

Group Theory \rightarrow ML

0. Summary of abstract

- [Aslan, Platt, Sheard, 2022]
Group Invariant Machine learning by Fundamental Domain Projection.
- Problem: We have a problem we're trying to solve that is invariant under some gp action. We are using some ML to solve the problem, so we want the ML output to be group invariant. This isn't often the case.
- Solution: project input data into a geometric space that parameterizes the orbits of the symmetry group.
- They give an algorithm to compute the projection, and found an increase in accuracy compared to other algorithms.

ML



Problem

ML Solution

gp-invariant \rightarrow might not be gp-in. \Rightarrow lower accuracy.

Use symmetry gp to fix \uparrow
 \Rightarrow higher accuracy results

1. Introduction

- Many tasks in machine learning are essentially approximating a function $\alpha: X \rightarrow Y$ where X is a feature space, Y an output space.
- We consider the problem in the presence of symmetries.
- e.g.: Recognising a single handwritten digit which might have been rotated by factor of 90° .
- Defn: A group acts on a set, $G \curvearrowright X$, if it does something to the set.
Denoted $g \cdot x$ for $g \in G, x \in X$.
- e.g. $\mathbb{Z}/4 = \{0, 1, 2, 3\} \curvearrowright \boxed{9}$ by 90° ^{clockwise} rotation.
i.e.: $\{0\} \curvearrowright \boxed{9} = \boxed{9}$, $\{1\} \curvearrowright \boxed{9} = \boxed{\text{rotated 9}}$, etc.
- Defn: Let $G \curvearrowright X$, $\alpha: X \rightarrow Y$. α satisfies the covariance property if $\alpha(g \cdot x) = \alpha(x) \forall x \in X, g \in G$.
- Let $\beta: X \rightarrow Y$ be the ML approximant of α . If α G -inv., we want β to be G -inv.
- e.g. since $\alpha: \{\text{handwritten digits}\} \rightarrow \{\text{digits } 0-9\}$ is \mathbb{Z}_4 invariant, $\beta: X \rightarrow Y$ should be too.
- We will restrict to the case that feature space X is a Riemannian mfd, $G \curvearrowright X$ discretely via isom.

§1.1: Methods

- There are two approaches to the problem of group invariant MLNs.
- ① Symmetrisation based: averaging a non- G -invariant model over the action of G .
- ② Intrinsic: designing the model to be G -invariant by imposing conditions coming from group action.
- E.g.: [Symmetrisation] Data augmentation
 - Increase size of training data
$$D_{\text{train}} = \{(x, y) \mid x \in X_{\text{train}} \subset X, y = \alpha(x) \in Y\}.$$
 - By applying sample element $G_0 \in G$, to get
$$D_{\text{train}}^{\text{aug}} = \{(g \cdot x, y) \mid (x, y) \in D_{\text{train}}, g \in G_0\}.$$
- E.g. [Intrinsic] This paper. They suggest a G -invariant pre-processing step to be applied to the input data that can be composed with any ML architecture
 - Done in general by imposing restrictions on weights

§ 2.1: Fundamental domains

- A fundamental domain represents $G \curvearrowright X$.
- "Defn": F is a fundamental domain for $G \curvearrowright X$ if $X = \bigcup_{g \in G} g \cdot F$
 - i.e. F is the building block of the action.
 - e.g. for $\mathbb{Z}_4 \curvearrowright \{\text{handwritten digits}\}$,
 $F = \{\boxed{\dots}, \dots, \boxed{\dots} \mid \boxed{\dots} \text{right way up}\}$
- F is all the info we need for $G \curvearrowright X$.
& It's G -invariant.
- We need to find $\pi: G \rightarrow F$ s.t. π is G -invariant.
- Then can apply MLMs to $\alpha|_F: F \rightarrow Y$
traced on $\text{Domain} = \{(\pi(x), y) \mid (x, y) \in \text{Domain}\}$
Then $\beta = \bar{\beta} \circ \pi$ gives required approx

$$\begin{array}{ccc} X & \xrightarrow{\beta} & Y \\ \pi \downarrow & \nearrow \bar{\beta} & \\ F & & \end{array}$$

§ 2.2: Dirichlet projection

• F_{Dir} :

- Start with a base pt $x_0 \in X$ (only fixed, by $g \in G$ fixing x pointwise)
- $F = \{x \in X \mid d(x, x_0) < d(x, g \cdot x_0) \forall g \in G\}$
- F is all points closer to x_0 than any other pts of $G \cdot x_0$.

- Finding $\Pi_{\text{Dir}}: X \rightarrow F_{\text{Dir}}$ is a minimisation problem for the metric on X . I want to find $g \in G$ minimising $d(g \cdot x, x_0)$.
- Can be approximated using a discrete gradient descent algorithm.

- This alg. cannot be guaranteed to find the minimum, so can only approximate Π .

§ 2-3: Combinatorial Projections

- We would like to have an explicit and easy to compute description of Π .
- The paper gives an algorithm to do this for $G < S_n \curvearrowright X = \mathbb{R}^n$ by coord. permutation:

as then can't get from
 $\sigma \in F \hookrightarrow \sigma \in F$ via other
of S_n , fits defn (1 below)
- F corresponds to a consistent choice of reordering. e.g. $F = \{(x_1, \dots, x_n) \in \mathbb{R}^n \mid x_i < x_{i+1}, \forall i \leq n\}$
- Then our projection to F is applying group elements which order x_i with our choice
- e.g. There is the ascending projection map
 Π_F .
- Once we've applied the projection, we conduct ML on $\Pi(X)$ to get $\bar{\beta} : \Pi(X) \rightarrow Y$ and $\bar{\beta} \circ \Pi : X \rightarrow Y$ is given by design, which is what we wanted.

Summary of results

- Augmentation is a data pre-processing step: computationally impractical for large groups.
- Intrinsic group equivariant neural networks are model-specific.
- Fund. dom. projections are easy to use, maintain original dim. and geom. of data, and are compatible with any MLN.
- Resulting β is G -equivariant.