculate the max** (largest element), the LHS of the Bellman eq and the policy fn:

```
[W,index]=max(W'); % Find the max over h (next period asset)
```

- **4.3.- LHS of the Bellman equation and policy function:**

```
Vnew=W'; % LHS of Bellman eq
Pol=index'; % Calculates the policy fn (choice of h for each i)
```

- **4.4.- Check for convergence:**

```
% Check for convergence
if max(abs(Vnew-V))<eps;
    fprintf(1,'The value function has CONVERGED in %2.0f iterations.\n',l);
    break; % If convergence if achieved (change is less than eps) stop loop
end;
```

- **4.5.- If no convergence, update value function** and continue until convergence:

```
V=Vnew; % Update value function
end;
```



# Matlab Implementation - Plot Results

$$v(a) = \max_{a'} \left\{ u[(1+r)a + w - a'] + \beta v(a') \right\}, \text{ or } \underset{(n \times 1)}{v} = \max \left\{ \underset{(n \times n)}{R_{\bullet, \bullet}} + \beta \underset{(n \times 1)}{1_n} \underset{(1 \times n)}{v'} \right\}$$

- **5.- Plot** the value and policy functions:

```
% value function
subplot(2,1,1)
plot(a,V,'b-')
title('Value function');
xlabel('Current asset level');

% policy function
subplot(2,1,2)
plot(a,a(Pol),'b-')
title('Policy function');
xlabel('Current asset level');
ylabel('Next period asset level');
```

# Stochastic Case

- Household's consumption/saving problem (sequential formulation).

$$\begin{aligned}
 \text{(S.P.)} \quad & \max_{\{c_t, a_{t+1}\}_{t=0}^{\infty}} E_0 \left\{ \sum_{t=0}^{\infty} \beta^t u(c_t) \right\}, \quad 0 < \beta < 1, \\
 \text{s.t.} \quad & a_{t+1} = (1 + r)a_t + ws_t - c_t, \\
 & c_t \geq 0, \quad a_{t+1} \geq 0. \quad \text{for } t \geq 0
 \end{aligned} \tag{7.9}$$

where  $\{s_t\}$  follows a Markov process.

$s_t$  can be interpreted as productivity or the employment status.

- Assume that  $\beta \leq \frac{1}{1+r}$ .

# Bellman Equation and Discretization of Problem

- The dynamic programming formulation, **Bellman equation**, of the problem is

$$\begin{aligned}
 \text{(D.P.)} \quad v(a, s) = \max_{a'} & \left\{ u[(I + r)a + ws - a'] + \beta E[v(a', s') | a, s] \right\}, \\
 \text{s.t.} \quad & 0 \leq a' \leq (I + r)a + ws.
 \end{aligned} \tag{7.10}$$

- Assume  $\{s_t\}$  is a **finite-state Markov chain** with transition matrix  $P_{(m \times m)}$  and state space  $\mathcal{S} = (\bar{s}_1, \bar{s}_2, \dots, \bar{s}_m)$ .

- $v(a, s)$  can be represented as a collection of functions of a single variable

$$v(a, s) = \left( \underset{(n \times m)}{v_1(a)}, \dots, \underset{(n \times 1)}{v_j(a)}, \dots, \underset{(n \times 1)}{v_m(a)} \right) \quad \text{where the } i\text{-th element of } v_j \text{ is } v_{ij}.$$

- Under these assumptions, we can write the Bellman equation as

$$\begin{aligned}
 v_j(a) = \max_{a'} & \left\{ u[(I + r)a + w\bar{s}_j - a'] + \beta \sum_{k=1}^m P_{jk} v_k(a') \right\}, \\
 \text{s.t.} \quad & 0 \leq a' \leq (I + r)a + w\bar{s}_j, \quad \text{for } j = 1, 2, \dots, m.
 \end{aligned} \tag{7.11}$$

