Zeroth-Order Frank-Wolfe Optimization for Black-Box Adversarial Attacks

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Introduction



- Goal of the project: comparing Zeroth-Order Frank-Wolfe variants in constraint optimization problems and testing on black-box adversarial attacks against MNIST.
- Implemented Algorithms:
 - FZCGS: Faster Zeroth-Order Conditional Gradient Sliding Method (Gao et al.)
 - **SGFFW**: Stochastic Gradient-Free Frank-Wolfe, with three different gradient approximation schemes:
 - KWSA: Kiefer-Wolfowitz Stochastic Approximation
 - RDSA: Random Directions Stochastic Approximation
 - I-RDSA: Improvised Random Directions Stochastic Approximation
- Adversarial Attack: deliberate manipulation of the input data with the intention of causing a ML model to make a mistake or produce incorrect output. This is done through perturbation of the input in a way that is not easily noticeable to a human observer.

FZCGS: Faster Zeroth-Order Conditional Gradient Sliding



Employs Coordinate-wise Gradient Estimator

$$\hat{\nabla}f(\mathbf{x}) = \sum_{j=1}^{d} \frac{f(\mathbf{x} + \mu_j \mathbf{e}_j) - f(\mathbf{x} - \mu_j \mathbf{e}_j)}{2\mu_j} \mathbf{e}_j$$

Algorithm 2 Faster Zeroth-Order Conditional Gradient Method (FZCGS)

Input: $\mathbf{x}_0, q > 0, \mu > 0, K > 0, \eta > 0, \gamma > 0, n$

- 1: **for** $k = 0, \dots, K 1$ **do**
- 2: **if** mod(k, q) = 0 **then**
- 3: Sample S_1 without replacement to compute $\hat{\mathbf{v}}_k = \hat{\nabla} f_{S_1}(\mathbf{x}_k)$
- 4: else
- 5: Sample S_2 with replacement to compute $\hat{\mathbf{v}}_k = \frac{1}{|S_2|} \sum_{i \in S_2} [\hat{\nabla} f_i(\mathbf{x}_k) \hat{\nabla} f_i(\mathbf{x}_{k-1}) + \hat{\mathbf{v}}_{k-1}]$
- 6: **end if**
- 7: $\mathbf{x}_{k+1} = \operatorname{condg}(\hat{\mathbf{v}}_k, \mathbf{x}_k, \gamma_k, \eta_k)$
- 8: end for

Output: Randomly choose \mathbf{x}_{α} from $\{\mathbf{x}_k\}$ and return it

- $\hat{\nabla} f(\mathbf{x})$ is the estimated gradient of the function f in \mathbf{x}
- d is the dimensionality of the optimization space
- $\mu_j > 0$ is a smoothing parameter
- e_j ∈ R^d is the basis vector where only the j-th element is 1 and all others are 0.

Algorithm 3 $\mathbf{u}^+ = \operatorname{condg}(\mathbf{g}, \mathbf{u}, \gamma, \eta)$ (Qu et al., 2017)

- 1: $\mathbf{u}_1 = \mathbf{u}, t = 1$
- 2: \mathbf{v}_t be an optimal solution for

$$V_{\mathbf{g}, \mathbf{u}, \gamma}(\mathbf{u}_t) = \max_{\mathbf{x} \in \Omega} \langle \mathbf{g} + \frac{1}{\gamma} (\mathbf{u}_t - \mathbf{u}), \mathbf{u}_t - \mathbf{x} \rangle$$

- 3: If $V_{\mathbf{g},\mathbf{u},\gamma}(\mathbf{u}_t) \leq \eta$, return $\mathbf{u}^+ = \mathbf{u}_t$.
- 4: Set $\mathbf{u}_{t+1} = (1 \alpha_t)\mathbf{u}_t + \alpha_t\mathbf{v}_t$ where $\alpha_t = \min\{1, \frac{\langle \frac{1}{\gamma}(\mathbf{u} \mathbf{u}_t) \mathbf{g}, \mathbf{v}_t \mathbf{u}_t \rangle}{\frac{1}{c} \|\mathbf{v}_t \mathbf{u}_t\|^2}\}$.
- 5: Set $t \leftarrow t + 1$ and goto step 2.

