

Image Analysis and Computer Vision 2021/2022

Semantic Sampling Localization: RGB-D Patch-Based Triplet Network

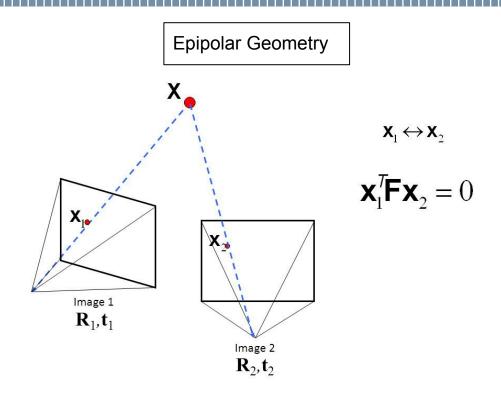
Marco **Petri** 10569751 Mirko **Usuelli** 10570238

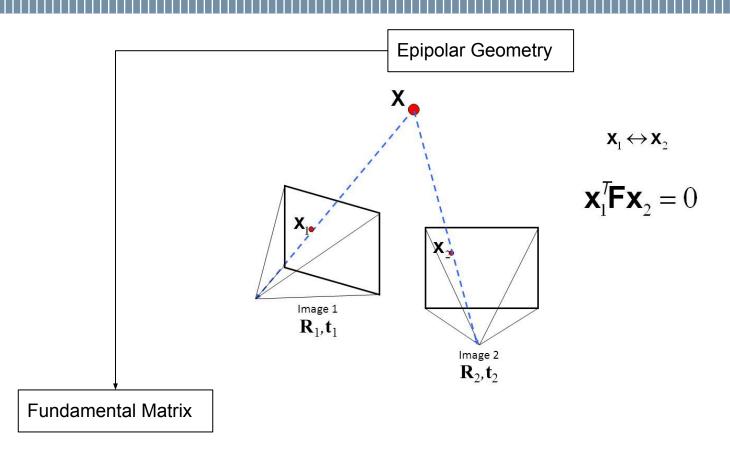
Professor: Vincenzo Caglioti

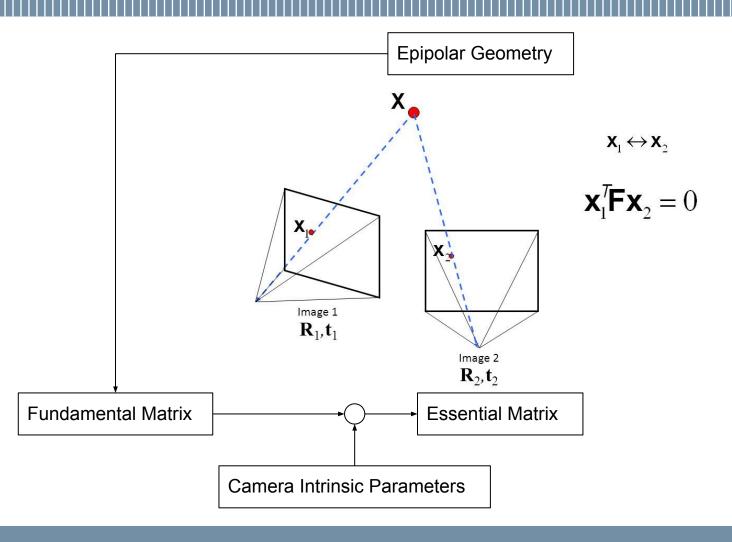
Advisors: Giacomo Boracchi, Luca Magri, Antonino Maria Rizzo

