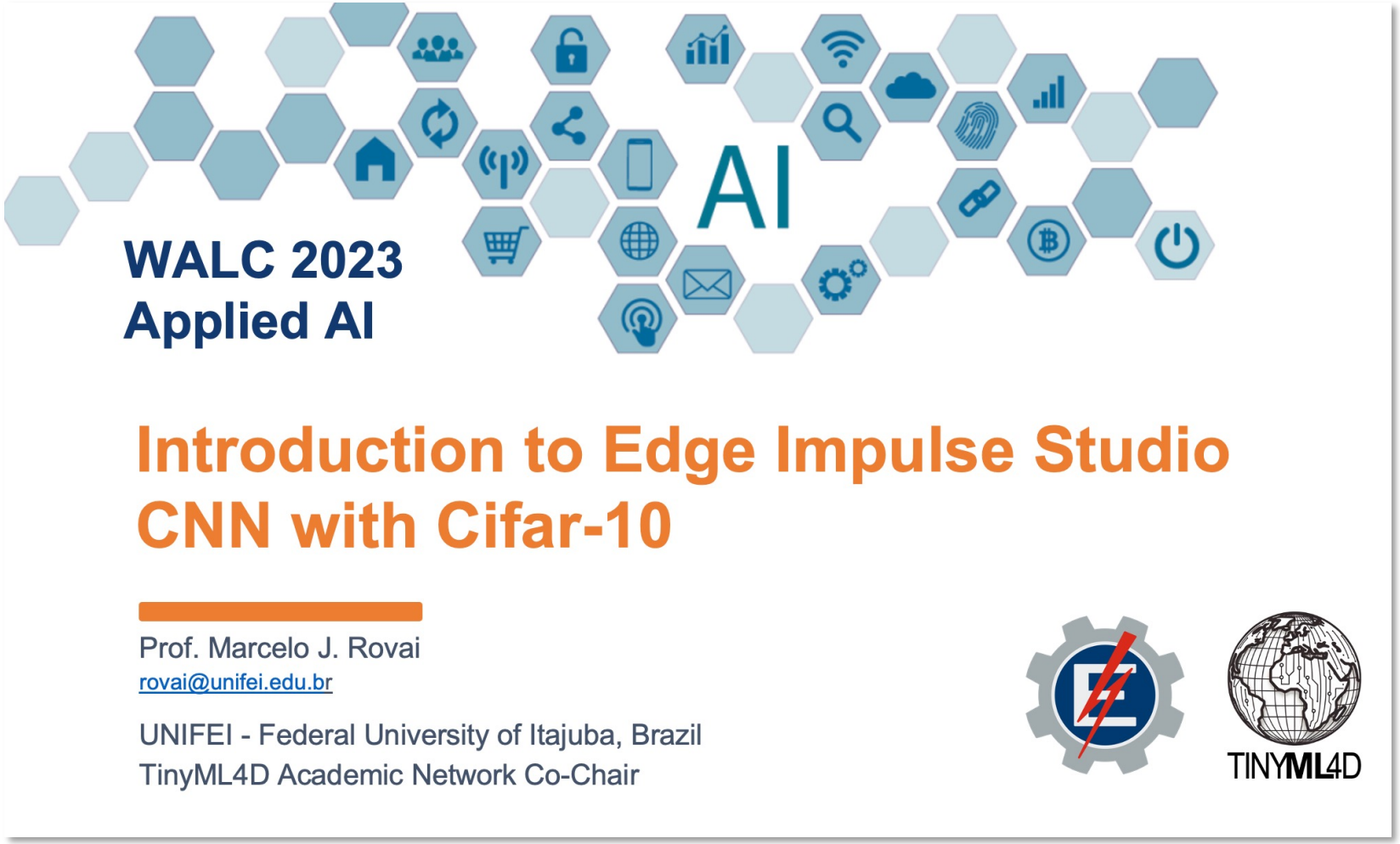
Introduction to Edge Impulse Studio CNN with Cifar-10

Marco Zennaro, PhD

TinyML4D Academic Network Co-Chair

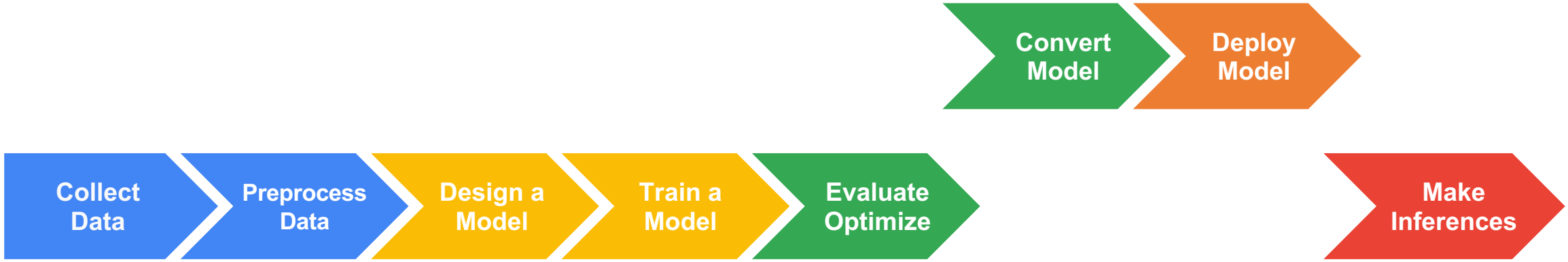
All the credit goes to Prof.Marcelo Rovai:



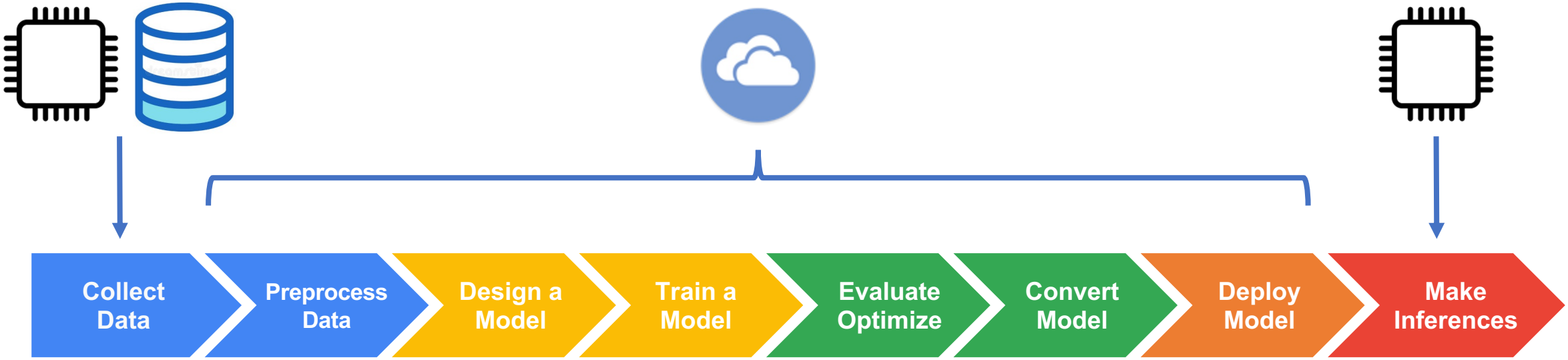
Embedded Machine Learning (TinyML) Workflow Review

Machine Learning Workflow

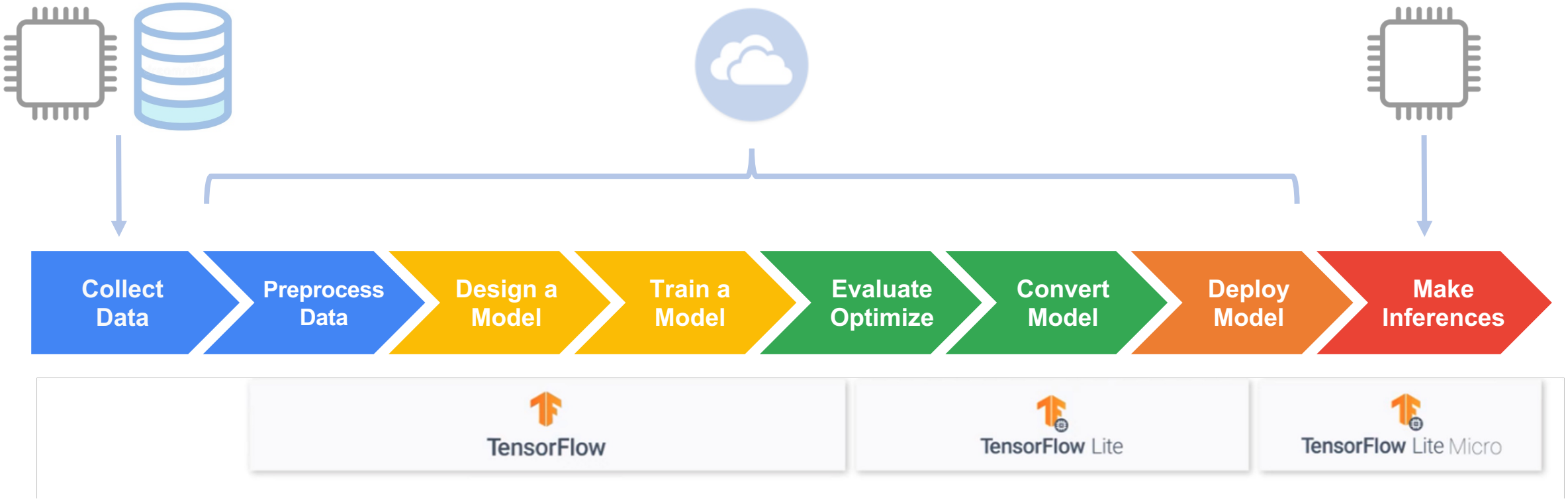
Tiny Machine Learning Workflow ("What")



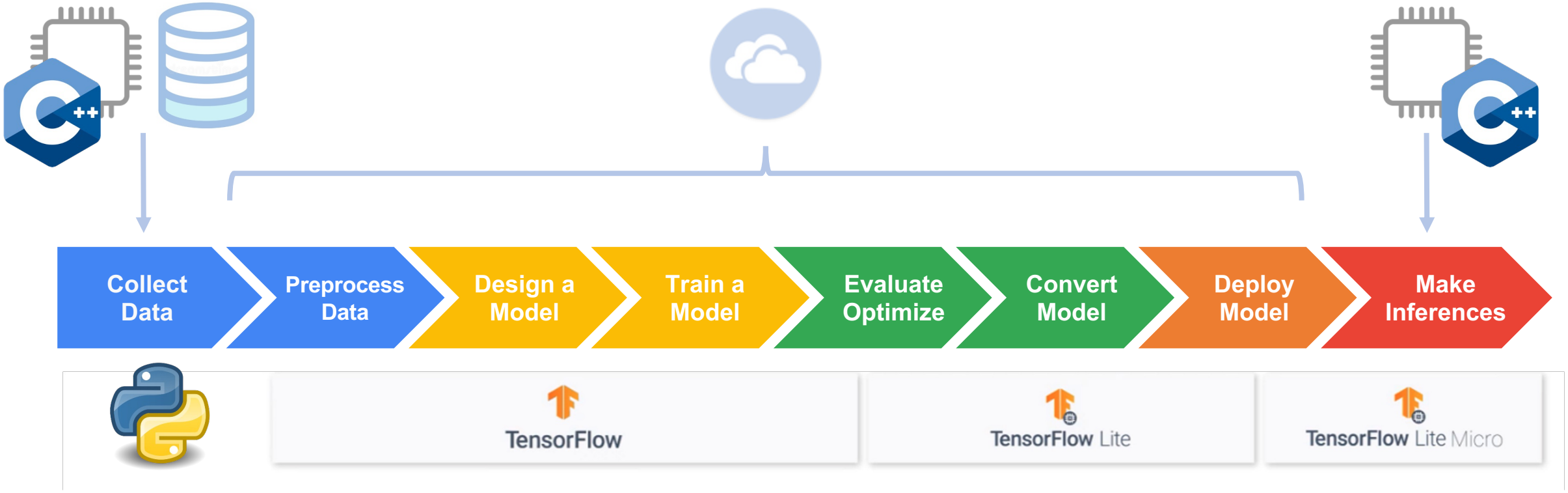
Tiny Machine Learning Workflow ("Where")



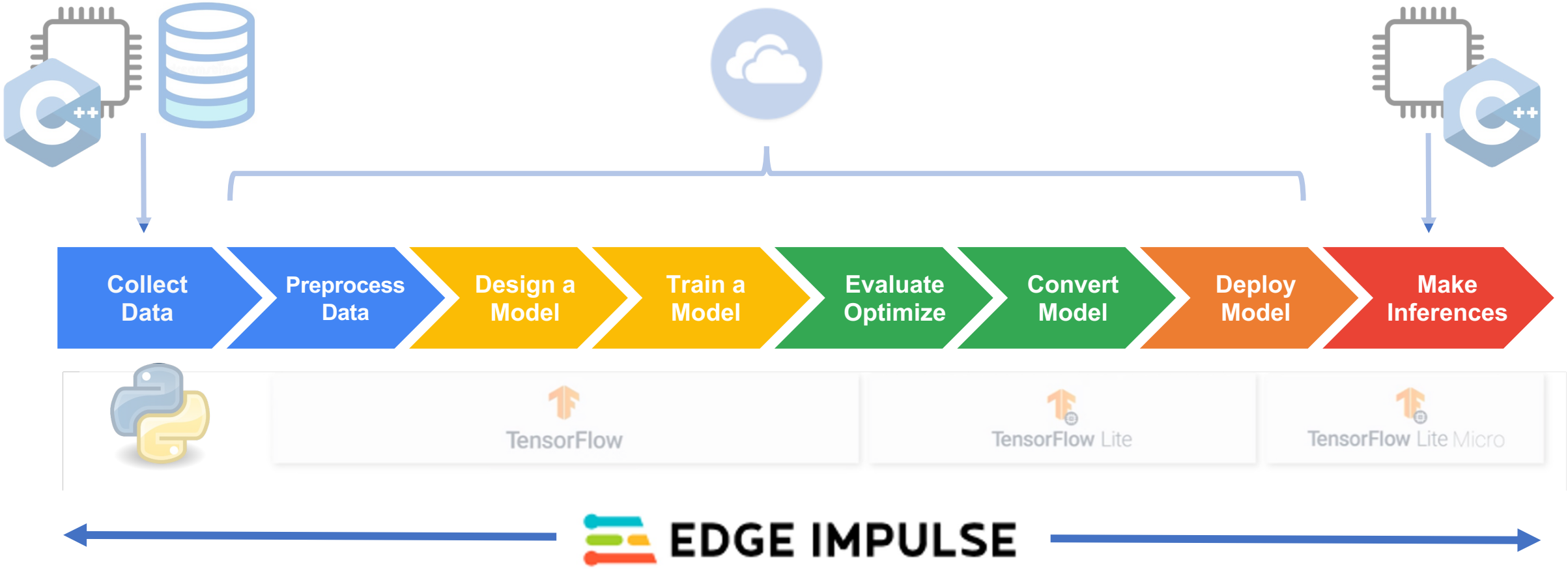
Machine Learning Workflow ("How")

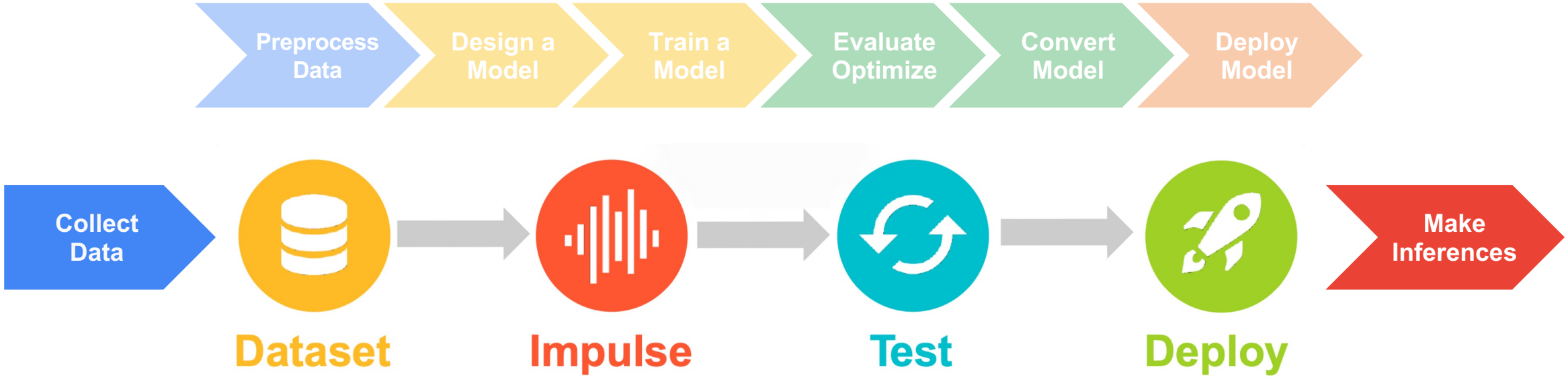


Machine Learning Workflow ("How")

