

---

## Introduction to the Course

---

Estimated time to completion: **3 minutes**

### 1.2 Start Practicing!

With the proper introductions made, it is time to get started. And, as always, at the Robot Ignite Academy, you will start with practice! In the following example, you will use a Neobotix 3-MX robot, which runs in ROS2. So, start!

- Demo -

a) First, source ROS2 to execute ROS2 commands.

► Execute in Shell #1

```
In [ ]: source /opt/ros/humble/setup.sh
```

b) Now, execute a simple ROS2 command that will make the robot start moving.