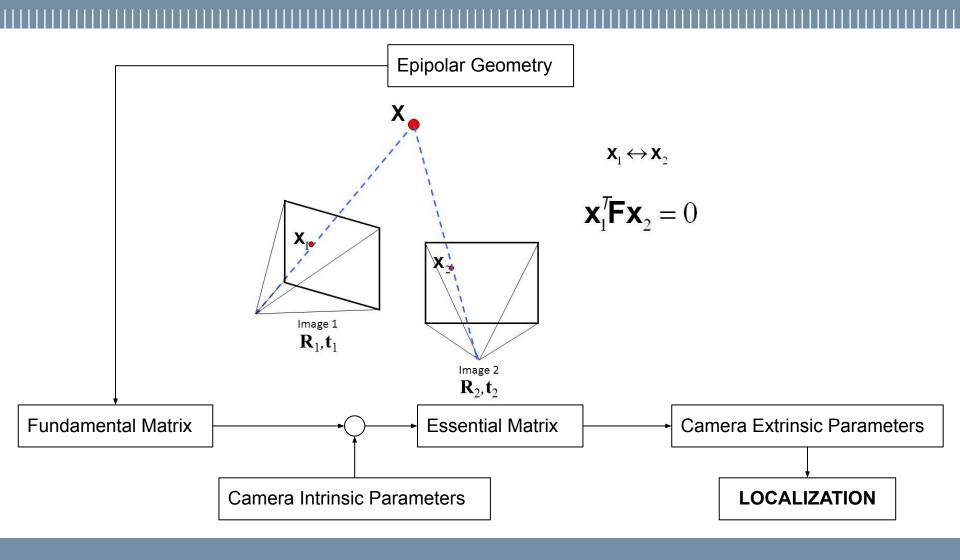
LOCALIZATION

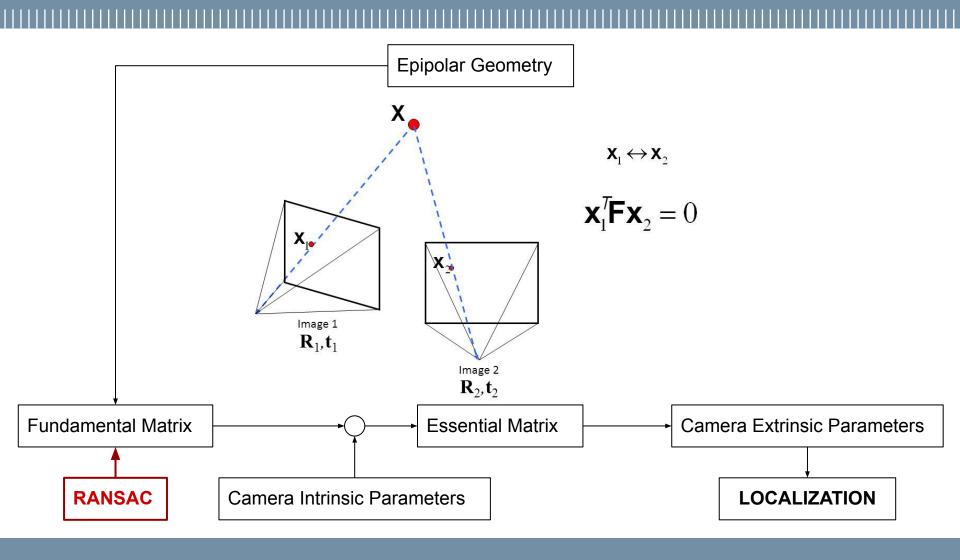








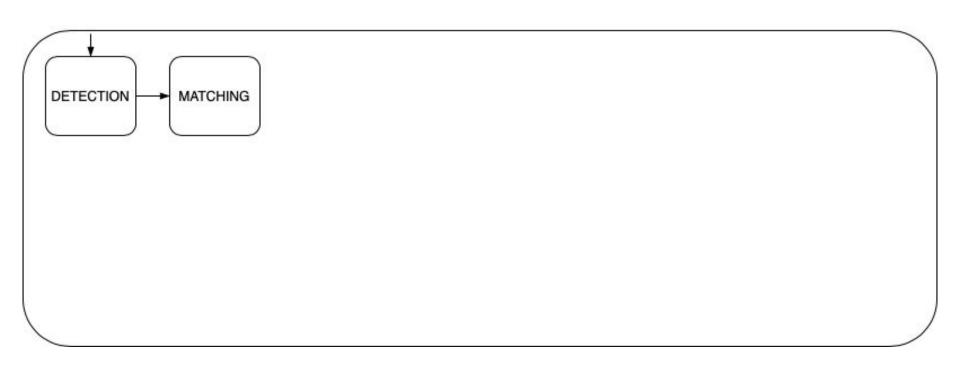


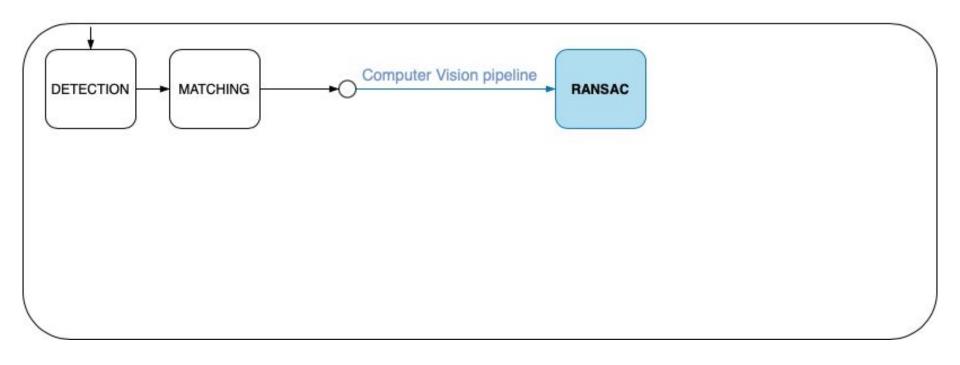


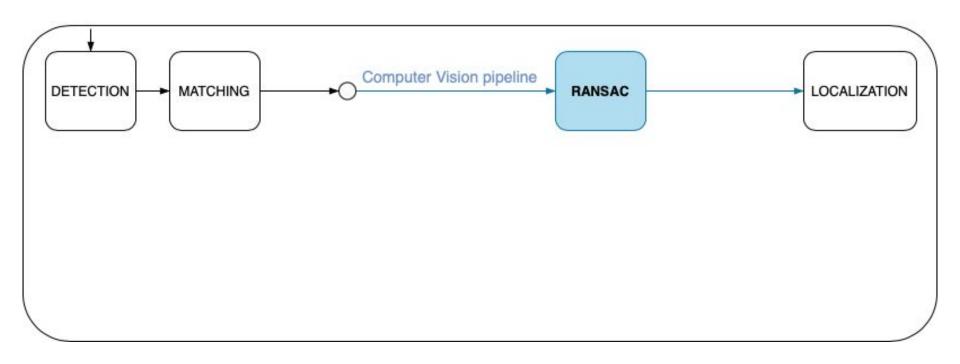
WORKFLOW

