

1 - Introduction

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Motivation

Deep Learning models have played a transformative role in Computer Vision over the last decade, significantly enhancing and expanding the capabilities to process visual data.

The integration of Deep Learning in Computer Vision has massively improved the accuracy and efficiency of visual recognition, classification, and analysis. This has opened up new possibilities in applications such as automated driving, facial recognition, and medical image analysis. These models are now embedded in a wide variety of products and services. Examples in the field of image processing with Deep Learning are shown in Figure 1, Figure 2, and Figure 3.

i Question

What steps do you think the model in Figure 3 performs?

The increasingly better models and the ability to run them quickly and resource-efficiently on mobile devices have enabled such applications. Figure 4 shows that special chips have been developed to process images with Deep Learning models quickly.

Challenges

We will now explore some challenges that must be overcome when analyzing images with machine learning models.

Semantic Gap

The semantic gap refers to the discrepancy between low-level information that can be extracted from an image and the interpretation of an image by a viewer. Simply put: an image often consists of millions of pixels whose information must be condensed to ultimately derive semantically meaningful information. This is an extremely complex task.

Werbung für Kameras: Fotos Schärfen mit AI



Figure 1: Example from [Link](#). Left is the original image, right is the version enhanced with Deep Learning.

Werbung für Kameras: Objekte Entfernen mit AI

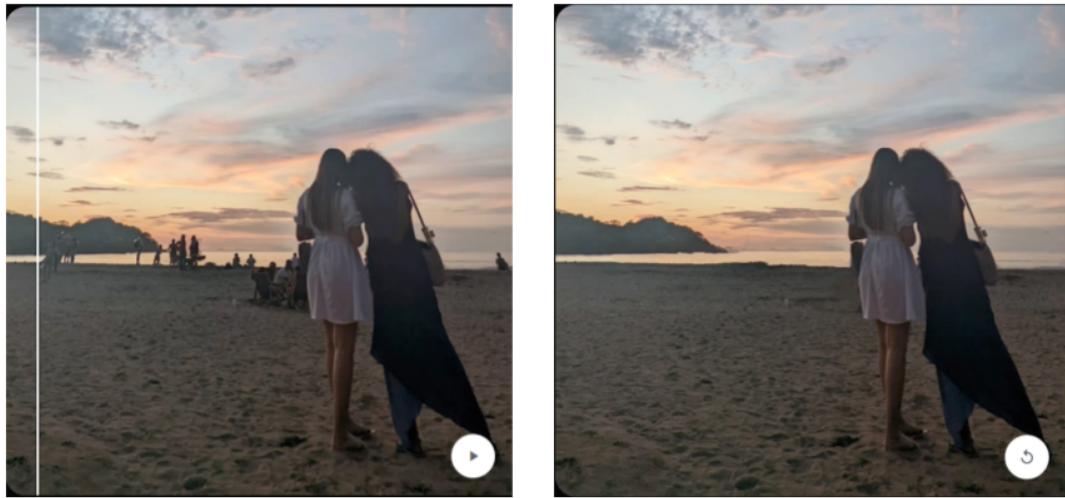


Figure 2: Example from [Link](#). Left is the original image, right is the manipulated version.

Werbung für Kameras: Manipulationen und Effekte mit AI

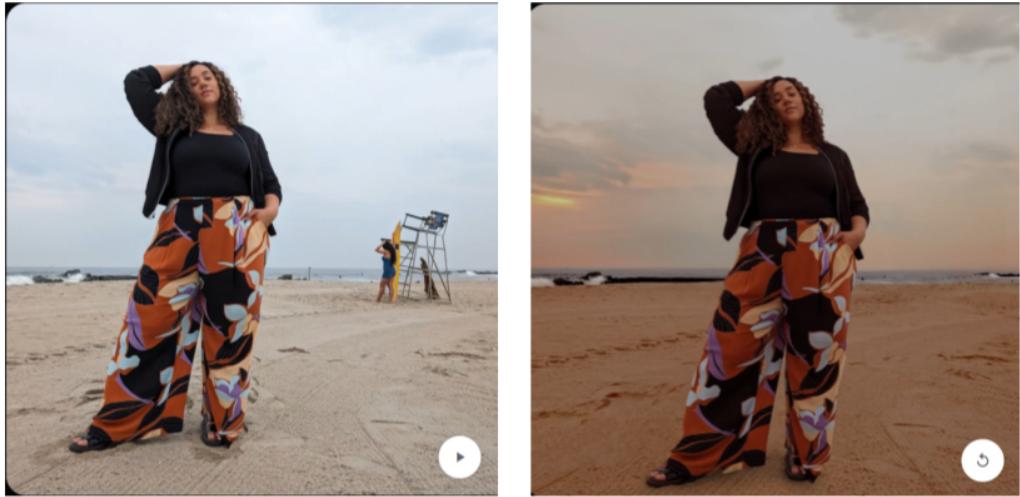


Figure 3: Example from [Link](#). Left is the original image, right is the manipulated version.

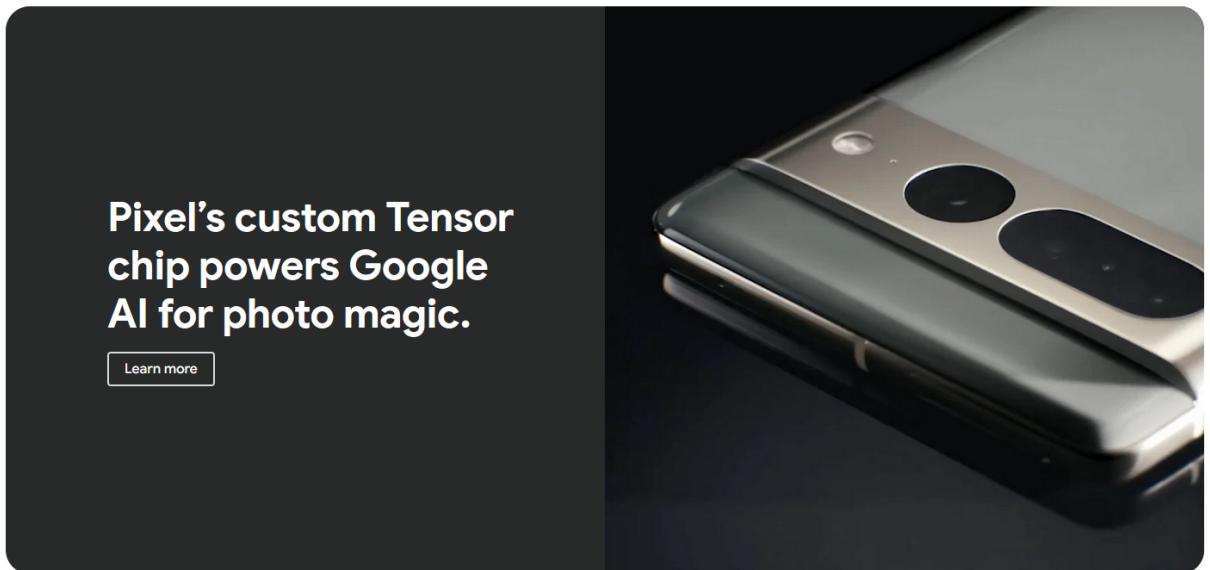
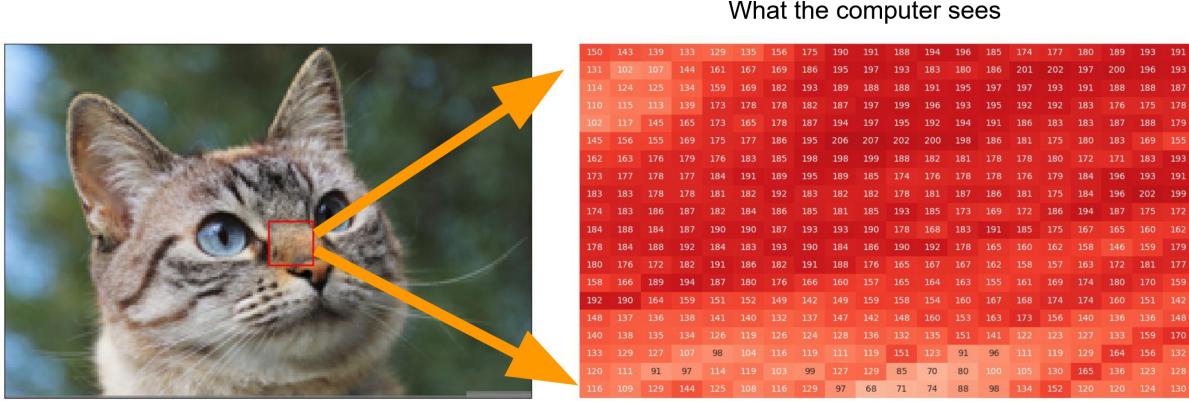


Figure 4: From [Link](#).



Input Tensor: [width, height, 3 (colors)]
Values in [0, 255]

Figure 5: Illustration of the semantic gap.

Viewpoint

The meaning of the image does not change with the viewpoint, but the pixels do.

Deformation

Objects are often flexible and appear in different shapes and poses.

Illumination

Changes in illumination affect pixel values and the visibility of objects.

Background

Background pixels can resemble objects and make their exact delineation or visibility more difficult.

