Sistema de seguridad en cámaras frigoríficas

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Capítulo 1

Índice jerárquico

1.1. Jerarquía de clases

Este listado de herencia está ordenado de forma general pero no está en orden alfabético estricto:

accesoRFID	. 7
MFRC522Extended::Ats	. 16
MFRC522Extended::Ats.ta1	. 16
MFRC522Extended::Ats.tb1	. 16
MFRC522Extended::Ats.tc1	. 16
DHT11	
MFRC522	. 11
MFRC522Extended	16
MFRC522::MIFARE_Key	. 11
MFRC522Extended::PcbBlock	
MFRC522Extended::PcbBlock.inf	
MFRC522Extended::PcbBlock.prologue	
MFRC522Extended::TagInfo	. 16
MERC522···liid	11

2 Índice jerárquico

Capítulo 2

Índice de estructuras de datos

2.1. Estructuras de datos

Lista de estructuras con breves descripciones:

accesorfid
Clase para manejar el acceso usando el módulo RFID-RC522
DHT11
MFRC522
MERC522Extended

Capítulo 3

Índice de archivos

3.1. Lista de archivos

Lista de todos los archivos documentados y con breves descripciones:

main/libraries/DHT11-HW-481/DHT11.h	29
main/libraries/DHT11-HW-481/setPin.cpp	
Función amiga setPinDHT11	29
main/libraries/DHT11-HW-481/setPin.h	31
main/libraries/RFID-RC522/accesoRFID.h	32
main/libraries/RFID-RC522/deprecated.h	32
main/libraries/RFID-RC522/MFRC522.h	32
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main/libraries/RFID-RC522/require_cpp11.h	38

6 Índice de archivos

Capítulo 4

Documentación de estructuras de datos

4.1. Referencia de la clase accesoRFID

Clase para manejar el acceso usando el módulo RFID-RC522.

#include <accesoRFID.h>

Diagrama de colaboración de accesoRFID:

+ accesoRFID() + start() + mostrarID() + autorizar() + detectarTarjeta()

Métodos públicos

- accesoRFID (byte ssPin, byte rstPin, String autorizarID)
 - Constructor de la clase accesoRFID.
- void start ()
 - void start(); Inicia la comunicación SPI con el módulo RFID (usando sus métodos).
- void mostrarID ()
 - void mostrarID(); Imprime por puerto serie el UID de la tarjeta detectada por el RFID
- bool autorizar ()
 - bool autorizar(); Compara el UID de la tarjeta con el UID autorizado. Devuelve true (acceso permitido) o un false (acceso denegado).
- bool detectarTarjeta ()
 - bool detectarTarjeta(); Lee el UID de la tarjeta para implementarla en el sistema.

4.1.1. Descripción detallada

Clase para manejar el acceso usando el módulo RFID-RC522.

Esta clase permite inicializar el lector RFID y verificar si una tarjeta tiene autorización para entrar.

4.1.2. Documentación de constructores y destructores

4.1.2.1. accesoRFID()

Constructor de la clase accesoRFID.

Parámetros

ssPin	El pin SS (Slave Select) para la comunicación SPI.
rstPin	es el pin de Reset para el módulo RFID.
autorizarID	El UID de la tarjeta autorizada para el acceso.

La documentación de esta clase está generada del siguiente archivo:

■ main/libraries/RFID-RC522/accesoRFID.h

4.2. Referencia de la clase DHT11

```
#include <DHT11.h>
```

Diagrama de colaboración de DHT11:

DHT11 + ERROR_CHECKSUM + ERROR_TIMEOUT + TIMEOUT_DURATION + DHT11() + setDelay() + readHumidity() + readTemperature() + readTemperatureHumidity()	
+ ERROR_TIMEOUT + TIMEOUT_DURATION + DHT11() + setDelay() + readHumidity() + readTemperature()	DHT11
+ TIMEOUT_DURATION + DHT11() + setDelay() + readHumidity() + readTemperature()	+ ERROR_CHECKSUM
+ DHT11() + setDelay() + readHumidity() + readTemperature()	+ ERROR_TIMEOUT
+ setDelay() + readHumidity() + readTemperature()	+ TIMEOUT_DURATION
+ readHumidity() + readTemperature()	+ DHT11()
+ readTemperature()	+ setDelay()
•	+ readHumidity()
+ readTemperatureHumidity()	+ readTemperature()
1 70	+ readTemperatureHumidity()

Métodos públicos

- DHT11 (int pin)
- void setDelay (unsigned long delay)
- int readHumidity ()
- int readTemperature ()
- int readTemperatureHumidity (int &temperature, int &humidity)

Atributos públicos estáticos

- static const int ERROR_CHECKSUM = 254
- static const int **ERROR_TIMEOUT** = 253
- static const int **TIMEOUT_DURATION** = 1000

Amigas

void setPinDHT11 (DHT11 &sensor, int pin)

4.2.1. Descripción detallada

DHT11.h Header file for the DHT11 library, providing functionalities to interface with the DHT11 temperature & humidity sensor.

Author: Dhruba Saha Version: 2.1.0 License: MIT DHT11 Class Provides methods to read temperature and humidity data from the DHT11 sensor.

4.2.2. Documentación de constructores y destructores

4.2.2.1. DHT11()

```
DHT11::DHT11 ( int pin)
```

Constructor Initializes the data pin to be used for communication with the DHT11 sensor.

Parámetros

pin Digital pin number on the Arduino board to which the DHT11 sensor is connected.

4.2.3. Documentación de funciones miembro

4.2.3.1. readHumidity()

```
int DHT11::readHumidity ()
```

Reads and returns the humidity from the DHT11 sensor.

Devuelve

: Humidity value in percentage. Returns DHT11_ERROR_TIMEOUT if reading times out. Returns DHT11_ ERROR_CHECKSUM if checksum validation fails.

4.2.3.2. readTemperature()

```
int DHT11::readTemperature ()
```

Reads and returns the temperature from the DHT11 sensor.

Devuelve

: Temperature value in Celsius. Returns DHT11_ERROR_TIMEOUT if reading times out. Returns DHT11_ ERROR_CHECKSUM if checksum validation fails.

4.2.3.3. readTemperatureHumidity()

Reads and returns the temperature and humidity from the DHT11 sensor.

Parámetros

temperature	Reference to a variable where the temperature value will be stored.
humidity	Reference to a variable where the humidity value will be stored.

Devuelve

: true if the reading is successful, false if it fails due to timeout or checksum error.

4.2.3.4. setDelay()

```
void DHT11::setDelay (
          unsigned long delay)
```

Sets the delay between consecutive sensor readings. If this method is not called, a default delay of 500 milliseconds is used.

Parámetros

delay	Delay duration in milliseconds between sensor readings.

4.2.4. Documentación de símbolos amigos y relacionados

4.2.4.1. setPinDHT11

Bloque if-else Controla si el pin ingresado es uno físicamente válido. Imprime por puerto serie UART un mensaje de error en caso de no serlo.

pinMode(sensor._pin, INPUT) "Desactiva" el pin anterior.

sensor._pin = pin Actualiza el pin.

pinMode(pin, OUTPUT) y digitalWrite(pin, HIGH) Inicializa el nuevo pin como lo hace internamente la clase DHT11 delay(250) Tiempo de espera a que el sensor se estabilice.

La documentación de esta clase está generada del siguiente archivo:

main/libraries/DHT11-HW-481/DHT11.h

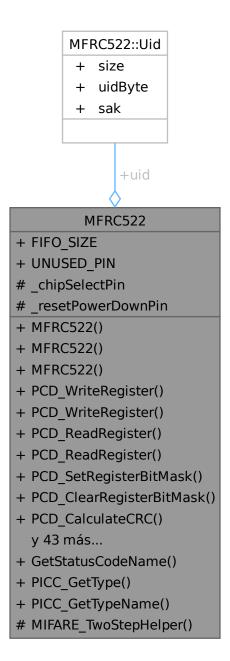
4.3. Referencia de la clase MFRC522

Diagrama de herencia de MFRC522

MFRC522 + uid + FIFO_SIZE + UNUSED_PIN # _chipSelectPin # _resetPowerDownPin + MFRC522() + MFRC522() + MFRC522() + PCD_WriteRegister() + PCD_WriteRegister() + PCD_ReadRegister() + PCD_ReadRegister() + PCD_SetRegisterBitMask() + PCD_ClearRegisterBitMask() + PCD_CalculateCRC() y 43 más... + GetStatusCodeName() + PICC_GetType() + PICC_GetTypeName() # MIFARE_TwoStepHelper() MFRC522Extended + tag + MFRC522Extended() + MFRC522Extended() + MFRC522Extended() + PICC_Select() + PICC_RequestATS() + PICC_PPS() + PICC_PPS()

+ TCL_Transceive() + TCL_Transceive() + TCL_TransceiveRBlock()

y 8 más... + PICC_GetType() + PICC_GetType() Diagrama de colaboración de MFRC522:



