

Real-time Graphics

4. Global Illumination

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Rendering equation

$$L_o(\mathbf{x}, \omega, \lambda, t) = L_e(\mathbf{x}, \omega, \lambda, t) + \int_{\Omega} f_r(\mathbf{x}, \omega', \omega, \lambda, t) L_i(\mathbf{x}, \omega', \lambda, t) (-\omega' \cdot \mathbf{n}) d\omega'.$$

- λ is a particular wavelength of light
 - t is time
 - $L_o(\mathbf{x}, \omega, \lambda, t)$ is the total amount of light of wavelength λ directed outward along direction ω at time t , from a particular position \mathbf{x}
 - $L_e(\mathbf{x}, \omega, \lambda, t)$ is emitted light
 - $\int_{\Omega} \dots d\omega'$ is an integral over a hemisphere of inward directions
 - $f_r(\mathbf{x}, \omega', \omega, \lambda, t)$ is the proportion of light reflected from ω' to ω at position \mathbf{x} , time t , and at wavelength λ
 - $L_i(\mathbf{x}, \omega', \lambda, t)$ is light of wavelength λ coming inward toward \mathbf{x} from direction ω' at time t
 - $-\omega' \cdot \mathbf{n}$ is the attenuation of inward light due to incident angle
- Global illumination: contribution of neighboring scene points to illumination
 - Ambient occlusion, shadows, ray-tracing, radiosity, photon mapping, path tracing, reflections, refractions, caustics, ...



Ambient term

- Simulating light scattered many times by environment
- There are surface points with different number of accumulating rays (plane parts vs. corners)
- Ambient light is NOT constant for all points
- Perceptual clues – depth, curvature, spatial proximity



Ambient occlusion



Ambient occlusion

- For illuminating point P , compute visibility from P in all hemisphere directions

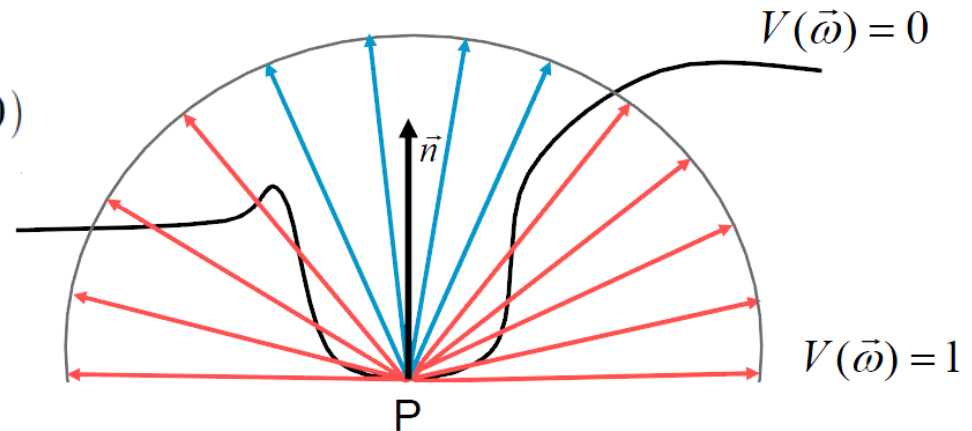
$$AO(P, \vec{n}) = \frac{1}{\pi} \int_{\Omega} V(P, \vec{\omega}) \cdot \max(\vec{n} \cdot \vec{\omega}, 0) d\vec{\omega}$$

P – illuminated point

\vec{n} – normal at point P

$V(P, \vec{\omega})$ – visibility function

$$AO(P, \vec{n}) = \frac{1}{\pi} \sum_{\Omega} V(P, \vec{\omega}) \cdot \max(\vec{n} \cdot \vec{\omega}, 0)$$



AO computation

- Monte Carlo – computing integral by sampling hemisphere with random rays

$$AO(P, \vec{n}) = \frac{1}{n} \sum_{i=0}^{n-1} V(P, \vec{rnd}_i \omega) \cdot \max(\vec{n} \cdot \vec{rnd}_i \omega, 0)$$

$\vec{rnd}_i \omega = i\text{-th random vector}$

- Distribution of random rays?
- Still not real-time
- Static geometry & lights – offline precomputation of ambient maps



AO – object space

- Compute intersection with of ray from illuminating point with objects in scene
- Intersection with hierarchical simplified geometry
- Intersection only with close objects
- Usually computation per-vertex
- Performance dependent on geometry complexity



AO – screen space

- Computation of visibility function in screen space, using data about pixels (fragments)
- State of the Art
- Post-processing effect
- Geometry independent
- Requires (1. pass)
 - Pixel depth values
 - Pixel normal values

