Marco Pratticò

Curriculum Vitae

Computational Statistics and Machine Learning (CSML)

Italian Institute of Technology

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□ @marcopra in Linkedin □ Scholar

Education

2024-present PhD, Applied Mathematics, Italian Institute of Technology, Genoa, Italy.

Research in Reinforcement Learning algorithms for improving sample-efficiency and multi-task learning.

2021–2023: MSc, Computer Engineering, Politecnico di Torino, Turin, Italy.

Grade: Magna cum laude

Thesis: "Towards Autonomous Robotic Spray Painting with Unsupervised Reinforcement Learning"

2018–2021: **BSc, Electronic Engineering**, *Politecnico di Torino*, Turin, Italy.

Publications

In Conference Proceedings

2024 Pietro Novelli, **Marco Pratticò**, Massimiliano Pontil, and Carlo Ciliberto. In *Operator World Models for Reinforcement Learning*. Neural Information Processing Systems (NeurIPS), 2024.

Research Experience

Italian Institute of Technology

2024 **Research Fellow**, Italian Institute of Technology, CSML group.

Advisor: **Prof. Massimiliano Pontil**, *PI*, Italian Institute of Technology & *Associate Professor, AI Center*, University College of London (*Personal Web-page*)

Politecnico di Torino

2022 - 2024 *RoboTO*, *Politecnico di Torino*, Student team.

Student team involved in RobomasterNA competition. I was the supervisor of the projects "Auto-aim system with Deep RL" and "Autonomous navigation system with Deep RL".

2023 **Thesist Student**, Politecnico di Torino, Vandal Group.

Development of my master thesis "Towards Autonomous Robotic Spray Painting with Unsupervised Reinforcement Learning".

Advisor: **Prof.Tatiana Tommasi**, Associate Professor, Department of Control and Computer Engineering, Politecnico di Torino (*Personal Web-page*)

Prof.Raffaello Camoriano, Assistant Professor, Department of Control and Computer Engineering, Politecnico di Torino (*Personal Web-page*)

Academic Projects

Politecnico di Torino

2023 Towards Autonomous Robotic Spray Painting with Unsupervised Reinforcement Learning, MSc Thesis, Vandal Group.

Conducted research on leveraging *Unsupervised Reinforcement Learning* to pre-train policies, enhancing the sample efficiency of fine-tuning for generating target-coverage trajectories. Focused on robotic spray painting within coverage path planning, optimizing trajectory generation for surface coverage

2023 Al Talk - Reinforcement Learning, Conference speaker.

I was a speaker at the Reinforcement Learning conference at Politecnico di Torino. This conference has been conducted in collaboration with DataPizza, Aiko and RoboTO Student Team. Link to conference recording

- 2023 Sim-to-Real transfer of Reinforcement Learning policies in robotics using SAC.

 Study the basics of Sim-to-Real transfer of policies using a custom Sim-to-sim environment. Link to GitHub project
- 2022 **Development of Spiking Neural Networks using Rust**.

 Development of a *Rust* library for efficiently implementing spiking Neural Networks. Link to GitHub
- 2021 2022 Adversarial Attacks and Toggle Activity on a Deep Neural Network, *CAD Group*. We studied the effects of adversarial attacks on a deep neural network and how this affects the network's "toggle activity", a newly proposed method to measure the changing of the neuron's output. Link to GitHub project | Link to report

Advisor: **Prof.Edgar Ernesto Sanchez Sanchez**, Associate Professor, Department of Control and Computer Engineering, Politecnico di Torino (Personal Web-page)

Computer skills

Programming Python (PyTorch, JAX, NumPy), C, C++, Java, MATLAB, Rust Languages

Web HTML 5, Javascript, CSS

Technologies

Database SQL, MySQL

Hardware VHDL

Markup LATEX

Language

Operative Windows, MacOS, Linux

Systems

Advisors

Prof. Massimiliano Pontil

Italian Institute of Technology
AI Center, University College of London

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Prof. Carlo Ciliberto

Al Center, University College of London

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