

DAGs and Bad Controls

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Core Empirical Research Methods

Selection on observables again...

Last Time

- ▶ Binary treatment D , potential outcomes (Y_0, Y_1) .
- ▶ Observed outcome $Y = (1 - D)Y_0 + DY_1$.
- ▶ Selection on observables: $D \perp\!\!\!\perp (Y_0, Y_1) | \mathbf{X}$ for observed covariates \mathbf{X} .
- ▶ Overlap: $0 < p(\mathbf{X}) < 1$. (Recall that we can check this.)
- ▶ Regression Adjustment, Propensity Score weighting, Matching

Elephant in the Room

We have completely ignored the question of what to include in \mathbf{X} .

The Omitted Variables Bias (OVB) Formula¹

- ▶ To keep things simple, assume a linear model with homogeneous effects:

$$Y = \alpha + \beta D + \gamma X + U, \quad \text{Cov}(D, U) = \text{Cov}(X, U) = \mathbb{E}(U) = 0.$$

- ▶ In other words:

$$Y_0 = \alpha + \gamma X + U, \quad Y_1 = Y_0 + \beta, \quad \text{ATE} = \text{TOT} = \beta$$

- ▶ What does a regression of Y on D identify?

$$\frac{\text{Cov}(D, Y)}{\text{Var}(D)} = \frac{\text{Cov}(D, \alpha + \beta D + \gamma X + U)}{\text{Var}(D)} = \beta + \gamma \frac{\text{Cov}(D, X)}{\text{Var}(X)}$$

- ▶ “Short” regression coefficient only equals β if $\gamma = 0$ or $\text{Cov}(D, X) = 0$.

¹See, e.g., Section 3.2.2 of *Mostly Harmless Econometrics*.

How *not* to interpret the OVB Formula.

- ▶ OVB Formula tells us *when* and *how* the coefficient on D differs depending on whether we include X in the regression.
- ▶ “Short” regression includes only D ; “Long” regression includes both D and X .
- ▶ “Short” and “Long” coefficients for D agree if:
 1. X does not help predict Y in the “Long” regression or
 2. X is uncorrelated with D .
- ▶ Only if we **assume** that the long regression is the true causal model does this tell us whether we need to adjust for X .

Bad Advice: "Adjust for any observed variable that is correlated with D and Y ."

Example 1: A prototypical bad control.

```
set.seed(1693)
n <- 5000
d <- rbinom(n, 1, 0.4)
x <- rbinom(n, 1, 0.25 + 0.5 * d)
y <- x + rnorm(n)
mean(y[d == 1]) - mean(y[d == 0])
## [1] 0.523149
```

```
library(broom); library(tidyverse)
xtilde <- x - mean(x)
reg <- lm(y ~ d + x + d:xtilde)
tidy(reg) |> filter(term == 'd') |>
  select(estimate, std.error)

## # A tibble: 1 x 2
##   estimate std.error
##   <dbl>     <dbl>
## 1  0.0113    0.0343
```

$$\begin{aligned}\mathbb{E}[Y_1 - Y_0] &= \mathbb{E}[Y|D = 1] - \mathbb{E}[Y|D = 0] \\ &= \mathbb{E}[X|D = 1] - \mathbb{E}[X|D = 0] = 0.5\end{aligned}$$

Why is X a bad control?

Intermediate Outcome

- ▶ Example 1: X is *itself* an outcome of D that *goes on* to cause Y .
- ▶ Adjusting for an intermediate outcome masks the true causal effect of D .
- ▶ E.g. randomized early childhood intervention causes college; college causes wage.
- ▶ In the simulation, 100% of the effect of D on Y goes through X .

Common Advice

Variables measured before the variable of interest [D] was determined are usually good controls. In particular, because these variables were determined before the variable of interest, they cannot themselves be outcomes in the causal nexus.²

²From Section 3.2.3 of *Mostly Harmless Econometrics*, but similar statements are common.

Example 2: This bad control *is not* an intermediate outcome.

```
library(mvtnorm)
R <- matrix(c(1, 0.5, 0.5, 1),
            2, 2)
errors <- rmvnorm(n, sigma = R)
u <- errors[,1]
v <- errors[,2]
x <- rbinom(n, 1, 0.5)
d <- 1 * ((-1 + 2 * x + v) > 0)
y <- -0.3 + d + u

mean(y[d == 1]) - mean(y[d == 0])

## [1] 1.511498
```

```
xtilde <- x - mean(x)
lm(y ~ d + x + d:xtilde) |>
  tidy() |>
  filter(term == 'd') |>
  select(estimate, std.error)

## # A tibble: 1 x 2
##   estimate std.error
##   <dbl>     <dbl>
## 1     1.90     0.0355
```

Why is X a bad control?

