# Dynamic Indexes Algorithmic Design

Alberto Casagrande Email: acasagrande@units.it

a.y. 2020/2021



# A Simple Problem for Registry Office

Let us consider the registry office

For each newborn, they record a set of data e.g., name, birthday, parents, etc.

So, the registry data-set (hopefully) changes quite often

What if they frequently perform a birthday-based search on the data-set? E.g., Find all the baby born a given (variable) day?

# Some Possible Strategies



### Some Possible Strategies

#### They may:

scan all the data-set at each query



### They may:

scan all the data-set at each query

Takes time  $\Theta(n)$ 

• sort the data-set by birthday at each insertion

Takes time  $\Theta(n)$  per insertion (Radix Sort) +  $\Theta(\log n)$  per query. What if they also want to perform searches by name?

### Some Possible Strategies

#### They may:

scan all the data-set at each query

Takes time  $\Theta(n)$ 

- sort the data-set by birthday at each insertion Takes time  $\Theta(n)$  per insertion (Radix Sort) +  $\Theta(\log n)$  per query. What if they also want to perform searches by name?
- sort the data-set by birthday at each query

Takes time  $\Theta(n + \log n) = \Theta(n)$  per query (Radix Sort and DS)

### Some Possible Strategies

#### They may:

scan all the data-set at each query

Takes time 
$$\Theta(n)$$

- sort the data-set by birthday at each insertion Takes time  $\Theta(n)$  per insertion (Radix Sort) +  $\Theta(\log n)$  per query. What if they also want to perform searches by name?
- sort the data-set by birthday at each query

Takes time 
$$\Theta(n + \log n) = \Theta(n)$$
 per query (Radix Sort and DS)

The data-set often changes, thus, array is not the most suitable data structure to achieve this goal

# A Dynamic Data Structure for Indexing

We need a data structure providing (efficient) support for:

- adding new data
- searching data
- removing data

### A Dynamic Data Structure for Indexing

We need a data structure providing (efficient) support for:

- adding new data
- searching data
- removing data

We are aiming to build an index i.e., an auxiliary data structure to "efficiently" perform above operations



We have already introduced trees as ADT.

As far as searching trees concern, the following notation holds

We have already introduced trees as ADT.

As far as searching trees concern, the following notation holds

x.left and x.right are the left and right children of x,
respectively

We have already introduced trees as ADT.

As far as searching trees concern, the following notation holds

x.left and x.right are the left and right children of x, respectively

x.parent is the parent of x

We have already introduced trees as ADT.

As far as searching trees concern, the following notation holds

x.left and x.right are the left and right children of x, respectively

x.parent is the parent of x

x.key is the value stored in x i.e., its key

We have already introduced trees as ADT.

As far as searching trees concern, the following notation holds

x.left and x.right are the left and right children of x, respectively

x.parent is the parent of x

x.key is the value stored in x i.e., its key

x.left=NIL, then x misses the left child

We have already introduced trees as ADT.

As far as searching trees concern, the following notation holds

x.left and x.right are the left and right children of x, respectively

x.parent is the parent of x

x.key is the value stored in x i.e., its key

x.left=NIL, then x misses the left child

T.root is the root of the tree T and T.root.parent=NIL

# Some Useful $\Theta(1)$ Functions

```
def IS_ROOT(x):
  return x.parent=NIL
enddef
def IS_RIGHT_CHILD(x):
  return \neg IS_ROOT(x) and x.parent.right=x
enddef
def SIBLING(x): # get x's sibling
  if IS_RIGHT_CHILD(x):
    return x.parent.left
  endif
  return x.parent.right
enddef
```

# Some Useful $\Theta(1)$ Functions (Cont'd)

```
def CHILDHOOD_SIDE(x): # get x's side w.r.t.
                      # its parent
  if IS_RIGHT_CHILD(x):
    return RIGHT
  endif
  return LEFT
enddef
def REVERSE_SIDE(side):
                       # reverse the side
  if side=LEFT:
    return RIGHT
  endif
  return LEFT
enddef
```

# Some Useful $\Theta(1)$ Functions (Cont'd 2)

```
def GET_CHILD(x, side): # get x's child on side
  if side=LEFT:
    return x.left
  endif

return x.right
enddef
```

# Some Useful $\Theta(1)$ Functions (Cont'd 3)

```
def SET_CHILD(x, side, y): # set x's child
  if side=LEFT:
    x.left \leftarrow y
  else:
    x.right \leftarrow y
  endif
  if y≠NIL:
     y.parent \leftarrow x
  endif
enddef
```

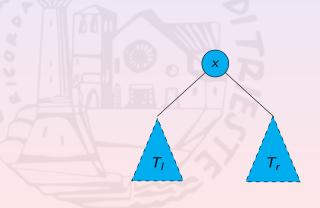
# Some Useful $\Theta(1)$ Functions (Cont'd 4)

```
def UNCLE(x): #get x's uncle
  return SIBLING(x.parent)
enddef
def GRANDPARENT(x): # get x's granpa
  return x. parent. parent
enddef
def NEW_NODE(v):
                  # build a new node
  x. key \leftarrow v
  x.parent \leftarrow NIL
  x.right \leftarrow NIL
  x.left \leftarrow NIL
enddef
```

### Binary Search Trees

A Binary Search Tree (BST) is a tree s.t.:

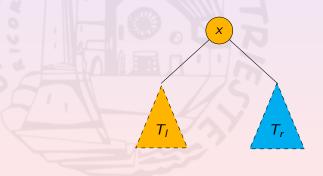
ullet all the keys belong to a totally ordered set w.r.t.  $\preceq$ 



### Binary Search Trees

A Binary Search Tree (BST) is a tree s.t.:

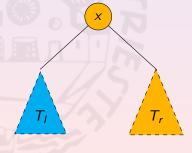
- ullet all the keys belong to a totally ordered set w.r.t.  $\preceq$
- if  $x_l$  is in the left sub-tree of x, then  $x_l$ . $key \leq x$ .key