Occlusion

Objects are not always fully visible, which can make their detection more difficult.

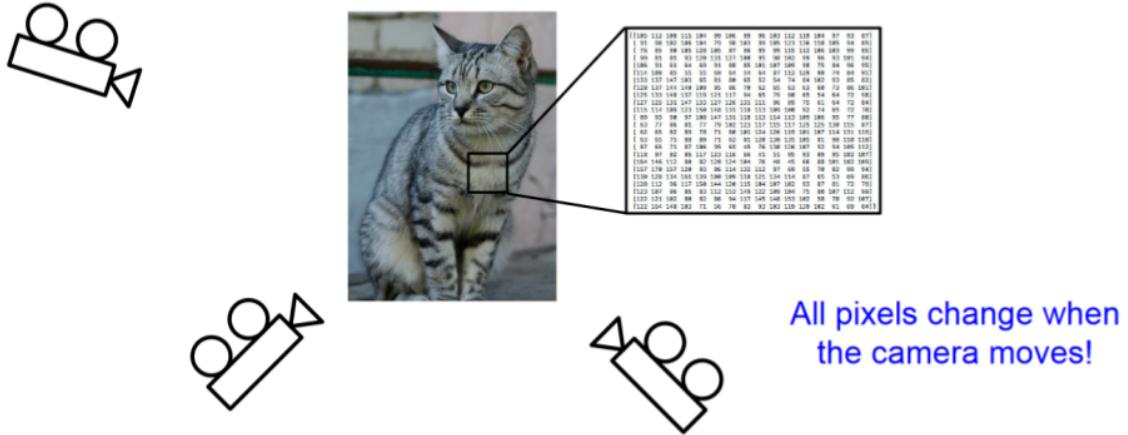


Figure 6: Source



Figure 7: Source



Figure 8: Source



Figure 9: [Source](#)



Figure 10: [Source](#)

Intra-Class Variation

Objects of the same class can exhibit large intra-class variability.



Figure 11: [Source](#)

Context Dependence

Figure 12 shows that context information can be important to correctly classify an object.

Problem Statements

There are various problem statements in image processing that can be modeled with Deep Learning. Below, we will see some of them.

Image Classification

In image classification, an image is assigned to a predefined set of classes. In multi-class classification, there are 2 classes; in binary classification, there are 2 classes; and in multi-label classification, there are multiple sets of classes. Figure 13 shows an example from the paper by Krizhevsky, Sutskever, and Hinton (2012) (multi-class classification), which achieved

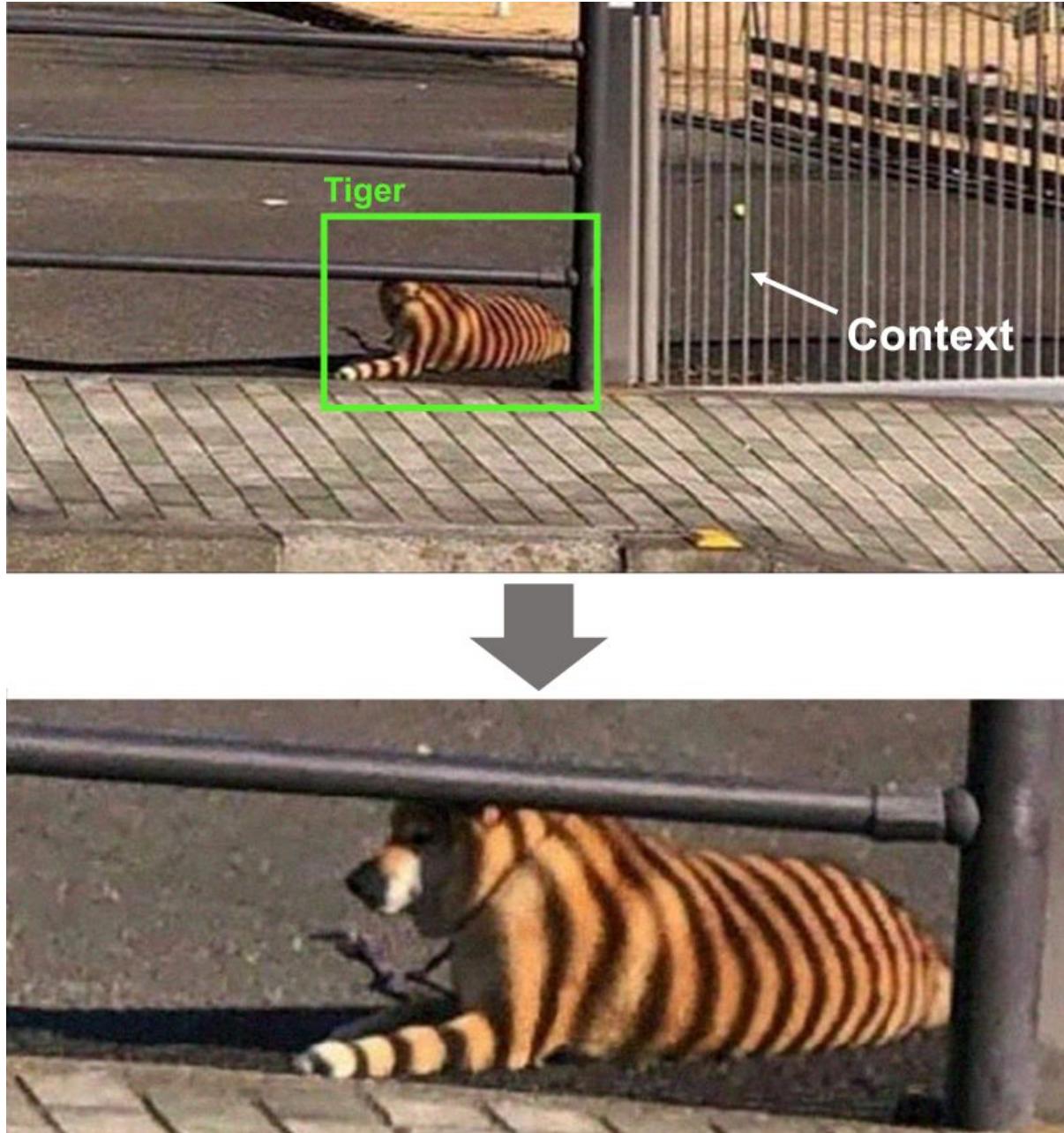


Figure 12: Context Source

the best results in the ImageNet competition in 2012 and demonstrated the effectiveness of CNNs.



Figure 13: Multi-Class Image Classification example (from Krizhevsky, Sutskever, and Hinton (2012)).

Object Detection

Object detection involves locating and recognizing (multiple) objects in an image. Figure 14 shows an example from the paper by Redmon et al. (2016). Each object is localized with a bounding box and assigned an object class.

Segmentation

In segmentation, individual pixels are assigned to specific objects (instance segmentation) or classes (semantic segmentation). Figure 15 shows an example of object segmentation (instance segmentation) from the paper by He et al. (2018), where individual objects are detected and precisely localized (segmented) at the pixel level.

The following video shows an example of semantic segmentation:

Keypoint Detection

In keypoint detection, keypoints of people are localized. People must be detected and their keypoints (joints) localized. Figure 16 shows an example of keypoint detection from the paper by He et al. (2018), where

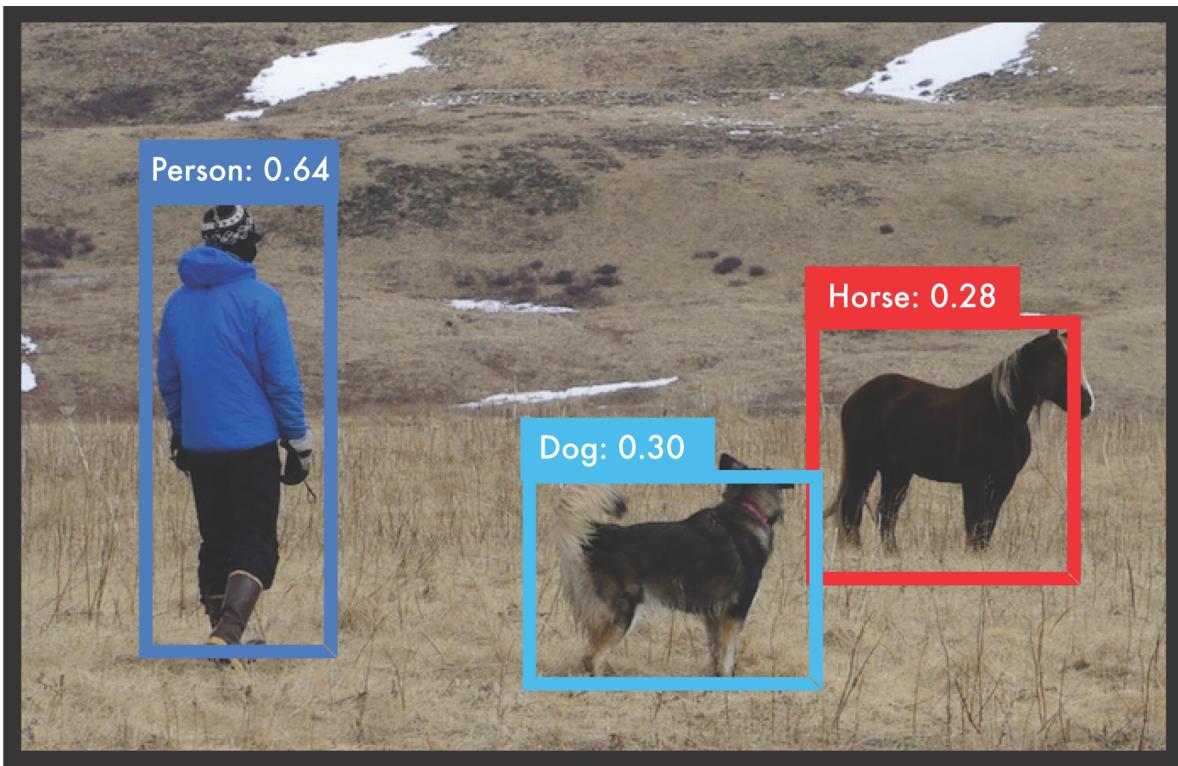


Figure 14: Object Detection example (from Redmon et al. (2016)). Bounding boxes localize the objects, indicating the most likely class and confidence for each object.



