# Reasoning behind ocamltsp

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## 1 Introduction

The purpose of *ocamltsp* is to demonstrate abilities of writing basic OCaml programs and share my knowledge of optimization. The purpose of this document is to show some formal logic behind it.

Writing a complete formal proof of *ocamltsp* is beyond the scope of that demo, however I would like to explain some reasoning behind it, that in future can serve to write a proper proof of optimality.

## 2 Optimal solution

#### 2.1 Definitions

Let path' be a path for problem instance P and  $p_{min}$  be a distance of path'. Let's assume path' fulfills following properties

- 1 path' is a Hamiltonian cycle
- 2  $p_{min}$  is of globally minimal distance

Properties 1 and 2 define optimal solution to instance P of a Traveling  $Salesman\ Problem$ .

## 2.2 Program properties

For convenience main search function optimize is renamed to f.

$$f(path, d, ub)$$
 returns  $(p, d')$ 

Let's assume f be a function that accepts a partial path, it's distance d and best known  $upper\ bound\ ub$ . It returns a tuple of path p and distance d' associated to p.

Function f fulfills following properties

- 3 Final path will be a Hamiltonian cycle (source code line 4)
- 4 f performs a depth first search (recursive calls)
- 5 if branch is cut it implies that it doesn't contain solution better than best known solution (source code line 12)
- 6 optimal solution is guaranteed to be returned at the end
- 7 final solution is optimal solution to TSP

Some additional reasoning to justify points 5, 6 and 7.

- (5) explored branch of f(path, d, ub) will result with distance  $d' \geq ub$
- (6) suppose optimal solution  $p_{min}$  is not returned, this contradicts either property 4 not all solutions have been enumerated either property 5 optimal solution has been in one of excluded branches
- (7) because path' is a Hamiltonian cycle, if not then contradicts property 3 and  $p_{min}$  is of minimal overall length, if not contradicts property 6, if solution that is a Hamiltonian cycle of minimal overall distance is not a solution to  $Traveling\ Salesman\ Problem$  then it contradicts properties 1 and 2

## 3 Source code

```
let rec optimize (dom, dist, path, cost, ub, visit) =
2
      if dom = []
3
      then
        if hamiltonian (1, path, visit)
4
5
        then
6
          (cost, path)
7
        else
8
          (-1, [])
9
      else
10
        if length(hd(dom)) = 1
11
12
          if cost + hd(hd(dist)) \le ub
13
            optimize(tl(dom), tl(dist), insert(path, hd(hd(dom))),
14
                 hd(hd(dist)) + cost, ub, visit)
15
          else
16
            (-1, [])
17
        else
          let (pub, ppath) = optimize(tl(dom), tl(dist), insert(
18
              path, hd(hd(dom))), hd(hd(dist)) + cost, ub, visit)
19
20
            if pub != -1
21
            then
22
              if pub <= ub
23
              then
24
                 let (qub, qpath) = optimize(tl(hd(dom)) :: tl(dom)
                     , tl(hd(dist)) :: tl(dist), path, cost, pub,
                     visit)
25
                in
26
                   if qub != -1
27
                   then
28
                     if pub < qub
29
                     then
30
                       (pub, ppath)
31
                     else if qub < pub
32
                     then
33
                       (qub, qpath)
34
                     else
35
                       (qub, qpath)
                   else
36
37
                     (pub, ppath)
38
              else
39
                 optimize(tl(hd(dom)) :: tl(dom), tl(hd(dist)) ::
                     tl(dist), path, cost, ub, visit)
40
            else
              optimize(tl(hd(dom)) :: tl(dom), tl(hd(dist)) :: tl(
41
                  dist), path, cost, ub, visit);;
```