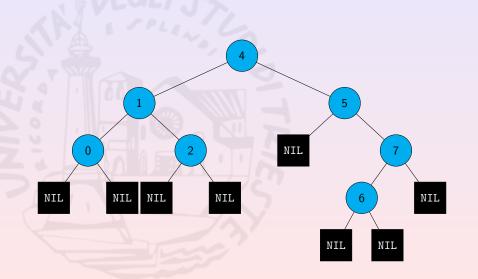
### Binary Search Trees

### A Binary Search Tree (BST) is a tree s.t.:

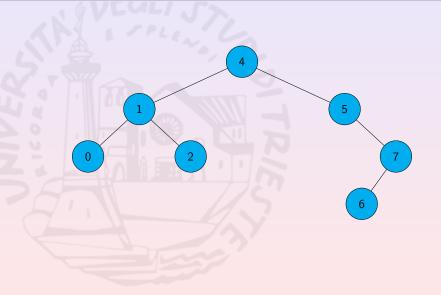
- ullet all the keys belong to a totally ordered set w.r.t.  $\preceq$
- if  $x_l$  is in the left sub-tree of x, then  $x_l$ . $key \leq x$ .key
- if  $x_r$  is in the right sub-tree of x, then  $x.key \leq x_r.key$



# Binary Search Trees: an Example



# Binary Search Trees: an Example

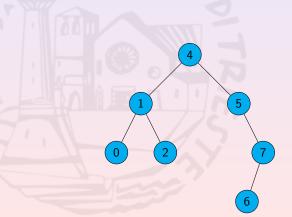


### In-Order Walk

```
def INORDER_WALK_AUX(x):
  if x≠NIL:
    INORDER_WALK_AUX(x.left)
    print x. key
    INORDER_WALK_AUX(x.right)
  endif
endif
def INORDER_WALK(T):
  INORDER_WALK_AUX(T. root)
endif
```

Due to the BST property:

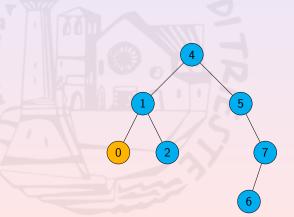
• the minimum key is contained by the first node on the leftmost branch that has not a left child



#### Due to the BST property:

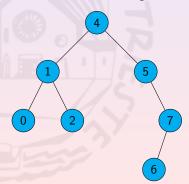
Motivations

• the minimum key is contained by the first node on the leftmost branch that has not a left child



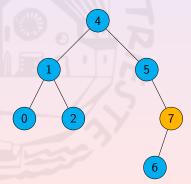
#### Due to the BST property:

- the minimum key is contained by the first node on the leftmost branch that has not a left child
- the maximum key is contained by the first node on the rightmost branch that has not a right child



#### Due to the BST property:

- the minimum key is contained by the first node on the leftmost branch that has not a left child
- the maximum key is contained by the first node on the rightmost branch that has not a right child



# Searching for the Maximum/Minimum: Pseudo-Code

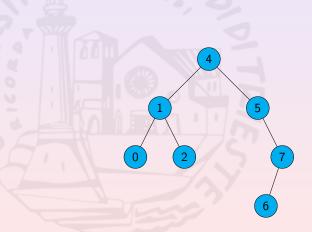
```
def MINIMUM_IN_SUBTREE(x):
  while x.left \neq NIL:
    x \leftarrow x. left
  endif
  return x
endif
def MAXIMUM_IN_SUBTREE(x):
  while x.right \neq NIL:
    x \leftarrow x. right
  endif
  return x
endif
```

### Searching for the Maximum/Minimum: Pseudo-Code

```
def MINIMUM_IN_SUBTREE(x):
  while x.left \neq NIL:
    x \leftarrow x. left
                                        O(h_T)
  endif
  return x
endif
def MAXIMUM_IN_SUBTREE(x):
  while x.right \neq NIL:
                                        O(h_T)
    x \leftarrow x. right
  endif
  return x
endif
```

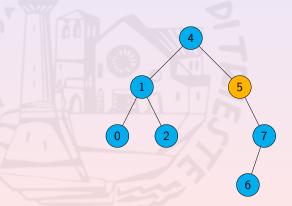
### Successor of a Node

Due to the BST property, the successor w.r.t.  $\leq$  of n is either



### Successor of a Node

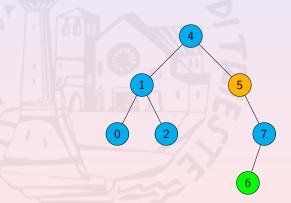
Due to the BST property, the successor w.r.t.  $\leq$  of n is either • the node containing the minimum in the right sub-tree of n



#### Successor of a Node

Due to the BST property, the successor w.r.t.  $\leq$  of n is either

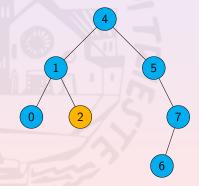
• the node containing the minimum in the right sub-tree of n or



#### Successor of a Node

Due to the BST property, the successor w.r.t.  $\leq$  of n is either

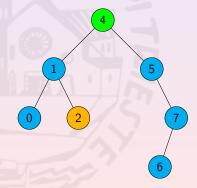
- the node containing the minimum in the right sub-tree of n or
- ullet the nearest "right-ancestor" of n, if n has not right child



#### Successor of a Node

Due to the BST property, the successor w.r.t.  $\leq$  of n is either

- the node containing the minimum in the right sub-tree of *n* or
- ullet the nearest "right-ancestor" of n, if n has not right child



### Successor of a Node: Pseudo-Code

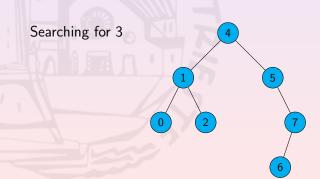
```
def SUCCESSOR(x):
  if x.right \neq NIL:
     return MINIMUM_IN_SUBTREE(x.right)
  endif
  y \leftarrow x.parent
  while y \neq NIL and IS_RIGHT_CHILD(x):
     x \leftarrow y
     y \leftarrow x.parent
  endwhile
  return y
enddef
```

