

Closure properties of CFL

- Find satisfactory answer to the following question;
When we perform operations (union, intersection, etc.) with CFLs, do we get as a result a CFL?
- We raised similar questions about RLs, and had easy answers.
- When we ask the same questions about CFLs, we encounter some difficulties.

The Closure Theorems

Closure under Union, Concatenation, Kleene Star, Reverse and Letter Substitution.

Let $G_1 = (V_1, T_1, S_1, R_1)$, $G_2 = (V_2, T_2, S_2, R_2)$, such that $V_1 \cap V_2 = \{ \}$.

Union, Proof: We can construct

$G_3 = (V_1 \cup V_2 \cup \{S_3\}, T_1 \cup T_2, S_3, P_3)$, where

$$P_3 = P_1 \cup P_2 \cup \{S_3 \rightarrow S_1 | S_2\}$$

Clearly G_3 is CF, and it is easy to see that

$$L(G_3) = L(G_1) \cup L(G_2).$$

Concatenation, proof: Similarly we can construct G_3 where

$$P_3 = P_1 \cup P_2 \cup \{S_3 \rightarrow S_1 S_2\}$$

Clearly G_3 is CF and $L(G_3) = L(G_1)L(G_2)$.

The Closure Theorems (cnt.)

Kleene *, Proof: We can construct $G_3 = (V_1 \cup \{S_3\}, T_1, S_3, P_3)$, where

$$P_3 = P_1 \cup \{S_3 \rightarrow \epsilon, S_3 \rightarrow S_1 S_3\}$$

Clearly G_3 is CF and $L(G_3) = L(G_1)^*$.

Reverse, proof: Given $G = (V, T, P, S)$ in CNF, we can construct $G^R = (V, T, P^R, S)$, where P^R is obtained as follows:

- For every rule in P of the form $X \rightarrow AB$, add to P^R the rule $X \rightarrow BA$.
- For every rule in P of the form $X \rightarrow a$, add to P^R the rule $X \rightarrow a$.

It is easy to see that G^R is CF and $L(G^R) = L(G)^R$.

The Closure Theorems (cnt.)

Definition of Letter Substitution: Consider two sets of symbols T_1 and T_2 . Let sub be any function from T_1 to T_2^* . Then $letsub$ is a letter substitution function from L_1 to L_2 iff $letsub(L_1) = \{w \in T_2^* : \exists y \in L_1\}$, where $w = y$ except that every character c of y has been replaced by $sub(c)$.

Letter substitution, proof: Given $G = (V, T, P, S)$ in CNF, and a mapping $sub : T \rightarrow T_1^*$. We can construct

$G^S = (V, T_1^*, P^S, S)$, where P^S is obtained as follows:

- For every rule in P of the form $X \rightarrow AB$, add to P^S the rule $X \rightarrow AB$.
- For every rule in P of the form $X \rightarrow w$, add to P^S the rule $X \rightarrow y$, where $w = y$ except that every character c of y has been replaced by $sub(c)$.

It is easy to see G is CF and $L(G^S) = sub(L(G))$.

The Closure Theorems (cnt.)

Nonclosure under Intersection, Complement, and Difference.

Intersection, proof: If L_1 and L_2 are CF, then $L_1 \cap L_2$ is not necessarily CF.

- Consider two languages CFLs

$$L_1 = \{a^n b^n c^m : n \geq 0, m \geq 0\}, L_2 = \{a^n b^m c^m : n \geq 0, m \geq 0\}$$

- Notice that $L_1 \cap L_2 = \{a^n b^n c^n : n \geq 0, m \geq 0\}$
- But $\{a^n b^n c^n : n \geq 0, m \geq 0\}$ is not CF.
- Using the PL: Let p be a number and $z = a^p b^p c^p \in L_1 \cap L_2$. Considering possible decompositions for $z = uvwxy$, there is no decomposition (obeying the PL reqs.) that would allow to pump v and x and produce a string in the language.

The Closure Theorems (cnt.)

