

Application Note

Calibration at Toyota Motor Corporation using Vibration Transducer Calibration System Type 9610

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For several years Toyota Motor Corporation have used a traditional manually operated back-to-back vibration transducer calibration system based on older Brüel & Kjær equipment.

However, continuously adding vibration transducers, Toyota Motor Corporation developed a need for a more efficient means of calibrating these transducers. To ensure continued optimum vibration measurement results, reliability, high precision and high accuracy were vital factors when the Calibration Laboratory began looking for a suitable calibration system.

Vibration Transducer Calibration System Type 9610, providing automated FFT-based sensitivity and phase calibration of vibration transducers over a wide frequency range, was chosen for reasons of accuracy, confidence and durability.

This Application Note introduces the concept of FFT-based vibration transducer calibration and discusses the features, advantages and benefits of the Vibration Transducer Calibration System Type 9610 in connection with its use at Toyota Motor Corporation.

Introduction

Refined Noise and Vibration Harshness (NVH) characteristics of automobiles have become one of the key factors in the quest for higher customer satisfaction. Amongst other things, this implies a large number of vibration measurements, with applications ranging from general one-channel measurements to advanced experimental modal analysis, often requiring multichannel systems with many vibration transducers.

Today, a multitude of sophisticated vibration analysis tools are available, allowing the engineer to validate the analysis. An excellent example of this is the recent development of experimental modal analysis software where the analysis result, the modal model, can be validated using ad-



vanced algorithms, giving increased confidence in the analysis results.

However, the validity of the transducers used for the measurements upon which the analysis are founded is totally dependent upon proper calibration and, as should be emphasized, compensating for damaged out-of-tolerance vibration transducers by post-processing is impossible!

The calibration of vibration transducers therefore plays a decisive role in the quality, accuracy and consistency of any vibration measurement.

Aspects of calibration

The reliability and versatility of a vibration transducer is of only limited value if the measurements cannot somehow be traced to an absolute physical standard. Calibration ensures this traceability and hence provides a defined degree of confidence in any vibration measurement. It is therefore an act of establishing the link to the physical quantity of interest, the vibration sensitivity [1].

From a practical measurement point of view, it is advisable to calibrate the sensitivity of a vibration transducer at more than one frequen-

cy. Preferably, the vibration transducer should be calibrated over its entire useful frequency range, or at least the frequency response curve should be measured, to ensure that the transducer has not been damaged. Such damage will typically show up as irregularities in the frequency response curve as well as in the curve that can be drawn from the individual, discrete frequency, calibrations.

An example of this is shown in Fig. 1 where the frequency response of a damaged accelerometer has been drawn. Note the peak/notch phenomenon, a clear indication of damage which did not reveal anything unusual when a back-to-back calibration was carried out at the reference frequency of 160 Hz.

Calibration Methods

Sensitivity calibration of vibration transducers can be divided into three distinct groups: absolute methods (includes laser interferometry, reciprocity and Earth's gravity), comparison or back-to-back methods, and finally calibrator methods, involving the use of an exciter of known vibration level.

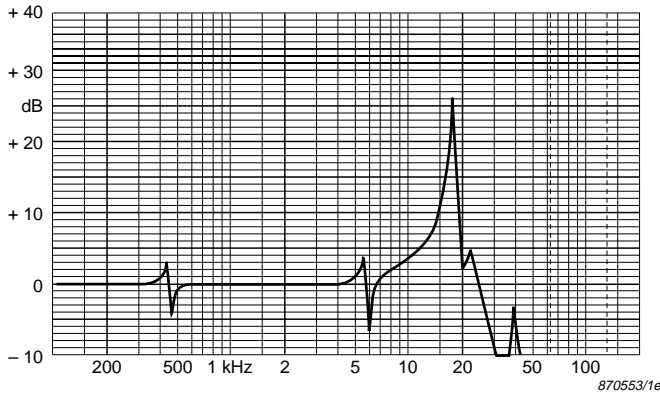


Fig. 1 Frequency response of a damaged accelerometer

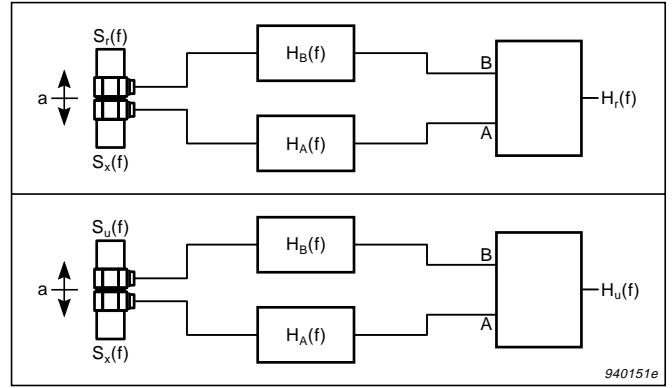


Fig. 3 Principle of improved back-to-back calibration by substitution

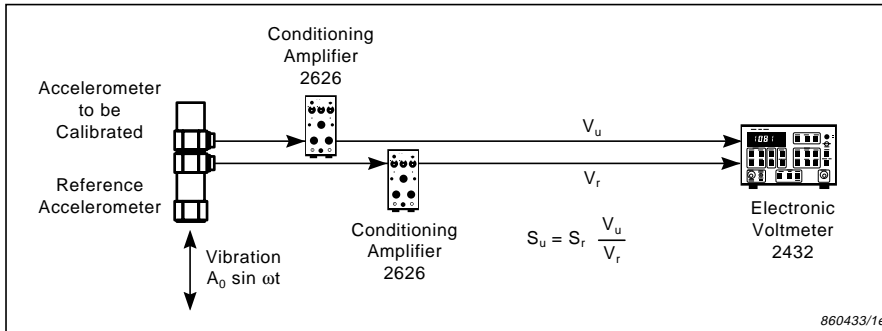


Fig. 2 Principle of traditional back-to-back calibration

The back-to-back comparison method is ideal for every-day calibrations of non-standard reference accelerometers due to its relative simplicity, accuracy and cost effectiveness. Moreover, the method's inherent qualities make it well-suited for large scale vibration transducer calibration.

