

Inequalities, Household Behavior and the Macroeconomy *(Solving Consumption-Saving Models)*

Course Director: Zoltán Rácz

SSE, Department of Finance

April 11, 2024

Last lecture

- Discussed how to include borrowing limits in our model
- Zeldes(1989)
- Started to talk about solving models

Today

Solving models with a computer – in detail

- (Theory) Dynamic programming: Solve a series of simple problems instead of one complicated one
- (Practice) Understanding code to solve the consumption-saving problem
- I have to leave at 11:55

Full model

With uncertainty and borrowing limits:

$$V_0(z_0) = \max_{\{c_s(z_s), a_s(z_s)\}_{s=0}^T} \sum_{s=0}^T \sum_{z_s} \pi(z_s) \beta^s u(c_s(z_s))$$

$$s.t. \quad a_s(z_s) = (1+r)a_{s-1}(z_{s-1}) + y_s(z_s) - c_s(z_s) \quad \forall s \in \{0, 1, \dots, T\}, \quad \forall z_s$$

$$a_s(z_s) \geq -b \quad \forall s \in \{0, 1, \dots, T\}, \quad \forall z_s$$

$$a_T(z_T) \geq 0 \quad \forall z_T$$

$$a_{-1} \text{ given}$$

Solving means finding optimal policies for all times and all histories.

Note that $a_{-1} \in z_0$.

Problem of agent of age t

$$V_t(z_t) = \max_{\{c_s(z_s), a_s(z_s)\}_{s=t}^T} \sum_{s=t}^T \sum_{z_s \subset z_t} \frac{\pi(z_s)}{\pi(z_t)} \beta^{s-t} u(c_s(z_s))$$

$$s.t. \quad a_s(z_s) = (1+r)a_{s-1}(z_{s-1}) + y_s(z_s) - c_s(z_s) \quad \forall s \in \{t, t+1, \dots, T\}, \quad \forall z_s \subset z_t$$

$$a_s(z_s) \geq -b \quad \forall s \in \{t, t+1, \dots, T\}, \quad \forall z_s \subset z_t$$

$$a_T(z_T) \geq 0 \quad \forall z_T$$

$$a_{t-1} \text{ given}$$

- Need to take into account only those future histories, which are continuations of the current (already realized) history. Notation: $z_s \subset z_t$
- If z_s is a continuation of z_t , then $\pi(z_s)/\pi(z_t)$ is the probability of z_s happening, conditional on z_t having happened. (Remember: π still means probabilities when looking from forward from period 0.)
- We can solve this for any reasonable history z_t . We are interested in histories that won't lead to $V_t = -\infty$.

Turn sequential problem into a sequence of problems

- Optimization problems of agents with different ages are not independent.
- Bellman's principle of optimality (1957):

"An optimal policy has the property that whatever the initial state and initial decision are, the remaining decisions must constitute an optimal policy with regard to the state resulting from the first decision"
- We have many decisions and constraints in the full problem. Separate them to simplify!
 - ▶ Decisions and constraints now
 - ▶ Decisions and constraints later

Problem of agent of age t

$$\begin{aligned} V_t(z_t) &= \max_{\{c_s(z_s), a_s(z_s)\}_{s=t}^T} \sum_{s=t}^T \sum_{z_s \subset z_t} \frac{\pi(z_s)}{\pi(z_t)} \beta^{s-t} u(c_s(z_s)) = \\ &= \max_{c_t(z_t), a_t(z_t)} \left\{ u(c_t(z_t)) + \max_{\{c_s(z_s), a_s(z_s)\}_{t+1}^T} \sum_{s=t+1}^T \sum_{z_s \subset z_t} \frac{\pi(z_s)}{\pi(z_t)} \beta^{s-t} u(c_s(z_s)) \right\} \end{aligned}$$