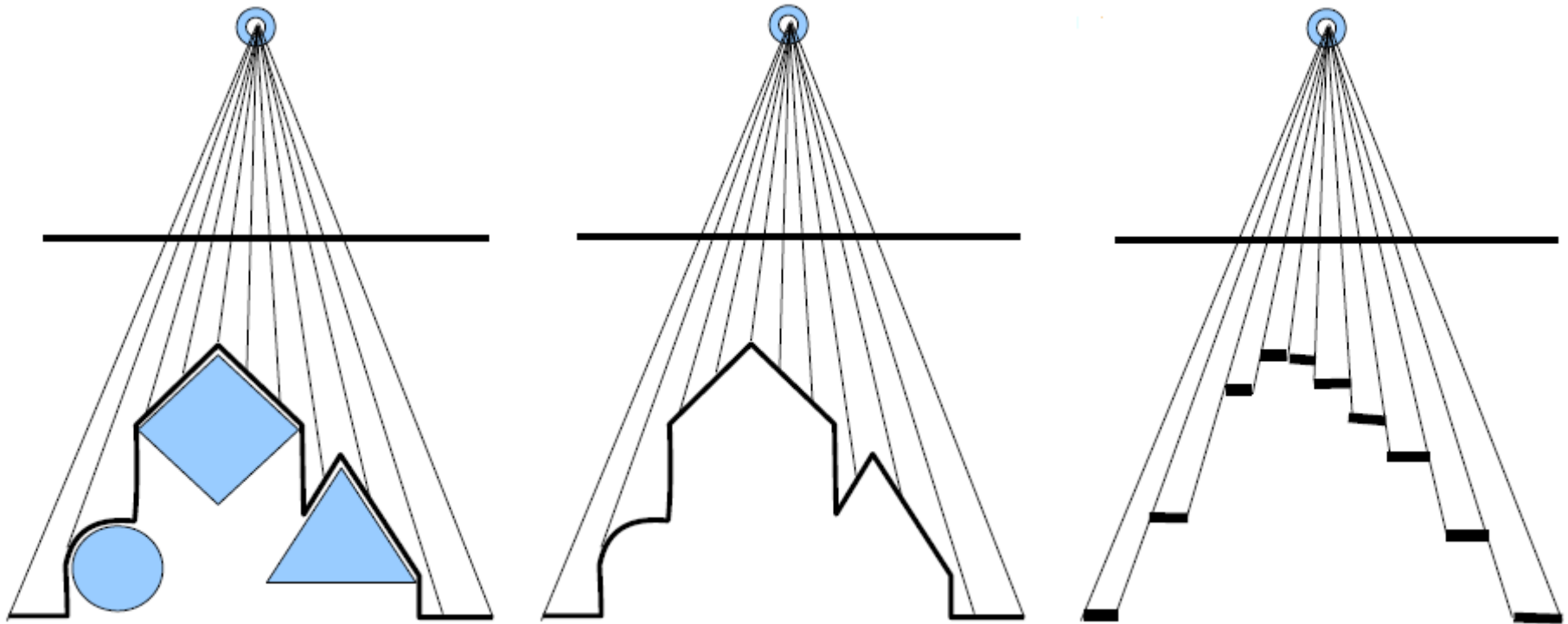


Blizzard Entertainment



Depth buffer

- Approximation of visible geometry



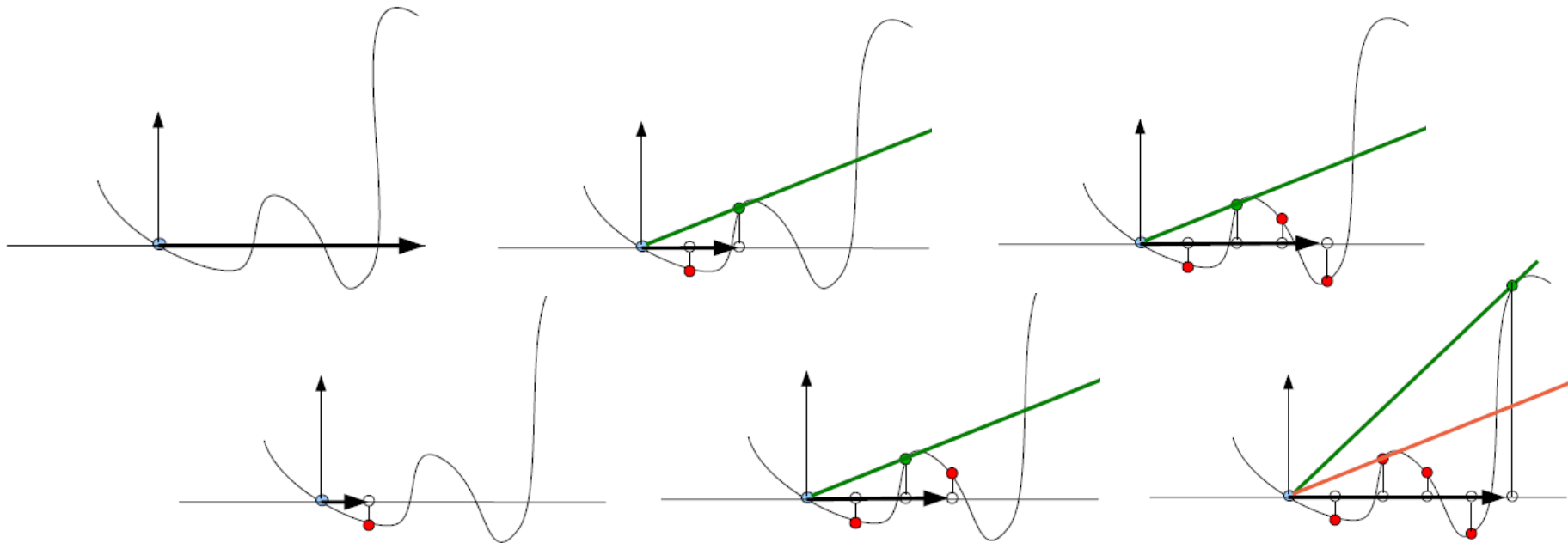
SSAO

- Screen-space ambient occlusion
- Computation of visibility functions from depth values and from normals
- For illuminating point P , sample depth values in P neighborhood and approximate visibility function
- Sampling first in given direction and given region of interest



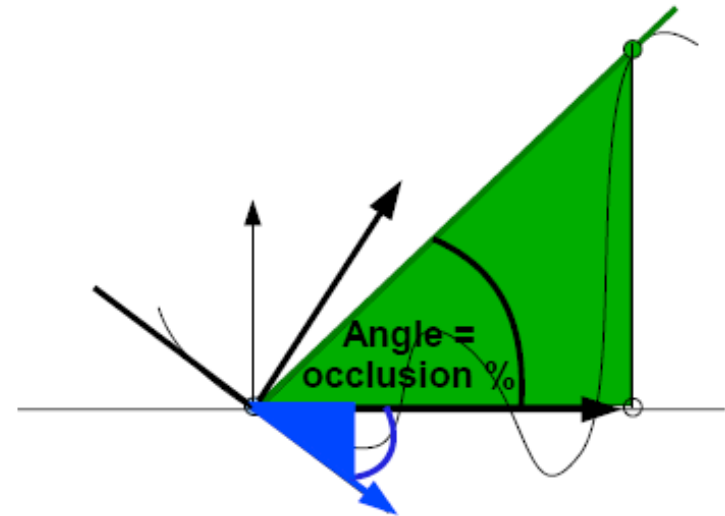
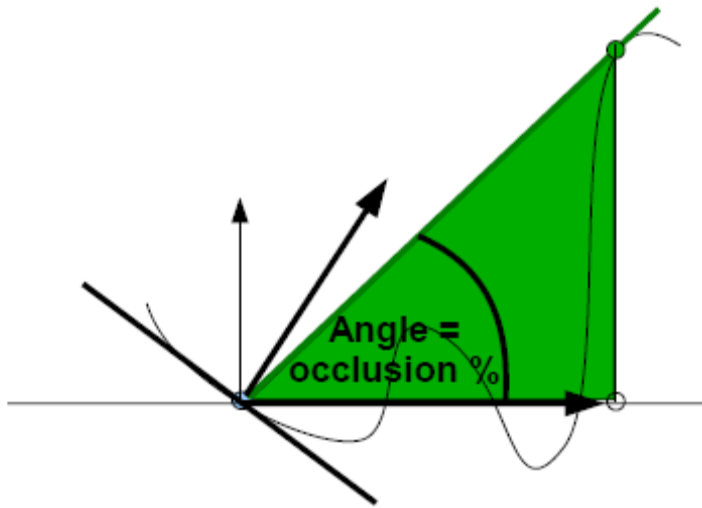
Horizon-based SSAO