Estructuras de datos

- struct MIFARE_Key
- struct Uid

Tipos públicos

enum PCD_Register : byte {
CommandReg = 0x01 << 1 , ComlEnReg = 0x02 << 1 , DivlEnReg = 0x03 << 1 , ComlrqReg = 0x04</p>

```
<<1,
  DivIrgReg = 0x05 << 1, ErrorReg = 0x06 << 1, Status1Reg = 0x07 << 1, Status2Reg = 0x08 << 1,
  FIFODataReg = 0x09 << 1, FIFOLevelReg = 0x0A << 1, WaterLevelReg = 0x0B << 1, ControlReg =
  0x0C << 1,
  \textbf{BitFramingReg} = 0 \times 0 D << 1 \text{ , CollReg} = 0 \times 0 E << 1 \text{ , ModeReg} = 0 \times 11 << 1 \text{ , TxModeReg} = 0 \times 12 <<
  RxModeReg = 0x13 << 1, TxControlReg = 0x14 << 1, TxASKReg = 0x15 << 1, TxSelReg = 0x16 << 1
  RxSelReg = 0x17 << 1, RxThresholdReg = 0x18 << 1, DemodReg = 0x19 << 1, MfTxReg = 0x1C
  <<1,
  MfRxReg = 0x1D << 1, SerialSpeedReg = 0x1F << 1, CRCResultRegH = 0x21 << 1, CRCResultRegL
  = 0x22 << 1,
  ModWidthReg = 0x24 << 1, RFCfgReg = 0x26 << 1, GsNReg = 0x27 << 1, CWGsPReg = 0x28 << 1
  ModGsPReg = 0x29 << 1, TModeReg = 0x2A << 1, TPrescalerReg = 0x2B << 1, TReloadRegH = 0x2B
  0x2C << 1,
  TReloadRegL = 0x2D << 1, TCounterValueRegH = 0x2E << 1, TCounterValueRegL = 0x2F << 1,
  TestSel1Rea = 0x31 << 1.
  \textbf{TestSel2Reg} = 0x32 << 1 \text{ , TestPinEnReg} = 0x33 << 1 \text{ , TestPinValueReg} = 0x34 << 1 \text{ , TestBusReg}
  = 0x35 << 1,
  AutoTestReg = 0x36 << 1, VersionReg = 0x37 << 1, AnalogTestReg = 0x38 << 1, TestDAC1Reg =
  0x39 << 1.
  TestDAC2Reg = 0x3A << 1, TestADCReg = 0x3B << 1}
enum PCD Command : byte {
  PCD Idle = 0x00, PCD Mem = 0x01, PCD GenerateRandomID = 0x02, PCD CalcCRC = 0x03,
  PCD_Transmit = 0x04, PCD_NoCmdChange = 0x07, PCD_Receive = 0x08, PCD_Transceive = 0x0C,
  PCD_MFAuthent = 0x0E, PCD_SoftReset = 0x0F}
■ enum PCD RxGain : byte {
  RxGain_18dB = 0x00 << 4, RxGain_23dB = 0x01 << 4, RxGain_18dB_2 = 0x02 << 4, RxGain_ \leftrightarrow
  23dB_2 = 0x03 << 4
  RxGain 33dB = 0x04 << 4, RxGain 38dB = 0x05 << 4, RxGain 43dB = 0x06 << 4, RxGain 48dB =
  0x07 << 4.
  RxGain_min = 0x00 << 4, RxGain_avg = 0x04 << 4, RxGain_max = 0x07 << 4
enum PICC_Command : byte {
  PICC CMD REQA = 0x26, PICC CMD WUPA = 0x52, PICC CMD CT = 0x88, PICC CMD SEL CL1 =
  0x93.
  PICC CMD SEL CL2 = 0x95, PICC CMD SEL CL3 = 0x97, PICC CMD HLTA = 0x50, PICC CMD \leftrightarrow
  RATS = 0xE0.
  PICC CMD MF AUTH KEY A = 0x60, PICC CMD MF AUTH KEY B = 0x61, PICC CMD MF READ
  = 0x30, PICC CMD MF WRITE = 0xA0,
  PICC CMD MF DECREMENT = 0xC0, PICC CMD MF INCREMENT = 0xC1, PICC CMD MF \leftrightarrow
  RESTORE = 0xC2, PICC_CMD_MF_TRANSFER = 0xB0,
  PICC CMD UL WRITE = 0xA2}
enum MIFARE_Misc { MF_ACK = 0xA , MF_KEY_SIZE = 6 }
enum PICC_Type : byte {
  PICC_TYPE_UNKNOWN , PICC_TYPE_ISO_14443_4 , PICC_TYPE_ISO_18092 , PICC_TYPE_←
  MIFARE MINI,
  PICC TYPE MIFARE 1K , PICC TYPE MIFARE 4K , PICC TYPE MIFARE UL , PICC TYPE \leftrightarrow
  MIFARE PLUS,
  PICC TYPE MIFARE DESFIRE, PICC TYPE TNP3XXX, PICC TYPE NOT COMPLETE = 0xff }
enum StatusCode : byte {
  STATUS OK, STATUS ERROR, STATUS COLLISION, STATUS TIMEOUT,
  STATUS NO ROOM, STATUS INTERNAL ERROR, STATUS INVALID, STATUS CRC WRONG,
  STATUS_MIFARE_NACK = 0xff }
```

Métodos públicos

■ **MFRC522** (byte resetPowerDownPin)

- MFRC522 (byte chipSelectPin, byte resetPowerDownPin)
- void PCD_WriteRegister (PCD_Register reg, byte value)
- void PCD WriteRegister (PCD Register reg, byte count, byte *values)
- byte PCD_ReadRegister (PCD_Register reg)
- void PCD ReadRegister (PCD Register reg, byte count, byte *values, byte rxAlign=0)
- void PCD_SetRegisterBitMask (PCD_Register reg, byte mask)
- void PCD_ClearRegisterBitMask (PCD_Register reg, byte mask)
- StatusCode PCD_CalculateCRC (byte *data, byte length, byte *result)
- void PCD Init ()
- void PCD Init (byte resetPowerDownPin)
- void **PCD_Init** (byte chipSelectPin, byte resetPowerDownPin)
- void PCD Reset ()
- void PCD AntennaOn ()
- void PCD_AntennaOff ()
- byte PCD GetAntennaGain ()
- void PCD SetAntennaGain (byte mask)
- bool PCD_PerformSelfTest ()
- void PCD SoftPowerDown ()
- void PCD_SoftPowerUp ()
- StatusCode PCD_TransceiveData (byte *sendData, byte sendLen, byte *backData, byte *backLen, byte *validBits=nullptr, byte rxAlign=0, bool checkCRC=false)
- StatusCode PCD_CommunicateWithPICC (byte command, byte waitIRq, byte *sendData, byte sendLen, byte *backData=nullptr, byte *backLen=nullptr, byte *validBits=nullptr, byte rxAlign=0, bool checkCRC=false)
- StatusCode PICC_RequestA (byte *bufferATQA, byte *bufferSize)
- StatusCode **PICC_WakeupA** (byte *bufferATQA, byte *bufferSize)
- StatusCode PICC_REQA_or_WUPA (byte command, byte *bufferATQA, byte *bufferSize)
- virtual StatusCode PICC_Select (Uid *uid, byte validBits=0)
- StatusCode PICC HaltA ()
- StatusCode PCD Authenticate (byte command, byte blockAddr, MIFARE Key *key, Uid *uid)
- void PCD StopCrypto1 ()
- StatusCode MIFARE_Read (byte blockAddr, byte *buffer, byte *bufferSize)
- StatusCode MIFARE Write (byte blockAddr, byte *buffer, byte bufferSize)
- StatusCode MIFARE Ultralight Write (byte page, byte *buffer, byte bufferSize)
- StatusCode MIFARE Decrement (byte blockAddr, int32 t delta)
- StatusCode MIFARE_Increment (byte blockAddr, int32_t delta)
- StatusCode MIFARE_Restore (byte blockAddr)
- StatusCode MIFARE_Transfer (byte blockAddr)
- StatusCode MIFARE_GetValue (byte blockAddr, int32_t *value)
- StatusCode MIFARE_SetValue (byte blockAddr, int32_t value)
- StatusCode PCD_NTAG216_AUTH (byte *passWord, byte pACK[])
- StatusCode PCD_MIFARE_Transceive (byte *sendData, byte sendLen, bool acceptTimeout=false)
- void PCD_DumpVersionToSerial ()
- void PICC DumpToSerial (Uid *uid)
- void PICC_DumpDetailsToSerial (Uid *uid)
- void PICC DumpMifareClassicToSerial (Uid *uid, PICC Type piccType, MIFARE Key *key)
- void PICC DumpMifareClassicSectorToSerial (Uid *uid, MIFARE Key *key, byte sector)
- void PICC DumpMifareUltralightToSerial ()
- void MIFARE SetAccessBits (byte *accessBitBuffer, byte g0, byte g1, byte g2, byte g3)
- bool MIFARE_OpenUidBackdoor (bool logErrors)
- bool MIFARE_SetUid (byte *newUid, byte uidSize, bool logErrors)
- bool MIFARE_UnbrickUidSector (bool logErrors)
- virtual bool PICC_IsNewCardPresent ()
- virtual bool PICC_ReadCardSerial ()

Métodos públicos estáticos

- static const __FlashStringHelper * **GetStatusCodeName** (StatusCode code)
- static PICC_Type PICC_GetType (byte sak)
- static const __FlashStringHelper * PICC_GetTypeName (PICC_Type type)

Campos de datos

Uid uid

Atributos públicos estáticos

- static constexpr byte FIFO SIZE = 64
- static constexpr uint8_t **UNUSED_PIN** = UINT8_MAX

Métodos protegidos

StatusCode MIFARE_TwoStepHelper (byte command, byte blockAddr, int32 t data)

Atributos protegidos

- byte _chipSelectPin
- byte _resetPowerDownPin

4.3.1. Documentación de estructuras de datos

4.3.1.1. struct MFRC522::MIFARE_Key

Diagrama de colaboración de MFRC522::MIFARE_Key:

MFRC522::MIFARE_Key
+ keyByte

Campos de datos

byte keyByte[MF_KEY_SIZE]

4.3.1.2. struct MFRC522::Uid

Diagrama de colaboración de MFRC522::Uid:



Campos de datos

byte	sak	
byte	size	
byte	uidByte[10]	