$$\text{s.t. } a_t(z_t) = (1+r)a_{t-1}(z_{t-1}) + y_t(z_t) - c_t(z_t)$$

$$a_s(z_s) = (1+r)a_{s-1}(z_{s-1}) + y_s(z_s) - c_s(z_s) \quad \forall s \in \{t+1, t+2, \dots, T\}, \quad \forall z_s \subset z_t$$

$$a_t(z_t) \geq -b$$

$$a_s(z_s) \geq -b \quad \forall s \in \{t+1, t+2, \dots, T\}, \quad \forall z_s \subset z_t$$

$$a_T(z_T) \geq 0 \quad \forall z_T$$

$$a_{t-1} \text{ given}$$

Problem of agent of age t

$$\begin{aligned}
 V_t(z_t) &= \max_{\{c_s(z_s), a_s(z_s)\}_{s=t}^T} \sum_{s=t}^T \sum_{z_s \subset z_t} \frac{\pi(z_s)}{\pi(z_t)} \beta^{s-t} u(c_s(z_s)) = \\
 &= \max_{c_t(z_t), a_t(z_t)} \left\{ u(c_t(z_t)) + \max_{\{c_s(z_s), a_s(z_s)\}_{t+1}^T} \sum_{z_{t+1} \subset z_t} \frac{\pi(z_{t+1})}{\pi(z_t)} \sum_{s=t+1}^T \sum_{z_s \subset z_{t+1}} \frac{\pi(z_s)}{\pi(z_{t+1})} \beta^{s-t} u(c_s(z_s)) \right\}
 \end{aligned}$$

$$s.t. \quad a_t(z_t) = (1+r)a_{t-1}(z_{t-1}) + y_t(z_t) - c_t(z_t)$$

$$a_s(z_s) = (1+r)a_{s-1}(z_{s-1}) + y_s(z_s) - c_s(z_s) \quad \forall s \in \{t+1, t+2, \dots, T\}, \quad \forall z_s \subset z_t$$

$$a_t(z_t) \geq -b$$

$$a_s(z_s) \geq -b \quad \forall s \in \{t+1, t+2, \dots, T\}, \quad \forall z_s \subset z_t$$

$$a_T(z_T) \geq 0 \quad \forall z_T$$

$$a_{t-1} \text{ given}$$

Problem of agent of age t

$$\begin{aligned}
 V_t(z_t) &= \max_{\{c_s(z_s), a_s(z_s)\}_{s=t}^T} \sum_{s=t}^T \sum_{z_s \subset z_t} \frac{\pi(z_s)}{\pi(z_t)} \beta^{s-t} u(c_s(z_s)) = \\
 &= \max_{c_t(z_t), a_t(z_t)} \left\{ u(c_t(z_t)) + \beta \sum_{z_{t+1} \subset z_t} \frac{\pi(z_{t+1})}{\pi(z_t)} \max_{\{c_s(z_s), a_s(z_s)\}_{t+1}^T} \sum_{s=t+1}^T \sum_{z_s \subset z_{t+1}} \frac{\pi(z_s)}{\pi(z_{t+1})} \beta^{s-(t+1)} u(c_s(z_s)) \right\}
 \end{aligned}$$

$$s.t. \quad a_t(z_t) = (1+r)a_{t-1}(z_{t-1}) + y_t(z_t) - c_t(z_t)$$

$$a_s(z_s) = (1+r)a_{s-1}(z_{s-1}) + y_s(z_s) - c_s(z_s) \quad \forall s \in \{t+1, t+2, \dots, T\}, \quad \forall z_s \subset z_t$$

$$a_t(z_t) \geq -b$$

$$a_s(z_s) \geq -b \quad \forall s \in \{t+1, t+2, \dots, T\}, \quad \forall z_s \subset z_t$$