Instrumental Variable

- ▶ Example 2: X is a valid instrument for the endogenous treatment D .
- ▶ But this is the **wrong** way to use an instrumental variable: should run IV.
- ▶ Adjusting for X soaks up the **exogenous** part of D , making the bias worse.³

```
library(AER)
ivreg(y ~ d | x) |> tidy() |> filter(term == 'd') |>
  select(estimate, std.error)
```

```
## # A tibble: 1 x 2
##   estimate std.error
##   <dbl>    <dbl>
## 1     1.01    0.0430
```

³See [here](#) for a proof.

“No causes in; no causes out.”⁴

Feeling confused?

- ▶ How can we tell which variables to adjust for and which are bad controls?
- ▶ Is it simply a matter of “I know it when I see it”?

Bad News

- ▶ Meaningful causal inference **always** requires assumptions, even in RCTs.
- ▶ Causal inference from observational data requires **even more** assumptions.

Good News

- ▶ If you make your assumptions explicit, there is a **definitive** solution.
- ▶ If it's possible to use selection-on-observables, find the correct **X**; if it's not possible, show why this is so.
- ▶ Free bonus: better intuition about bad controls.

⁴Nancy Cartwright

The Birthweight Paradox⁵

The analyses in Yerushalmy's paper indicated that, among low birthweight infants of less than 2500g, maternal smoking was associated with lower infant mortality. The results have been replicated in a number of studies and populations, and these seemingly paradoxical associations are now often referred to as the 'birthweight paradox'

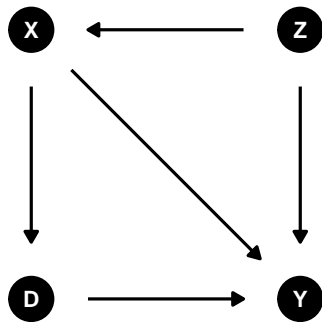
- ▶ $D = 1$ mother smokes while pregnant
- ▶ $Y = 1$ infant dies
- ▶ $X = 1$ low birthweight

Should we adjust for birthweight when studying the causal effect of maternal smoking on infant mortality?

⁵Quote from VanderWeele (2014).

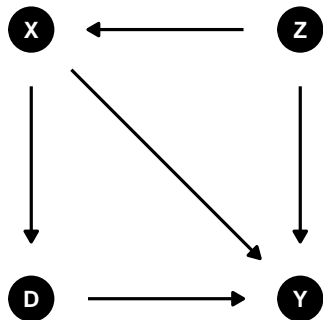
Graph: set of **nodes** connected by **edges**.

- ▶ Two nodes are **adjacent** if connected by an edge.
- ▶ Edges can be **directed** (figure) or **undirected**.
- ▶ Directed edge points from **parent** to **child**.
- ▶ **Directed graph** has only directed edges.
- ▶ **Path**: sequence of connected vertices.
- ▶ **Directed Path**: a path that “obeys one-way signs”
- ▶ Directed path points from **ancestor** to **descendant**.
- ▶ **Cycle**: directed path that returns to starting node.
- ▶ **Acyclic Graph**: a graph without any cycles.



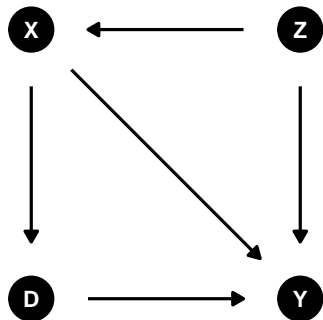
Exercise

1. Is this graph directed?
2. Is this graph acyclic?
3. Are Z and D adjacent?
4. List all paths between D and Y .
5. List all *directed* paths from D to Y .



Exercise

1. Is this graph directed?
2. Is this graph acyclic?
3. Are Z and D adjacent?
4. List all paths between D and Y .
5. List all *directed* paths from D to Y .