### Successor of a Node: Pseudo-Code

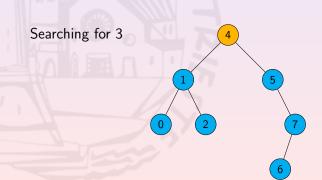
```
def SUCCESSOR(x):
  if x.right \neq NIL:
     return MINIMUM_IN_SUBTREE(x.right)
  endif
  y \leftarrow x.parent
                                                   O(h_T)
  while y \neq NIL and IS_RIGHT_CHILD(x):
     x \leftarrow y
     y \leftarrow x.parent
  endwhile
  return y
enddef
```

#### To so all form and a little louis and a little way.

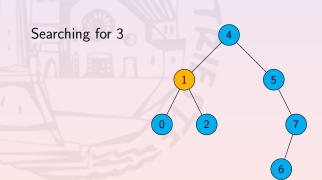
- if n is NIL or x. key = v, return n
- if  $x.key \leq v$ , search on the right sub-tree
- if  $x.key \not \leq v$ , search on the left sub-tree



- if n is NIL or x.key = v, return n
- if  $x.key \leq v$ , search on the right sub-tree
- if  $x.key \not \leq v$ , search on the left sub-tree

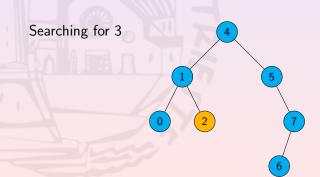


- if n is NIL or x. key = v, return n
- if  $x.key \leq v$ , search on the right sub-tree
- if  $x.key \not \leq v$ , search on the left sub-tree

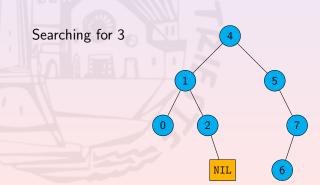


# Searching for a Value in a BST

- if *n* is NIL or x.key = v, return *n*
- if  $x.key \prec v$ , search on the right sub-tree
- if  $x.key \not \leq v$ , search on the left sub-tree



- if n is NIL or x.key = v, return n
- if  $x.key \leq v$ , search on the right sub-tree
- if  $x.key \not \leq v$ , search on the left sub-tree



## Searching for a Value in a BST: Pseudo-Code

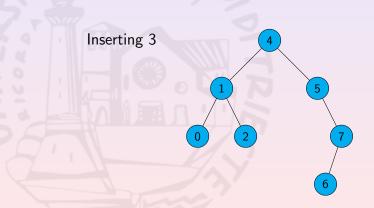
```
def SEARCH_SUBTREE(x, v):
  while x ≠ NIL:
     if x.key \leq v:
       if v \leq x. key:
          return x
       endif
       x \leftarrow x.right
     else:
       x \leftarrow x. left
     endif
  endwhile
enddef
```

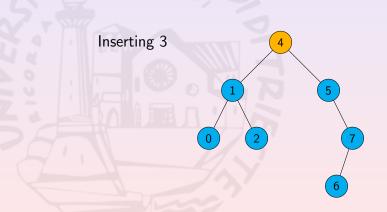
## Searching for a Value in a BST: Complexity

Each iteration performs  $\Theta(1)$  operations

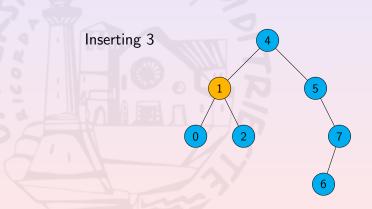
The # of iterations depends on the height  $h_T$  of T and on v

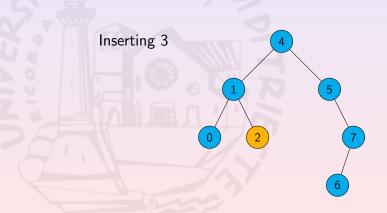
The algorithm takes time  $O(h_T)$ 

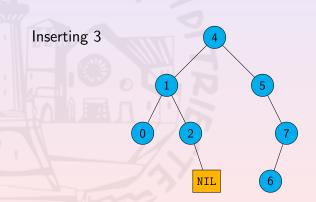


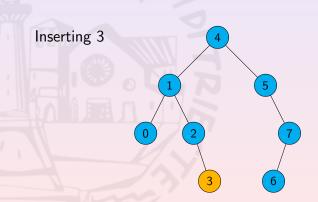


Motivations









## Inserting a Value in a BST: Pseudo-Code

```
def INSERT_BST(T, v): # v is the new value
  x \leftarrow T. root
  y \leftarrow NIL \# y \text{ is } x \text{'s parent}
  # search the right place for z
  while x \neq NIL:
     y \leftarrow x
     if v \prec x. key:
      if x.key \prec v:
          return HANDLE_MULTI_INSERT(x,v)
      endif
     x \leftarrow x.left
     else:
       x \leftarrow x. right
     endif
  endwhile
```

## Inserting a Value in a BST: Pseudo-Code

Motivations

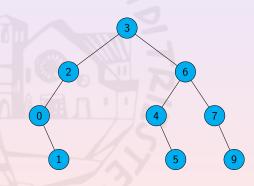
```
def INSERT_BST(T, v): # v is the new value
  x \leftarrow T. root
  y \leftarrow NIL \# y \text{ is } x's \text{ parent}
  # search the right place for z
  while x \neq NIL:
     y \leftarrow x
     if v \prec x. key:
      if x.key \prec v:
                                                            O(h_T)
          return HANDLE_MULTI_INSERT(x,v)
      endif
     x \leftarrow x.left
     else:
       x \leftarrow x. right
     endif
  endwhile
```