La documentación de esta clase está generada del siguiente archivo:

■ main/libraries/RFID-RC522/MFRC522.h

4.4. Referencia de la clase MFRC522Extended

#include <MFRC522Extended.h>

Diagrama de herencia de MFRC522Extended

MFRC522

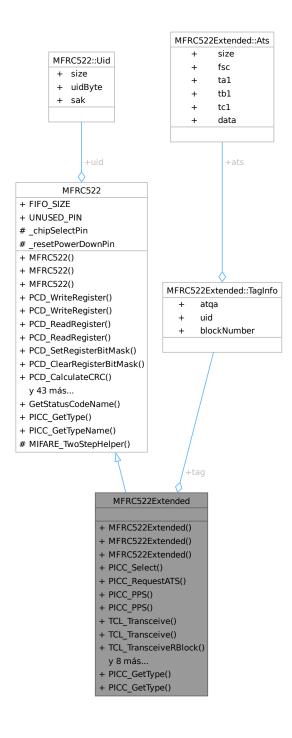
- + uid
- + FIFO_SIZE
- + UNUSED_PIN
- # _chipSelectPin
- # _resetPowerDownPin
- + MFRC522()
- + MFRC522()
- + MFRC522()
- + PCD_WriteRegister()
- + PCD_WriteRegister()
- + PCD_ReadRegister()
- + PCD_ReadRegister()
- + PCD_SetRegisterBitMask()
- + PCD_ClearRegisterBitMask()
- + PCD_CalculateCRC()
- y 43 más...
- + GetStatusCodeName() + PICC_GetType()
- + PICC_GetTypeName()
- # MIFARE_TwoStepHelper()



MFRC522Extended

- + tag
- + MFRC522Extended()
- + MFRC522Extended()
- + MFRC522Extended()
- + PICC_Select()
- + PICC_RequestATS()
- + PICC_PPS()
- + PICC_PPS()
- + TCL_Transceive()
- + TCL_Transceive()
- + TCL_TransceiveRBlock() y 8 más...
- + PICC_GetType()
- + PICC_GetType()

Diagrama de colaboración de MFRC522Extended:



Estructuras de datos

- struct Ats
- struct Ats.ta1
- struct Ats.tb1
- struct Ats.tc1
- struct PcbBlock

- struct PcbBlock.inf
- struct PcbBlock.prologue
- struct TagInfo

Tipos públicos

■ enum TagBitRates : byte { BITRATE_106KBITS = 0x00 , BITRATE_212KBITS = 0x01 , BITRATE_424←
KBITS = 0x02 , BITRATE_848KBITS = 0x03 }

Tipos públicos heredados de MFRC522

```
enum PCD_Register : byte {
  CommandReg = 0x01 << 1, ComIEnReg = 0x02 << 1, DivIEnReg = 0x03 << 1, ComIrqReg = 0x04
  DivIrgReg = 0x05 << 1, ErrorReg = 0x06 << 1, Status1Reg = 0x07 << 1, Status2Reg = 0x08 << 1,
  FIFODataReg = 0x09 << 1, FIFOLevelReg = 0x0A << 1, WaterLevelReg = 0x0B << 1, ControlReg =
  0x0C << 1,
  BitFramingReg = 0x0D << 1, CollReg = 0x0E << 1, ModeReg = 0x11 << 1, TxModeReg = 0x12 <<
  RxModeReg = 0x13 << 1, TxControlReg = 0x14 << 1, TxASKReg = 0x15 << 1, TxSelReg = 0x16 << 1
  RxSelReg = 0x17 << 1, RxThresholdReg = 0x18 << 1, DemodReg = 0x19 << 1, MfTxReg = 0x1C
  <<1 .
  MfRxReg = 0x1D << 1, SerialSpeedReg = 0x1F << 1, CRCResultRegH = 0x21 << 1, CRCResultRegL
  = 0x22 << 1,
  ModWidthReg = 0x24 << 1, RFCfgReg = 0x26 << 1, GsNReg = 0x27 << 1, CWGsPReg = 0x28 << 1
  ModGsPReg = 0x29 << 1, TModeReg = 0x2A << 1, TPrescalerReg = 0x2B << 1, TReloadRegH = 0x2B
  0x2C << 1,
  TReloadRegL = 0x2D << 1, TCounterValueRegH = 0x2E << 1, TCounterValueRegL = 0x2F << 1,
  TestSel1Req = 0x31 << 1,
  TestSel2Reg = 0x32 << 1, TestPinEnReg = 0x33 << 1, TestPinValueReg = 0x34 << 1, TestBusReg
  AutoTestReg = 0x36 << 1, VersionReg = 0x37 << 1, AnalogTestReg = 0x38 << 1, TestDAC1Reg =
  0x39 << 1,
  TestDAC2Reg = 0x3A << 1, TestADCReg = 0x3B << 1}
enum PCD Command : byte {
  PCD_Idle = 0x00 , PCD_Mem = 0x01 , PCD_GenerateRandomID = 0x02 , PCD_CalcCRC = 0x03 ,
  PCD_Transmit = 0x04 , PCD_NoCmdChange = 0x07 , PCD_Receive = 0x08 , PCD_Transceive = 0x0C ,
  PCD MFAuthent = 0x0E, PCD SoftReset = 0x0F }
■ enum PCD RxGain : byte {
  RxGain 18dB = 0x00 << 4, RxGain 23dB = 0x01 << 4, RxGain 18dB 2 = 0x02 << 4, RxGain \leftrightarrow
  23dB 2 = 0x03 << 4,
  RxGain_33dB = 0x04 << 4, RxGain_38dB = 0x05 << 4, RxGain_43dB = 0x06 << 4, RxGain_48dB = 0x06 << 4
  0x07 << 4,
  RxGain\_min = 0x00 << 4, RxGain\_avg = 0x04 << 4, RxGain\_max = 0x07 << 4
■ enum PICC Command : byte {
  PICC_CMD_REQA = 0x26, PICC_CMD_WUPA = 0x52, PICC_CMD_CT = 0x88, PICC_CMD_SEL_CL1 =
  PICC CMD SEL CL2 = 0x95, PICC CMD SEL CL3 = 0x97, PICC CMD HLTA = 0x50, PICC CMD \leftrightarrow
  RATS = 0xE0.
  PICC CMD MF AUTH KEY A = 0x60, PICC CMD MF AUTH KEY B = 0x61, PICC CMD MF READ
  = 0x30, PICC CMD MF WRITE = 0xA0,
  PICC CMD MF DECREMENT = 0xC0, PICC CMD MF INCREMENT = 0xC1, PICC CMD MF \leftrightarrow
  RESTORE = 0xC2, PICC_CMD_MF_TRANSFER = 0xB0,
  PICC CMD UL WRITE = 0xA2 }
```

- enum MIFARE_Misc { MF_ACK = 0xA , MF_KEY_SIZE = 6 }
- enum PICC_Type : byte {

PICC_TYPE_UNKNOWN , PICC_TYPE_ISO_14443_4 , PICC_TYPE_ISO_18092 , PICC_TYPE_ \leftrightarrow MIFARE MINI ,

PICC_TYPE_MIFARE_1K , PICC_TYPE_MIFARE_4K , PICC_TYPE_MIFARE_UL , PICC_TYPE_ \leftrightarrow MIFARE PLUS ,

PICC TYPE MIFARE DESFIRE, PICC TYPE TNP3XXX, PICC TYPE NOT COMPLETE = 0xff }

■ enum StatusCode : bvte {

STATUS_OK, STATUS_ERROR, STATUS_COLLISION, STATUS_TIMEOUT, STATUS_NO_ROOM, STATUS_INTERNAL_ERROR, STATUS_INVALID, STATUS_CRC_WRONG, STATUS_MIFARE_NACK = 0xff }

Métodos públicos

- MFRC522Extended (uint8 t rst)
- MFRC522Extended (uint8_t ss, uint8_t rst)
- StatusCode PICC Select (Uid *uid, byte validBits=0) override
- StatusCode PICC_RequestATS (Ats *ats)
- StatusCode PICC PPS ()
- StatusCode PICC PPS (TagBitRates sendBitRate, TagBitRates receiveBitRate)
- StatusCode TCL_Transceive (PcbBlock *send, PcbBlock *back)
- StatusCode TCL_Transceive (TagInfo *tag, byte *sendData, byte sendLen, byte *backData=NULL, byte *backLen=NULL)
- StatusCode TCL_TransceiveRBlock (TagInfo *tag, bool ack, byte *backData=NULL, byte *backLen=NULL)
- StatusCode TCL Deselect (TagInfo *tag)
- void PICC_DumpToSerial (TagInfo *tag)
- void PICC_DumpDetailsToSerial (TagInfo *tag)
- void PICC_DumpISO14443_4 (TagInfo *tag)
- bool PICC_IsNewCardPresent () override
- bool PICC_ReadCardSerial () override
- void PICC DumpToSerial (Uid *uid)
- void PICC_DumpDetailsToSerial (Uid *uid)

Métodos públicos heredados de MFRC522

- MFRC522 (byte resetPowerDownPin)
- MFRC522 (byte chipSelectPin, byte resetPowerDownPin)
- void PCD_WriteRegister (PCD_Register reg, byte value)
- void **PCD** WriteRegister (PCD Register reg, byte count, byte *values)
- byte PCD_ReadRegister (PCD_Register reg)
- void PCD_ReadRegister (PCD_Register reg, byte count, byte *values, byte rxAlign=0)
- void PCD SetRegisterBitMask (PCD Register reg, byte mask)
- void PCD_ClearRegisterBitMask (PCD_Register reg, byte mask)
- StatusCode PCD_CalculateCRC (byte *data, byte length, byte *result)
- void PCD_Init ()
- void PCD_Init (byte resetPowerDownPin)
- void PCD_Init (byte chipSelectPin, byte resetPowerDownPin)
- void PCD_Reset ()
- void PCD_AntennaOn ()
- void PCD AntennaOff ()
- byte PCD GetAntennaGain ()
- void PCD SetAntennaGain (byte mask)
- bool PCD_PerformSelfTest ()