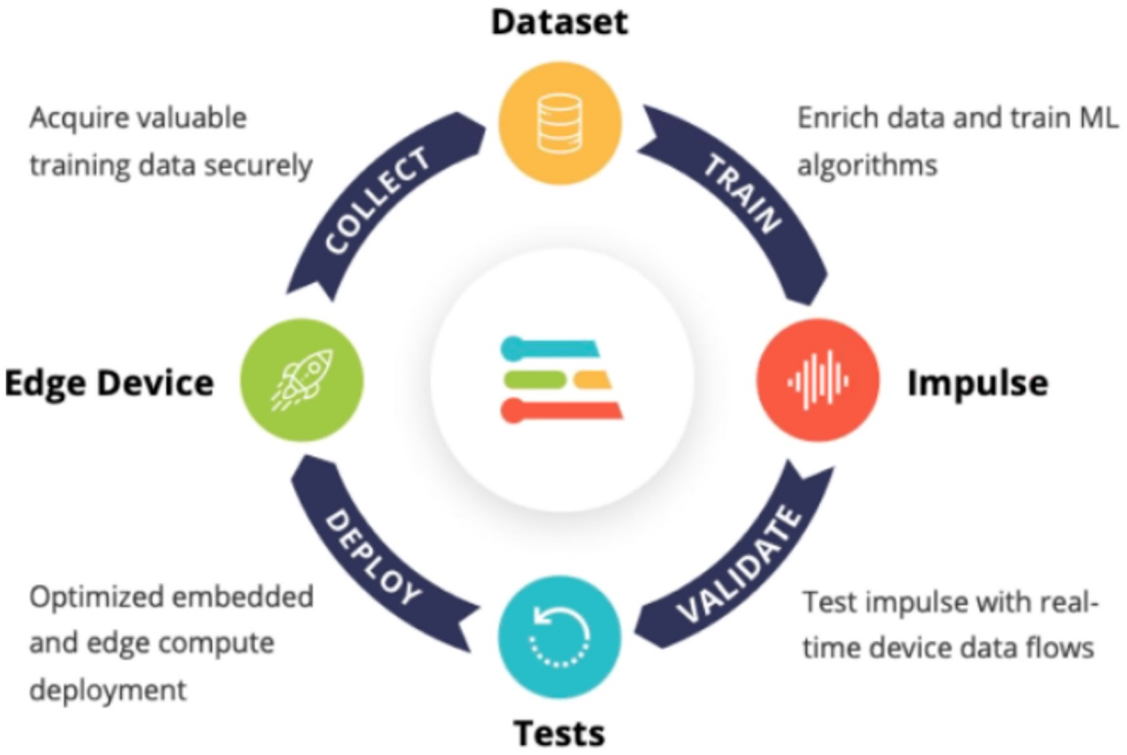


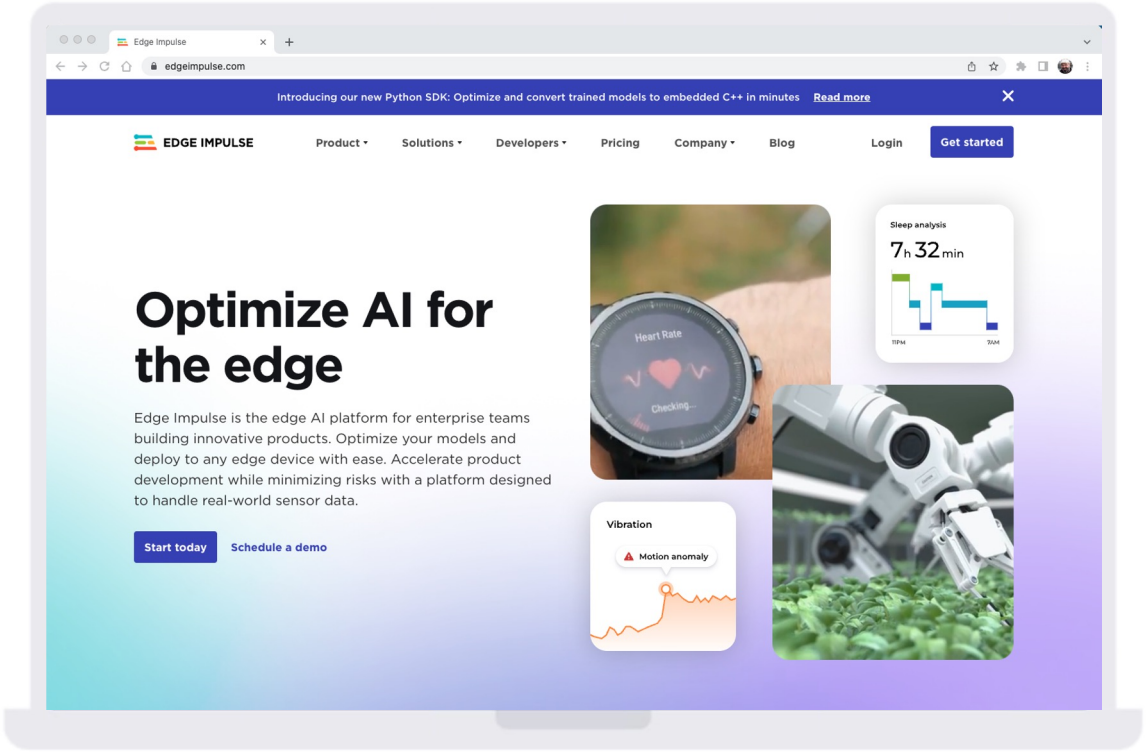
Machine Learning Workflow ("How")




Preprocess Data
Design a Model
Train a Model
Evaluate Optimize
Convert Model
Deploy Model
Collect Data
Dataset
Impulse
Test
Deploy
Make Inferences

EI Studio - Embedded ML platform ("AutoML")





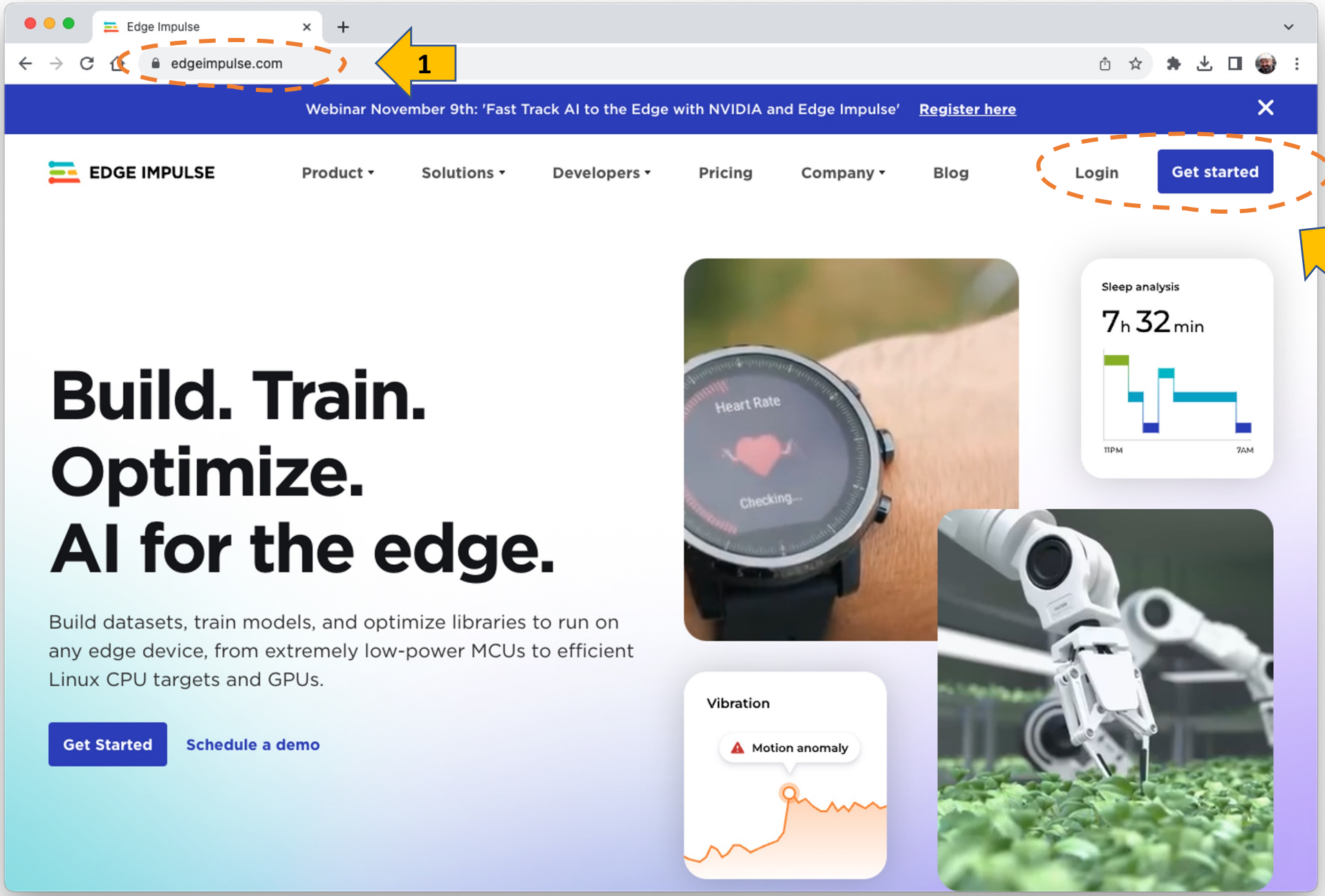
Learn more at http://edgeimpulse.com

[2023 SciTinyML Workshop - Edge Impulse Overview by Shawn Hymel]

Cifar10
Edge Impulse Studio

Dataset: https://github.com/YoongiKim/CIFAR-10-images

EI Studio Public Project: https://studio.edgeimpulse.com/public/51070/latest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1
Webinar November 9th: 'Fast Track AI to the Edge with NVIDIA and Edge Impulse' Register here
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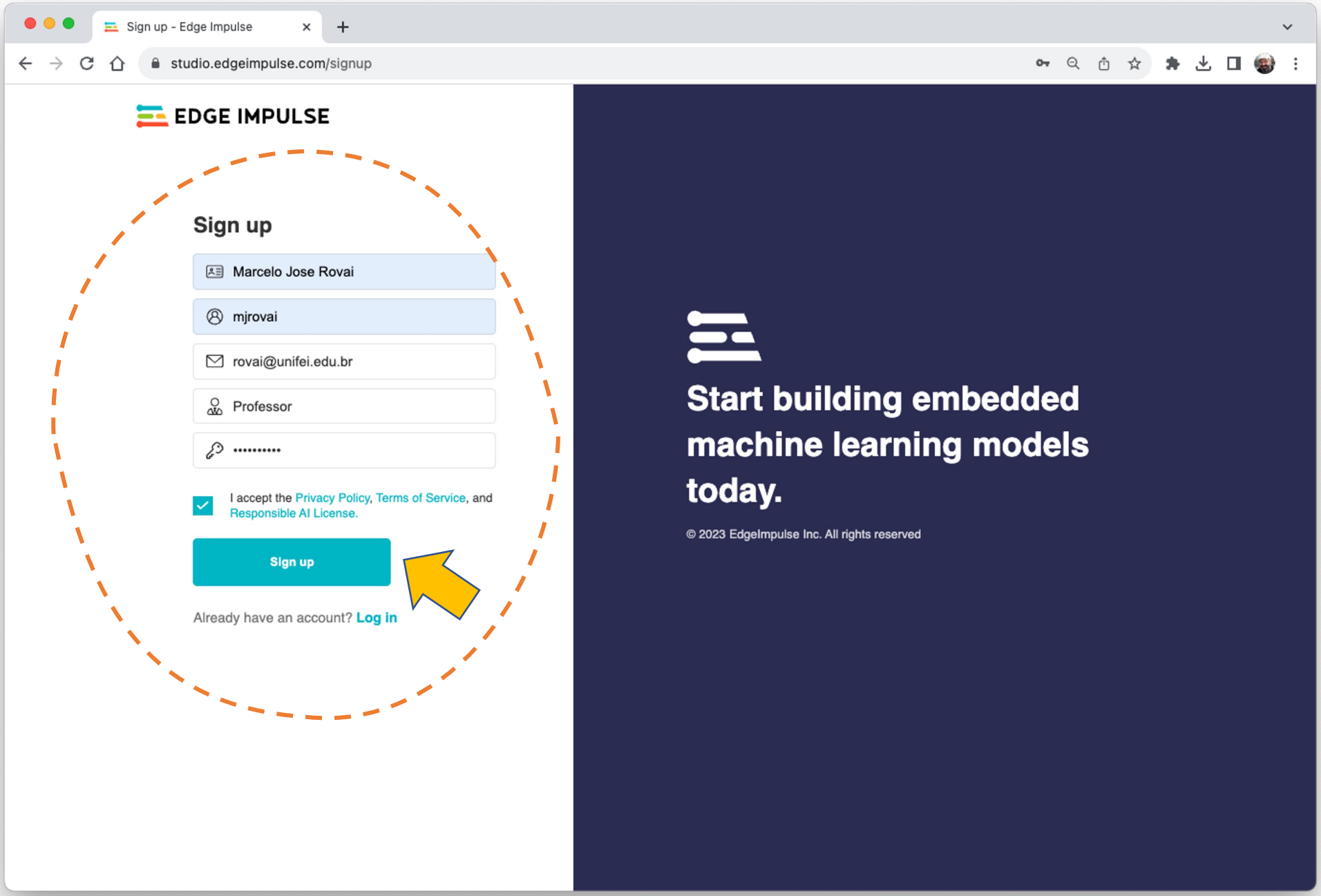
Get started
2
Build. Train.
Optimize.
AI for the edge.
Build datasets, train models, and optimize libraries to run on any edge device, from extremely low-power MCUs to efficient Linux CPU targets and GPUs.
Get Started
Schedule a demo
Heart Rate
Checking...
Sleep analysis
7h 32 min
11PM
7AM
Vibration
Motion anomaly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mjrovai
rovai@unifei.edu.br
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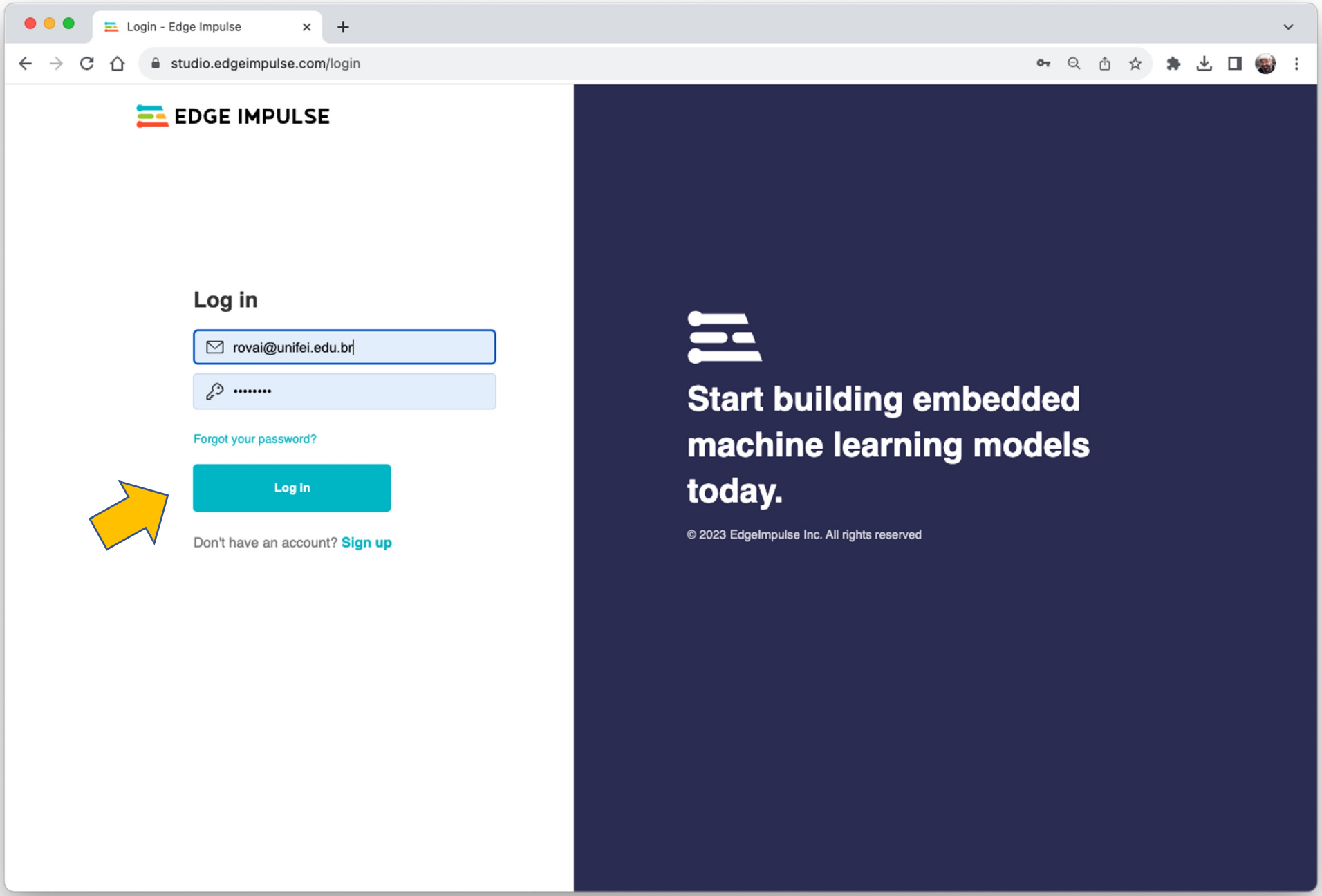
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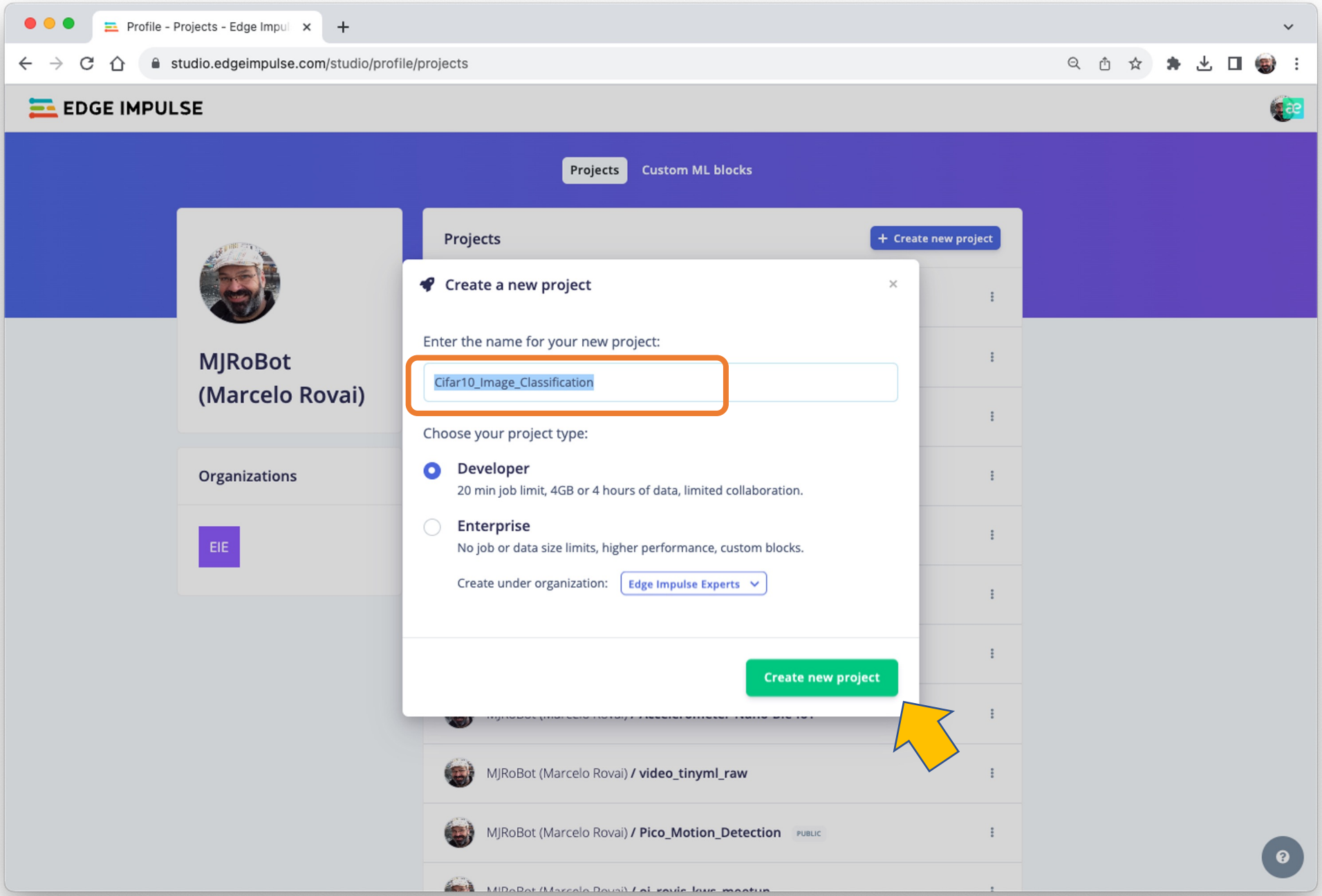
Profile - Projects - Edge Impul
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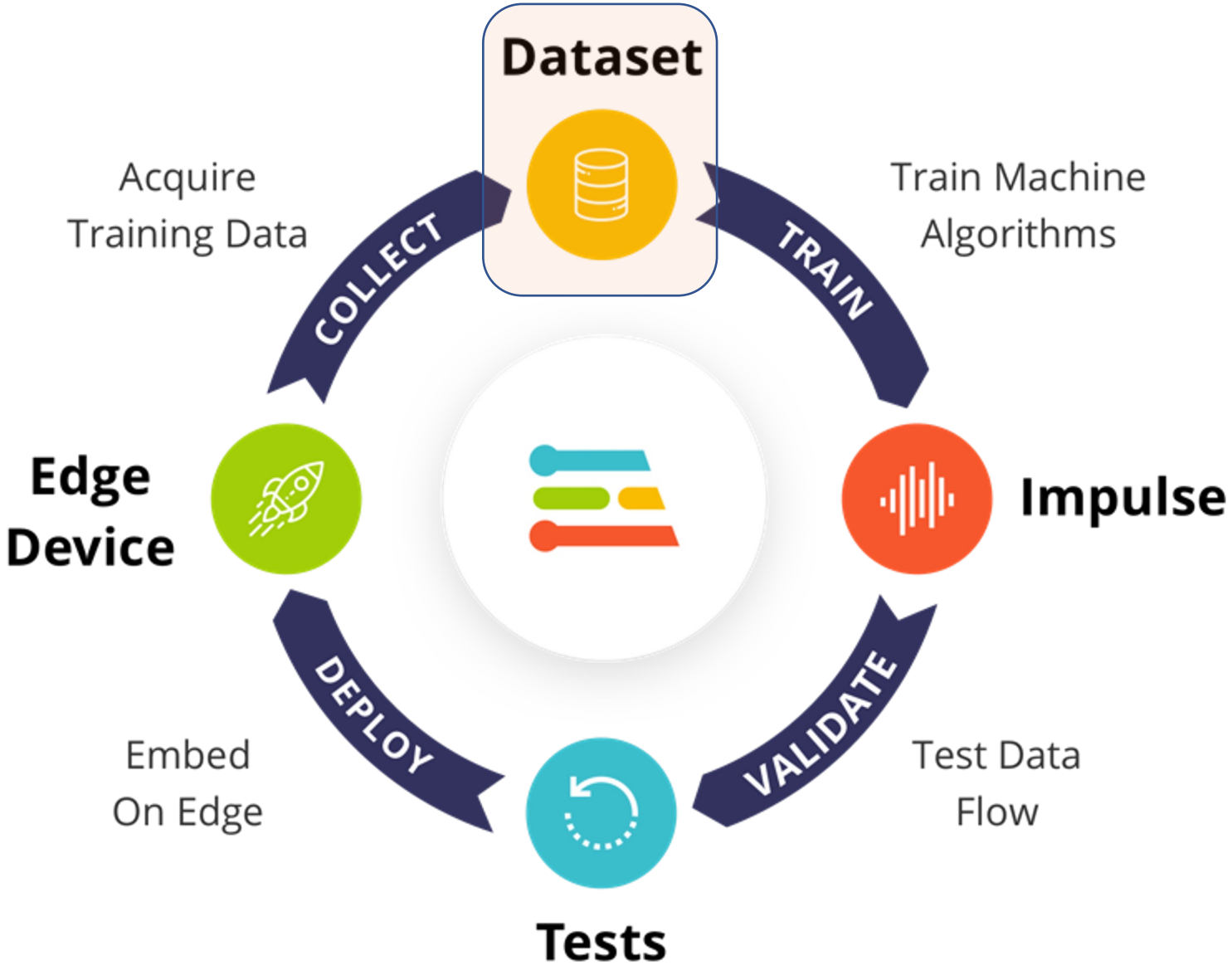
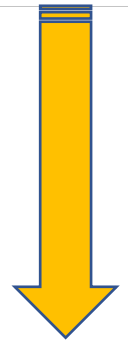
EDGE IMPULSE
Projects
Custom ML blocks
MJRoBot
(Marcelo Rovai)
Organizations
EIE
Projects
+ Create new project
Create a new project
Enter the name for your new project:
Cifar10_Image_Classification
Choose your project type:
Developer
20 min job limit, 4GB or 4 hours of data, limited collaboration.
Enterprise
No job or data size limits, higher performance, custom blocks.
Create under organization:
Edge Impulse Experts
Create new project
MJRoBot (Marcelo Rovai) / video_tinyml_raw
MJRoBot (Marcelo Rovai) / Pico_Motion_Detection
PUBLIC