Complement, proof: If \overline{L} always was CF, it would follow that

$$L_1 \cap L_2 = \overline{\overline{L_1} \cup \overline{L_2}} \text{ always would be CF.}$$

However, CFLs are closed under union. If they were closed under complement, then they would necessarily be closed under intersection.

Difference, proof: Given any language L and M ,

$$L - M = L \cap \overline{M}.$$

If L and M are CFLs and they were closed under difference, then they would necessarily be closed under intersection and complement.

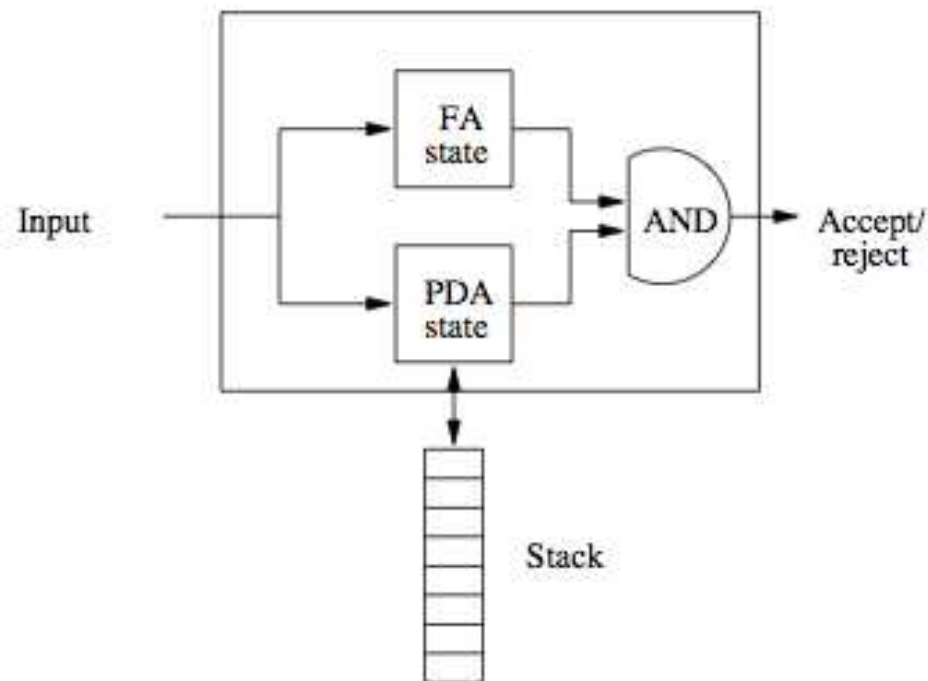
CFL \cap Regular is a CFL

Theorem : If L is CF and R is regular, then $L \cap R$ is CF.

Proof: Let L be accepted by PDA

$P = (Q_P, \Sigma, \Gamma, \delta_P, q_P, Z_0, F_P)$ by final state, and let R be accepted by DFA $A = (Q_A, \Sigma, \delta_A, q_A, F_A)$

We'll construct a PDA for $L \cap R$ according to the picture



Proof idea

Formally, we define

$$P' = (Q_P \times Q_A, \Sigma, \Gamma, \Delta, (q_P, q_A), Z_0, F_P \times F_A)$$

where

$$\delta((q, p), a, X) = \{((r, \delta_A(p, a)), \gamma) : (r, \gamma) \in \delta_P(q, a, X)\}$$

