

5). Idem \exists con $V_c(t)$ determinar $t-T_y$ con probar.

$$V_c(t) = R i_L(t) + L \frac{di_L(t)}{dt}$$

$$\text{con } i_L(t) = i(t) - i_C(t) = i(t) - C \frac{dV_c(t)}{dt}$$

$$V_c(t) = R i(t) - RC \frac{dV_c(t)}{dt} + L \left\{ \frac{di_L(t)}{dt} \right\}$$

$$\frac{di_L(t)}{dt} = \frac{di(t)}{dt} - C \frac{d^2 V_c(t)}{dt^2}$$

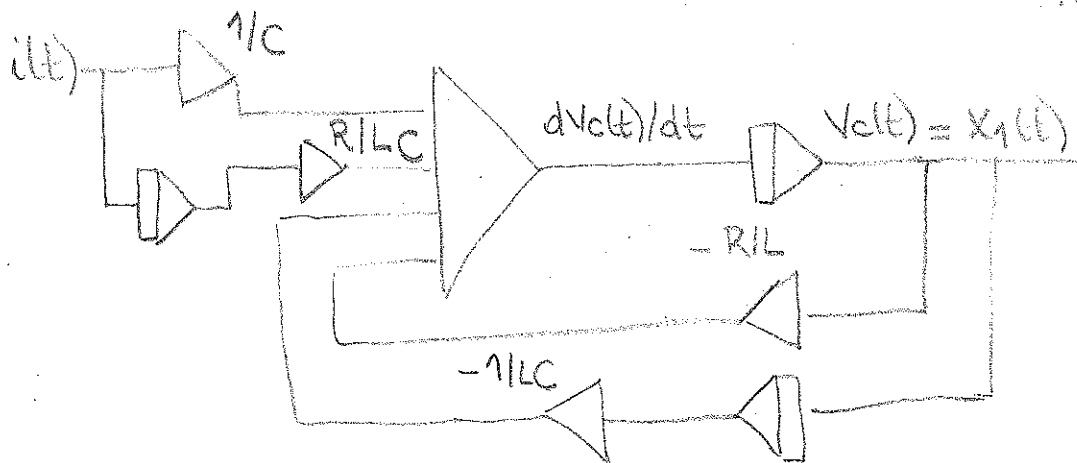
$$V_c(t) = R i(t) - RC \frac{dV_c(t)}{dt} + L \frac{di(t)}{dt} - LC \frac{d^2 V_c(t)}{dt^2}$$

$$LC \frac{d^2 V_c(t)}{dt^2} = R i(t) + L \frac{di(t)}{dt} - RC \frac{dV_c(t)}{dt} - V_c(t)$$

$$\frac{d^2 V_c(t)}{dt^2} = \frac{R}{LC} i(t) + \frac{1}{C} \frac{di(t)}{dt} - \frac{R}{L} \frac{dV_c(t)}{dt} - \frac{1}{LC} V_c(t)$$

Así el diagrama de simulación analógica es:

$$\frac{dV_c(t)}{dt} = \frac{R}{LC} \int i(t) dt + \frac{1}{C} i(t) - \frac{R}{L} V_c(t) - \frac{1}{LC} \int V_c(t) dt$$



Con $x_1(t) = V_c(t) \therefore$

$$V_c(t) = x_1(t)$$

ecuación de salida

$$\dot{x}_1(t) = \int \left[-\frac{R}{L} x_1(t) - \frac{1}{LC} \int x_1(t) dt + \frac{1}{C} i(t) + \frac{R}{LC} \int i(t) dt \right] dt. \quad (5)$$

$$\therefore \dot{x}_1(t) = \underbrace{-\frac{R}{L} x_1(t) - \frac{1}{LC} \int x_1(t) dt}_{(A)} + \underbrace{\frac{1}{C} i(t) + \frac{R}{LC} \int i(t) dt}_{(B)}$$

Los términos (A) y (B) no pueden formar parte de la ecuación de estado, en este caso no podemos elegir la variable de estado como salida del integrador solamente. Al no poder incluir en el segundo miembro derivadas/integrales, definiremos a $x_2(t)$ como:

$$x_2(t) = -\frac{1}{LC} \int x_1(t) dt + \frac{R}{LC} \int i(t) dt$$

con lo que

$$\begin{cases} \dot{x}_1(t) = -\frac{R}{L} x_1(t) + x_2(t) + \frac{1}{C} i(t) \\ \dot{x}_2(t) = -\frac{1}{LC} x_1(t) + \frac{R}{LC} i(t) \end{cases} \quad \begin{array}{l} \text{ecuaciones} \\ \text{de} \\ \text{estado.} \end{array}$$