# Bellman with Discretized State Space

- Restating the Bellman equation (7.11):

$$v_j(a) = \max_{a'} \left\{ u[(1+r)a + w\bar{s}_j - a'] + \beta \sum_{k=1}^m P_{jk} v_k(a') \right\}, \quad j = 1, 2, \dots, m.$$

- With  $\mathcal{A} = (\bar{a}_1, \dots, \bar{a}_n)$ , the Bellman equation becomes

$$v_{ij} = \max_{h \in \{1, 2, \dots, n\}} \left\{ u[(1+r)\bar{a}_i + w\bar{s}_j - \bar{a}_h] + \beta \sum_{k=1}^m P_{jk} v_{hk} \right\}. \quad (7.12)$$

where  $i$  is the index for current asset holdings,

$h$  is the index for next period's asset holdings,

$j$  is the index for employment status.

- Let  $R_{ihj} \equiv u[(1+r)\bar{a}_i + w\bar{s}_j - \bar{a}_h]$ , and  $V$  be the vector whose  $(i,j)$  element is  $v_{ij}$ .

$$v_{ij} = \max \left\{ R_{i,\bullet,j} + \beta P_{j,\bullet} V' \right\}, \quad \begin{matrix} (n \times m) \\ (1 \times n) \quad (1 \times m) \quad (m \times n) \end{matrix} \quad \begin{matrix} \text{"max" is the} \\ \text{"largest element"}. \end{matrix} \quad (7.13)$$

where  $V = \begin{bmatrix} v_1 & \dots & v_j & \dots & v_m \end{bmatrix}$ .

$(n \times m) \quad (n \times 1) \quad (n \times 1) \quad (n \times 1)$

# Bellman using Matrix Algebra

- Writing equation (7.13) in full:

$$v_{ij} = \max_{(1 \times n)} \left\{ R_{i,\bullet,j} + \beta \underset{(1 \times m)}{P_{j,\bullet}} \underset{(m \times n)}{V'} \right\}$$

$$= \max \left[ R_{i1j} + \beta \sum_{k=1}^m P_{jk} v_{1k} \cdots R_{ihj} + \beta \sum_{k=1}^m P_{jk} v_{hk} \cdots R_{inj} + \beta \sum_{k=1}^m P_{jk} v_{nk} \right]$$

- " $\underset{(1 \times m)}{P_{j,\bullet}} \underset{(m \times n)}{V'}$ " does not depend on  $i$ . Hence (restating LS (4.3.1)):

$$v_j = \max_{(n \times 1)} \left\{ \underset{(n \times n)}{R_{\bullet,\bullet,j}} + \beta \underset{(n \times 1)}{1_n} \underset{(1 \times m)}{P_{j,\bullet}} \underset{(m \times n)}{V'} \right\}, \quad j = 1, 2, \dots, m. \quad (7.14)$$

"max A" is a column vector whose  $i$ -th element is the largest element of the  $i$ -th row of A.

# Non-negativity Constraints

- Reproducing equation (7.14)

$$v_j = \max_{(n \times 1)} \left\{ R_{\bullet, \bullet, j} + \beta \frac{1_n}{(n \times 1)} P_{j, \bullet} V' \right\}, \quad j = 1, 2, \dots, m.$$

- Recall that  $R_{ihj} \equiv u[(1+r)\bar{a}_i + w\bar{s}_j - \bar{a}_h]$ .
- What about  $0 \leq a' \leq (1+r)a + w\bar{s}$ ?
  - Not including negative numbers in  $\mathcal{A}$  takes care of  $0 \leq a'$ .
  - The non-negativity constraint on consumption (i.e.,  $(1+r)a + ws_j - a' \geq 0$ ) can be taken care of by assigning a large negative number to  $R_{ihj}$  when  $(1+r)a + ws_j - a' < 0$ .

$$v(a, s) = \max_{a'} \left\{ u[(1+r)a + ws - a'] + \beta E[v(a', s')|a, s] \right\}$$

- 1.- Discretize asset space:  $\mathcal{A} = (\bar{a}_1, \dots, \bar{a}_n)$

```
a = (0:0.05:20)'; % State space for assets
n = size(a,1); % n is the number of states for assets
```

