



# Fall detection system based on incremental development model *exposition*

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Cracow, 19th January 2018

- 1 **Introduction.**
- 2 Selected components.
- 3 System overview.
- 4 Fall detection background.
- 5 Outcome.

### Goal

Design a **Fall Detector** which should:

- signalize a fall using a sound,
- fit in a pocket,
- have its own supply source.

### Additional functions

- motion parameters recording,
- auxiliary application for analysis and processing.

### Milestones

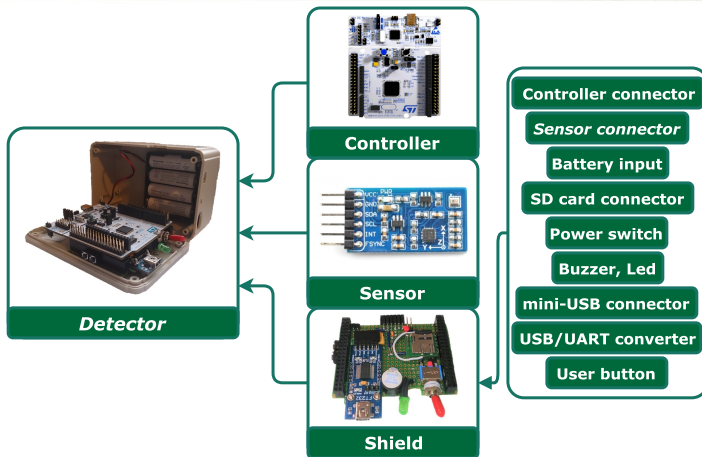
- 1 prepare the measurement system (device and auxiliary application),
- 2 analyze typical ADL scenarios,
- 3 develop and implement fall detection algorithm,
- 4 deploy an alarm feature.

### Incremental model

- the product was designed, implemented and tested incrementally: 12 weeks, every week with a new important feature added,
- chosen because of low cost and highly effective delivery.

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## Selected components - Detector



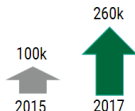
**Figure.** Hardware components of the detector.



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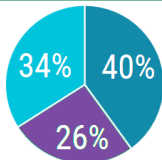
## Selected components - Mbed

### Over 250k registered developers

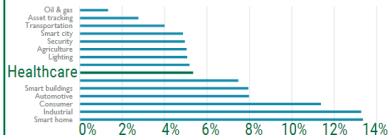


### A third of developers are professionals

- Professional Developer
- Hobbyist
- Student or Educator



### Products target a diversity of IoT markets



### Chosen because of:

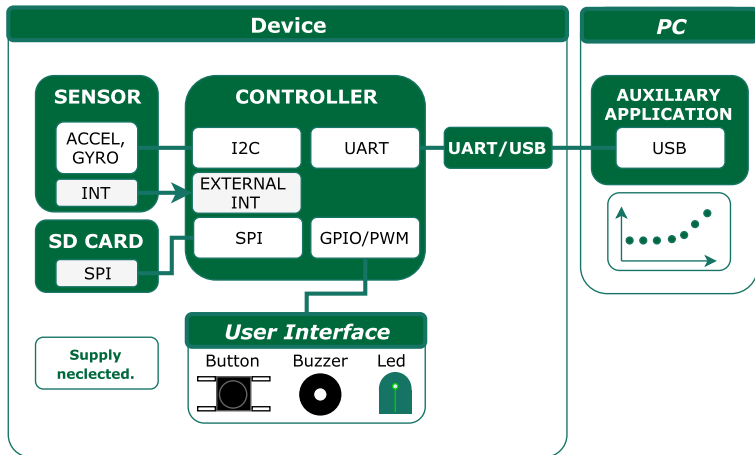
- lightweight driver abstraction layer,
- good C/C++ compiler,
- access to the standard library,
- revision system availability,
- large set of examples,
- clear documentation.

Figures based on ARM mbed Technical Overview [2].

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## System overview



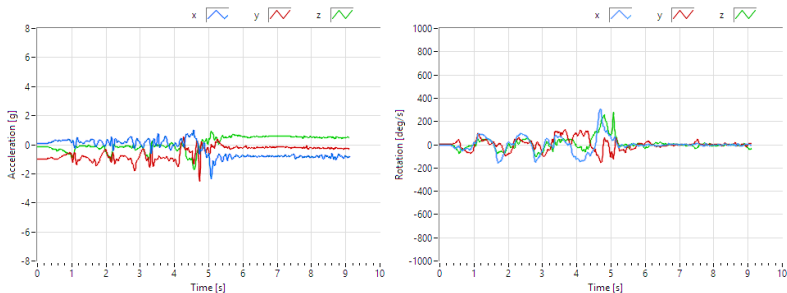
**Figure.** Distributed system overview.

