Xolotl: A Fast and Comprehensible Neuronal Simulator

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ABSTRACT

`xolotl` is an open-source neuronal simulator written in `C++` with `MATLAB` wrappers. Complex models and networks can be designed efficiently using an intuitive language tightly coupled to the object-based architecture of the underlying `C++` code. Models are specified by adding conductances to compartment objects. The structure is modular, serialized, and searchable, permitting high-level programmatic control over nearly all features of the models. `C++` templates are provided for developing new conductances, compartments, and integration schemata. `xolotl` readily implements parallel-processing on multicore processors and high-performance computing clusters. It also includes a customizable graphical user interface ('puppeteer') for rapid prototyping and hand-tuning conductances in real-time. In addition, `xolotl` comes packaged with a powerful optimization toolbox (`procrustes`) for optimizing any model parameters accessible in the `xolotl` tree. The modular structure and accessibility to all parameters, variables, and dynamics of the model network in `MATLAB` facilitate interoperability with other specifications (viz. `NeuroML`, `SBML`), simulators (viz `NEURON`, `Brian`, `NEST`), and web-based applications (viz. `Geppetto`). `xolotl` is freely available at `https://github.com/sg-s/xolotl`. This tool provides rapid implementation and fast simulation of neuronal models while permitting full control over every aspect of the network and integration.

Keywords: simulator, MATLAB, C++, xolotl, conductance-based, computational, keyword, keyword

