

The Road to Artificial Intelligence: From Sensors to Concepts to Analogies

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Problem Setup

Related Work

Building a
Cortex

Cortex beyond
Perception

Conclusion

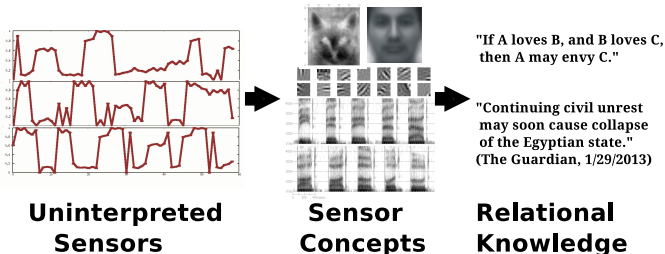
Problem setup

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Big problem for AI: **Knowledge Acquisition Bottleneck**

- “Difficult” problems in AI easy for 5-year-old.
 - Language, object recognition, climbing stairs, story understanding.
 - These rely on “common sense” knowledge.
- Where does knowledge come from?
 - Can hand-code knowledge. (Expensive and brittle!)
 - Can *learn* knowledge.

Q1: How can machines learn knowledge from uninterpreted data?



Problem setup: Uninterpreted data?

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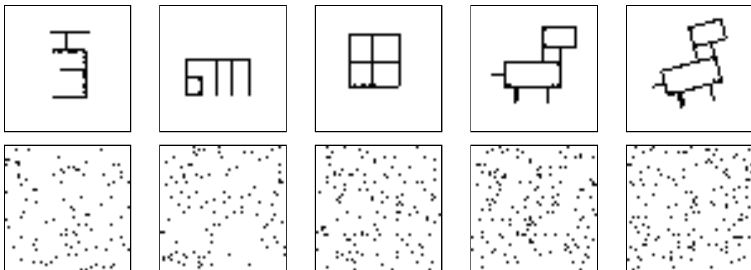
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Computer sees this:

{ S0002=1, S0017=1, S0048=1, S0055=0, S0056=1, S0117=1,
S0175=1, S0180=0, S0197=1, S0233=0, S0269=1, S0284=1,
S2214=1, S2218=1, S2227=1, S2247=1, S2258=0, S2308=1,
S2325=1, S2344=1, S2355=1, S2363=1, S2398=1, S2406=1,
S0000=0, S0001=0, S0003=0, etc.... (2,473 more sensors) }

Why uninterpreted?

We know some vision, but what about new senses (*modalities*)?

Seismic, Infrared, Sonar, Traffic Speed Sensors, etc.

(In Part 2 of this talk, topology *must* be learned.)

Problem setup: Invariance

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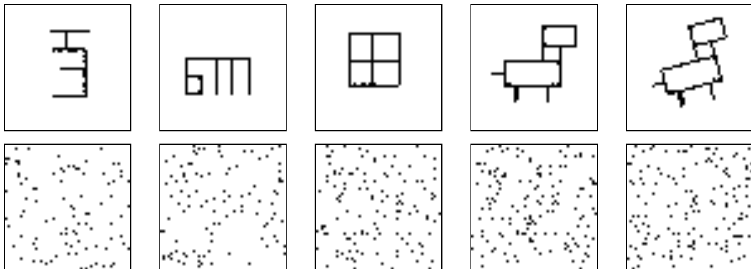
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Invariance

- “Same” shape though nearly disjoint pixels.
- Scale, Translation, Shading, etc.

Problem addendum: Invariance

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Q1: How can machines learn knowledge from uninterpreted data?

Q2: How can machines learn *invariant* concepts from uninterp. data?

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Given lots of images, learn **visual objects**

invariant to **translation, rotation, scale, shading**, etc.

Given large speech stream, learn **phonemes** and **words**

invariant to **pitch, cadence, accent**, etc.

Other modalities? Seismic, Sonar

A core algorithm for concept learning?

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Problem Setup

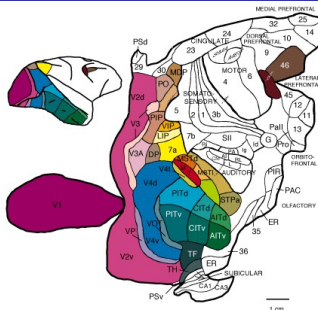
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*Flattened
Macaque
Brain*



Mountcastle, 1978:

“Cortex (memory & cognition) is 2D sheet that looks the same everywhere.”