Figure 15: Object Segmentation example (from He et al. (2018)).

individual people are detected and their joints localized. This can be used to transfer movements from a person to an avatar or to recognize activities of people (action recognition).



Figure 16: Keypoint Detection example (from He et al. (2018)).

Image Generation

There are various applications where models transform input images into specific output images (image-to-image or image translation) or generate completely new images (image generation). Below are some examples.

Image Translation

Figure 17 shows an example of image generation from the paper by Isola et al. (2018), where images are generated conditioned on image inputs (translated).

Image Super Resolution

In the gaming industry, Deep Learning is used to generate high-resolution images, scaling low-resolution images efficiently (image super resolution), as shown in Figure 18. This allows for higher frame rates.

Image Colorization

Image colorization can be learned with Deep Learning. This involves transforming a black-and-white image into an RGB image. Figure 19 shows an example.

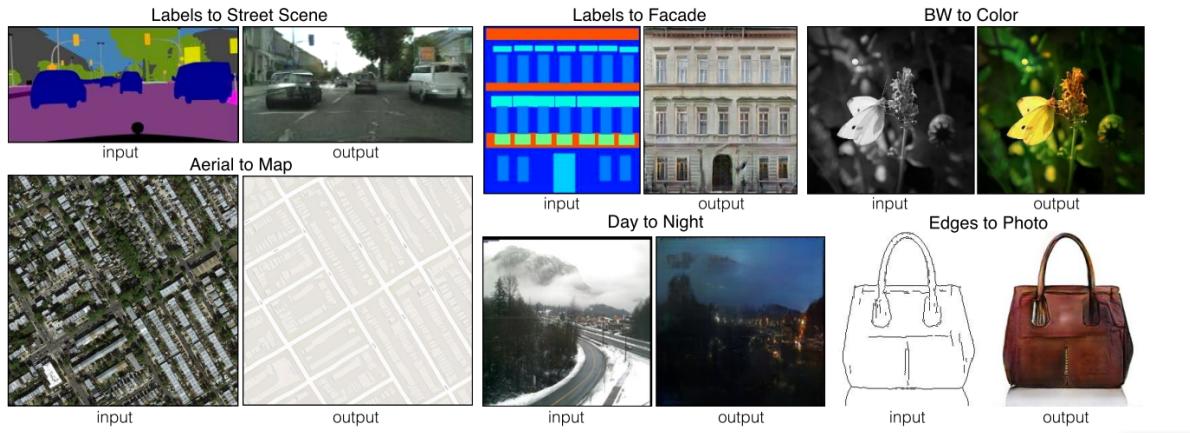


Figure 17: Image Generation example (from Isola et al. (2018)).



Figure 18: Nvidia DLSS: [Link](#)



Figure 19: Norwegian Bride (est late 1890s) from DeOldify: [Link](#)

View Synthesis

In view synthesis, views of certain scenes are generated from models. Neural Radiance Fields (NeRFs) are simple models that can generate new views from known viewpoints and their images. Figure 20 shows the data on which such a model is trained and what can be generated with it.

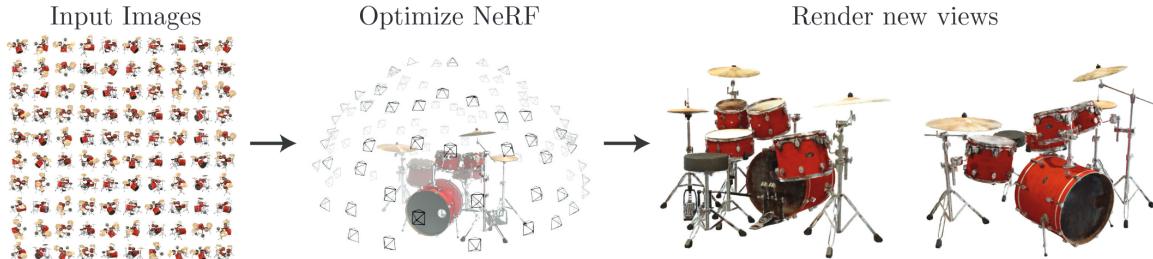


Figure 20: Neural Radiance Fields - example (from Mildenhall et al. (2020)).

Unconditional Generation

In unconditional image generation, data (images) are generated that resemble those in the training data. Here, you have no direct control over the model's output. However, you can often make changes to generated images or interpolate between data points. Figure 21 shows generated images from a model trained on portrait images of people.

Figure 22 shows how generated images can be further adjusted with manually set reference points.

Text to Image

Figure 23 shows an example of image generation from the paper by Rombach et al. (2022), where images are generated conditioned on text inputs.

On [civitai](#), there are numerous examples and models to admire or download.

Pipelines

Various models can also be combined into pipelines. One example is [Grounded-Segment-Anything](#), shown in Figure 24. Object detection models that process text queries are used to detect objects. These detections are used by a segmentation model to segment the target object. This segmentation is then used in a text-to-image model to make the desired change at the correct location.



Figure 21: StyleGan3 (from Karras et al. (2021)).

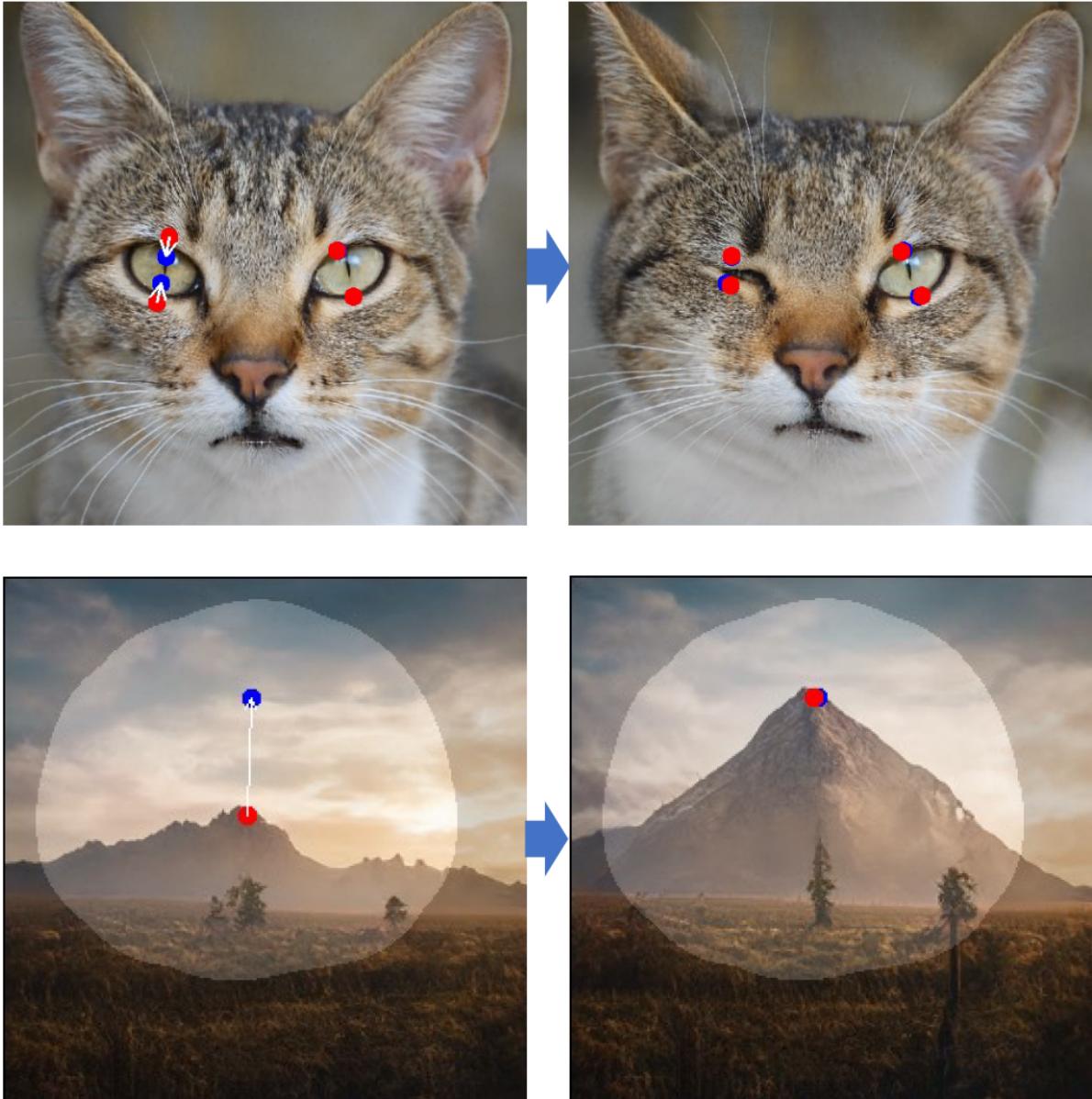


Figure 22: DragGAN (from Pan et al. (2023)).

