

Marco Ferreira

(PF&W 11.1)

- ▶ Latent factor models with one factor
- ▶ MCMC computations
- ▶ Latent  $k$ -factor models
- ▶ Choice of number of factors
- ▶ Example: troposphere temperature

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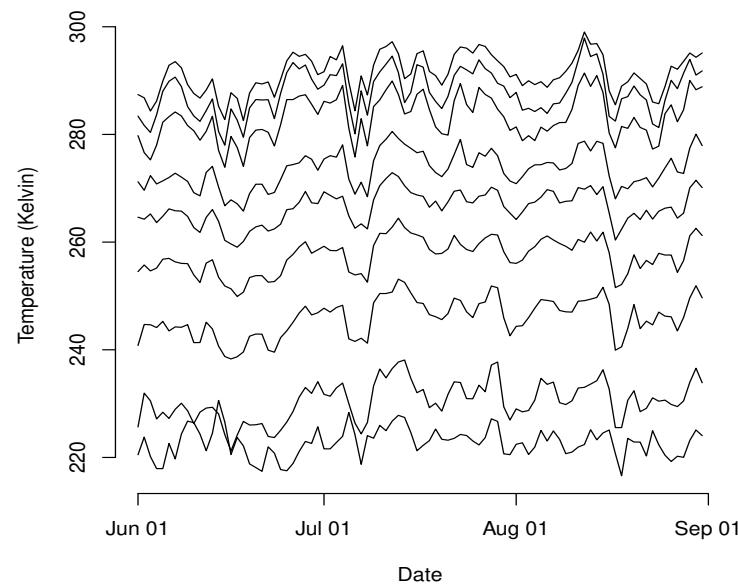
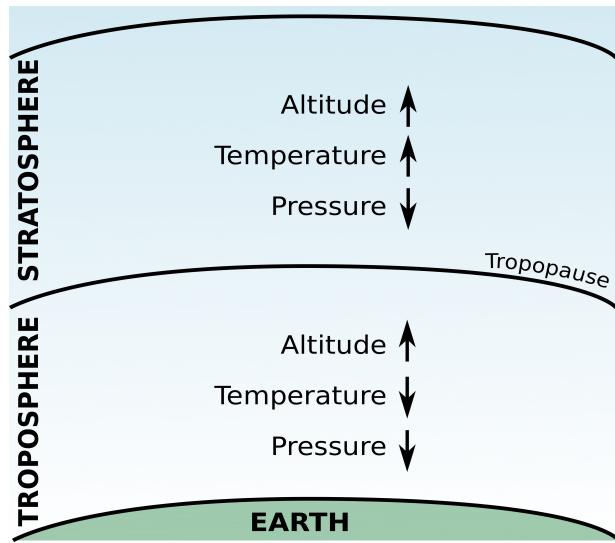
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# Working example



**Figure:** Daily average troposphere temperatures at longitude  $-100^{\circ}$  and latitude  $55^{\circ}$  (over Canada) from June 1 to August 31, 2015, at different altitudes. Observation vector of dimension  $r = 9$ .  $n = 92$  time points.

# Latent 1-factor model

Observation equation:  $\mathbf{y}_i = \mathbf{B}\mathbf{x}_i + \mathbf{v}_i,$

- ▶  $\mathbf{y}_i$ :  $i$ th observation of  $r$ -dimensional vector of interest.
- ▶  $\mathbf{B} = (b_1, \dots, b_r)'$ :  $r$ -dimensional vector of factor loadings.
- ▶  $\mathbf{x}_i$ :  $i$ th realization of one-dimensional latent factor process.
- ▶  $\mathbf{x}_1, \dots, \mathbf{x}_n$  i.i.d.  $N(0, H)$ .
- ▶  $\mathbf{v}_i$ :  $r$ -dimensional error vector for the  $i$ th observation.
- ▶  $\mathbf{v}_1, \dots, \mathbf{v}_n$  i.i.d.  $N(\mathbf{0}, \mathbf{V})$ , with  $\mathbf{V} = \text{diag}(\sigma_1^2, \dots, \sigma_r^2)$ .
- ▶  $\sigma_1^2, \dots, \sigma_r^2$ : idiosyncratic variances.

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- ▶  $\sigma_1^2, \dots, \sigma_r^2$ : idiosyncratic variances.

- ▶ If  $x_1, \dots, x_n$  were known, then the latent 1-factor model would be a multivariate regression model.
- ▶ In that case, conditional on  $x_i$ , the second-order moments would be  $\text{var}(y_{ij}|x_i) = \sigma_j^2$  and  $\text{cov}(y_{ij}, y_{ik}|x_i) = 0$ .
- ▶ With known  $x_1, \dots, x_n$ , the factor loadings  $b_1, \dots, b_r$  would be the regression coefficients that measure the impact of the univariate factor  $x_i$  on each element of the vector  $y_i$ .
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- ▶ However, for statistical factor models,  $x_1, \dots, x_n$  are not observable.

- ▶ Thus, to obtain the first- and second-order moments of the observation vector  $\mathbf{y}_i$ , we have to integrate out  $\mathbf{x}_i$ .
- ▶ By doing that, we find that the expected value of  $\mathbf{y}_i$  is  $E(\mathbf{y}_i) = \mathbf{0}$  (we usually center the variables of interest before using these factor models).
- ▶ In addition, the covariance matrix of  $\mathbf{y}_i$  is  $Cov(\mathbf{y}_i) = \mathbf{H}\mathbf{B}\mathbf{B}' + \mathbf{V}$ .

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- ▶ Hence, this factor model with one factor induces a very specific covariance structure with  $\text{var}(y_{ij}) = \textcolor{red}{H} \textcolor{blue}{b}_j^2 + \textcolor{green}{\sigma}_j^2$  and  $\text{cov}(y_{ij}, y_{ik}) = \textcolor{red}{H} \textcolor{blue}{b}_j \textcolor{blue}{b}_k$ .
- ▶ Therefore, the factor loadings vector  $\mathbf{B} = (\textcolor{blue}{b}_1, \dots, \textcolor{blue}{b}_r)$  plays a critical role in the covariance structure of  $\mathbf{y}_i$ , with larger  $\textcolor{blue}{b}_j$  implying larger variances and covariances.

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- ▶ Alternatively, we can write the 1-factor model in matrix notation

$$\mathbf{Y} = \mathbf{X}\mathbf{B}' + \mathbf{v},$$

- ▶  $\mathbf{Y} = (\mathbf{y}_1', \dots, \mathbf{y}_n')$ ' is the  $n$  by  $r$  matrix of observations,
- ▶  $\mathbf{X} = (x_1, \dots, x_n)'$  is the  $n$  dimensional vector of latent factors,
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# Identifiability

- ▶ Identifiability is an important issue in factor models.
- ▶ Note that if we define  $\mathbf{B}^* = a\mathbf{B}$  and  $x_i^* = x_i/a$  for a scalar  $a \neq 0$ , then  $\mathbf{y}_i = \mathbf{B}^*x_i^* + \mathbf{v}_i$  is exactly the same model for the observations as  $\mathbf{y}_i = \mathbf{B}x_i + \mathbf{v}_i$ .
- ▶ There are many ways to resolve this identifiability problem.
- ▶ One simple and intuitive way that we use here is to set the first element of  $\mathbf{B}$  to be equal to 1, that is,  $b_1 = 1$ .

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# Priors

- ▶ For the factor loadings  $(b_2, \dots, b_r)$  we consider independent priors  $N(0, \tau^2)$ .
- ▶ For the latent factor variance  $H$  we assume  $IG(n_H/2, n_H s_H^2/2)$ .
- ▶ For the idiosyncratic variances  $\sigma_1^2, \dots, \sigma_r^2$  we assume independent priors  $IG(n_\sigma/2, n_\sigma s_\sigma^2/2)$ .
- ▶ Finally, for the factor loadings variance  $\tau^2$  we assume the prior  $IG(n_\tau/2, n_\tau s_\tau^2/2)$ .

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# Full conditional distributions

- ▶ Latent factor  $x_i$ :

$$N \left( \frac{\sum_{j=1}^r \sigma_j^{-2} b_j y_{ij}}{H^{-1} + \sum_{j=1}^r \sigma_j^{-2} b_j^2}, \frac{1}{H^{-1} + \sum_{j=1}^r \sigma_j^{-2} b_j^2} \right).$$

- ▶ Factor loading  $b_j$ :

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- ▶ Idiosyncratic variance  $\sigma_j^2$ :

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- ▶ Factor loadings variance  $\tau^2$ :

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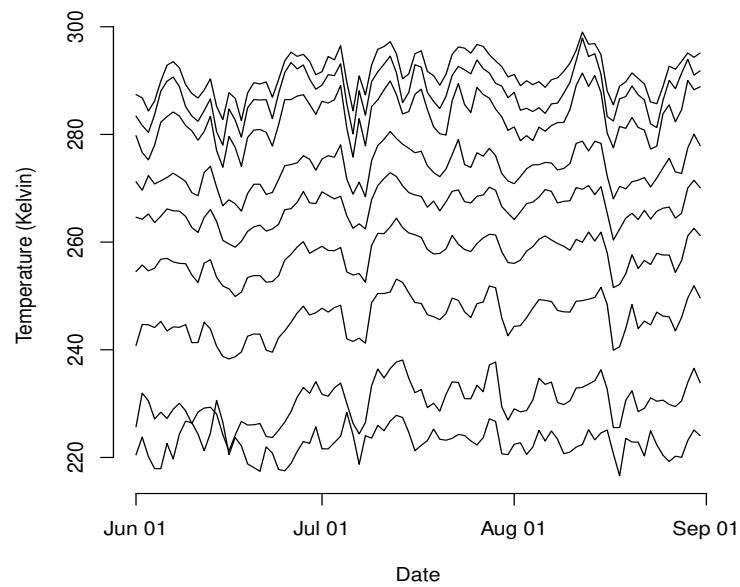
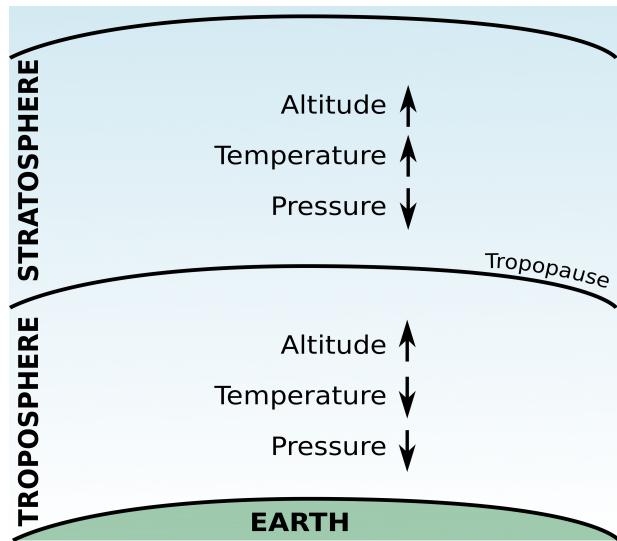
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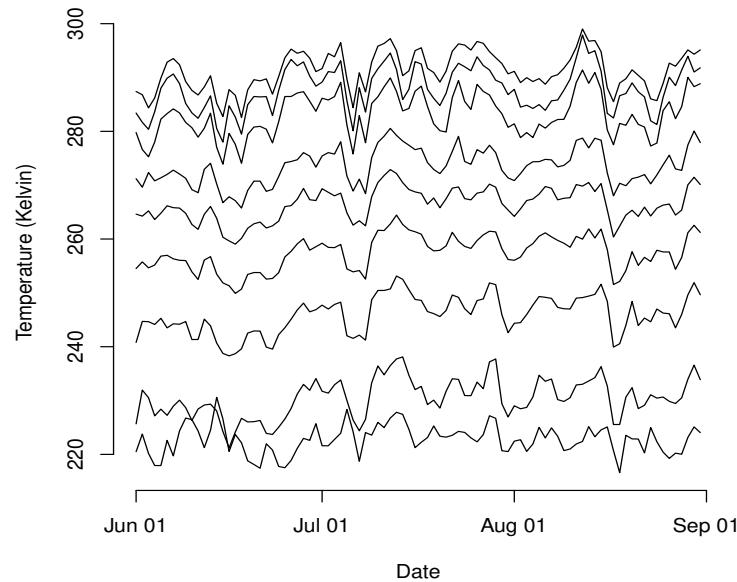
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# Back to working example

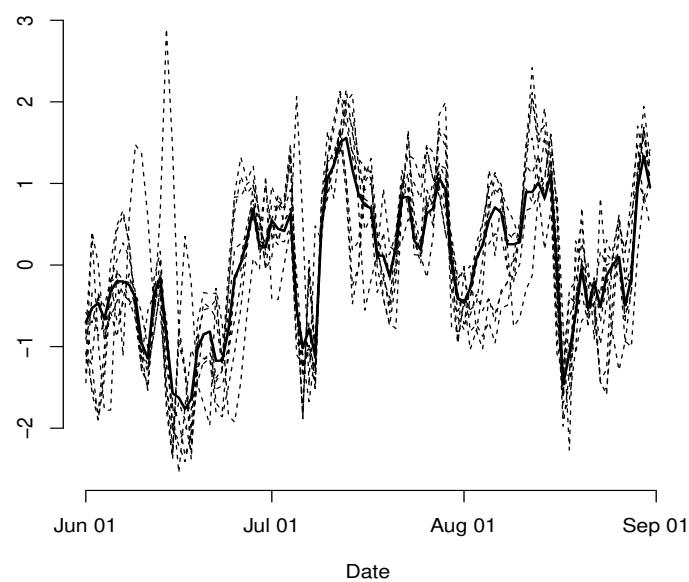


**Figure:** Daily average troposphere temperatures at longitude  $-100^\circ$  and latitude  $55^\circ$  (over Canada) from June 1 to August 31, 2015, at different altitudes. Observation vector of dimension  $r = 9$ .  $n = 92$  time points.

## └ Latent 1-factor model: Application to troposphere temperature



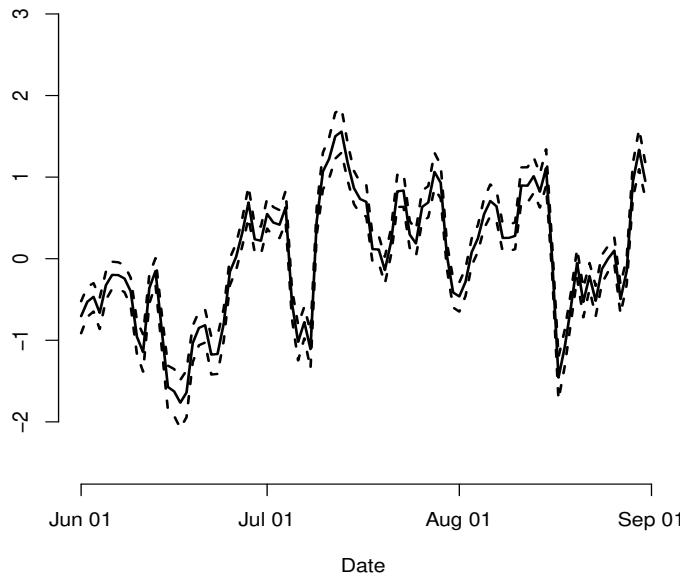
(a)



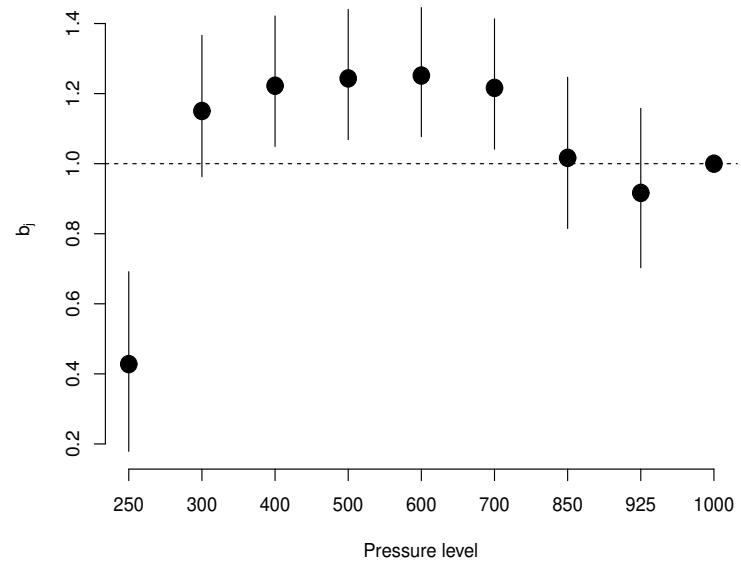
(b)

**Figure:** (a) Daily average troposphere temperatures. (b) Standardized temperature series (dashed lines) and estimated common factor (bold solid line).