Solution

1. Yes: all edges in the graph are directed.
2. Yes: there is no directed path that takes you back to the node where you started.
3. Z and D are not adjacent: there is no edge between them.
4. There are three: $(D \rightarrow Y)$, $(D \leftarrow X \rightarrow Y)$, and $(D \leftarrow X \leftarrow Z \rightarrow Y)$.
5. There is only one: $(D \rightarrow Y)$.

Graphical Causal Models: Directed Acyclic Graphs (DAGs)

Graphical Causal Model

Directed edges encode assumptions about the “flow” of causation (edge) or lack thereof (no edge).

Potential Cause

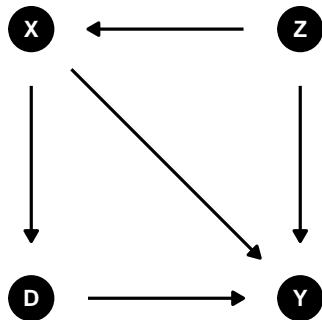
If D is an ancestor of Y , it is a **potential cause** of Y .

Direct Cause

If D is a parent of Y , it is a **direct cause** of Y .

Back Door Criterion

Can we learn ($D \rightarrow Y$) using selection on observables? If so, what covariates should we adjust for?



“Draw Your Assumptions” – Birthweight Example

Birthweight Paradox

- ▶ Y mortality
- ▶ X birthweight
- ▶ D maternal smoking
- ▶ U unobserved: e.g. malnutrition / birth defect

Should we condition on X ?

Can't adjust for U : unobserved. Should we adjust for birthweight when studying (smoking \rightarrow mortality) effect?

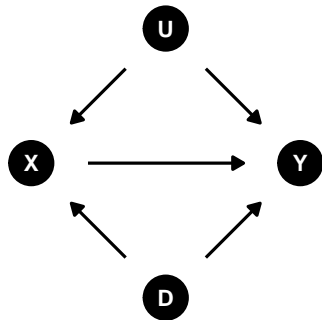


Figure 1: A possible model for the birthweight example.

Causal and Non-causal Paths

Causal Path

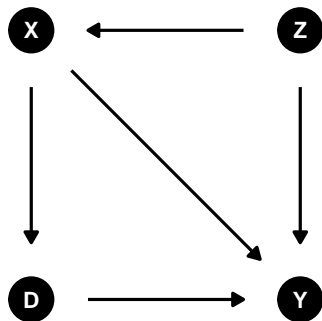
Directed path between treatment and outcome; always starts with an edge pointing *out* of treatment.

Backdoor Path

Noncausal path path between treatment and outcome; always starts with an edge pointing *into* treatment.

Exercise

1. List all causal paths from D to Y .
2. List all backdoor paths between D and Y .



Causal and Non-causal Paths

Causal Path

Directed path between treatment and outcome; always starts with an edge pointing *out* of treatment.

Backdoor Path

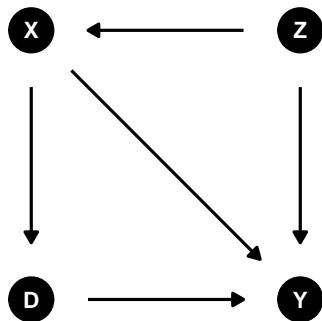
Noncausal path path between treatment and outcome; always starts with an edge pointing *into* treatment.

Exercise

1. List all causal paths from D to Y .
2. List all backdoor paths between D and Y .

Solution

1. $(D \rightarrow Y)$
2. $(D \leftarrow X \rightarrow Y)$, and $(D \leftarrow X \leftarrow Z \rightarrow Y)$.



Graph Surgery

Observational Distribution: $\mathbb{P}(Y|D = d)$

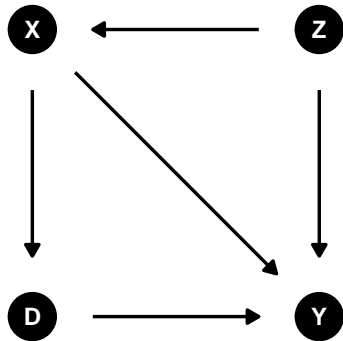
- ▶ *Actual* distribution of Y among people observed to have $D = d$.
- ▶ DAG shows the observational distribution and how it arises from our causal model.