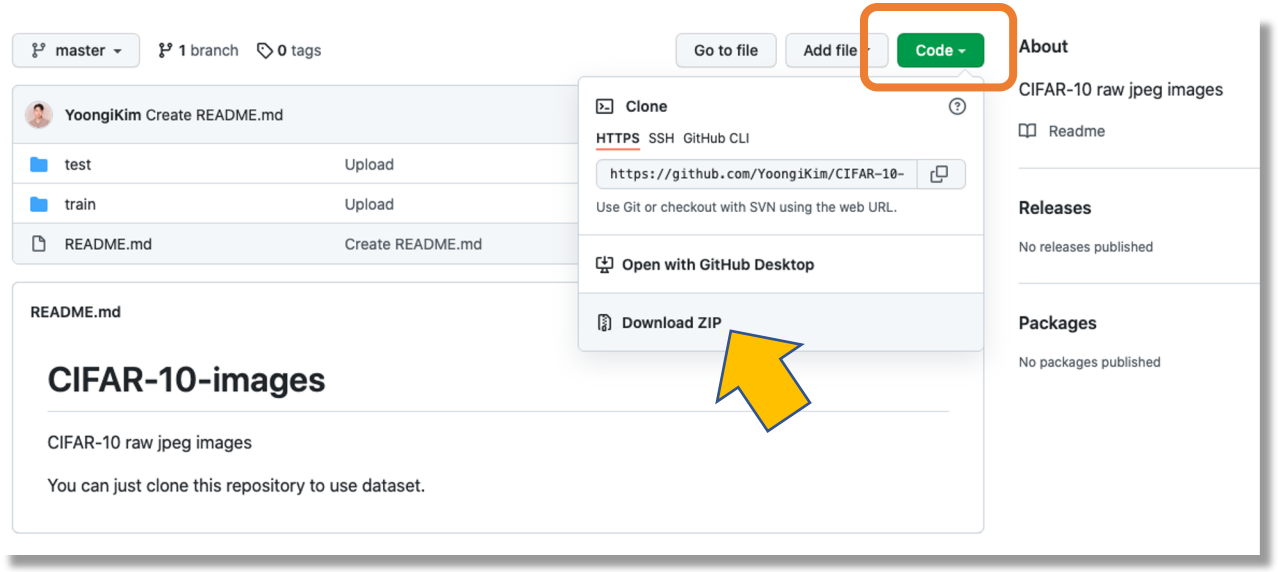


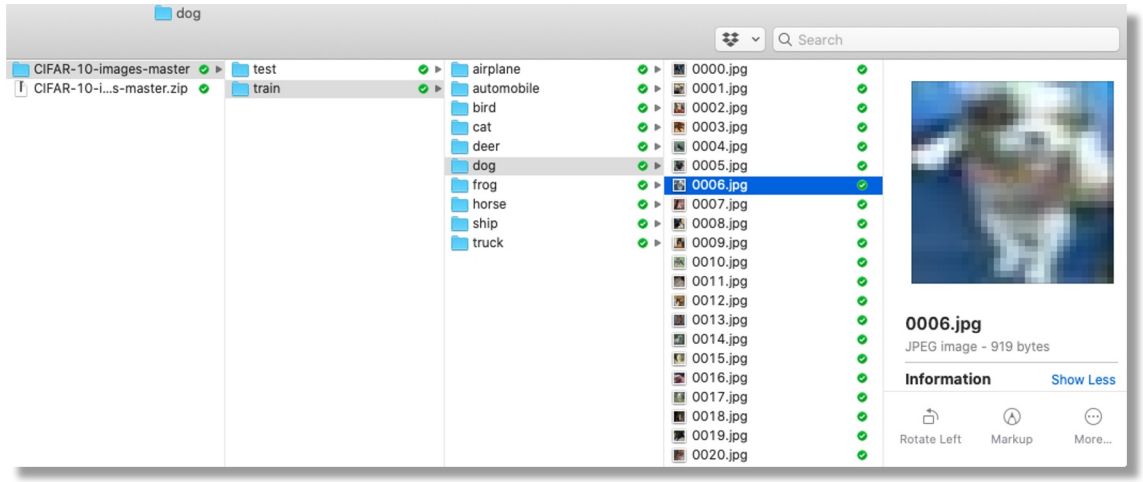
- Pre-Processing Data
- Design a Model
- Train a Model