- void PCD_SoftPowerDown ()
- void PCD SoftPowerUp ()
- StatusCode PCD_TransceiveData (byte *sendData, byte sendLen, byte *backData, byte *backLen, byte *validBits=nullptr, byte rxAlign=0, bool checkCRC=false)
- StatusCode PCD_CommunicateWithPICC (byte command, byte waitIRq, byte *sendData, byte sendLen, byte *backData=nullptr, byte *backLen=nullptr, byte *validBits=nullptr, byte rxAlign=0, bool checkCRC=false)
- StatusCode PICC_RequestA (byte *bufferATQA, byte *bufferSize)
- StatusCode PICC WakeupA (byte *bufferATQA, byte *bufferSize)
- StatusCode PICC_REQA_or_WUPA (byte command, byte *bufferATQA, byte *bufferSize)
- StatusCode PICC_HaltA ()
- StatusCode PCD Authenticate (byte command, byte blockAddr, MIFARE Key *key, Uid *uid)
- void PCD StopCrvpto1 ()
- StatusCode MIFARE_Read (byte blockAddr, byte *buffer, byte *bufferSize)
- StatusCode MIFARE_Write (byte blockAddr, byte *buffer, byte bufferSize)
- StatusCode MIFARE_Ultralight_Write (byte page, byte *buffer, byte bufferSize)
- StatusCode MIFARE Decrement (byte blockAddr, int32 t delta)
- StatusCode MIFARE_Increment (byte blockAddr, int32_t delta)
- StatusCode MIFARE Restore (byte blockAddr)
- StatusCode MIFARE Transfer (byte blockAddr)
- StatusCode MIFARE_GetValue (byte blockAddr, int32_t *value)
- StatusCode MIFARE_SetValue (byte blockAddr, int32_t value)
- StatusCode PCD_NTAG216_AUTH (byte *passWord, byte pACK[])
- StatusCode PCD_MIFARE_Transceive (byte *sendData, byte sendLen, bool acceptTimeout=false)
- void PCD DumpVersionToSerial ()
- void PICC DumpToSerial (Uid *uid)
- void PICC_DumpDetailsToSerial (Uid *uid)
- void PICC_DumpMifareClassicToSerial (Uid *uid, PICC_Type piccType, MIFARE_Key *key)
- void PICC_DumpMifareClassicSectorToSerial (Uid *uid, MIFARE_Key *key, byte sector)
- void PICC DumpMifareUltralightToSerial ()
- void MIFARE_SetAccessBits (byte *accessBitBuffer, byte g0, byte g1, byte g2, byte g3)
- bool MIFARE OpenUidBackdoor (bool logErrors)
- bool MIFARE SetUid (byte *newUid, byte uidSize, bool logErrors)
- bool MIFARE_UnbrickUidSector (bool logErrors)

Métodos públicos estáticos

- static PICC Type PICC GetType (TagInfo *tag)
- static PICC_Type PICC_GetType (byte sak)

Métodos públicos estáticos heredados de MFRC522

- static const FlashStringHelper * **GetStatusCodeName** (StatusCode code)
- static PICC Type PICC GetType (byte sak)
- static const __FlashStringHelper * PICC_GetTypeName (PICC_Type type)

Campos de datos

TagInfo tag

Campos de datos heredados de MFRC522

Uid uid

Otros miembros heredados

Atributos públicos estáticos heredados de MFRC522

- static constexpr byte FIFO_SIZE = 64
- static constexpr uint8_t UNUSED_PIN = UINT8_MAX

Métodos protegidos heredados de MFRC522

StatusCode MIFARE_TwoStepHelper (byte command, byte blockAddr, int32_t data)

Atributos protegidos heredados de MFRC522

- byte _chipSelectPin
- byte _resetPowerDownPin

4.4.1. Descripción detallada

Library extends MFRC522.h to support RATS for ISO-14443-4 PICC. RATS - Request for Answer To Select.

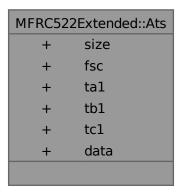
Autor

JPG-Consulting

4.4.2. Documentación de estructuras de datos

4.4.2.1. struct MFRC522Extended::Ats

Diagrama de colaboración de MFRC522Extended::Ats:



Campos de datos

byte	data[FIFO_SIZE - 2]	
byte	fsc	
byte	size	
struct Ats.ta1	ta1	
struct Ats.tb1	tb1	
struct Ats.tc1	tc1	

4.4.2.2. struct MFRC522Extended::Ats.ta1

Diagrama de colaboración de MFRC522Extended::Ats.ta1:

MFRC522Extended::Ats.ta1		
+	transmitted	
+	sameD	
+	ds	
+	dr	

TagBitRates	dr	
TagBitRates	ds	
bool	sameD	
bool	transmitted	

4.4.2.3. struct MFRC522Extended::Ats.tb1

Diagrama de colaboración de MFRC522Extended::Ats.tb1:

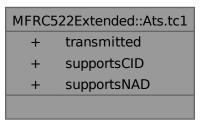
MFRC522Extended::Ats.tb1	
+	transmitted
+	fwi
+	sfgi

Campos de datos

byte	fwi	
byte	sfgi	
bool	transmitted	

4.4.2.4. struct MFRC522Extended::Ats.tc1

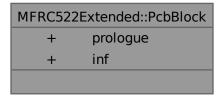
Diagrama de colaboración de MFRC522Extended::Ats.tc1:



bool	supportsCID	
bool	supportsNAD	
bool	transmitted	

4.4.2.5. struct MFRC522Extended::PcbBlock

Diagrama de colaboración de MFRC522Extended::PcbBlock:

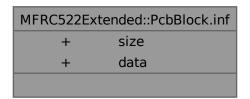


Campos de datos

struct PcbBlock.inf	inf	
struct PcbBlock.prologue	prologue	

4.4.2.6. struct MFRC522Extended::PcbBlock.inf

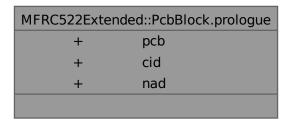
Diagrama de colaboración de MFRC522Extended::PcbBlock.inf:



byte *	data	
byte	size	

4.4.2.7. struct MFRC522Extended::PcbBlock.prologue

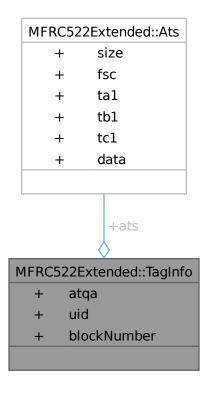
Diagrama de colaboración de MFRC522Extended::PcbBlock.prologue:



byte	cid	
byte	nad	
byte	pcb	

4.4.2.8. struct MFRC522Extended::TagInfo

Diagrama de colaboración de MFRC522Extended::TagInfo:



Campos de datos

uint16_t	atqa	
Ats	ats	
bool	blockNumber	
Uid	uid	

4.4.3. Documentación de funciones miembro

4.4.3.1. PICC_IsNewCardPresent()

bool MFRC522Extended::PICC_IsNewCardPresent () [override], [virtual]

Reimplementado de MFRC522.

4.4.3.2. PICC_ReadCardSerial()

bool MFRC522Extended::PICC_ReadCardSerial () [override], [virtual]

Reimplementado de MFRC522.

4.4.3.3. PICC_Select()

Reimplementado de MFRC522.

La documentación de esta clase está generada del siguiente archivo:

■ main/libraries/RFID-RC522/MFRC522Extended.h

Capítulo 5

Documentación de archivos

5.1. DHT11.h

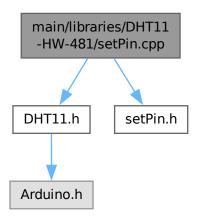
```
00001
00011 #ifndef DHT11_h
 00012 #define DHT11_h
 00014 #include "Arduino.h"
00015
00021 class DHT11
00022 {
 00023
 00024 public:
 00031
                    DHT11(int pin);
 00032
                     void setDelay(unsigned long delay);
 00039
 00040
 00047
                     int readHumidity();
 00048
 00055
                     int readTemperature();
00056
00064
                     int readTemperatureHumidity(int &temperature, int &humidity);
00065
00066
                     // Constants to represent error codes.
                                                                                                                                          // Error code indicating checksum mismatch.
// Error code indicating a timeout occurred during
                    static const int ERROR_CHECKSUM = 254;
00067
00068
                      static const int ERROR_TIMEOUT = 253;
                reading.
00069
                     static const int TIMEOUT_DURATION = 1000; // Duration (in milliseconds) to wait before timing out.
00070
                      // static String getErrorString(int errorCode);
 00077
 00078
 00079 private:
00080 int_pin; // Pin number used for communication with the constitution of the constitution with the constit
                                                                                                             // Pin number used for communication with the DHT11 sensor.
00093
                     int readRawData(byte data[5]);
00094
 00100
                    byte readByte();
 00101
00107
                    void startSignal();
00108
                      friend void setPinDHT11(DHT11& sensor, int pin);
00109
 00110
00111 };
 00112
00113 #endif
```

5.2. Referencia del archivo main/libraries/DHT11-HW-481/setPin.cpp

Función amiga setPinDHT11.

```
#include "DHT11.h"
#include "setPin.h"
```

Gráfico de dependencias incluidas en setPin.cpp:



Funciones

void setPinDHT11 (DHT11 &sensor, int pin)

5.2.1. Descripción detallada

Función amiga setPinDHT11.

