Image Classification

Homework 1 - Artificial Neural Networks and Deep Learning 2020

DATASET LOADING

The images of the training set have been automatically arranged in three separate folders, one per label, by executing the simple Python script JSONToFolders. The training-validation split is operated by the function shuffle validation weighted, which takes the percentage of examples to be used for validation as input and moves the files in a hierarchical folder structure, such that it works with flow from directory. The validation examples are selected at random, depending on the numpy seed, which is fixed at the start of each notebook. The training set and the validation set are then loaded through ImageDataGenerator objects, resized, pre-processed and augmented.

FIRST TESTS WITH BASIC NETWORK

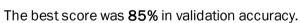
The model is a simple. LeNet-inspired convolutional neural network, composed of an alternating sequence of Conv2D and MaxPool2D layers for the feature extractor part, followed by a Flatten, and two Dense layers for the classifier. All layers use the ReLU activation, except for the last one, which uses Softmax.

The following hyperparameters were tuned:

- Depth (number of layers)
- Width (number of filters per layer)
- Resolution of the input images
- Learning rate
- Batch size
- Number of neurons in the first Dense layer

Furthermore, the addition of a *Dropout* layer between the two Dense ones was tested with various rates. The Early Stopping technique was employed to speed up the testing process. The

SGD optimizer was initialised to a momentum of 0.9 to better escape local minima.

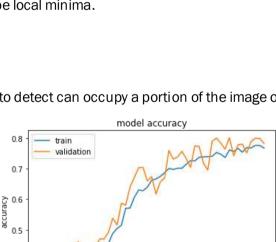


INCEPTION-LIKE CUSTOM MODEL

It has been observed that the face masks the network is supposed to detect can occupy a portion of the image of

variable size. Therefore, a model which employs several filters with different dimensions at the same time was considered especially suitable for the problem. The basic network was modified by integrating modules inspired by the Inception architecture, consisting of 1x1, 3x3 and 5x5 parallel convolutional layers with same padding and a Concatenate layer, followed by max pooling. The 3x3 and 5x5 convolutions were preceded by 1x1 convolutions to enhance performance by reducing the number of input channels.

Additionally, BatchNormalization layers were added after each concatenation, with the purpose of limiting overfitting. The hyperparameters were selected through a simple grid search.



model accuracy

train validation

0.8

0.7

0.6

0.5

0.3

The model achieved a maximum validation accuracy of 80% with a depth of 4 (stacked modules).

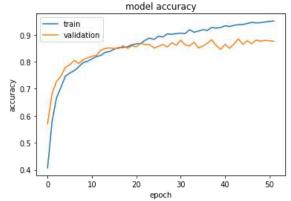
XCEPTION

The next step was trying to use transfer learning on the Xception network architecture.

The starting weights were obtained on the ImageNet dataset. The classifier was rebuilt by adding a *GlobalAveragePooling2D* layer and a variable number of *Dense + Dropout* couples before the final Softmax *Dense*. The optimizer was changed to Adam.

First, the network was retrained in its entirety. This approach scored a maximum of **88%** validation accuracy.

A great performance improvement was obtained by locking all layers of the convolutional part, except for the last two blocks,



which were retrained together with the classifier. This allowed the network to achieve a validation accuracy of 93% in just 15 epochs, which was later increased to 94% by unlocking the rest of the network and retraining everything together.

Further advancements were made possible by three, main intuitions:

- 1. Applying L2 kernel regularisation to the Dense layers to reduce overfitting;
- 2. Increasing the resolution of the input images to 512x512;
- 3. Weighting the loss function to compensate the imbalance in the number of samples per class in the dataset, as to reduce bias.

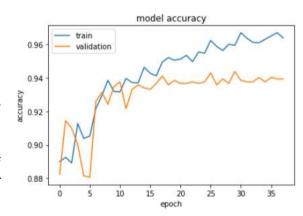
These observations allowed us to score a 96% validation accuracy and a 95.77% accuracy on the test set.

VGG19

The much simpler VGG19 architecture was also tested extensively for transfer learning.

The classifier was constructed by inserting a GlobalAveragePooling2D, two Dense ReLUs with Dropout and a final Softmax Dense. The network was later modified by adding BatchNormalization layers after the convolutional ones. L2 kernel regularisation and weighted loss function were used.

The process consisted in training, unblocking a small number of convolutional layers and retraining the network gradually, in four total steps.



VGG19 performed similarly to Xception, although it required much more time to train.

The best result was a 95% validation accuracy and a 94.44% accuracy on the test set.

FURTHER TESTING

Other popular architectures were tested, most notably: EfficientNetB0, MobileNetV2, ResNet-50.

See the notebooks for more details.

Marco Premi - 941388

Alessio Martignetti – 968430

Francesco Sammarco - 966229