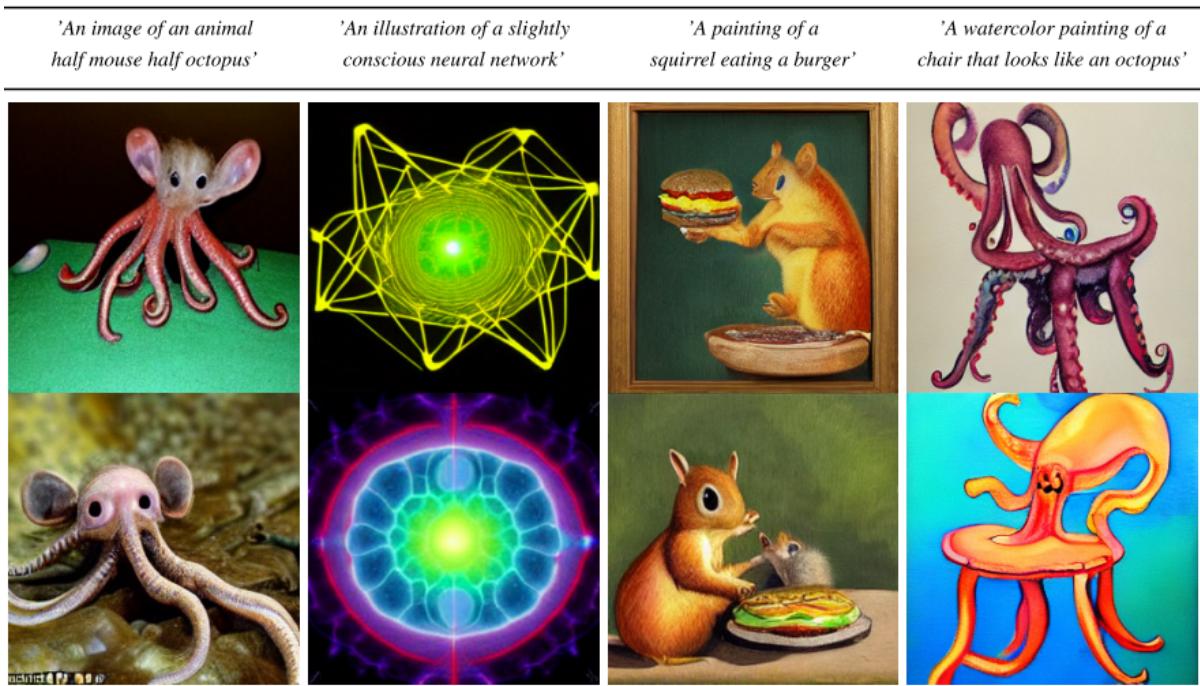


Figure 23: Image Generation example (from Rombach et al. (2022).)

Input Image	Det Prompt	Annotated Image	Inpaint Prompt	Inpaint Image
	Bench		A sofa, high quality, detailed	

Figure 24: Example from Grounded-Segment-Anything [Link](#)

Image Analysis Libraries

There are numerous open-source libraries that provide pre-trained models to handle the tasks mentioned above. Therefore, you do not always have to train a model yourself. Figure 25 shows the capabilities of Detectron 2, an object detection library from Facebook, which can also be used for other tasks like segmentation.



Figure 25: Example from Facebook's Detectron Library [Link](#)

Hugging Face is also well-known. It offers numerous models and datasets for various computer vision questions like object detection, segmentation, and classification.

Machine Learning

We follow a data-driven approach in machine learning to solve various tasks. Typically, the process involves:

- Collecting a dataset of images and their labels.
- Using a machine learning algorithm to train a model that learns to associate images with labels.
- Evaluating/applying the model on new data.

```

def train(images, labels):
    """ Train a Model """
    # Fit Model here
    return model

def predict(test_images, model):
    """ Predict """
    predictions = model(test_images)
    return predictions

```

i Question

How would you train a model for super resolution? The task of the model would be to scale low-resolution images to high-resolution images with the best possible quality.

Machine Learning Process

When modeling data, one often follows certain process steps: acquiring data, preparing it, training multiple models, selecting the most suitable model, estimating its future performance, and finally deploying it in production. Figure 26 illustrates this process graphically.

At the core of a machine learning application is typically a mathematical model, which is fitted to a dataset so that it can then be used for prediction (in supervised learning). We often refer to ‘models’, meaning the mathematical description of the dataset.

Models

A model is typically described as a function of a data point, generating an output \hat{y} :

$$f(\mathbf{x}^{(i)}) = \hat{y}^{(i)}$$

Most models have parameters or coefficients that describe the model. The entirety of all parameters is denoted by θ .

$$f_{\theta}(\mathbf{x}^{(i)}) \text{ or } f(\theta, \mathbf{x}^{(i)})$$

For simplicity, we often omit θ : $f(\mathbf{x}^{(i)})$

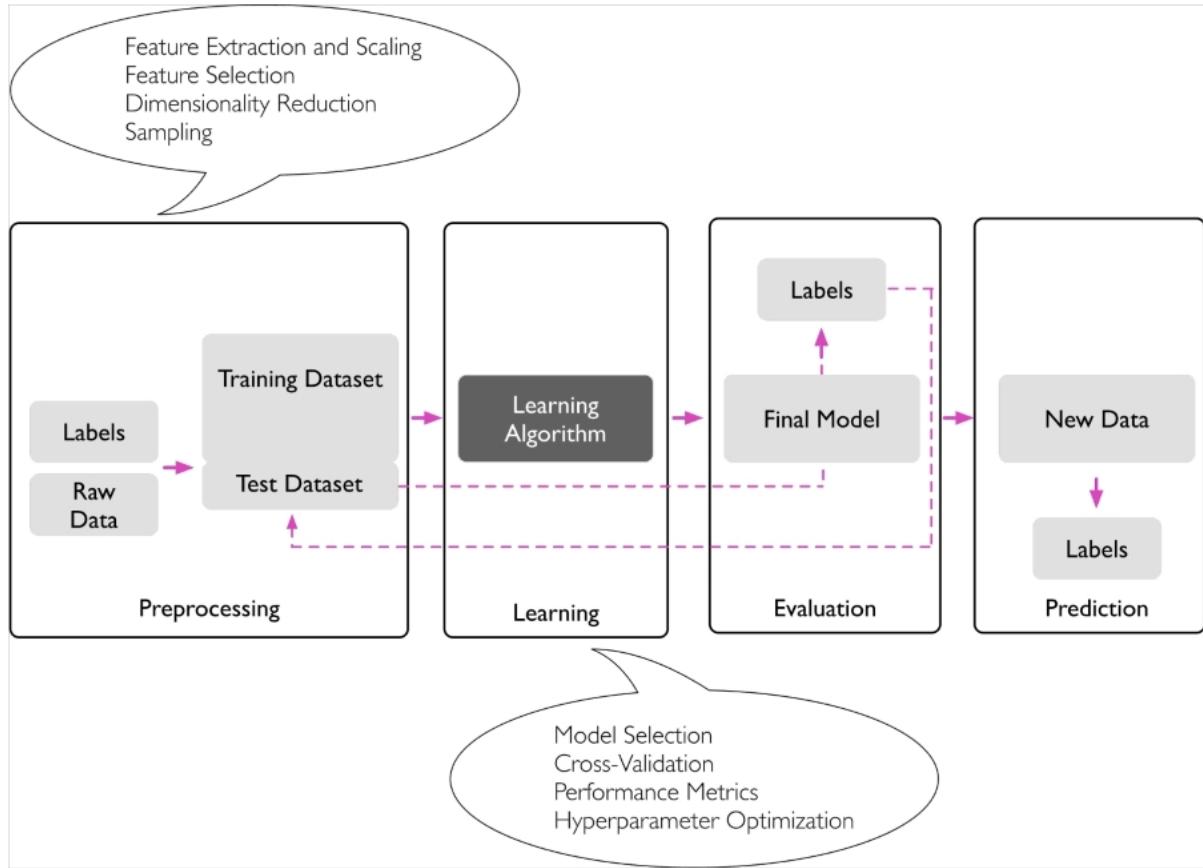


Figure 26: Machine Learning Pipeline (Source: Raschka and Mirjalili (2020))

Optimization

The coefficients are fitted to a training dataset through an optimization procedure.

The optimization procedure can often be influenced by additional factors, called hyperparameters (α, λ, \dots). These cannot be directly optimized.