- Occlusion in height field
- Sampling height field along ray



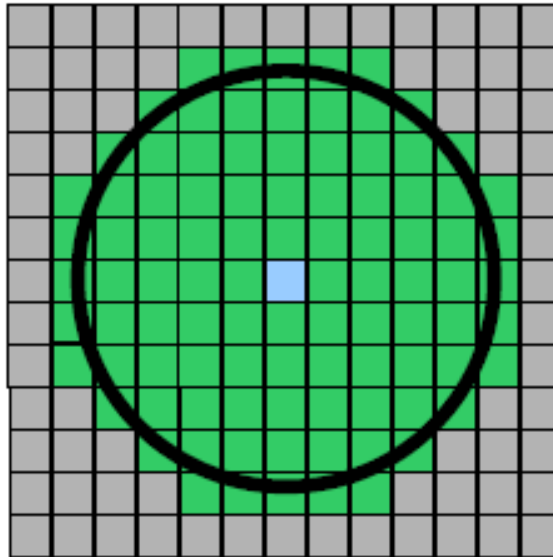
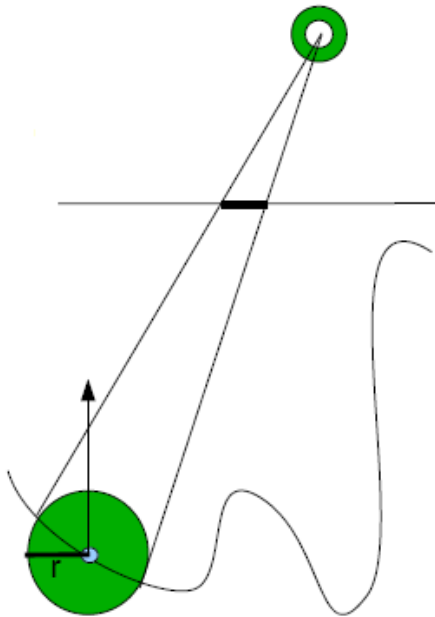
Horizon-based SSAO

- Getting horizon angle $h(\theta)$ for direction θ
- Given normal in P -> tangent vector in P -> signed tangent angle $t(\theta)$
- $AO = \sin(h(\theta)) - \sin(t(\theta))$



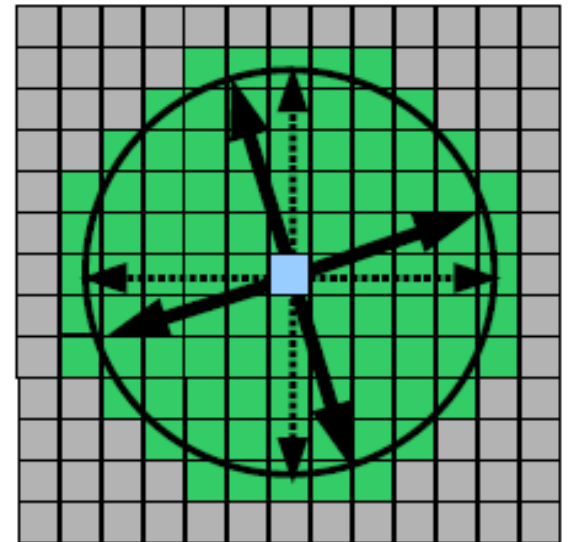
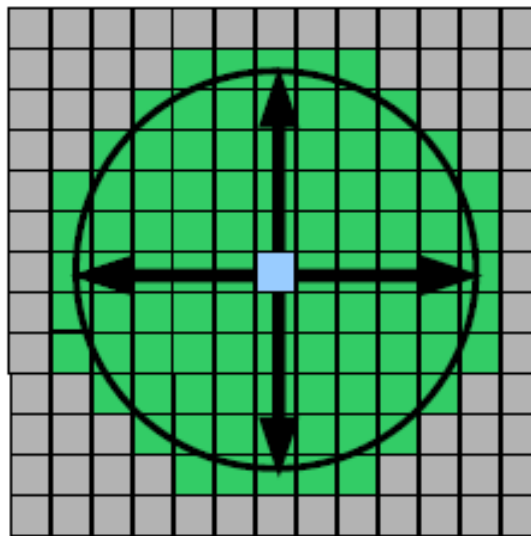
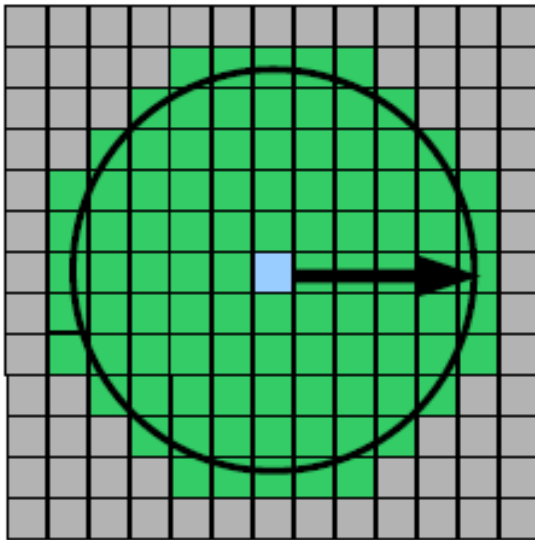
SSAO parameters

- Number of samples per ray = area of interest
- Radius r is constant and defined in eye space
- Calculate projection of sphere in screen space



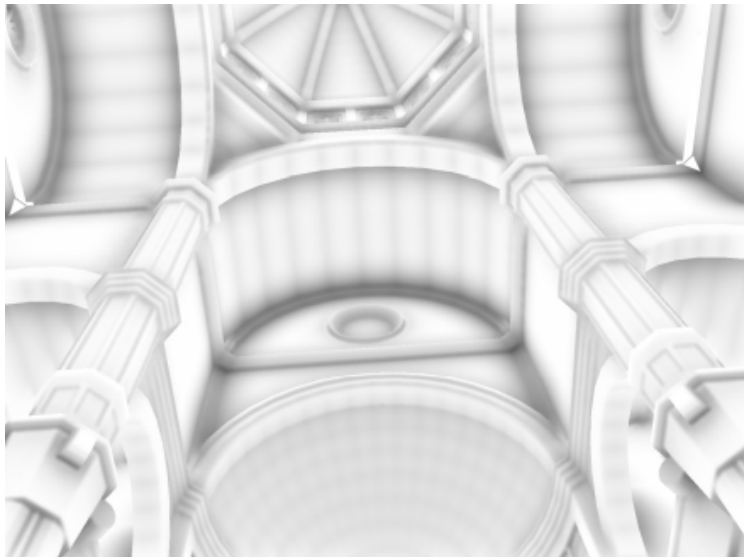
SSAO parameters

- Sampling rays – user defined number
- Random rotation of rays
- Jitter samples along ray