Parámetros

DHT11&	sensor: recibe una referencia al objeto de la clase DHT11 al cual se le cambiará el pin de conexión	
	correspondiente al sensor de temperatura.	
int	pin: es el nuevo pin para la entrada de datos del sensor de temperatura.	

La función comprueba si el pin es válido, luego "desactiva" el pin anterior para inicializar el nuevo.

5.2.2. Documentación de funciones

5.2.2.1. setPinDHT11()

```
void setPinDHT11 ( {\tt DHT11 \& sensor,} {\tt int } pin)
```

Bloque if-else Controla si el pin ingresado es uno físicamente válido. Imprime por puerto serie UART un mensaje de error en caso de no serlo.

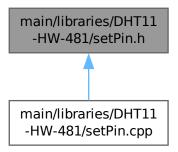
pinMode(sensor._pin, INPUT) "Desactiva" el pin anterior.

```
sensor._pin = pin Actualiza el pin.
```

pinMode(pin, OUTPUT) y digitalWrite(pin, HIGH) Inicializa el nuevo pin como lo hace internamente la clase DHT11 delay(250) Tiempo de espera a que el sensor se estabilice.

5.3. Referencia del archivo main/libraries/DHT11-HW-481/setPin.h

Gráfico de los archivos que directa o indirectamente incluyen a este archivo:



Funciones

void setPinDHT11 (DHT11 &sensor, int pin)

5.3.1. Descripción detallada

Este archivo contiene las declaraciones de la clase DHT11 y su función amiga setPinDHT11.

5.3.2. Documentación de funciones

5.3.2.1. setPinDHT11()

Bloque if-else Controla si el pin ingresado es uno físicamente válido. Imprime por puerto serie UART un mensaje de error en caso de no serlo.

pinMode(sensor._pin, INPUT) "Desactiva" el pin anterior.

sensor._pin = pin Actualiza el pin.

pinMode(pin, OUTPUT) y digitalWrite(pin, HIGH) Inicializa el nuevo pin como lo hace internamente la clase DHT11 delay(250) Tiempo de espera a que el sensor se estabilice.

5.4. setPin.h

Ir a la documentación de este archivo.

```
00001 #ifndef SETPIN_H
00002 #define SETPIN_H
00003
00009 class DHT11;
00010 void setPinDHT11(DHT11& sensor, int pin);
00011
00012 #endif
```

5.5. accesoRFID.h

```
00001 #ifndef ACCESORRFID_H
00002 #define ACCESORRFID_H
00003
00004 #include <SPI.h>
00005 #include "MFRC522.h"
00006
00016 class accesoRFID {
00017
        public:
00018
00027
            accesoRFID(byte ssPin, byte rstPin, String autorizarID);
00028
00034
            void start();
00035
00042
            void mostrarID();
00043
00049
            bool autorizar();
00050
            bool detectarTarjeta();
00056
00057
          private:
00059
              MFRC522 rdif;
00060
               String autorizarID;
00061
00062 };
00063
00064 #endif
```

5.6. deprecated.h

```
00001
00007 #ifndef DEPRECATED_H
00008 #define DEPRECATED_H
00009
00010 #ifdef __has_cpp_attribute
00011 #if __has_cpp_attribute(deprecated)
00012 #define DEPRECATED [[deprecated]]
00013 #define DEPRECATED_MSG(msg) [[deprecated(msg)]]
00014 #endif // __has_cpp_attribute(deprecated)
00015 #else
00016 #define DEPRECATED __attribute__((deprecated))
00017 #define DEPRECATED_MSG(msg) __attribute__((deprecated(msg)))
0018 #endif // __has_cpp_attribute
00019
00020 #endif // DEPRECATED_H
```

5.7. MFRC522.h

```
00001
00010 #ifndef MFRC522_h
00011 #define MFRC522_h
00012
00013 #include "require_cpp11.h"
00014 #include "deprecated.h"
00015 // Enable integer limits
00016 #define __STDC_LIMIT_MACROS
00017 #include <stdint.h>
00018 #include <Arduino.h>
00019 #include <SPI.h>
00020
00021 #ifndef MFRC522_SPICLOCK
```