$$a_T(z_T) \geq 0 \quad \forall z_T$$

$$a_{t-1} \text{ given}$$

$$\begin{aligned}
 V_t(z_t) &= \max_{\{c_s(z_s), a_s(z_s)\}_{s=t}^T} \sum_{s=t}^T \sum_{z_s \subset z_t} \frac{\pi(z_s)}{\pi(z_t)} \beta^{s-t} u(c_s(z_s)) = \\
 &= \max_{c_t(z_t), a_t(z_t)} \left\{ u(c_t(z_t)) + \beta \sum_{z_{t+1} \subset z_t} \frac{\pi(z_{t+1})}{\pi(z_t)} V_{t+1}(z_{t+1}) \right\}
 \end{aligned}$$

$$\begin{aligned}
 \text{s.t. } \quad & a_t(z_t) = (1+r)a_{t-1}(z_{t-1}) + y_t(z_t) - c_t(z_t) \\
 & a_t(z_t) \geq -b \\
 & a_{t-1} \text{ given}
 \end{aligned}$$

$$\begin{aligned}
 V_t(z_t) &= \max_{\{c_s(z_s), a_s(z_s)\}_{s=t}^T} \sum_{s=t}^T \sum_{z_s \subset z_t} \frac{\pi(z_s)}{\pi(z_t)} \beta^{s-t} u(c_s(z_s)) = \\
 &= \max_{c_t(z_t), a_t(z_t)} \left\{ u(c_t(z_t)) + \beta \mathbb{E}_t[V_{t+1}(z_{t+1})] \right\}
 \end{aligned}$$

$$\begin{aligned}
 s.t. \quad & a_t(z_t) = (1+r)a_{t-1}(z_{t-1}) + y_t(z_t) - c_t(z_t) \\
 & a_t(z_t) \geq -b \\
 & a_{t-1} \text{ given}
 \end{aligned}$$

Bellman-equation

$$V_t(z_t) = \max_{c_t(z_t), a_t(z_t)} \left\{ u(c_t(z_t)) + \beta \mathbb{E}_t [V_{t+1}(z_{t+1})] \right\}$$

$$\begin{aligned} s.t. \quad & a_t(z_t) = (1 + r)a_{t-1}(z_{t-1}) + y_t(z_t) - c_t(z_t) \\ & a_t(z_t) \geq -b \end{aligned}$$

Intuition:

- V_{t+1} incorporates everything about the future effects of your choices that you need to care about,
- so once you use this information through V_{t+1} , you don't need to care about future actions and constraints anymore to decide optimally today!

iid income shocks

- z_t denotes a whole history - very general framework, let's check something simpler!
- The simplest case is of iid income shocks. z_t is the series of past income shocks
 $z_t = \{y_0, y_1, \dots, y_t\}$

iid income shocks

- z_t denotes a whole history - very general framework, let's check something simpler!
- The simplest case is of iid income shocks. z_t is the series of past income shocks
 $z_t = \{y_0, y_1, \dots, y_t\}$
- Independent income shocks \Rightarrow past income realization levels are not informative to predict future income!
- Past income shocks matter only through current wealth.

What does this mean?

iid income shocks

- z_t denotes a whole history - very general framework, let's check something simpler!
- The simplest case is of iid income shocks. z_t is the series of past income shocks
 $z_t = \{y_0, y_1, \dots, y_t\}$
- Independent income shocks \Rightarrow past income realization levels are not informative to predict future income!
- Past income shocks matter only through current wealth.

What does this mean?

- No need to keep track of whole histories
- Can condense information into the pair (a_{t-1}, y_t)
- (a_{t-1}, y_t) determines the "state": they contain all the knowledge we need to make optimal decisions.