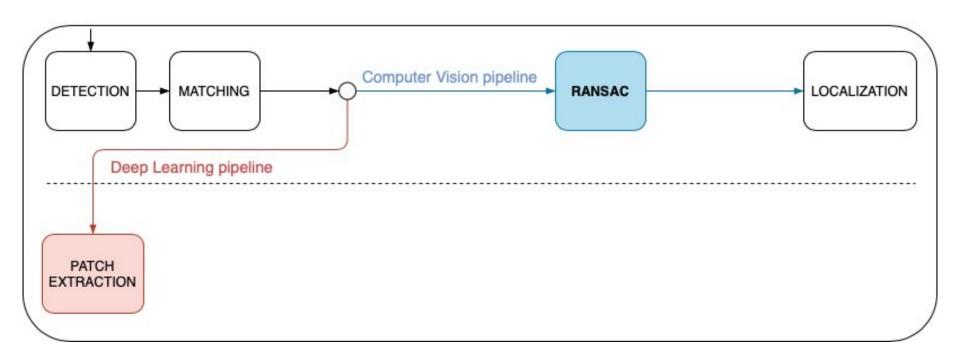


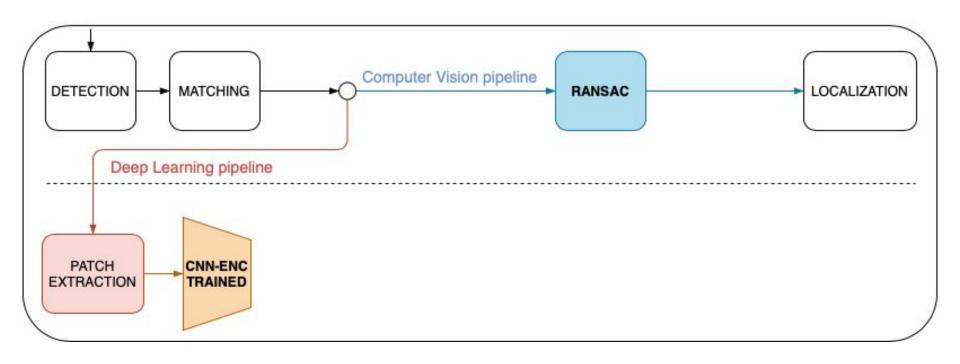


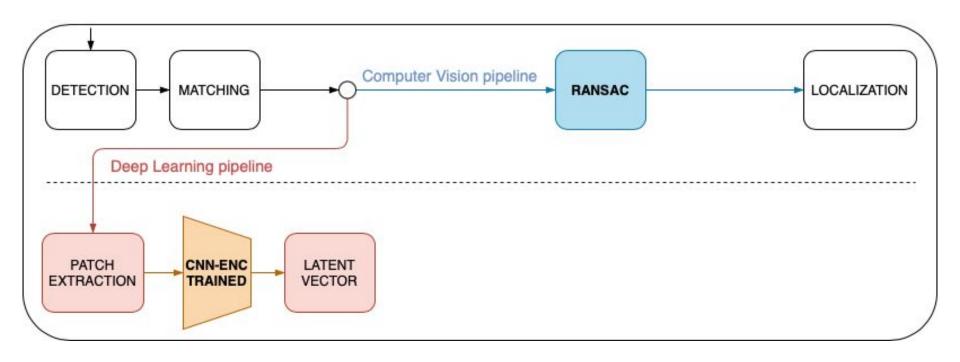


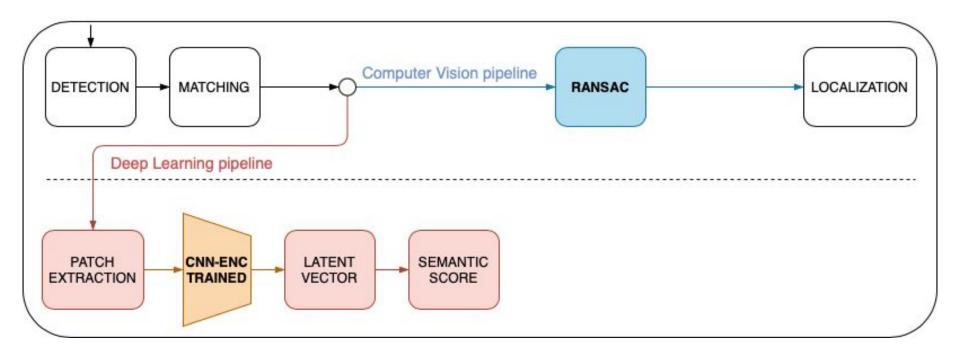


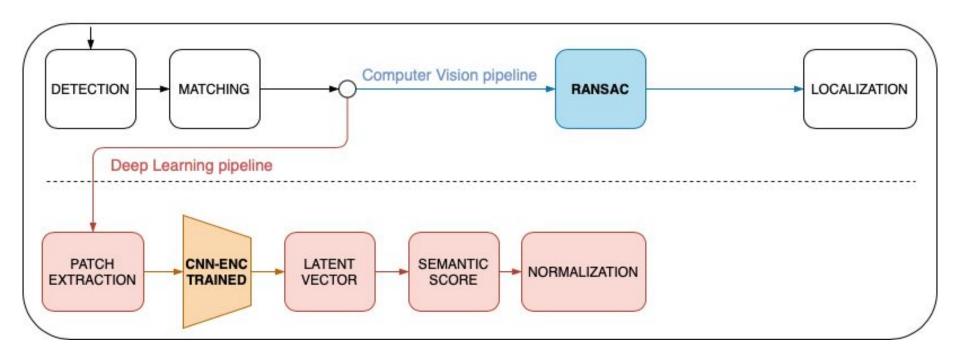


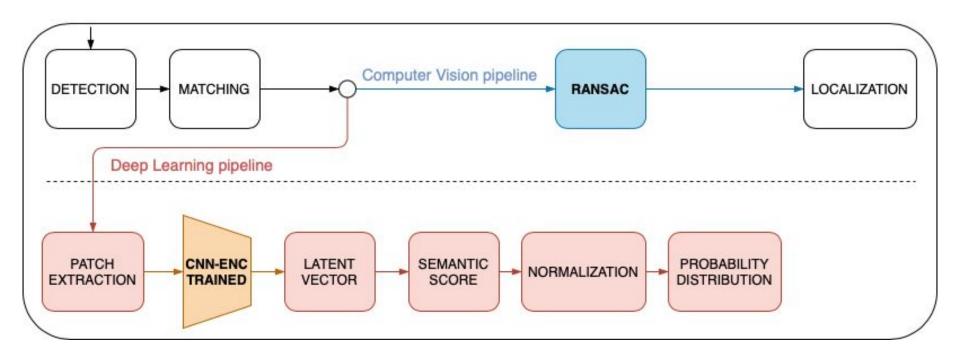