Assumptions:

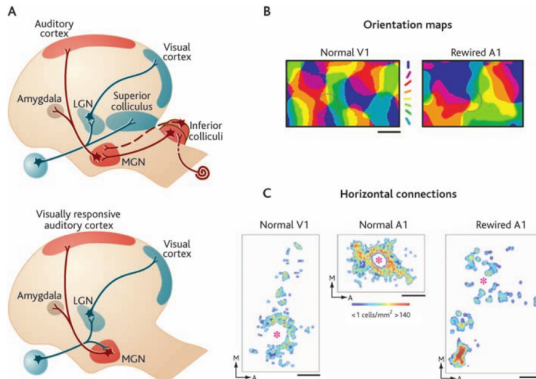
- 1 Memory is **one** algorithm repeated many times (“cortical column”).
- 2 This algo is basic engine of intelligence.
- 3 **Modality independence** is possible and important.
Audio, Video, Image, Sonar, etc. (This matters for higher cognition.)
- 4 There is objective information-theoretic metric for concept utility.

Not constrained by neuroscience, but nice to have existence proof.

Existence Proof: Newborn Ferret Cortex

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Newborn ferret *auditory* cortex can learn vision! (Sur & Rubenstein, 2005)



Difference between brains of Mice and Men:

- Both have same basic architecture
- Humans just have (significantly) larger cortex
- So, higher cognition uses same algo as perception? **How?**

Problem, rephrased

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Q1: How can machines learn knowledge from uninterpreted data?

Q2: How can machines learn invariant concepts from uninterp. data?

Q3: How can we implement a "cortex"?

- Given vision, learn objects...
- Given speech, learn phonemes and words...
- Given seismic or sonar learn ??...
- ...all with relevant invariances.



Problem Setup

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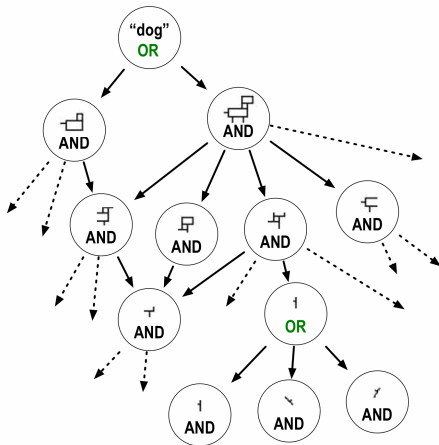
Cortex beyond
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Cortex: Invariant Representation

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Invariant recognition **HMax** (Riesenhuber and Poggio, 1999):

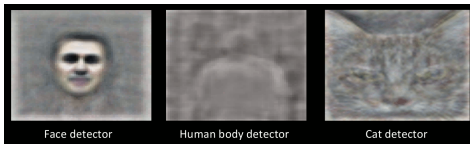


Uses layers of "AND"s and "OR"s.

Cortex: Deep Learning (Le et al., 2012)

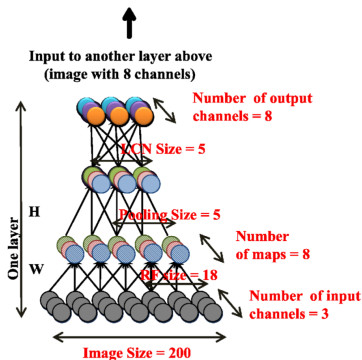
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Unsupervised learning of invariant concepts in images



Cortex: Deep Learning (Le et al., 2012)

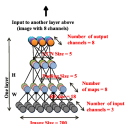
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- 9 layers of nodes: 3 × (AND, OR, Normalization)
- Search in weight space to minimize:
Reconstruction-Cost (compression) + Sparsity-Constraint ("OR" units off)
- 1 billion tunable parameters
- 10,000,000 200x200 images from YouTube (1 image per video)

Cortex: Deep Learning (Le et al., 2012)

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Great work...

- Learns invariant concepts without being told explicitly. (Unlike hand-built invariant features (e.g., SIFT or HOG))
- Outperforms SIFT & HOG: 9.5% → 15.8% on ImageNet
- Why? Learns other invariances (shading, *out of plane* rotation)

...but room for improvement

- Doesn't work off the shelf, like Ferret
 - E.g., Action Recognition in Videos (needs new structures)
 - Implicitly told system about vision in structure of network
 - Needs new structure for learning speech data
- Would be nice if structure could be *learned* in addition to parameters.