## Latent 1-factor model: Application to troposphere temperature



(a)



(b)

**Figure:** (a) Common factor ( $x_{1:T}$ ) posterior mean (solid line) and 95% credible intervals (dashed lines); (b) Posterior means (circles) and 95% credible intervals (vertical lines) of factor loadings  $b_j$  for each pressure level.



# Latent $k$ -factor model

Observation equation:  $\mathbf{y}_i = \mathbf{B}\mathbf{x}_i + \mathbf{v}_i$ .

- ▶  $\mathbf{y}_i$ :  $i$ th observation of the  $r$ -dimensional vector of interest.
- ▶  $\mathbf{B}$ :  $r \times k$  matrix of factor loadings.
- ▶  $\mathbf{x}_i$ :  $i$ th realization of  $k$ -dimensional latent factor process.
- ▶  $\mathbf{x}_1, \dots, \mathbf{x}_n$  i.i.d.  $N(\mathbf{0}, \mathbf{H})$  with  $\mathbf{H} = \text{diag}(h_1, \dots, h_k)$ .
- ▶  $\mathbf{v}_i$ :  $r$ -dimensional error vector for the  $i$ th observation.
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# Identifiability

Hierarchical structural constraint on factor loadings matrix  $\mathbf{B}$ :

$$\mathbf{B} = \begin{pmatrix} 1 & 0 & 0 & \cdots & 0 \\ b_{21} & 1 & 0 & \cdots & 0 \\ b_{31} & b_{32} & 1 & \cdots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ b_{k1} & b_{k2} & b_{k3} & \cdots & 1 \\ b_{k+1,1} & b_{k+1,2} & b_{k+1,3} & \cdots & b_{k+1,k} \\ \vdots & \vdots & \vdots & & \vdots \\ b_{r1} & b_{r2} & b_{r3} & \cdots & b_{rk} \end{pmatrix}$$

$\mathbf{B}$  is a full rank block lower triangular matrix with diagonal elements equal to 1.

- ▶ Hierarchical structural constraint on  $\mathbf{B}$  has important implications for the interpretation of the factors.
- ▶ Order of the variables in  $\mathbf{y}_t$  defines the factors.
- ▶ First variable is equal to first factor plus noise, second variable is equal to  $b_{21}$  times first factor plus second factor plus noise, etc.
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- ▶ However, for a fixed number of factors  $k$ , the ordering has no influence either on the covariance matrix of  $\mathbf{y}_i$  or on forecasts.
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# Bayesian analysis

- ▶ Conditionally conjugate priors.
- ▶ MCMC to explore posterior distribution.
- ▶ Marginal data density to choose number of factors  
(Laplace-Metropolis approximation).

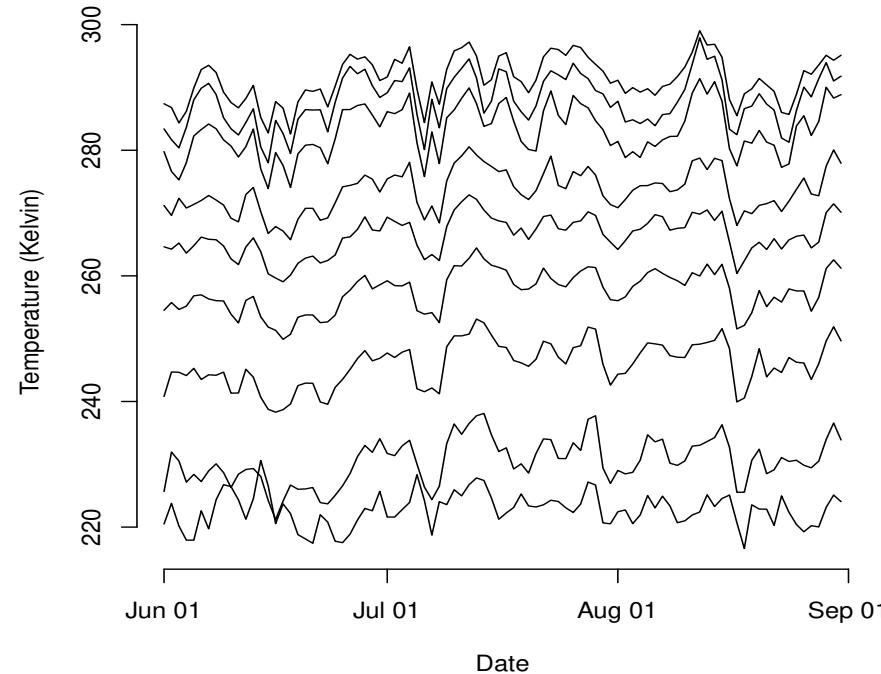
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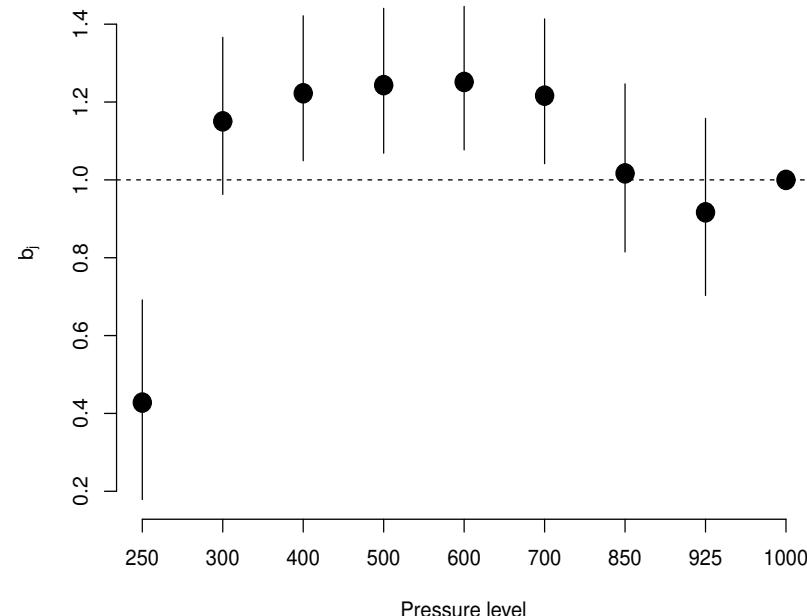
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# Latent $k$ -factor model for troposphere temperature



# Deciding the order of the variables

Recall the factor loadings  $b_j$  for the 1-factor model:



- ▶ In 1-factor model, the largest estimated factor loading is for altitude pressure level of 600 millibars.
- ▶ Temperature at that altitude seems to behave similarly to temperatures at other troposphere mid-altitudes.
- ▶ First position in  $\mathbf{y}_j$ : standardized temperature at altitude pressure level of 600 millibars.

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- ▶ The order for the remaining variables is the original order from lower to upper altitudes.

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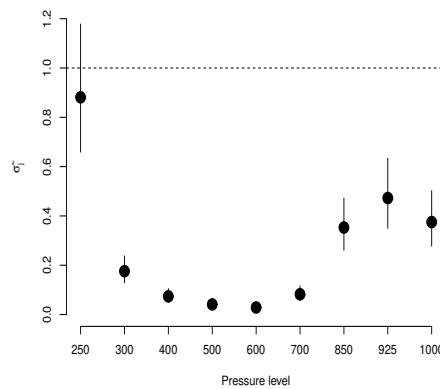
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# Choice of the number of factors

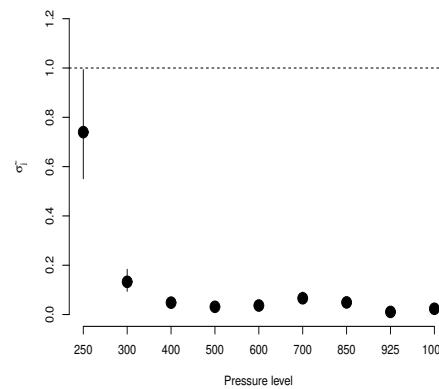
**Table:** Troposphere temperature. Logarithm of marginal data density for factor models with distinct number of factors.

	Number of factors				
	1	2	3	4	5
Log marginal density	89.7	319.2	326.3	310.0	300.6

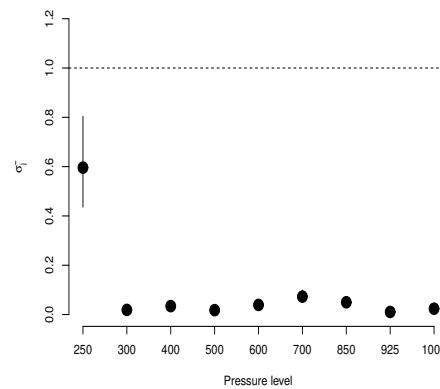
# Choice of the number of factors



(a)



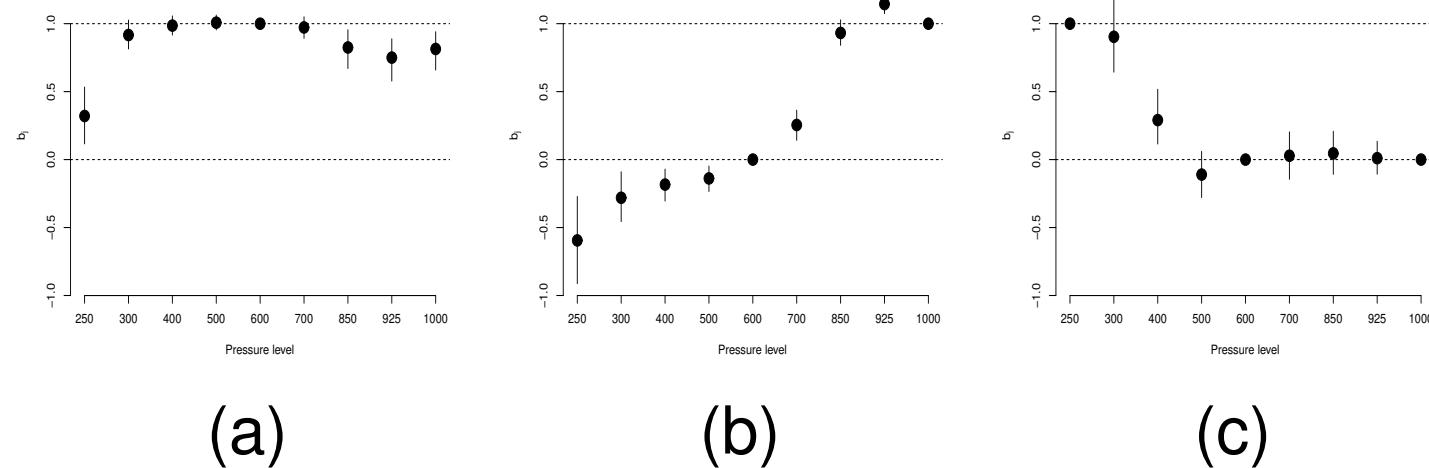
(b)



(c)

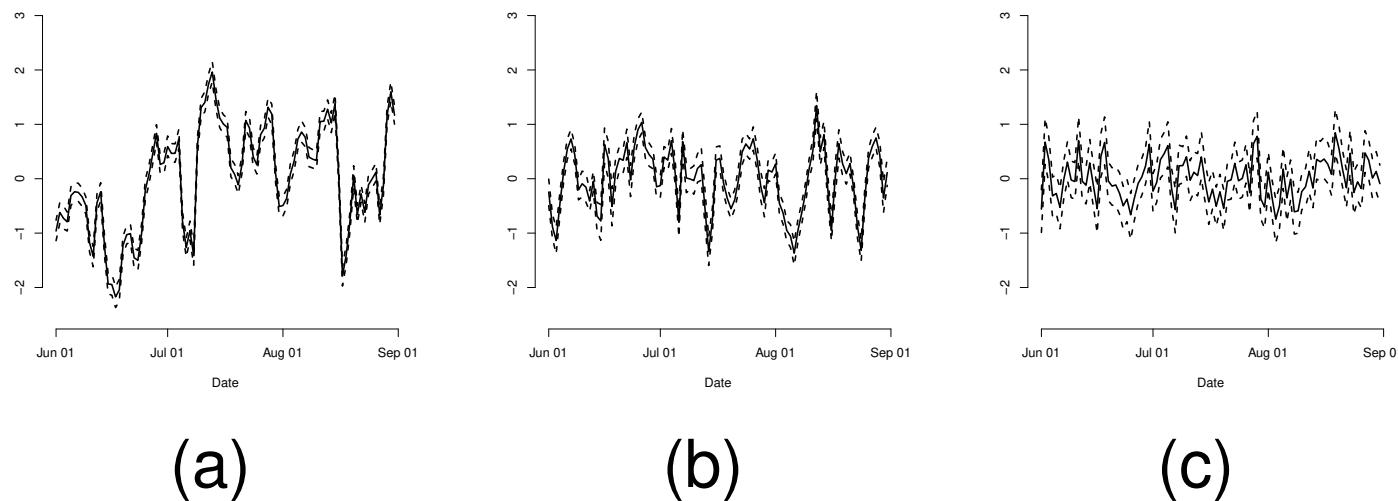
**Figure:** Troposphere temperature –  $k$ -factor models. Idiosyncratic variances  $\sigma_j^2$  based on factor models with (a) 1, (b) 2, and (c) 3 factors.

# Analysis with 3-factor model



**Figure:** Troposphere temperature – 3-factor model. Factor loadings for (a) first factor, (b) second factor, and (c) third factor.

# Analysis with 3-factor model



**Figure:** Troposphere temperature – 3-factor model. Time series plots of common factors posterior means (solid line) and 95% credible intervals for (a) first factor, (b) second factor, and (c) third factor.