### Created interfaces:

- 1 serial command interface (communicate the device and auxiliary application),
- 2 sensor configuration interface (formatted JSON[3]),
- 3 data transfer interface (sensor configuration and measurement packet) via serial port.

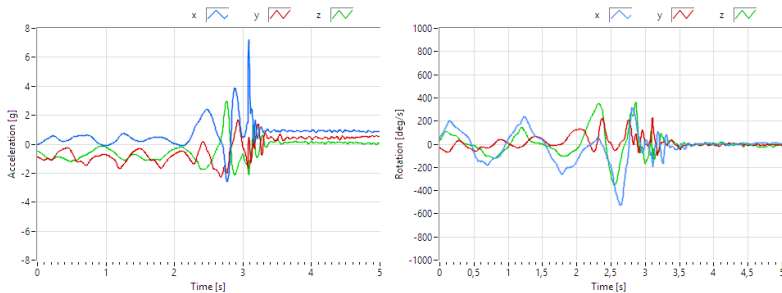
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*Device in the pocket = impact too small to distinguish fall from walk.*



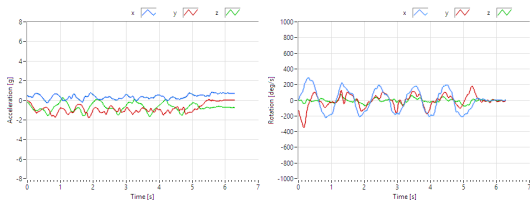
**Figure.** Fall down after a walk - device in the pocket.

*Device beside hand = better exposition on impact.*

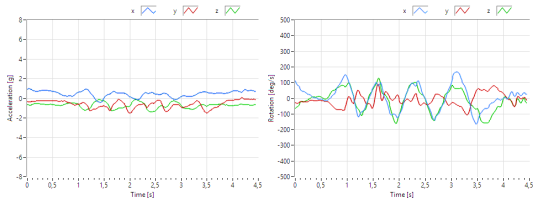


**Figure.** Fall down after a walk - device hold in hand.

# Fall detection background - Activities of daily living I

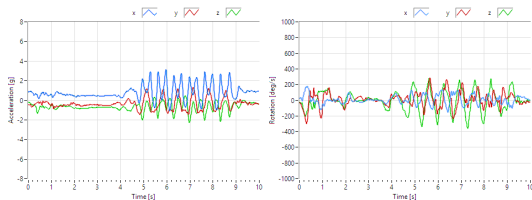


**Figure. Walking - record.**

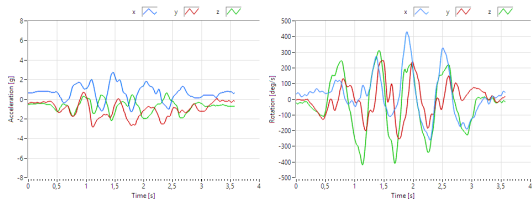


**Figure. Walking upstairs - record.**

## Fall detection background - Activities of daily living II



**Figure. Running - record.**



**Figure. Running upstairs - record.**

## Fall detection background - Activities of daily living III

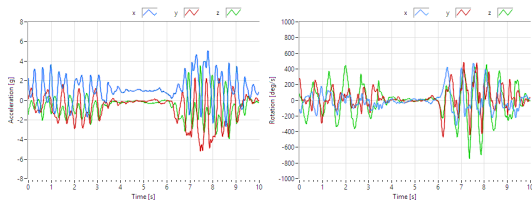


Figure. Sprint - record.

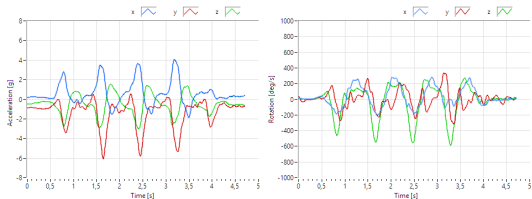
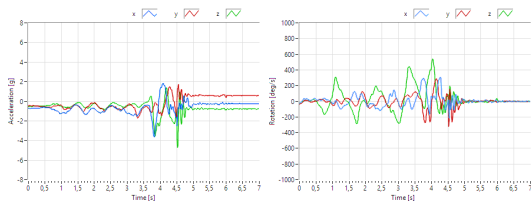


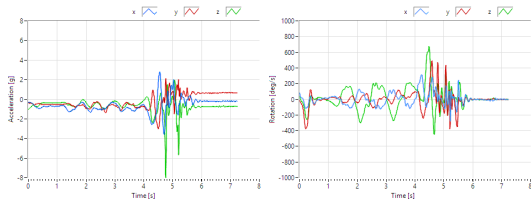
Figure. Jumping - record.