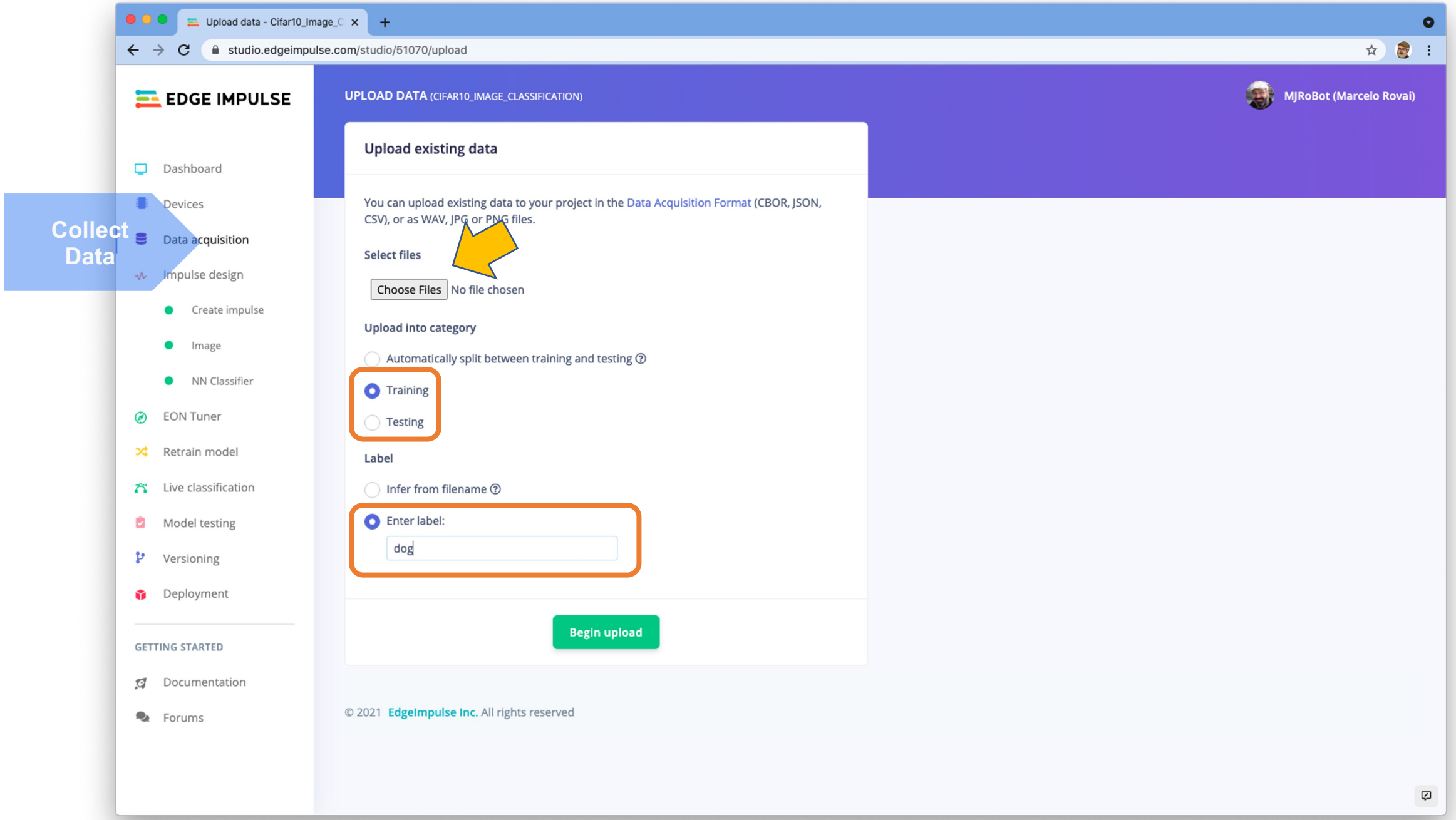
Download Dataset

https://github.com/YoongiKim/CIFAR-10-images








Upload data - Cifar10_Image_C
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EDGE IMPULSE
UPLOAD DATA (CIFAR10_IMAGE_CLASSIFICATION)
MJRoBot (Marcelo Rovai)
Collect Data
Dashboard
Devices
Data acquisition
Impulse design
Create impulse
Image
NN Classifier
EON Tuner
Retrain model
Live classification
Model testing
Versioning
Deployment
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Upload existing data
You can upload existing data to your project in the Data Acquisition Format (CBOR, JSON, CSV), or as WAV, JPG or PNG files.
Select files
Choose Files
No file chosen
Upload into category
Automatically split between training and testing
Training
Testing
Label
Infer from filename
Enter label:
dog
Begin upload
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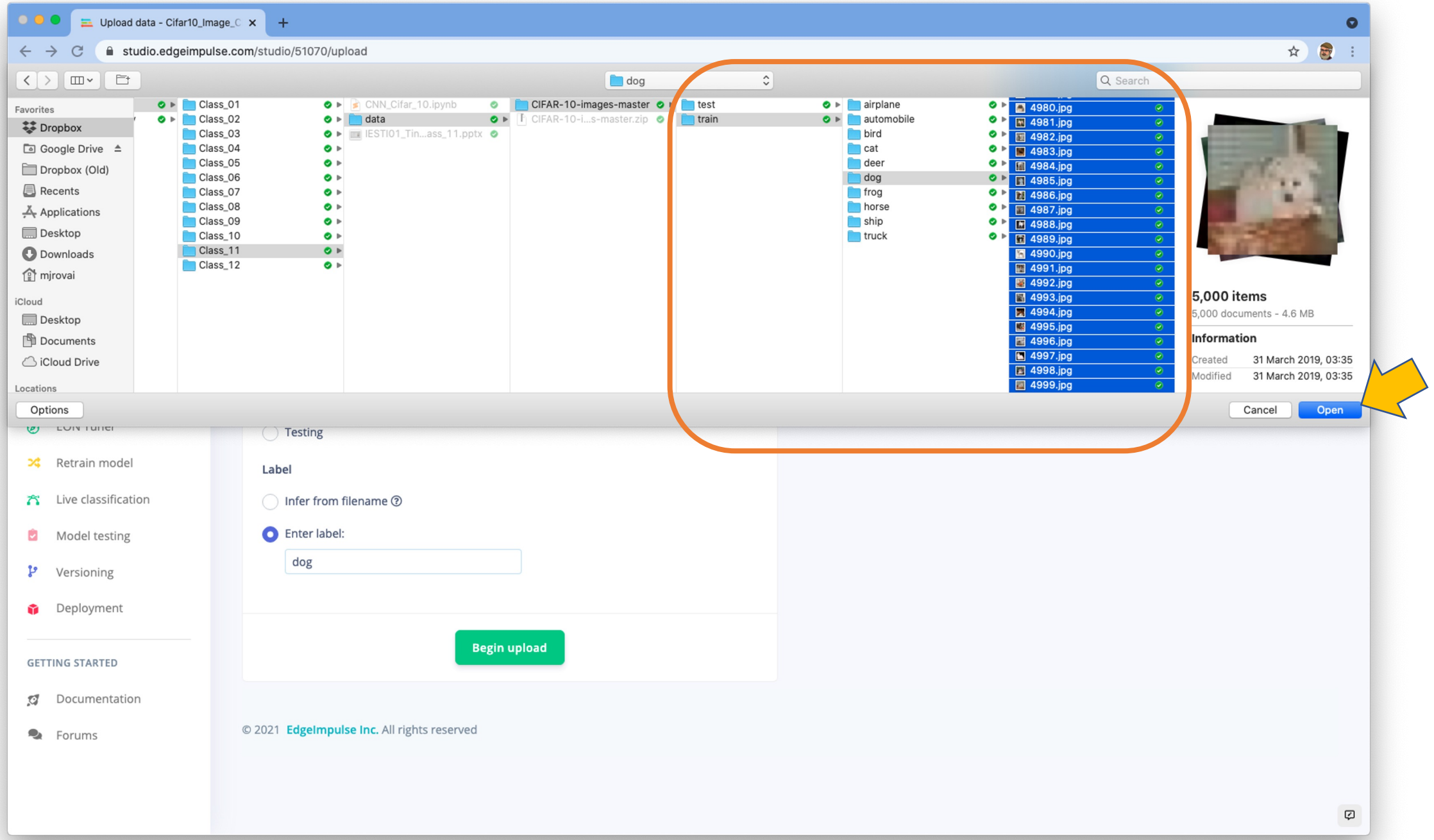
Upload data - Cifar10_Image_C
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dog
Search
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Dropbox
Google Drive
Dropbox (Old)
Recents
Applications
Desktop
Downloads
mjrovai
iCloud
Desktop
Documents
iCloud Drive
Locations
Class_01
Class_02
Class_03
Class_04
Class_05
Class_06
Class_07
Class_08
Class_09
Class_10
Class_11
Class_12
CNN_Cifar_10.ipynb
data
IESTI01_Tin...ass_11.pptx
CIFAR-10-images-master
CIFAR-10-i...s-master.zip
test
train
airplane
automobile
bird
cat
deer
dog
frog
horse
ship
truck
4980.jpg
4981.jpg
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4983.jpg
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4991.jpg
4992.jpg
4993.jpg
4994.jpg
4995.jpg
4996.jpg
4997.jpg
4998.jpg
4999.jpg
5,000 items
5,000 documents - 4.6 MB
Information
Created 31 March 2019, 03:35
Modified 31 March 2019, 03:35
Options
Cancel
Open
Retrain model
Live classification
Model testing
Versioning
Deployment
GETTING STARTED
Documentation
Forums
Testing
Label
Infer from filename
Enter label:
dog
Begin upload
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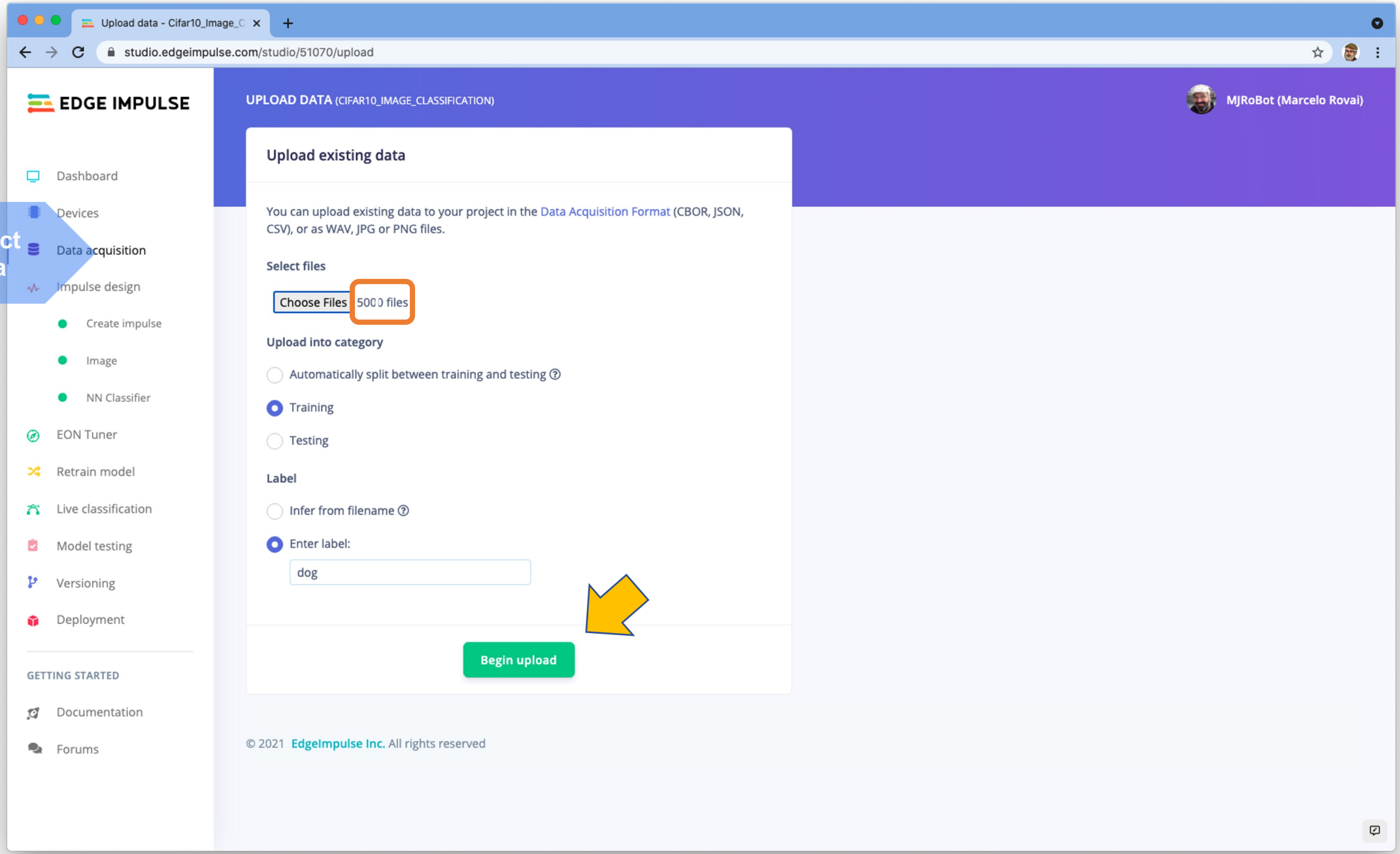
Upload data - Cifar10_Image_C
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UPLOAD DATA (CIFAR10_IMAGE_CLASSIFICATION)
MJRoBot (Marcelo Rovai)
Collect Data
Dashboard
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Create impulse
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EON Tuner
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Upload existing data
You can upload existing data to your project in the Data Acquisition Format (CBOR, JSON, CSV), or as WAV, JPG or PNG files.
Select files
Choose Files
5000 files
Upload into category
Automatically split between training and testing
Training
Testing
Label
Infer from filename
Enter label:
dog
Begin upload
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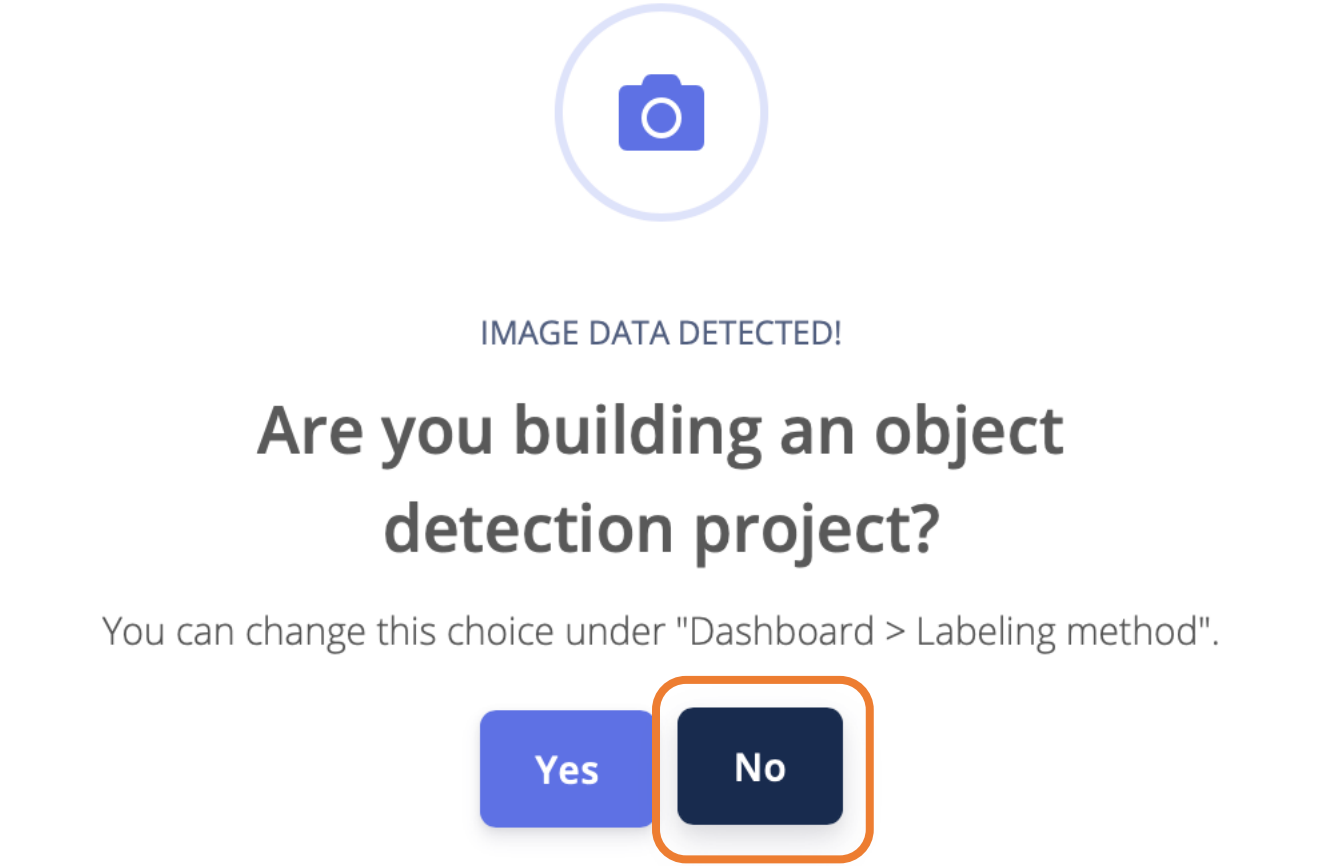
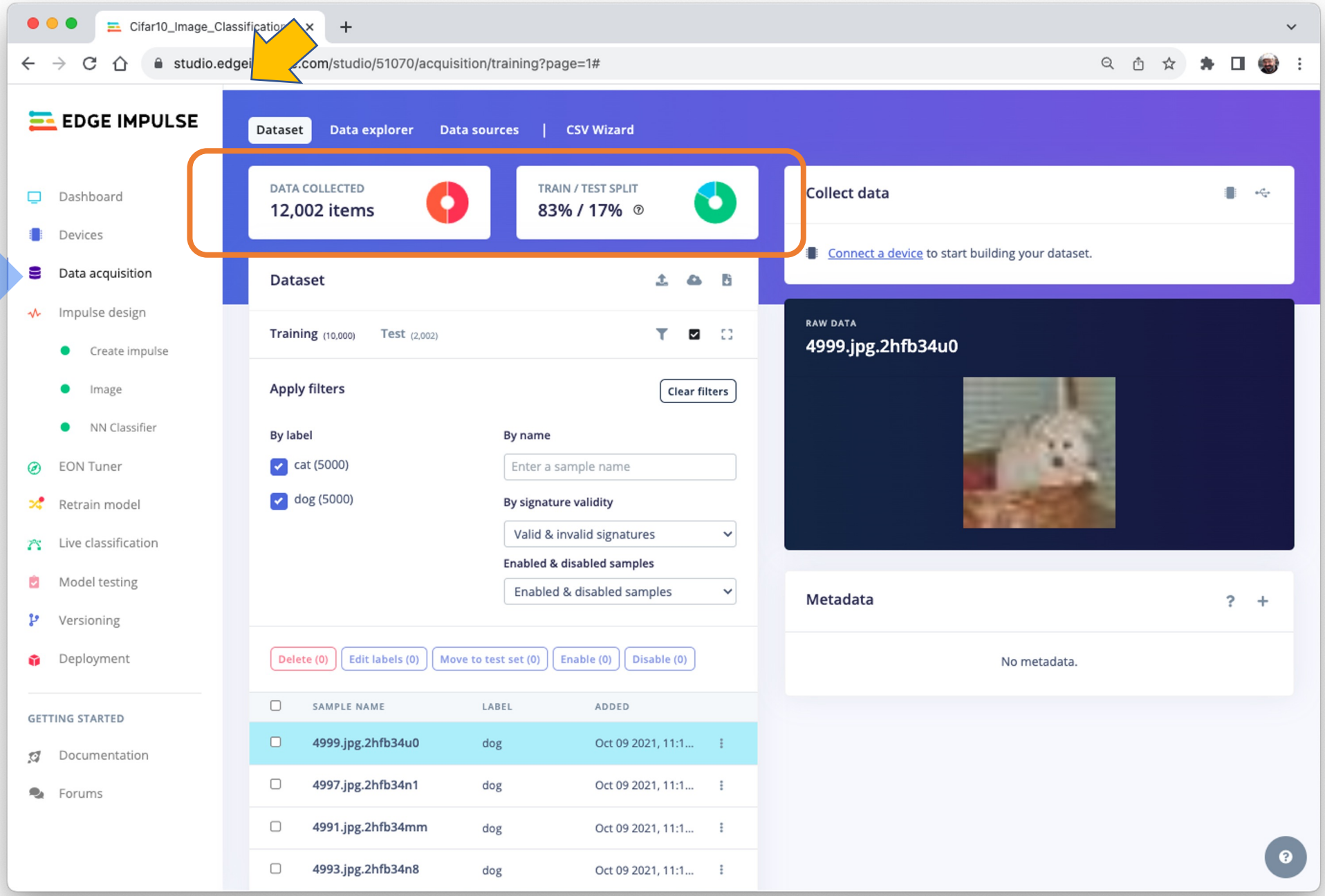
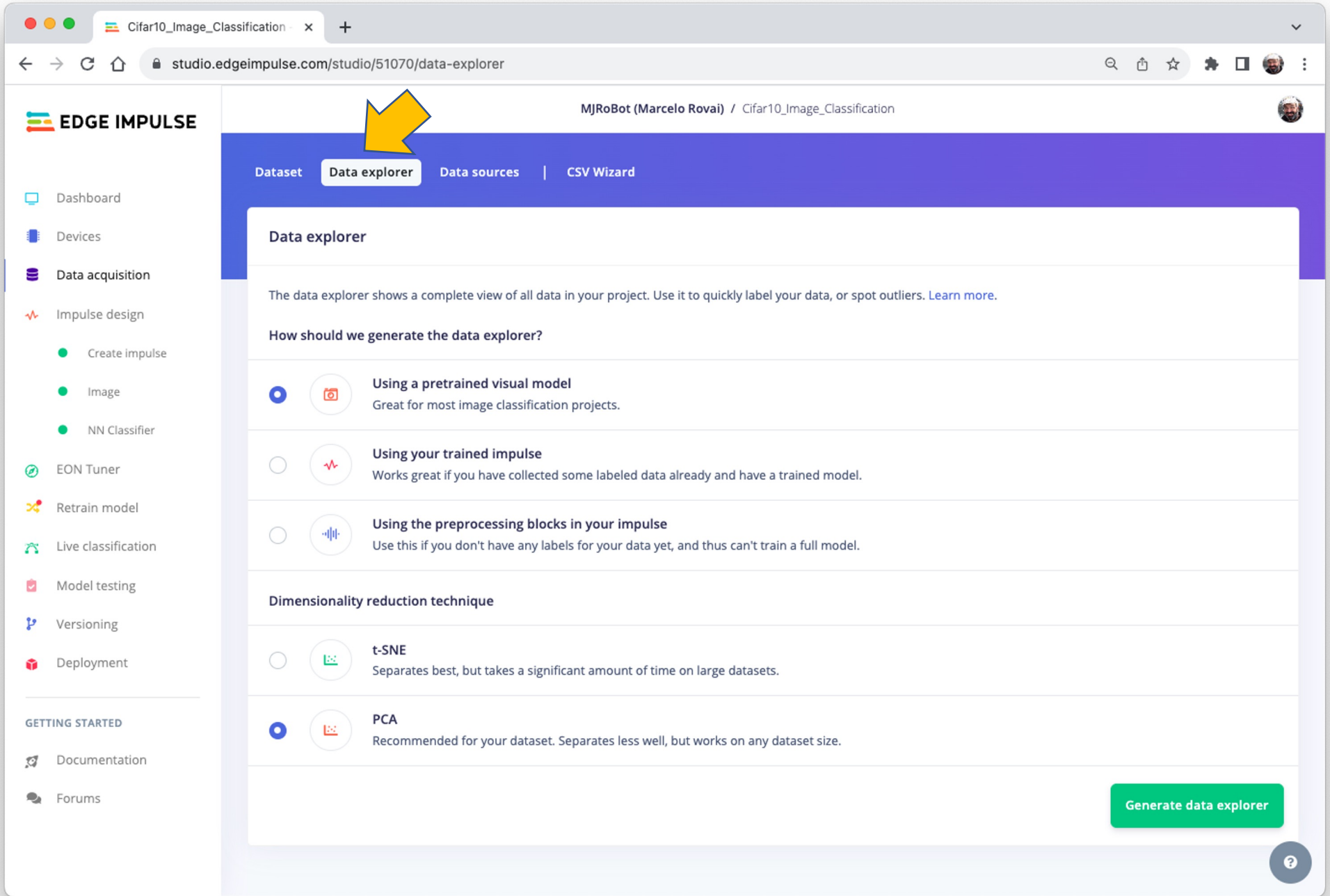