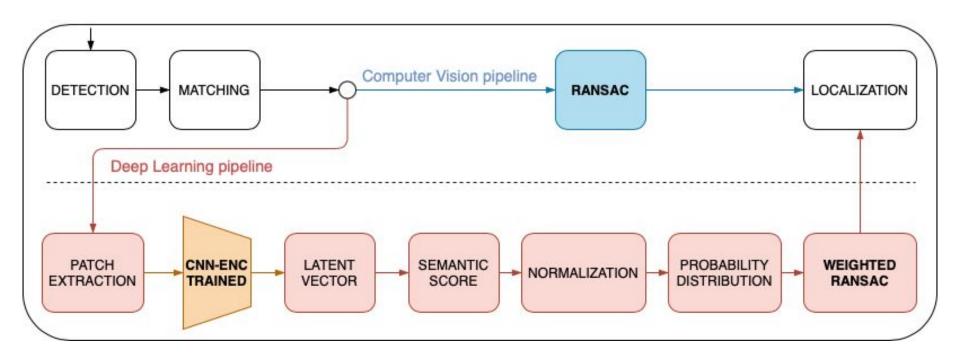




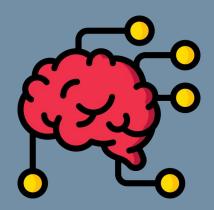




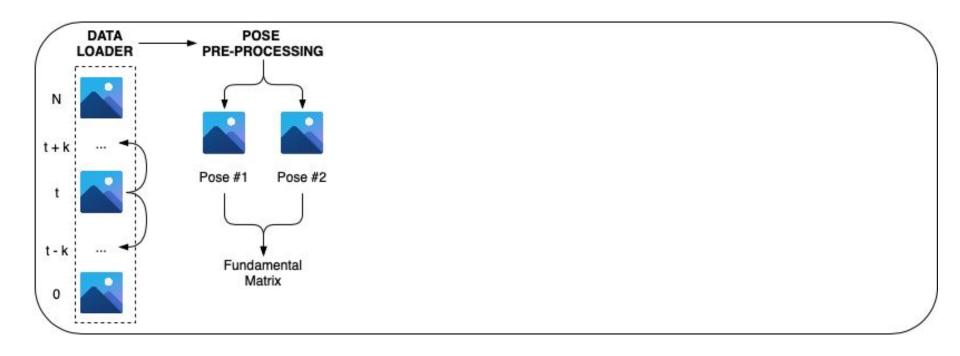


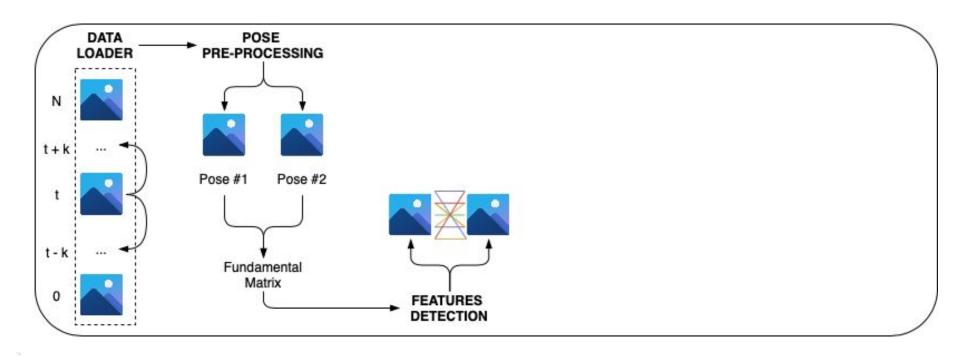


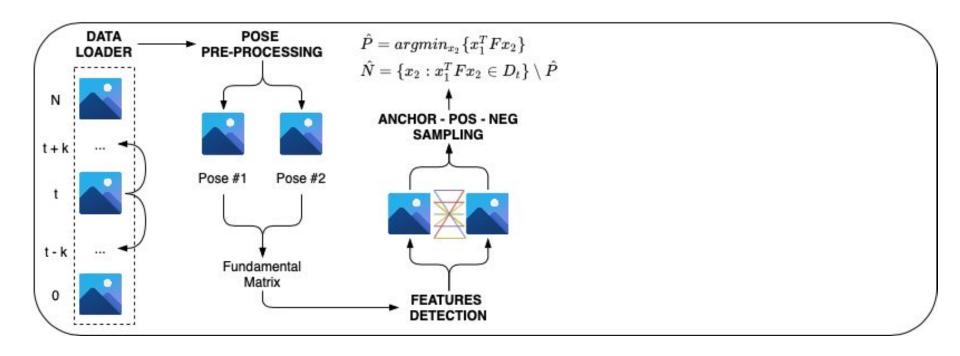
TRIPLET NETWORK