# Inserting a Value in a BST: Pseudo-Code (Cont'd)

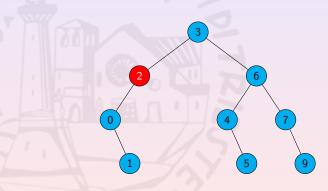
```
# attaching the new node
  x \leftarrow NEW\_NODE(v)
  if T.root≠NIL:
    if v \leq y. key:
       SET_CHILD(y, LEFT, x)
    else:
       SET_CHILD(y, RIGHT, x)
     endif
  else:
    T. root \leftarrow x
  endif
  return x
enddef
```

```
# attaching the new node
  x \leftarrow NEW\_NODE(v)
  if T.root≠NIL:
     if v \leq y. key:
       SET_CHILD(y, LEFT, x)
     else:
                                                 \Theta(1)
       SET_CHILD(y, RIGHT, x)
     endif
  else:
    T. root \leftarrow x
  endif
  return x
enddef
```

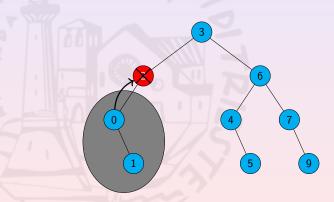
Search the node x containing the key. Either



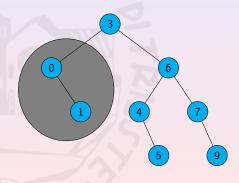
Search the node x containing the key. Either



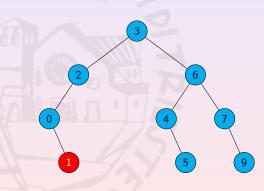
Search the node x containing the key. Either



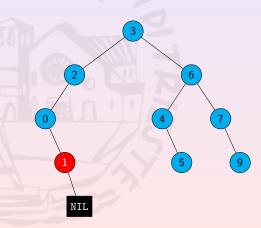
Search the node x containing the key. Either



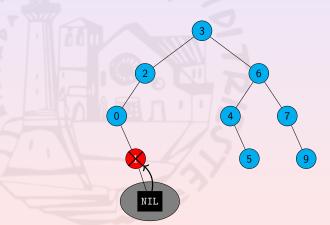
Search the node x containing the key. Either



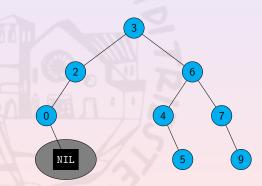
Search the node x containing the key. Either



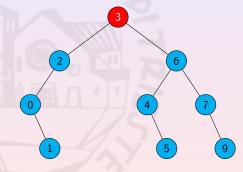
Search the node x containing the key. Either



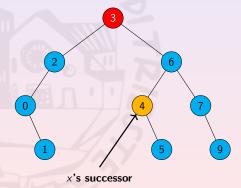
Search the node x containing the key. Either



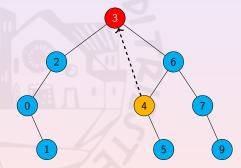
- x has one child at most or
- x has two children



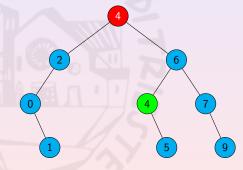
- x has one child at most or
- x has two children



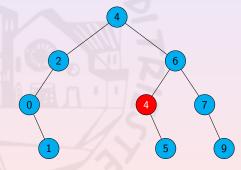
- x has one child at most or
- x has two children



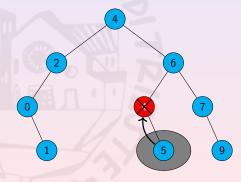
- x has one child at most or
- x has two children



- x has one child at most or
- x has two children



- x has one child at most or
- x has two children

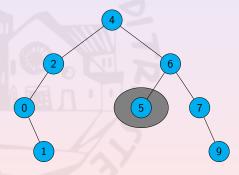


### Removing a Key from a BST

Motivations

Search the node x containing the key. Either

- x has one child at most or
- x has two children



## Removing a Key from a BST: Pseudo-Code

```
def TRANSPLANT(T,x,y): # replace x by y
  if IS_ROOT(x):
    T.root \leftarrow y
    if y \neq NIL:
     y.parent \leftarrow NIL
    endif
  else:
                     # x has a parent
    x_side \leftarrow CHILDHOOD_SIDE(x)
    # attach y in place of x
    SET_CHILD(x.parent, x_side, y)
  endif
enddef
```

# Removing a Key from a BST: Pseudo-Code (Cont'd)

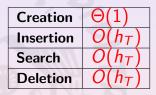
```
def REMOVE_BST(T,x): # remove x.key from T and
                    # return a removed node
  if x.left=NIL: # if x lacks of left child
   TRANSPLANT(T,x,x.right)
    return x
  endif
  if x.right=NIL: # if x lacks of right child
   TRANSPLANT(T,x,x.left)
    return x
  endif
  y \leftarrow MINIMUM_IN_SUBTREE(x.right)
  x. key \leftarrow y. key
  return REMOVE_BST(T,y) # y lacks of left child
enddef
```

TRANSPLANT costs  $\Theta(1)$ , while MINIMUM\_IN\_TREE  $O(h_T)$ 

So, if x has at most one child, removing it costs  $\Theta(1)$ 

In the general case, removing x takes time  $O(h_T)$ 

# Summarizing BSTs...



### Summarizing BSTs...

Creation	$\Theta(1)$
Insertion	$O(h_T)$
Search	$O(h_T)$
Deletion	$O(h_T)$

However,  $h_T$  may be equal to the number n of nodes e.g., keep inserting always the maximum

## Summarizing BSTs...

Creation	$\Theta(1)$
Insertion	O(n)
Search	O(n)
Deletion	O(n)

However,  $h_T$  may be equal to the number n of nodes e.g., keep inserting always the maximum

BSTs cost more than single-linked lists (insertion  $\Theta(1)$ )

The minimum height for a binary tree having n nodes is  $\lceil \log_2 n \rceil$ 

We aim to balance the trees i.e., bring their heights to  $O(\log n)$ 

How to do it?

The minimum height for a binary tree having n nodes is  $\lceil \log_2 n \rceil$ 

We aim to balance the trees i.e., bring their heights to  $O(\log n)$ 

How to do it?