Marco Ferreira

(PF&W 11.2-11.4)

- ▶ Dynamic latent factor models
- ▶ Example: time series troposphere temperature
- ▶ Dynamic spatiotemporal factor model
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# Dynamic latent factor model

Putting together latent factor models and DLMs:

$$\begin{aligned}\mathbf{y}_t &= \mathbf{F}'_t \boldsymbol{\theta}_t + \mathbf{B}_t \mathbf{x}_t + \boldsymbol{\nu}_t, \quad \boldsymbol{\nu}_t \sim N(\mathbf{0}, \mathbf{V}_t), \\ \boldsymbol{\theta}_t &= \mathbf{G}_t \boldsymbol{\theta}_{t-1} + \boldsymbol{\omega}_t, \quad \boldsymbol{\omega}_t \sim N(\mathbf{0}, \mathbf{W}_t),\end{aligned}$$

- ▶  $\mathbf{x}_t = (x_{t,1}, \dots, x_{t,k})'$ , a  $k$ -vector dynamic latent factor process,
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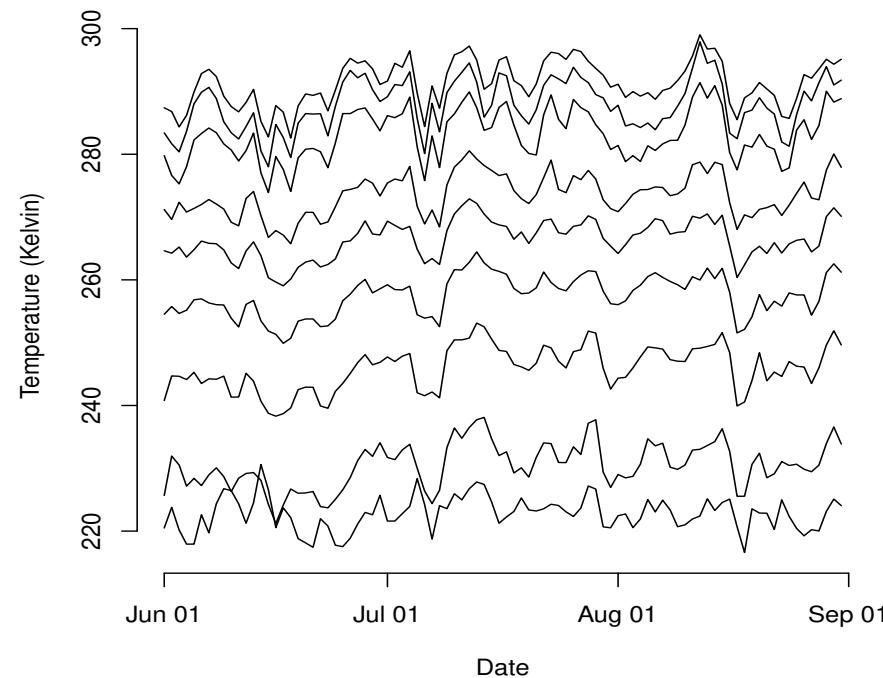
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Example: a dynamic 3-factor model for troposphere temperature

# Dynamic 3-factor model: troposphere temperature



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- ▶ Exploratory analysis of estimated common factors in the static 3-factor model indicates that each of the three common factors may be better modeled with autoregressive processes.
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- ▶  $\mathbf{B}$  fixed through time,
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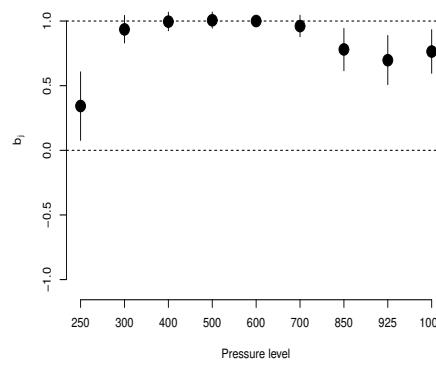
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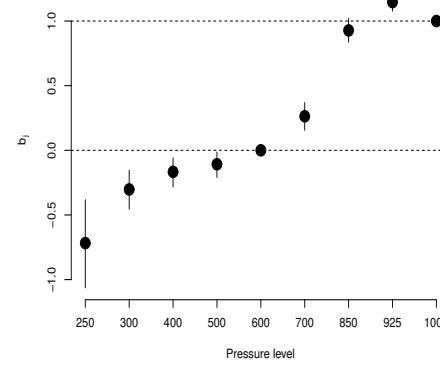
- ▶ Matrices  $\mathbf{F}$ ,  $\mathbf{G}$ , and  $\mathbf{W}$  are block-diagonal matrices with  $l$ th block representing in state-space form the  $\text{AR}(p_l)$  process for  $x_{tl}$ .
- ▶  $\mathbf{V} = \text{diag}(\sigma_1^2, \dots, \sigma_r^2)$  where  $\sigma_1^2, \dots, \sigma_r^2$  are idiosyncratic variances.

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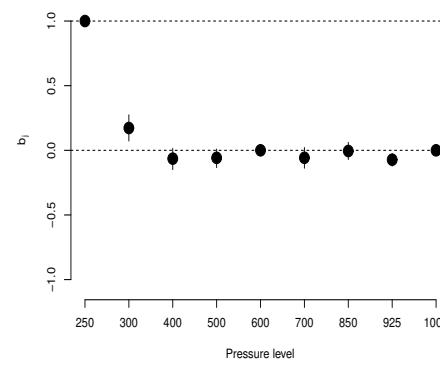
# Dynamic 3-factor model: Factor loadings



1st factor



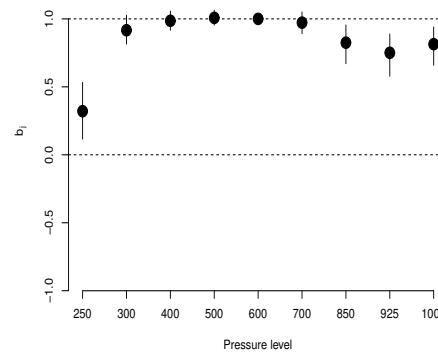
2nd factor



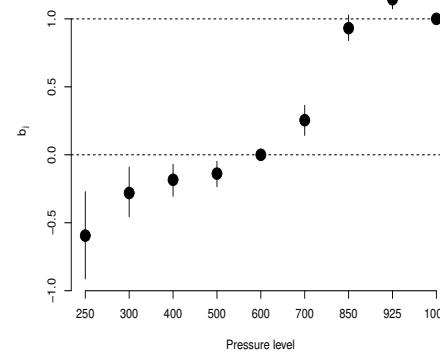
3rd factor

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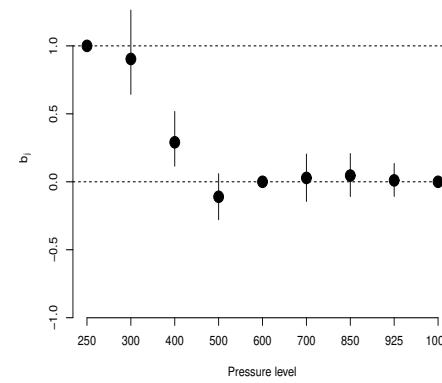
# Compare: static 3-factor model loadings



1st factor



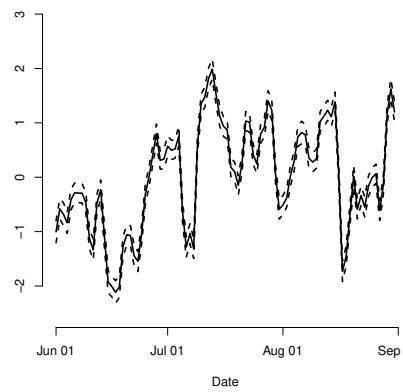
2nd factor



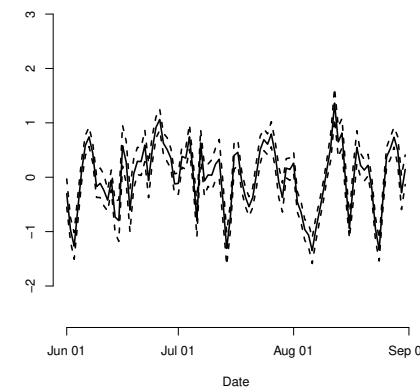
3rd factor

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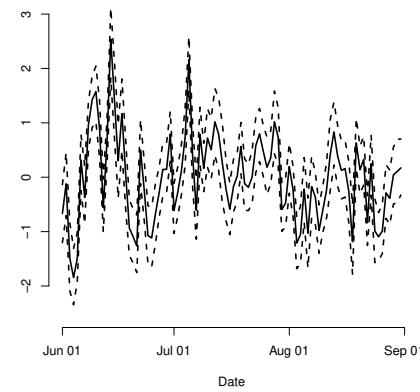
# Dynamic 3-factor model: Estimated latent factors



1st factor



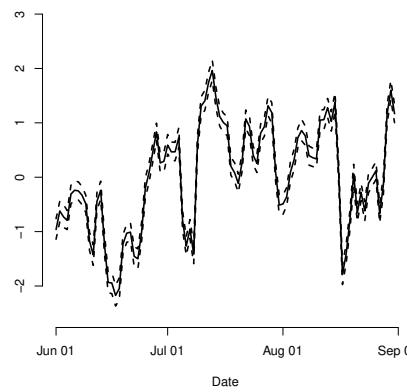
2nd factor



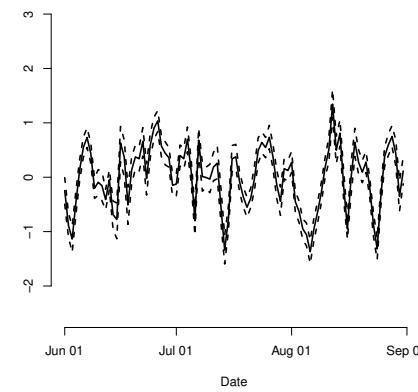
3rd factor

Example: a dynamic 3-factor model for troposphere temperature

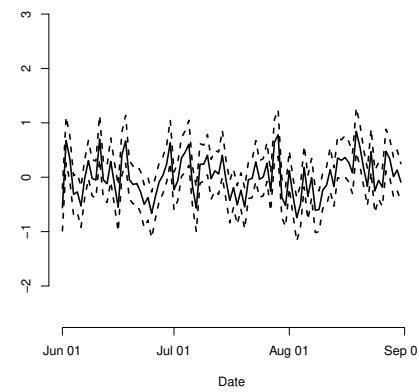
# Compare: latent factors for static 3-factor model



1st factor



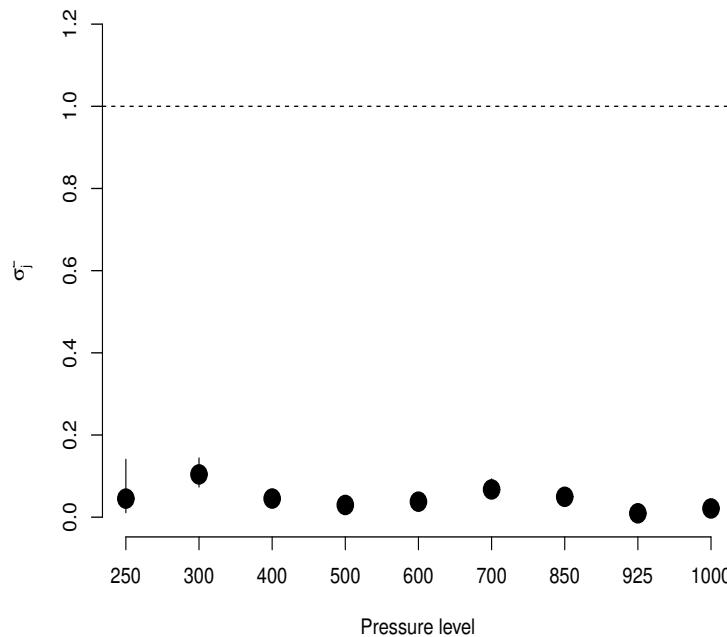
2nd factor



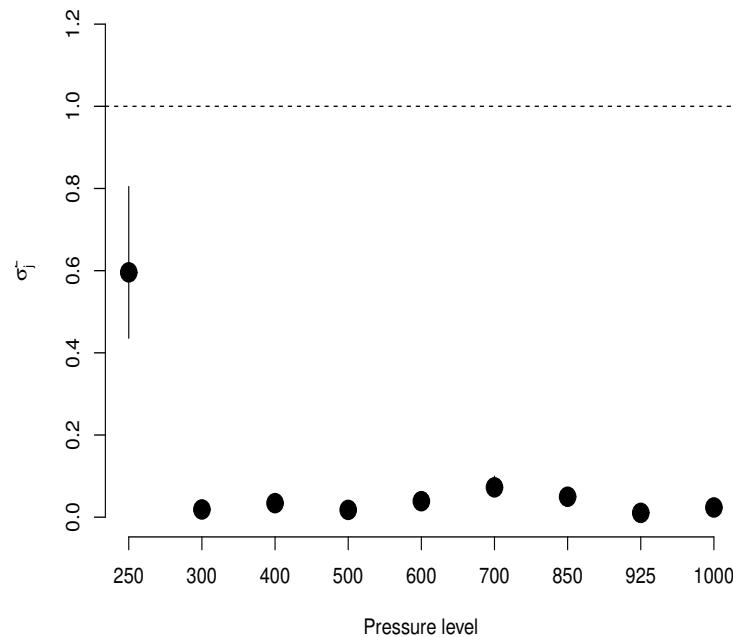
3rd factor

Example: a dynamic 3-factor model for troposphere temperature

# Compare: Idiosyncratic variances



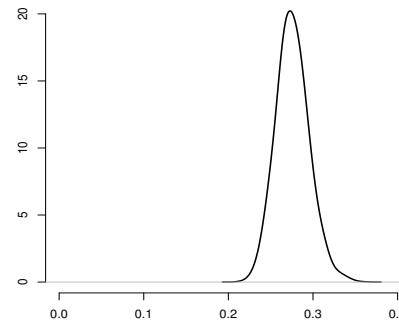
Dynamic 3-factor model



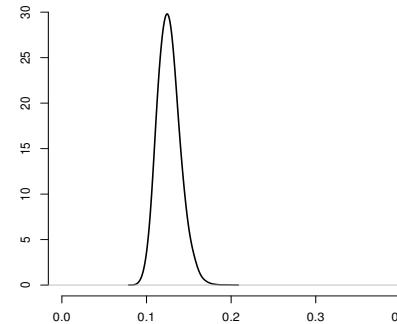
Static 3-factor model

Example: a dynamic 3-factor model for troposphere temperature

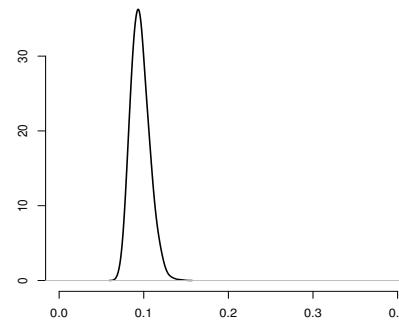
# Proportion of unexplained variance



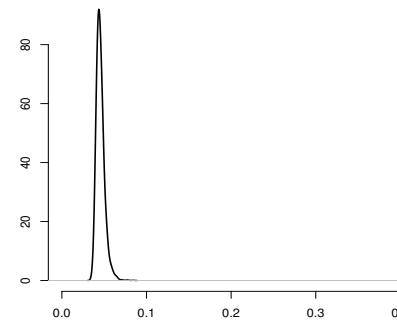
1-factor model



2-factor model



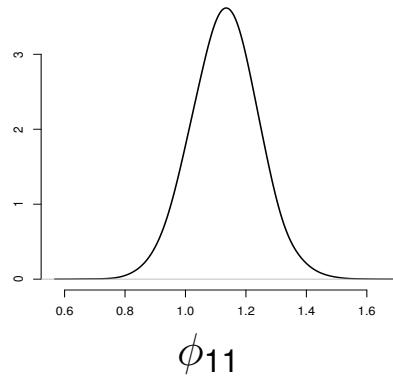
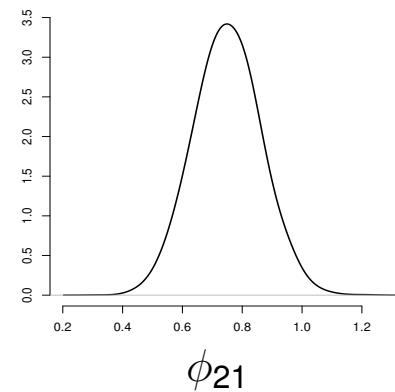
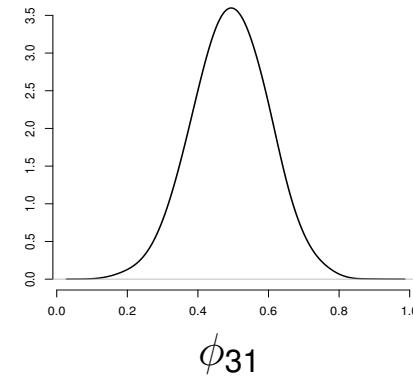
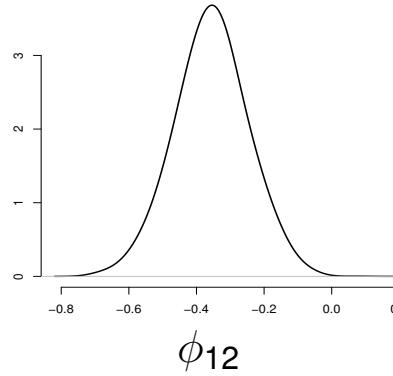
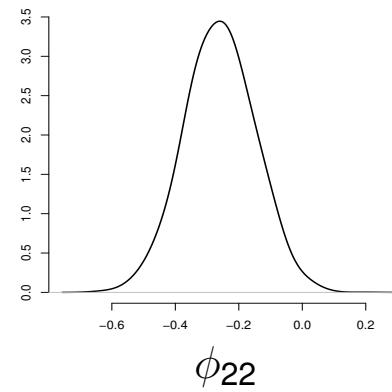
3-factor model



Dynamic 3-factor model

Example: a dynamic 3-factor model for troposphere temperature

# Dynamic 3-factor model: autoregressive coefficients for common factors

 $\phi_{11}$  $\phi_{21}$  $\phi_{31}$  $\phi_{12}$  $\phi_{22}$

### Example: a dynamic 3-factor model for troposphere temperature

---

- ▶ Posterior means:  $\hat{\phi}_{11} = 1.13$ ,  $\hat{\phi}_{12} = -0.36$ ,  $\hat{\phi}_{21} = 0.75$ ,  
 $\hat{\phi}_{22} = -0.26$ , and  $\hat{\phi}_{31} = 0.49$ .
- ▶ Roots of the characteristic polynomials for the first and second common factors are complex conjugates, implying that these common factors have stochastic cycles.