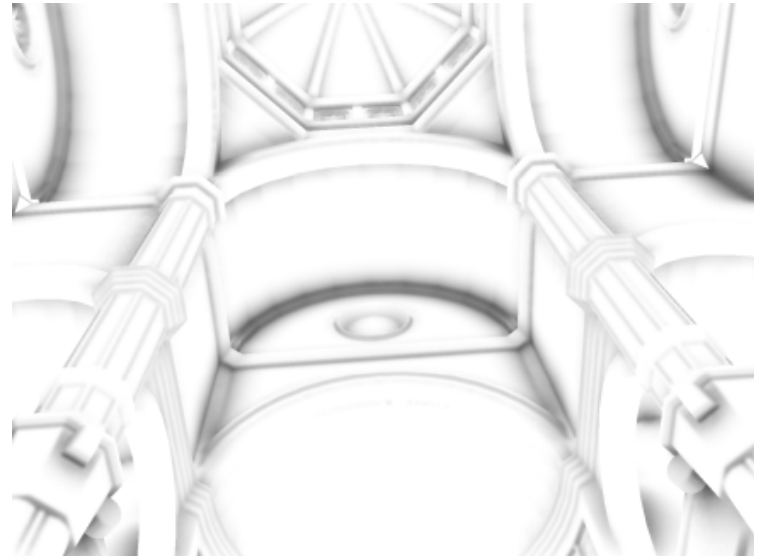


SSAO angle bias

- Ignore occlusion near the tangent plane
- Remove low tessellation artifacts
- Horizon angle is at least some value



No angle bias

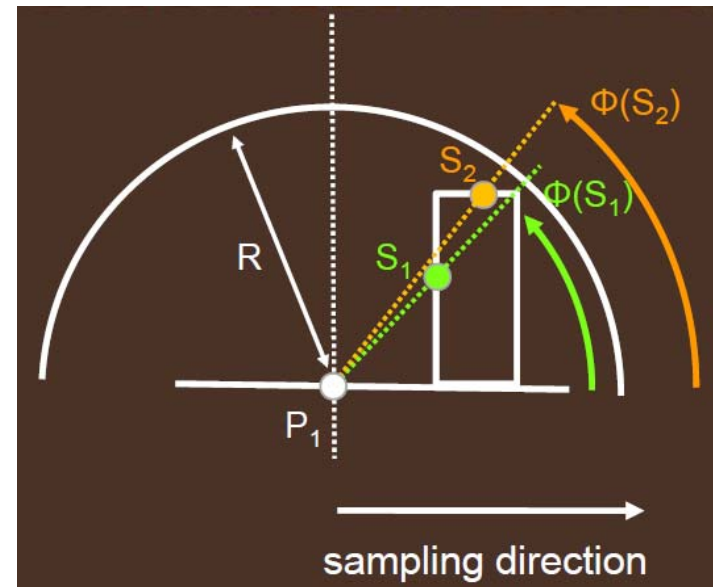


With 30 deg angle bias



Distance attenuation

- Solving large differences of SSAO values for neighboring pixels
- Using weights for each sample, $W(r) = 1-r^2, \dots$
- Cumulating AO while sampling along ray
 - Initialize WAO = 0
 - After sample S_1
 - $AO(S_1) = \sin(\Phi(S_1)) - \sin t$
 - $WAO += W(S_1) AO(S_1)$
 - After sample S_2
 - If $\Phi(S_2) > \Phi(S_1)$
 - $AO(S_2) = \sin(\Phi(S_2)) - \sin t$
 - $WAO += W(S_2)(AO(S_2) - AO(S_1))$



Distance attenuation



No attenuation



With attenuation, $W(r)=1-r^2$



Noise reduction

- Sampling only few values -> noise, alias
 - Process downscaled depth/normal buffers
 - Blur AO values (remove high frequencies), use depth dependent Gaussian blur