## Fall detection background - Falls



**Figure. Light fall (after walk) - record.**



**Figure. Severe fall (after walk) - record.**

### Algorithm

Let:

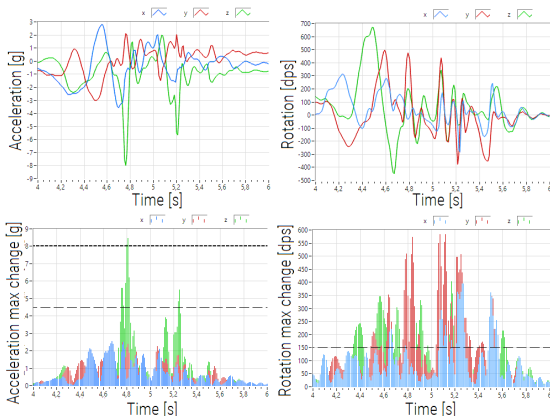
- $V_{pp}$  - peak-to-peak amplitude of discrete signal  $V$  within the selected time window  $w$ ,
- $AX, AY, AZ, GX, GY, GZ$  - parts (within the selected time window  $w$ ) of measured axes of acceleration and angular velocity,
- time window is 50 ms and shifts while data update (every 10 ms).

Then:

$$fall\ detected \Leftrightarrow \exists w : \max(AX_{pp}, AY_{pp}, AZ_{pp}) > 8g \vee (\max(AX_{pp}, AY_{pp}, AZ_{pp}) > 4.5g \wedge \max(GX_{pp}, GY_{pp}, GZ_{pp}) > 150dps).$$

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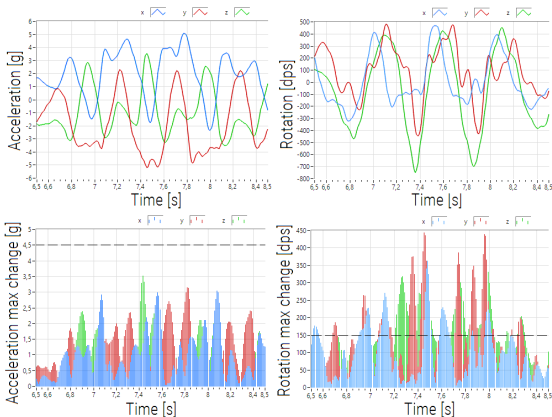
## Outcome - Test results I



*Fall detected: second condition met at 4.76 s (first met at 4.80 s).*

**Figure.** Fall - event analysis.

## Outcome - Test results II



*Fall not detected. Acceleration threshold not exceeded.*

**Figure.** Sprint - event analysis.

## Outcome - Test results III

*TN - true negatives*

*FP - false positives*

*TP - true positives*

*FN - false negatives*

Test case	TN	FP	TP	FN	True	All	Efficiency
Jumping	9	1	-	-	9	10	90 %
Sprint	8	2	-	-	8	10	80 %
Fall from standing	-	-	10	5	10	15	67 %
Fall from walking	-	-	12	3	12	15	80 %
<b>Sum</b>	<b>17</b>	<b>3</b>	<b>22</b>	<b>8</b>	<b>39</b>	<b>50</b>	<b>78 %</b>

### Advantages:

- motion parameters analysis,
- easily-reconfigurable device,
- storage and export system,
- alarm while falling (78 % of the efficiency),
- long battery life,
- full project history.

### Shortcomings:

- 78 % is still below 100 % (limited algorithm),
- performance tested only by the author (human parameters not taken into consideration),
- dimensions.



### Possibilities:

- implement more professional algorithm (increasing efficiency),
- miniaturize and prepare the device for a mass production,
- deliver automatic ambulance notification,
- integrate application in sport and smart watches.

**Let's examine the device  
in the action!**

- [1] FreePik. Paratrooper falling silhouette: [https://www.flaticon.com/free-icon/paratrooper-falling-silhouette\\_38661](https://www.flaticon.com/free-icon/paratrooper-falling-silhouette_38661).
- [2] ARM Ltd. Arm mbed technical overview: [https://www.arm.com/files/event/20170628\\_atf\\_korea\\_b2.pdf](https://www.arm.com/files/event/20170628_atf_korea_b2.pdf).
- [3] Douglas Crockford. Json: <http://json.org/>.