Interventional Distribution: $\mathbb{P}(Y|\text{do}(D = d))$

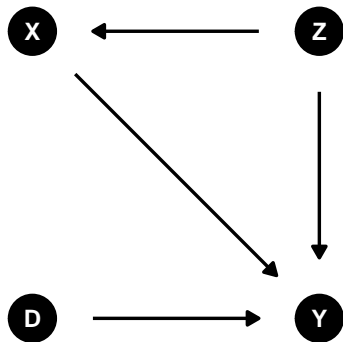
- ▶ Distribution of Y that we *would obtain* if we *intervened* and set $D = d$ for everyone.
- ▶ Obtain from DAG by removing edges pointing into D .
- ▶ Causal effect of interest is the path from D to Y in this “modified” graph.
- ▶ $\text{ATE} = \mathbb{E}(Y_1 - Y_0) = \mathbb{E}(Y|\text{do}(D = 1)) - \mathbb{E}(Y|\text{do}(D = 0))$
- ▶ This is what an experiment does: removes all causes of treatment!

Graph Surgery: Delete Edges Pointing Into D

Observational Distribution



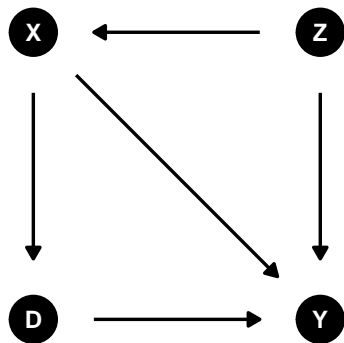
Interventional Distribution: $\text{do}(D)$



Interventional DAG has *no backdoor paths*. To use the observational distribution for causal inference, we will attempt to “block” the backdoor paths by conditioning.

Exercise: Draw the DAG for the $\text{do}(X)$ Interventional Distribution

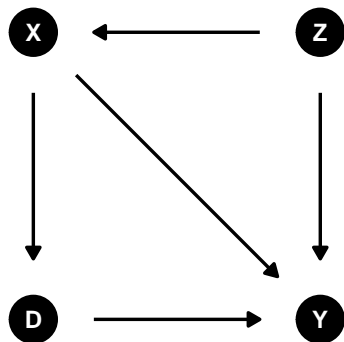
Observational Distribution



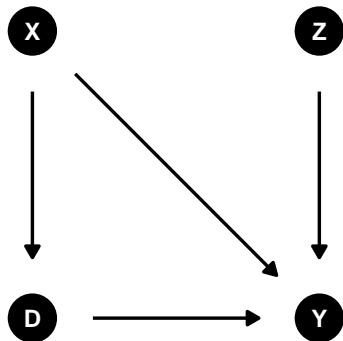
Interventional Distribution: $\text{do}(X)$

Exercise: Draw the DAG for the $\text{do}(X)$ Interventional Distribution

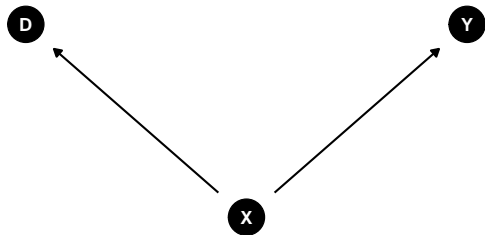
Observational Distribution



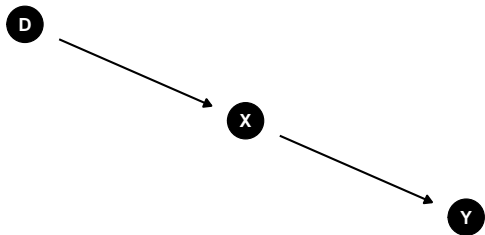
Interventional Distribution: $\text{do}(X)$



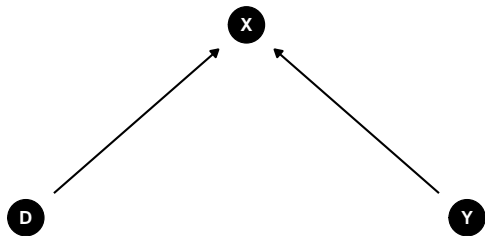
Fork



Pipe



Collider



Descendant

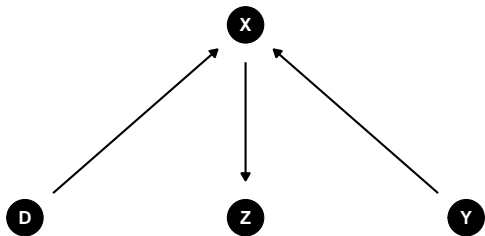


Figure 2: The Four Basic DAGs

Fork = Common Cause / Confounder

Confounder = Good Control

- ▶ D and Y are dependent: **open** path between them.
- ▶ But D doesn't cause Y : X causes D and Y .
- ▶ Conditioning on X **blocks the path** from D to Y .