└ Example: a dynamic 3-factor model for troposphere temperature

---

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- ▶ Roots of the characteristic polynomials for the first and second common factors are complex conjugates, implying that these common factors have stochastic cycles.

### └ Example: a dynamic 3-factor model for troposphere temperature

---

- ▶ First common factor: estimated period is 19.3 days;  
estimated modulus of reciprocal roots is 0.59.
  
- ▶ Second common factor: estimated period is 8.4 days;  
estimated modulus of reciprocal roots is 0.51.

### └ Example: a dynamic 3-factor model for troposphere temperature

---

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### Example: a dynamic 3-factor model for troposphere temperature

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- ▶ Estimated moduli of the reciprocal roots for the three dynamic common factors are all less than 0.60.
- ▶ Therefore, the forecast functions for each of these three common factors decay to zero fairly fast.

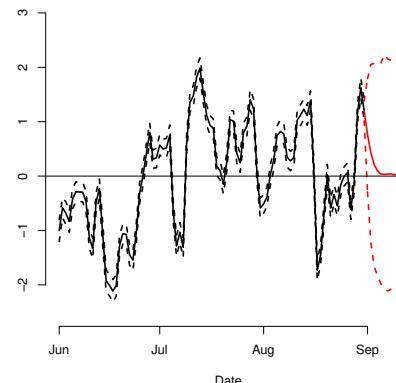
### Example: a dynamic 3-factor model for troposphere temperature

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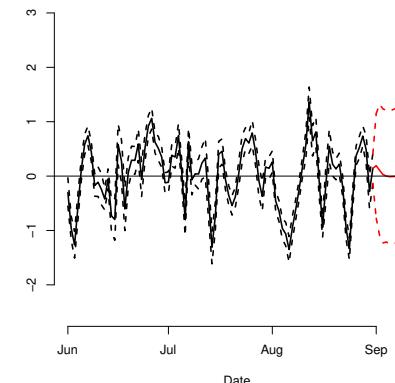
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Example: a dynamic 3-factor model for troposphere temperature

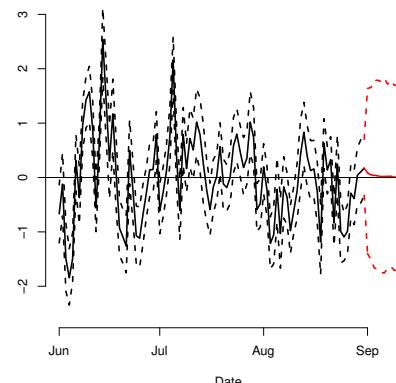
# Dynamic 3-factor model: forecasts



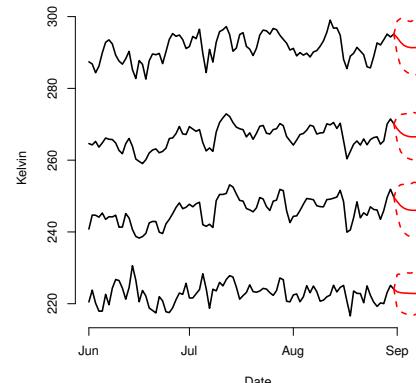
1st factor



2nd factor



3rd factor



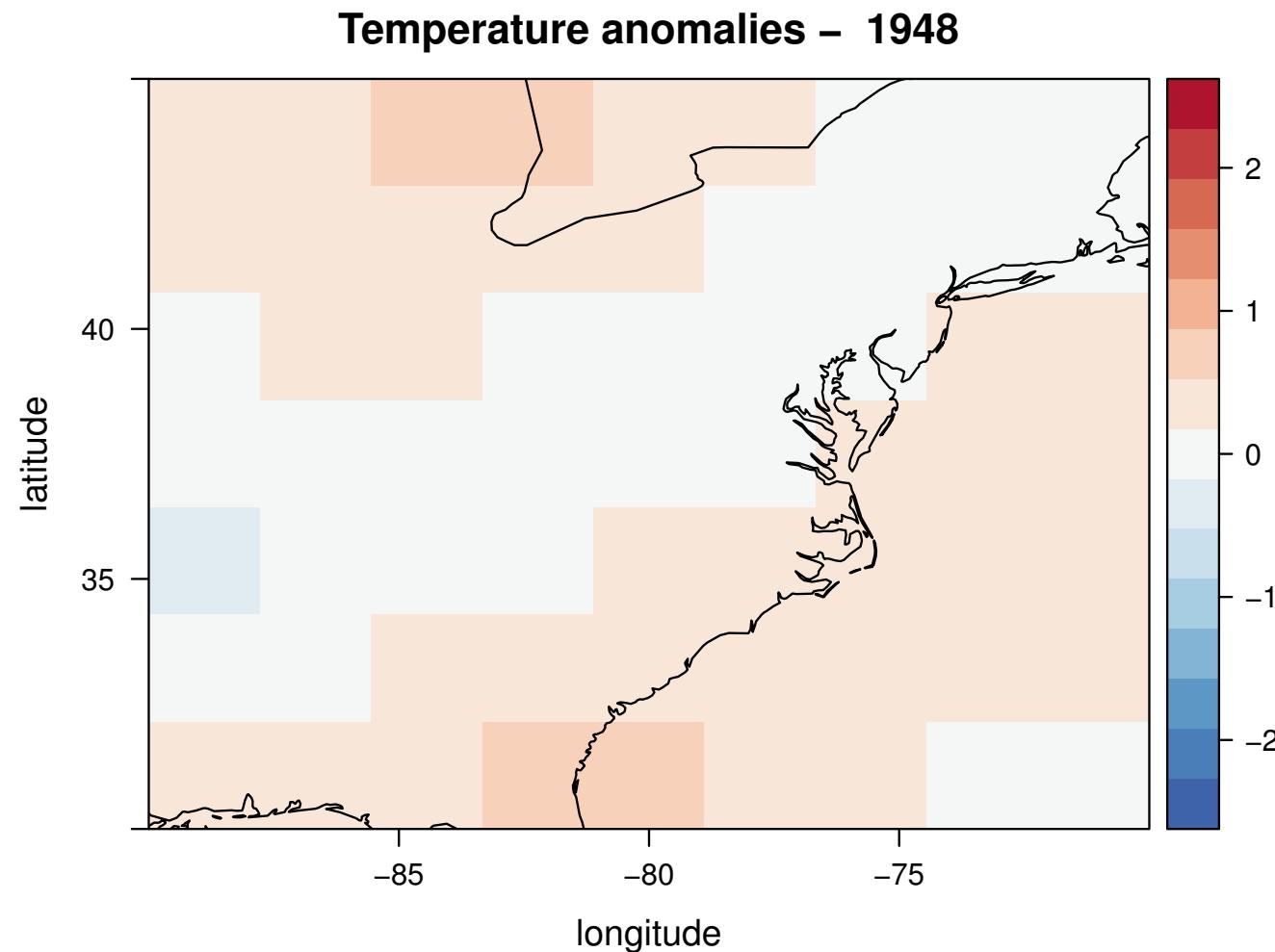
Temperatures



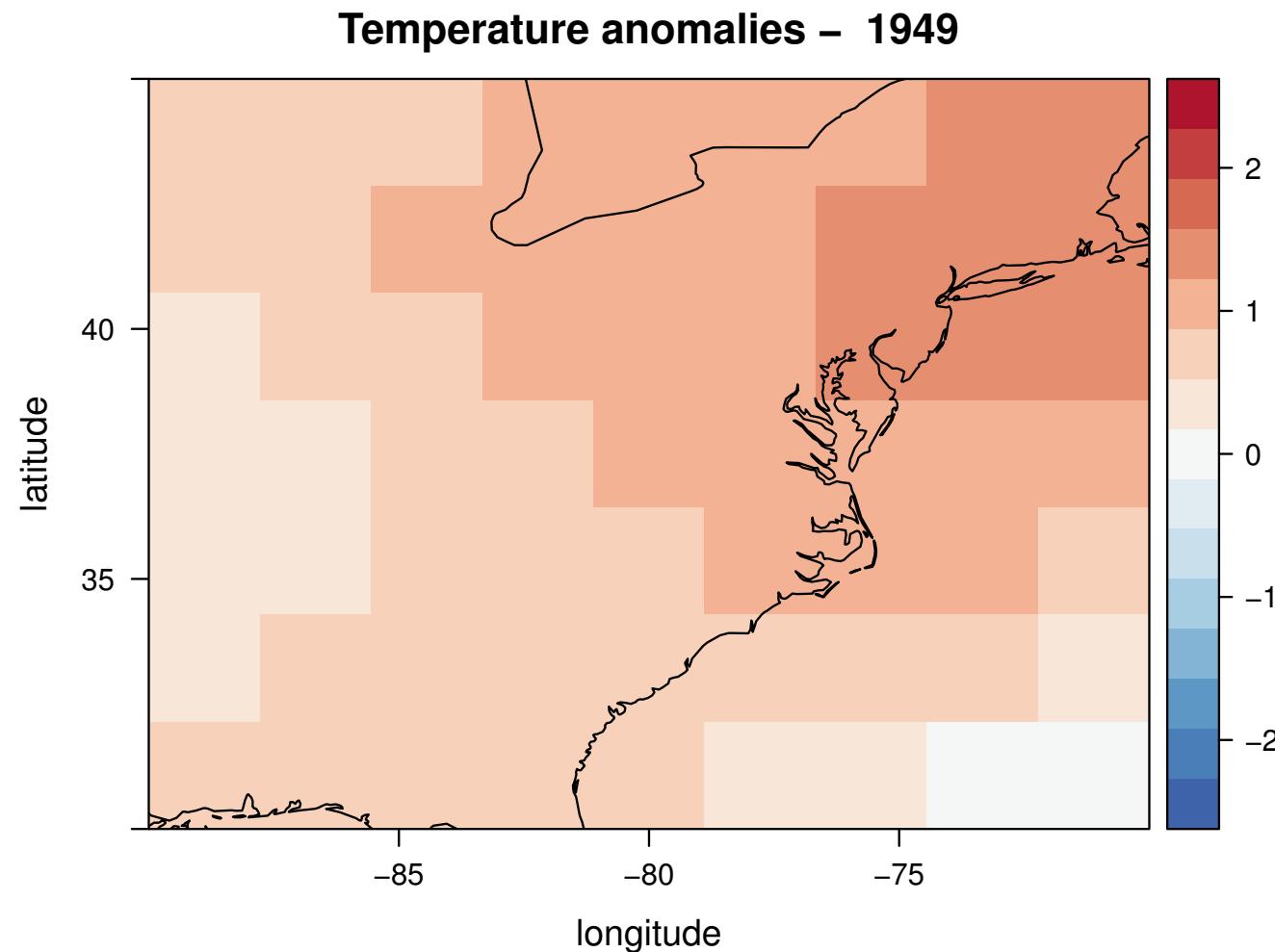
# Working example: Temperature Anomalies in Eastern USA

- ▶ Temperature anomalies (Kelvin) in Eastern USA.
- ▶ Pressure level 1000 Psi.
- ▶ From 1948 to 2016.
- ▶ NCEP Reanalysis dataset.