IMAGE DATA DETECTED!
Are you building an object detection project?
You can change this choice under "Dashboard > Labeling method".
Yes
No

Collect Data




Cifar10_Image_Classification
studio.edgeimpulse.com/studio/51070/data-explorer
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MJRoBot (Marcelo Rovai) / Cifar10_Image_Classification
Dataset
Data explorer
Data sources
CSV Wizard
Dashboard
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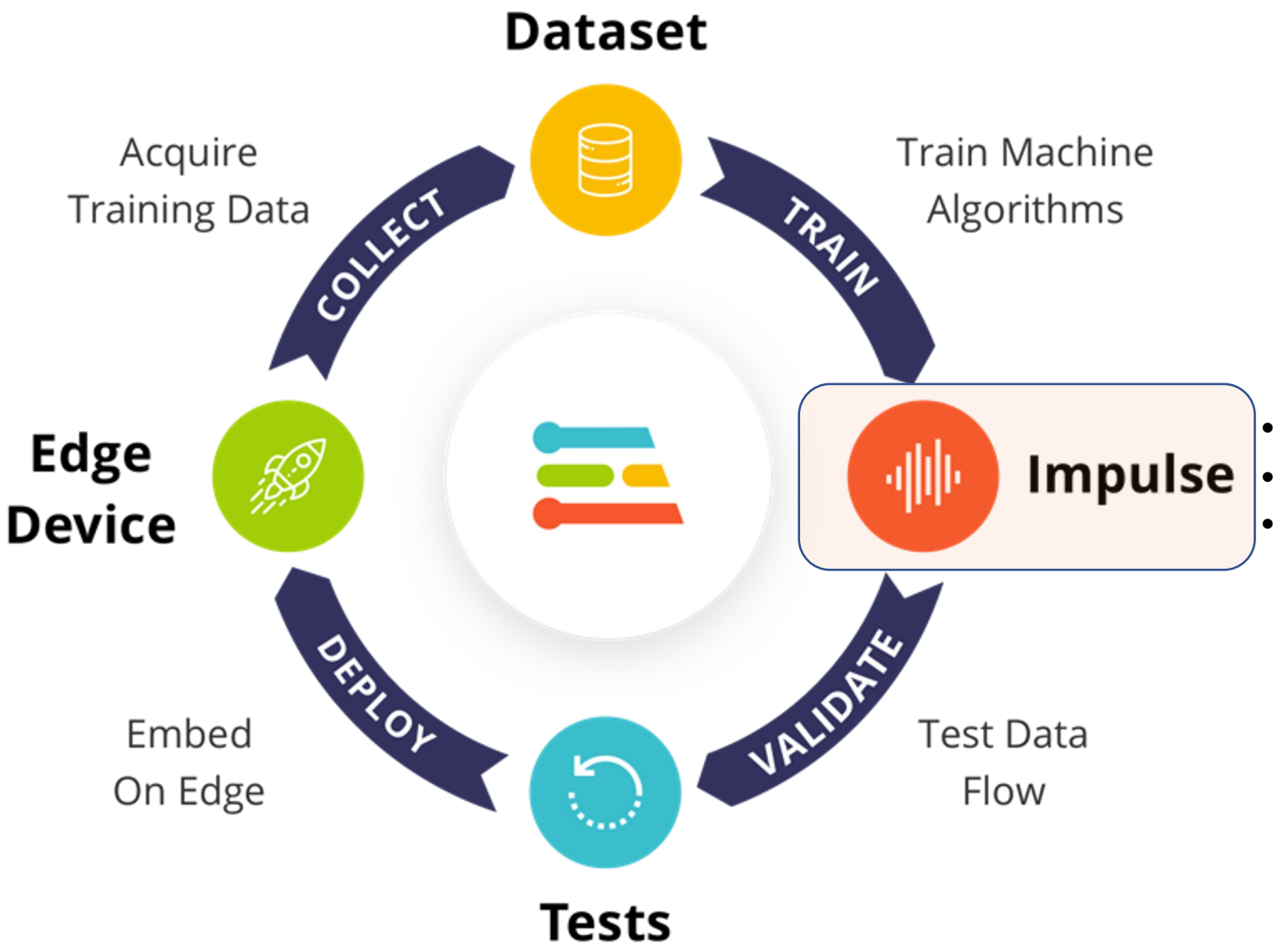
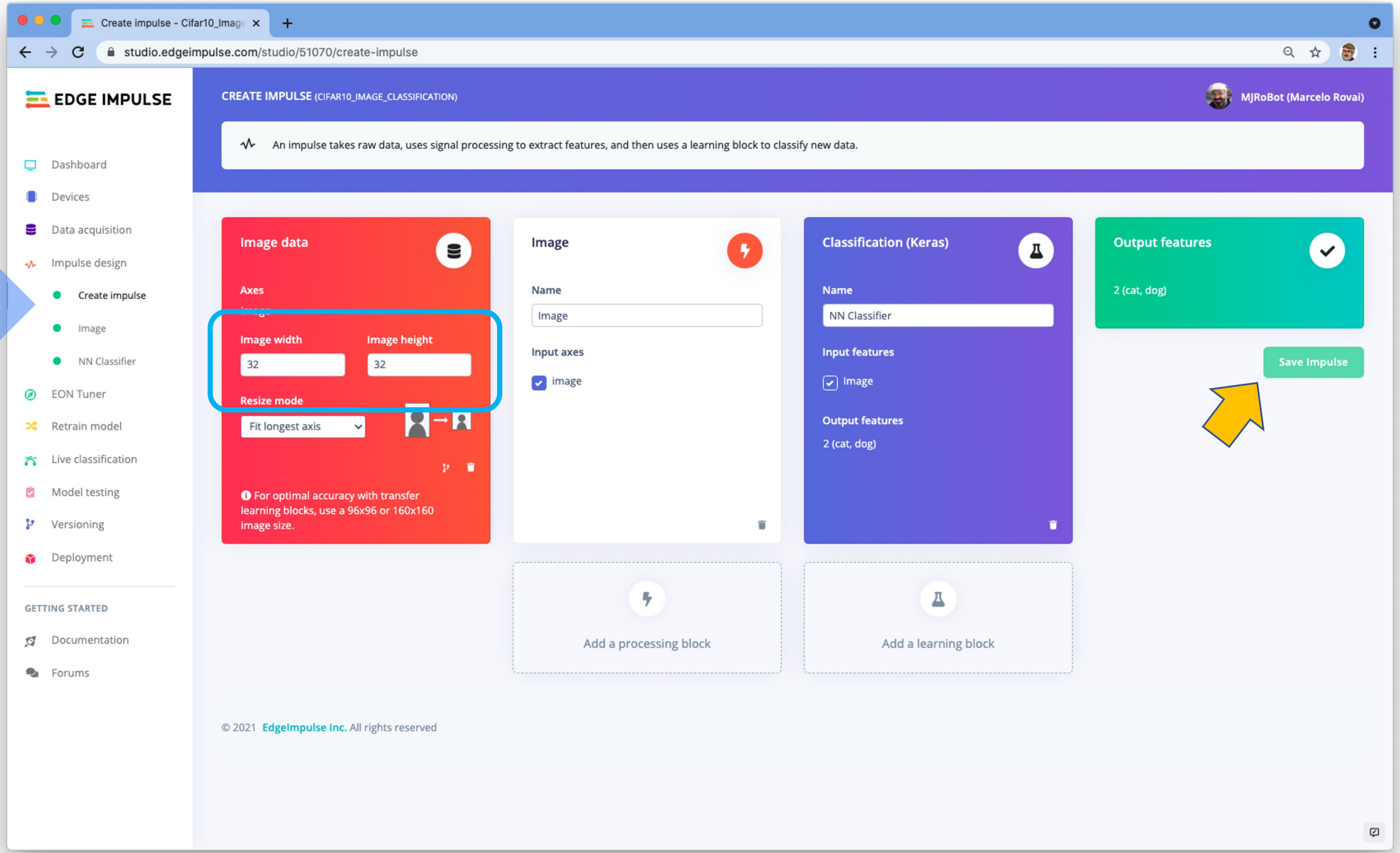
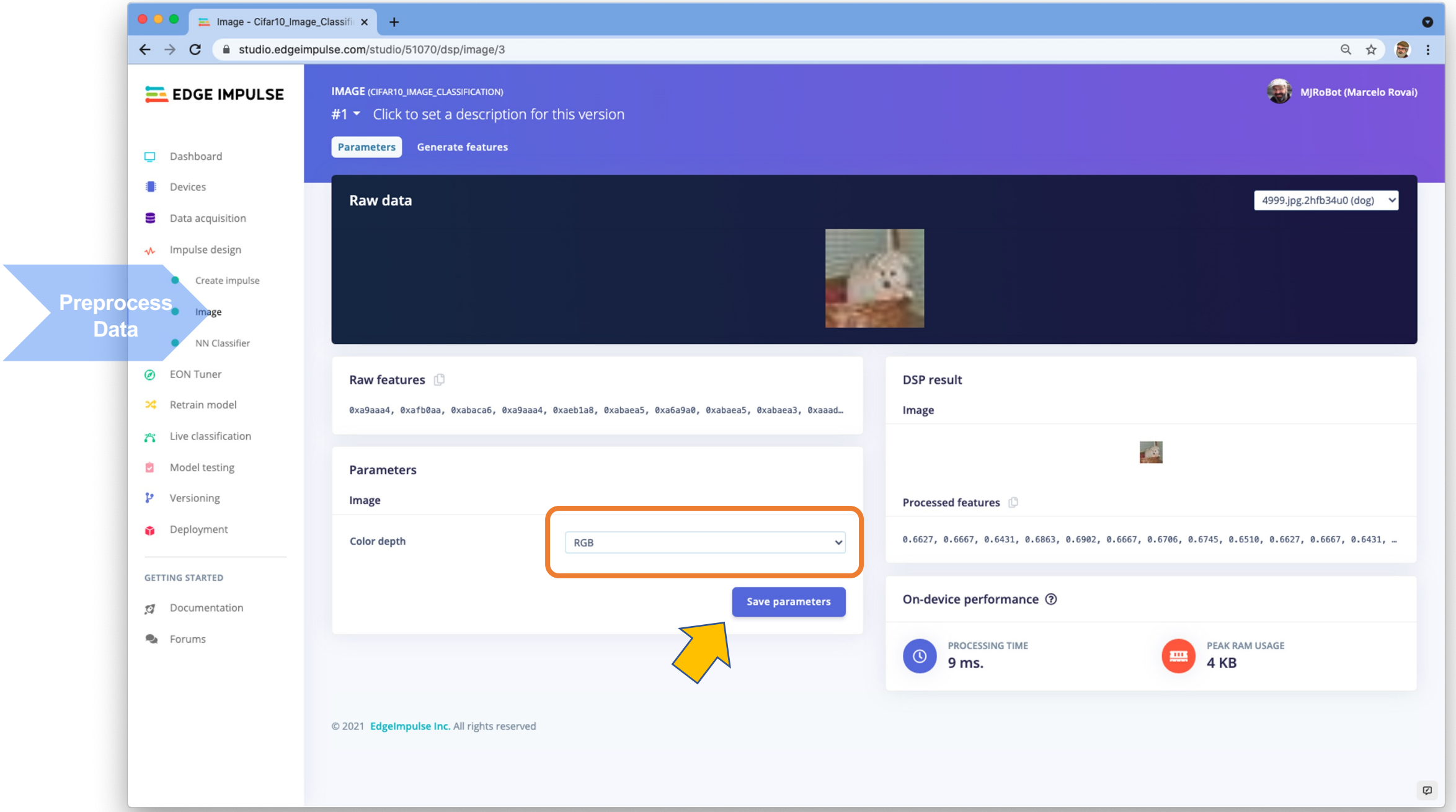
Data explorer
The data explorer shows a complete view of all data in your project. Use it to quickly label your data, or spot outliers. Learn more.
How should we generate the data explorer?
Using a pretrained visual model
Great for most image classification projects.
Using your trained impulse
Works great if you have collected some labeled data already and have a trained model.
Using the preprocessing blocks in your impulse
Use this if you don't have any labels for your data yet, and thus can't train a full model.
Dimensionality reduction technique
t-SNE
Separates best, but takes a significant amount of time on large datasets.
PCA
Recommended for your dataset. Separates less well, but works on any dataset size.
Generate data explorer



- Pre-Processing Data
- Design a Model
- Train a Model



Create Impulse



Preprocess Data

Preprocess Data

Image - Cifar10_Image_Classifi

studio.edgeimpulse.com/studio/51070/dsp/image/3/generate-features

EDGE IMPULSE

- Dashboard
- Devices
- Data acquisition
- Impulse design
  - Create impulse
  - Image
  - NN Classifier
- EON Tuner
- Retrain model
- Live classification
- Model testing
- Versioning
- Deployment

GETTING STARTED

- Documentation
- Forums

IMAGE (CIFAR10_IMAGE_CLASSIFICATION)

#1 Click to set a description for this version

MJRoBot (Marcelo Rovai)

Parameters | Generate features

Training set

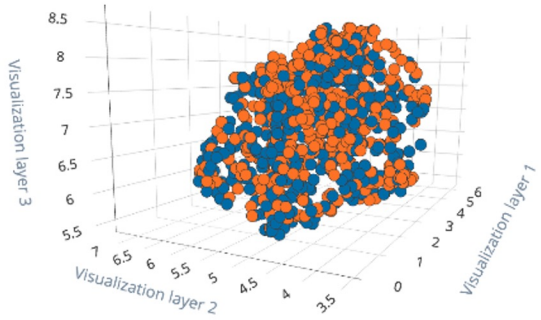
Data in training set	10,000 items
Classes	2 (cat, dog)

Generate features

Feature explorer (10,000 samples)

X Axis: Visualization layer 1 | Y Axis: Visualization layer 2 | Z Axis: Visualization layer 3