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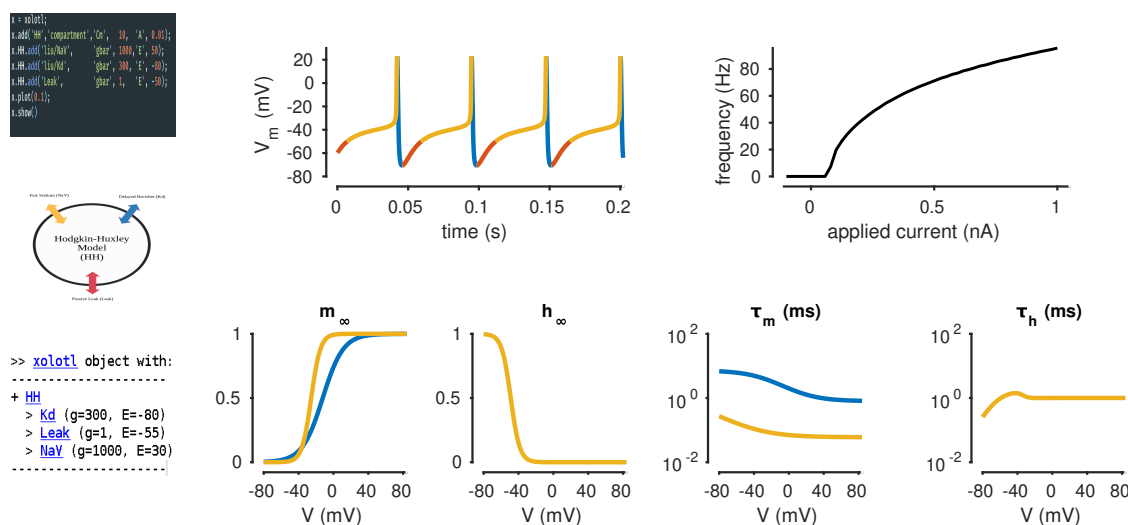
Figure 1. `xolotl` can quickly set up and simulate conductance-based models. (A) Cartoon of a Hodgkin-Huxley single-compartment neuron model with fast sodium, delayed rectifier, and leak currents. (B) Code snippet in `MATLAB` used to implement D, F-I. (C) `xolotl` schematic displayed in the `MATLAB` command prompt. (D) Simulated voltage trace with 0.1 nA applied current. Colors indicate the dominant current (gold is fast sodium, blue is delayed rectifier, red is leak). (E) Frequency-input relation displaying firing rate as a function of applied current. (F-G) Steady-state gating functions for activation (m) and inactivation (h) gating variables. Variables not plotted are unity for all voltage. (H-I) Voltage-dependence of time constants for activation (m) and inactivation (h) gating variables. Variables not plotted are unity for all voltage. Colors indicate conductance type (gold is fast sodium, blue is delayed rectifier, red is leak).
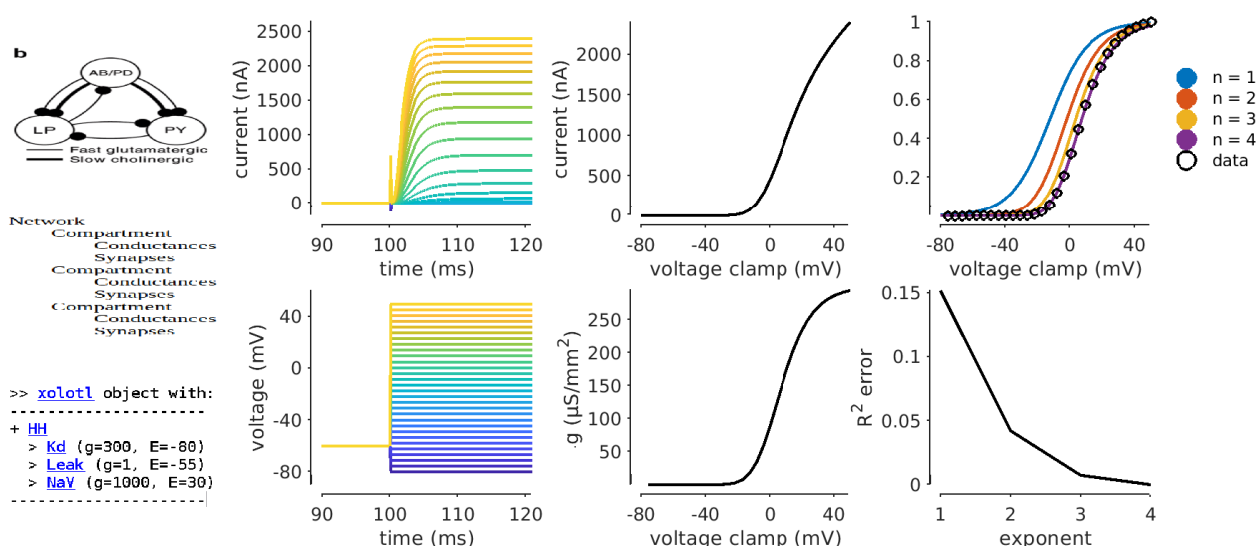
Figure 2. `xolotl` readily implements voltage clamp. (A) Cartoon of a cell with potassium conductance with experimentally-fixed voltage. (B) Structure of `xolotl` object in A. (C) Code snippet depicting integration under voltage clamp. (D-E) Current response to steps in voltage from a holding potential of $V_m = -60$ mV. (F) Current-voltage relation of the steady-state current ($t = 400$ ms) indicating a reversal potential of $E = -80$ mV and no inactivation. (G) Conductance-voltage relation at steady-state takes the form of a sigmoid. (H) Sigmoids of the form m^n fit to the model data indicating that $n = 4$ is the best fit. (I) R^2 correlation of the sigmoid fits at various powers where $n = 4$ is an exact fit.