- 2.- Specify Markov chain:  $\mathcal{S} = (\bar{s}_1, \bar{s}_2, \dots, \bar{s}_m)$  and  $P$ .

```
s = [0.1;1]; % State space for employment
P = [0.6, 0.4;0.3,0.7]; % Markov transition matrix
m = size(s,1); % m is the number of employment states
```

- 3.- Choose parameter values

```
bet = 0.95; sig = 1; % Discount factor and degree of risk aversion.
r = 0.04; w = 1; % Rate of return on assets and wage rate when employed.
MxIt= 1000; eps = 0.001; % Maximum number of iterations and Convergence criterium
```

- 4.- Calculate matrix of current returns  $R$ , where  $R_{ihj} \equiv u[(1+r)\bar{a}_i + w\bar{s}_j - \bar{a}_h]$   
( $n \times n \times j$ )

```
R=zeros(n,n,m); % Initialize R, which is n by n by j (j is the emp. state)
% Calculate the matrix of current returns for each j (employment state)
for j=1:m; % Calculation for each j (employment state)
    % Calculate matrix of consumption (n by n) for assets states (i,h) [current,future] given j
    C=(1+r)*a*ones(1,n)+w*s(j)*ones(n,n)-ones(n,1)*a';
    % Calculate matrix of current returns for each c (if cons. is neg. util = -999)
    R(:,:,j)=UtilFn(C.*(C>=0),sig).*(C>=0)-999*(C<0);
end;
```

# Matlab Implementation - Value Function Iteration

$$v(a, s) = \max_{a'} \left\{ u[(1+r)a + ws - a'] + \beta E[v(a', s') | a, s] \right\} \text{ or } v_j = \max_{(n \times 1)} \left\{ R_{\bullet, \bullet, j} + \beta \mathbf{1}_n P_{j, \bullet} V' \right\}_{(n \times n) \quad (n \times 1) (1 \times m) (m \times n)}$$

- 5.- Iterate on the bellman equation until it converges: for  $j = 1, 2, \dots, m$

```
V = ones(n,m); Vnew = ones(n,m); Pol = ones(n,m); % Initialize value fns, pol. fn
for l=1:MxIt; % Iterate until the max iterations has been reached
    for j=1:m; % Calculation for each j (employment status)
```

- 5.1.- Calculate RHS of the Bellman eq before finding the max:  $R + \beta \mathbf{1}_n P_{j, \bullet} V'$

```
W=R(:, :, j)+bet*ones(n,1)*P(j, :)*V'; % RHS of Bellman eq for i and h, given j.
```

- 5.2.- Calculate the max (largest element), the LHS of the Bellman eq and the policy fn:

```
[W,index]=max(W'); % Find the max over h (next period asset)
```

- 5.3.- LHS of the Bellman equation and policy function:

```
Vnew=W'; % LHS of Bellman eq
Pol=index'; % Calculates policy fn (choice of h for each i, given j)
end;
```

- 5.4.- Check for convergence:

```
if max((max(abs(Vnew-V)))') < eps; break;
    fprintf(1, 'The value function has CONVERGED in %2.0f iterations.\n', l);
end;
```

- 5.5.- If no convergence, update value function and continue until convergence:

```
V=Vnew; % Update value function
end;
```



$$v(a, s) = \max_{a'} \left\{ u[(1+r)a + ws - a'] + \beta E[v(a', s') | a, s] \right\} \text{ or } v_j = \max_{(n \times 1)} \left\{ R_{\bullet, \bullet, j} + \beta \sum_{(n \times 1)} \sum_{(1 \times m)} P_{j, \bullet} V' \right\}$$

for  $j = 1, 2, \dots, m$

## ■ 6.- Plot the value and policy functions:

```
% value function
subplot(2,1,1)
plot(a,V(:,1),'r:',a,V(:,2),'b-')
title('Value function');
legend('Unemployed','Employed',4);
xlabel('Current asset level');

% policy function
subplot(2,1,2)
plot(a,a(Pol(:,1)),'r:',a,a(Pol(:,2)),'b-')
title('Policy function');
legend('Unemployed','Employed',4)
xlabel('current asset level');
ylabel('Next period asset level');
```