Without Blur

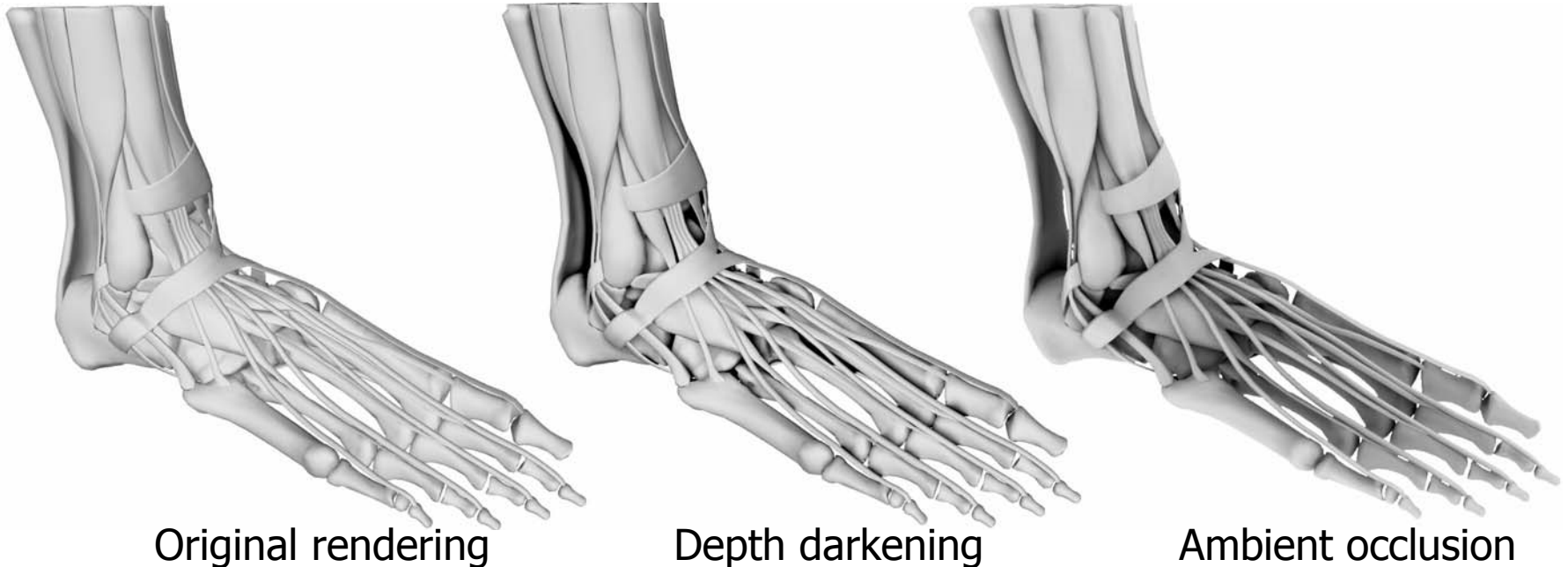


With 15x15 Blur



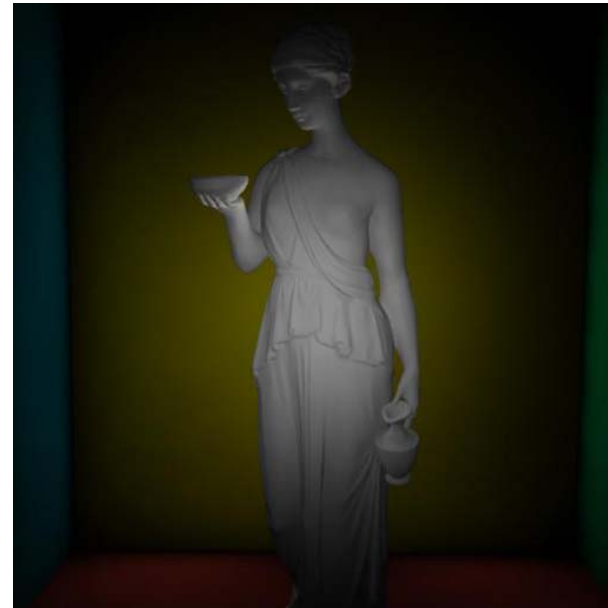
Depth buffer masking

- Depth buffer is blurred, then subtracted from the original depth buffer
- Difference is added to color channels



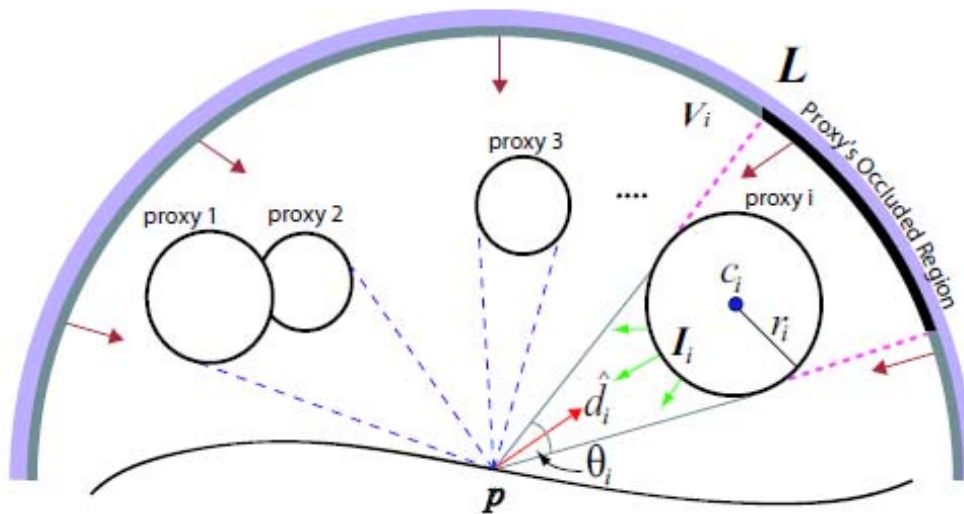
Real-time GI

- Simulating indirect lighting with high number of small direct lights
- Using deferred rendering



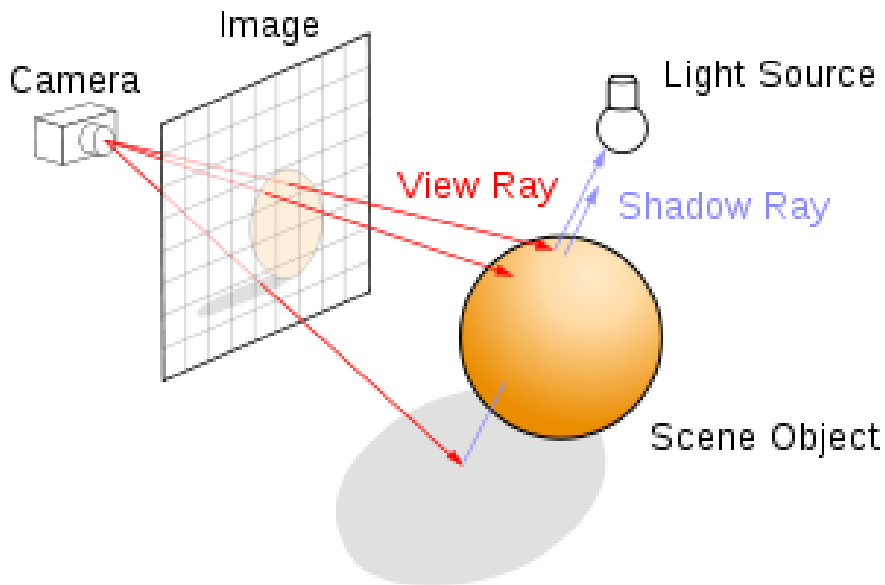
Real-time GI

- Sloan et al.
- Using spherical proxies – simplification of dynamical geometry



Ray tracing

- Backtracking ray that comes to eye
- On surface – multiple bounces – Monte Carlo



Ray tracing

- Crucial – intersection of ray and object in scene
- Intersection speed up
 - Data structures – BVH trees, uniform grids, kD trees, octrees, ...
 - Efficient algorithms
- Local illumination in intersection
- Handle absorption, reflection, refraction and fluorescence in intersection



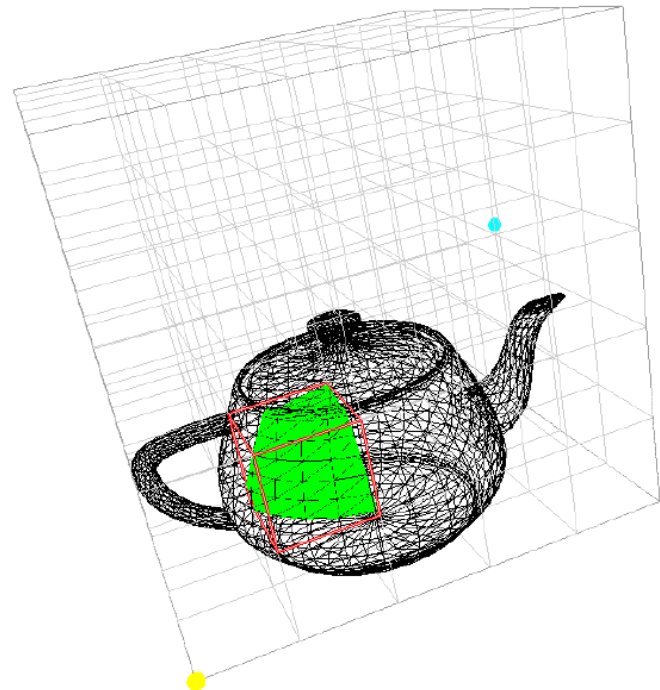
Ray tracing

- Traverse acceleration structure
 - Cull away parts that ray cannot hit
 - Leaf nodes contain primitives
- Primitive intersection
 - Intersect ray directly
 - Return hit status to traversal
- Generate secondary rays from hit

