Homework 1

Solutions: 27.05.2024

Part I: Theory

I.1. Linear model example

Exercise I.1 (Polynomial Curve Fitting)**.** Given a set of points and their targets $\{x_i, t_i\}_{i=1}^N$ so that for $i \in [N]$, $x_i \in \mathbb{R}$ and $t_i \in \mathbb{R}$, the *curve fitting problem* is loosely defined as finding a function $f : \mathbb{R} \to \mathbb{R}$ such that $f(x_i) \approx t_i$ for all $i \in [N]$.

In order to find such a function, we restrict ourselves to a set of parametrized functions $\mathcal{F}$: each function can be parametrized with a vector $\boldsymbol{w} \in \mathbb{R}^{D+1}$.

To quantify the problem further, in this exercise, we limit ourselves to *polynomial functions* of degree D for the set $\mathcal{F}$, and can therefore write

$$f(x, \boldsymbol{w}) = w_0 + w_1 x + \ldots + w_D x^D = \sum_{k=0}^{D} w_k x^k \tag{1}$$

Notice how f is *linear* in $\boldsymbol{w}$, the parameter. Such model is called a *linear model.*

With N samples, we defined the loss (or error, or energy) of our parameter as the point-wise square distance between its estimation and the target:

$$E(\boldsymbol{w}) = \frac{1}{2} \sum_{i=1}^{N} \left(f(x_i, \boldsymbol{w}) - t_i\right)^2 \tag{2}$$

1. Is the function E convex in $\boldsymbol{w}$? How to find the optimal parameter $\boldsymbol{w}^\star$ at which the loss is minimum?

2. Compute the gradient $\nabla_{\boldsymbol{w}} E(\boldsymbol{w}) = \begin{pmatrix} \partial_{w_0} E(\boldsymbol{w}) \\ \vdots \\ \partial_{w_D} E(\boldsymbol{w}) \end{pmatrix} \in \mathbb{R}^{D+1}$.

3. Show that the optimal parameter $\boldsymbol{w}^\star$ satisfies the following system of equation:

$$\forall k \in [D+1], \quad \sum_{j=0}^{D} A_{kj} w_j^\star = T_k,$$

where

$$A_{kj} = \sum_{i=1}^{N} (x_i)^{k+j}, \qquad T_k = \sum_{i=1}^{N} (x_i)^k t_i. \tag{3}$$

4. Is such a system of equation solvable? When / not?

It is usual to add a *regularizer* to the objective, penalizing "complex" models. This also can help selecting a model when several models are solutions to the optimization problem.

One of the most common regularizer is the parameter squared-norm: with a *penalizer weight* $\lambda \in \mathbb{R}_+$, the Equation (2) is modified to give

$$E_\lambda(\boldsymbol{w}) = E(\boldsymbol{w}) + \frac{\lambda}{2}\|\boldsymbol{w}\|^2 = \frac{1}{2}\sum_{i=1}^{N}\left(f(x_i,\boldsymbol{w}) - t_i\right)^2 + \frac{\lambda}{2}\|\boldsymbol{w}\|^2. \tag{4}$$

resume What is the role of λ?

resume Is E_λ convex?

resume Show that each component of the optimal weight $\boldsymbol{w}_i^\star$ is now found by solving

$$\forall k \in [D+1], \quad \sum_{j=0}^{D} A_{kj}w_j + \lambda w_k = T_k,$$

with A_{kj} and T_k defined as in Equation (3).

Matrix expression It is sometimes preferable to deal with vector and matrices, rather than scalar expressions. When the model is linear in $\boldsymbol{w}$, it is possible to express it as a *linear product* between a matrix and a vector. The expression in Equation (1) can be thought as a dot product between w and the vector of powers of x, that define as $\boldsymbol{\phi}(x) \coloneqq \begin{pmatrix} 1 \\ x \\ x^2 \\ \vdots \\ x^D \end{pmatrix}$, so that

$$f(x,\boldsymbol{w}) = \boldsymbol{w}^\top \boldsymbol{\phi}(x).$$

Stacking all the N examples in a matrix, and denoting $\boldsymbol{\phi}_i \coloneqq \boldsymbol{\phi}(x_i)$, we define

$$\Phi \coloneqq \begin{pmatrix} | & | & & | \\ \boldsymbol{\phi}_1 & \boldsymbol{\phi}_2 & \cdots & \boldsymbol{\phi}_N \\ | & | & & | \end{pmatrix} \in \mathbb{R}^{(D+1)\times N}$$