Back-to-Back Vibration Transducer Calibration

The traditional back-to-back calibration technique is based on the principle shown in Fig. 2. The device under test (DUT) is mounted back-to-back with a standard reference accelerometer. The combination is mounted on a suitable vibration source. When excited, the input acceleration to each accelerometer is identical and consequently, their sensitivity ratio is simply the ratio of their outputs.

Traditionally, the accelerometers are excited at one frequency and their outputs are measured (after preamplification) using a high-quality electronic voltmeter of known accuracy. This method produces good results, but as it produces a measure of the sensitivity at a single frequency, attaining a comprehensive knowledge of an accelerometer's characteristics can be rather time consuming.

However, the advent of two-channel FFT analyzers, coupled with broad-band random excitation techniques, meant the introduction of innovative calibration techniques since the two-channel FFT analyzer made it possible to calibrate a vibration transducer at a large number of points over a wide frequency range in a single measurement. Combining this with the ability of a PC to control the analyzer formed the basis for an advanced automated vibration transducer calibration system. By supplying the output from the standard reference accelerometer to the channel A input, and the output from the DUT to the channel B input, the ratio of the sensitivities can be measured as the frequency response function.

It has been shown [2] that such a basic FFT-based back-to-back calibration will result in a total uncertainty of approximately 5%. To improve this method and achieve an even better uncertainty, a new technique, calibration by substitution, was developed.

Improved Back-to-Back Calibration by Substitution

This unique technique involves making two measurements in order to obtain the final calibration result of the DUT. Initially, the frequency response function between a so-called

working standard accelerometer and the standard reference accelerometer is measured and stored. Then the frequency response function between the DUT and the working standard accelerometer, known as the reference frequency response function, is also measured and stored. The working standard accelerometer remains fixed to the calibration fixture. Now, the charge sensitivity of the DUT can be calculated as:

$$\frac{S_u(f)}{S_x(f)} \times \frac{S_x(f)}{S_r(f)} = \frac{H_u(f)}{H_r(f)}$$

or

$$S_u(f) = S_r(f) \times H_u(f) / H_r(f)$$

where (as a function of frequency): $S_u(f)$ is the DUT's charge sensitivity

$S_r(f)$ is the standard reference accelerometer's charge sensitivity
 $S_x(f)$ is the working standard accelerometer's charge sensitivity
 $H_u(f)$ is the frequency response function between the DUT and the working standard accelerometer
 $H_r(f)$ is the frequency response function between the standard reference accelerometer and the working standard accelerometer

The principle of improved back-to-back calibration by substitution is shown in Fig. 3. The complete Vibration Transducer Calibration System Type 9610, centring around Multichannel Analysis System Type 3550 as the two-channel FFT analyzer, is shown in Fig. 4. The system calibrates the sensitivity and phase of accelerometers and velocity pick-ups in a frequency range from 5 Hz up to 5 or 10 kHz.

Note that since the contribution from the working standard accelerometer cancels out, the working



Fig.5 Vibration Transducer Calibration System Type 9610 in use at the Calibration Center

standard reference accelerometer and working standard accelerometer.

This ensures a consistent calibration philosophy with a constant and thorough focus on error reduction.

Thirdly, the combination of random excitation and the improved FFT calibration by substitution provides very fast calibrations. Obtaining a typical calibration (sensitivity as well as phase at 1550 frequencies) takes approximately three minutes, including all manual work.

A natural consequence of this is higher calibration productivity and the Calibration Center has, not sur-

prisingly, reported a reduction in calibration costs.

Finally, by combining the FFT calibration technique with a PC to manage data, data retrieval, trend analysis, calibration comparisons, etc. are easy and straightforward.

According to the Calibration Center, the above factors were all carefully examined prior to purchase in order to evaluate their usefulness and their impact on the calibration strategy. The center explains: "Today's automobile customers are extremely demanding and critical, they do not accept half solutions – and neither do we. The Vibration Transducer Calibration System Type 9610 provides us with fast, reliable and accurate calibrations and fits perfectly well into our quality optimization strategy due to its innovative improved FFT calibration by substitution technique".

Fig. 5 shows Vibration Transducer Calibration System Type 9610 in use at the Calibration Center.

Conclusions

The evolution of the traditional back-to-back calibration method into the FFT-based improved back-to-back calibration by substitution method has been discussed along with the features and benefits of implementing the technique in Vibration Transducer Calibration System Type 9610.

Also, by examining the use of Vibration Transducer Calibration System Type 9610 at Toyota Motor Corporation, it was shown how the system has enabled the Calibration Center to further optimize their calibration strategy, increase productivity and calibrate with more accuracy and more confidence.

References

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** The verification procedures are divided into three: System Verification, Standard Voltage Verification and Standard Charge Verification. System Verification involves a series of measurements to validate the stability of the system. Standard Voltage Verification and Standard Charge Verification are performed to ensure the validity of the Standard Reference Accelerometer and the Calibration Set Type 3506 which are used as charge and voltage standards, respectively