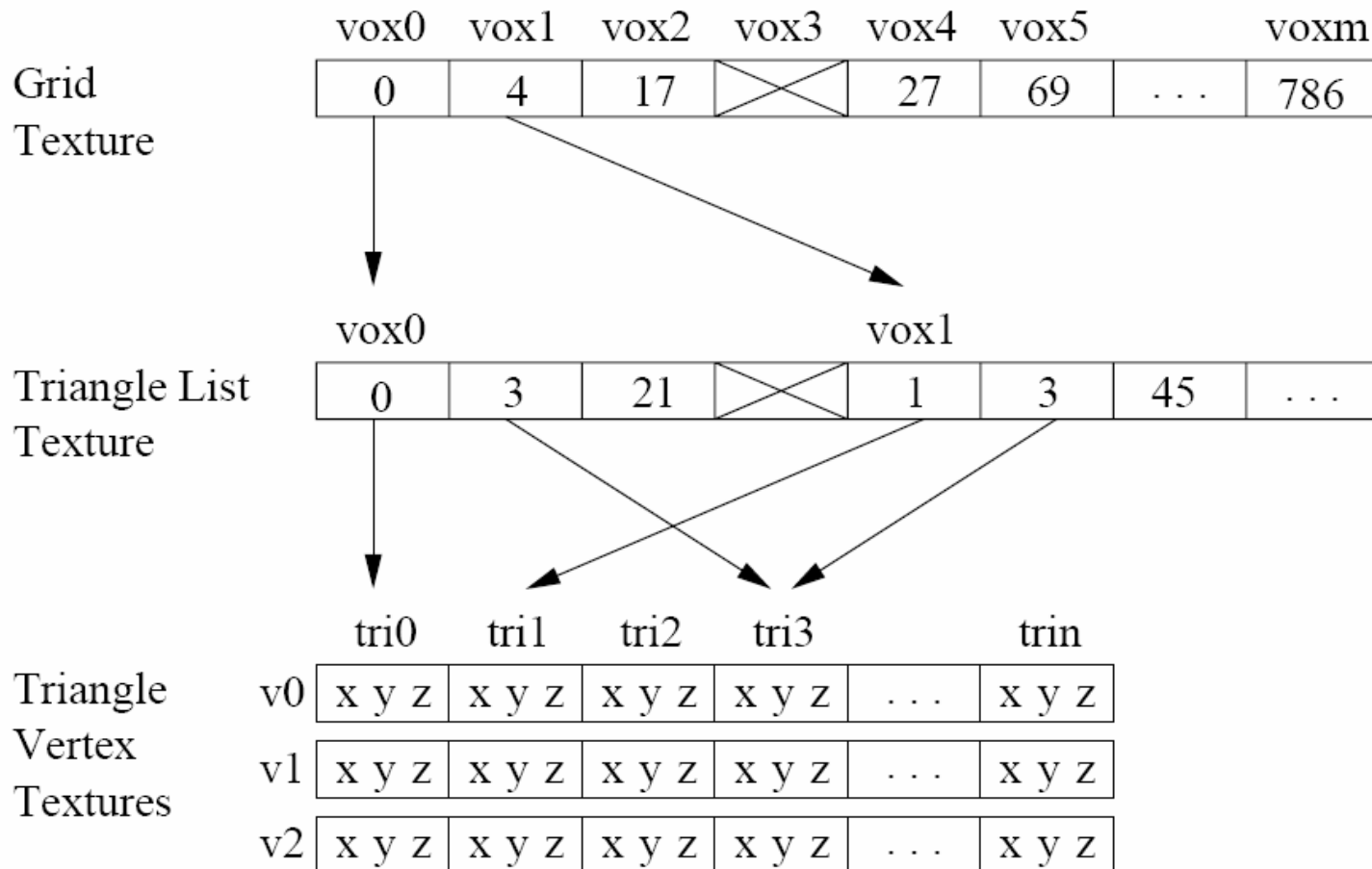


Uniform grid

- GPU friendly → 3D texture
- Dependent fetches for lookup
- Each voxel → several primitives (parts)
- Precomputed on CPU
- Static scene
- Resolution?



Uniform grid - GPU

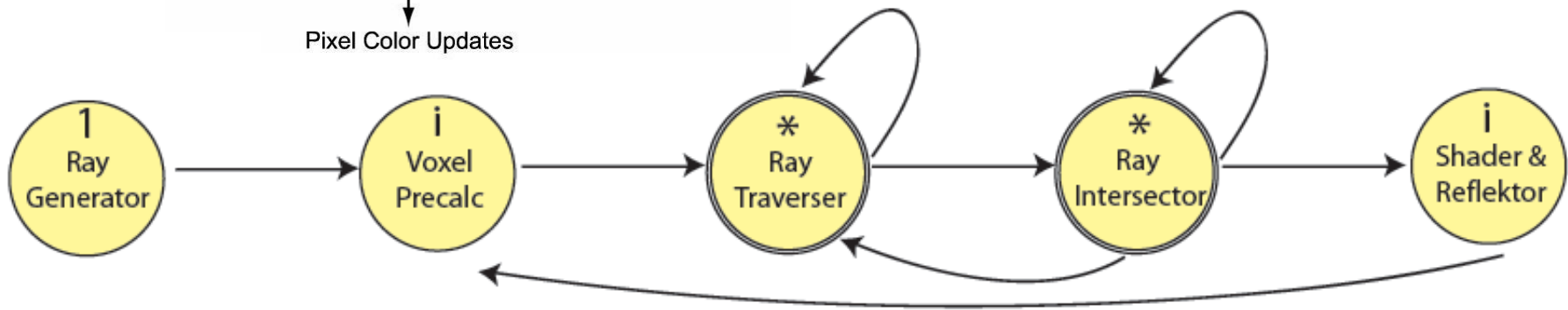
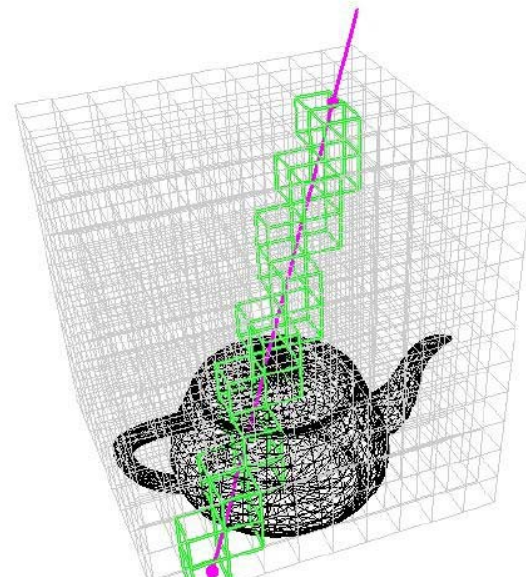
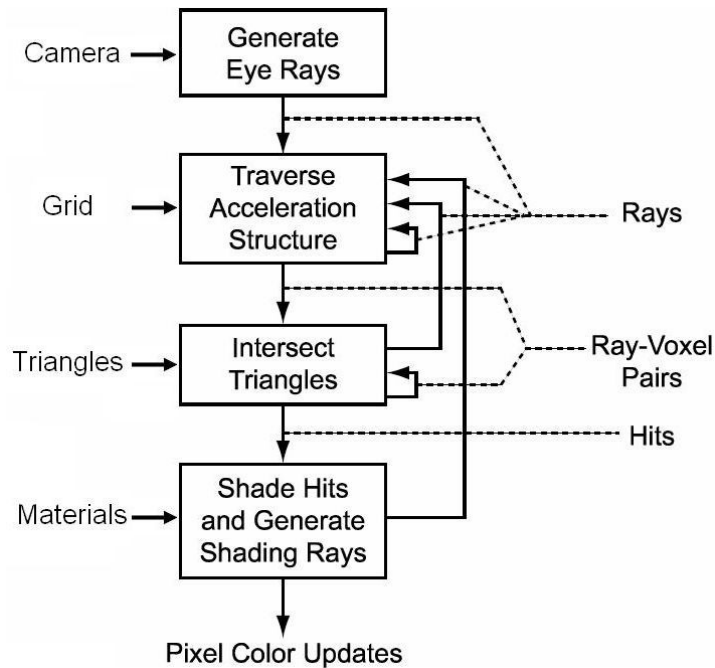