Example

D is shoe size, Y is reading ability, X is age.

Fork Rule

If X is a common cause of D and Y and there is only one path between D and Y , then $D \perp\!\!\!\perp Y | X$.

“Condition on things that cause both D and Y .”

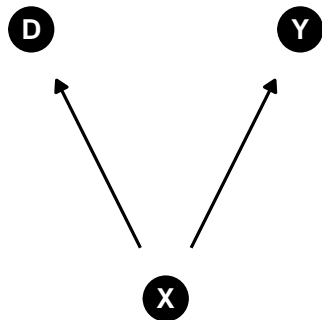


Figure 3: X is a confounder.
Good control for $D \rightarrow Y$.

Pipe = Mediator

Mediator = Bad Control

- ▶ D and Y are dependent: **open** path between them.
- ▶ D causes Y through its causal effect on X .
- ▶ Conditioning on X **blocks the path** from D to Y .

Example

D is SAT coaching, X is SAT score, Y is college acceptance

Pipe Rule

If there is only one directed path from D to Y and X intercepts that path, then $D \perp\!\!\!\perp Y | X$.

“Don’t condition on an intermediate outcome.”

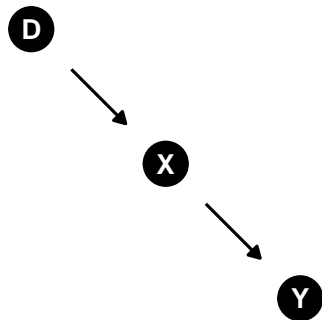


Figure 4: X is a mediator.
Bad control for $D \rightarrow Y$.

Collider = Common Effect

Common Effect = Bad Control

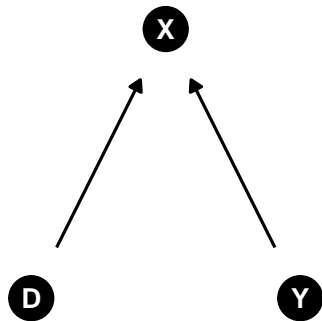
- ▶ D and Y are independent: **blocked** path between them.
- ▶ D and Y both cause X , but neither causes the other.
- ▶ Conditioning on X **unblocks** the path between D and Y .

Example

D, Y indep. coins; X = bell rings if at least one HEADS.

Collider Rule

If there is only one path between D and Y and X is their common effect, then $D \perp\!\!\!\perp Y$ but $D \not\perp\!\!\!\perp Y | X$.



Why are brilliant researchers lousy teachers?

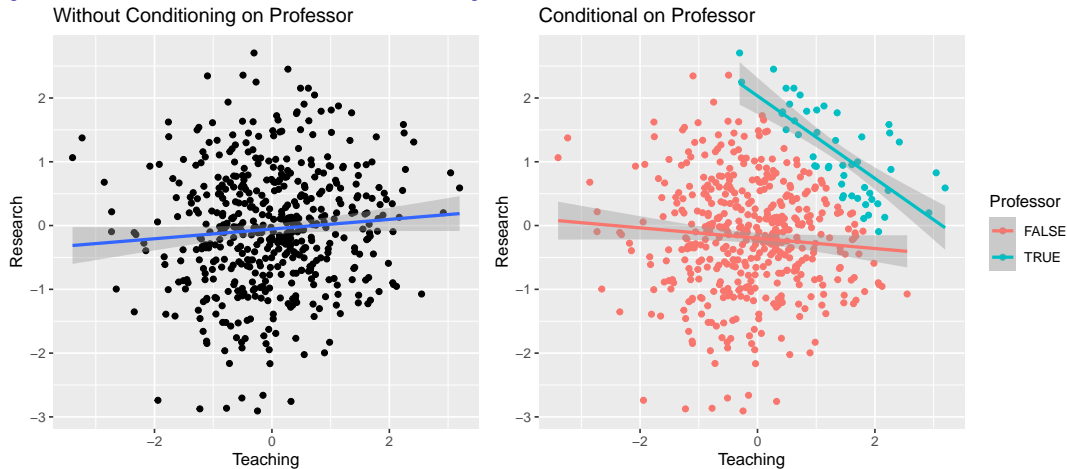


Figure 5: Teaching and Research are independent $N(0, 1)$. Professor is a collider: TRUE if the sum of Research and Teaching is in the top 10th percentile of all observations.