The function/quantity to be optimized is usually called the cost function, i.e., cost function (other terms include objective function, loss function, etc.). We use $J(\cdot)$ to denote the cost function. Often, the cost function is also referred to as the loss function $L(\cdot)$. We use $l(\cdot)$ for the per-sample loss, i.e., the computation of the cost function on a single sample.

Our goal is to find a model (and its parameters) that minimizes the cost function:

$$\operatorname{argmin}_{\theta, \lambda} J(f_{\theta, \lambda}(\mathbf{X}), \mathbf{y})$$

Usually, preprocessing of variables precedes the learning of

the coefficients. Forms of preprocessing include standardizing, normalizing, feature encoding, dimensionality reduction, and more. This preprocessing also affects the optimization procedure and can be considered hyperparameters.

Model Selection

Model selection is one of the most important and complex components of the machine learning process. This step involves comparing multiple models and selecting the “best” model for the task to be modeled. Which model is the “best” must be defined based on a metric that measures the model’s performance.

If we calculate the value of the metric on the training dataset, our model is usually too optimistic about its general performance. This is because the data points in the training dataset were directly used to optimize the cost function, and the model coefficients are thus optimally adjusted to them. New data points, for which predictions are to be made, could not have been used for optimization. Therefore, a dataset is usually divided into a training set and a test set. The model is trained with the training set and its performance is measured on the test set. When comparing many models, it is advisable to compare them on a separate validation set (see Figure 27) and evaluate only the best model on the test set. This makes the estimate on the test set more accurate.

Train-Test Split

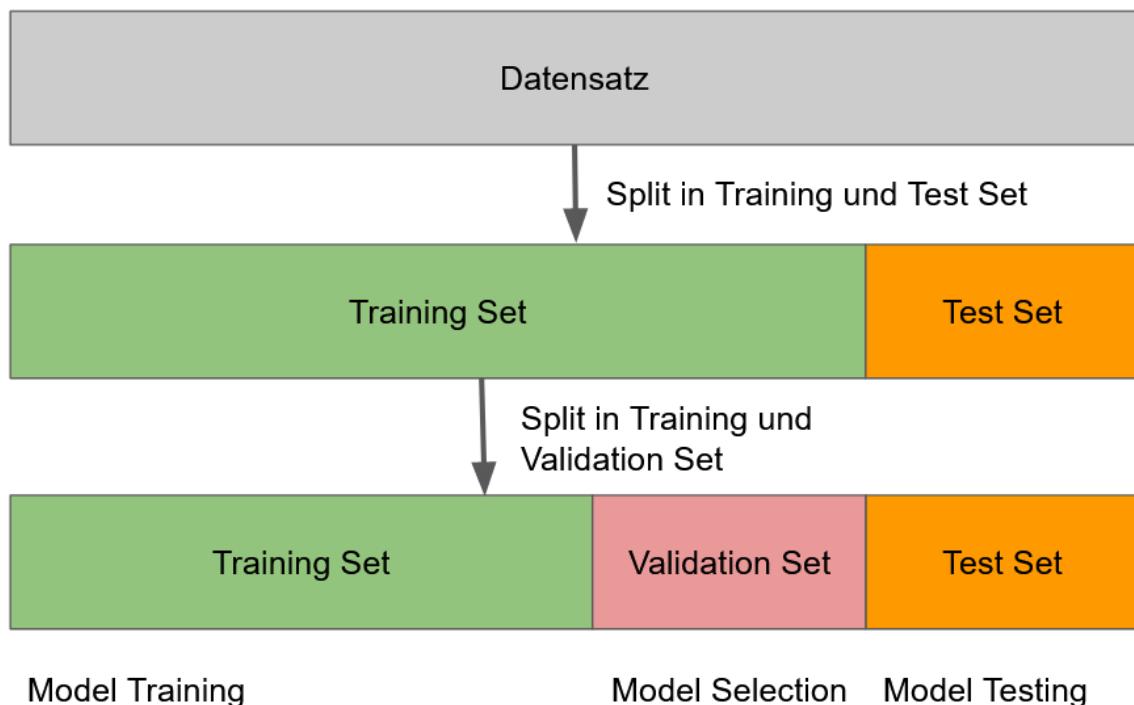


Figure 27: Train-Test Split to select and evaluate models.

ML with Classical Computer Vision

Images typically have very high dimensionality. For example, an RGB image with a resolution of 800×600 has a dimensionality of $800 \times 600 \times 3 = 1,440,000$. Classical machine learning algorithms often struggle with such high dimensionalities:

- They are very slow or require a lot of memory.
- They cannot exploit the 2-D structure of images.
- They are very sensitive to slight changes in images (e.g., rotations).
- They can easily overfit, as the number of features is close to the number of observations (training set).

When modeling images with (classical) machine learning algorithms, methods from (classical) computer vision are often used. With the help of such methods, features can be extracted from images, and the algorithms can learn on these features. This avoids modeling high-dimensional raw data. Figure 28, Figure 29, and Figure 30 show various feature extraction methods.

Figure 28 shows that, for example, the distribution over the color spectrum can be extracted from an image. This could be an important feature.

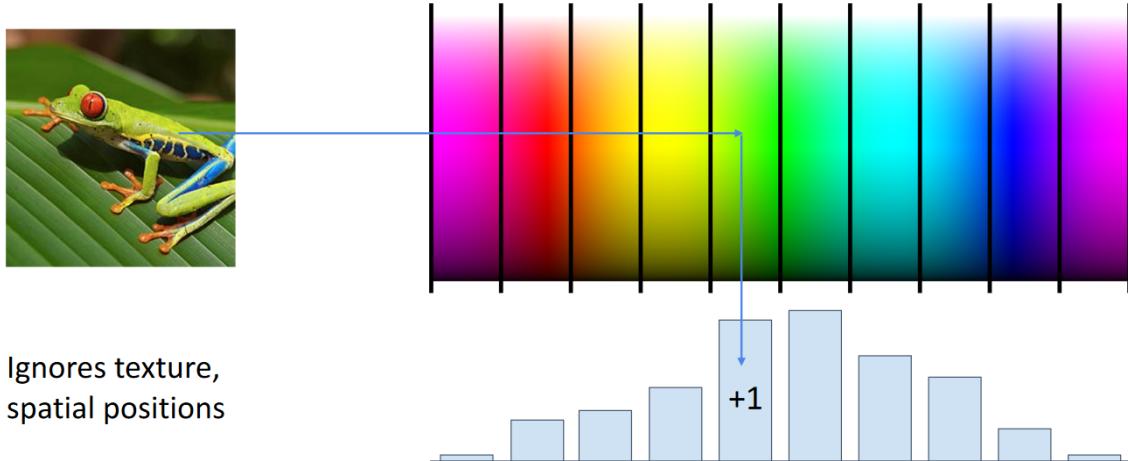


Figure 28: Color Histograms as Features (Source: Johnson (2022))

Figure 29 shows that techniques like Histogram of Oriented Gradients (HOG) Dalal and Triggs (2005) can be used to extract structures from images. Such features were successfully used for pedestrian detection Dalal and Triggs (2005).

Figure 30 shows another feature variant. Visual patches can be extracted from a dataset, clustered, and then used as descriptors.

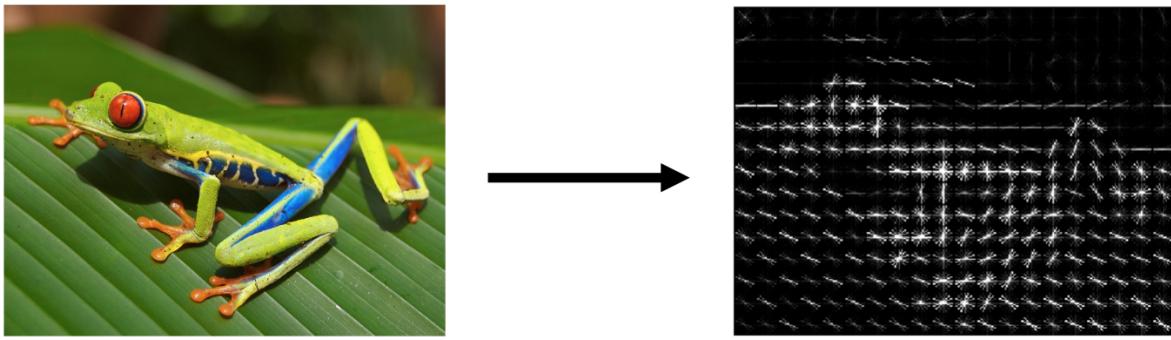


Figure 29: HOG as Features (Source: Johnson (2022))

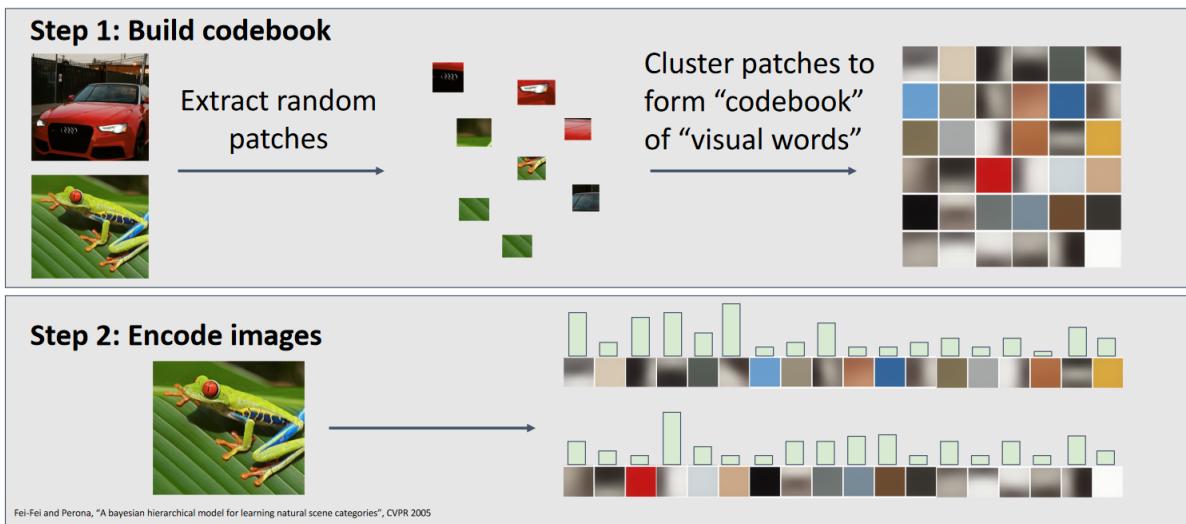


Figure 30: Bag of (visual) words Features (Source: Johnson (2022))

Finally, all features can be combined, often more is better, as shown in Figure 31.