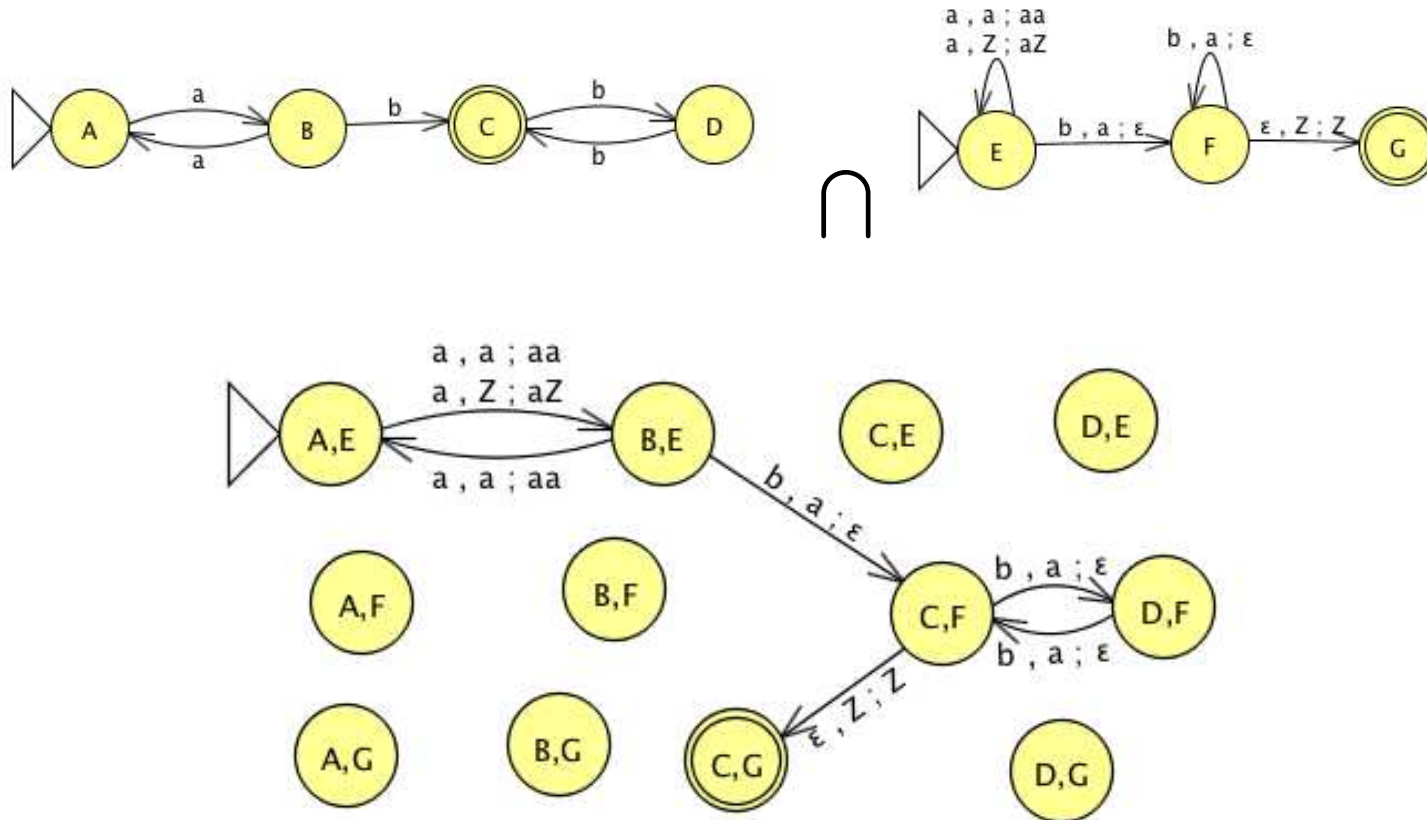
Then carry out a proof by induction on \vdash^* that

$$(q_P, w, Z_0) \vdash_P^* (q, \epsilon, \gamma) \text{ if and only if}$$

$$((q_P, q_A), w, Z_0) \vdash_{P'}^* ((q, \hat{\delta}(q_A, w)), \epsilon, \gamma)$$

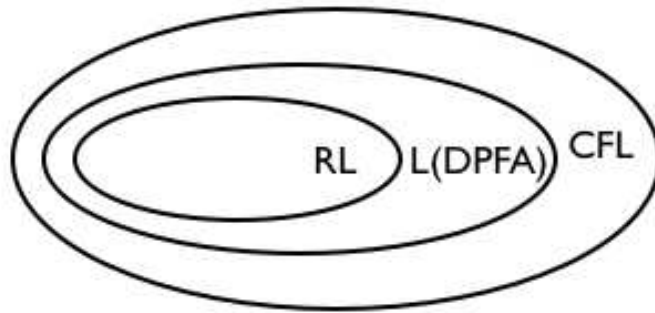
Example

Is $L = \{a^i b^j : i, j \text{ are odd}\} \cap \{a^n b^n : n \geq 1\}$ context free?