GLOBALLY: balance the whole BST after each insertion/deletion

The minimum height for a binary tree having n nodes is  $\lceil \log_2 n \rceil$ 

We aim to balance the trees i.e., bring their heights to  $O(\log n)$ 

How to do it?

GLOBALLY: balance the whole BST after each insertion/deletion O(n)

The minimum height for a binary tree having n nodes is  $\lceil \log_2 n \rceil$ 

We aim to balance the trees i.e., bring their heights to  $O(\log n)$ 

How to do it?

GLOBALLY: balance the whole BST after each insertion/deletion

O(n)

LOCALLY: balance only the "unbalanced" part of the tree

The minimum height for a binary tree having n nodes is  $\lceil \log_2 n \rceil$ 

We aim to balance the trees i.e., bring their heights to  $O(\log n)$ 

How to do it?

GLOBALLY: balance the whole BST after each insertion/deletion O(n)

LOCALLY: balance only the "unbalanced" part of the tree How to know if it is unbalanced?

The minimum height for a binary tree having n nodes is  $\lceil \log_2 n \rceil$ 

We aim to balance the trees i.e., bring their heights to  $O(\log n)$ 

How to do it?

GLOBALLY: balance the whole BST after each insertion/deletion O(n)

LOCALLY: balance only the "unbalanced" part of the tree How to know if it is unbalanced? How to handle branches' lengths?



### **RBTs:** Definition

Are BSTs satisfying the following conditions:

- each node is either a RED or a BLACK node
- the tree's root is BLACK
- all the leaves are BLACK NIL nodes
- all the RED nodes must have BLACK children
- for each node x, all the branches from x contain the same # of black nodes

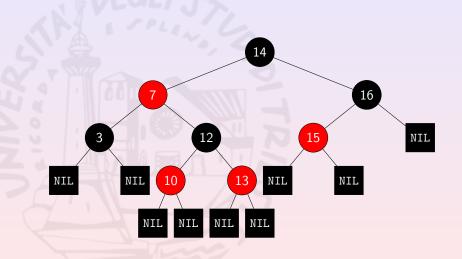
#### **RBTs:** Definition

Are BSTs satisfying the following conditions:

- each node is either a RED or a BLACK node
- the tree's root is BLACK
- all the leaves are BLACK NIL nodes
- all the RED nodes must have BLACK children
- for each node x, all the branches from x contain the same # of black nodes

BH(x) will be the # of BLACK nodes below x in any branch

### RBTs: An Example



## Another Useful $\Theta(1)$ Function

```
def COLOR(x):
    if x=NIL:
        return BLACK
    endif

    return x.color
enddef
```

### How "Tall" Are RB-Trees?

#### Theorem (Heights of a RB-Tree)

Any RBT with n internal nodes has height at most  $2 \log_2 (n+1)$ 

#### Proof Sketch:

- prove that the sub-tree rooted in x has at least  $2^{BH(x)}-1$  internal nodes
- BH(x) is at least half of x's height h then

$$n \ge 2^{h/2} - 1$$

### How "Tall" Are RB-Trees?

The ratio between x's height and BH(x) is topped by 2

#### Theorem (Heights of a RB-Tree)

Any RBT with n internal nodes has height at most  $2 \log_2 (n+1)$ 

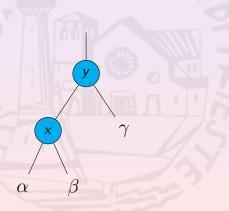
#### Proof Sketch:

- prove that the sub-tree rooted in x has at least  $2^{BH(x)} 1$  internal nodes
- BH(x) is at least half of x's height h then

$$n \ge 2^{h/2} - 1$$

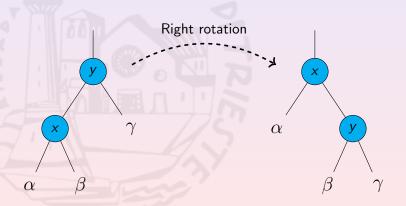
### Rotating a Sub-Tree

Rotations are operations on the tree structure. They preserve the BST property.



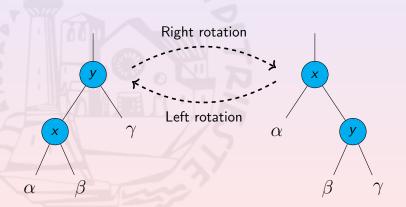
### Rotating a Sub-Tree

Rotations are operations on the tree structure. They preserve the BST property.



### Rotating a Sub-Tree

Rotations are operations on the tree structure. They preserve the BST property.



## Rotating a Sub-Tree: Pseudo-Code

```
def ROTATE(T, x, side ):
  r_side \leftarrow REVERSE_SIDE(side)
  y \leftarrow GET_CHILD(x, r_side)
  TRANSPLANT(T, x, y)
  beta ← GET_CHILD(y, side)
  TRANSPLANT(T, beta, x)
  SET_CHILD(x,r_side, beta) # move beta
enddef
```

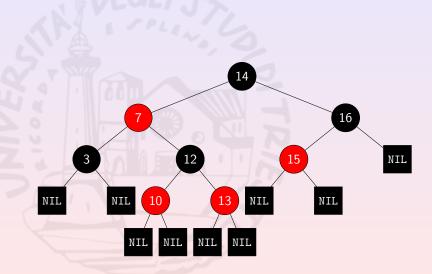
```
def ROTATE(T, x, side ):
  r_side ← REVERSE_SIDE(side)
  y \leftarrow GET_CHILD(x, r_side)
  TRANSPLANT(T, x, y)
                                               \Theta(1)
  beta ← GET_CHILD(y, side)
  TRANSPLANT(T, beta, x)
  SET_CHILD(x,r_side, beta) # move beta
enddef
```