5.7 MFRC522.h 33

```
00022 #define MFRC522_SPICLOCK (4000000u) // MFRC522 accept upto 10MHz, set to 4MHz.
00024
00025 // Firmware data for self-test
00026 // Reference values based on firmware version
00027 // Hint: if needed, you can remove unused self-test data to save flash memory
00029 // Version 0.0 (0x90)
00030 // Philips Semiconductors; Preliminary Specification Revision 2.0 - 01 August 2005; 16.1 self-test
00031 const byte MFRC522_firmware_referenceV0_0[] PROGMEM = {
          0x00, 0x87, 0x98, 0x0f, 0x49, 0xFF, 0x07, 0x19,
00032
00033
          0xBF, 0x22, 0x30, 0x49, 0x59, 0x63, 0xAD, 0xCA,
00034
          0x7F, 0xE3, 0x4E, 0x03, 0x5C, 0x4E, 0x49, 0x50,
          0x47, 0x9A, 0x37, 0x61, 0xE7, 0xE2, 0xC6, 0x2E,
00035
00036
          0x75, 0x5A, 0xED, 0x04, 0x3D, 0x02, 0x4B, 0x78,
00037
          0x32, 0xFF, 0x58, 0x3B, 0x7C, 0xE9, 0x00, 0x94,
00038
          0xB4, 0x4A, 0x59, 0x5B, 0xFD, 0xC9, 0x29, 0xDF,
00039
          0x35, 0x96, 0x98, 0x9E, 0x4F, 0x30, 0x32, 0x8D
00040 };
00041 // Version 1.0 (0x91)
00042 // NXP Semiconductors; Rev. 3.8 - 17 September 2014; 16.1.1 self-test
00043 const byte MFRC522_firmware_referenceV1_0[] PROGMEM = {
00044
          0x00, 0xC6, 0x37, 0xD5, 0x32, 0xB7, 0x57, 0x5C,
00045
          0xC2, 0xD8, 0x7C, 0x4D, 0xD9, 0x70, 0xC7, 0x73,
00046
          0x10, 0xE6, 0xD2, 0xAA, 0x5E, 0xA1, 0x3E, 0x5A,
00047
          0x14, 0xAF, 0x30, 0x61, 0xC9, 0x70, 0xDB, 0x2E,
00048
          0x64, 0x22, 0x72, 0xB5, 0xBD, 0x65, 0xF4, 0xEC,
00049
          0x22, 0xBC, 0xD3, 0x72, 0x35, 0xCD, 0xAA, 0x41,
00050
          0x1F, 0xA7, 0xF3, 0x53, 0x14, 0xDE, 0x7E, 0x02,
00051
          0xD9, 0x0F, 0xB5, 0x5E, 0x25, 0x1D, 0x29, 0x79
00052 1:
00053 // Version 2.0 (0x92)
00054 // NXP Semiconductors; Rev. 3.8 - 17 September 2014; 16.1.1 self-test
00055 const byte MFRC522_firmware_referenceV2_0[] PROGMEM = {
00056
          0x00, 0xEB, 0x66, 0xBA, 0x57, 0xBF, 0x23, 0x95,
00057
          0xD0, 0xE3, 0x0D, 0x3D, 0x27, 0x89, 0x5C, 0xDE,
          0x9D, 0x3B, 0xA7, 0x00, 0x21, 0x5B, 0x89, 0x82,
00058
          0x51, 0x3A, 0xEB, 0x02, 0x0C, 0xA5, 0x00, 0x49,
00060
          0x7C, 0x84, 0x4D, 0xB3, 0xCC, 0xD2, 0x1B, 0x81,
00061
          0x5D, 0x48, 0x76, 0xD5, 0x71, 0x61, 0x21, 0xA9,
00062
          0x86, 0x96, 0x83, 0x38, 0xCF, 0x9D, 0x5B, 0x6D,
00063
          0xDC, 0x15, 0xBA, 0x3E, 0x7D, 0x95, 0x3B, 0x2F
00064 1:
00065 // Clone
00066 // Fudan Semiconductor FM17522 (0x88)
00067 const byte FM17522_firmware_reference[] PROGMEM = {
00068
          0x00, 0xD6, 0x78, 0x8C, 0xE2, 0xAA, 0x0C, 0x18,
00069
          0x2A, 0xB8, 0x7A, 0x7F, 0xD3, 0x6A, 0xCF, 0x0B,
          0xB1, 0x37, 0x63, 0x4B, 0x69, 0xAE, 0x91, 0xC7,
00070
00071
          0xC3, 0x97, 0xAE, 0x77, 0xF4, 0x37, 0xD7, 0x9B,
          0x7C, 0xF5, 0x3C, 0x11, 0x8F, 0x15, 0xC3, 0xD7,
00073
          0xC1, 0x5B, 0x00, 0x2A, 0xD0, 0x75, 0xDE, 0x9E,
00074
          0x51, 0x64, 0xAB, 0x3E, 0xE9, 0x15, 0xB5, 0xAB,
00075
          0x56, 0x9A, 0x98, 0x82, 0x26, 0xEA, 0x2A, 0x62
00076 };
00077
00078 class MFRC522 {
00079 public:
00080
         // Size of the MFRC522 FIFO
00081
          static constexpr byte FIFO_SIZE = 64;
                                                      // The FIFO is 64 bytes.
00082
          // Default value for unused pin
00083
          static constexpr uint8 t UNUSED PIN = UINT8 MAX;
00084
00085
          // MFRC522 registers. Described in chapter 9 of the datasheet.
          // When using SPI all addresses are shifted one bit left in the "SPI address byte" (section
00086
     8.1.2.3)
00087
          enum PCD_Register : byte {
00088
            // Page 0: Command and status
00089
                                        0x00
                                                        // reserved for future use
00090
              CommandReg
                                       = 0 \times 01 \ll 1,
                                                      // starts and stops command execution
00091
                                       = 0x02 \ll 1,
                                                       // enable and disable interrupt request control bits
              ComIEnReg
00092
              DivIEnReg
                                      = 0x03 \ll 1,
                                                      \ensuremath{//} enable and disable interrupt request control bits
                                      = 0x04 \ll 1,
00093
              ComIrqReg
                                                      // interrupt request bits
                                                      // interrupt request bits
00094
                                      = 0x05 \ll 1,
              DivIrqReq
                                                      // error bits showing the error status of the last
00095
                                       = 0x06 \ll 1,
              ErrorReg
     command executed
00096
              Status1Reg
                                       = 0x07 \ll 1,
                                                       // communication status bits
00097
              Status2Reg
                                       = 0x08 \ll 1,
                                                       // receiver and transmitter status bits
00098
              FIFODataReg
                                       = 0 \times 09 \times 1.
                                                       // input and output of 64 byte FIFO buffer
00099
                                       = 0 \times 0 A \ll 1.
                                                      // number of bytes stored in the FIFO buffer
              FIFOLevelRea
                                                      // level for FIFO underflow and overflow warning
00100
                                       = 0x0B \ll 1,
              WaterLevelReg
                                      = 0x0C \ll 1,
              ControlReg
                                                      // miscellaneous control registers
                                       = 0x0D \ll 1,
                                                       // adjustments for bit-oriented frames
00102
              BitFramingReg
              CollReg
                                      = 0x0E \ll 1,
                                                      // bit position of the first bit-collision detected on
00103
     the RF interface
00104
              //
                                         0×0F
                                                       // reserved for future use
00105
```

```
// Page 1: Command
                                                             0x10
                                                                                   // reserved for future use
00108
                      ModeReg
                                                          = 0x11 \ll 1,
                                                                                 // defines general modes for transmitting and receiving
                                                          = 0x12 \ll 1,
00109
                      TxModeReg
                                                                                 // defines transmission data rate and framing
00110
                      RxModeRea
                                                          = 0x13 \ll 1,
                                                                                 // defines reception data rate and framing
00111
                      TxControlReg
                                                          = 0x14 \ll 1,
                                                                                  // controls the logical behavior of the antenna driver
        pins TX1 and TX2
00112
                      TxASKReg
                                                          = 0x15 \ll 1
                                                                                  \ensuremath{//} controls the setting of the transmission modulation
                      TxSelReg
                                                          = 0x16 \ll 1,
00113
                                                                                  // selects the internal sources for the antenna driver
                                                          = 0x17 \ll 1.
                                                                                  // selects internal receiver settings
00114
                      RxSelReg
                      RxThresholdReg
00115
                                                          = 0x18 \ll 1.
                                                                                  // selects thresholds for the bit decoder
00116
                      DemodReg
                                                           = 0x19 \ll 1,
                                                                                  // defines demodulator settings
00117
                     //
                                                                                  // reserved for future use
                                                             0x1B
00118
                                                                                   // reserved for future use
parameters 00120
                     MfTxReg
                                                          = 0x1C \ll 1,
                                                                                  \ensuremath{//} controls some MIFARE communication transmit
                     MfRxReq
                                                          = 0x1D \ll 1,
                                                                                  // controls some MIFARE communication receive
MfI parameters
                                                             0x1E
                                                                                   // reserved for future use
00122
                                                          = 0x1F \ll 1,
                                                                                 // selects the speed of the serial UART interface
                      SerialSpeedReg
00123
                     // Page 2: Configuration
00124
00125
                                                             0 \times 2.0
                                                                                   // reserved for future use
00126
                      CRCResultRegH
                                                          = 0x21 \ll 1,
                                                                                 // shows the MSB and LSB values of the CRC calculation
00127
                      CRCResultRegL
                                                           = 0x22 \ll 1,
00128
                                                             0x23
                                                                                   // reserved for future use
                      ModWidthReg
00129
                                                          = 0x24 \ll 1
                                                                                  \//\ controls the ModWidth setting?
00130
                                                             0 \times 2.5
                                                                                   // reserved for future use
                      RFCfgReg
00131
                                                          = 0x26 \ll 1.
                                                                                 // configures the receiver gain
         GsNReg
TX1 and TX2 for modulation
                                                          = 0x27 \ll 1.
00132
                                                                                 // selects the conductance of the antenna driver pins
00133
                      CWGsPReg
                                                          = 0x28 \ll 1,
                                                                                 // defines the conductance of the p-driver output
        during periods of no modulation
                     ModGsPReg
00134
                                                          = 0x29 \ll 1.
                                                                                  // defines the conductance of the p-driver output
        during periods of modulation
00135
                      TModeReg
                                                          = 0x2A \ll 1,
                                                                                  // defines settings for the internal timer
                    TPrescalerReg
00136
                                                                                  // the lower 8 bits of the TPrescaler value. The 4 high
                                                          = 0x2B \ll 1,
        bits are in TModeReg.
                   TReloadRegH
00137
                                                          = 0x2C \ll 1,
                                                                                  // defines the 16-bit timer reload value
00138
                      TReloadRegL
                                                          = 0x2D \ll 1.
                      TCounterValueRegH
                                                          = 0 \times 2 E \ll 1.
00139
                                                                                  // shows the 16-bit timer value
                      TCounterValueRegL
                                                          = 0x2F \ll 1,
00140
00141
00142
                     // Page 3: Test Registers
00143
                                                             0x30
                                                                                   // reserved for future use
00144
                     TestSel1Reg
                                                          = 0x31 \ll 1.
                                                                                  // general test signal configuration
                      TestSel2Reg
00145
                                                          = 0x32 \ll 1,
                                                                                  \label{eq:configuration} \mbox{// general test signal configuration}
                                                                                 // general test styling sense of the property 
00146
                      TestPinEnReg
                                                          = 0x33 \ll 1.
                      TestPinValueReg
                                                          = 0x34 \ll 1.
00147
        an I/O bus
00148
                     TestBusReg
                                                          = 0x35 \ll 1,
                                                                                  // shows the status of the internal test bus
00149
                      AutoTestReg
                                                          = 0x36 \ll 1,
                                                                                  // controls the digital self-test
00150
                      VersionReg
                                                          = 0x37 \ll 1,
                                                                                  // shows the software version
                     AnalogTestReg
                                                          = 0x38 \ll 1.
                                                                                  // controls the pins AUX1 and AUX2
00151
                      TestDAC1Reg
                                                                                  // defines the test value for TestDAC1
00152
                                                          = 0x39 \ll 1,
                      TestDAC2Reg
                                                                                  // defines the test value for TestDAC2
                                                           = 0x3A \ll 1.
                                                                                  // shows the value of ADC I and Q channels
00154
                      TestADCReg
                                                           = 0x3B \ll 1
00155
                                                             0x3C
                                                                                   // reserved for production tests
                      //
                      //
00156
                                                             0 \times 3D
                                                                                   // reserved for production tests
                      11
                                                                                   // reserved for production tests
00157
                                                              0 \times 3 E
00158
                      //
                                                                                   // reserved for production tests
                                                              0x3F
00159
00160
00161
               // MFRC522 commands. Described in chapter 10 of the datasheet.
00162
               enum PCD_Command : byte {
                                                          = 0x00,
00163
                    PCD_Idle
                                                                             \ensuremath{//} no action, cancels current command execution
00164
                      PCD Mem
                                                                             // stores 25 bytes into the internal buffer
                                                          = 0 \times 01.
00165
                      PCD_GenerateRandomID
                                                        = 0 \times 02
                                                                            // generates a 10-byte random ID number
                                                                             // activates the CRC coprocessor or performs a self-test
00166
                      PCD_CalcCRC
                                                          = 0x03,
                      PCD_Transmit
                                                          = 0 \times 04,
                                                                             // transmits data from the FIFO buffer
00167
                     PCD_NoCmdChange
                                                         = 0 \times 07,
00168
                                                                             // no command change, can be used to modify the CommandReg
        register bits without affecting the command, for example, the PowerDown bit

PCD_Receive = 0x08, // activates the receiver circuits

PCD_Transceive = 0x0C, // transmits data from FIFO buffer to antenna and
00169
00170
        automatically activates the receiver after transmission
                                             = 0x0E, // performs the MIFARE standard authentication as a reader = 0x0F // resets the MFRC522
00171
                    PCD_MFAuthent
00172
                     PCD_SoftReset
00173
               };
00174
               // MFRC522 RxGain[2:0] masks, defines the receiver's signal voltage gain factor (on the PCD).
00175
               // Described in 9.3.3.6 / table 98 of the datasheet at
00176
        http://www.nxp.com/documents/data_sheet/MFRC522.pdf
00177
               enum PCD_RxGain : byte {
                 RxGain_18dB
                                                                                  // 000b - 18 dB, minimum
00178
                                                          = 0x00 \ll 4.
                                                                                 // 001b - 23 dB
00179
                      RxGain 23dB
                                                          = 0x01 \ll 4
                                                                                 // 010b - 18 dB, it seems 010b is a duplicate for 000b
00180
                     RxGain_18dB_2
                                                          = 0x02 \ll 4.
```