Wealth and income as states

$$V_t(a_{t-1}, y_t) = \max_{c_t(a_{t-1}, y_t), a_t(a_{t-1}, y_t)} \left\{ u(c_t(a_{t-1}, y_t)) + \beta \mathbb{E}_t \left[V_{t+1}(a_t(a_{t-1}, y_t), y_{t+1}) \right] \right\}$$

$$s.t. \quad a_t(a_{t-1}, y_t) = (1 + r)a_{t-1} + y_t - c_t(a_{t-1}, y_t)$$

$$a_t(a_{t-1}, y_t) \geq -b$$

Wealth and income as states

$$V_t(a_{t-1}, y_t) = \max_{c_t(a_{t-1}, y_t), a_t(a_{t-1}, y_t)} \left\{ u(c_t(a_{t-1}, y_t)) + \beta \mathbb{E}_t \left[V_{t+1}(a_t(a_{t-1}, y_t), y_{t+1}) \right] \right\}$$

$$s.t. \quad a_t(a_{t-1}, y_t) = (1 + r)a_{t-1} + y_t - c_t(a_{t-1}, y_t)$$

$$a_t(a_{t-1}, y_t) \geq -b$$

We can substitute out consumption using the constraint! \Rightarrow We only have one decision variable

$$V_t(a_{t-1}, y_t) = \max_{a_t(a_{t-1}, y_t) \geq -b} \left\{ u((1+r)a_{t-1} + y_t - a_t(a_{t-1}, y_t)) + \beta \mathbb{E}_t \left[V_{t+1}(a_t(a_{t-1}, y_t), y_{t+1}) \right] \right\}$$

Wealth and income as states

$$V_t(a_{t-1}, y_t) = \max_{c_t(a_{t-1}, y_t), a_t(a_{t-1}, y_t)} \left\{ u(c_t(a_{t-1}, y_t)) + \beta \mathbb{E}_t \left[V_{t+1}(a_t(a_{t-1}, y_t), y_{t+1}) \right] \right\}$$
$$\text{s.t. } a_t(a_{t-1}, y_t) = (1+r)a_{t-1} + y_t - c_t(a_{t-1}, y_t)$$
$$a_t(a_{t-1}, y_t) \geq -b$$

We can substitute out consumption using the constraint! \Rightarrow We only have one decision variable

$$V_t(a_{t-1}, y_t) = \max_{a_t(a_{t-1}, y_t) \geq -b} \left\{ u((1+r)a_{t-1} + y_t - a_t(a_{t-1}, y_t)) + \beta \mathbb{E}_t \left[V_{t+1}(a_t(a_{t-1}, y_t), y_{t+1}) \right] \right\}$$

To simplify notation, we often write

$$V_t(a_{t-1}, y_t) = \max_{a_t \geq -b} \left\{ u((1+r)a_{t-1} + y_t - a_t) + \beta \mathbb{E}_t \left[V_{t+1}(a_t, y_{t+1}) \right] \right\}$$

It is still true that the current policy a_t is a function of the current state (a_{t-1}, y_t) !

Cash-on-hand as state

Actually, we can do better!

- We don't care where our current resources come from, only matters, how much!
- Cash-on-hand

$$x_t = (1 + r)a_{t-1} + y_t$$

is the perfect state variable (when income is iid).

Cash-on-hand as state

Actually, we can do better!

- We don't care where our current resources come from, only matters, how much!
- Cash-on-hand

$$x_t = (1 + r)a_{t-1} + y_t$$

is the perfect state variable (when income is iid).

$$V_t(x_t) = \max_{c_t, a_t} \left\{ u(c_t) + \beta \mathbb{E}_t[V_{t+1}(x_{t+1})] \right\}$$

$$s.t. \quad a_t = x_t - c_t$$

$$x_{t+1} = (1 + r)a_t + y_{t+1}$$

$$a_t \geq -b$$

Cash-on-hand as state

Actually, we can do better!

- We don't care where our current resources come from, only matters, how much!
- Cash-on-hand

$$x_t = (1 + r)a_{t-1} + y_t$$

is the perfect state variable (when income is iid).

$$V_t(x_t) = \max_{c_t, a_t} \left\{ u(c_t) + \beta \mathbb{E}_t[V_{t+1}(x_{t+1})] \right\}$$

$$s.t. \quad a_t = x_t - c_t$$

$$x_{t+1} = (1 + r)a_t + y_{t+1}$$

$$a_t \geq -b$$

Again we can substitute out!

$$V_t(x_t) = \max_{a_t \geq -b} \left\{ u(x_t - a_t) + \beta \mathbb{E}_t[V_{t+1}(a_t(1 + r) + y_{t+1})] \right\}$$

What is a 'solution' of a model?