cat
dog



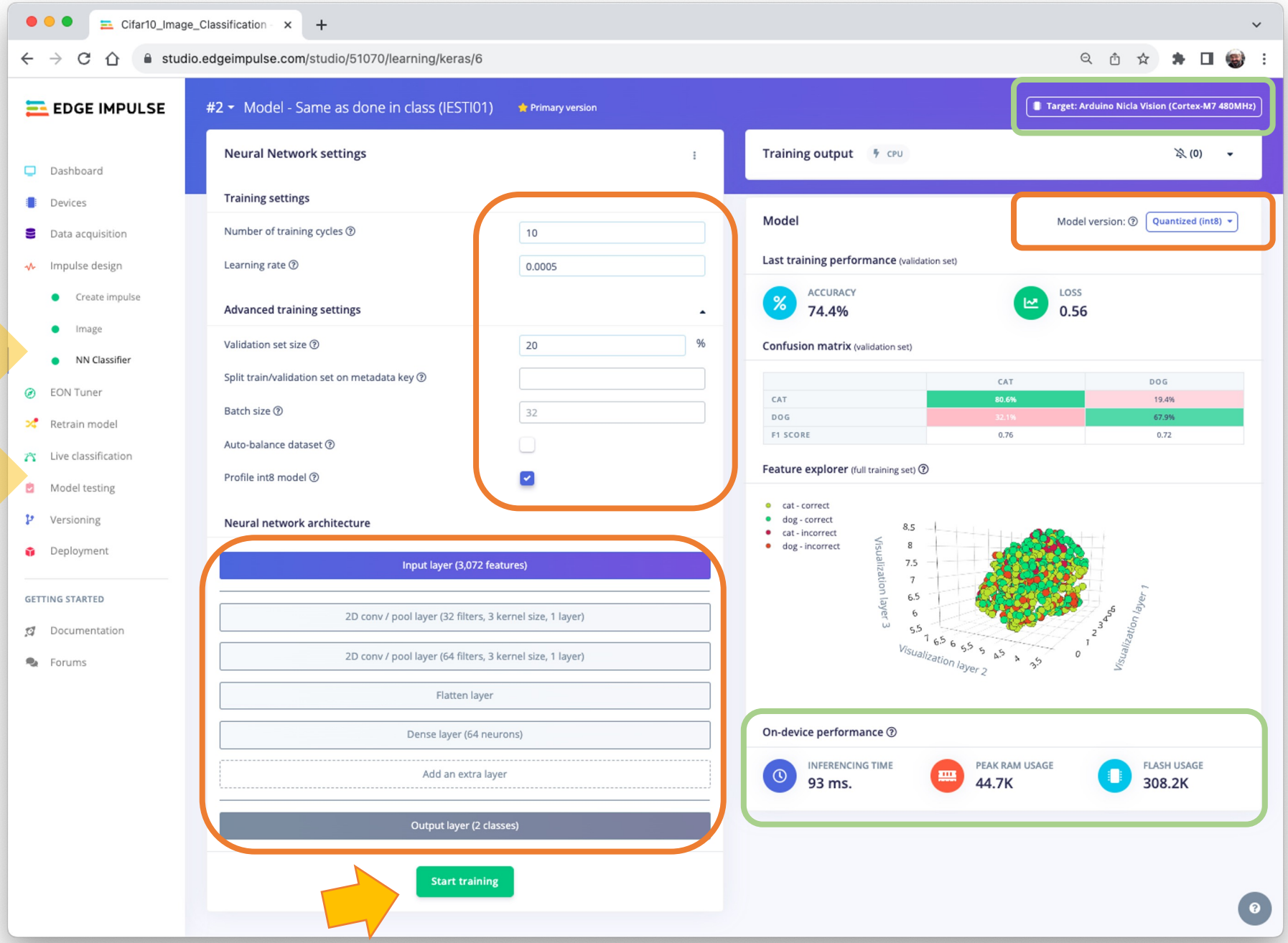
On-device performance

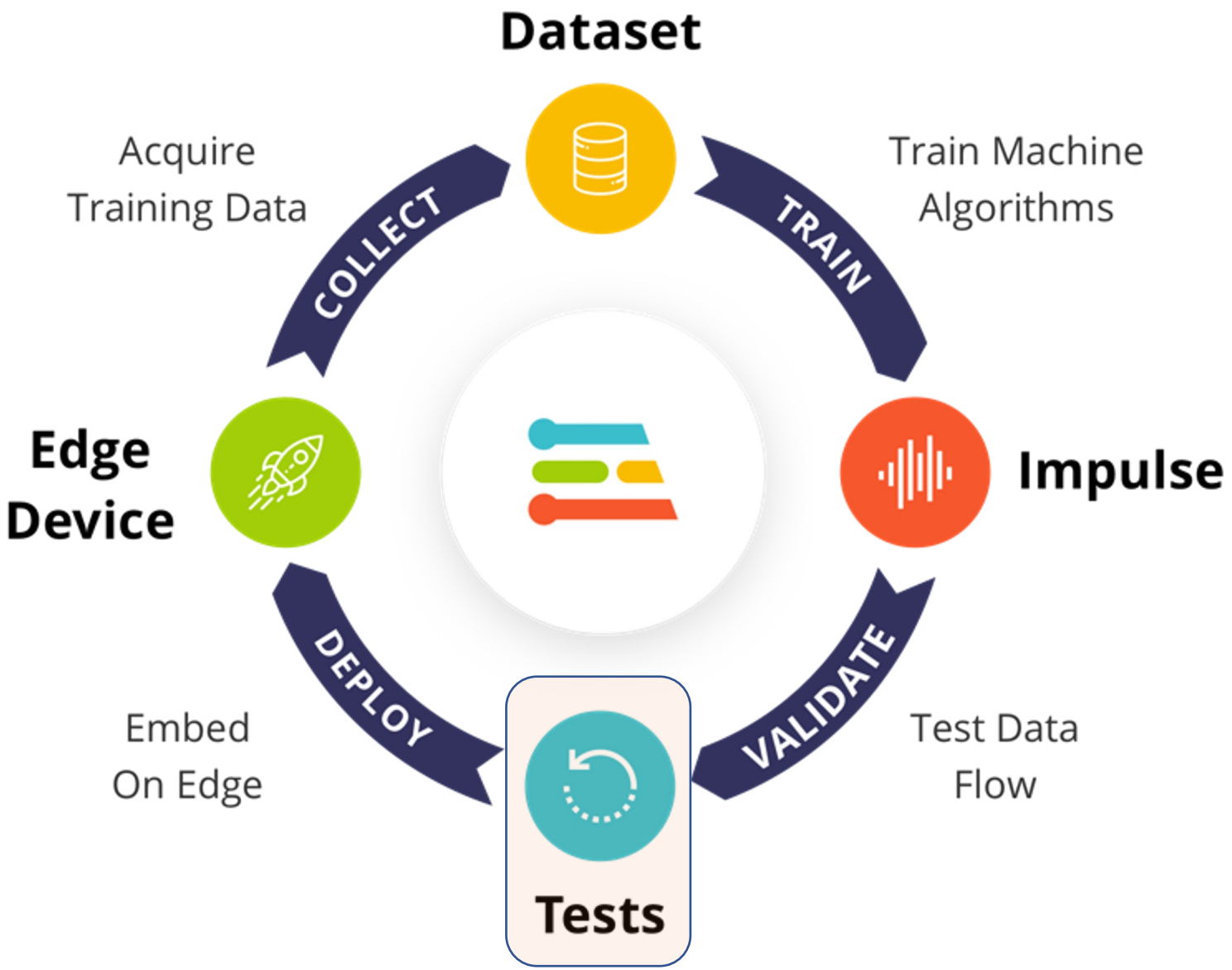
PROCESSING TIME
9 ms.

PEAK RAM USAGE
4 KB

Design a Model

Train a Model





- Pre-Processing Data
- Design a Model
- Train a Model

Model testing - Cifar10_Image | Upload data - Cifar10 Classific

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GETTING STARTED

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Evaluate
Optimize

Test data

Classify all

Set the 'expected outcome' for each sample to the desired outcome to au... ...core the impulse.

SAMPLE NAME	EXPECTED OUTCOME	LENGTH	ACCURACY	RESULT
testing.2hfe5uat	testing	-		1 cat
0999.jpg.2hfb7a...	cat	-	100%	1 cat
0997.jpg.2hfb7a...	cat	-	100%	1 cat
0998.jpg.2hfb7a...	cat	-	100%	1 cat
0996.jpg.2hfb7a...	cat	-	0%	1 uncertain
0993.jpg.2hfb7a...	cat	-	100%	1 cat
0995.jpg.2hfb7a...	cat	-	0%	1 dog
0991.jpg.2hfb7a...	cat	-	100%	1 cat
0994.jpg.2hfb7a...	cat	-	100%	1 cat
0992.jpg.2hfb7a...	cat	-	100%	1 cat
0990.jpg.2hfb79...	cat	-	100%	1 cat
0988.jpg.2hfb79...	cat	-	100%	1 cat
0985.jpg.2hfb79...	cat	-	0%	1 uncertain

Model testing output

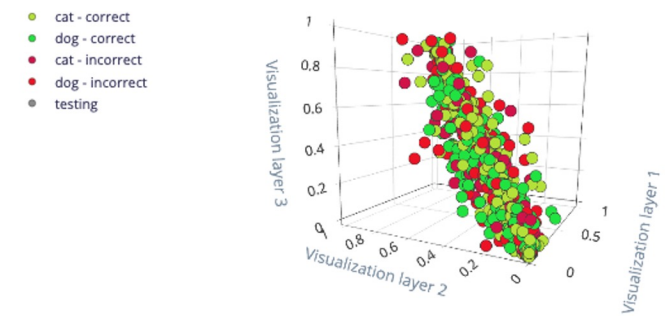
```
Classifying data for NN Classifier...
Copying features from processing blocks...
Copying features from DSP block...
Copying features from DSP block OK
Copying features from processing blocks OK

Classifying data for float32 model...
Scheduling job in cluster...
Job started
Classifying data for NN Classifier OK


Job completed
```