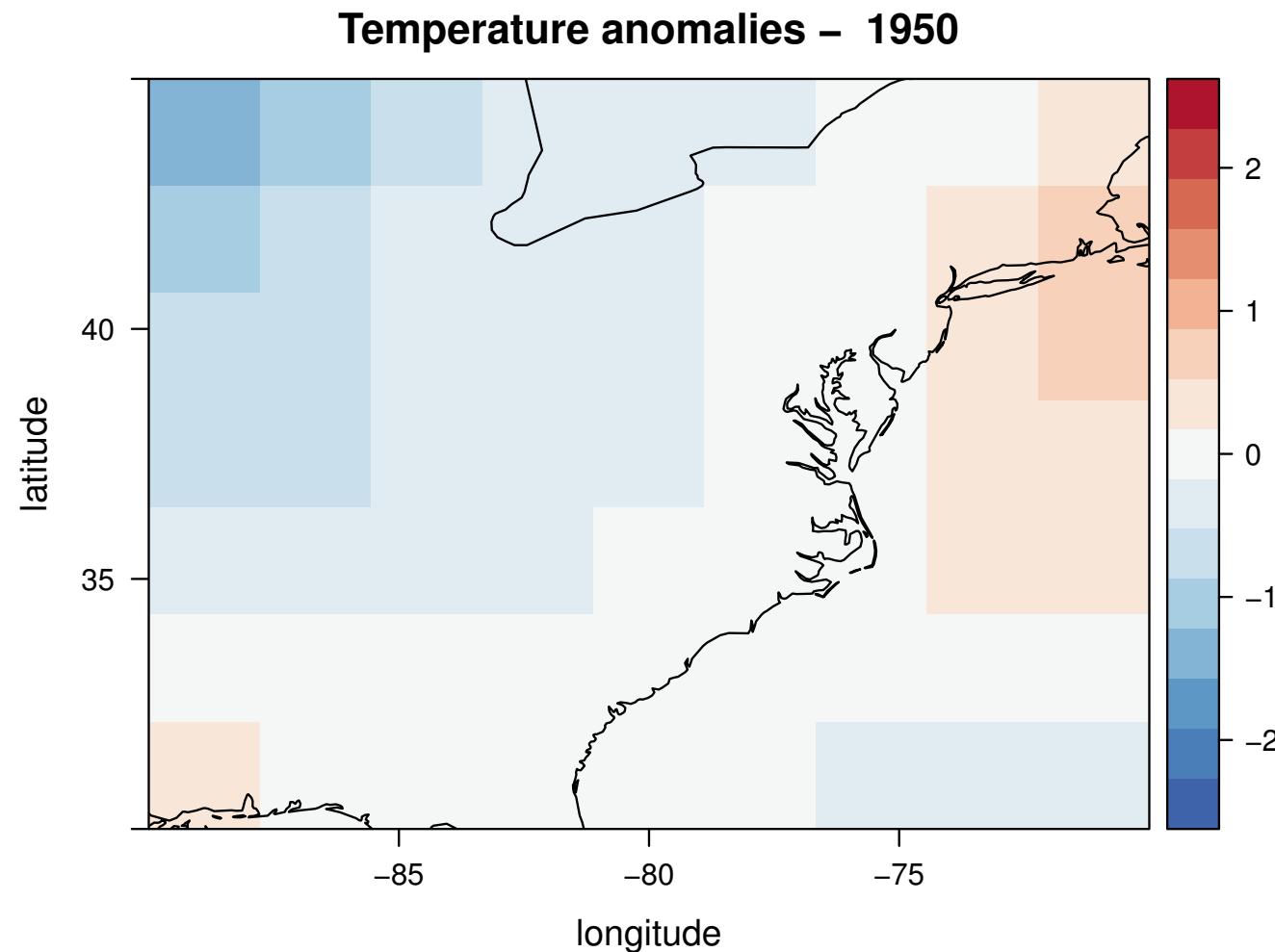
# Temperature Anomalies in Eastern USA



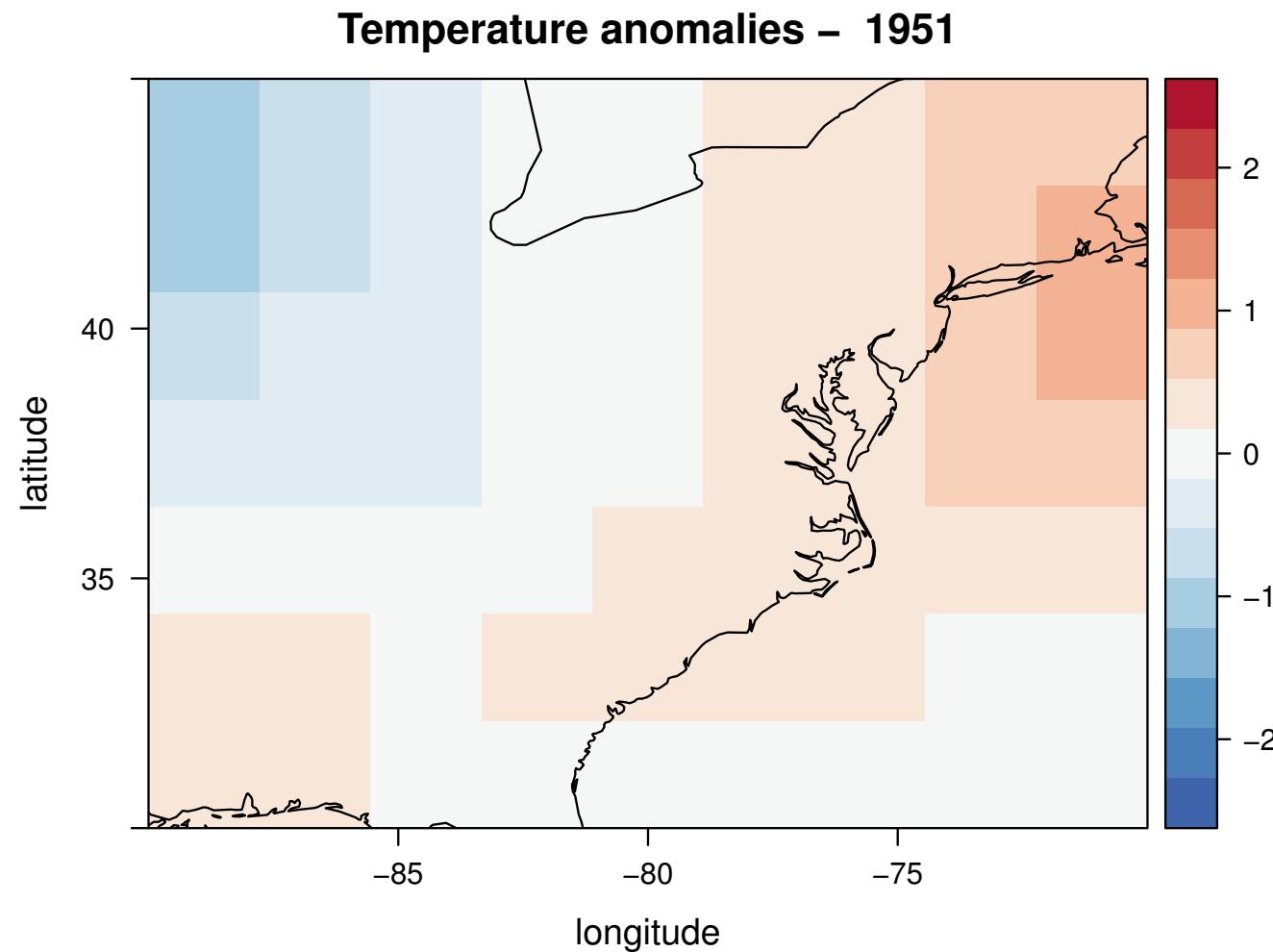
# Temperature Anomalies in Eastern USA



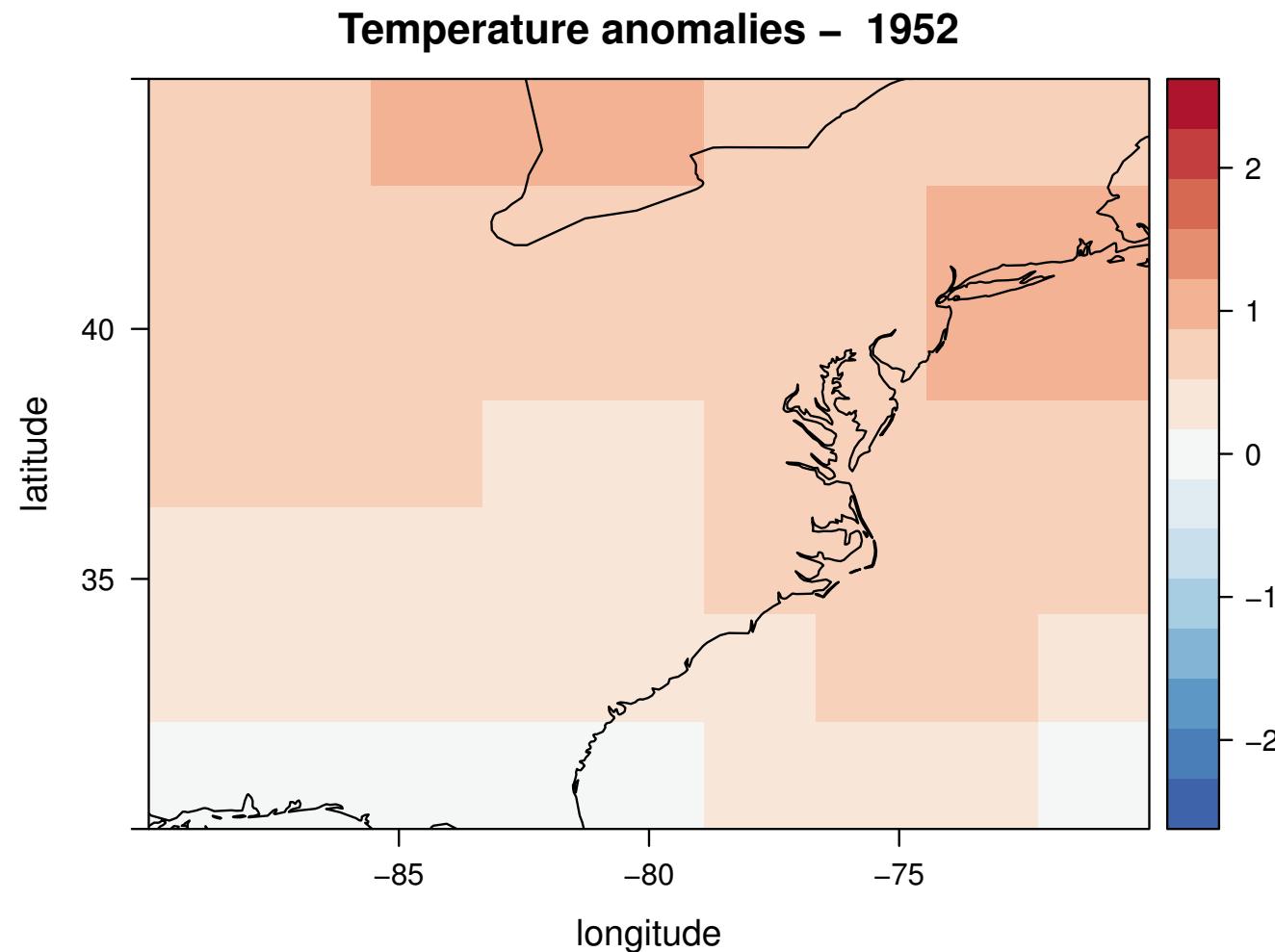
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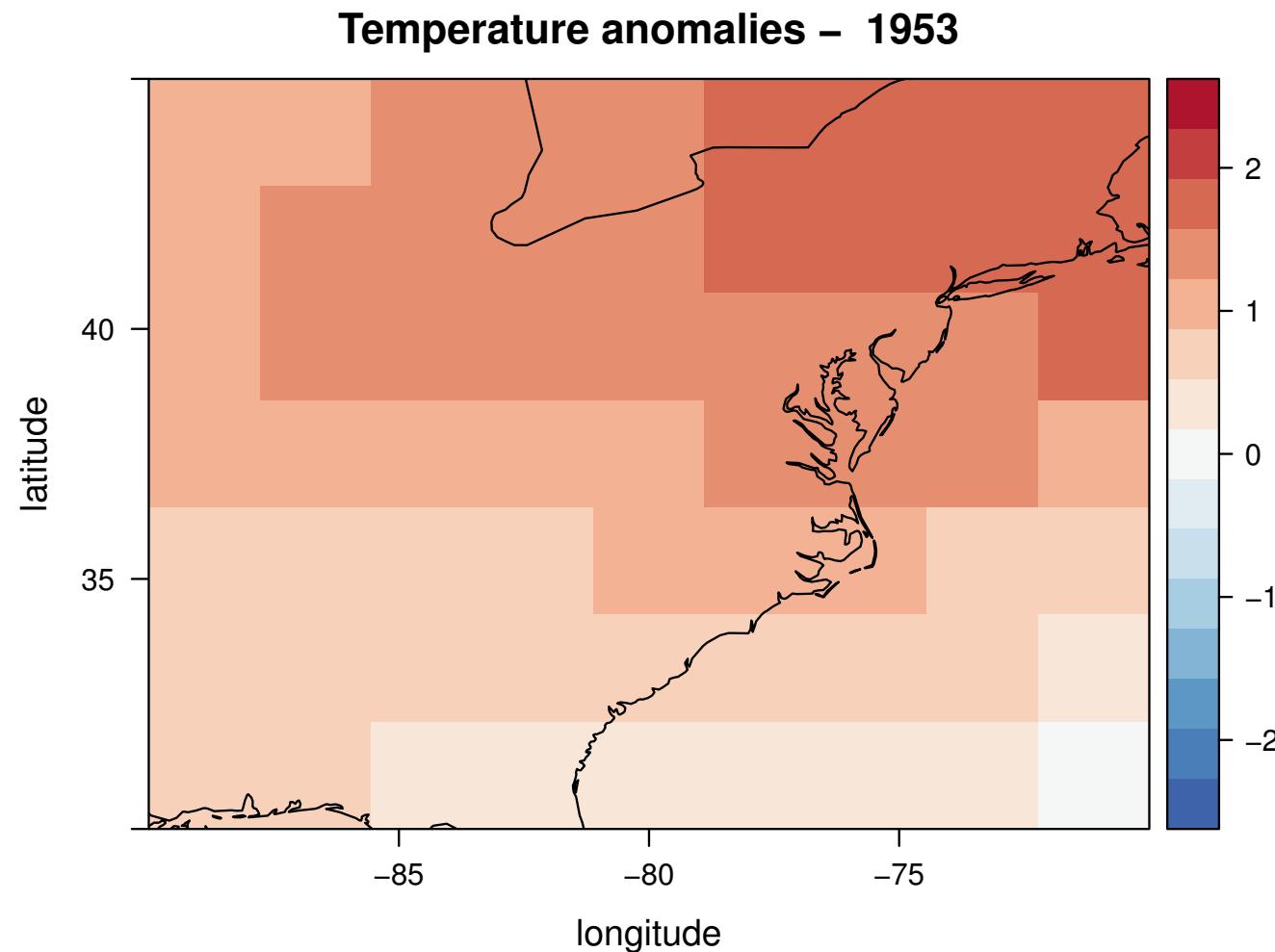
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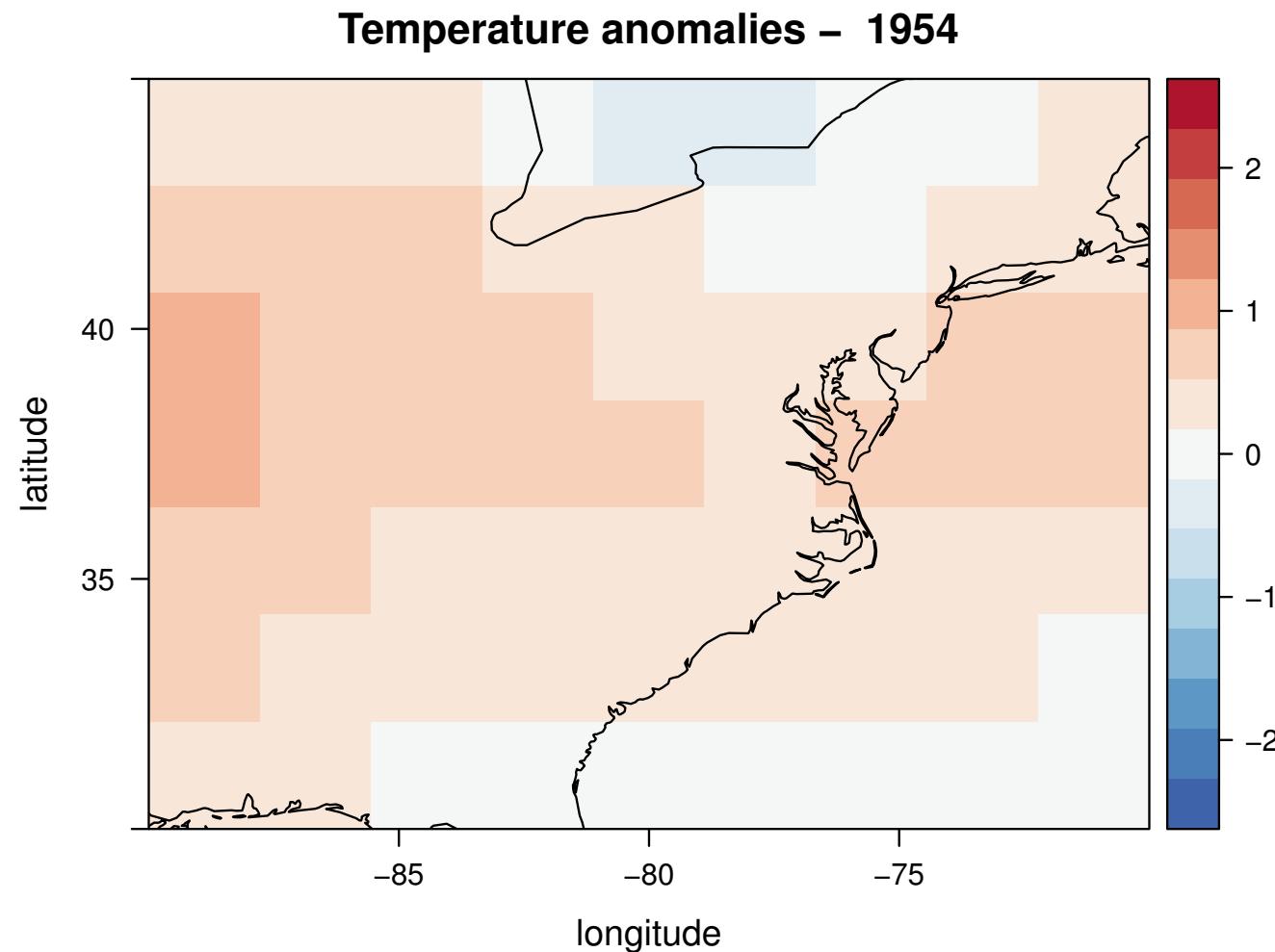