Our recent studies

- So far, we have been studying simple **classes of languages** (problems related to searching text, analysis of protocols, and parsing).
- We saw that PDAs are more powerful than finite automata.
- We saw that CFL, while fundamental to the study of programming languages, are limited in scope; e.g., $a^n b^n c^n$ and ww although quite simple, are not CF.
- What is then beyond CFL? And how can we define new language families that include these examples?



In search for a more powerful automaton

- **FA vs PDA:** the nature of the temporary storage captures the difference between them.
 - if there is no storage, we have an FA; if the storage is a stack, then we have the more powerful PDA
- By extrapolation, we can expect to discover even more powerful languages if we give the automaton more flexible storage, e.g., two stacks, three stacks, a queue or some other storage device, etc.
- What can we say of the most powerful automaton and the limits of computation?
- The **Turing Thesis** maintains that the **Turing Machine** is such automaton.

Turing Machines



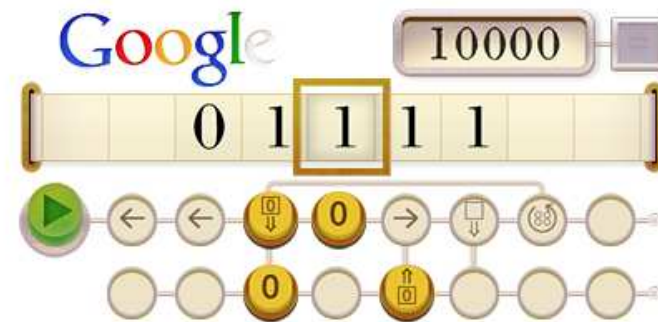
From Google's "Turing Machine doodle" (June 23, 2012), in commemoration of Alan Turing's 100th Birthday.

Motivation for studying this stuff

- To provide guidance to programmers on what they might or might not be able to accomplish through programming.
- How do Turing Machines fit in this context?
 - It is a tool that will allow us to prove everyday questions undecidable or intractable.
- To prove a problem undecidable, we'll reduce it to a problem that the TM cannot decide.

The Turing Machine (1936)

- Has a **finite-state control** unit, like all automata.
- One infinite read-write **tape** serves as both input and unbounded storage device.
- The tape:
 - divided into **cells**;
 - each cell holds one symbol from the **tape alphabet**;
 - the head marks the *current* cell, which is the only cell that can influence the move of the TM.
 - Initially, tape holds $a_1a_2 \cdots a_nBB \cdots$, where $a_1a_2 \cdots a_n$ is the input, chosen from an **input alphabet** (subset of the tape alphabet) and B is the “blank” symbol.



A move of a TM

- A move of a Turing machine (TM) is a function of **the state** of the finite control and **the tape symbol** just scanned.
- In one move, the TM will:
 1. Change state.
 2. **Write a tape symbol** in the cell scanned.
 3. Move the tape head **left or right**.

TMs: formally

A TM is a 7-tuple $M = (Q, \Sigma, \Gamma, \delta, q_0, B, F)$, where:

- Q, Σ, δ, q_0 and F are our old friends.
- Γ is the set of tape symbols, $\Sigma \subset \Gamma$.
- $\delta : Q \times \Gamma \rightarrow Q \times \Gamma \times \{L, R\}$, e.g.: $\delta(q, X) = (p, Y, \mathcal{D})$, where q is a state, X is a tape symbol
 - p is the next state,
 - Y is the symbol written in the cell being scanned, replacing whatever was there, and
 - \mathcal{D} is the direction, either L or R , of the next move.
- $B \in \Gamma$ is the blank symbol; $B \notin \Sigma$