Learning Features

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“Chunker” Algorithm: (Pickett, 2011)

- Input uninterpreted data (e.g., raw sensors)
- Learn hierarchy of features
- Use info. theory constraints (probabilistic compression)
- Iteratively **chunks** (for ANDs) and **merges** (for ORs)

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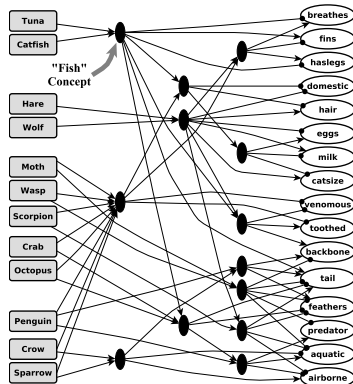
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Animals

(Toy example from U.C. Irvine ML Repository)

Name	hair	feathers	eggs	...
aardvark	1	0	0	...
antelope	1	0	0	...
bass	0	0	1	...
bear	1	0	0	...
...				
worm	0	0	1	...
wren	0	1	1	...



Chunking Patches from Photos

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Input: 50x50 Image Patches (uninterpreted)



Some Concepts Learned



Concepts learned from chunking not only compress data, but also:

- Are useful for semi-supervised learning. (Pickett, 2011)
- Can produce useful macro-actions in Reinforcement Learning (Pickett & Barto 2002).

Learning ORs: Merging

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- Merging finds “OR”s or Equivalence Classes
- Interchangeable concepts form OR
- Find ORs by chunking context

Problem Setup

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A	$P(ran A)$	$P(sat A)$	$P(dog A)$	$P(cat A)$	$P(meow A)$
<i>ran</i>	1.00	0.02	0.23	0.32	0.01
<i>sat</i>	0.01	1.00	0.21	0.34	0.03
<i>dog</i>	0.45	0.37	1.00	0.03	0.02
<i>cat</i>	0.41	0.39	0.04	1.00	0.30

$dog \vee cat$	0.43	0.38			
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To date: Recovers small artificial grammars (Pickett, 2011).

Current work: scaling this up to images!

Now what?

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Problem Setup

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If we have cortex, what to do with it?

Problem 4: Relational Data

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Q1: How can machines learn knowledge from uninterpreted data?

Q2: How can machines learn invariant concepts from uninterp. data?

Q3: How can we implement a “cortex”?



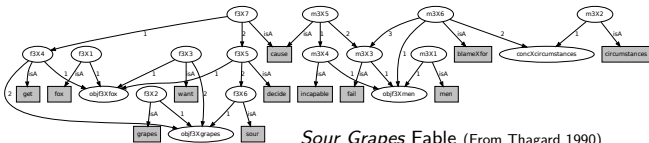
Q4: How can we leverage a “cortex” to process relational data?

- Given stories, learn cliches and plot devices...
- Given descriptions of battles, learn tactics (e.g., “counter-attack”, “defense”, “attrition”)

Relational Structures as “Sensors”

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Q4: How can we leverage a “cortex” to process relational data?



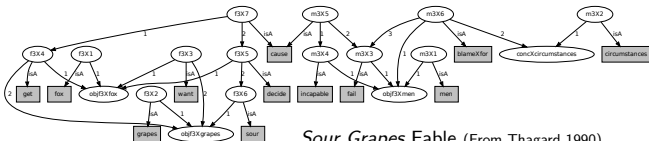
Sour Grapes Fable (From Thagard 1990)



Relational Structures as “Sensors”

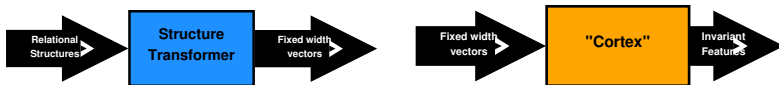
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Q4: How can we leverage a “cortex” to process relational data?



Sour Grapes Fable (From Thagard 1990)

Transform relational structures into input data for “cortex”.



Structure Transformer: I

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English (for clarity)

"A fox wanted some grapes, but could not get them. This caused him to decide that the grapes were sour, though the grapes weren't. Likewise, men often blame their failures on their circumstances, when the real reason is that they are incapable."

Predicate Form (actual input)

fox Of3Fox	cause m34 m33	sameAs f36 (sour Of3Grapes)
false f36	grapes Of3Grapes	sameAs f35 (decide Of3Fox f36)
cause f34 f35	incapable Of3Men	sameAs f34 (get Of3Fox Of3Grapes)
false f34	decide Of3Fox f36	sameAs m34 (incapable Of3Men)
men Of3Men	sameAs m33 (fail Of3Men)	blameFor Of3Men concCircum m33
fail Of3Men	want Of3Fox Of3Grapes	circumstances concCircum

Transforming a Window

```
blameFor Of3Men concCircum m33
sameAs m33 (fail Of3Men)
fail Of3Men
circumstances concCircum
men Of3Men
incapable Of3Men
```



```
blameFor1=blameFor3.fail1
circumstances1=blameFor2
fail1=blameFor3.fail1
fail1=blameFor1
incapable1=blameFor3.fail1
incapable1=blameFor1
incapable1=fail1
men1=blameFor3.fail1
men1=blameFor1
men1=fail1
men1=incapable1
```