The Descendant

Descendant Rule

Conditioning on a descendant Z of X has the effect of *partially conditioning* on X itself.

Collider Corollary

In the figure, $D \perp\!\!\!\perp Y$ but $D \not\perp\!\!\!\perp Y|Z$.

Discussion

- ▶ What this means depends on the situation.
- ▶ In the figure X is a collider.
- ▶ Could also have X as the middle node in pipe/fork.
- ▶ Pipe/fork: adjust for $Z \Rightarrow$ **partially block** D, Y path.

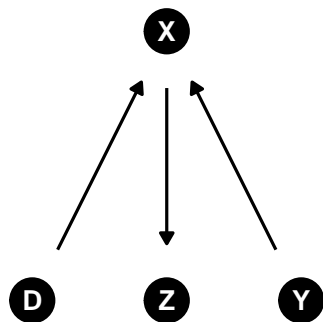


Figure 6: Z is a descendant of the collider X . Bad control for $D \rightarrow Y$

Exercise: Find all examples of the four basic DAGs.

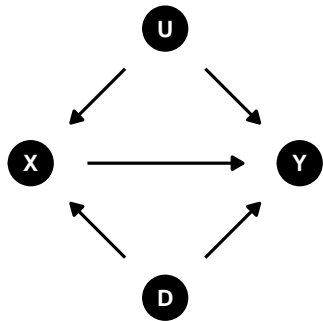


Figure 7: Birthweight DAG

Exercise: Find all examples of the four basic DAGS.

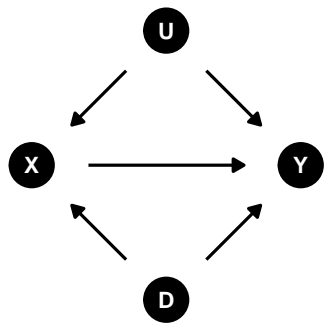


Figure 7: Birthweight DAG

Solution

1. **Forks:** $X \leftarrow U \rightarrow Y$ and $X \leftarrow D \rightarrow Y$
2. **Pipes:** $D \rightarrow X \rightarrow Y$, $U \rightarrow X \rightarrow Y$
3. **Colliders:** $D \rightarrow X \leftarrow U$ and $D \rightarrow Y \leftarrow U$.
4. **Descendant:** Y is a descendant of the collider $D \rightarrow X \leftarrow U$.

Blocking and Opening Paths in the Four Basic DAGs

Fork

$D \leftarrow X \rightarrow Y$ is an **open** path; conditioning on the **confounder** X **blocks** the path.

Pipe

$D \rightarrow X \rightarrow Y$ is an **open** path; conditioning on the **mediator** X **blocks** the path.

Collider

$D \rightarrow X \leftarrow Y$ is a **blocked** path; conditioning on the **collider** X **opens** the path.

Descendant

Conditioning on the descendant of a **confounder** / **mediator** partially blocks the open path. Conditioning on the descendant of a **collider** partially opens the blocked path.

Backdoor Criterion

Use what we know about the four basic DAGs to **block** all backdoor paths between D and Y in our “big” DAG. Obtain interventional distribution from observational data.

The Backdoor Criterion

Recall: Backdoor Path

Noncausal path between D and Y ; starts with edge pointing **into** D .

Blocked Path

A set of nodes X **blocks** a path p if and only if p contains: (1) a **pipe** or **fork** whose middle node is in X or (2) a **collider** that is *not* in X and has no descendants in X .

Backdoor Criterion

A set of nodes X satisfies the back-door criterion relative to (D, Y) if no node in X is a descendant of D and X blocks every back-door path between D and Y .

A Less Formal Statement of the Back-door Criterion

1. List all the paths that connect treatment and outcome.
2. Check which of them *open*. A path is *open* unless it contains a collider.
3. Check which of them are *back-door paths*: contain an arrow pointing at D .
4. If there are no open back-door paths, you're done. If not, look for nodes you can condition on to **block** remaining open back-door paths without opening new ones.

