

Random Polygons

2. Zwischenpräsentation

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- ▶ Testing framework for algorithms related to random polygons
- ▶ Generate random polygons (fair, representative)
- ▶ Run shortest path algorithm on polygon
- ▶ Statistical analysis

- ▶ accomplish 6.12.-12.12.
- ▶ all polygon generation algorithms
- ▶ shortest path algorithm
- ▶ GUI basic version

- ▶ needed for some polygon generation algorithms
- ▶ existing:
 - ▶ needed accuracy not given
 - ▶ too big
 - ▶ partly inconsistent
 - ▶
- ▶ therefore small own implementation

Permute and Reject by Auer and Held

input: size n or n points

- i. generate points, if necessary
 - ii. permute points
 - iii. test if polygon simple. if not, continue with ii.
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- ▶ simple to implement
 - ▶ generates all simple polygons with uniform distribution
 - ▶ runtime depends on polygons needed to be generated to encounter simple polygon (max. $n=15$ for fast results)
 - ▶ not suited for practical use

2opt.-Moves by Auer and Held

input: size n or n points

- i. generate random permutation of n points
- ii. for every self intersection of two edges \overline{ab} and \overline{cd}
 - a. remove \overline{ab} and \overline{cd}
 - b. insert \overline{ac} and \overline{bd}

- ▶ needs special treatment for polygons not in general position
- ▶ generates all polygons, but not with uniform distribution

Space Partitioning by Auer and Held

input: set S of n points

- i. choose points $s_f, s_t \in S$ at random
 - ii. draw line $\overline{s_f s_t} \rightarrow 2$ sets
 - iii. recursively for all subsets S' , s'_f first, s'_t last point:
 - a. if S' only consists of s'_f, s'_t , return $\overline{s'_f s'_t}$
 - b. choose s' from S' at random
 - c. draw random line through s' intersecting $\overline{s'_f s'_t}$, thereby creating subsets S'' , S''' , first and last point s'_f, s' and s', s'_t
- generates not every possible simple polygon

Incremental Construction & Backtracking by Auer and Held

input: n points

- i. set of all possible edges, all unmarked, randomly choose current point s
 - ii. recursively for current point:
 - a. add next possible unmarked edge to polygon, mark all intersecting edges
 - b. backtrack if no unmarked edges left and incompleted polygon
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- ▶ speed depends on backtracking
 - ▶ complex to optimize backtracking
 - ▶ currently not suited for practical use

Generating random Polygons by O'Rourke and Virmani

input: size n , radius circle, max. speed, steps t

- i. generate random points on circle \rightarrow regular polygon
 - ii. t times:
 - a. move each vertex with random speed and direction
 - b. test if move violates 2 conditions:
 - ▶ polygon is simple
 - ▶ vertices in bounding region
 - c. discard last step if violation of conditions
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- ▶ still not accessible from GUI
 - ▶ seems to generate specific class of polygons
 - ▶ interesting for statistical analysis

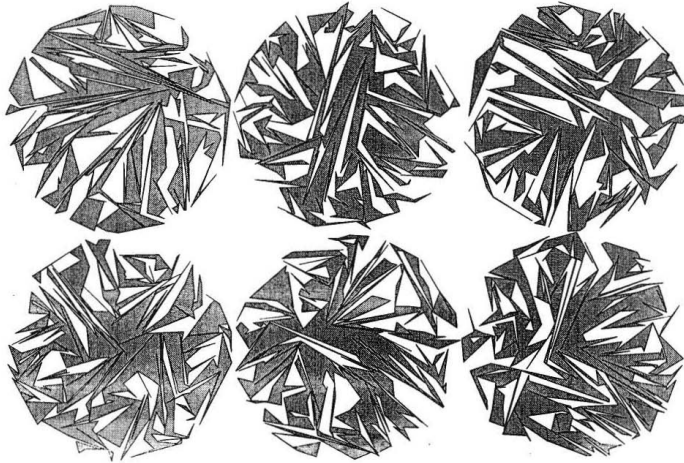


Figure 6: $n = 360$, $t = 1000$, six different random seeds.

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Random Polygon Algorithm by Dailey and Whitfield

input: size n

- i. generate 3 random points \rightarrow random n -gon P size 3
- ii. randomly choose and discard edge \overline{ab}
- iii. determine region P' in polygon visible from \overline{ab}
- iv. randomly choose point c in P'
- v. add edges \overline{ac} , \overline{bc} to polygon P

- ▶ main reason for geometry framework
- ▶ nontrivial problem to determine visible region P'
- ▶ most complex of all generation algorithms

- ▶ order of points representing polygon: cc-wise
- ▶ triangularization
- ▶ random point in polygon
- ▶ intersection line with polygon
- ▶ surface area of polygon

- ▶ basic version
- ▶ next important step: better way to pass parameters

This Milestone:

- ▶ 2 polygon generation algorithms missing
- ▶ shortest path generator missing
- ▶ possible in 1 week

Next Milestone:

- ▶ history objects
- ▶ step-by-step visualization
- ▶ statistic backend