FZCGS: Faster Zeroth-Order Conditional Gradient Sliding



- Employs:
 - Coordinate-wise Gradient Estimation
 - Variance Reduction technique
 - Conditional Gradient Sliding

Algorithm 2 Faster Zeroth-Order Conditional Gradient Method (FZCGS)

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Input: \mathbf{x}_0, q > 0, \mu > 0, K > 0, \eta > 0, \gamma > 0, n

1: for k = 0, \dots, K - 1 do

2: if \operatorname{mod}(\mathbf{k}, \mathbf{q}) = 0 then

3: Sample S_1 without replacement to compute \hat{\mathbf{v}}_k = \hat{\nabla} f_{S_1}(\mathbf{x}_k)

4: else
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- 5: Sample S_2 with replacement to compute $\hat{\mathbf{v}}_k = \frac{1}{|S_2|} \sum_{i \in S_2} [\hat{\nabla} f_i(\mathbf{x}_k) \hat{\nabla} f_i(\mathbf{x}_{k-1}) + \hat{\mathbf{v}}_{k-1}]$
- 6: **end if**
- 7: $\mathbf{x}_{k+1} = \operatorname{condg}(\hat{\mathbf{v}}_k, \mathbf{x}_k, \gamma_k, \eta_k)$
- 8: end for

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Algorithm 3 $\mathbf{u}^+ = \text{condg}(\mathbf{g}, \mathbf{u}, \gamma, \eta)$ (Qu et al., 2017)

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- 4: Set $\mathbf{u}_{t+1} = (1 \alpha_t)\mathbf{u}_t + \alpha_t\mathbf{v}_t$ where $\alpha_t = \min\{1, \frac{\langle \frac{1}{\gamma}(\mathbf{u} \mathbf{u}_t) \mathbf{g}, \mathbf{v}_t \mathbf{u}_t \rangle}{\frac{1}{\gamma}\|\mathbf{v}_t \mathbf{u}_t\|^2}\}$.
- 5: Set $t \leftarrow t + 1$ and goto step 2.

SGFFW: Stochastic Gradient-Free Frank-Wolfe



- It was one of the first approaches to Stochastic Zeroth-Order Frank-Wolfe
- Uses Random Directions Gradient Estimator
- Employs an averaging trick to counter diverging gradient
- Sampled Directions:
 - KWSA: along each coordinate direction (d directions, with d dimensionality of the problem space)
 - RDSA: one random direction
 - I-RDSA: m < d independently sampled directions

Algorithm 2 Stochastic Gradient Free Frank Wolfe

Require: Input, Loss Function F(x), Convex Set C, number of directions m, sequences $\gamma_t = \frac{2}{t+8}$,

$$(\rho_t, c_t)_{RDSA} = \left(\frac{4}{d^{1/3}(t+8)^{2/3}}, \frac{2}{d^{3/2}(t+8)^{1/3}}\right)$$
$$(\rho_t, c_t)_{I-RDSA} = \left(\frac{4}{\left(1 + \frac{d}{m}\right)^{1/3}(t+8)^{2/3}}, \frac{2\sqrt{m}}{d^{3/2}(t+8)^{1/3}}\right)$$
$$(\rho_t, c_t)_{KWSA} = \left(\frac{4}{(t+8)^{2/3}}, \frac{2}{d^{1/2}(t+8)^{1/3}}\right).$$

Output: \mathbf{x}_T or $\frac{1}{T} \sum_{t=0}^{T-1} \mathbf{x}_t$.

- 1: Initialize $\mathbf{x}_0 \in \overline{\mathcal{C}}$
- 2: **for** $t = 0, 2, \dots, T 1$ **do**
- 3: Compute

KWSA:

$$\mathbf{g}(\mathbf{x}_t; \mathbf{y}) = \sum_{i=1}^{d} \frac{F(\mathbf{x}_t + c_t \mathbf{e}_i; \mathbf{y}) - F(\mathbf{x}_t; \mathbf{y})}{c_t} \mathbf{e}_i$$

RDSA: Sample $\mathbf{z}_t \sim \mathcal{N}(0, \mathbf{I}_d)$,

$$\mathbf{g}(\mathbf{x}_t; \mathbf{y}, \mathbf{z}_t) = \frac{F(\mathbf{x}_t + c_t \mathbf{z}_t; \mathbf{y}) - F(\mathbf{x}_t; \mathbf{y})}{c_t} \mathbf{z}_t$$

I-RDSA: Sample $\{\mathbf{z}_{i,t}\}_{i=1}^{m} \sim \mathcal{N}(0, \mathbf{I}_d),$

$$\mathbf{g}(\mathbf{x}_t; \mathbf{y}, \mathbf{z}_t) = \frac{1}{m} \sum_{i=1}^{m} \frac{F(\mathbf{x}_t + c_t \mathbf{z}_{i,t}; \mathbf{y}) - F(\mathbf{x}_t; \mathbf{y})}{c_t} \mathbf{z}_{i,t}$$