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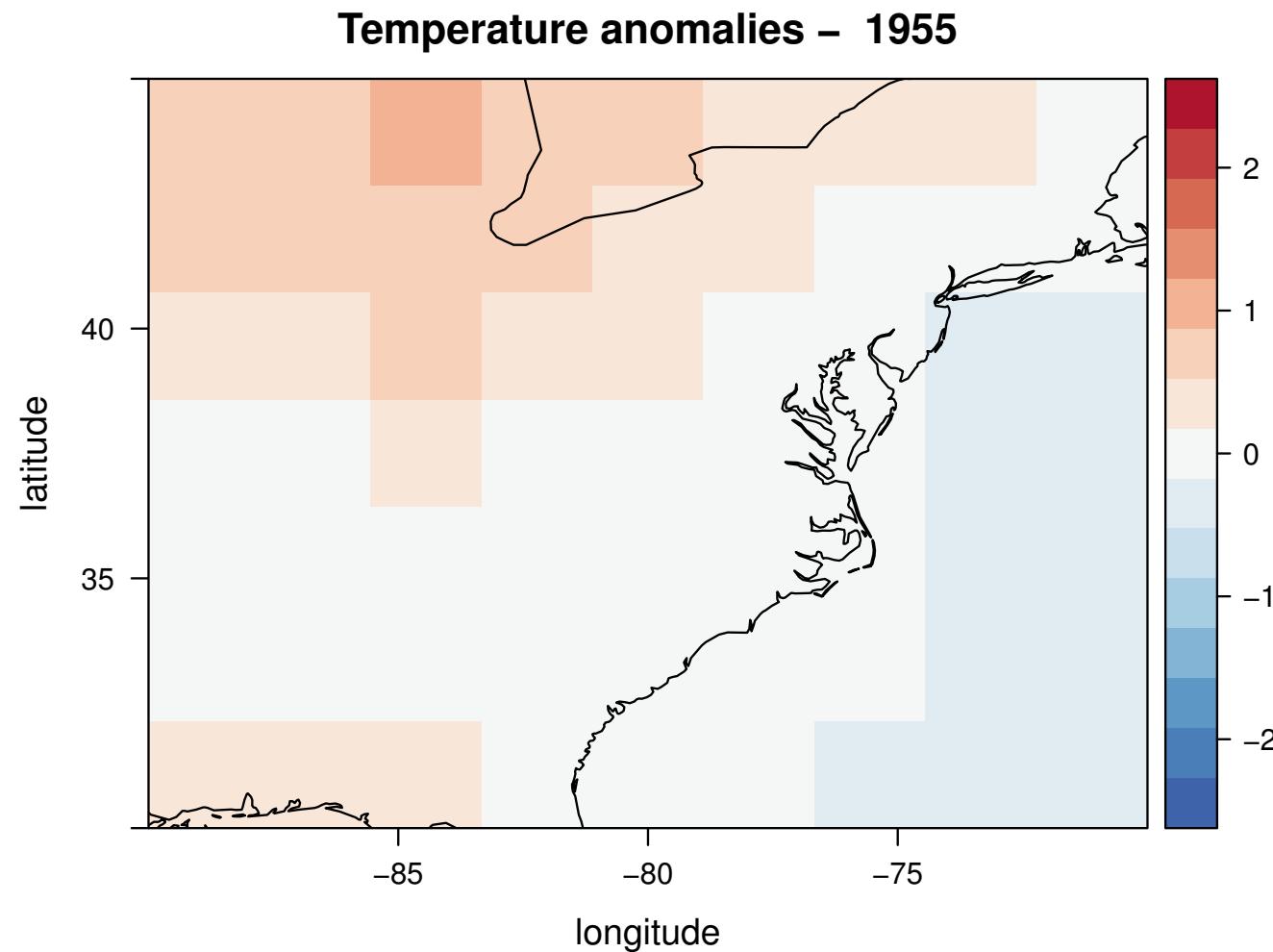
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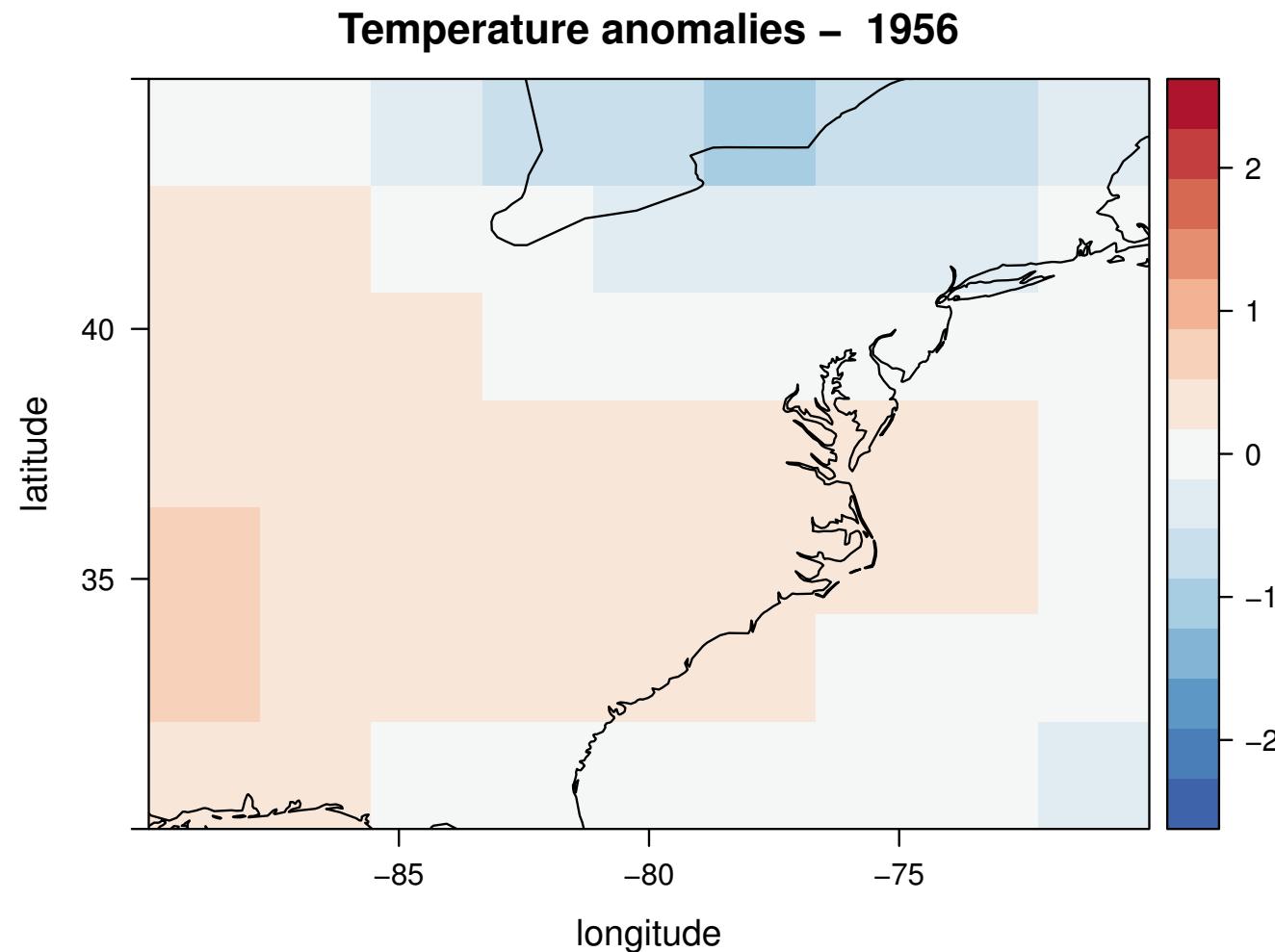
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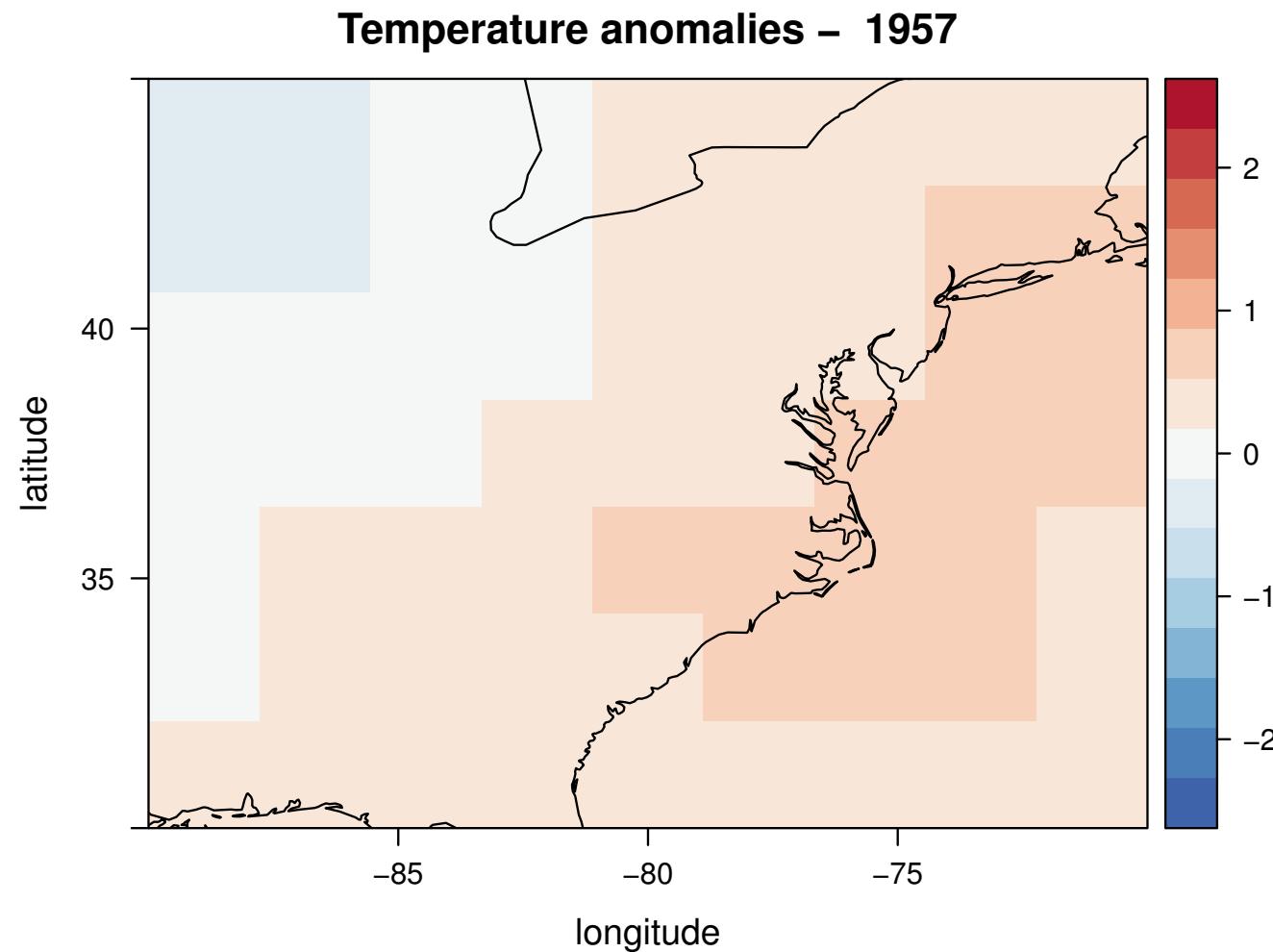
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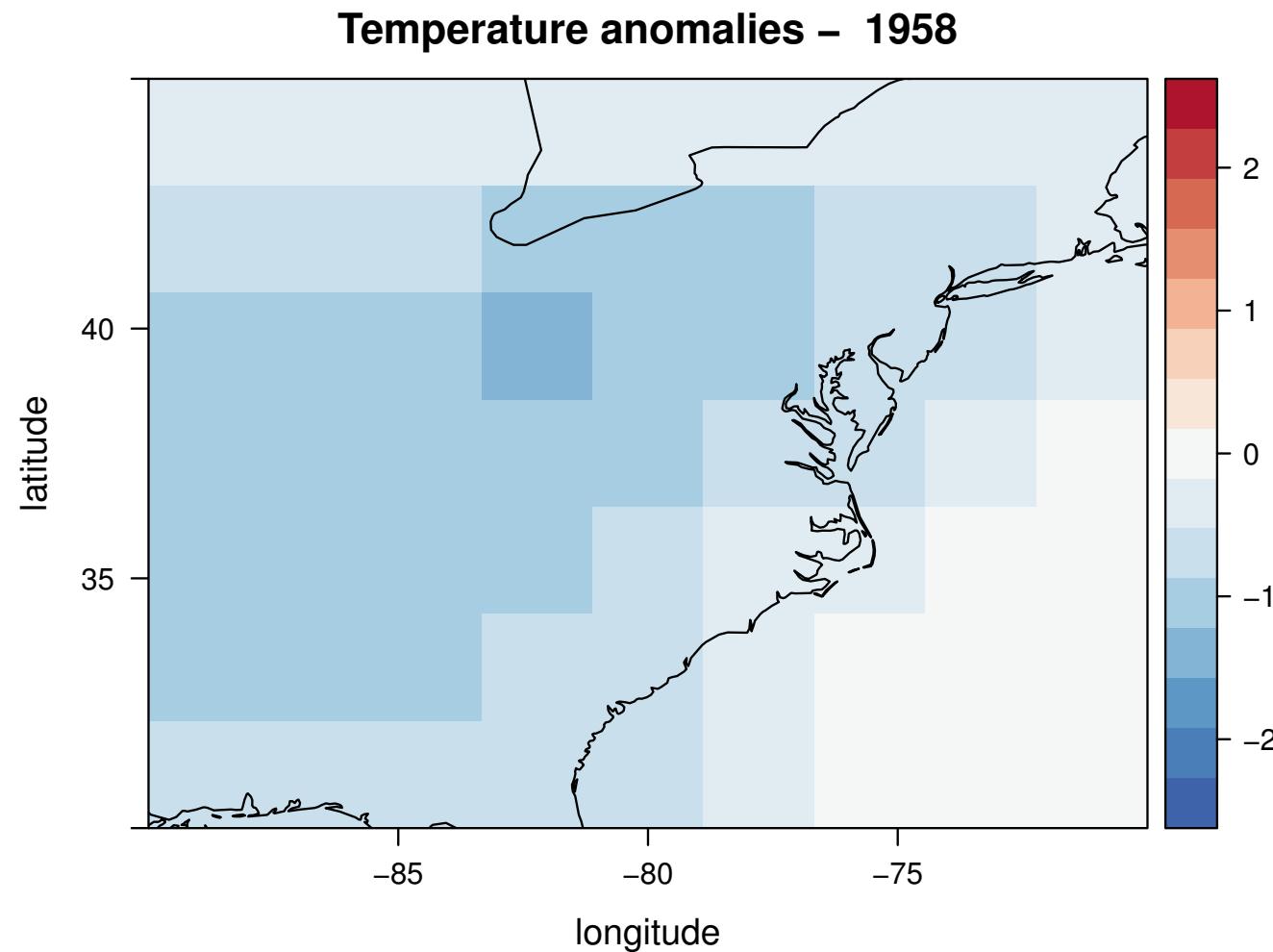
