

Soluciones 2º parcial 5R1

03/11/09.

1) El sistema con el valor de K ajustado es:

(1)

$$G(s)H(s) = 30 \frac{s+1}{s^3+3s^2-4s-12}$$

El polinomio denominador factorizado es:

$$p(z) = 8 + 3 \cdot 4 - 4 \cdot 2 - 12 = 0 \therefore s_1 = 2$$

$$\begin{array}{r} s^3 + 3s^2 - 4s - 12 \quad | \quad s-2 \\ -s^3 + 2s^2 \\ \hline 5s^2 - 4s - 12 \end{array} \quad = s + 5s + 6$$

$$\begin{array}{r} / \quad 5s^2 - 4s \\ -5s^2 + 10s \\ \hline 6s - 12 \end{array}$$

$$\begin{array}{r} / \quad 6s - 12 \\ -6s + 12 \\ \hline 0 \end{array}$$

$$s_{2,3} = \frac{-5 \pm \sqrt{25-24}}{2} = \frac{-5 \pm 1}{2}$$

$$s_2 = -2; \quad s_3 = -3$$

$$G(s)H(s) = 30 \frac{s+1}{(s-2)(s+2)(s+3)}$$

En formato Bode:

$$G(s)H(s) = 30 \frac{s+1}{(-2)(-0,5s+1)2(0,5s+1)3(0,33s+1)}$$

$$G(s)H(s) = \frac{2,5}{(-1)} \frac{s+1}{(-0,5s+1)(0,5s+1)(0,33s+1)}$$

$$G(j\omega)H(j\omega) = \frac{2,5}{(-1)} \frac{1+j\omega}{(1-j0,5\omega)(1+j0,5\omega)(1+j0,33\omega)}$$

$$|G(j\omega)H(j\omega)|_{dB} = 20 \log \frac{|2,5|}{|-1|} \frac{|1+j\omega|}{|1-j0,5\omega||1+j0,5\omega||1+j0,33\omega|}$$

$$|2,5|_{dB} = 20 \log 2,5 = 7,96$$

$$|1+jw|_{dB} = 20 \log \sqrt{1+w^2} = 10 \log(1+w^2)$$

$$\left| \frac{1}{(-1)} \right|_{dB} = 20 \log 1 - 20 \log 1 = 0$$

$$\left| \frac{1}{1-j0,5w} \right|_{dB} = 20 \log 1 - 20 \log \sqrt{1+0,25w^2} = -10 \log(1+0,25w^2)$$

$$\left| \frac{1}{1+j0,5w} \right|_{dB} = 20 \log 1 - 20 \log \sqrt{1+0,25w^2} = -10 \log(1+0,25w^2)$$

$$\left| \frac{1}{1+j0,33w} \right|_{dB} = 20 \log 1 - 20 \log \sqrt{1+0,11w^2} = -10 \log(1+0,11w^2)$$

