Recorded at time: 1518707046.002 base link Broadcaster: /clustering_18103_1518706679862 Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.204 Hz Average rate: 10.208 Hz Average rate: 10.208 Hz Most recent transform: 1518707046.489 (-0.487 sec old) Most recent transform: 1518707045.937 (0.065 sec old) Most recent transform: 1518707045.910 (0.092 sec old) Buffer length: 4.800 sec Buffer length: 4.920 sec Buffer length: 4.800 sec link_1 camera_link base Broadcaster: /camera base link1 Broadcaster: /camera base link Broadcaster: /robot_state_publisher Average rate: 10.208 Hz Average rate: 10.194 Hz Average rate: 10.195 Hz Most recent transform: 1518707046.099 (-0.097 sec old) Most recent transform: 1518707046.043 (-0.041 sec old) Most recent transform: 1518707045.910 (0.092 sec old) Buffer length: 4.905 sec Buffer length: 4.806 sec Buffer length: 4.800 sec link_2 camera_rgb_frame camera_depth_frame Broadcaster: /camera_base_link3 Broadcaster: /camera base link2 Broadcaster: /robot_state_publisher Average rate: 10.198 Hz Average rate: 10.194 Hz Average rate: 10.208 Hz Most recent transform: 1518707046.048 (-0.046 sec old) Most recent transform: 1518707046.022 (-0.019 sec old) Most recent transform: 1518707045.910 (0.092 sec old) Buffer length: 4.805 sec Buffer length: 4.807 sec Buffer length: 4.800 sec camera_depth_optical_frame link_3 camera_rgb_optical_frame Broadcaster: /robot_state_publisher Average rate: 10.208 Hz Most recent transform: 1518707045.910 (0.092 sec old) Buffer length: 4.800 sec link_4 Broadcaster: /robot_state_publisher Average rate: 10.208 Hz Most recent transform: 1518707045.910 (0.092 sec old) Buffer length: 4.800 sec link_5 Broadcaster: /robot_state_publisher Average rate: 10.208 Hz Most recent transform: 1518707045.910 (0.092 sec old) Buffer length: 4.800 sec link_6 Broadcaster: /robot_state_publisher Average rate: 50.204 Hz Most recent transform: 1518707046.489 (-0.487 sec old) Buffer length: 4.920 sec base_link_BH Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot state publisher Average rate: 10.208 Hz Average rate: 10.208 Hz Average rate: 10.208 Hz Most recent transform: 1518707045.910 (0.092 sec old) Most recent transform: 1518707045.910 (0.092 sec old) Most recent transform: 1518707045.910 (0.092 sec old) Buffer length: 4.800 sec Buffer length: 4.800 sec Buffer length: 4.800 sec finger_2_prox_link finger_3_med_link finger_1_prox_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10.208 Hz Average rate: 10.208 Hz Average rate: 10.208 Hz Most recent transform: 1518707045.910 (0.092 sec old) Most recent transform: 1518707045.910 (0.092 sec old) Most recent transform: 1518707045.910 (0.092 sec old) Buffer length: 4.800 sec Buffer length: 4.800 sec Buffer length: 4.800 sec finger_1_med_liink finger_2_med_link finger_3_dist_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10.208 Hz Average rate: 10.208 Hz Most recent transform: 1518707045.910 (0.092 sec old) Most recent transform: 1518707045.910 (0.092 sec old) Buffer length: 4.800 sec Buffer length: 4.800 sec finger_2_dist_link finger_1_dist_link

view_frames Result