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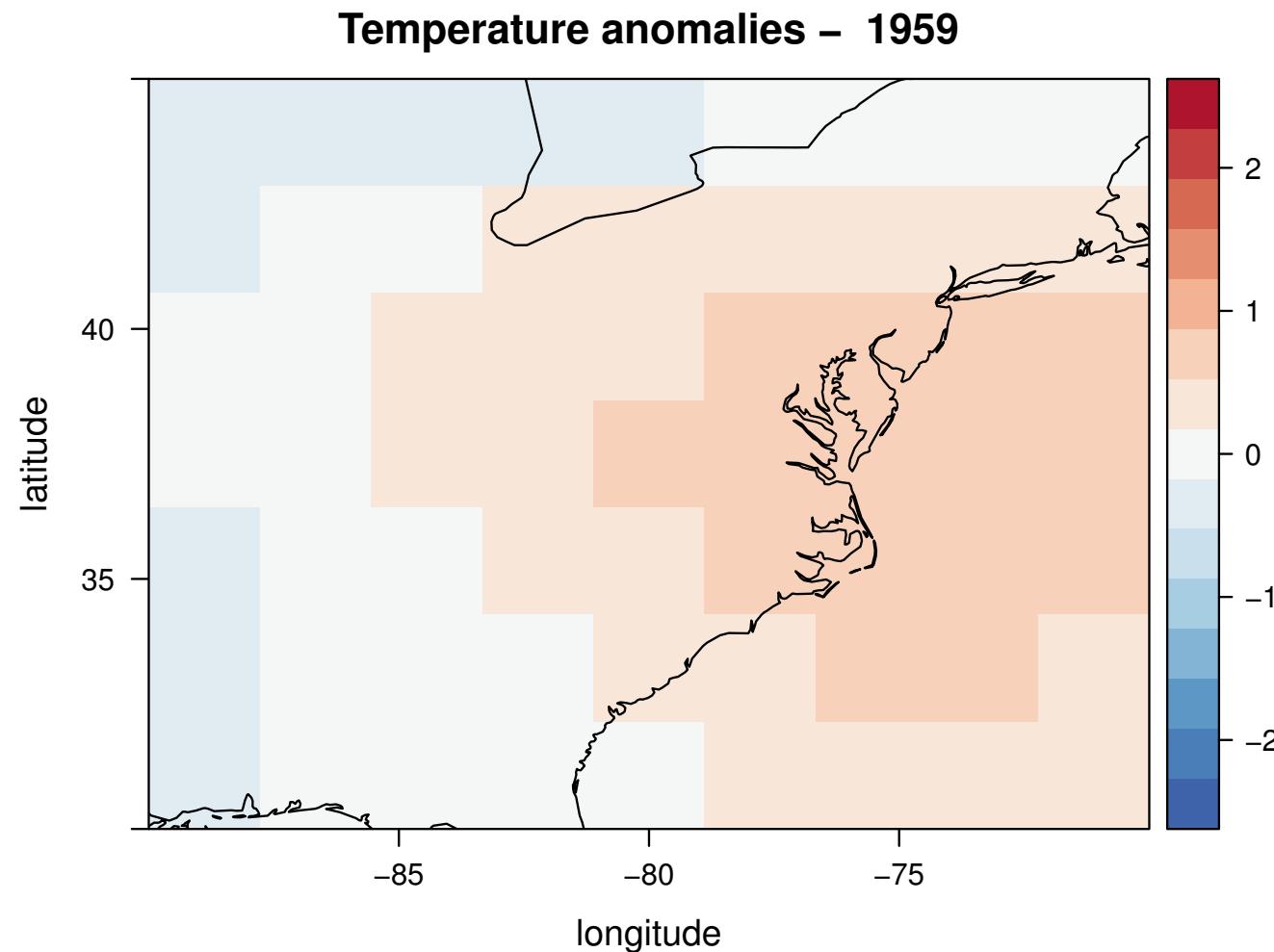
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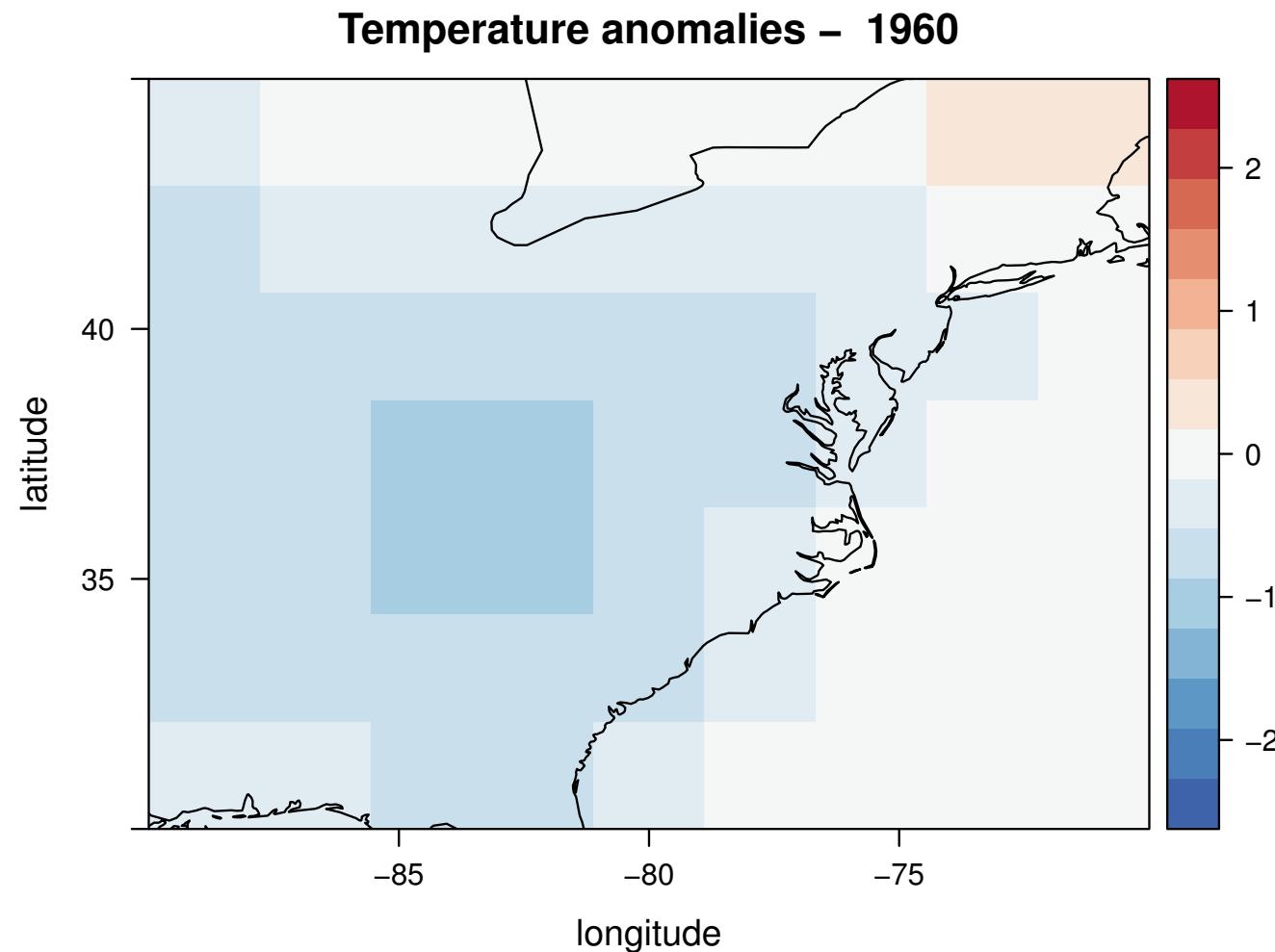
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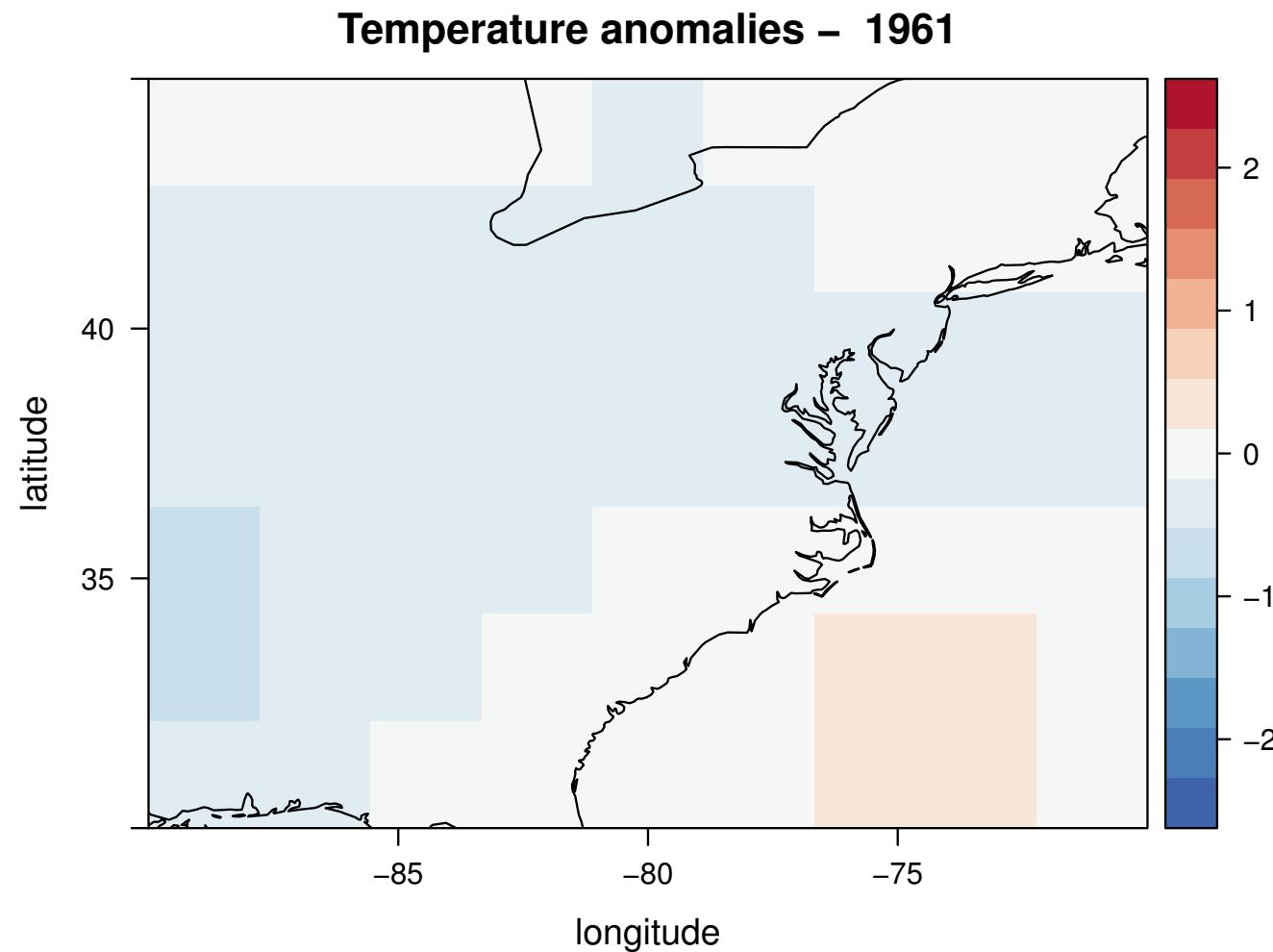
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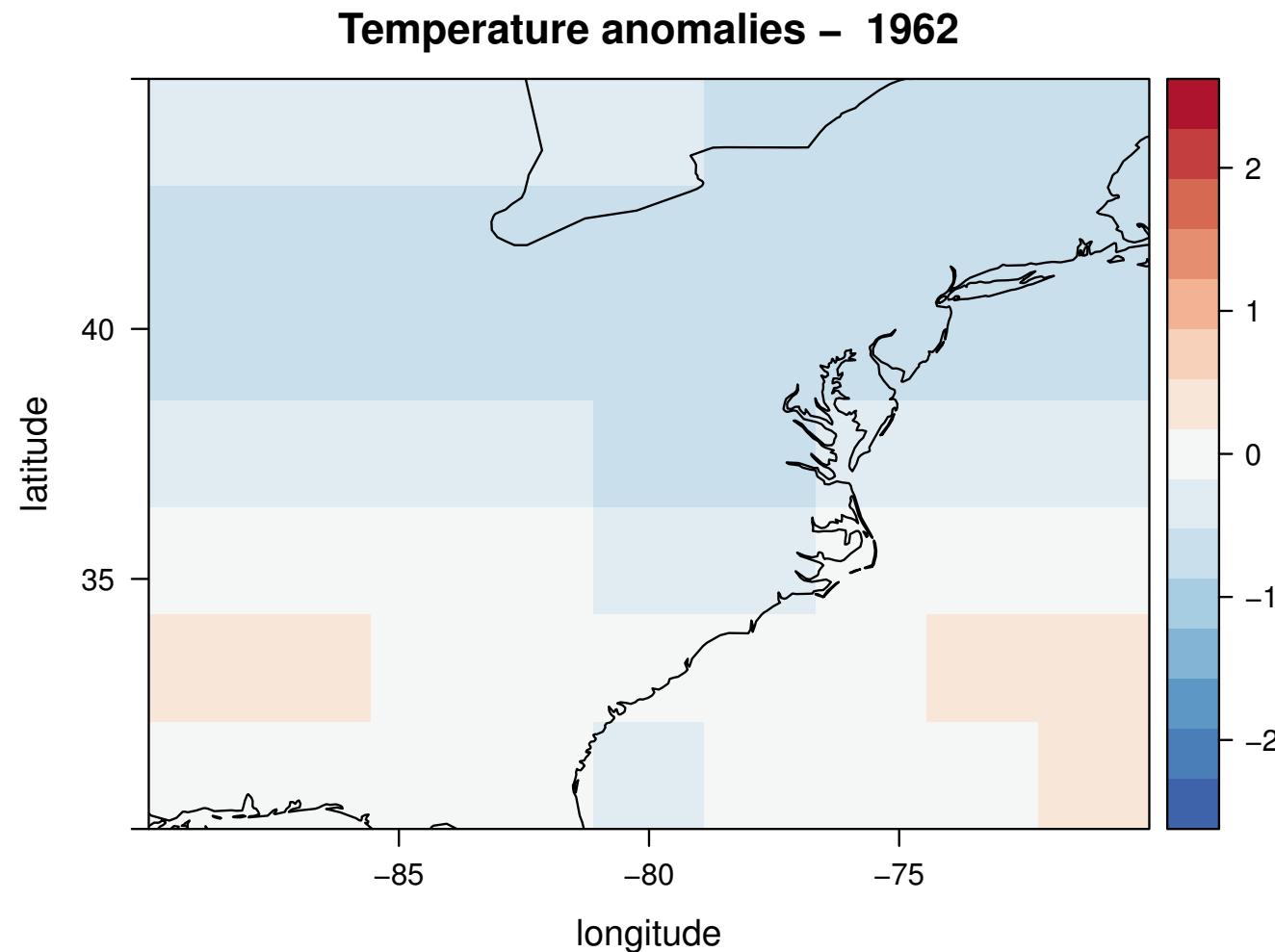