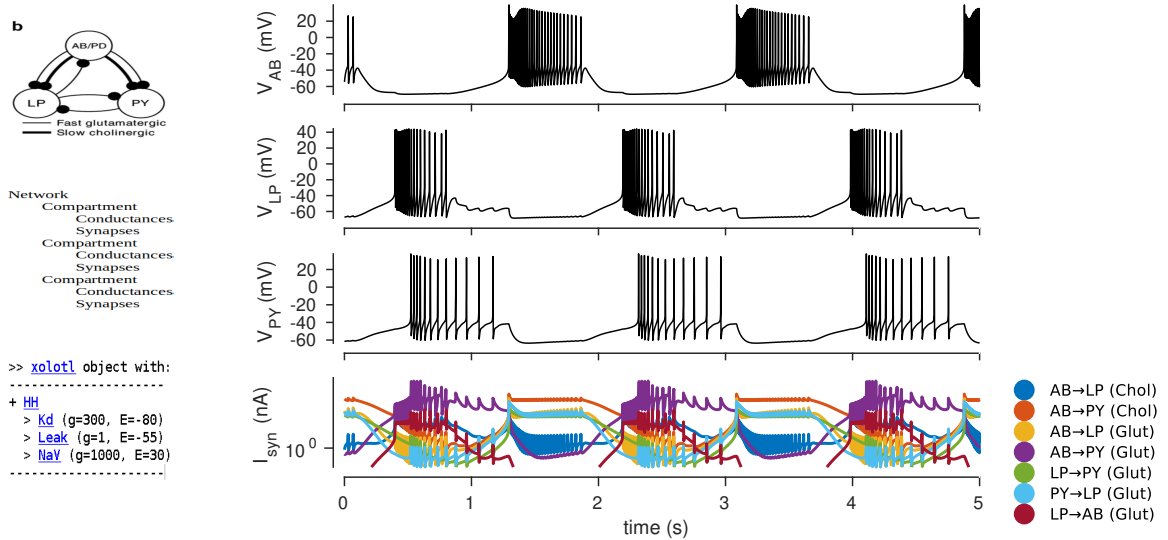
Figure 3. `xolotl` readily implements conductance-based network models. (A) Diagram of a network model of the pyloric rhythm in the crustacean stomatogastric ganglion (Prinz *et al.* 2004). (B) Hierarchical structure of a neuronal network considers compartments as components of the network and conductances and synapses as components of compartments. (C) *xolotl* implements conductances as fields of compartments and synapses as connections between compartments. (D-F) Simulated voltage trace of a model network for the three compartments. (G) Time series of synaptic currents in the simulated network with model cholinergic (chol) and glutamatergic (glut) synapses are outputs of the integration.
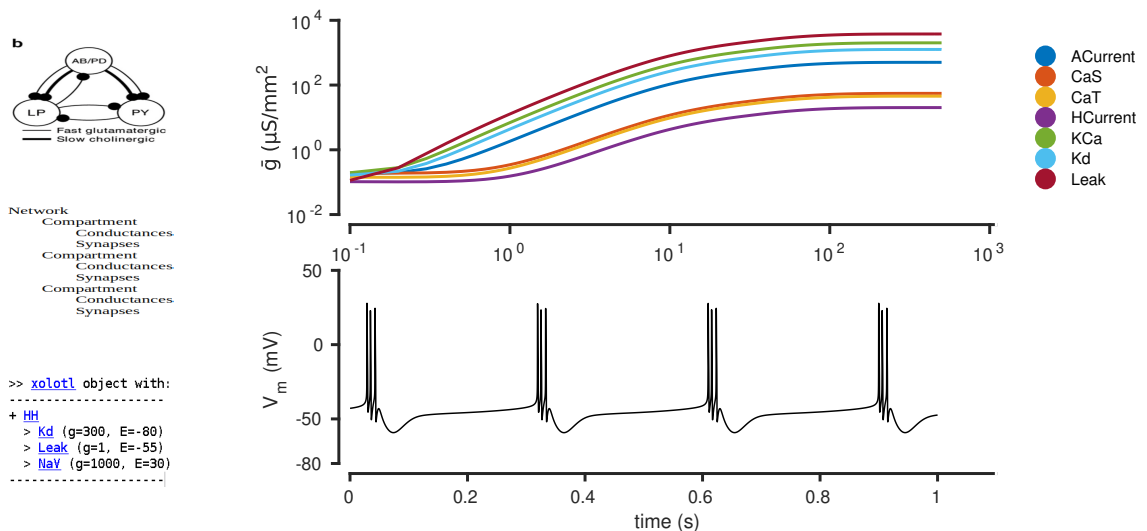
Figure 4. `xolotl` can implement homeostatic tuning rules as integral control. (A) Cartoon of a model neuron with integral control. (B) Hierarchical structure of a neuronal network considers controllers as components of compartments which act on conductances. (C) `xolotl` implements controllers XYZ. (D) Calcium sensors change maximal conductances to move a neuron from quiescence to a bursting state. (E) Voltage trace of the controlled neuron shows regular bursting activity.

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ACKNOWLEDGMENTS

69 This is a short text to acknowledge the contributions of specific colleagues, institutions, or agencies that
70 aided the efforts of the authors.

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