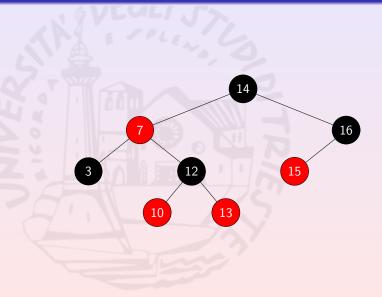
### Inserting a New Node

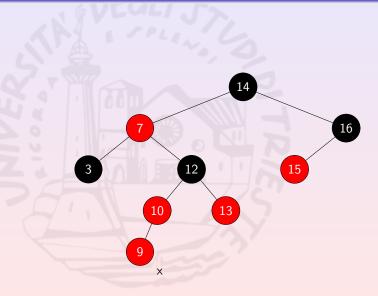
#### Requires:

- inserting as in BST
- RED-coloring the node
- fixing up RB-Tree properties

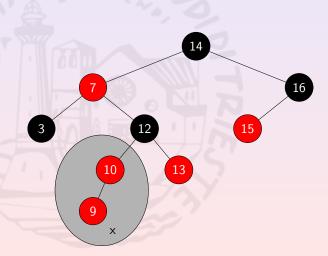
Motivations



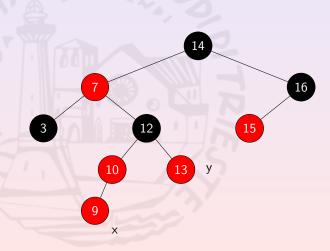




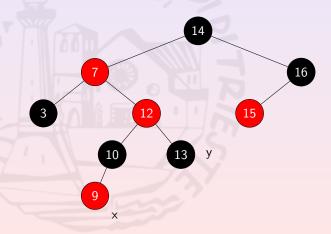
x's parent may be RED. How to fix it?



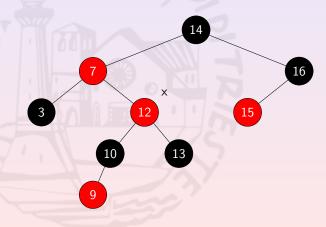
Case 1: x's uncle (y) is RED...



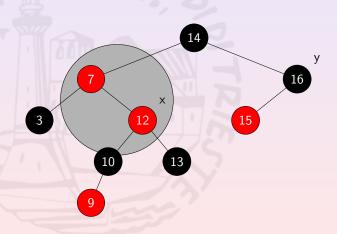
Case 1: x's uncle (y) is RED... RED-color x's granpa and BLACK-color x's parent and y.



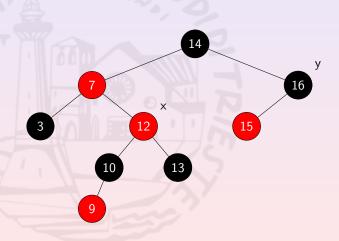
Case 1: x's uncle (y) is RED... RED-color x's granpa and BLACK-color x's parent and y. New x is former x's granpa



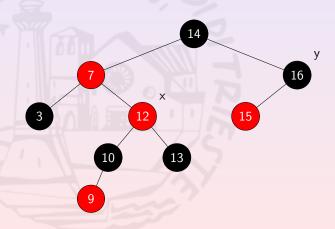
Still facing problems, but x's uncle is BLACK (not Case 1)



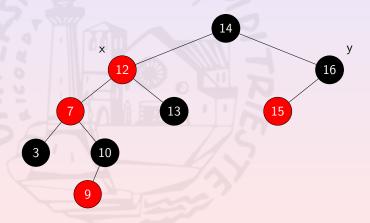
Case 2: y is BLACK and y and x are on the same side.



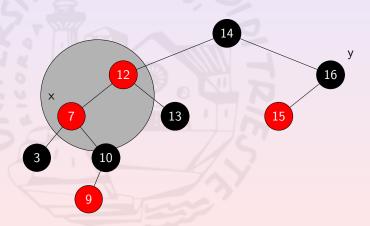
Case 2: y is BLACK and y and x are on the same side. Rotate on x's parent on the opposite side.



Case 2: y is BLACK and y and x are on the same side. Rotate on x's parent on the opposite side. New x is former x's parent



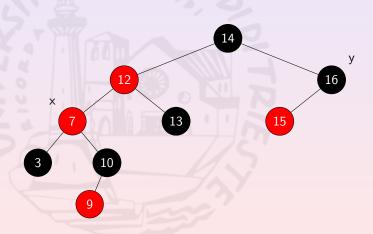
Still facing problems, but



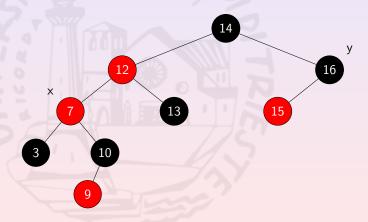
Motivations

#### Inserting a New Node: Example

Still facing problems, but y is still BLACK (no Case 1)

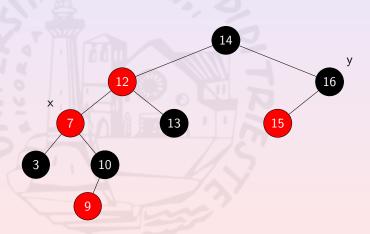


Still facing problems, but y is still BLACK (no Case 1) and x and y are on different sides (no Case 2)

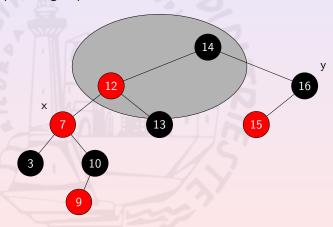


Motivations

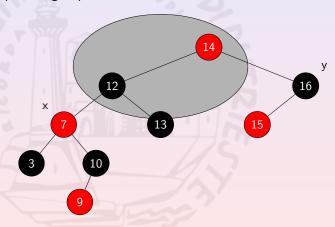
Case 3: y is BLACK and y and x are on different sides.