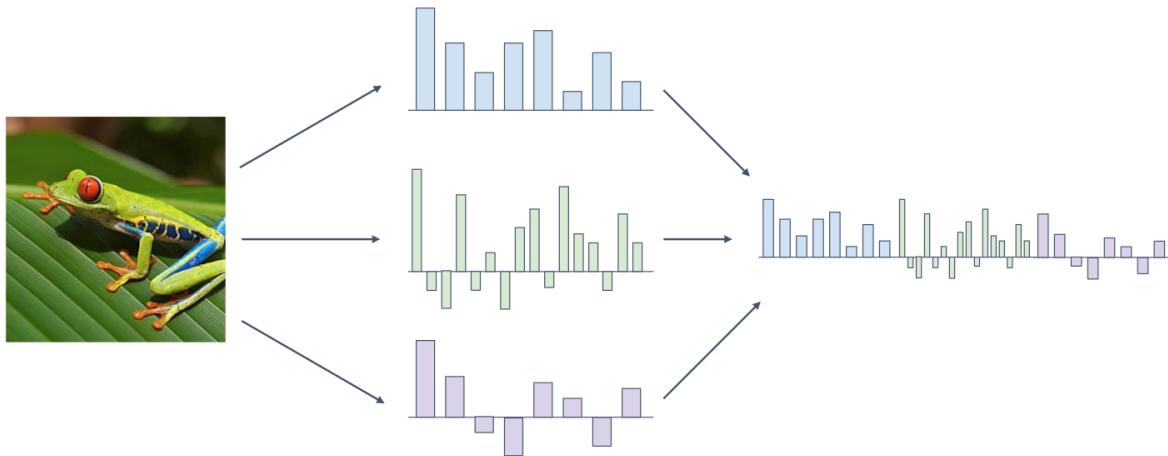


Figure 31: Image Features (Source: Johnson (2022))

Depending on the parameterization, HOG descriptors, for example, can be very large for images. The resulting feature vector from Figure 31 can still be reduced in dimensionality, e.g., with Principal Component Analysis.

Figure 32 shows the CIFAR10 dataset. A well-known dataset for testing models, consisting of 10 classes with 6,000 images each.

Deep Learning

To accelerate research in computer vision and make progress more measurable, the PASCAL VOC Challenges were introduced Everingham et al. (2007). These involved various tasks, such as detecting objects in photographs (Figure 33).

The easy availability of images on the internet has made it possible to collect increasingly larger datasets. [ImageNet](#) is such a very large, hierarchically annotated image dataset Deng et al. (2009) with over 1.4 million images, categorized into 1,000 object classes. Figure 34 illustrates the dataset.

Since 2010, challenges have been regularly conducted on the ImageNet dataset Russakovsky et al. (2015), such as image classification and object detection. Figure 35 shows the development of the error rate over time.

In 2011, a team won Perronnin et al. (2010) by combining various (classical) feature extraction methods with machine learning. They used, among other things, SIFT features to train SVMs.

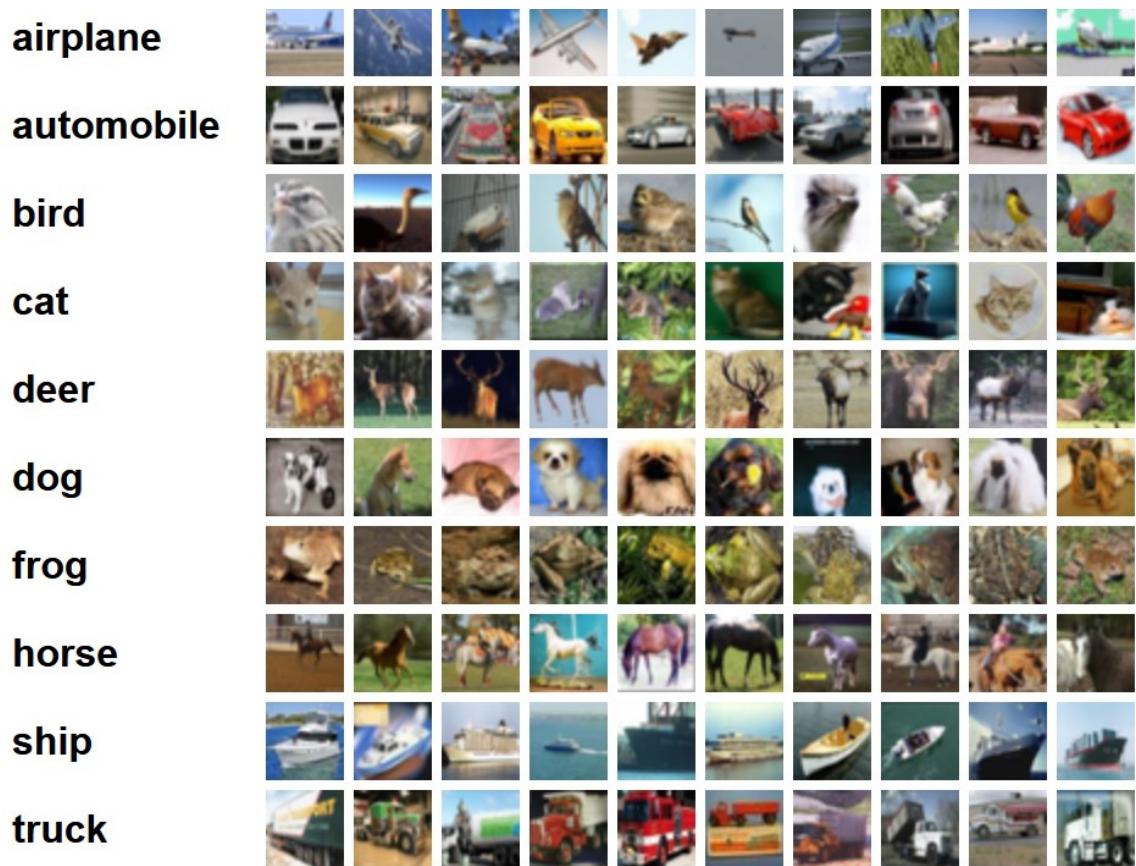


Figure 32: CIFAR10 Dataset [Source](#)

PASCAL VOC 2007

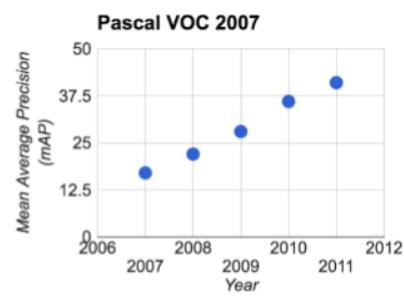
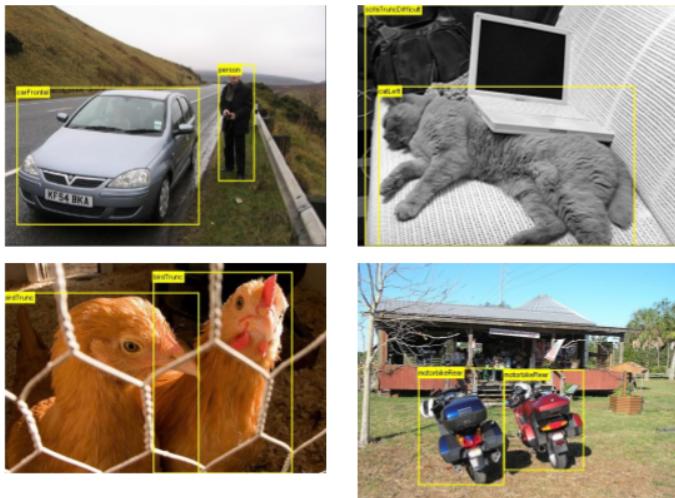


Figure 33: Images/illustrations from [Link](#) and Johnson (2022). On the left, you see object annotations in images, and on the right, you see the development of Mean Average Precision over the years.