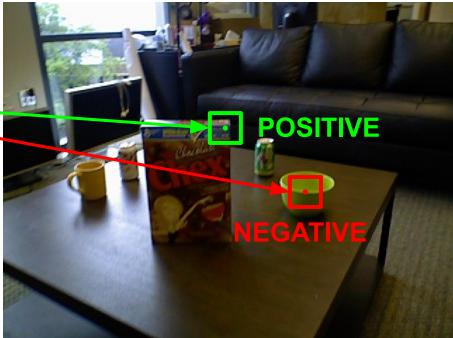






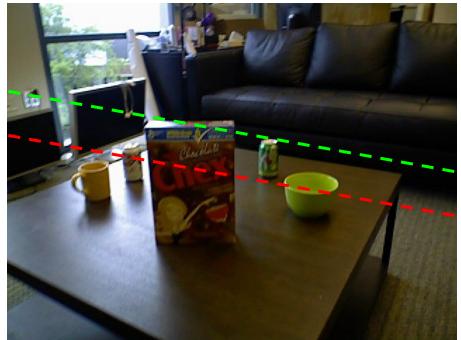
Anchor - Positive - Negative



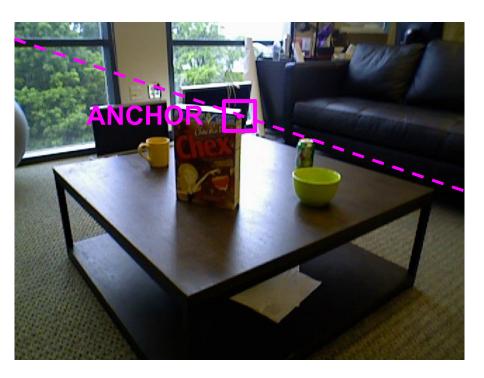


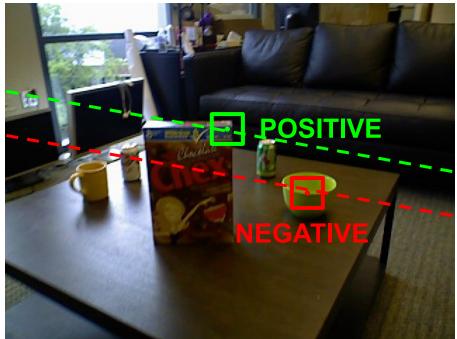
Anchor - Positive - Negative