# Matlab Implementation - Time Series Simulation

$$v(a, s) = \max_{a'} \left\{ u[(1+r)a + ws - a'] + \beta E[v(a', s')|a, s] \right\} \text{ or } v_j = \max_{(n \times 1)} \left\{ R_{\bullet, \bullet, j} + \beta \sum_{(n \times 1)} 1_n P_{j, \bullet} V' \right\}_{(1 \times m)(m \times n)}$$

for  $j = 1, 2, \dots, m$

## ■ 7.- Simulation preliminaries:

```
maxT = 5000; % Max periods
initial_emp = 1; % Initial employment state is 1
initial_asset = floor(n/3); % Initial assets state
[chain, state_emp] = markov(P, maxT, initial_emp, s'); % Generate Markov chain
state_emp = (1:1:m)*state_emp; % Employment state for t=2,...,T.
state_emp = [initial_emp state_emp]; % add employment state for t=1
```

## ■ 8.- Calculate the time series for consumption and assets:

```
c = zeros(maxT, 1); % Initialize consumption series
asset = zeros(maxT, 1); % Initialize asset level series
i = initial_asset; % Initialize the asset state

for t=1:maxT;
    j=state_emp(t); % Employment state in t is j.
    h=Pol(i, j); % Policy rule states to move from i to h.
    c(t)=(1+r)*a(i)+w*s(j)-a(h); % Implied consumption
    asset(t)=a(i); % Translate asset state i to asset level
    i=h; % Update the current asset state
end;

euler = zeros(maxT-1, 1); % Euler error
for t=1:maxT-1;
    euler(t)=bet*(1+r)*(MgUtilFn(c(t+1), sig)./MgUtilFn(c(t), sig))-1;
end;
```

# Matlab Implementation - Plot Simulation Results

$$v(a, s) = \max_{a'} \left\{ u[(1+r)a + ws - a'] + \beta E[v(a', s')|a, s] \right\} \text{ or } v_j = \max_{(n \times 1)} \left\{ R_{\bullet, \bullet, j} + \beta \frac{1_n}{(n \times 1)} \frac{P_{j, \bullet}}{(1 \times m)} \frac{V'}{(m \times n)} \right\}$$

for  $j = 1, 2, \dots, m$

## ■ 9.- Plot Simulation Results:

```
T = 100;

% Employment state
subplot(4,1,1)
x = (1:1:T-1);
bar(x, state_emp(1:T-1)-1, 1)
title('Employment status');
xlabel('Period');

% Assets
subplot(4,1,2)
x=(1:1:T);
plot(x, asset(1:T), 'b-'), title('Asset path');
xlabel('Period');

% Consumption
subplot(4,1,3)
x=(1:1:T);
plot(x, c(1:T), 'b-'), title('Consumption path');
xlabel('Period');

% Euler error
subplot(4,1,4)
x=(1:1:T);
plot(x, euler(1:T), 'b-'), title('Euler error');
xlabel('Period');
```

# Matlab Implementation - Plot Simulation Results

$$v(a, s) = \max_{a'} \left\{ u[(1+r)a + ws - a'] + \beta E[v(a', s')|a, s] \right\} \text{ or } v_j = \max_{(n \times 1)} \left\{ R_{\bullet, \bullet, j} + \beta \frac{1_n}{(n \times 1)} \frac{P_{j, \bullet}}{(1 \times m)} \frac{V'}{(m \times n)} \right\}$$

for  $j = 1, 2, \dots, m$

## ■ 9.- Plot Simulation Results:

```
% Scatterplot current Euler error on as a function of current assets

subplot(1,1,1)
x=asset(1:maxT-1);
scatter(x,euler,10,'*');
xlabel('Current assets');
ylabel('Euler error');
```