Bayesian Learning Lecture 6 - Bayesian regularization

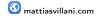


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Lecture overview

- Non-linear regression
- Regularization priors

Polynomial regression

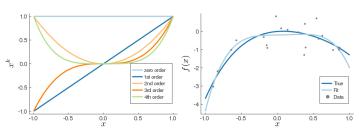
Polynomial regression

$$f(x_i) = \beta_0 + \beta_1 x_i + \beta_2 x_i^2 + \dots + \beta_k x_i^k, \quad \text{for } i = 1, \dots, n.$$
$$y = X\beta + \varepsilon,$$

where ith row of X is

$$(1, x_i, x_i^2, ..., x_i^k).$$

■ Still linear in β and $\hat{\beta} = (X^T X)^{-1} X^T y$. Bayes unchanged.

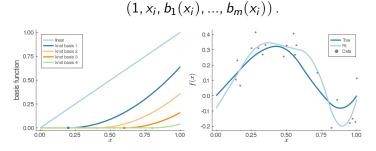


Spline regression

- Polynomials are too global. Need more local basis functions.
- **Truncated quadratic splines with knot locations** $\kappa_1, ..., \kappa_m$:

$$b_j(x) = egin{cases} (x - \kappa_j)^2 & ext{if } x > \kappa_j \ 0 & ext{otherwise} \end{cases}$$
 $y = X\beta + arepsilon,$

where ith row of X is



Regularization prior - Ridge

- Too many knots leads to over-fitting.
- Smoothness/shrinkage/regularization prior

$$\beta_i | \sigma^2 \stackrel{\text{iid}}{\sim} N\left(0, \frac{\sigma^2}{\lambda}\right)$$

- Larger λ gives smoother fit. Note: $\Omega_0 = \lambda I$ in conjugate prior.
- Equivalent to penalized likelihood:

$$-2 \cdot \log p(\boldsymbol{\beta}|\sigma^2, y, X) \propto (\boldsymbol{y} - \boldsymbol{X}\boldsymbol{\beta})^T (\boldsymbol{y} - \boldsymbol{X}\boldsymbol{\beta}) + \lambda \boldsymbol{\beta}^T \boldsymbol{\beta}$$

Posterior mean gives ridge regression estimator

$$\tilde{\boldsymbol{\beta}} = \left(\mathsf{X}^\mathsf{T} \mathsf{X} + \lambda \mathsf{I} \right)^{-1} \mathsf{X}^\mathsf{T} \mathsf{y}$$

Shrinkage toward zero

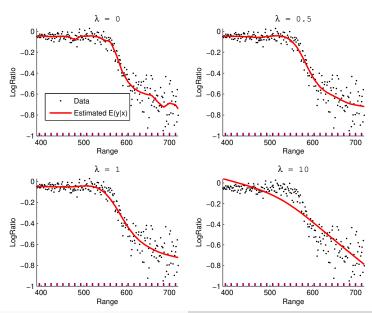
As
$$\lambda o \infty$$
, $ilde{oldsymbol{eta}} o 0$

lacksquare When $X^TX = I$

$$\tilde{oldsymbol{eta}} = rac{1}{1 \perp \lambda} \hat{oldsymbol{eta}}$$

Mattias Villani

Bayesian spline with regularization prior



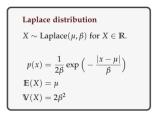
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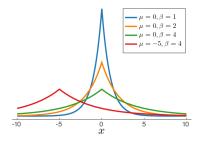
Bayesian regularization

Regularization prior - Lasso

Lasso is equivalent to posterior mode under Laplace prior

$$\beta_i | \sigma^2 \stackrel{\text{iid}}{\sim} \text{Laplace}\left(0, \frac{\sigma^2}{\lambda}\right)$$





- The Bayesian shrinkage prior is interpretable. Not ad hoc.
- Laplace distribution have heavy tails.
- **Laplace prior**: many β_i close to zero, but some β_i very large.
- Normal distribution have light tails.

Learning the shrinkage

- **Cross-validation** used to determine degree of smoothness, λ .
- Bayesian: λ is unknown \Rightarrow use a prior for λ !
- $\lambda \sim \text{Inv}-\chi^2(\eta_0,\lambda_0).$
- Hierarchical setup:

$$\begin{aligned} \mathbf{y} | \boldsymbol{\beta}, \sigma^2, \mathbf{X} &\sim \textit{N}(\mathbf{X} \boldsymbol{\beta}, \sigma^2 \textit{I}_n) \\ \boldsymbol{\beta} | \sigma^2, \lambda &\sim \textit{N}\left(0, \sigma^2 \lambda^{-1} \textit{I}_m\right) \\ \sigma^2 &\sim \textit{Inv} - \chi^2(\nu_0, \sigma_0^2) \\ \lambda &\sim \textit{Inv} - \chi^2(\eta_0, \lambda_0) \end{aligned}$$

so
$$\Omega_0 = \lambda I_m$$
.

Regression with learned shrinkage

The joint posterior of β , σ^2 and λ is

$$\begin{split} \beta|\sigma^2, \lambda, \mathbf{y} &\sim \textit{N}\left(\mu_n, \Omega_n^{-1}\right) \\ \sigma^2|\lambda, \mathbf{y} &\sim \textit{Inv} - \chi^2\left(\nu_n, \sigma_n^2\right) \\ \rho(\lambda|\mathbf{y}) &\propto \sqrt{\frac{|\Omega_0|}{|\mathbf{X}^T\mathbf{X} + \Omega_0|}} \left(\frac{\nu_n \sigma_n^2}{2}\right)^{-\nu_n/2} \cdot \rho(\lambda) \end{split}$$

where $\Omega_0 = \lambda I_m$, and $p(\lambda)$ is the prior for λ , and

$$\mu_n = \left(X^T X + \Omega_0\right)^{-1} X^T y$$

$$\Omega_n = X^T X + \Omega_0$$

$$\nu_n = \nu_0 + n$$

$$\nu_n \sigma_n^2 = \nu_0 \sigma_0^2 + y^T y - \mu_n^T \Omega_n \mu_n$$

More complexity

■ The location of the knots can be unknown. Joint posterior:

$$p(\boldsymbol{\beta}, \sigma^2, \lambda, \kappa_1, ..., \kappa_m | \mathbf{y}, \mathbf{X})$$

- The marginal posterior for $\kappa_1, ..., \kappa_m$ is a nightmare.
- Simulate from joint posterior by MCMC. Li and Villani (2013).
- The basic spline model can be extended with:
 - ► Heteroscedastic errors (also modelled with a spline)
 - ▶ Non-normal errors (student-t or mixture distributions)
 - Autocorrelated/dependent errors (AR process for the errors)