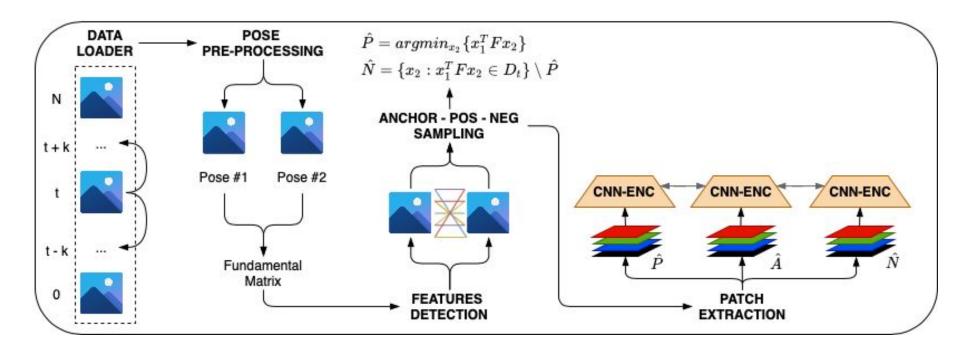




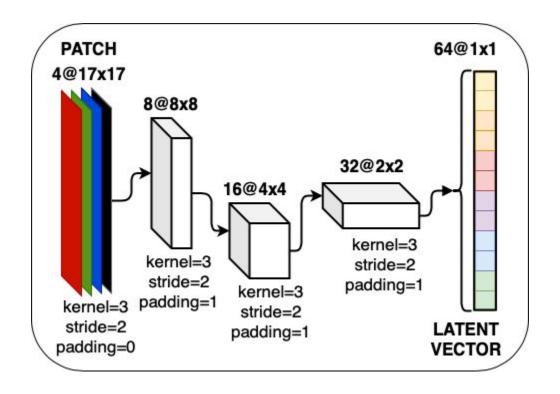
Anchor - Positive - Negative

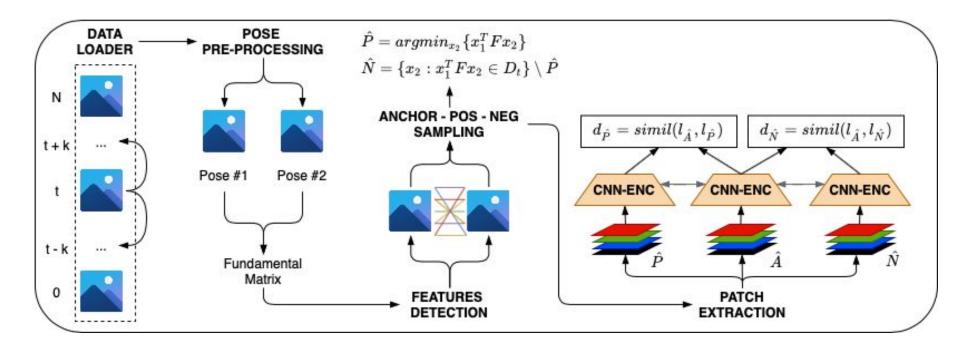


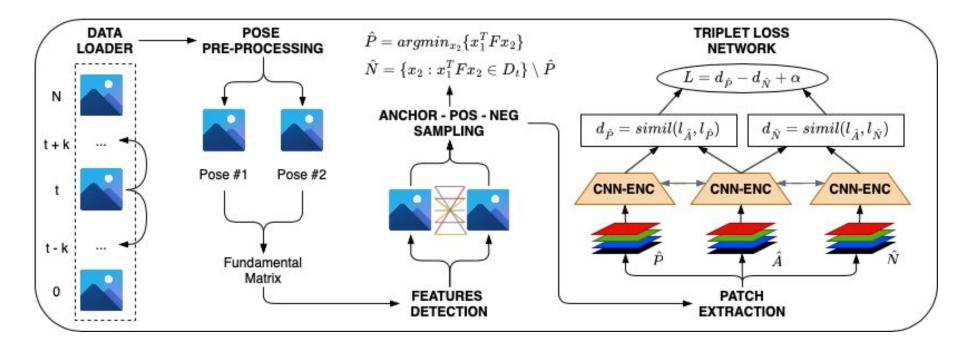




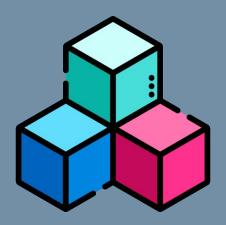
