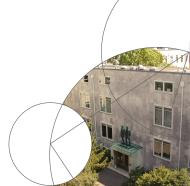


Faculty of Science

Multireduce and Multiscan on Modern GPUs

Master's thesis defence

Marco Eilers Department of Computer Science



#### Overview

- Introduction
- 2 Sequential algorithms
- GPUs and CUDA
- Sort-based algorithms
- **6** Adaptation of sequential algorithm
- 6 Example of multireduce in shared memory
- Results and conclusion



# Reduce and scan Works on any monoid M with binary function $\odot$



Works on any monoid M with binary function  $\odot$  Examples with integers and addition

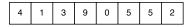


Works on any monoid M with binary function  $\odot$  Examples with integers and addition Input vector

| 4 | 1 | 3 | 9 | 0 | 5 | 5 | 2 |
|---|---|---|---|---|---|---|---|
|---|---|---|---|---|---|---|---|



Works on any monoid M with binary function  $\odot$  Examples with integers and addition Input vector

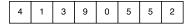


Reduce: Sum of all values

30



Works on any monoid M with binary function  $\odot$  Examples with integers and addition Input vector



Reduce: Sum of all values

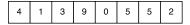
30

Scan: Sums of all prefixes





Works on any monoid M with binary function  $\odot$  Examples with integers and addition Input vector



Reduce: Sum of all values

30

Scan: Sums of all prefixes



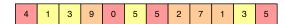
Segmented reduce/scan: Partition input into contiguous segments and reduce/scan them separately



#### Input labels

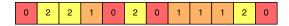


## Input values

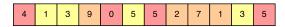




#### Input labels



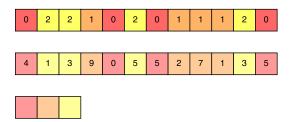
#### Input values



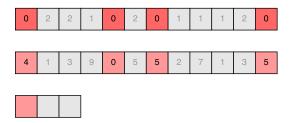
#### Output:



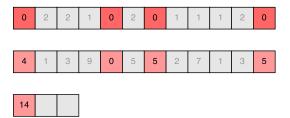




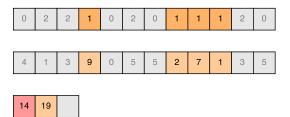




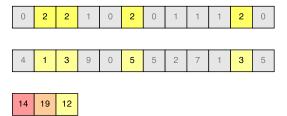












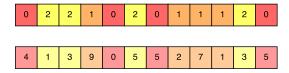


## Indentical inputs:

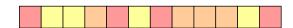
| 0 | 2 | 2 | 1 | 0 | 2 | 0 | 1 | 1 | 1 | 2 | 0 |
|---|---|---|---|---|---|---|---|---|---|---|---|
|   |   |   |   |   |   |   |   |   |   |   |   |
| 4 | 1 | 3 | 9 | 0 | 5 | 5 | 2 | 7 | 1 | 3 | 5 |



#### Indentical inputs:



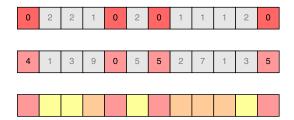
#### Different output:



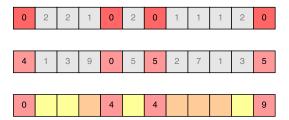


| 0 | 2 | 2 | 1 | 0 | 2 | 0 | 1 | 1 | 1 | 2 | 0 |
|---|---|---|---|---|---|---|---|---|---|---|---|
|   |   |   |   |   |   |   |   |   |   |   |   |
| 4 | 1 | 3 | 9 | 0 | 5 | 5 | 2 | 7 | 1 | 3 | 5 |
|   |   |   |   |   |   |   |   |   |   |   |   |
|   |   |   |   |   |   |   |   |   |   |   |   |