Figure 34: [ImageNet](#), [Image Source](#), details in Deng et al. (2009)

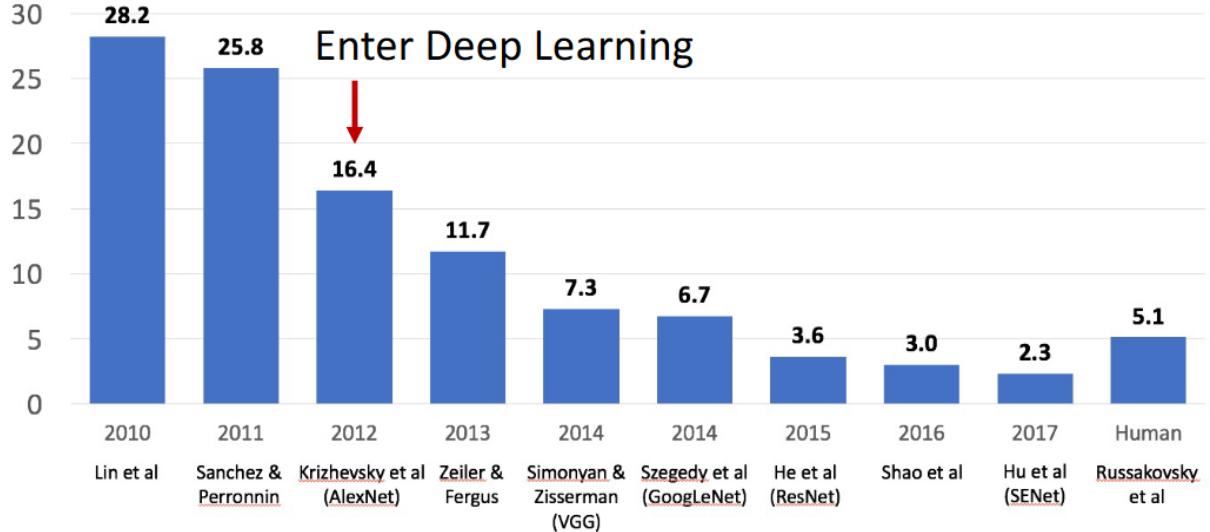


Figure 35: Source: Johnson (2022)

In 2012, a drastic reduction in the error rate was achieved in the ImageNet competition. This development marked the end of classical computer vision methods in many areas. Krizhevsky et al. Krizhevsky, Sutskever, and Hinton (2012) impressively demonstrated the potential of neural networks in 2012. They implemented a convolutional neural network (CNN) with multiple layers, the so-called AlexNet architecture, as shown in Figure 36.

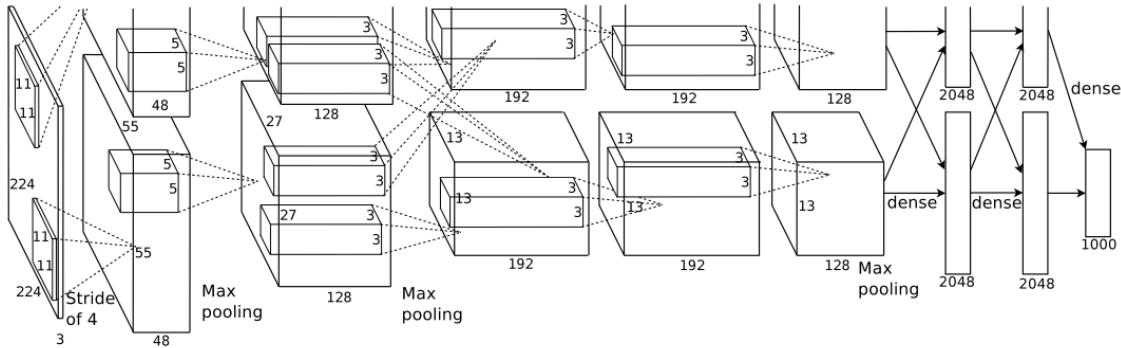


Figure 36: Alexnet Krizhevsky, Sutskever, and Hinton (2012).

While classical computer vision trains a machine learning model on features extracted with hand-crafted algorithms Figure 37, the development is increasingly moving towards end-to-end learning. In this approach, one avoids as much as possible static/hand-designed components and learns everything, including feature extraction, with machine learning Figure 38.

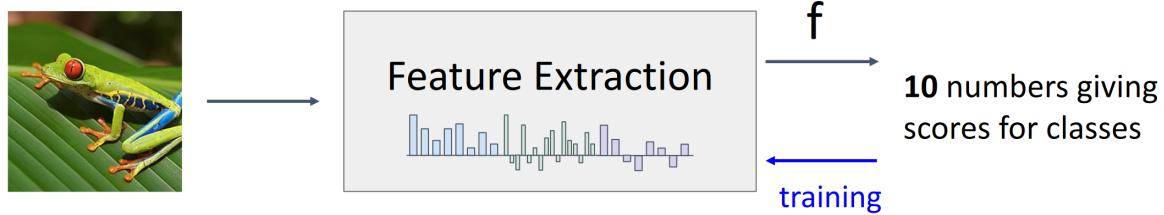


Figure 37: Illustration from Johnson (2022)

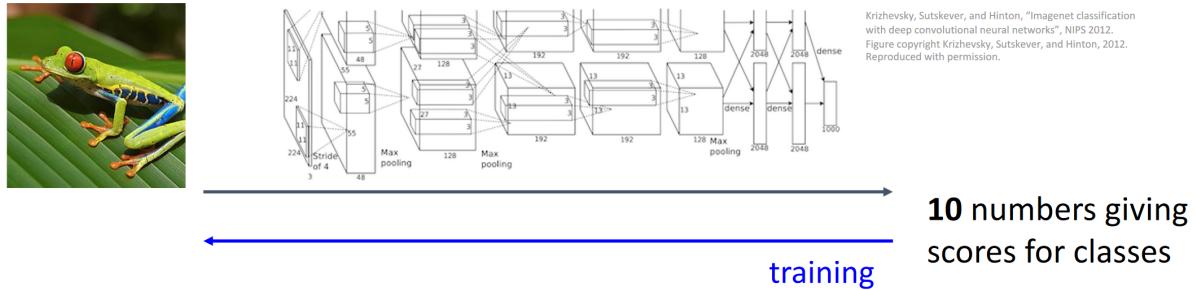


Figure 38: Illustration from Johnson (2022)

Deep learning-based approaches have several advantages over classical machine learning methods:

- Automatic feature extraction: no manual feature extraction procedures are needed.
- Hierarchical features: these are particularly valuable for processing and understanding visual data.
- Generalization: with more training data, deep learning methods generalize better.
- End-to-end learning: this approach allows many problems to be modeled similarly.
- Robustness to variability: certain models are naturally invariant to

transformations like translations, scalings, etc. - Adaptability and transferability: deep learning models can often be easily adapted (transfer learning) and can create good models even with little data.

Deep Learning History

We will now explore the most important milestones in deep learning for image analysis.

Hubel and Wiesel

Hubel and Wiesel (1959) showed in experiments on cats that there are complex cells/neurons in the visual cortex that only respond to certain patterns. In addition to these complex cells, there are also simple cells that only respond to lines at a certain angle.

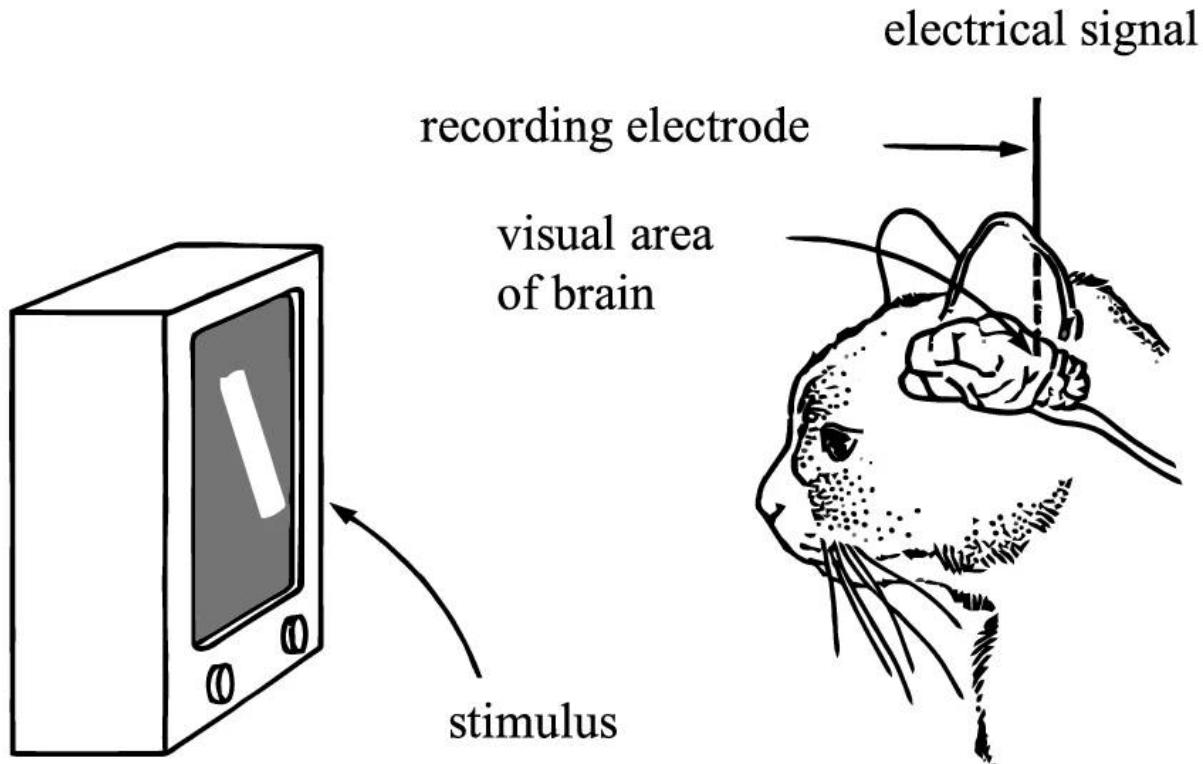


Figure 39: Illustration [Source](#)

Neocognitron

Fukushima (1980) defined a model of a neural network that can recognize visual patterns. It already has the hierarchical structure of a modern convolutional neural network and is inspired by biological neural networks, particularly from the insights of Hubel and Wiesel (1959).