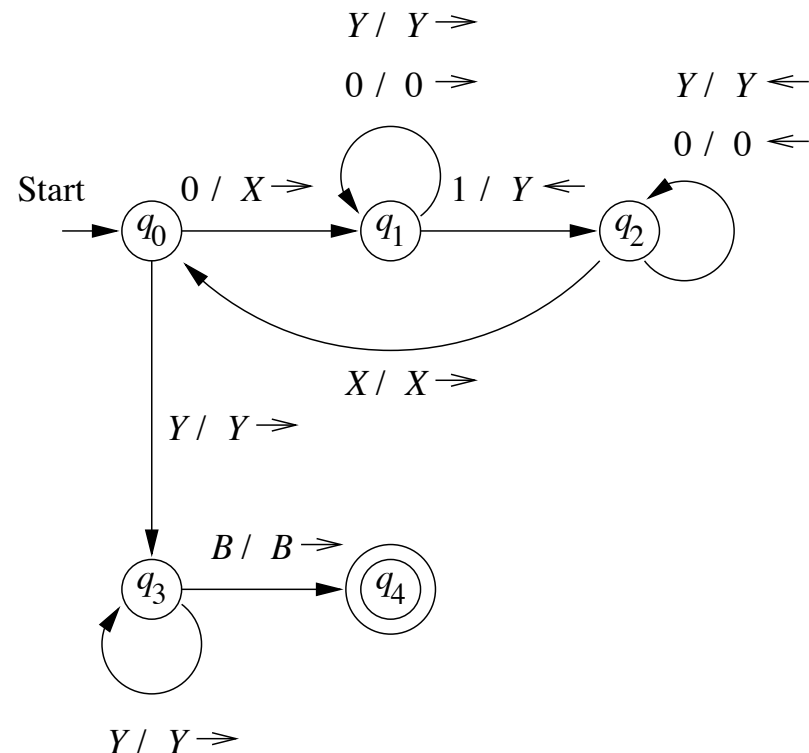
Instantaneous description for TMs

- An ID, denoted $\alpha q \beta$, represents what is going on at any moment with a TM:
 - α is the tape contents to the left of the head.
 - q is the state the TM is at the moment.
 - β is the nonblank tape contents at or to the right of the tape head.
- E.g.: XXq_3Y1BB
- as before, \vdash denotes one move; \vdash^* denotes zero, one, or more moves.

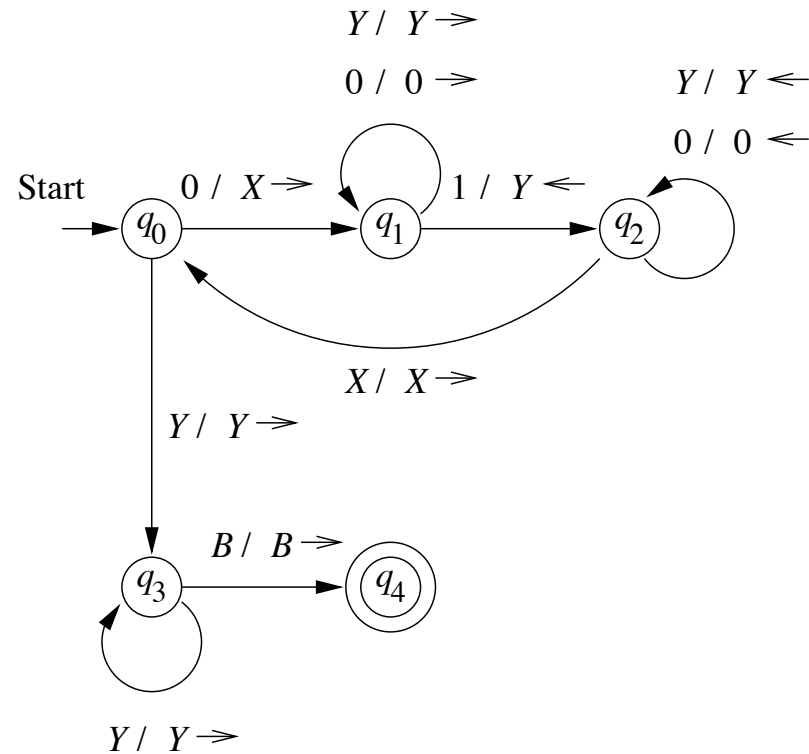
Example: a TM for $\{0^n 1^n : n \geq 1\}$