- 4: Compute $\mathbf{d}_t = (1 \rho_t) \mathbf{d}_{t-1} + \rho_t \mathbf{g}(\mathbf{x}_t, \mathbf{y}_t)$
- 5: Compute $\mathbf{v}_t = \operatorname{argmin}_{\mathbf{s} \in \mathcal{C}} \langle \mathbf{s}, \mathbf{d}_t \rangle$,
- 6: Compute $\mathbf{x}_{t+1} = (1 \gamma_t) \mathbf{x}_t + \gamma_t \mathbf{v}_t$.
- 7: end for

Experiments



- The experiment conducted on these Frank-Wolfe variants is a Black-Box Adversarial Attack on the MNIST Dataset.
 - This means that we have to find the **smallest perturbation** of the input 28x28 greyscale image of a handwritten digit, constrained by $\|\delta\|_{\infty} \leq s$, able to make the Deep Neural Network take the incorrect prediction.
- We follow the setup from nn-carlini pre-trained DNN for the MNIST dataset.
- Feasible Set used:
 - ullet As per section 4.3 of Gao et al., the feasible set used is $\|\delta\|_\infty \leq s$
 - s has different values based on the algorithm:
 - FZCGS: s = 4
 - SGFFW with RDSA: s = 8
 - SGFFW with I-RDSA and KWSA: s = 4

Changes from Theoretical Papers



- The implementative changes form the Theoretical Papers concern the FZCGS algorithm (Gao et al.). In particular, the Conditional Gradient Procedure.
- condg() from Gao et al. was changed with the condg() version from the paper Lobanov et al.
- condg() also presents an additional stopping condition based on the value of the alpha parameter.
 - This additional condition speeds up the already extremely long running times of FZCGS, whilst producing negligible deviations from the otherwise computed result.

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Algorithm 3 \mathbf{u}^+ = \text{condg}(\mathbf{g}, \mathbf{u}, \gamma, \eta) (Qu et al., 2017)
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- 1: $\mathbf{u}_1 = \mathbf{u}, t = 1$
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$$V_{\mathbf{g}, \mathbf{u}, \gamma}(\mathbf{u}_t) = \max_{\mathbf{x} \in \Omega} \langle \mathbf{g} + \frac{1}{\gamma} (\mathbf{u}_t - \mathbf{u}), \mathbf{u}_t - \mathbf{x} \rangle$$

- 3: If $V_{\mathbf{g},\mathbf{u},\gamma}(\mathbf{u}_t) \leq \eta$, return $\mathbf{u}^+ = \mathbf{u}_t$.
- 4: Set $\mathbf{u}_{t+1} = (1 \alpha_t)\mathbf{u}_t + \alpha_t\mathbf{v}_t$ where $\alpha_t =$ $\min\left\{1, \frac{\langle \frac{1}{\gamma}(\mathbf{u} - \mathbf{u}_t) - \mathbf{g}, \mathbf{v}_t - \mathbf{u}_t \rangle}{\frac{1}{2} \|\mathbf{v}_t - \mathbf{u}_t\|^2}\right\}.$
- 5: Set $t \leftarrow t + 1$ and goto step 2.

Conditional Gradient procedure (Gao et al.)

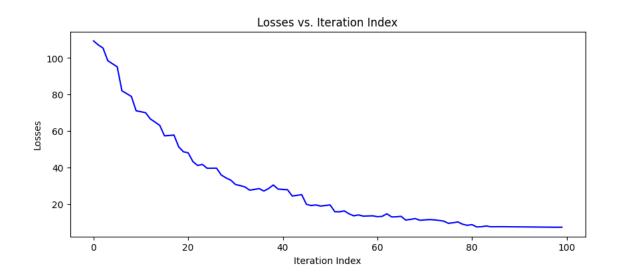
Algorithm 2 Conditional Gradient procedure