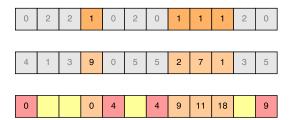




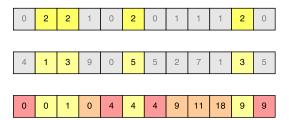














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Immediate applications are

- Radix sort
- Sparse matrix vector multiplication



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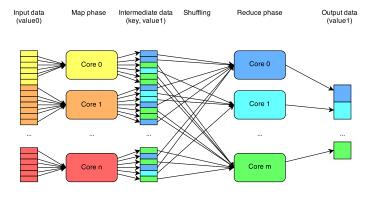
- Radix sort
- Sparse matrix vector multiplication

Multireduce generalizes important operations

- Histograms
- Scattering

General multireduce can be used for MapReduce framework







# Sequential algorithms

Sequential algorithms for both operations are trivial. **function** multiReduce(int n, int m, int indices[n], int values[n], int buckets[m]):

```
\begin{array}{c|c} \textbf{for } i=0 \textbf{ to } m-1 \textbf{ do} \\ \mid buckets[i]=0; \\ \textbf{end} \\ \textbf{for } i=0 \textbf{ to } n-1 \textbf{ do} \\ \mid buckets[indices[i]]+=values[i]; \\ \textbf{end} \\ \end{array}
```

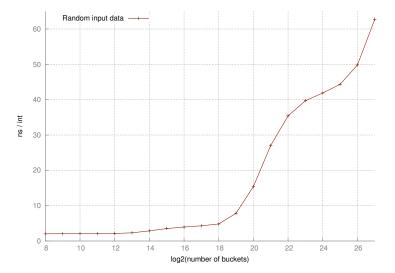


# Sequential algorithms

```
Sequential algorithms for both operations are trivial.
function multiScan(int n, int m, int indices [n], int
values[n], int result[n]):
   int buckets[m];
   for i = 0 to m - 1 do
       buckets[i] = 0;
   end
   for i = 0 to n - 1 do
       result[i] = buckets[indices[i]];
       buckets[indices[i]] += values[i];
   end
end
```



# Performance problems





# Performance problems

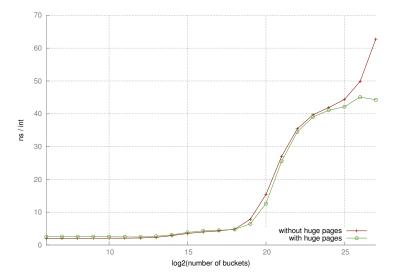
- TLB misses
- Cache misses





Huge pages can be used to mitigate the problem of TLB misses

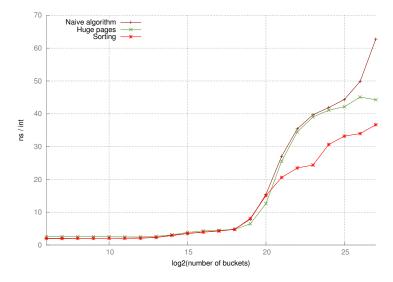






Sorting the input by labels turns random bucket accesses into sequential ones and avoids cache misses







# Applicability of sorting approach

Sorting *can* lead to a performance gain in some scenarios. Think accesses to disk, network, ...



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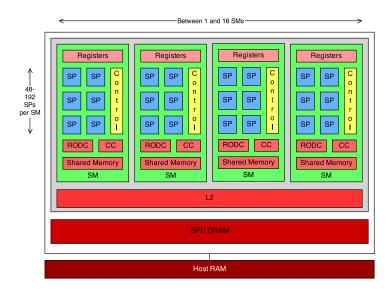
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- Finding the right parameters is non-trivial.

Developed a simulator to predict performance.

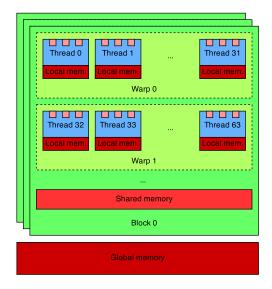


#### **GPUs**





#### CUDA architecture







Hundreds of threads per SM



- Hundreds of threads per SM
- Limited memory bandwidth



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- Limited memory bandwidth
- Latency hiding



