Assessing the Impact of Outliers on Least Square Variogram Model

Caterina Daidone, Marco Zanotti

University Milano-Bicocca





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1. Introduction

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Geostatistics

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Gaussian Random Field

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2. Methods

The classical variogram estimator based on Matheron (1962) is defined as:

$$2\hat{\gamma} = \frac{1}{|N(h)|} \sum_{N(h)} \left(Z(s_i) - Z(s_j)\right)^2, \ h \in \mathbb{R}^d$$

where $N(h) = \{(s_i, s_j) : s_i - s_j = h; i, j = 1, ..., n\}$ and |N(h)|is the number of distinct pairs in N(h).

The **robust variogram** estimator based on Cressie (1980) is defined as:

$$2\bar{\gamma}(h) \equiv \left\{\frac{1}{|N(h)|} \sum_{N(h} |Z(s_i) - Z(s_j)|^{1/2} \right\}^4 / (0.457 + 0.494/|N(h)|)$$

and

$$2\tilde{\gamma}(h) = [med\{|Z(s_i) - Z(s_j)|^{1/2} : (s_i, s_j) \in N(h)\}]^4 / B(h)$$

where $med\{\cdot\}$ is the median of the sequence and B(h) corrects for bias (asymptotically 0.457).



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3. Simulation & Results

Following Hawkins (1984), the departure from Gaussianity is obtained simulating a **GRF** with probability $1 - \epsilon$ and a **CGRF** with probability ϵ .

$$\begin{cases} Gau(0,c_o), & \textit{with probability } 1-\epsilon \\ Gau(0,k^2c_0), & \textit{with probability } \epsilon \end{cases}$$

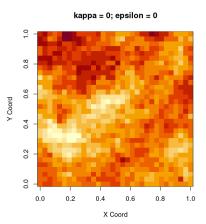
where ϵ is the probability of contamination and k measures the scale of the contamination.

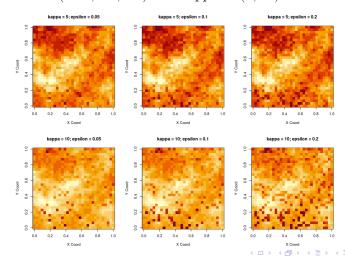
To practically simulate the underlying GRF, the **grf** function of the **geoR** package in R is used.



3. Simulation & Results

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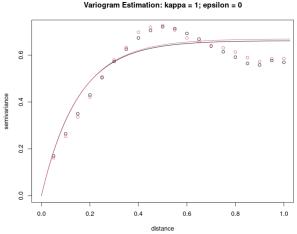




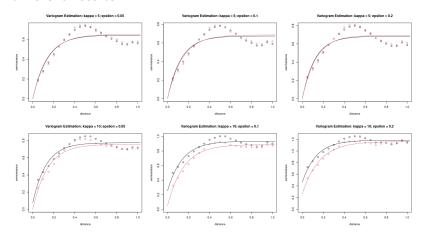
3. Simulation & Results

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results.



3. Simulation & Results



4. Conclusions

The theoretical considerations suggest that the robust variogram is less sensitive to the presence of outliers. For this reason it should be preferred when the data are contaminated.

The simulation study confirms this results and shows that:

- the robust variogram yields more stable estimates when the scale of the contamination increases
- if the **scale** of the contamination is **small**, the two methods provide **similar results**.

Bibliografy

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Thank you!