

# Assignment N. 4: Image Segmentation via N-cut on the "tree dataset"



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# Implementing the N-Cut Segmentation

### Segmentation process implemented via Scikit-Image library functions:

- Initial Segmentation via K-means:
  - k\_labels = segmentation.slic(image, compactness=compactness, n\_segments=n\_segments)
  - k\_out = color.label2rgb(k\_labels, image, kind='avg')
- Computing the Region Adjacency Graph (RAG):
  - rag = graph.rag\_mean\_color(image, k\_labels, mode='similarity')
- Performing the Normalized-Cut:
  - ncut\_labels = graph.cut\_normalized(k\_labels, rag)
  - ncut\_out = color.label2rgb(ncut\_labels, image, kind='avg')

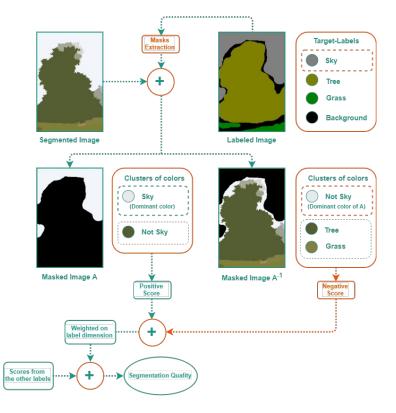
### Identification of of ideal parameters for the segmentation:

- (At first) By visual comparison of several combination of parameters (Screening)
  - Somewhat inefficient approach
  - Need for a measure of the quality of a segmentation

### Computing a Measure of the Segmentation Quality

#### For each labeled area on the target image:

- 1. Extract the label-specific masks
  - Area covered by the label
  - Area not covered by the target-label
- 2. Apply the masks on the segmented image
  - Obtain the masked images A and A-1
- 3. Compute the positive score on masked image A
  - Select the dominant color of the image as D\_clr
  - Compute the percentage of area covered by D\_clr within the target-label region
- 4. Compute the negative score on masked image A<sup>-1</sup>
  - Computing the percentage of the area covered by D\_clr outside of the target-label region
- 5. Sum the two scores and weight on the percentage of image covered by the target-label
- 6. Sum the scores for the remaining labels
  - Ex: Score = Sky + Tree + Grass + Background



# Analysing the results of the Segmentation

- Improved Model selection:
  - From visual comparison of k-means segmentations
  - o To grid-search approach based on average resemblance to labeled images
- Working on a unique set of parameters:
  - Overall average accuracy around 50%
  - Dense Trees: 60-80%
  - Sparse Trees: around 40%
- Splitting the dataset in tree-shape subsets
- Working on subset specific parameters:
  - Higher number of segments and lower compactness for sparse trees
  - Average accuracy over the whole dataset raised to 60%

### Final Considerations: Flaws and Improvements

#### Problematic Flaws / Conditions:

- Scattered and articulated forms
- Areas shared by different non-easily separable colors
  - Ex. Sky through the branches
- Asymmetrical influence of light on some objects
- Scalability of the manual recognition of the shape of objects

#### • Potential Improvements:

- Clustering for tree / object shape recognition
- Adaptive use of different segmentations
  - Increasing the segments in areas of high color diversity