Encoder



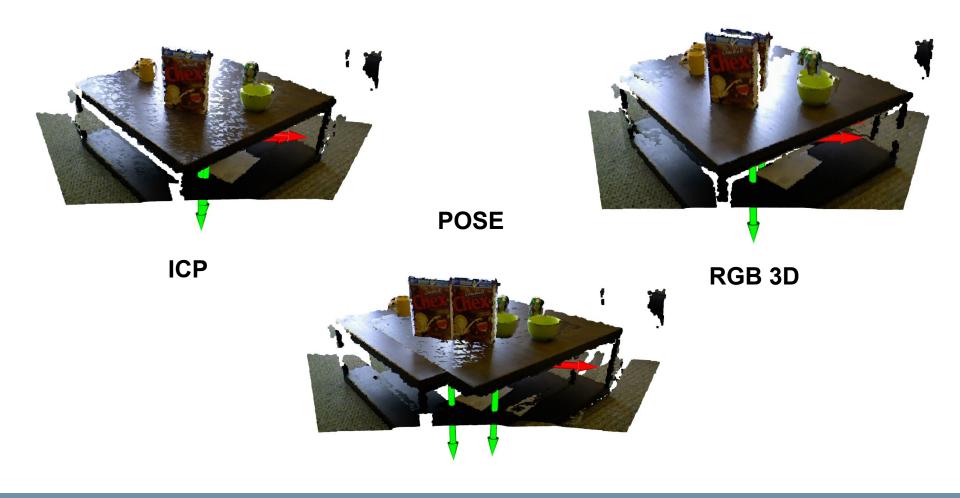




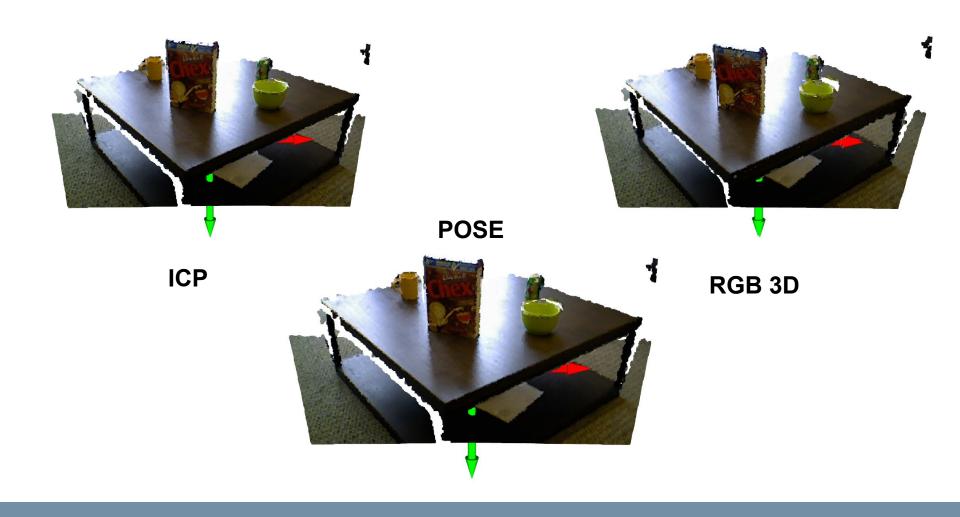
POINT CLOUD



Point clouds of images distant by 50 steps



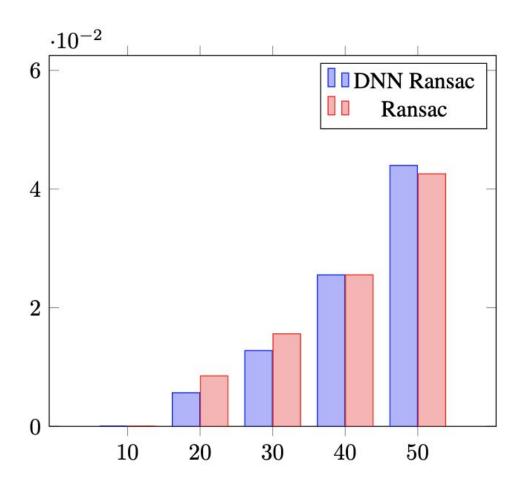
Point clouds of images distant by 20 steps