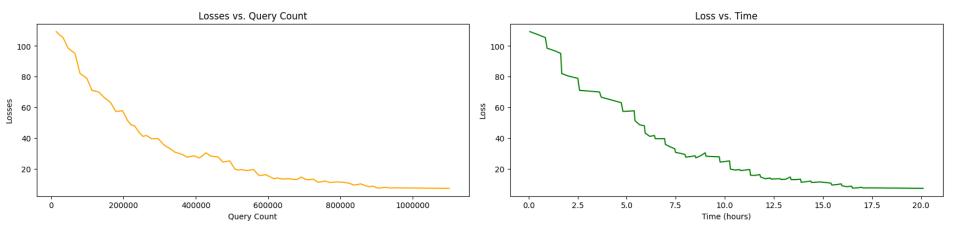
- 1: **for** t = 0, ..., T **do**
- $v_t \leftarrow \operatorname{argmin}_{v \in O} \langle g_t, v \rangle$
- if $\langle g_t, u_t v_t \rangle \leq \beta$ then
- 4: return u_t
- end if
- $\alpha_t \leftarrow \min\left\{\frac{\langle g_t, u_t v_t \rangle}{\eta \|u_t v_t\|^2}, 1\right\}$
- $u_{t+1} \leftarrow u_t + \alpha_t (v_t u_t)$
- $g_{t+1} \leftarrow g_0 + \eta(u_{t+1} u_0)$
- 9: end for

Conditional Gradient procedure (Lobanov et al.)

FZCGS Results



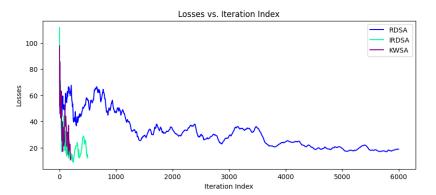


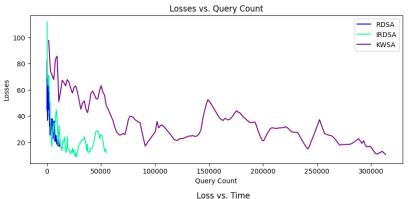


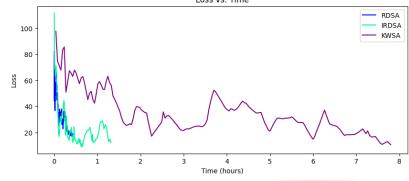
SGFFW Results (Compared)



- SGFFW has different behaviours depending on which gradient approximation scheme is used.
- RDSA: fastest in time and with limited query count, while requiring a lot of iterations.
- I-RDSA: requires extremely less iterations than RDSA, but requires more queries.
- KWSA: slowest in time, requires the least amount of iterations, at the expense of a very large query count.
- I-RDSA shows a remarkable compromise between iterations, query count and running time to converge.



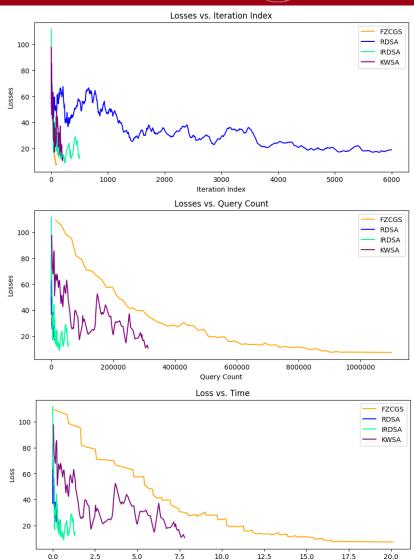




Results: All Algorithms Compared



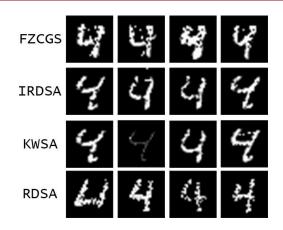
Algorithm	Metric	Value
FZCGS	Best Loss	7.283
	Last Loss	7.312
	Iteration Count	100
	Query Count	1100736
	Running Time (Hrs)	20.1
SGFFW-RDSA	Best Loss	16.9
	Last Loss	18.922
	Iteration Count	6000
	Query Count	12000
	Running Time (Hrs)	0.43
SGFFW-I-RDSA	Best Loss	8.96
	Last Loss	12.156
	Iteration Count	500
	Query Count	55000
	Running Time (Hrs)	1.3
SGFFW-KWSA	Best Loss	10.647
	Last Loss	10.647
	Iteration Count	200
	Query Count	313600
	Running Time (Hrs)	7.7



Time (hours)

Conclusions





- There is no overall best algorithm, since each of them has strengths and weaknesses.
- FZCGS has the best performance for iterations after SGFFW with KWSA, but is the worst for query count and running times.
- SGFFW with I-RDSA shows a remarkable compromise between all metrics:
 - Requires an acceptable amount of iterations
 - The query count is reasonably small
 - Running times are convenient
 - Reaches one of the lowest losses