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```
RxGain 23dB 2
                                            = 0x03 \ll 4.
                                                             // 011b - 23 dB, it seems 011b is a duplicate for 001b
                                                             // 100b - 33 dB, average, and typical default // 101b - 38 dB
00182
                RxGain_33dB
                                            = 0 \times 04 \ll 4
00183
                RxGain_38dB
                                            = 0x05 \ll 4
                                                              // 110b - 43 dB
00184
                RxGain_43dB
                                            = 0x06 \ll 4,
                                                              // 111b - 48 dB, maximum
                                            = 0x07 \ll 4
00185
                RxGain 48dB
                                                             // 000b - 18 dB, minimum, convenience for RxGain_18dB
00186
                RxGain min
                                            = 0x00 \ll 4
                                                              // 100b - 33 dB, average, convenience for RxGain_33dB
                RxGain_avg
                                            = 0 \times 04 \ll 4,
                                                              // 111b - 48 dB, maximum, convenience for RxGain_48dB
00188
                RxGain_max
                                            = 0x07 \ll 4
00189
           };
00190
           // Commands sent to the PICC.
00191
           enum PICC Command : bvte {
00192
                // The commands used by the PCD to manage communication with several PICCs (ISO 14443-3, Type
00193
      A, section 6.4)
00194
               PICC_CMD_REQA
                                           = 0x26,
                                                         // REQuest command, Type A. Invites PICCs in state IDLE to
      go to READY and prepare for anticollision or selection. 7 bit frame.  PICC\_CMD\_WUPA \hspace{1cm} = 0x52, \hspace{1cm} // \hspace{1cm} Wake-UP \hspace{1cm} command, \hspace{1cm} Type \hspace{1cm} A. \hspace{1cm} Invites \hspace{1cm} PICCs \hspace{1cm} in \hspace{1cm} state \hspace{1cm} IDLE \hspace{1cm} and \hspace{1cm} HALT \hspace{1cm} to \hspace{1cm} go \hspace{1cm} to \hspace{1cm} READY (*) \hspace{1cm} and \hspace{1cm} prepare \hspace{1cm} for \hspace{1cm} anticollision \hspace{1cm} or \hspace{1cm} selection. \hspace{1cm} 7 \hspace{1cm} bit \hspace{1cm} frame. 
00195
               PICC_CMD_CT
                                            = 0x88,
                                                         // Cascade Tag. Not really a command, but used during anti
      collision.
                                         = 0x93,
= 0x95,
= 0x07
                PICC_CMD_SEL_CL1
00197
                                                         // Anti collision/Select, Cascade Level 1
                                                         // Anti collision/Select, Cascade Level 2
// Anti collision/Select, Cascade Level 3
00198
                PICC_CMD_SEL_CL2
00199
                PICC_CMD_SEL_CL3
                                           = 0x97,
                PICC_CMD_HLTA
                                           = 0 \times 50.
                                                          // HaLT command, Type A. Instructs an ACTIVE PICC to go to
00200
      state HALT.
00201
               PICC_CMD_RATS
                                           = 0xE0,
                                                          // Request command for Answer To Reset.
                // The commands used for MIFARE Classic (from
00202
      http://www.mouser.com/ds/2/302/MF1S503x-89574.pdf, Section 9)
00203
                // Use PCD_MFAuthent to authenticate access to a sector, then use these commands to
      read/write/modify the blocks on the sector.
00204
                // The read/write commands can also be used for MIFARE Ultralight
00205
                PICC\_CMD\_MF\_AUTH\_KEY\_A = 0x60,
                                                          // Perform authentication with Key A
                PICC\_CMD\_MF\_AUTH\_KEY\_B = 0x61,
                                                          // Perform authentication with Key B
00206
00207
                PICC_CMD_MF_READ
                                           = 0x30,
                                                          // Reads one 16 byte block from the authenticated sector
      of the PICC. Also used for MIFARE Ultralight.

PICC_CMD_MF_WRITE = 0xA0, // Writes one 16 byte block to the authenticated sector of the PICC. Called "COMPATIBILITY WRITE" for MIFARE Ultralight.
00208
               PICC\_CMD\_MF\_DECREMENT = 0xC0,
                                                          // Decrements the contents of a block and stores the
      result in the internal data register.
00210
                PICC_CMD_MF_INCREMENT
                                           = 0xC1,
                                                          // Increments the contents of a block and stores the
      result in the internal data register.
                                           = 0xC2.
00211
               PICC_CMD_MF_RESTORE
                                                         // Reads the contents of a block into the internal data
      register.
00212
                PICC_CMD_MF_TRANSFER
                                           = 0xB0,
                                                          // Writes the contents of the internal data register to a
      block.
00213
                // The commands used for MIFARE Ultralight (from
      http://www.nxp.com/documents/data_sheet/MF0ICU1.pdf, Section 8.6)
// The PICC_CMD_MF_READ and PICC_CMD_MF_WRITE can also be used for MIFARE Ultralight.
00214
00215
               PICC CMD UL WRITE
                                           = 0xA2
                                                         // Writes one 4 byte page to the PICC.
00216
           \ensuremath{//} MIFARE constants that does not fit anywhere else
00218
00219
           enum MIFARE_Misc {
                                            = 0xA,
00220
               MF_ACK
                                                         // The MIFARE Classic uses a 4 bit ACK/NAK. Any other
      value than 0xA is NAK.
00221
               MF KEY SIZE
                                            = 6
                                                         // A Mifare Cryptol key is 6 bytes.
00222
00223
           // PICC types we can detect. Remember to update {\tt PICC\_GetTypeName}\,() if you add more.
00224
00225
           // last value set to 0xff, then compiler uses less ram, it seems some optimisations are triggered
00226
           enum PICC Type : byte {
00227
               PICC_TYPE_UNKNOWN
00228
                PICC_TYPE_ISO_14443_4
                                                // PICC compliant with ISO/IEC 14443-4
                PICC_TYPE_ISO_18092
                                                // PICC compliant with ISO/IEC 18092 (NFC)
00229
                PICC_TYPE_MIFARE_MINI ,
00230
                                                 // MIFARE Classic protocol, 320 bytes
00231
                PICC_TYPE_MIFARE_1K
                                                 // MIFARE Classic protocol, 1KB
                                                 // MIFARE Classic protocol, 4KB
00232
                PICC TYPE MIFARE 4K
                                                // MIFARE Ultralight or Ultralight C
00233
                PICC TYPE MIFARE UL
00234
                PICC_TYPE_MIFARE_PLUS
                                                // MIFARE Plus
                                                // MIFARE DESFire
                PICC_TYPE_MIFARE_DESFIRE,
                                                // Only mentioned in NXP AN 10833 MIFARE Type Identification
00236
                PICC_TYPE_TNP3XXX
      Procedure
00237
                PICC_TYPE_NOT_COMPLETE = 0xff // SAK indicates UID is not complete.
00238
00239
           // Return codes from the functions in this class. Remember to update GetStatusCodeName() if you
00241
           // last value set to 0xff, then compiler uses less ram, it seems some optimisations are triggered
00242
           enum StatusCode : byte {
00243
                STATUS OK
                                                 // Success
                                                 // Error in communication
00244
                STATUS ERROR
00245
                STATUS_COLLISION
                                                 // Collission detected
00246
                STATUS_TIMEOUT
                                                 // Timeout in communication.
00247
                STATUS_NO_ROOM
                                                 // A buffer is not big enough.
00248
                STATUS_INTERNAL_ERROR
                                                 // Internal error in the code. Should not happen ;-)
                                                // Invalid argument.
00249
                STATUS INVALID
00250
                STATUS_CRC_WRONG
                                                // The CRC_A does not match
```