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- Synchronization





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- Usually assume SIMD
  - Require sync after each step...
  - ...which is either slow or impossible
- No concept of block-level shared memory
- Generally not much attention paid to memory layout
  - Often uncoalesced memory accesses
  - Often bank conflicts
  - Generally less focus on avoiding memory accesses



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Apply it directly to the entire input



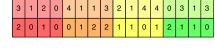
Assume, a multireduce algorithm is given. There are two possibilities to use it:

- Apply it directly to the entire input
- Partition the input into several segments, apply the algorithm to all segments in parallel, then combine partial results





Input labels



Core 0 Core 1 Core 2

Core 3

#### ←nSegments →

Store the partial reductions for each segment





Reduce partial results for each bucket





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- ... in global memory
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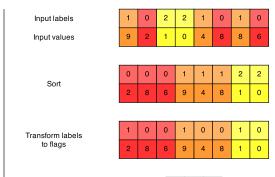
This results in three ways to implement (almost) any given algorithm.



# Sort-based algorithms

#### Idea:

- Sort input by labels, so that values for identical labels are adjacent
- 2 Reduce/scan values for each label...
  - ... using a segmented reduce/scan



Seamented reduce





## Adapting the sequential algorithm

Idea: Apply the partitioning trick again on a block level. Let each thread work sequentially on its own segment of the input data, calculating its own partial result ("bucket set").



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- Arbitrary amounts of parallelism
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#### Problems:

- Random access reads/writes
- Input data is required in contiguous blocks, but fastest access is strided
- Many partial results have to be combined



### Optimization for multireduce

Many of the most frequently used operators are commutative.



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- Input data can be processed in any order
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#### Consequently

- Less partial results to process
- Optimal data access pattern without further effort
- · Less cache misses
- Atomic operations needed



- Adaptation of sequential algorithm
- For commutative operators only
- Bucket sets stored in shared memory
- Derived from histogram algorithm



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Memory layout is the deciding factor.



#### Two approaches for histogram algorithms:

- Per-block bucket sets
  - Large amounts of parallelism
  - · Bank and write conflicts
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## Example of multireduce in shared memory

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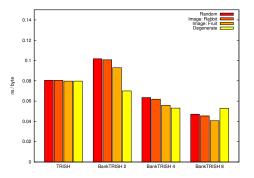
- Large amounts of parallelism
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Resulting multireduce is faster than the best histogram algorithm, but much more general.



## Application to histogramming

Algorithm can be transferred back to histogramming, resulting in a 40% speedup on average.







- Sorting approach
  - More complicated



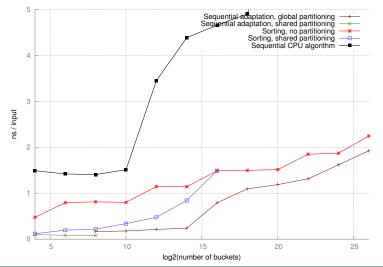
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- Sorting approach
  - More complicated
- Adaptation of sequential algorithm
  - Similar to non-commutative multireduce case
- PRAM algorithm by Sheffler
  - Frequent memory accesses
  - Frequent synchronizations
  - Much data, few threads



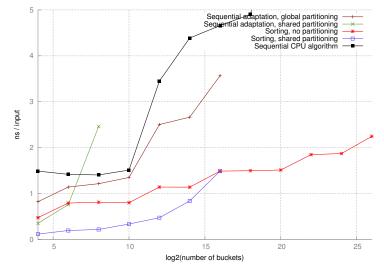
# Performance of multireduce With commutative operator:





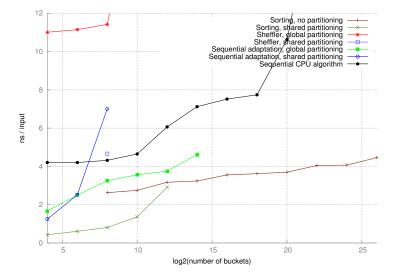
## Performance of multireduce

## With non-commutative operator:





## Performance of multiscan







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  - Improve simulator



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- Algorithm optimization



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- Explore sorting for better cache use
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- Algorithm optimization
- Applications of multireduce
- Language integration



Thank you for your attention!

Questions?