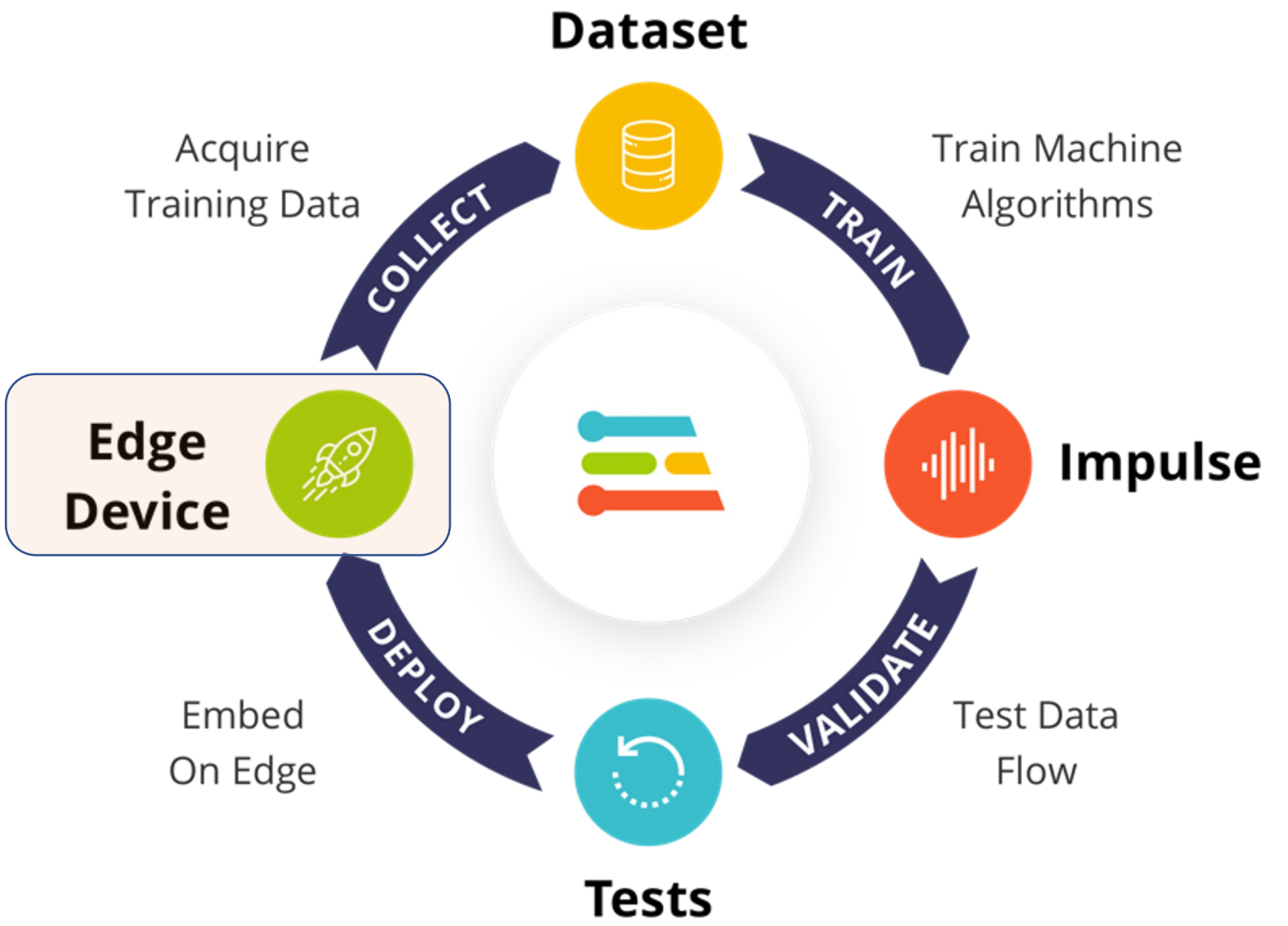
Model testing results

ACCURACY
64.95%

	CAT	DOG	UNCERTAIN
CAT	67.7%	16%	16.3%
DOG	21.2%	62.2%	16.6%
F1 SCORE	0.72	0.70	

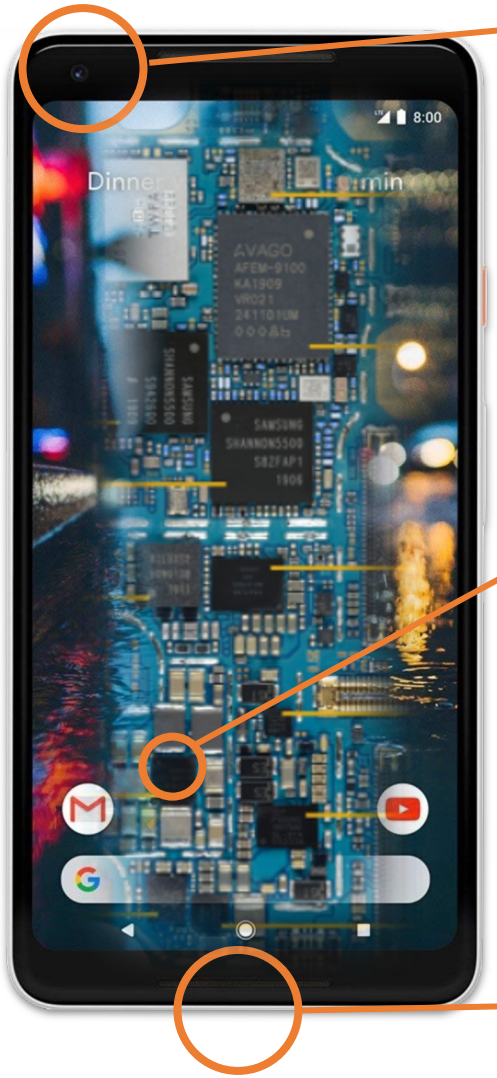
Feature explorer





- Pre-Processing Data
- Design a Model
- Train a Model

Edge Device & Sensors

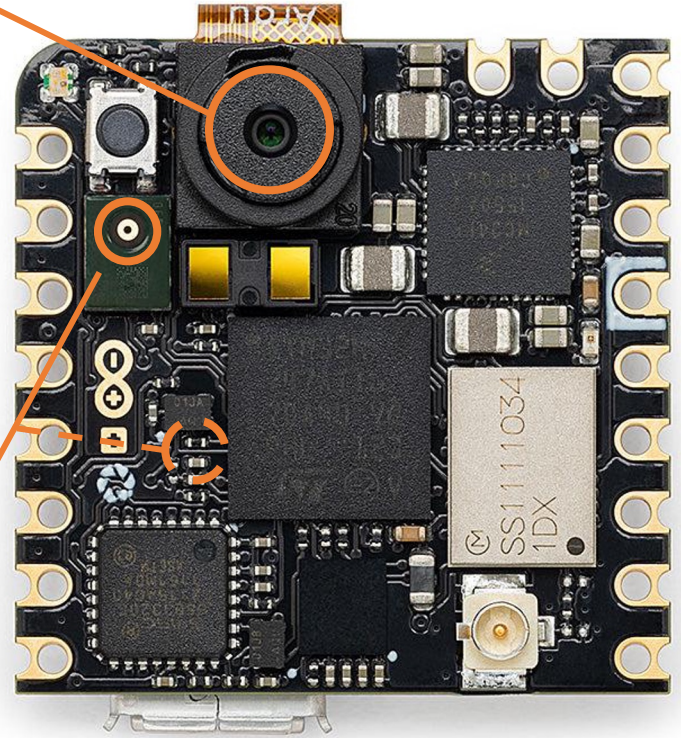


Camera

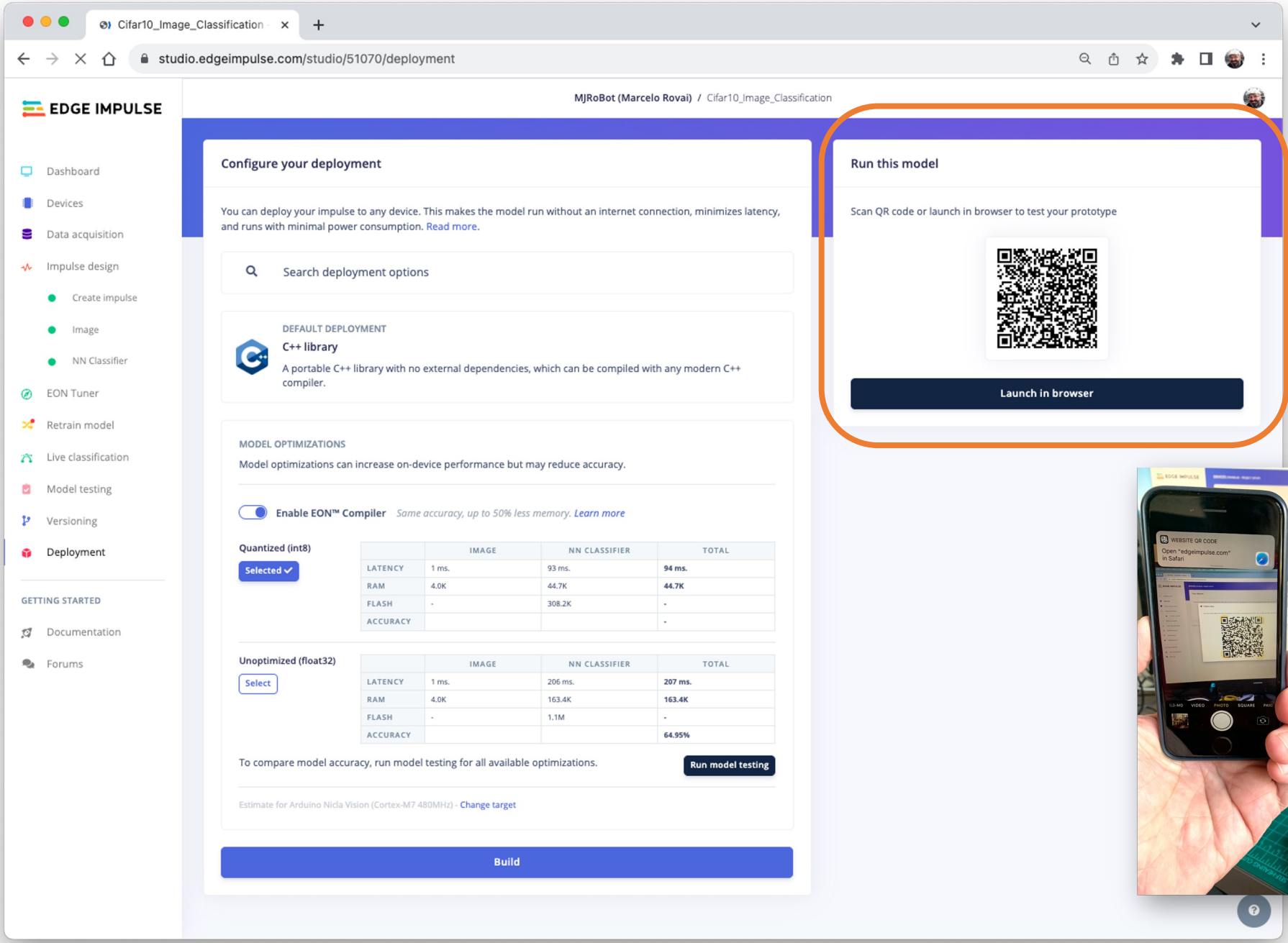
Accelerometer

Gyroscope

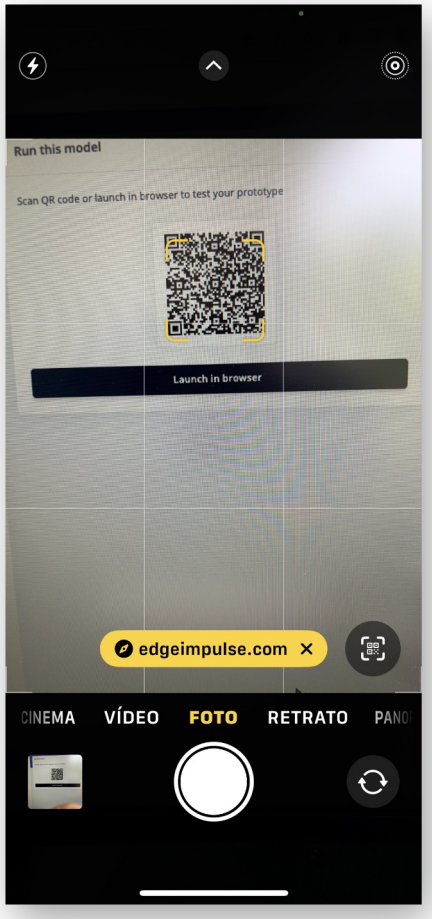
Microphone

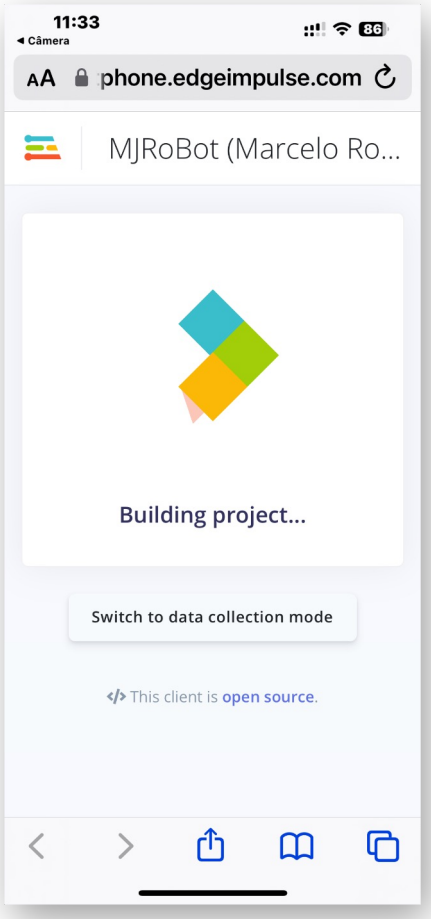


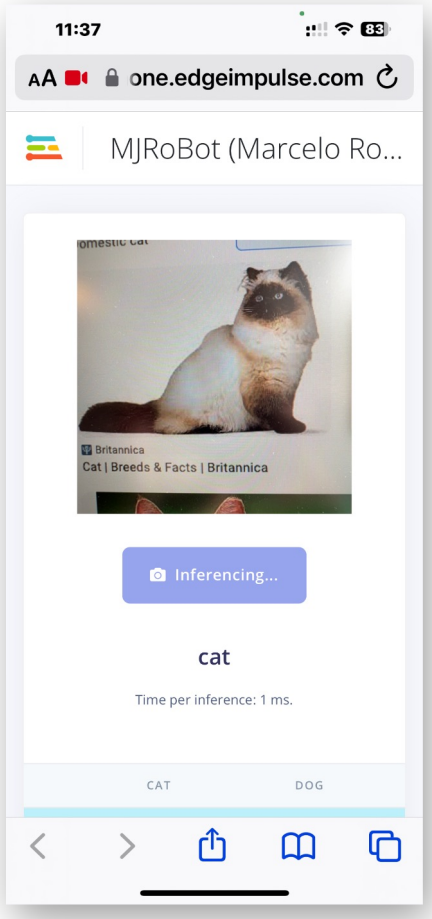
Deploy Model

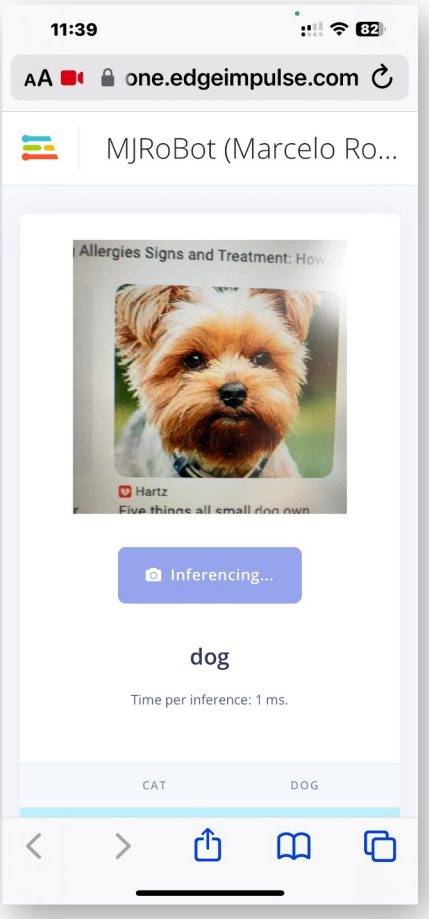


Make Inferences

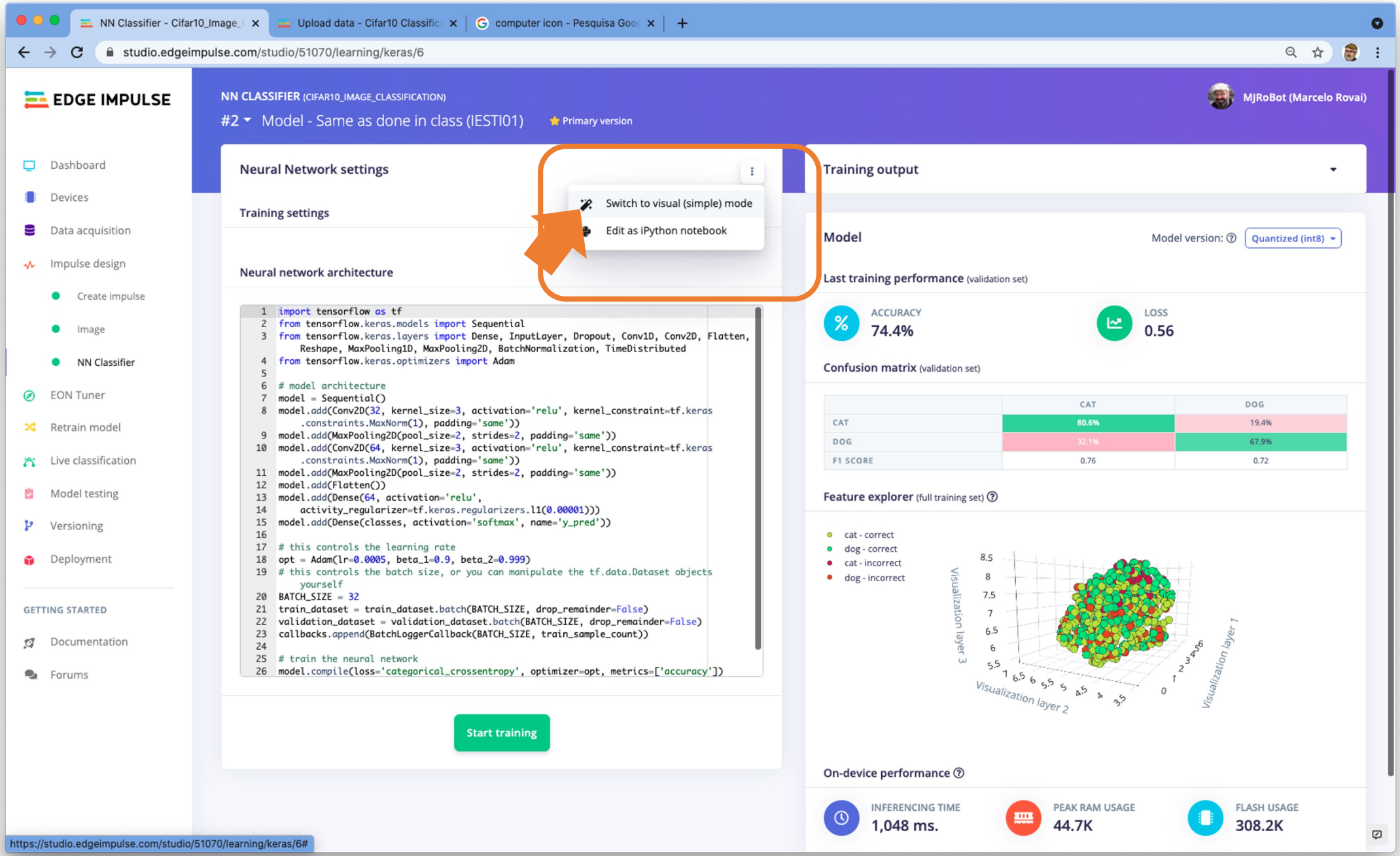




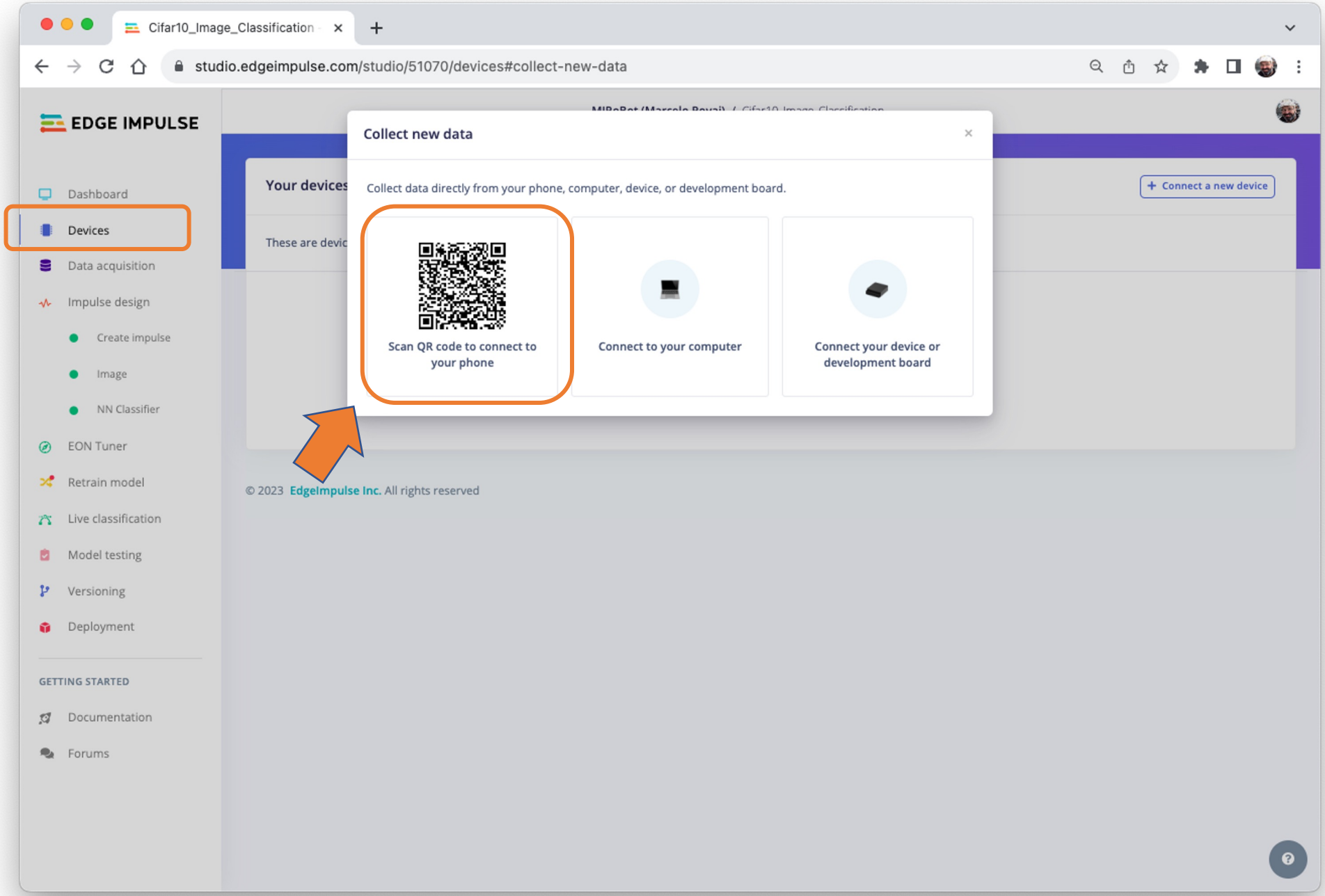




EI Studio “under the hood”


NN Classifier - Cifar10_Image_
Upload data - Cifar10 Classific
computer icon - Pesquisa Goo
studio.edgeimpulse.com/studio/51070/learning/keras/6
EDGE IMPULSE
NN CLASSIFIER (CIFAR10_IMAGE_CLASSIFICATION)
#2 Model - Same as done in class (IESTI01)
Primary version
MJRoBot (Marcelo Rovai)
Dashboard
Devices
Data acquisition
Impulse design
Create impulse
Image
NN Classifier
EON Tuner
Retrain model
Live classification
Model testing
Versioning
Deployment
GETTING STARTED
Documentation
Forums
Neural Network settings
Training settings
Switch to visual (simple) mode
Edit as iPython notebook
Neural network architecture
import tensorflow as tf
from tensorflow.keras.models import Sequential
from tensorflow.keras.layers import Dense, InputLayer, Dropout, Conv1D, Conv2D, Flatten, Reshape, MaxPooling1D, MaxPooling2D, BatchNormalization, TimeDistributed
from tensorflow.keras.optimizers import Adam
# model architecture
model = Sequential()
model.add(Conv2D(32, kernel_size=3, activation='relu', kernel_constraint=tf.keras.constraints.MaxNorm(1), padding='same'))
model.add(MaxPooling2D(pool_size=2, strides=2, padding='same'))
model.add(Conv2D(64, kernel_size=3, activation='relu', kernel_constraint=tf.keras.constraints.MaxNorm(1), padding='same'))
model.add(MaxPooling2D(pool_size=2, strides=2, padding='same'))
model.add(Flatten())
model.add(Dense(64, activation='relu', activity_regularizer=tf.keras.regularizers.l1(0.00001)))
model.add(Dense(classes, activation='softmax', name='y_pred'))
# this controls the learning rate
opt = Adam(lr=0.0005, beta_1=0.9, beta_2=0.999)
# this controls the batch size, or you can manipulate the tf.data.Dataset objects yourself
BATCH_SIZE = 32
train_dataset = train_dataset.batch(BATCH_SIZE, drop_remainder=False)
validation_dataset = validation_dataset.batch(BATCH_SIZE, drop_remainder=False)
callbacks.append(BatchLoggerCallback(BATCH_SIZE, train_sample_count))
# train the neural network
model.compile(loss='categorical_crossentropy', optimizer=opt, metrics=['accuracy'])
Start training
Training output
Model
Model version:
Quantized (int8)
Last training performance (validation set)
ACCURACY
74.4%
LOSS
0.56
Confusion matrix (validation set)
CAT
DOG
F1 SCORE
80.6%
19.4%
32.1%
67.9%
0.76
0.72
Feature explorer (full training set)
cat - correct
dog - correct
cat - incorrect
dog - incorrect
Visualization layer 3
Visualization layer 2
Visualization layer 1
On-device performance
INFERENCING TIME
1,048 ms.
PEAK RAM USAGE
44.7K
FLASH USAGE
308.2K
https://studio.edgeimpulse.com/studio/51070/learning/keras/6#