```
STATUS MIFARE NACK
                                                           = 0xff // A MIFARE PICC responded with NAK.
00252
00253
00254
                // A struct used for passing the UID of a PICC.
00255
                typedef struct {
00256
                                          size:
                      bvte
                                                                   // Number of bytes in the UID. 4, 7 or 10.
                      bvte
                                         uidByte[10];
                                                                   // The SAK (Select acknowledge) byte returned from the PICC after
00258
                      byte
         successful selection.
00259
               } Uid;
00260
                // A struct used for passing a MIFARE Cryptol key
00261
00262
                typedef struct {
                                          keyByte[MF_KEY_SIZE];
00263
00264
                } MIFARE_Key;
00265
                // Member variables
00266
00267
                Uid uid;
                                                                            // Used by PICC ReadCardSerial().
00268
00270
                // Functions for setting up the Arduino
00272
00273
                MFRC522(byte resetPowerDownPin);
00274
                MFRC522(byte chipSelectPin, byte resetPowerDownPin);
00275
00277
                // Basic interface functions for communicating with the MFRC522
00279
                void PCD_WriteRegister(PCD_Register reg, byte value);
00280
                void PCD_WriteRegister(PCD_Register reg, byte count, byte *values);
00281
                byte PCD_ReadRegister(PCD_Register reg);
00282
                void PCD_ReadRegister(PCD_Register reg, byte count, byte *values, byte rxAlign = 0);
                void PCD_SetRegisterBitMask(PCD_Register reg, byte mask);
00283
00284
                void PCD_ClearRegisterBitMask(PCD_Register reg, byte mask);
00285
                StatusCode PCD_CalculateCRC(byte *data, byte length, byte *result);
00286
00288
                // Functions for manipulating the MFRC522
00290
                void PCD_Init();
00291
                void PCD_Init(byte resetPowerDownPin);
00292
                void PCD_Init(byte chipSelectPin, byte resetPowerDownPin);
00293
                void PCD_Reset();
00294
                void PCD_AntennaOn();
00295
                void PCD_AntennaOff();
00296
                byte PCD_GetAntennaGain();
00297
                void PCD_SetAntennaGain(byte mask);
00298
                bool PCD PerformSelfTest();
00299
00301
                // Power control functions
00303
                void PCD_SoftPowerDown();
00304
                void PCD_SoftPowerUp();
00305
00307
                // Functions for communicating with PICCs
         StatusCode PCD_TransceiveData(byte *sendData, byte sendLen, byte *backData, byte *backLen, byte *validBits = nullptr, byte rxAlign = 0, bool checkCRC = false);
00309
00310
                StatusCode PCD_CommunicateWithPICC(byte command, byte waitIRq, byte *sendData, byte sendLen, byte
         *backData = nullptr, byte *backLen = nullptr, byte *validBits = nullptr, byte rxAlign = 0, bool checkCRC = false);
                skckc = laise);
StatusCode PICC_RequestA(byte *bufferATQA, byte *bufferSize);
StatusCode PICC_WakeupA(byte *bufferATQA, byte *bufferSize);
StatusCode PICC_REQA_or_WUPA(byte command, byte *bufferATQA, byte *bufferSize);
00311
00312
00314
                virtual StatusCode PICC_Select(Uid *uid, byte validBits = 0);
00315
                StatusCode PICC_HaltA();
00316
00318
                // Functions for communicating with MIFARE PICCs
00320
                StatusCode PCD_Authenticate(byte command, byte blockAddr, MIFARE_Key *key, Uid *uid);
00321
                void PCD_StopCrypto1();
                StatusCode MIFARE_Read(byte blockAddr, byte *buffer, byte *bufferSize);
00322
00323
                StatusCode MIFARE_Write(byte blockAddr, byte *buffer, byte bufferSize);
00324
                StatusCode MIFARE_Ultralight_Write(byte page, byte *buffer, byte bufferSize);
                StatusCode MIFARE_Decrement(byte blockAddr, int32_t delta);
00325
00326
                StatusCode MIFARE_Increment (byte blockAddr, int32_t delta);
00327
                StatusCode MIFARE_Restore(byte blockAddr);
00328
                StatusCode MIFARE_Transfer(byte blockAddr);
                StatusCode MIFARE_GetValue(byte blockAddr, int32_t *value);
StatusCode MIFARE_SetValue(byte blockAddr, int32_t value);
00329
00330
00331
                StatusCode PCD_NTAG216_AUTH(byte *passWord, byte pACK[]);
00332
00334
                // Support functions
                StatusCode PCD_MIFARE_Transceive(byte *sendData, byte sendLen, bool acceptTimeout = false);
00336
                // old function used too much memory, now name moved to flash; if you need char, copy from flash
00337
00338
                //const char *GetStatusCodeName(byte code);
                \verb|static const with the static constant with the static c
00339
                static PICC_Type PICC_GetType(byte sak);
00340
00341
                // old function used too much memory, now name moved to flash; if you need char, copy from flash
00342
                //const char *PICC_GetTypeName(byte type);
00343
                static const __FlashStringHelper *PICC_GetTypeName(PICC_Type type);
00344
00345
                // Support functions for debuging
```

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```
void PCD_DumpVersionToSerial();
00347
         void PICC_DumpToSerial(Uid *uid);
00348
         void PICC_DumpDetailsToSerial(Uid *uid);
         \verb|void PICC_DumpMifareClassicToSerial(Uid *uid, PICC_Type piccType, \verb|MIFARE_Key *key|);|\\
00349
         \verb|void PICC_DumpMifareClassicSectorToSerial(Uid *uid, MIFARE\_Key *key, byte sector)|; \\
00350
00351
         void PICC_DumpMifareUltralightToSerial();
00352
00353
         // Advanced functions for MIFARE
00354
         00355
         bool MIFARE_OpenUidBackdoor(bool logErrors);
00356
         bool MIFARE_SetUid(byte *newUid, byte uidSize, bool logErrors);
00357
         bool MIFARE UnbrickUidSector(bool logErrors);
00358
00360
         // Convenience functions - does not add extra functionality
00362
         virtual bool PICC_IsNewCardPresent();
00363
         virtual bool PICC_ReadCardSerial();
00364
00365 protected:
00366
        byte _chipSelectPin;
                                   // Arduino pin connected to MFRC522's SPI slave select input (Pin 24,
     NSS, active low)
         byte _resetPowerDownPin;
                                  // Arduino pin connected to MFRC522's reset and power down input (Pin
     6, NRSTPD, active low)
00368
        StatusCode MIFARE_TwoStepHelper(byte command, byte blockAddr, int32_t data);
00369 };
00370
00371 #endif
```

5.8. MFRC522Extended.h

```
00001
00006 #ifndef MFRC522Extended_h
00007 #define MFRC522Extended_h
00009 #include <Arduino.h>
00010 #include "MFRC522.h"
00011
00012 class MFRC522Extended : public MFRC522 {
00013
00014 public:
00015
         // ISO/IEC 14443-4 bit rates
00016
          enum TagBitRates : byte {
              BITRATE_106KBITS = 0 \times 00,
BITRATE_212KBITS = 0 \times 01,
00017
00018
              BITRATE\_424KBITS = 0x02,
00019
00020
              BITRATE_848KBITS = 0x03
00021
00022
00023
          // Structure to store ISO/IEC 14443-4 ATS
00024
          typedef struct {
00025
             bvte size:
00026
                                         // Frame size for proximity card
              byte fsc:
00027
00028
              struct {
00029
                 bool transmitted;
                            sameD; // Only the same D for both directions supported
00030
                  bool
                  TagBitRates ds:
00031
                                       // Send D
                                       // Receive D
00032
                  TagBitRates dr;
00033
              } ta1;
00034
00035
00036
                  bool transmitted:
00037
                                       // Frame waiting time integer
                  bvte fwi;
00038
                  byte sfqi;
                                       // Start-up frame guard time integer
00039
              } tb1;
00040
00041
              struct {
00042
                  bool transmitted;
00043
                  bool supportsCID;
00044
                  bool supportsNAD;
00045
              } tc1;
00046
00047
00048
              byte data[FIFO_SIZE - 2]; // ATS cannot be bigger than FSD - 2 bytes (CRC), according to ISO
     14443-4 5.2.2
00049
         } Ats;
00050
00051
          // A struct used for passing the PICC information
00052
          typedef struct {
00053
              uint16_t
                          atqa;
00054
              Hid
                            mid:
00055
              Ats
                           ats:
00056
              // For Block PCB
```

```
bool blockNumber;
           } TagInfo;
00059
00060
00061
           // A struct used for passing PCB Block \,
00062
           typedef struct {
00063
               struct {
00064
                   byte pcb;
00065
                    byte cid;
00066
                   byte nad;
00067
                } proloque;
00068
                struct {
00069
                  byte size;
00070
                    byte *data;
00071
               } inf;
00072
           } PcbBlock;
00073
00074
           // Member variables
00075
           TagInfo tag;
00076
00078
            // Contructors
           MFRC522Extended() : MFRC522() {};
00080
           MFRC522Extended(uint8_t rst) : MFRC522(rst) {};
00081
           MFRC522Extended(uint8_t ss, uint8_t rst) : MFRC522(ss, rst) {};
00082
00083
00085
            // Functions for communicating with PICCs
           StatusCode PICC_Select(Uid *uid, byte validBits = 0) override; // overrride
00087
00088
           StatusCode PICC_RequestATS(Ats *ats);
00089
           StatusCode PICC_PPS();
                                                                                               // PPS command without
      bitrate parameter
           StatusCode PICC_PPS(TagBitRates sendBitRate, TagBitRates receiveBitRate); // Different D values
00090
00091
00093
            // Functions for communicating with ISO/IEC 14433-4 cards
00095
           StatusCode TCL_Transceive(PcbBlock *send, PcbBlock *back);
00096
           \texttt{StatusCode TCL\_Transceive}(\texttt{TagInfo} \star \texttt{tag, byte} \star \texttt{sendData, byte sendLen, byte} \star \texttt{backData} = \texttt{NULL, byte}
      *backLen = NULL);
00097
           StatusCode TCL_TransceiveRBlock(TagInfo *tag, bool ack, byte *backData = NULL, byte *backLen =
      NULL);
00098
           StatusCode TCL_Deselect(TagInfo *tag);
00099
           // Support functions
static PICC_Type PICC_GetType(TagInfo *tag);
using MFRC522::PICC_GetType;// // make old PICC_GetType(byte sak) available, otherwise would be
00101
00103
00104
      hidden by PICC_GetType(TagInfo *tag)
00105
00106
            // Support functions for debuging
00107
           void PICC_DumpToSerial(TagInfo *tag);
      using MFRC522::PICC_DumpToSerial; // make old PICC_DumpToSerial(Uid *uid) available, otherwise would be hidden by PICC_DumpToSerial(TagInfo *tag)
00108
00109
           void PICC_DumpDetailsToSerial(TagInfo *tag);
           using MFRC522::PICC_DumpDetailsToSerial; // make old PICC_DumpDetailsToSerial(Uid *uid) available,
00110
      otherwise would be hidden by PICC_DumpDetailsToSerial(TagInfo *tag)
00111
           void PICC_DumpISO14443_4(TagInfo *tag);
00112
00114
           // Convenience functions - does not add extra functionality
           bool PICC_IsNewCardPresent() override; // overrride bool PICC_ReadCardSerial() override; // overrride
00116
00117
00118 };
00119
00120 #endif
```

5.9. require cpp11.h

```
00001
00005 #ifndef REQUIRE_CPP11_H
00006 #define REQUIRE_CPP11_H
00007
00008 #if __cplusplus < 201103L
00009 #error "This library needs at least a C++11 compliant compiler, maybe compiler argument for C++11 support is missing or if you use Arduino IDE upgrade to version >=1.6.6"
00010 #endif
00011
00012 #endif // REQUIRE_CPP11_H
```

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