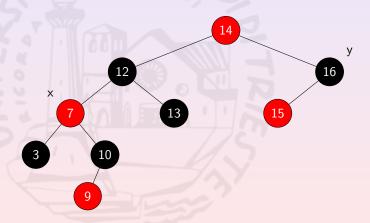
Case 3: y is BLACK and y and x are on different sides. Invert x's pa and granpa colors



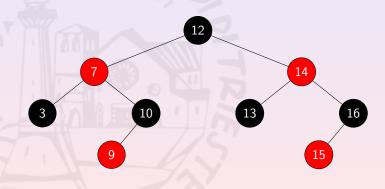
Case 3: y is BLACK and y and x are on different sides. Invert x's pa and granpa colors



Case 3: y is BLACK and y and x are on different sides. Invert x's pa and granpa colors and rotate on x's granpa on y's side



Case 3: y is BLACK and y and x are on different sides. Invert x's pa and granpa colors and rotate on x's granpa on y's side



If x parent is BLACK: done



If x parent is BLACK: done

If x has no uncle, either x or x.parent are the root: BLACK-color it



If x parent is BLACK: done

If x has no uncle, either x or x.parent are the root: BLACK-color it

If x has an uncle, we can always choose between Cases 1, 2, or 3

If x parent is BLACK: done

If x has no uncle, either x or x.parent are the root: BLACK-color it

If x has an uncle, we can always choose between Cases 1, 2, or 3

Case 1 either removes the problem or pushes it towards the root

If x parent is BLACK: done

If x has no uncle, either x or x.parent are the root: BLACK-color it

If x has an uncle, we can always choose between Cases 1, 2, or 3

Case 1 either removes the problem or pushes it towards the root

Case 2 brings to Case 3

If x parent is BLACK: done

If x has no uncle, either x or x. parent are the root: BLACK-color it

If x has an uncle, we can always choose between Cases 1, 2, or 3

Case 1 either removes the problem or pushes it towards the root

Case 2 brings to Case 3

Case 3 solves the problem

If x parent is BLACK: done

If x has no uncle, either x or x.parent are the root: BLACK-color it

If x has an uncle, we can always choose between Cases 1, 2, or 3

Case 1 either removes the problem or pushes it towards the root

Case 2 brings to Case 3

Case 3 solves the problem

In the worst case, the algorithm keeps repeating Case 1 steps along the insertion branch and the complexity is  $O(\log n)$ 

# Inserting a New Node: Code

Motivations

```
def INSERT_RBTREE(T, v):
  x \leftarrow INSERT_BST(T, v)
  x.color \leftarrow RED
  FIX_INSERT_RBTREE(T, x)
enddef
def FIX_INSERT_RBT_CASE1(T,x):
  UNCLE(x).color \leftarrow BLACK
  x.parent.color \leftarrow BLACK
  GRANDPARENT(x).color \leftarrow RED
  return GRANDPARENT(x)
endif
```

# Inserting a New Node: Code (Cont'd)

```
def FIX_INSERT_RBT_CASE2(T,x):
    x_side ← CHILDHOOD_SIDE(x)

p ← x.parent
ROTATE(T,p,REVERSE_SIDE(x_side))

return p
endif
```

# Inserting a New Node: Code (Cont'd 2)

```
def FIX_INSERT_RBT_CASE3(T,x):
    g ← GRANDPARENT(z)

    x.parent.color ← BLACK
    g.color ← RED

    x_side ← CHILDHOOD_SIDE(x)

ROTATE(T,g,REVERSE_SIDE(x_side))
endif
```

# Inserting a New Node: Code (Cont'd 3)

```
def FIX_INSERT_RBTREE(T, x):
  while (\neg IS_ROOT(x)) and
         (\neg IS\_ROOT(x.parent)  or x.parent.color=RED)):
     if COLOR(UNCLE(x))=RED:
       z \leftarrow FIX\_INSERT\_RBT\_CASE1(T,x)
    else:
       if (CHILDHOOD\_SIDE(x) \neq
            CHILDHOOD_SIDE(x.parent)):
         z \leftarrow FIX\_INSERT\_RBT\_CASE2(T,x)
       endif
       FIX_INSERT_RBT_CASE3(T, x)
    endif
  endwhile
  T.root.color \leftarrow BLACK
enddef
```

Removing a key as in BST removes also a node y which is replaced by its former child x



Removing a key as in BST removes also a node y which is replaced by its former child x

If y was RED, the RB-Tree properties are preserved

Removing a key as in BST removes also a node y which is replaced by its former child x

If y was RED, the RB-Tree properties are preserved

If y was BLACK, the branches through x lost 1 BLACK node

In particular, BH(x) = BH(w) - 1 where w is x's sibling

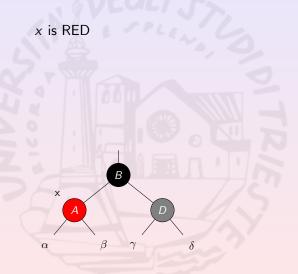
Removing a key as in BST removes also a node y which is replaced by its former child x

If y was RED, the RB-Tree properties are preserved

If y was BLACK, the branches through x lost 1 BLACK node

In particular, BH(x) = BH(w) - 1 where w is x's sibling

The fixing procedure iteratively balances BH on the sub-tree rooted on x's parent



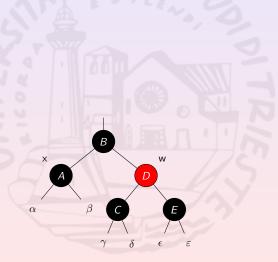
#### x is RED

BLACK-color x

BH(x) is increased by 1 and the tree has been fixed



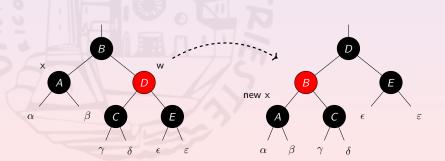
x's sibling is RED



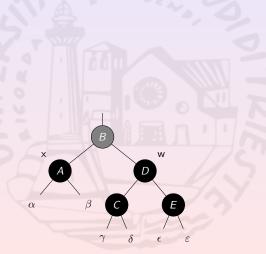
#### x's sibling is RED

- invert colors in x's parent and sibling
- rotate x's parent on x's side

#### BH(x) does not change



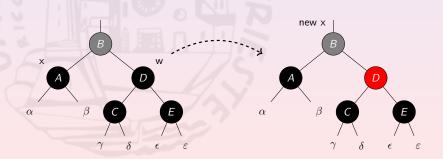
x's sibling and nephews are BLACK



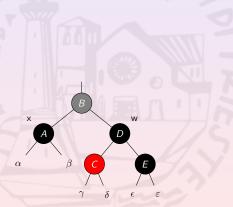
x's sibling and nephews are BLACK

• RED-color x's sibling

BH(x) does not change, while the BLACK height of both x's parent and sibling are decreased by 1



