Marco Maida

Tech Lead, Inference Performance

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I'm a software engineer with over **ten years of experience** building systems that address complex, real-world problems. I worked in the fields of **industrial software**, **videogames**, **real-time systems**, **formal verification**, and **autonomous vehicles**. I'm currently based in **London**, where I lead the inference performance team at **Wayve**. We focus on improving the latency and reliability of Wayve's self-driving stack. I work mainly in **C++**, **Rust**, and **Python**, and I'm particularly interested in problems where **performance**, **correctness**, and **practical constraints** come together.

Professional Experience

Since 2022 **Software Engineer – Autonomous Vehicles**

Wayve Ltd

I designed, implemented, and maintained several key systems within Wayve's on-board software stack for autonomous vehicles. This includes sensor data collection, alignment, packaging, data upload, and real-time neural network inference. Since December 2024, I have been serving as the **Tech Lead** of the inference performance team, responsible for the core inference component. (ROS2, Linux Kernel, C++, Rust, Python).

2016-2019 **Software Engineer – Videogames**

34BigThings

I contributed to five major game titles, focusing on game infrastructure, AI, gameplay, and development tools. I worked on both single-player and online multiplayer games shipped on Steam, PS4, XboxOne, Switch, and mobile platforms. (Unity3D, C#, Unreal Engine, C++).

2015-2016 **Software Engineer – Videogames, Simulation**

Maserati, Choralia

I led two freelance B2B projects: developing an educational game for mobile and browsers, and collaborating to create a 3D visualization tool for product presentation. (*Unity3D*, *C#*, *JavaScript*).

2013-2016 **Software Engineer – Industrial Software**

R.O. sr

I contributed to a suite of software solutions for glass processing factories, focusing on order tracking and optimizing machine work, product waste, and logistics. During my third year, I managed a team of 4 junior engineers. (C, C++, C#, SQL).

Education and Research

2022 Research Internship

Bloomberg LP

I worked on accelerating SAT solving using GPUs. (C++, CUDA).

2019-2022 **PhD Student**

Max Planck Institute

My research focused on formal verification and real-time systems, specifically verifying the timeliness of software systems. I published three papers and mentored three interns. (COQ, C, Rust).

2019-2022 Master's in Computer Science

Technische Universität Kaiserslautern

I specialized in real-time systems as part of a joint master's and PhD program.

2016-2019 Bachelor's in Computer Science

Università degli Studi di Torino

I specialized in computability and formal methods.

Selected Publications

2025 Claycode: Stylable and Deformable 2D Scannable Codes

SIGGRAPH 2025

★ Journal publication in Transactions of Graphics. Selected for CAF trailer.

We introduced Claycodes, a new type of visual code that breaks free from traditional rigid grids like QR codes. Claycodes encode data as a tree structure and allow full customizability and deformation, with real-time scanning capabilities. (https://arxiv.org/abs/2505.08666).

2022 From Intuition to Coq: A Case Study in Verified Response-Time Analysis, FIFO Scheduling

RTSS 2022

We developed a formally verified response-time analysis for FIFO schedulers, challenging traditional pen-and-

paper methods. (https://people.mpi-sws.org/~kbedarka/rtss22.pdf).

Foundational Response-Time Analysis as Explainable Evidence of Timeliness

ECRTS 2022

×Outstanding Paper Award.

I developed POET, a tool for formally verified worst-case scenario timing analysis. (https://drops.dagstuhl.de/opus/volltexte/2022/16336/pdf/LIPIcs-ECRTS-2022-19.pdf).

Selected Open-Source Projects

2025 Claycode https://claycode.io

Inventor and lead contributor. Claycode includes a generator website, an Android scanner app, and a large

amount of research code.

2020-2022 PROSA https://gitlab.mpi-sws.org/RT-PROOFS/rt-proofs

Main contributor to PROSA, one of the leading formally-verified frameworks in the real-time systems commu-

nity.

2022 Treecode www.maida.me/treecode

The precursor to Claycode, a novel 2D scannable code that encodes messages as unique trees.

2021 POET https://gitlab.mpi-sws.org/RT-PROOFS/POET

First-ever implementation of a foundational response-time analysis tool, created as part of my first academic

publication.

2018 Fast Mobile Cycle (FMC) Framework and Toolkit

www.github.com/340penThings

Developed a Unity3D framework that accelerates production-ready casual game creation, paired with a Python

toolkit for bulk operations.