Of course we can only condition on *observed variables*!

Important Note

In a given DAG there may be *no way* to satisfy the back-door criterion, given what we observe. There may also be *multiple ways*!

Backdoor Theorem = Selection on observables!

Backdoor Theorem

If X satisfies the back-door criterion relative to (D, Y) , then

$$\mathbb{P}(Y = y | \text{do}(D = d)) = \sum_{\text{all } x} \mathbb{P}(Y = y | D = d, X = x) \cdot \mathbb{P}(X = x)$$

What if X is empty?

Then we don't to condition on anything: $\mathbb{P}(Y = y | \text{do}(D = d)) = \mathbb{P}(Y = y | D = d)$

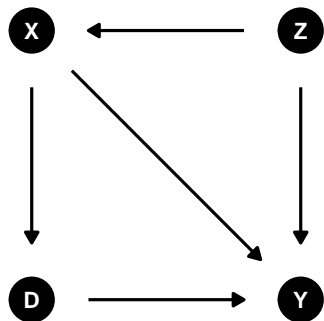
Counterfactual Interpretation

If X satisfies the back-door criterion relative to (D, Y) , then $Y_d \perp\!\!\!\perp D | X$ for all d .

Translating to Potential Outcomes

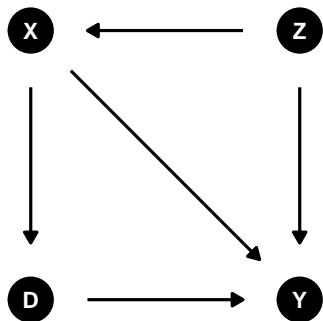
- ▶ The “counterfactuals” Y_d are our potential outcomes from earlier in this lecture.
- ▶ Back-door criterion implies selection on observables assumption for D given X .
- ▶ The formula above is nothing more than **regression adjustment**.

Exercise: What to adjust for to learn the effect of each intervention?



1. The effect of D on Y .
2. The effect of X on Y .
3. The effect of Z on Y ?

Exercise: What to adjust for to learn the effect of each intervention?



1. The effect of D on Y .
2. The effect of X on Y .
3. The effect of Z on Y ?

Solution

1. There are two backdoor paths. In $(D \leftarrow X \rightarrow Y)$, the middle node in a fork is X . In $(D \leftarrow X \leftarrow Z \rightarrow Y)$ the middle node in a pipe is X . Adjusting for X blocks both.
2. The only backdoor path is $(X \leftarrow Z \rightarrow Y)$, a fork with Z as its middle node. Adjusting for Z blocks this path.
3. There are no arrows pointing into Z , hence no backdoor paths. We don't have to adjust for anything.

(Possible) Solution to Birthweight Paradox

Among low birthweight infants. . . maternal smoking was associated with lower infant mortality.

Notation

Y mortality, X birthweight, D maternal smoking, and U unobserved: e.g. malnutrition / birth defect

Birthweight is a bad control!

- ▶ Can't adjust for U because it's unobserved.
- ▶ No arrows pointing into D so no backdoor paths.
- ▶ X is a collider: conditioning on it creates spurious dependence between D and U .

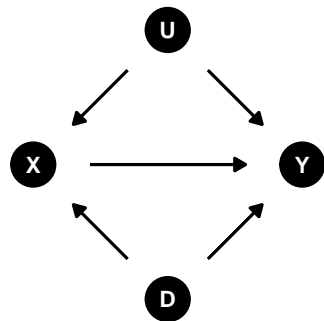


Figure 8: If we believe this model, X is a bad control.

Low birthweight infants whose mothers did *not* smoke must have an unfavorable value of U , making it appear as though smoking has health benefits.

Exercise / Cancer Example Continued

- ▶ X is a **collider**: it *blocks* the back-door path between D and Y through (U, V) .
- ▶ Adjusting for X *opens* this blocked path, so X is a **bad control**.
- ▶ Back door criterion is satisfied with $Z = \emptyset$: don't condition on *anything*!

```
library(dagitty)
library(ggdag)
dagify(Y ~ D + U, D ~ V, X ~ U + V) |>
  paths(from = 'D', to = 'Y')
```

```
## $paths
## [1] "D -> Y"           "D <- V -> X <- U -> Y"
##
## $open
## [1] TRUE FALSE
```