

Report Project1: Printouts and Source code

SF2565: Program construction in C++ for Scientific Computing

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Task 1: Taylor Series

Printouts from `taylor.cpp` for different number of terms n in Taylor series:

Computing Taylor series of $\sin(x)$ and $\cos(x)$ using 1 terms.

x	$\sin(x)$	$\sinTaylor(x)$	error	bound
-1	-0.841471	-0.833333	8.137651e-03	4.166667e-02
1	0.841471	0.833333	8.137651e-03	4.166667e-02
2	0.909297	0.666667	2.426308e-01	1.333333e-01
3	0.141120	-1.500000	1.641120e+00	6.750000e-01
5	-0.958924	-0.931044	2.788020e-02	1.163805e+00
10	-0.544021	0.250759	7.947804e-01	1.253796e+00

x	$\cos(x)$	$\cosTaylor(x)$	error	bound
-1	0.540302	0.500000	4.030231e-02	4.166667e-02
1	0.540302	0.500000	4.030231e-02	4.166667e-02
2	-0.416147	-1.000000	5.838532e-01	3.333333e-01
3	-0.989992	-3.500000	2.510008e+00	2.625000e+00
5	0.283662	0.176718	1.069445e-01	3.681619e-01
10	-0.839072	-2.293129	1.454058e+00	1.910941e+01

Computing Taylor series of $\sin(x)$ and $\cos(x)$ using 2 terms.

x	$\sin(x)$	$\sinTaylor(x)$	error	bound
-1	-0.841471	-0.841667	1.956819e-04	2.003968e-02
1	0.841471	0.841667	1.956819e-04	2.003968e-02
2	0.909297	0.933333	2.403591e-02	8.888889e-02
3	0.141120	0.525000	3.838800e-01	1.125000e-01
5	-0.958924	-0.960035	1.110960e-03	5.714495e-01
10	-0.544021	-0.676958	1.329368e-01	1.611805e+00

x	$\cos(x)$	$\cosTaylor(x)$	error	bound
-1	0.540302	0.541667	1.364361e-03	1.805556e-02
1	0.540302	0.541667	1.364361e-03	1.805556e-02
2	-0.416147	-0.333333	8.281350e-02	4.444444e-02
3	-0.989992	-0.125000	8.649925e-01	3.750000e-02
5	0.283662	0.289683	6.021163e-03	2.414028e-01
10	-0.839072	-0.485679	3.533923e-01	1.618931e+00

Computing Taylor series of $\sin(x)$ and $\cos(x)$ using 5 terms.

x	$\sin(x)$	$\sinTaylor(x)$	error	bound
-1	-0.841471	-0.841471	1.598285e-10	5.394045e-03

1	0.841471	0.841471	1.598285e-10	5.394045e-03
2	0.909297	0.909296	1.290863e-06	2.331529e-02
3	0.141120	0.140875	2.454139e-04	8.127380e-03
5	-0.958924	-0.958924	4.074587e-09	1.536738e-01
10	-0.544021	-0.543988	3.261118e-05	3.487106e-01

x	cos(x)	cosTaylor(x)	error	bound
-1	0.540302	0.540302	2.076253e-09	4.093199e-03
1	0.540302	0.540302	2.076253e-09	4.093199e-03
2	-0.416147	-0.416155	8.366275e-06	1.261076e-02
3	-0.989992	-0.991049	1.056611e-03	6.757153e-02
5	0.283662	0.283662	4.123022e-08	5.372389e-02
10	-0.839072	-0.839236	1.644090e-04	6.357848e-01

Computing Taylor series of sin(x) and cos(x) using 10 terms.

x	sin(x)	sinTaylor(x)	error	bound
-1	-0.841471	-0.841471	0.000000e+00	1.662986e-03
1	0.841471	0.841471	0.000000e+00	1.662986e-03
2	0.909297	0.909297	3.330669e-16	7.188122e-03
3	0.141120	0.141120	3.587630e-12	2.510040e-03
5	-0.958924	-0.958924	1.110223e-16	4.737768e-02
10	-0.544021	-0.544021	9.992007e-14	1.075141e-01

x	cos(x)	cosTaylor(x)	error	bound
-1	0.540302	0.540302	1.110223e-16	1.169486e-03
1	0.540302	0.540302	1.110223e-16	1.169486e-03
2	-0.416147	-0.416147	3.663736e-15	3.603003e-03
3	-0.989992	-0.989992	2.747003e-11	1.928557e-02
5	0.283662	0.283662	3.330669e-16	1.534969e-02
10	-0.839072	-0.839072	8.897327e-13	1.816172e-01

Computing Taylor series of sin(x) and cos(x) using 100 terms.

x	sin(x)	sinTaylor(x)	error	bound
-1	-0.841471	-0.841471	0.000000e+00	2.052068e-05
1	0.841471	0.841471	0.000000e+00	2.052068e-05
2	0.909297	0.909297	0.000000e+00	8.869896e-05
3	0.141120	0.141120	5.551115e-17	3.097303e-05
5	-0.958924	-0.958924	1.110223e-16	5.846244e-04
10	-0.544021	-0.544021	5.551115e-16	1.326687e-03

x	cos(x)	cosTaylor(x)	error	bound
-1	0.540302	0.540302	1.110223e-16	1.330728e-05
1	0.540302	0.540302	1.110223e-16	1.330728e-05
2	-0.416147	-0.416147	5.551115e-17	4.099767e-05
3	-0.989992	-0.989992	1.110223e-16	2.194457e-04
5	0.283662	0.283662	3.330669e-16	1.746602e-04
10	-0.839072	-0.839072	3.330669e-16	2.066577e-03

