

Aprententatge Automàtic per a Xarxes (ML4Net)

Seminar 3 - K-means

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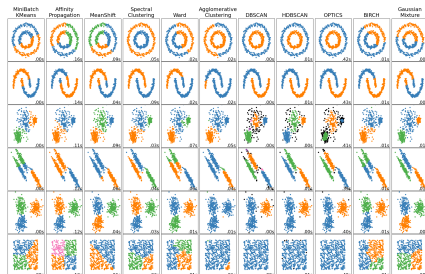


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Clustering via unsupervised learning

Key concepts:

- **Features (x):** Available data points to be clustered, $X = \{x_1, x_2, \dots, x_n\}$, where $x_i \in \mathbb{R}^d$.
- **Labels (y):** The ground truth (if any!) associated with the data points.
- **Model (h):** Function $f : X \rightarrow \{1, 2, \dots, k\}$ that assigns each data point $x \in X$ to a cluster $c \in \{1, 2, \dots, k\}$.
- **Goal:** Group similar data into clusters (other unsupervised learning goals include anomaly detection, dimensionality reduction, or density estimation).

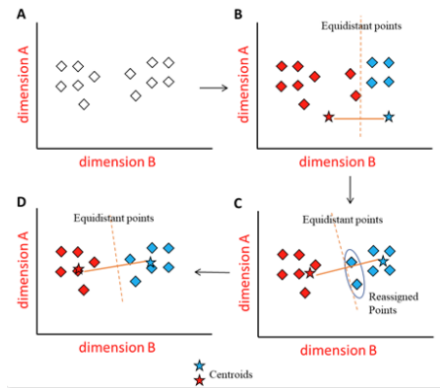


[Source: <https://scikit-learn.org/stable/modules/clustering.html>]

K-means

- We want to divide the data points $x \in X$ into C disjoint clusters.
- Each cluster c is described by a centroid, which is computed as the mean of the samples in the cluster μ_c .
- How do we find the best centroids?

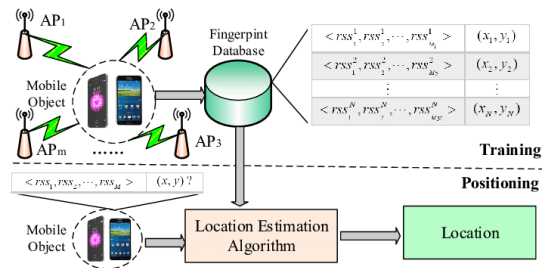
$$\sum_{i=0}^n \min_{\mu_j \in C} (\|x_i - \mu_j\|^2)$$



[Source: <https://www.blopig.com/blog/2020/07/k-means-clustering-made-simple/>]

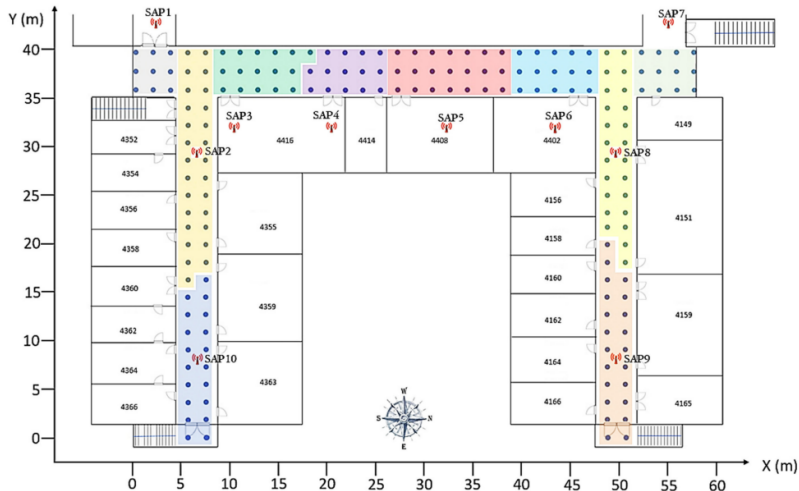
Dataset (I)

- Wi-Fi fingerprinting is a technique used for indoor positioning
- It is based on the RSSI measured at different APs, which are divided into reference points (RPs).
- Two phases:
 - Offline phase: Acquire measurements (RSSI) from different RPs at different APs and derive a model (e.g., K-means, KNNs, NNs).
 - Online phase: New RSSI values are processed and passed to the trained model.



Gu, F., Hu, X., Ramezani, M., Acharya, D., Khoshelham, K., Valaee, S., & Shang, J. (2019). Indoor localization improved by spatial context—A survey. *ACM Computing Surveys (CSUR)*, 52(3), 1-35.

Dataset (II)



Ezhumalai, B., Song, M., & Park, K. (2021). An efficient indoor positioning method based on Wi-Fi RSS fingerprint and classification algorithm. *Sensors*, 21(10), 3418.

Dataset (III)

- `rss_data.csv`: Wi-Fi RSSI measurements taken at $K = 3$ different APs (AP1, AP2, and AP3), for $P = 5$ positions in which the STA was placed.
 - In each row, there is the RSSI perceived by each of the APs for a single measurement.
 - The dataset includes $M = 300$ measurements per location $p \in P$
 - It contains $(P \times M) \times K$ values.
- `labels_data.csv`: The ground truth (i.e., the real position of the STA, p) for each measurement.
 - Contains $P \times M$ values.