$M = (\{q_0, q_1, q_2, q_3, q_4\}, \{0, 1\}, \{0, 1, X, Y, B\}, \delta, q_0, B, \{q_4\})$
 where δ is given by the following table:

	0	1	X	Y	B
$\rightarrow q_0$	(q_1, X, R)			(q_3, Y, R)	
q_1	$(q_1, 0, R)$	(q_2, Y, L)		(q_1, Y, R)	
q_2	$(q_2, 0, L)$		(q_0, X, R)	(q_2, Y, L)	
q_3				(q_3, Y, R)	
$\star q_4$					(q_4, B, R)

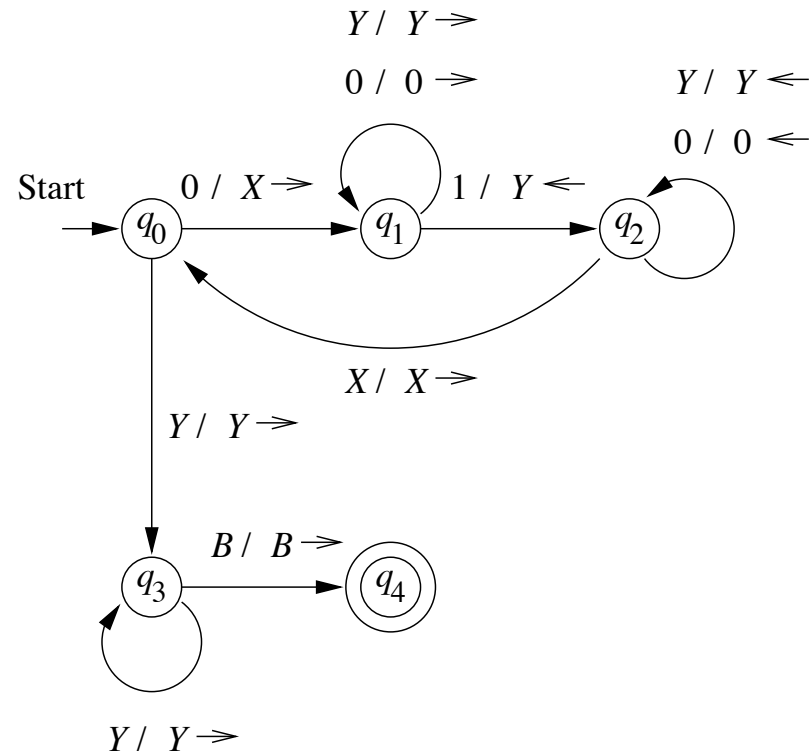


An accepting computation by M



$q_0 0 0 1 1 \vdash X q_1 0 1 1 \vdash X 0 q_1 1 1 \vdash X q_2 0 Y 1 \vdash q_2 X 0 Y 1$
 $X q_0 0 Y 1 \vdash X X q_1 Y 1 \vdash X X Y q_1 1 \vdash X X q_2 Y Y \vdash X q_2 X Y Y \vdash$
 $X X q_0 Y Y \vdash X X Y q_3 Y \vdash X X Y Y q_3 B \vdash X X Y Y B q_4 B$

A non-accepting computation by M



$q_0 0 0 1 0 \vdash X q_1 0 1 0 \vdash X 0 q_1 1 0 \vdash X q_2 0 Y 0 \vdash q_2 X 0 Y 0$
 $X q_0 0 Y 0 \vdash X X q_1 Y 0 \vdash X X Y q_1 0 \vdash X X Y 0 q_1 B$