- Closed-form solution:

Interesting variable = Formula involving parameters & other given quantities

Very convenient, but for our models usually doesn't exist.

What is a 'solution' of a model?

- Closed-form solution:

Interesting variable = Formula involving parameters & other given quantities

Very convenient, but for our models usually doesn't exist.

- Numerical solution:

We are able to compute the optimal policies for a given set of parameters and state variables. We don't know the formula!

What is a 'solution' of a model?

- Closed-form solution:

Interesting variable = Formula involving parameters & other given quantities

Very convenient, but for our models usually doesn't exist.

- Numerical solution:

We are able to compute the optimal policies for a given set of parameters and state variables. We don't know the formula!

In our model,

- given a set of parameters,
- for any age and
- for any cash-on-hand level;
- we want to be able to compute optimal consumption and saving, and the value function.

Solving our consumption-saving model

Last period is trivial:

- Save nothing, consume all cash-on-hand: $a_T(x_T) = 0$ $c_T(x_T) = x_T$
- Value coincides with utility from eating everything: $V_T(x_T) = u(x_T)$

Solving our consumption-saving model

Last period is trivial:

- Save nothing, consume all cash-on-hand: $a_T(x_T) = 0$ $c_T(x_T) = x_T$
- Value coincides with utility from eating everything: $V_T(x_T) = u(x_T)$

What to do next? We continue with $t = T - 1$ based on

$$V_{T-1}(x_{T-1}) = \max_{a_{T-1} \geq -b} \left\{ u(x_{T-1} - a_{T-1}) + \beta \mathbb{E}_{T-1} \left[V_T(a_{T-1}(1+r) + y_T) \right] \right\}$$

Solving our consumption-saving model

Last period is trivial:

- Save nothing, consume all cash-on-hand: $a_T(x_T) = 0$ $c_T(x_T) = x_T$
- Value coincides with utility from eating everything: $V_T(x_T) = u(x_T)$

What to do next? We continue with $t = T - 1$ based on

$$V_{T-1}(x_{T-1}) = \max_{a_{T-1} \geq -b} \left\{ u(x_{T-1} - a_{T-1}) + \beta \mathbb{E}_{T-1} \left[V_T(a_{T-1}(1+r) + y_T) \right] \right\}$$

- We can compute value and policies for a given $x = x_{T-1}$.
- But we want to solve for the whole functions (we want to evaluate the solutions potentially anywhere). How to do that on the computer?

Solving our consumption-saving model

Last period is trivial:

- Save nothing, consume all cash-on-hand: $a_T(x_T) = 0$ $c_T(x_T) = x_T$
- Value coincides with utility from eating everything: $V_T(x_T) = u(x_T)$

What to do next? We continue with $t = T - 1$ based on

$$V_{T-1}(x_{T-1}) = \max_{a_{T-1} \geq -b} \left\{ u(x_{T-1} - a_{T-1}) + \beta \mathbb{E}_{T-1} \left[V_T(a_{T-1}(1+r) + y_T) \right] \right\}$$

- We can compute value and policies for a given $x = x_{T-1}$.
- But we want to solve for the whole functions (we want to evaluate the solutions potentially anywhere). How to do that on the computer?
- Interpolation! We store approximations of the exact solution functions.
- We compute the exact values at certain points for x (grid points) and then we perform interpolation over these exact values.
- Then we can get a(n approximated) solution when evaluating c_{T-1} , a_{T-1} or V_{T-1} for any x without going back to the Bellman-equation all the time.