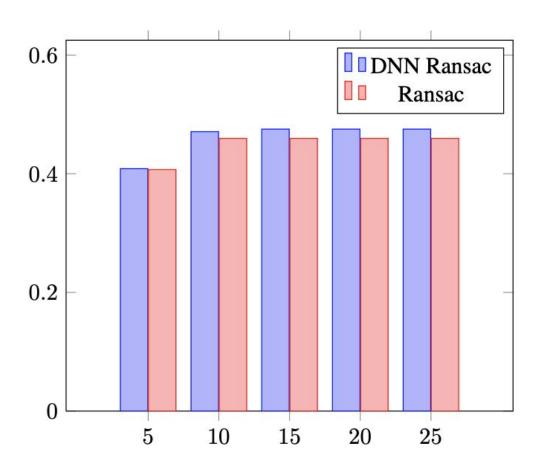
ANALYTICAL RESULTS



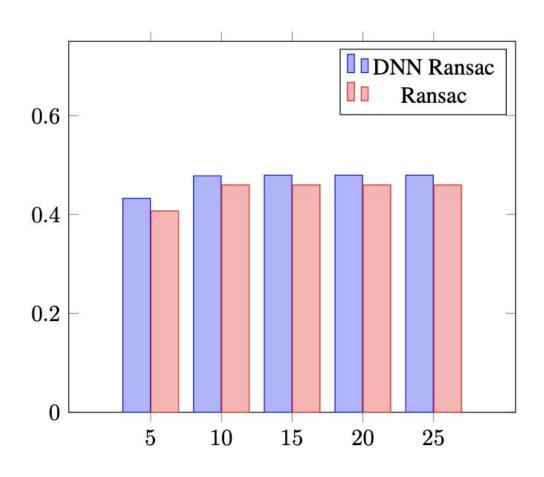
Photo tourism: Exploring photo collections in 3d



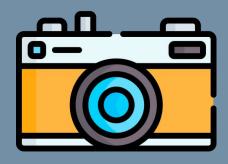
RGB (Washington Dataset)



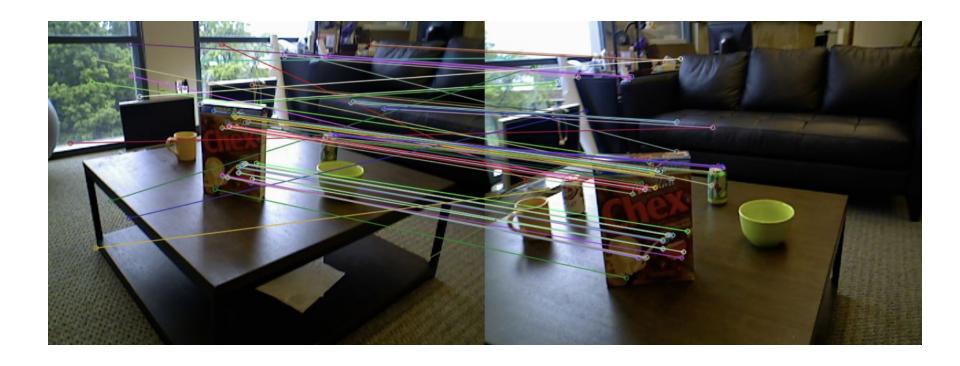
RGB-D (Washington Dataset)



TESTING SET VISUAL RESULTS



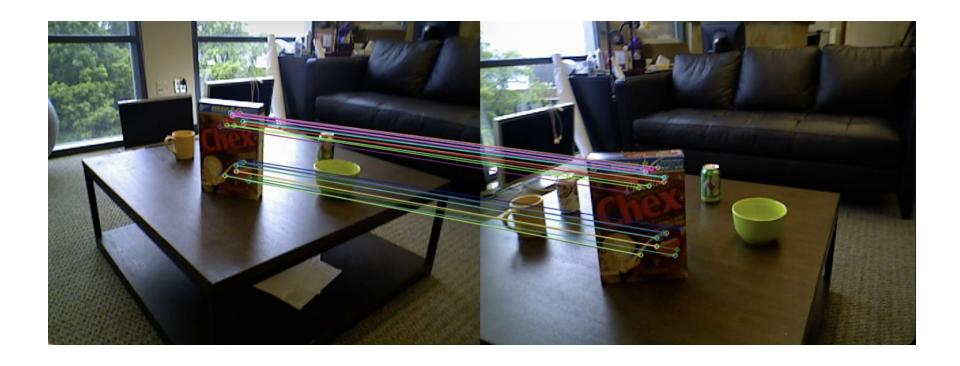
Detection + Matching without RANSAC



Computer Vision Pipeline (RANSAC)



Deep Learning Pipeline (DNN RANSAC)



THE END