Source code

The Main program `taylor.cpp`:

```
#include <iostream>
#include <cmath>
#include <vector>
#include <stdio.h>
#include "taylor.hpp"

using namespace std;

// Reduce x to the interval [-pi, pi)
double argumentReduction(double radians) {
    return radians - 2*M_PI*round(radians / (2*M_PI) );
}

double sinTaylor(int n, double x) {

    x = argumentReduction(x);

    int sign = -1;
    double sum, t;
    t = x; // term for n=0 is x
    sum = x;
    for (int i = 1; i <= n; ++i) {
        t = t * (x * x / ((2*i + 1) * (2*i)));
        sum = sum + sign * t;
        sign = -sign;
    }
    return sum;
}

double cosTaylor(int n, double x) {

    x = argumentReduction(x);

    int sign = -1;
    double sum, t;
    t = 1.0; // term for n=0 is 1
    sum = 1.0;
    for (int i = 1; i <= n; ++i) {
        t = t * (x * x / ((2*i) * (2*i - 1)));
        sum = sum + sign * t;
        sign = -sign;
    }
    return sum;
}

int main() {

    vector<double> x = {-1, 1, 2, 3, 5, 10}; // Values of x for sin(x) and cos(x)
    int n;
    cout << "\nSelect number of terms in Taylor series: ";
    cin >> n;

    double sinx, cosx;
    double sinApprox, cosApprox;
    double error, bound;
```

```

printf("Computing Taylor series of sin(x) and cos(x) using %d terms.\n\n", n);
cout << "x \t sin(x) \t sinTaylor(x) \t error \t\t bound \t" << endl;
for (int i = 0; i != x.size(); ++i) {
    sinx = sin(x[i]);
    sinApprox = sinTaylor(n, x[i]);
    error = abs(sinx - sinApprox);
    bound = pow(-1.0, n+1) * sinApprox * (x[i] * x[i]) / ( (2*(n+1) + 1) * (2*(n+1) ) );
    printf("%.f \t %1.6f \t %1.6f \t %1.6e \t %1.6e \n",
           x[i], sinx, sinApprox, error, abs(bound));
}

cout << "\nx \t cos(x) \t cosTaylor(x) \t error \t\t bound \t" << endl;
for (int i = 0; i != x.size(); ++i) {
    cosx = cos(x[i]);
    cosApprox = cosTaylor(n, x[i]);
    error = abs(cosx - cosApprox);
    bound = pow(-1.0, n+1) * cosApprox * (x[i] * x[i]) / ( (2*(n+1)) * (2*(n+1) - 1) );
    printf("%.f \t %1.6f \t %1.6f \t %1.6e \t %1.6e \n",
           x[i], cosx, cosApprox, error, abs(bound));
}
return 0;
}

```

The header file asi.hpp:

```

#ifndef TAYLOR_HPP
#define TAYLOR_HPP

double sinTaylor(int n, double x);

double cosTaylor(int n, double x);

double argumentReduction(double radians);

#endif

```

Task 2: Adaptive Integration

Printouts from file asi.cpp:

Adaptive Simpson Integration of $f(x) = 1 + \sin(\exp(3x))$:

I	tolerance
2.548323	1e-01
2.505996	1e-02
2.499857	1e-03

Adaptive Simpson Integration of $f(x) = 1 + \sin(\exp(3x))$:

I	tolerance
2.500809	1e-07

Source code

The Main program asi.cpp:

```
#include <iostream>
#include <stdio.h>
#include <cmath>
#include <vector>
#include "asi.hpp"

using namespace std;

// target function is f(x) = 1 + sin(exp(3*x))
double target(double x) {
    return 1 + sin( exp(3*x) );
}

double simpsonRule(FunctionPointer f, double a, double b) {
    return ((b - a) / 6.0) * ( f(a) + 4 * f((a+b)/2) + f(b) );
}

double ASI(FunctionPointer f, double a, double b, double tol) {
    double I1, I2, gamma, errest;
    gamma = 0.5 * (a + b); // mid point
    I1 = simpsonRule(f, a, b);
    I2 = simpsonRule(f, a, gamma) + simpsonRule(f, gamma, b);
    errest = abs(I1 - I2);
    if (errest < 15.0*tol) {
        return I2;
    }
    return ASI(f, a, gamma, tol/2) + ASI(f, gamma, b, tol/2);
}

int main() {
    double I;
    vector<double> tol = {10e-2, 10e-3, 10e-4};

    printf("Adaptive Simpson Integration of f(x) = 1 + sin(exp(3*x)): \n");
    printf(" I \t\t tolerance \n");
    for (int i = 0; i != tol.size(); ++i) {
        I = ASI(&target, -1.0, 1.0, tol[i]);
        printf(" %3.6f \t %.e \n", I, tol[i]);
    }
    return 0;
}
```

The header file asi.hpp:

```

#ifndef ASI_HPP
#define ASI_HPP

typedef double (*FunctionPointer)(double);

double ASI(FunctionPointer f, double a, double b, double tol);

double simpsonRule(FunctionPointer f, double a, double b);

#endif

Matlab code task2.m:

fun = @(x) 1 + sin(exp(3*x));
I = integral(fun, -1, 1);
fprintf('Integral of f(x) = 1 + sin(exp(3*x)): %2.6f \n', I)

```