Solving our consumption-saving model

What to do with the previous periods? We iterate backwards based on

$$V_t(x_t) = \max_{a_t \geq -b} \left\{ u(x_t - a_t) + \beta \mathbb{E}_t \left[V_{t+1}(a_t(1+r) + y_{t+1}) \right] \right\}$$

So (knowing V_T) we can compute everything in $T-1$, then we can do $T-2$, and so on until $t=0$.

Solving our consumption-saving model

What to do with the previous periods? We iterate backwards based on

$$V_t(x_t) = \max_{a_t \geq -b} \left\{ u(x_t - a_t) + \beta \mathbb{E}_t \left[V_{t+1}(a_t(1+r) + y_{t+1}) \right] \right\}$$

So (knowing V_T) we can compute everything in $T-1$, then we can do $T-2$, and so on until $t=0$.

In the end we have

- an interpolated value function
- an interpolated consumption function
- an interpolated saving function

for all ages $t \in \{0, 1, 2, \dots, T\}$. Then we are done!

The catch

Over which grid should we interpolate? – Difficult question!

The catch

Over which grid should we interpolate? – Difficult question!

- Top of the grid
 - ▶ Large enough, so that we have a good approximation for any agent in the simulated population
 - ▶ No need to go above plausible wealth levels in the model economy

The catch

Over which grid should we interpolate? – Difficult question!

- Top of the grid
 - ▶ Large enough, so that we have a good approximation for any agent in the simulated population
 - ▶ No need to go above plausible wealth levels in the model economy
- Bottom of the grid
 - ▶ coh should be high enough to satisfy the borrowing limit at the end of the current period without negative consumption:

$$x_t = c_t + a_t \geq a_t \geq -b$$

The catch

Over which grid should we interpolate? – Difficult question!

- Top of the grid
 - ▶ Large enough, so that we have a good approximation for any agent in the simulated population
 - ▶ No need to go above plausible wealth levels in the model economy
- Bottom of the grid
 - ▶ coh should be high enough to satisfy the borrowing limit at the end of the current period without negative consumption:

$$x_t = c_t + a_t \geq a_t \geq -b$$

- ▶ Ignore wealth levels that lead to $-\infty$ value. A debt that cannot be surely repaid results in $-\infty$ value (as it forces negative consumption with positive probability). Natural borrowing limit

$$x_t = c_t + a_t \geq a_t \geq - \sum_{s=t+1}^T \frac{\min\{y_s\}}{(1+r)^{s-t}}$$

is the discounted value of future income **in the worst case**. This is the largest debt that can surely be repaid (under 0 future consumption).

The catch

Over which grid should we interpolate? – Difficult question!

- Top of the grid
 - ▶ Large enough, so that we have a good approximation for any agent in the simulated population
 - ▶ No need to go above plausible wealth levels in the model economy
- Bottom of the grid
 - ▶ coh should be high enough to satisfy the borrowing limit at the end of the current period without negative consumption:

$$x_t = c_t + a_t \geq a_t \geq -b$$

- ▶ Ignore wealth levels that lead to $-\infty$ value. A debt that cannot be surely repaid results in $-\infty$ value (as it forces negative consumption with positive probability). Natural borrowing limit

$$x_t = c_t + a_t \geq a_t \geq - \sum_{s=t+1}^T \frac{\min\{y_s\}}{(1+r)^{s-t}}$$

is the discounted value of future income **in the worst case**. This is the largest debt that can surely be repaid (under 0 future consumption).

Taking the maximum of the above two limits works well.

The catch

Over which grid should we interpolate? – Difficult question!

- How to space points over the grid?
 - ▶ Even is simple
 - ▶ Usually better to have relatively more points at the bottom (low wealth), as functions are more curved there (more curvature \Rightarrow more errors)

The catch

Over which grid should we interpolate? – Difficult question!

- How to space points over the grid?
 - ▶ Even is simple
 - ▶ Usually better to have relatively more points at the bottom (low wealth), as functions are more curved there (more curvature \Rightarrow more errors)
- How many grid points?
 - ▶ A lot. Converge to true solution as the grid is getting more dense.
 - ▶ If further increasing the number of points has little effect on solutions, you probably have enough.