Connect device for data capture
Mobile Phone


Cifar10_Image_Classification
studio.edgeimpulse.com/studio/51070/devices#collect-new-data
EDGE IMPULSE
Dashboard
Devices
Data acquisition
Impulse design
Create impulse
Image
NN Classifier
EON Tuner
Retrain model
Live classification
Model testing
Versioning
Deployment
GETTING STARTED
Documentation
Forums
Your devices
These are devic
+ Connect a new device
Collect new data
Collect data directly from your phone, computer, device, or development board.
Scan QR code to connect to your phone
Connect to your computer
Connect your device or development board
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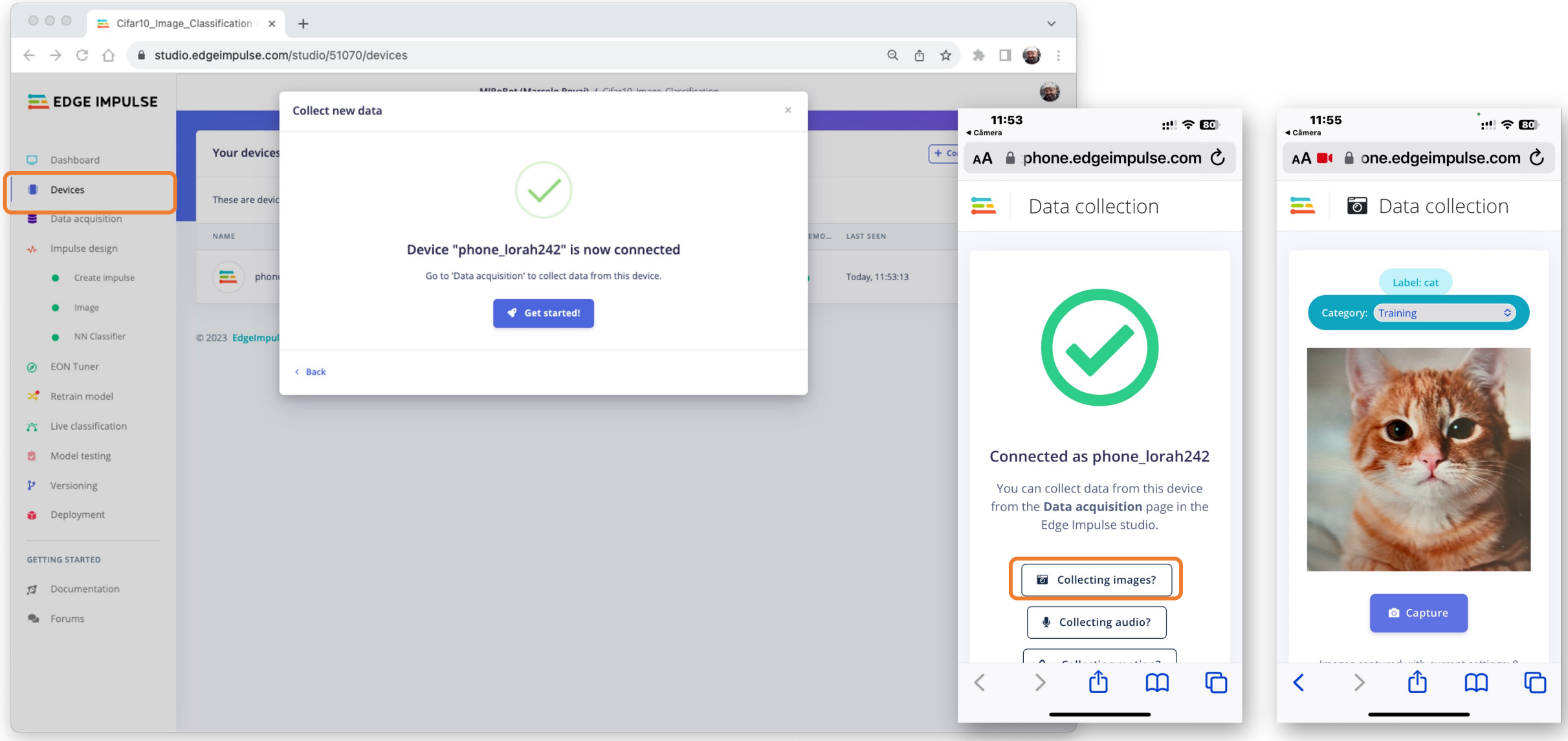
Cifar10_Image_Classification
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EDGE IMPULSE
Dashboard
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Impulse design
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Retrain model
Live classification
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Versioning
Deployment
GETTING STARTED
Documentation
Forums
Your devices
NAME
LAST SEEN
Today, 11:53:13
Collect new data
Device "phone_lorah242" is now connected
Go to 'Data acquisition' to collect data from this device.
Get started!
Back
11:53
phone.edgeimpulse.com
Data collection
Connected as phone_lorah242
You can collect data from this device from the Data acquisition page in the Edge Impulse studio.
Collecting images?
Collecting audio?
11:55
one.edgeimpulse.com
Data collection
Label: cat
Category: Training
Capture

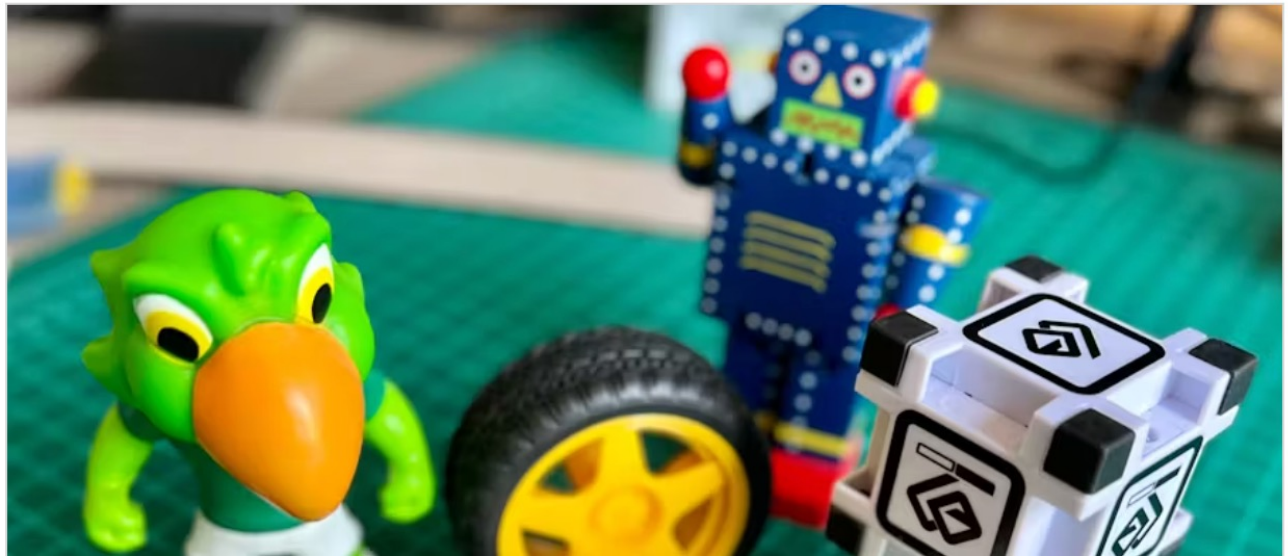
Using Edge Impulse and the Grove Vision AI Module V2

MJRoBot (Marcelo Rovai)
Published February 22, 2024 © Apache-2.0

Computer Vision at the Edge with Grove Vision AI Module V2

Exploring Computer Vision applications such as Image Classification, Object Detection, and Pose estimation.

Intermediate | Full instructions provided | 8 hours | 2,658



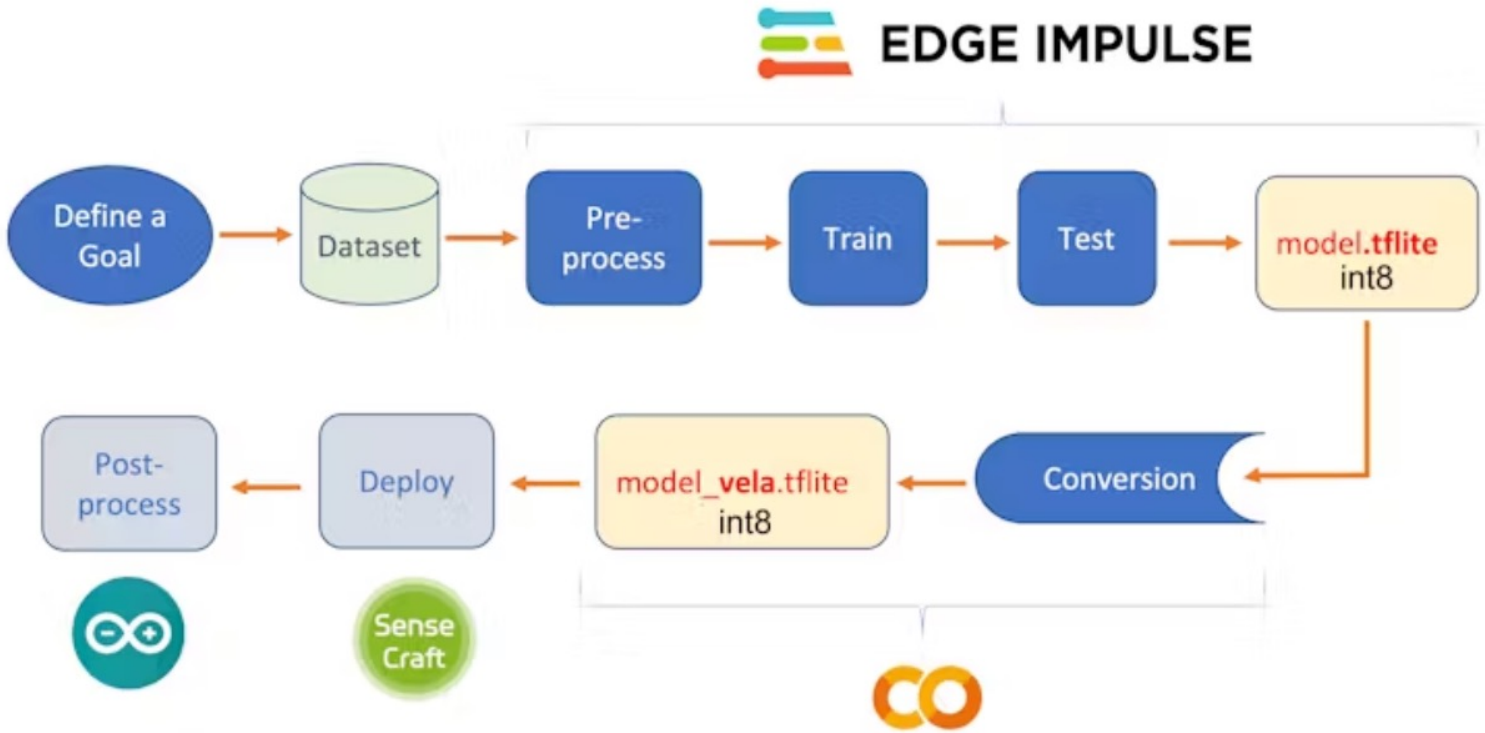
https://www.hackster.io/mjrobot/computer-vision-at-the-edge-with-grove-vision-ai-module-v2-0003c7?f=1

4. An Image Classification Project from Scratch

Introduction

So far, we have explored several computer vision models previously uploaded by Seeed Studio. Let's develop our CV project from scratch, starting with image classification.

Below, we can see the project's main steps and where we will do it:



Now, we will use Vela, a tool to compile our quantized int8 TensorFlow Lite neural network model (`ei-periquito-vs-robot-int8.tflite)` into an optimized version that can run on an embedded system containing an Arm Ethos-U NPU (`ei-periquito-vs-robot-int8_vela.tflite`).

The optimized model will contain TensorFlow Lite Custom operators for those parts of the model that the Ethos-U NPU can accelerate. Parts of the model that cannot be accelerated are left unchanged and will run on the Cortex-M series CPU using an appropriate kernel (such as the Arm optimized CMSIS-NN kernels). After compilation, the optimized model can only be run on an Ethos-U NPU embedded system, such as the Grove AI Vision (V2).

On a Google CoLab, run the lines below:

```
!pip install ethos-u-vela
!!vela --version
```

We should get: `3.10.0`

Deploy model on the SenseCraft Web-Toolkit

On SenseCraft-Web-Toolkit, use the blue button at the bottom of the page: `[Upload Custom AI Model]`. A window will pop up. Enter the Model file that you downloaded to your computer from Google Colab, choose a Model Name, and enter with labels (ID:Object):

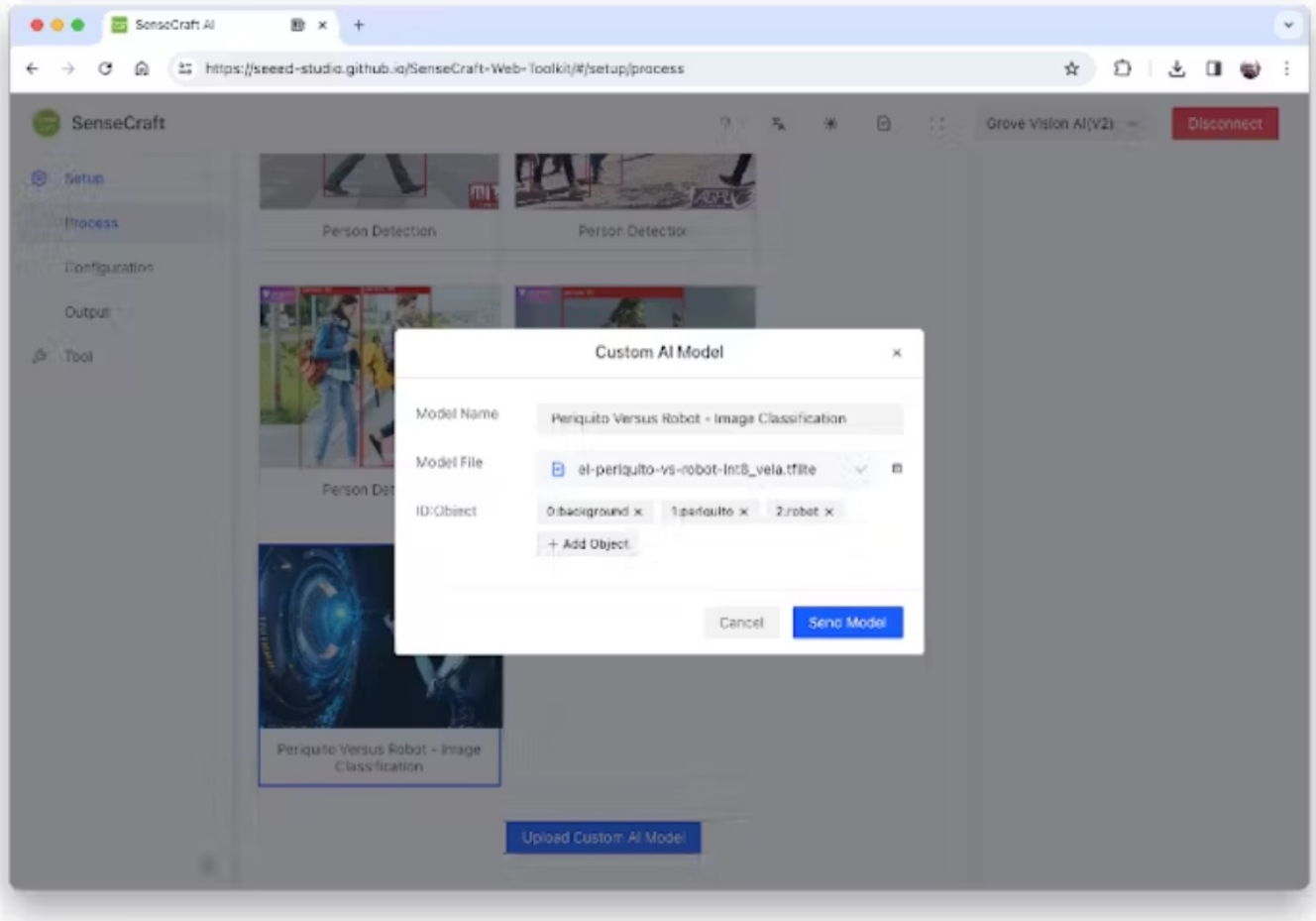
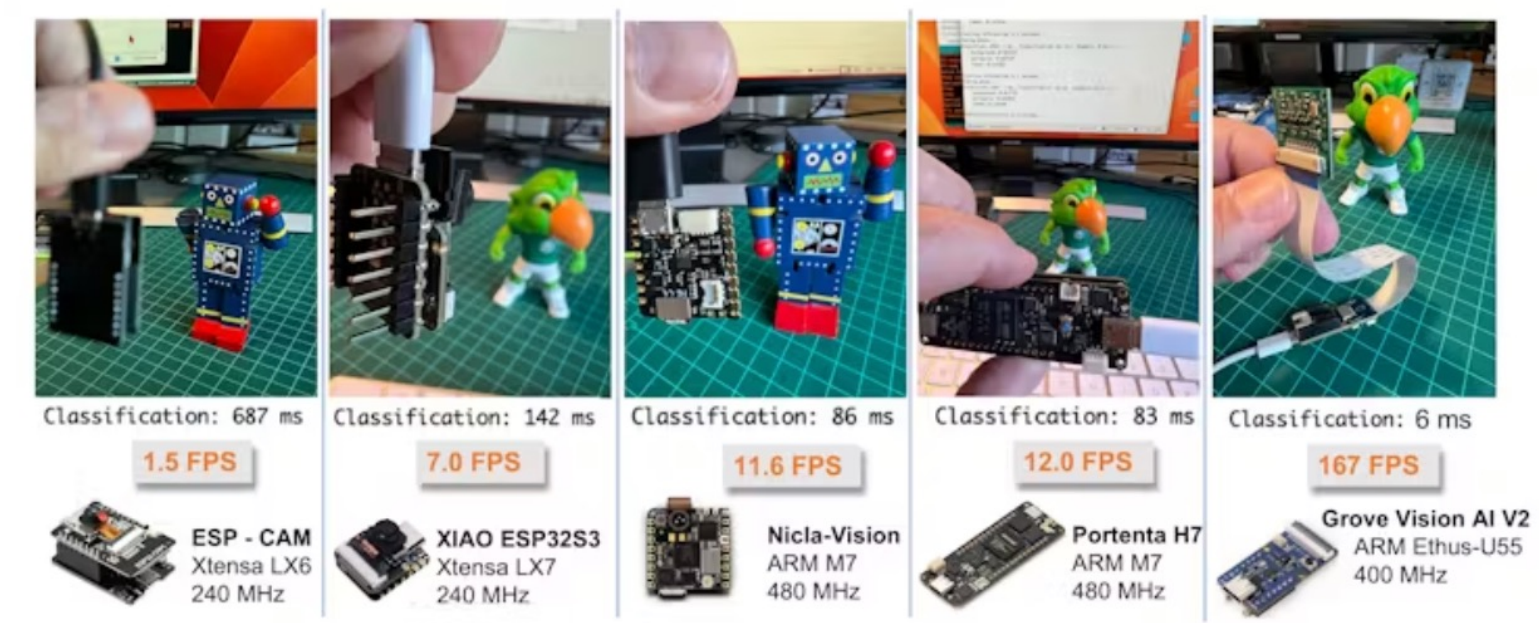


Image Classification (non-official) Benchmark

Several development boards can be used for embedded machine learning (tinyML), and the most common ones (so far) for Computer Vision applications (with low energy), are the ESP32 CAM, the Seeed XIAO ESP32S3 Sense, the Arduinos Nicla Vison, and Portenta.

Using the opportunity, a similarly trained model MobilenetV2 96x96, but with an alpha 0.1, was deployed on the ESP-CAM, the XIAO, and Portenta (in this one, the model was trained using grayscaled images to be compatible with its camera). Here is the result:



Thanks