$$|G(jw)H(jw)| = |2,5| + |1+jw| - |1| - |1-j0,5w| - |1+j0,5w| - |1+j0,33w|$$

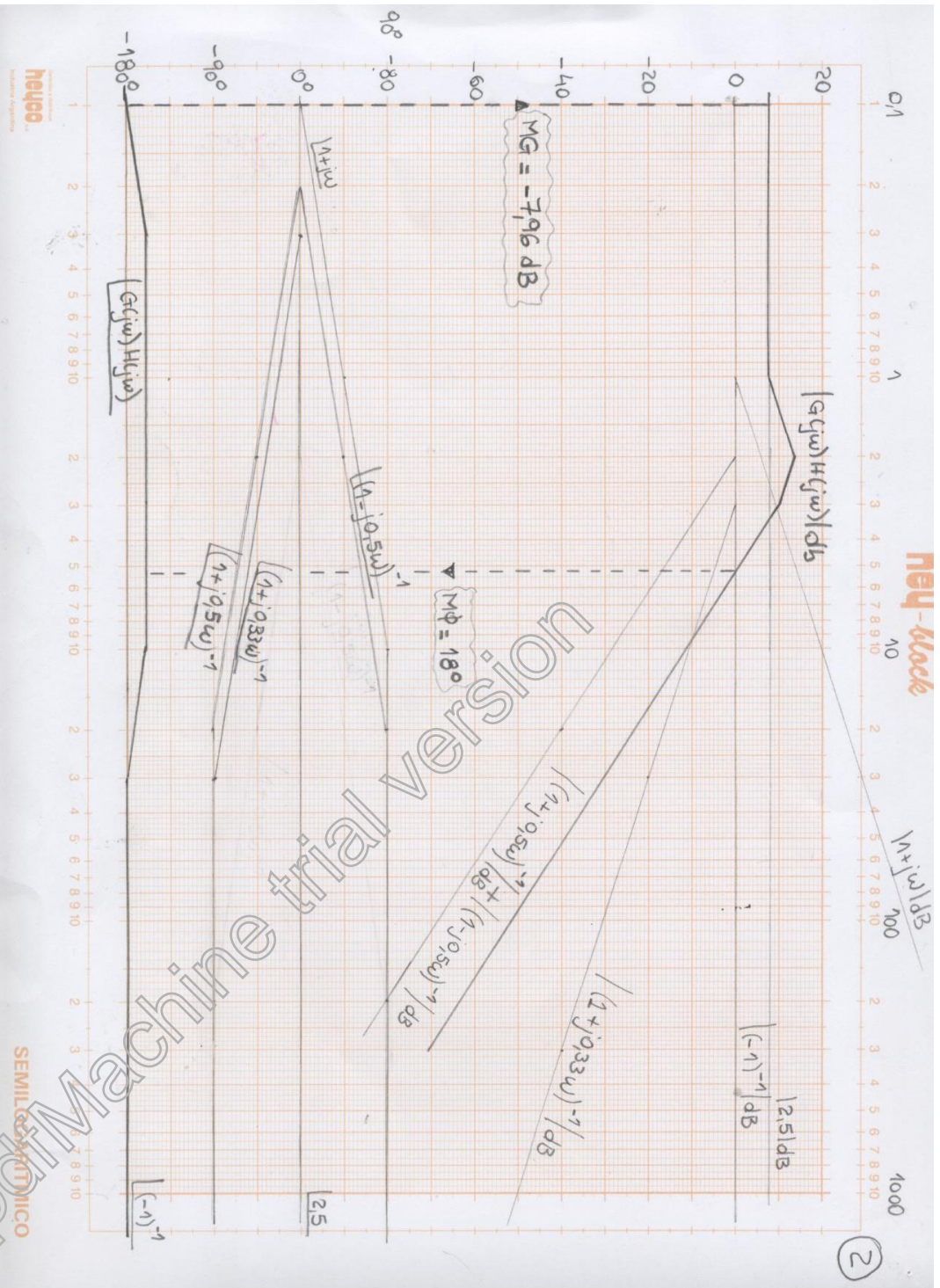
$$\angle 2,5 = \arctg \frac{0}{2,5} = 0^\circ \quad \angle 1+jw = \arctg w$$

$$\left| \frac{1}{(-1)} \right| = \angle 1 - \angle (-1) = 0^\circ - \arctg \frac{0}{-1} = 0^\circ - 180^\circ = -180^\circ$$

$$\left| \frac{1}{1-j0,5w} \right| = \angle 1 - \angle 1-j0,5w = -\arctg(-0,5w) = \arctg 0,5w$$

$$\left| \frac{1}{1+j0,5w} \right| = \angle 1 - \angle 1+j0,5w = -\arctg 0,5w$$

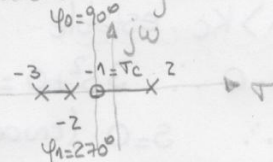
$$\left| \frac{1}{1+j0,33w} \right| = \angle 1 - \angle 1+j0,33w = -\arctg 0,33w$$



2) Veamos primero el lugar de raíces sin la compensación (3)
en atraso

$$G(s)H(s) = K \frac{s+1}{s^3+3s^2-4s-12} = K \frac{s+1}{(s-2)(s+2)(s+3)}$$

- Lugar de raíz sobre el eje real:



- Asintotas $p-z=3-1=2 \therefore K=0,1$.

$$\varphi_K = \frac{180^\circ (2K+1)}{p-z}; \quad \varphi_0 = \frac{180^\circ}{2} = 90^\circ; \quad \varphi_1 = \frac{180^\circ}{2} \cdot 3 = 270^\circ$$

$$\sigma_c = \frac{\sum \text{Re}[p] - \sum \text{Re}[z]}{p-z} = \frac{-3-2-1-(-1)}{3-1} = \frac{-2}{2} = -1$$

- Punto de bifurcación:

$$K \frac{s+1}{s^3+3s^2-4s-12} + 1 = 0 \quad K = - \frac{s^3+3s^2-4s-12}{s+1}$$

$$\frac{\partial K}{\partial s} = - \frac{(3s^2+6s-4)(s+1) - (s^3+3s^2-4s-12)}{(s+1)^2} = 0$$

$$\frac{\partial K}{\partial s} = - \frac{3s^3+9s^2+2s-4-s^3-3s^2+4s+12}{(s+1)^2} = 0$$

$$2s^3+6s^2+6s+8=0 \therefore s^3+3s^2+3s+4=0$$

$$s_1 = -2,44 = p_b; \quad s_{2,3} = -0,28 \pm j1,25 \text{ (complejas conjugadas no son?B)}$$

$$K(p_b) = 0,76$$

Criterio de Routh:

$$K \frac{s+1}{s^3+3s^2-4s-12} + 1 = 0$$

$$s^3+3s^2-4s-12+K(s+1)=0$$

$$s^3 + 3s^2 + (K-4)s + (K-12) = 0$$

$$s^3 \quad 1 \quad K-4$$

$$s^2 \quad 3 \quad K-12$$

$$s \quad 2K$$

$$s^0 \quad K-12$$

$$3(K-4) - (K-12) = 3K - 12 - K + 12 = 2K$$

$$K - 12 = 0 \therefore K_c = 12$$

$K < K_c$ inestable con una raíz con $\text{Re}[s] > 0$

$K > K_c$ estable

Punto de cruce: $3s^2 + K_c - 12 = 0 \therefore 3s^2 + 0 = 0$

$$\therefore s = 0 \text{ (cruce eje imaginario)}$$

Puntos auxiliares para trazado del LR:

$$K=1 \quad s^3 + 3s^2 - 3s - 11 = 0 \quad s_1 = 1,86 \quad s_{2-3} = -2,43 \pm j0,3$$

$$K=5 \quad s^3 + 3s^2 + s - 7 = 0 \quad s_1 = 1,18 \quad s_{2-3} = -2,09 \pm j1,25$$

$$K=10 \quad s^3 + 3s^2 + 6s - 2 = 0 \quad s_1 = 0,29 \quad s_{2-3} = -1,65 \pm j2,06$$

$$K=20 \quad s^3 + 3s^2 + 16s + 8 = 0 \quad s_1 = -0,55 \quad s_{2-3} = -1,23 \pm j3,63 \text{ punto de diseño}$$

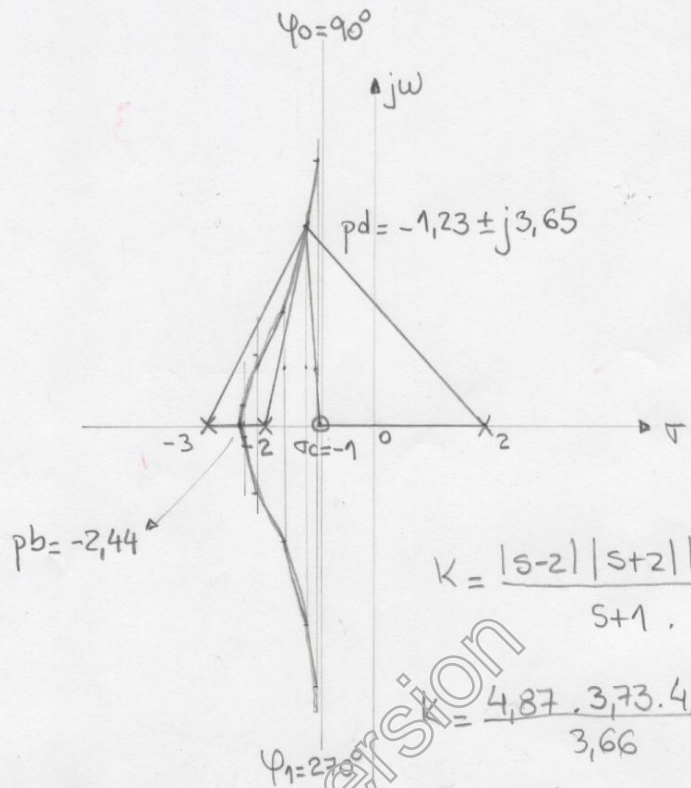
$$K=30 \quad s^3 + 3s^2 + 26s + 18 = 0 \quad s_1 = -0,74 \quad s_{2-3} = -1,13 \pm j4,8$$

Se asume el punto de diseño como L.R:

$$t_p = 0,86 \text{ seg} = \frac{\pi}{\omega_d} \quad \omega_d = \frac{\pi}{0,86} = 3,65 \frac{\text{rad}}{\text{seg}}$$

$$t_{s5\%} = 2,44 \text{ seg} = \frac{3}{\zeta} \quad \therefore \zeta = \frac{3}{2,44} = 1,23 \text{ seg}^{-1}$$

punto de diseño: $-1,23 \pm j3,65$



$$K = \frac{|s-2| |s+2| |s+3|}{s+1}$$

$$K = \frac{4,87 \cdot 3,73 \cdot 4,06}{3,66} = 20,15$$

$$G(s)H(s) = 20,15 \frac{s+1}{s^3+3s^2-4s-12}$$

$$K_p = \lim_{s \rightarrow 0} 20,15 \frac{1}{(-12)} = -1,68$$

compensador en atraso: $K_p = (-1,68) \frac{z_c}{p_c} = -3$

$$z_c = 1,79$$

$$0,62 > z_c > 0,12$$

$$z_c = 0,18 \therefore p_c = \frac{0,18}{1,79} = 0,1$$

$$G(s)H(s) = 20,15 \frac{s+1}{s^3+3s^2-4s-12} \cdot \frac{s+0,18}{s+0,1}$$