Infinite horizon

Infinite horizon means maximizing something like this

$$\mathbb{E}_0 \sum_{t=0}^{\infty} \beta^t u(c_t)$$

- Does it make sense to study infinite horizon models? What do you think?

Infinite horizon

Infinite horizon means maximizing something like this

$$\mathbb{E}_0 \sum_{t=0}^{\infty} \beta^t u(c_t)$$

- Does it make sense to study infinite horizon models? What do you think?

Bad:

- Not realistic
- Cannot study lifecycle patterns
- Difficult decisions when calibrating. For example, mean income should be
 - ▶ average income over the economy in a particular year? or
 - ▶ average income of a particular cohort over their career?

Infinite horizon

Infinite horizon means maximizing something like this

$$\mathbb{E}_0 \sum_{t=0}^{\infty} \beta^t u(c_t)$$

- Does it make sense to study infinite horizon models? What do you think?

Bad:

- Not realistic
- Cannot study lifecycle patterns
- Difficult decisions when calibrating. For example, mean income should be
 - ▶ average income over the economy in a particular year? or
 - ▶ average income of a particular cohort over their career?

Good:

- One state variable fewer (age) \Rightarrow easier to solve, simpler to understand solution
- Captures dynastic behavior in a compact way

Infinite horizon - how to solve them

- Can derive a similar Bellman equation to finite horizon problems (deeper math due to infinity)
- But there is no age t , so same value function in each period:

$$V(x) = \max_{a \geq -b} \left\{ u(x - a) + \beta \mathbb{E} \left[V(a(1 + r) + y') \right] \right\}$$

How to solve this functional equation numerically?

Infinite horizon - how to solve them

- Can derive a similar Bellman equation to finite horizon problems (deeper math due to infinity)
- But there is no age t , so same value function in each period:

$$V(x) = \max_{a \geq -b} \left\{ u(x - a) + \beta \mathbb{E} \left[V(a(1 + r) + y') \right] \right\}$$

How to solve this functional equation numerically?

- Start with any policy guess (e.g. eating everything, like people of age T in the finite horizon model). Implies a guess for the value function.
- Iterate backwards using the Bellman-equation for t and $t + 1$ value functions.
Interpretation: $t + 1$ is the old guess, t is the new guess.

Infinite horizon - how to solve them

- Can derive a similar Bellman equation to finite horizon problems (deeper math due to infinity)
- But there is no age t , so same value function in each period:

$$V(x) = \max_{a \geq -b} \left\{ u(x - a) + \beta \mathbb{E} \left[V(a(1 + r) + y') \right] \right\}$$

How to solve this functional equation numerically?

- Start with any policy guess (e.g. eating everything, like people of age T in the finite horizon model). Implies a guess for the value function.
- Iterate backwards using the Bellman-equation for t and $t + 1$ value functions. Interpretation: $t + 1$ is the old guess, t is the new guess.
- Continue iteration until V_t and V_{t+1} are close enough
- Then you can claim $V \approx V_t \approx V_{t+1}$.

Infinite horizon - how to solve them

- Can derive a similar Bellman equation to finite horizon problems (deeper math due to infinity)
- But there is no age t , so same value function in each period:

$$V(x) = \max_{a \geq -b} \left\{ u(x - a) + \beta \mathbb{E} \left[V(a(1 + r) + y') \right] \right\}$$

How to solve this functional equation numerically?

- Start with any policy guess (e.g. eating everything, like people of age T in the finite horizon model). Implies a guess for the value function.
- Iterate backwards using the Bellman-equation for t and $t + 1$ value functions. Interpretation: $t + 1$ is the old guess, t is the new guess.
- Continue iteration until V_t and V_{t+1} are close enough
- Then you can claim $V \approx V_t \approx V_{t+1}$.
- This procedure is guaranteed to converge to the unique true solution under quite broad assumptions. (Banach fixed-point theorem)