$$\begin{bmatrix} \dot{x}(t) \end{bmatrix} = \begin{bmatrix} A \end{bmatrix} \begin{bmatrix} x(t) \end{bmatrix} + \begin{bmatrix} B \end{bmatrix} \begin{bmatrix} u(t) \end{bmatrix}$$

$$\begin{bmatrix} y(t) \end{bmatrix} = \begin{bmatrix} C \end{bmatrix} \begin{bmatrix} x(t) \end{bmatrix} + \begin{bmatrix} D \end{bmatrix} \begin{bmatrix} u(t) \end{bmatrix}$$

$$\begin{bmatrix} \dot{x}_1(t) \\ \dot{x}_2(t) \end{bmatrix} = \begin{bmatrix} -\frac{R}{L} & 1 \\ -\frac{1}{LC} & 0 \end{bmatrix} \begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix} + \begin{bmatrix} \frac{1}{C} \\ \frac{R}{LC} \end{bmatrix} \begin{bmatrix} u(t) \end{bmatrix}$$

$$[V_c(t)] = \begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix} + \begin{bmatrix} 0 \end{bmatrix} [u(t)]$$

Función de transferencia.

$$V_c(t) = R i(t) - RC \frac{dV_c(t)}{dt} + L \frac{di(t)}{dt} - LC \frac{d^2 V_c(t)}{dt^2}$$

$$LC \frac{d^2 V_c(t)}{dt^2} + RC \frac{dV_c(t)}{dt} + V_c(t) = R i(t) + L \frac{di(t)}{dt}$$

Aplicando \mathcal{L} :

$$(LCs^2 + RCs + 1) V_c(s) = (R + sL) I(s)$$

$$\frac{V_c(s)}{I(s)} = \frac{L}{LC} \frac{s + R/L}{s^2 + \frac{R}{L}s + \frac{1}{LC}}$$

$$\frac{V_c(s)}{I(s)} = \frac{1}{C} \frac{s + R/L}{s^2 + \frac{R}{L}s + \frac{1}{LC}}$$

$$\frac{V_c(s)}{I(s)} = [C] (s[I] - [A])^{-1} [B] + D$$

$$s[I] - [A] = \begin{bmatrix} s & 0 \\ 0 & s \end{bmatrix} - \begin{bmatrix} -\frac{R}{L} & 1 \\ -\frac{1}{LC} & 0 \end{bmatrix} = \begin{bmatrix} s + \frac{R}{L} & -1 \\ \frac{1}{LC} & s \end{bmatrix}$$

$$|S[I] - [A]| = s^2 + \frac{R}{L}s + \frac{1}{LC}$$

(6)

Adjunto:

$$\text{Adj}(S[I] - [A]) = \begin{bmatrix} s & -\frac{1}{LC} \\ 1 & s + \frac{R}{L} \end{bmatrix}^T = \begin{bmatrix} s & 1 \\ -\frac{1}{LC} & s + \frac{R}{L} \end{bmatrix}$$

$$(S[I] - [A])^{-1} = \frac{\text{Adj}(S[I] - [A])}{|S[I] - [A]|}$$

$$(S[I] - [A])^{-1} = \begin{bmatrix} \frac{s}{s^2 + \frac{R}{L}s + \frac{1}{LC}} & \frac{1}{s^2 + \frac{R}{L}s + \frac{1}{LC}} \\ \frac{-1/LC}{s^2 + \frac{R}{L}s + \frac{1}{LC}} & \frac{s + R/L}{s^2 + \frac{R}{L}s + \frac{1}{LC}} \end{bmatrix}$$

$$[C] (S[I] - [A])^{-1} =$$

$$\begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} \frac{s}{s^2 + \frac{R}{L}s + \frac{1}{LC}} & \frac{1}{s^2 + \frac{R}{L}s + \frac{1}{LC}} \\ \frac{-1/LC}{s^2 + \frac{R}{L}s + \frac{1}{LC}} & \frac{s + R/L}{s^2 + \frac{R}{L}s + \frac{1}{LC}} \end{bmatrix}$$

$$[C] (s[I] - [A])^{-1} [B] =$$

$$\frac{1}{C}$$

$$\frac{R}{LC}$$

$$\frac{\frac{s}{s^2 + \frac{R}{L}s + \frac{1}{LC}} \quad \frac{1}{s^2 + \frac{R}{L}s + \frac{1}{LC}}}{\frac{\frac{1}{C}s + \frac{R}{LC}}{s^2 + \frac{R}{L}s + \frac{1}{LC}}}$$

Como $D=0$

$$\frac{V_C(s)}{I(s)} = \frac{\frac{1}{C}s + \frac{R}{LC}}{s^2 + \frac{R}{L}s + \frac{1}{LC}} = \frac{1}{C} \frac{s + \frac{R}{L}}{s^2 + \frac{R}{L}s + \frac{1}{LC}}$$