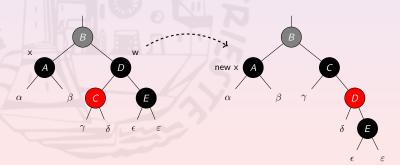
Among x's sibling and nephews, only the nephew on x's side is RED



Among x's sibling and nephews, only the nephew on x's side is RED

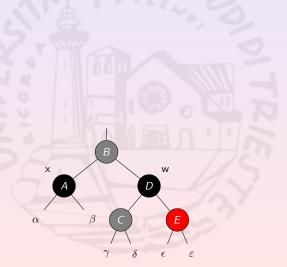
- rotate x's sibling on the opposite side w.r.t. x
- invert colors in both old and new siblings of x

The BLACK height of both x and x's parent does not change



Motivations

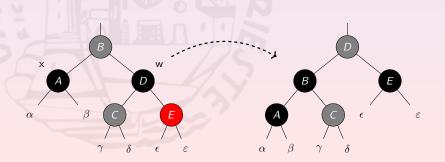
The x's nephew on the opposite side w.r.t. x is RED



The x's nephew on the opposite side w.r.t. x is RED

- switch colors of x's parent and sibling
- BLACK-color the x's nephew on the opposite side w.r.t. x
- rotate x's parent on x's side

The BLACK height of both x and x's parent does not change



All the case transformation procedures takes time  $\Theta(1)$ 



All the case transformation procedures takes time  $\Theta(1)$ 

Both Case 0 and Case 4 transformation procedures fix the RB-Tree

All the case transformation procedures takes time  $\Theta(1)$ 

Both Case 0 and Case 4 transformation procedures fix the RB-Tree

Case 1 cannot occur twice in-row

All the case transformation procedures takes time  $\Theta(1)$ 

Both Case 0 and Case 4 transformation procedures fix the RB-Tree

Case 1 cannot occur twice in-row

Case 2 pushes the problem one step towards the root

All the case transformation procedures takes time  $\Theta(1)$ 

Both Case 0 and Case 4 transformation procedures fix the RB-Tree

Case 1 cannot occur twice in-row

Case 2 pushes the problem one step towards the root

If Case 2 occurs after Case 1, Case 0 occurs next

All the case transformation procedures takes time  $\Theta(1)$ 

Both Case 0 and Case 4 transformation procedures fix the RB-Tree

Case 1 cannot occur twice in-row

Case 2 pushes the problem one step towards the root

If Case 2 occurs after Case 1, Case 0 occurs next

Case 3 transformation procedure brings to Case 4

In the worst case scenario, Case 2 is repeated until the problem is pushed up to the root  $(O(\log n))$  times

If this is the case, we have decreased the BLACK height of the tree and the problem is no more a problem

# Removing a Key: Code

```
def REMOVE_RBTREE(T, z):
  y \leftarrow REMOVE\_BST(T, z)
  if y.color = BLACK: # fix from its replacement
     if y.left = NIL
      x \leftarrow y.right
    else:
      x \leftarrow y.left
     endif
    FIX_REMOVE_RBTREE(T, x)
  endif
  return y
enddef
```

# Removing a Key: Code (Cont'd 2)

```
def FIX_REMOVE_RBT_CASE1(T, x):
  SIBLING(x). color \leftarrow BLACK
  x.parent.color \leftarrow RED
  ROTATE(T, x, CHILDHOOD_SIDE(x))
endif
def FIX_REMOVE_RBT_CASE2(T, x):
  SIBLING(x).color \leftarrow RED
  return x. parent
endif
```

# Removing a Key: Code (Cont'd 3)

```
def FIX_REMOVE_RBT_CASE3(T,x):
    x_side ← CHILDHOOD_SIDE(x)
    r_side ← REVERSE_SIDE(x_side)

    w ← GET_CHILD(w, r_side)
    GET_CHILD(w, x_side). color ← BLACK
    w. color ← RED

ROTATE(T,w, r_side)
endif
```

# Removing a Key: Code (Cont'd 4)

```
def FIX_REMOVE_RBT_CASE4(T, x):
  x_side \leftarrow CHILDHOOD_SIDE(x)
  r_side ← REVERSE_SIDE(x_side)
  w \leftarrow GET_CHILD(w, r_side)
  GET\_CHILD(w, r\_side).color \leftarrow BLACK
  w.color \leftarrow x.parent.color
  x.parent.color \leftarrow BLACK
  ROTATE(T, x. parent, x_side)
endif
```

# Removing a Key: Code (Cont'd 5)

```
def FIX_REMOVE_RBT(T,x):
    while x ≠ T.root and x.color ≠ RED:
        w ← SIBLING(x)
    if w = RED:
        x ← FIX_REMOVE_RBT_CASE1(T,x)
    else:
        x_side ← CHILDHOOD_SIDE(x)
        r_side ← REVERSE_SIDE(x_side)
```

# Removing a Key: Code (Cont'd 6)

```
if GET_CHILD(w, r_size) = RED:
        FIX_REMOVE_RBT_CASE4(T,x)
        return
      else:
        if GET_CHILD(w, x_side) = RED:
          FIX_REMOVE_RBT_CASE3(T,x)
        else:
          FIX_REMOVE_RBT_CASE2(T, x)
        endif
    endif
  endwhile
enddef
```