and can therefore compute the model *on the whole dataset* in one expression: $\boldsymbol{y}(\boldsymbol{w}) = \Phi^\top \boldsymbol{w} \in \mathbb{R}^N$. Each entry i of $\boldsymbol{y}$ corresponds to a different sample x_i. Then, stacking the targets into a vector $\boldsymbol{t} \in \mathbb{R}^N$, the error function (2) can equivalently written as

$$E(\boldsymbol{w}) = \frac{1}{2}\|\boldsymbol{y}(\boldsymbol{w}) - \boldsymbol{t}\|^2,$$

and the regularized error as

$$E_\lambda(\boldsymbol{w}) = \frac{1}{2}\|\boldsymbol{y}(\boldsymbol{w}) - \boldsymbol{t}\|^2 + \frac{\lambda}{2}\|\boldsymbol{w}\|^2$$

resume Show that $\nabla E_\lambda(\boldsymbol{w}) = \Phi(\Phi^\top \boldsymbol{w} - \boldsymbol{t}) + \lambda \boldsymbol{w}$, so that $\boldsymbol{w}^\star$ solves the linear equation

$$(\Phi\Phi^\top + \lambda I_{D+1})\boldsymbol{w}^\star = \Phi \boldsymbol{t}.$$

I.2. Subgradients

When a convex loss function $E\colon \mathbb{R}^d \to \mathbb{R}$ is not differentiable, its *subgradient* can be used. It is defined as the set, for $x \in \mathbb{R}^d$,

$$\partial E(x) = \{g \in \mathbb{R}^d \mid \forall y \in \mathbb{R}^d,\, E(y) \geqslant E(x) + \langle g, y - x\rangle\}.$$

If E is differentiable at x, then $\partial E(x) = \{\nabla E(x)\}$.

For instance, for $E\colon \mathbb{R} \to \mathbb{R}$, $x \mapsto E(x) = |x|$, E is differentiable at any $x \neq 0$, with gradient -1 on $(-\infty, 0)$ and 1 on $(0, +\infty)$.

At $x = 0$, we compute, for any $y \in \mathbb{R}$ and $g \in \mathbb{R}$:

$$\begin{aligned} E(y) \geqslant E(0) + \langle g, y - 0\rangle &\iff |y| \geqslant \langle g, y\rangle \\ &\iff |y| \geqslant gy \end{aligned}$$

This condition has to be true for *any* $y \in \mathbb{R}$. This is only true when $g \in [-1, 1]$. Therefore,

$$\partial E(x) = \begin{cases} \{-1\} & \text{if } x < 0 \\ [-1, 1] & \text{if } x = 0 \\ \{1\} & \text{if } x > 0 \end{cases}$$

Geometrically, this can be interpreted as having, for the absolute value at the origin, any lines with slope between -1 and 1 lower-bounding the graph of the function.

Exercise I.2. Let $E\colon \mathbb{R} \to \mathbb{R}$, $x \mapsto E(x) = \max(0, 1 - x)$.

1. Where is E differentiable?
2. Show that $\partial E(x) = \begin{cases} \{-1\} & \text{if } x < 1 \\ [-1, 0] & \text{if } x = 1 \\ \{0\} & \text{if } x > 1 \end{cases}$

Part II: Programming

Exercise II.1 (Model fitting)**.** This exercise implements some results found in Exercise I.1.

1. **Generation of the target.** In this toy example, we generate the N points ourselves. The true target t_i will be sinusoidal, with some noise, i.e. $t_i = \sin(2\pi x_i) + \varepsilon$, where $\varepsilon \sim \mathcal{N}(0, \sigma^2)$. The different scales (for σ,x_i) are given as $\sigma = 0.1$, and $x_i \sim \mathcal{U}([0, 1])$, uniform distribution on the segment $[0, 1]$.

   The generation of the data is performed by the function `gen_s_in_d_ata` in the file `ex02/utils.py`.

2. Implement the parametrization function (1) as `f(x,w)`, where the dimensions D is implied by the size of `w`.

3. Implement the error function E defined in (2), and its gradient $\nabla E(w)$.

4. Find $\boldsymbol{w}^\star$, either by

   a) gradient descent; or

   b) solving the linear system of equations (3).