GPU ray tracing

- Rendering quads with screen size
- Using fragment shaders for computation
- Storing data in textures
- Textures for rays, intersections,
- Using 3D DDA for uniform grid traversal
- Computing exact intersection of ray and triangle
- <http://www.clockworkcoders.com/oglsl/rt/>

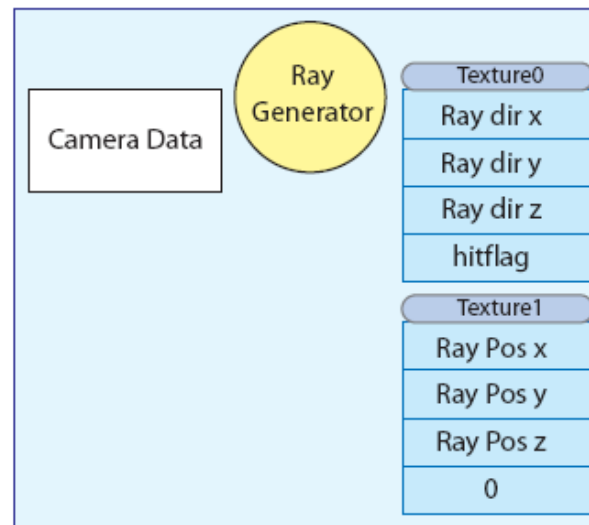


GPU ray tacing



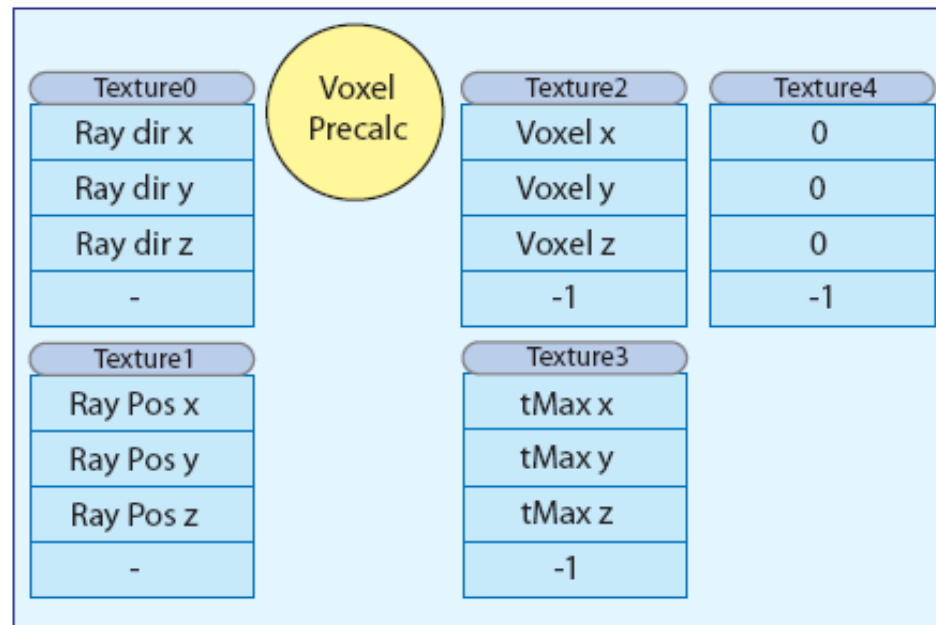
Ray generation

- Generation of ray parameters for each pixel
- In – camera data
- Out – ray starting point and direction, flag if ray hit bounding box of scene



Voxel Precalc

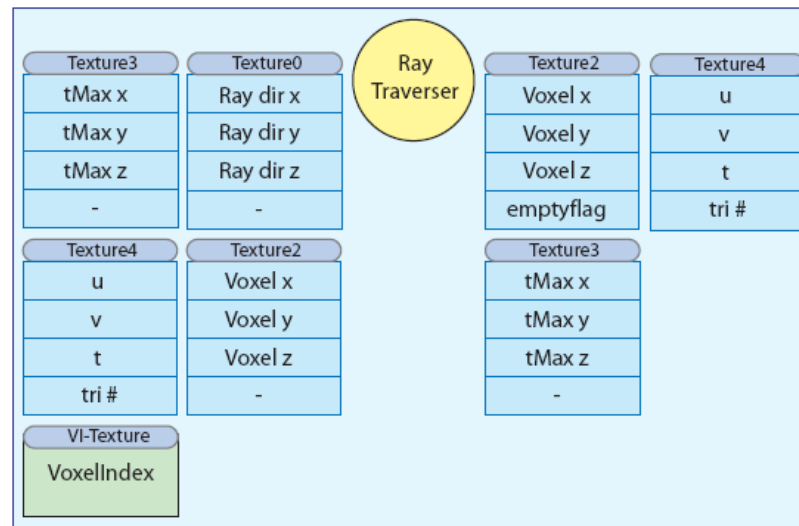
- First voxel of grid along ray
- In – ray vector, position (world coord)
- Out – in/out position (grid coord)