Backpropagation

Rumelhart, Hinton, and Williams (1986) introduced the backpropagation algorithm in the context of neural networks. This algorithm is used to train modern neural networks: it finds

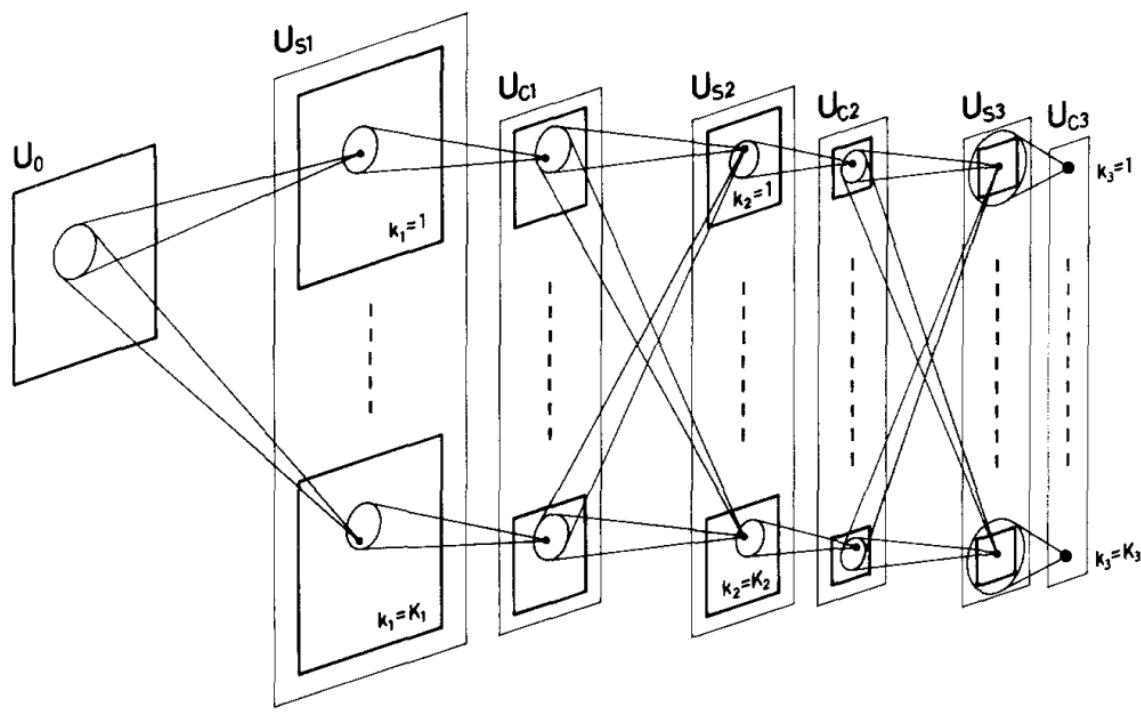


Figure 40: The Neocognitron Fukushima (1980).

the parameters of an artificial neural network (ANN) to solve a specific task. Backpropagation is based on the chain rule from calculus and is also important for other machine learning models.

The backward pass starts by computing $\partial E / \partial y_j$ for each of the output units. Differentiating equation (3) for a particular case, c , and suppressing the index c gives

$$\partial E / \partial y_j = y_j - d_j \quad (4)$$

We can then apply the chain rule to compute $\partial E / \partial x_j$

$$\partial E / \partial x_j = \partial E / \partial y_j \cdot dy_j / dx_j$$

Differentiating equation (2) to get the value of dy_j / dx_j and substituting gives

$$\partial E / \partial x_j = \partial E / \partial y_j \cdot y_j(1 - y_j) \quad (5)$$

This means that we know how a change in the total input x to an output unit will affect the error. But this total input is just a linear function of the states of the lower level units and it is also a linear function of the weights on the connections, so it is easy to compute how the error will be affected by changing these states and weights. For a weight w_{ji} , from i to j the derivative is

$$\begin{aligned} \partial E / \partial w_{ji} &= \partial E / \partial x_j \cdot \partial x_j / \partial w_{ji} \\ &= \partial E / \partial x_j \cdot y_i \end{aligned} \quad (6)$$

Figure 41: Backpropagation in neural networks Rumelhart, Hinton, and Williams (1986).

 Tip

A good video on backpropagation: [3Blue1Brown Backpropagation Calculus](#)

Convolutional Neural Networks (CNNs)

Lecun et al. (1998) implemented convolutional neural networks (CNNs) to recognize hand-written digits. It is specialized for the 2-D structure of the input data. They trained a model very similar to modern CNNs, as shown in Figure 42.

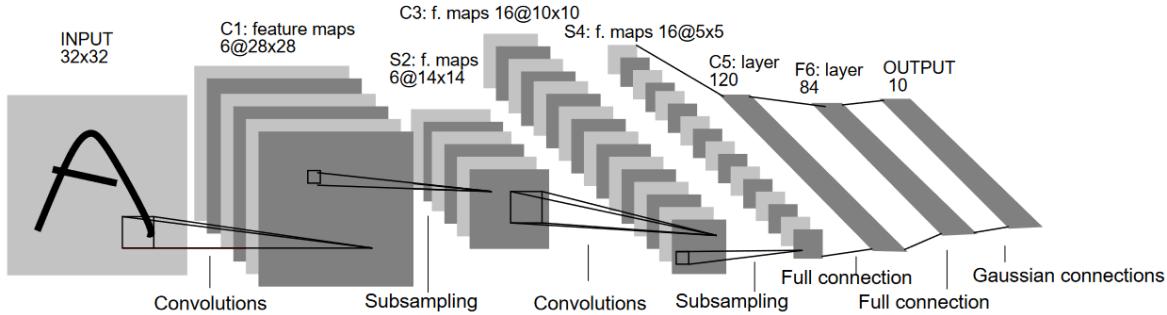


Figure 42: Modern CNN Lecun et al. (1998).

CNNs became extremely popular after winning the [ImageNet](#) competition. Krizhevsky, Sutskever, and Hinton (2012) implemented a CNN with multiple layers, the so-called AlexNet architecture, as shown in Figure 43.

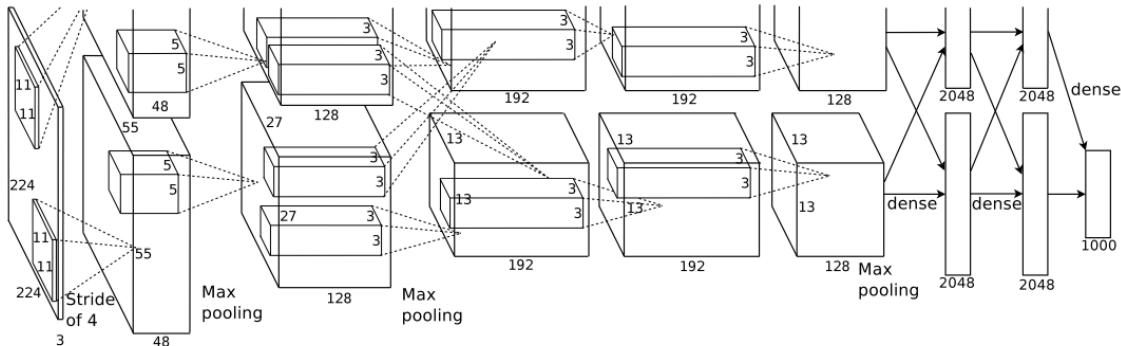


Figure 43: Alexnet Krizhevsky, Sutskever, and Hinton (2012).

Since the breakthrough in 2012, CNNs have been used for increasingly complex tasks and further developed. Well-known are, for example, the [COCO Challenges](#), with various tasks.

Other Architectures in Computer Vision

CNNs are still in use today (2024). Meanwhile, there are alternative architectures, such as transformer-based models Dosovitskiy et al. (2020), which are extremely successful in language modeling, or multilayer perceptron-based architectures Liu et al. (2021). However, it has been shown that CNNs are still competitive and sometimes superior to alternative architectures Woo et al. (2023). The question of which architecture type will prevail is open. Currently, it seems that CNNs and transformer-based models perform similarly Smith et al. (2023).

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