Structure Transformer: II

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Related Work

Cortex beyond Perception

Many Transformed Windows

```
blameFor1=blameFor3.fail1
circumstances1=blameFor2
fail1=blameFor3.fail1
fail1=blameFor1
incapable1=blameFor3.fail1
incapable1=blameFor1
incapable1=fail1
men1=blameFor3.fail1
men1=blameFor1
men1=fail1
men1=incapable1
```

```
false1.sour1=decide2.sour1
decide1=cause2.decide1
decide2=cause2.decide2
false1=cause2.decide2
false1=decide2
```

-
-
-
-
-

```
cause2.fail1=blameFor3.fail1
blameFor1=blameFor3.fail1
blameFor1=cause2.fail1
cause2=blameFor3
fail1=blameFor3.fail1
fail1=cause2.fail1
fail1=blameFor1
men1=blameFor3.fail1
men1=cause2.fail1
men1=blameFor1
men1=fail1
```

```
blameFor1=blameFor3.fail1
fail1=blameFor3.fail1
fail1=blameFor1
incapable1=blameFor3.fail1
incapable1=blameFor1
incapable1=fail1
men1=blameFor3.fail1
men1=blameFor1
men1=fail1
men1=incapable1
```

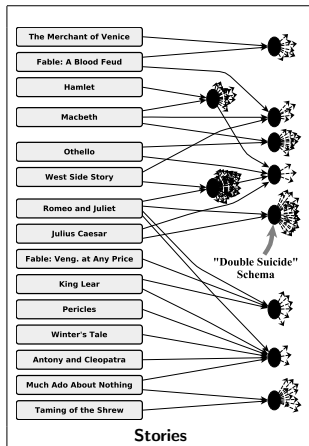
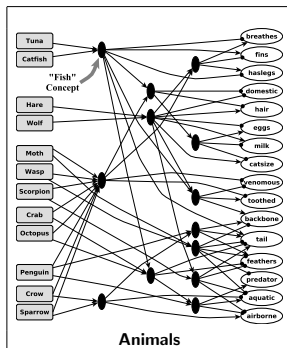
1111

Algorithm:

- Treat transformed windows as percepts: Chunk and Merge
- Treat bags of chunked and merged windows as inputs
 - Chunk and Merge these.

Concepts Learned from Stories (Pickett & Aha 2013)

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Solves Problem of Spontaneous Analog Retrieval!

(submitted to CogSci 2013)

	Analogs Found	Average Time (Comparisons)
Rachkovskij et al. 2012	100.00%	100.00
Ours	95.45%	15.43

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Review

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Q1: How can machines learn knowledge from uninterpreted data?

Q2: How can machines learn invariant concepts from uninterp. data?

Q3: How can we implement a "cortex"?

Answer: By (step 1) chunking and merging!

Q4: How can we leverage a "cortex" to process relational data?

Answer: By (step 2) transforming rel. structs. into fixed-width vectors,
and (step 3) feeding xformed structs. into cortex.

Step 1

Build Cortex



Step 2

Build Structure Transformer



Step 3

Connect them



Current and Future Work

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Q1: How can machines learn knowledge from uninterpreted data?

Q2: How can machines learn invariant concepts from uninterp. data?

Q3: How can we implement a “cortex”?

Q4: How can we leverage a “cortex” to process relational data?

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Currently:

- Scaling Merging up to images.
- Using knowledge for **prediction** and **planning**.
 - E.g., predict story or battle outcomes.
“Hero will defuse bomb at last second.”
 - Realtime battle simulation player that utilizes concepts
“counter-attack”, “defense”, “attrition”

Future:

Q5: How are relational structures learned to begin with?

Workshop: RepLearn 2013

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Learning Rich Representations from Low-Level Sensors

- In conjunction with AAAI 2013 (7/15) in Bellevue, WA
- Submission Deadline: April 3rd, 2013
- **Organizing Committee:**
 - Marc Pickett (Main contact)
 - Ben Kuipers, *Developmental Robotics*
 - Yann LeCun, *Deep Learning*
 - Clayton Morrison, *Developmental Robotics*
- **Invited Speakers:**
 - Yoshua Bengio, *Deep Learning*
 - Jeff Hawkins, *Neuroscience and AI (Inventor of Palm Pilot)*
 - Juergen Schmidhuber, *Artificial General Intelligence*
- See <http://marcpickett.com/RepLearn2013> for details.

Full Story Ontology

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