Ray Traverser

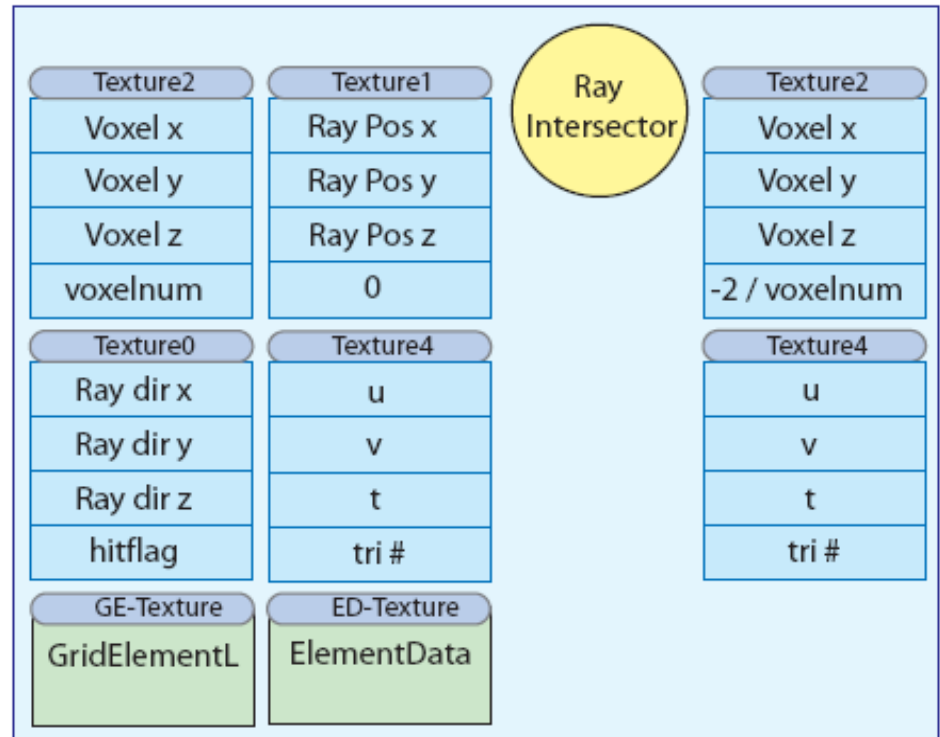
- Traversing grid along ray, setting state of ray based on voxel position and voxel triangles
- In – current voxel
- Out – next voxel

active	traverse Grid
wait	ready to check intersections
dead	ray doesn't hit grid (was already rejected in voxel precalculation)
inactive	a valid hit point was found
overflow	traversal left voxel space (no valid hits)

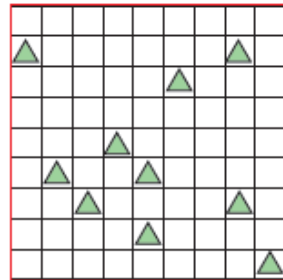


Ray Intersector

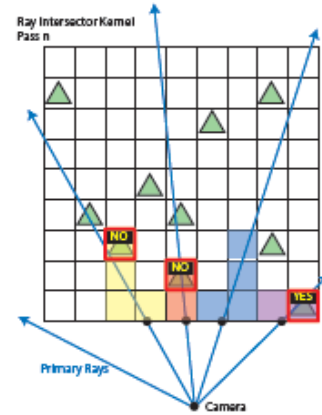
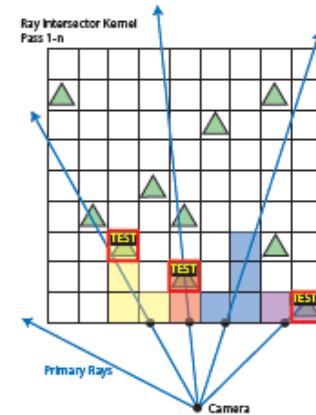
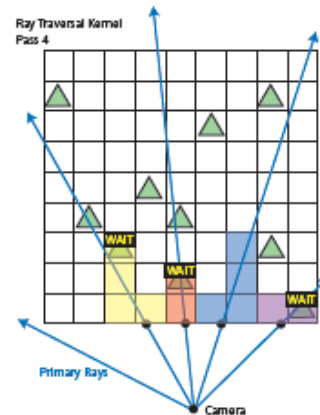
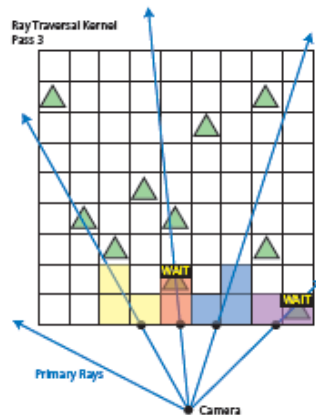
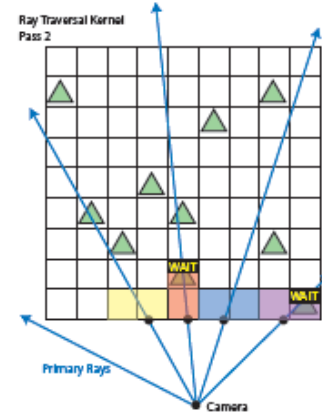
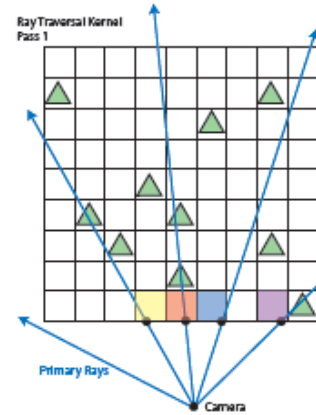
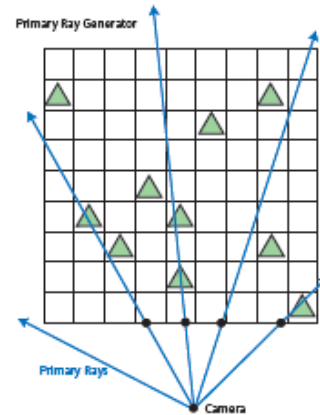
- For wait-state rays, computing intersection of ray and triangles in current ray's voxel
- In – current voxel
- Out – intersection



Loop



● Camera



GPU ray tracing



Other GI sources

- Using GPGPU capabilities, CUDA, OpenCL
- Path tracing
 - <http://igad.nhtv.nl/~bikker/> (CPU)
- Ray tracing:
 - http://www.nvidia.co.uk/object/optix_uk.html
 - <http://graphics.stanford.edu/papers/i3dkdtree>
 - <http://graphics.cs.uiuc.edu/geomrt/>
 - <http://www.mpi-inf.mpg.de/~guenther/BVHonGPU/index.html>



Questions?