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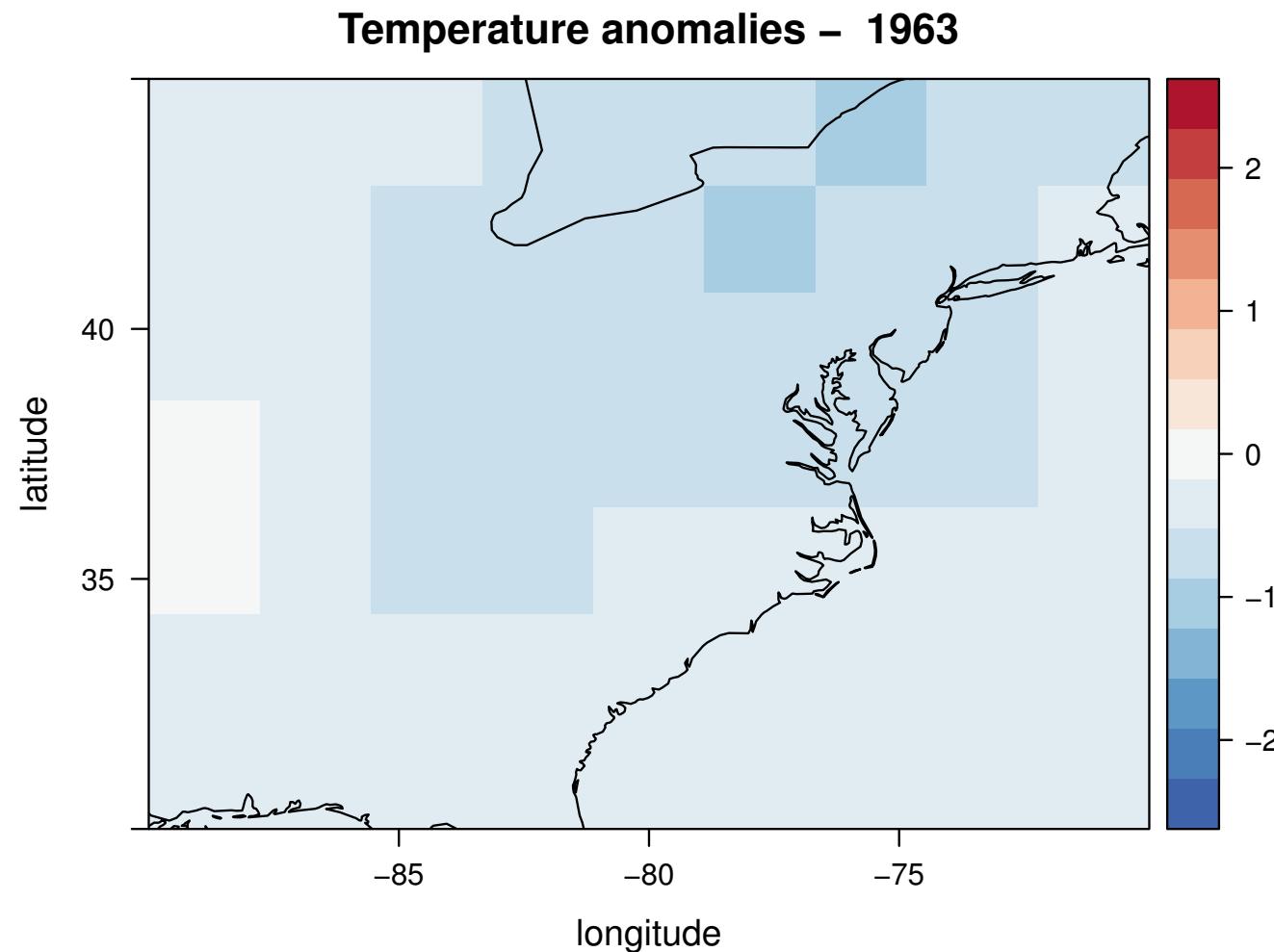
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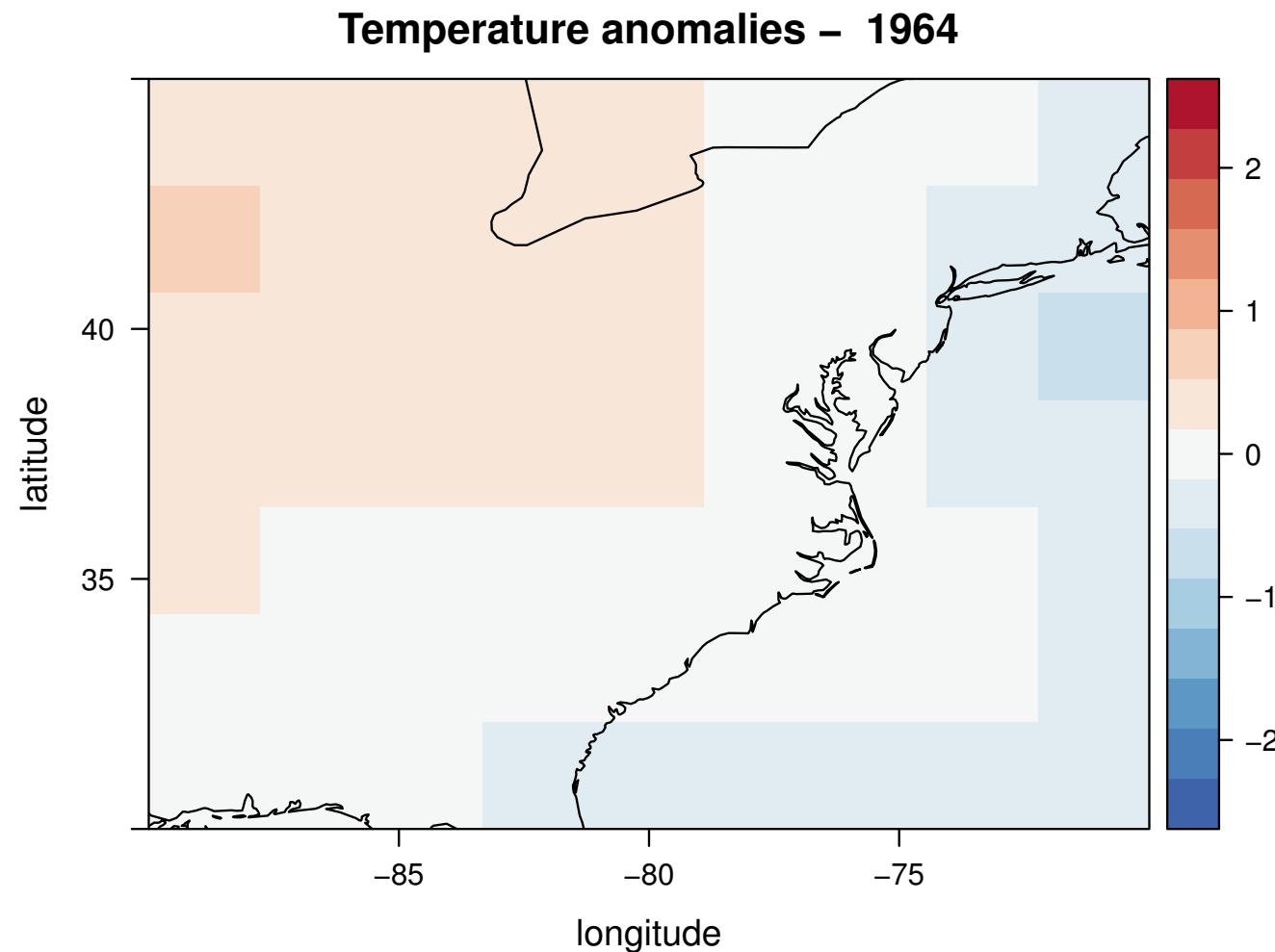
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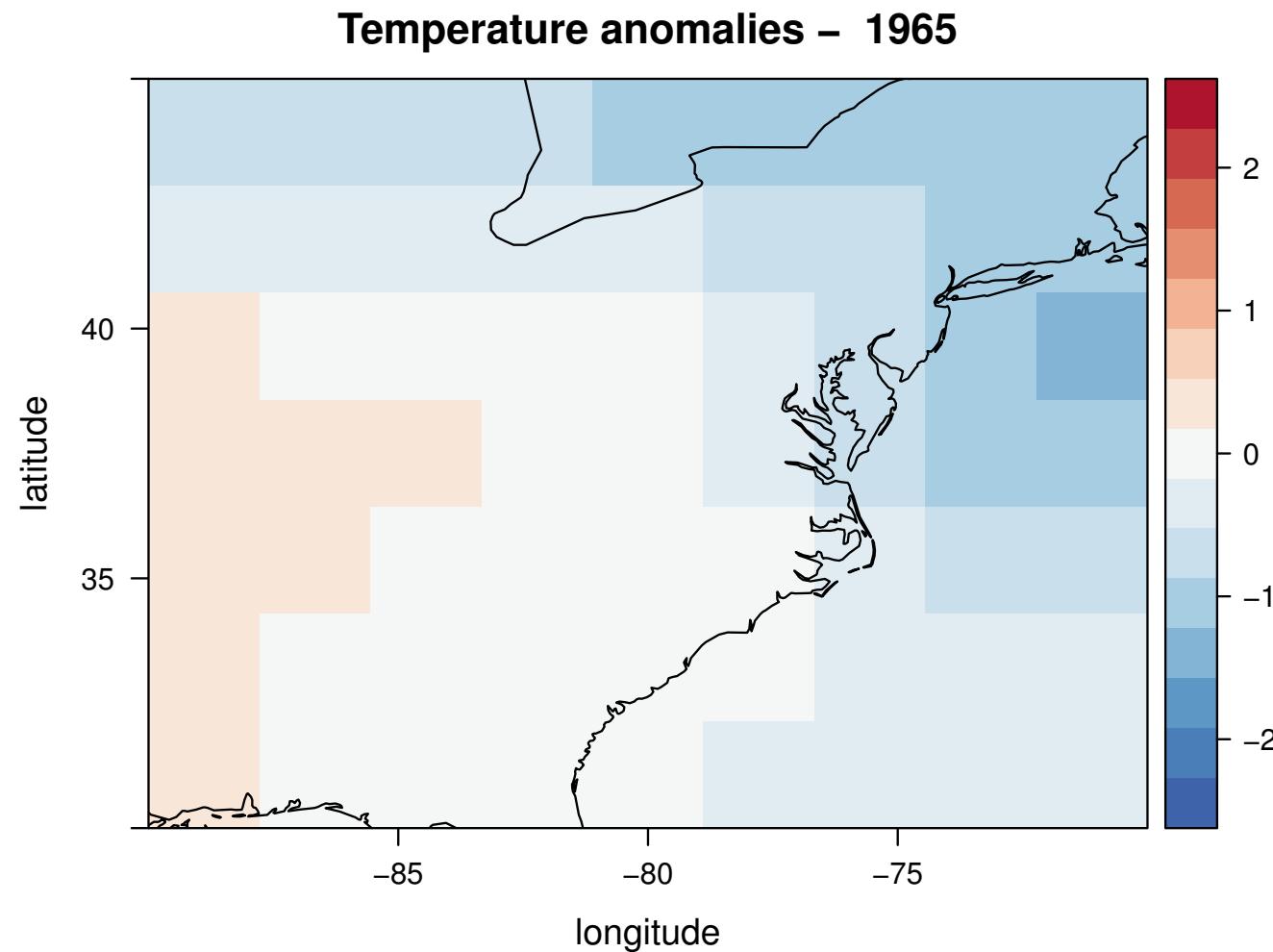
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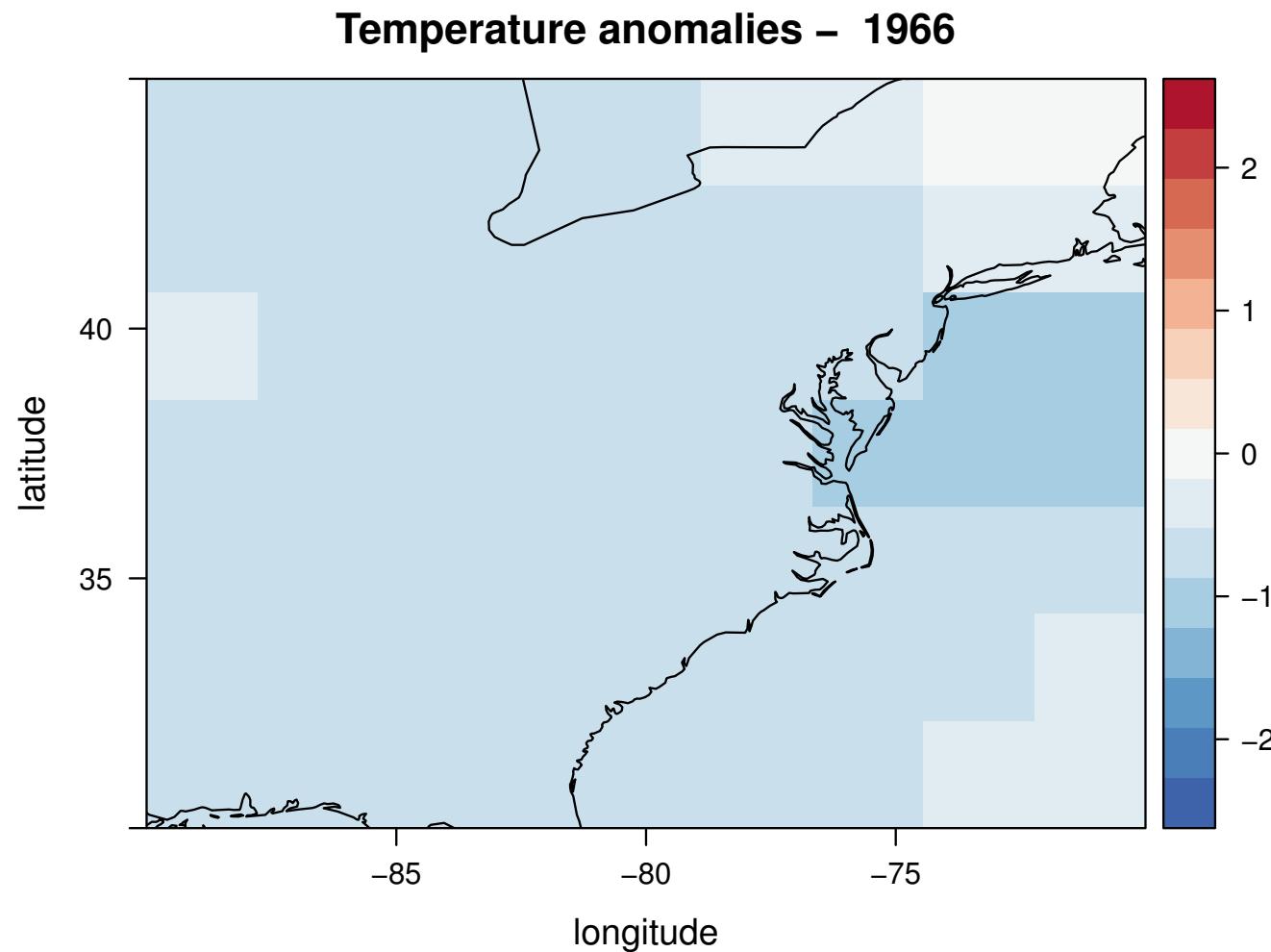
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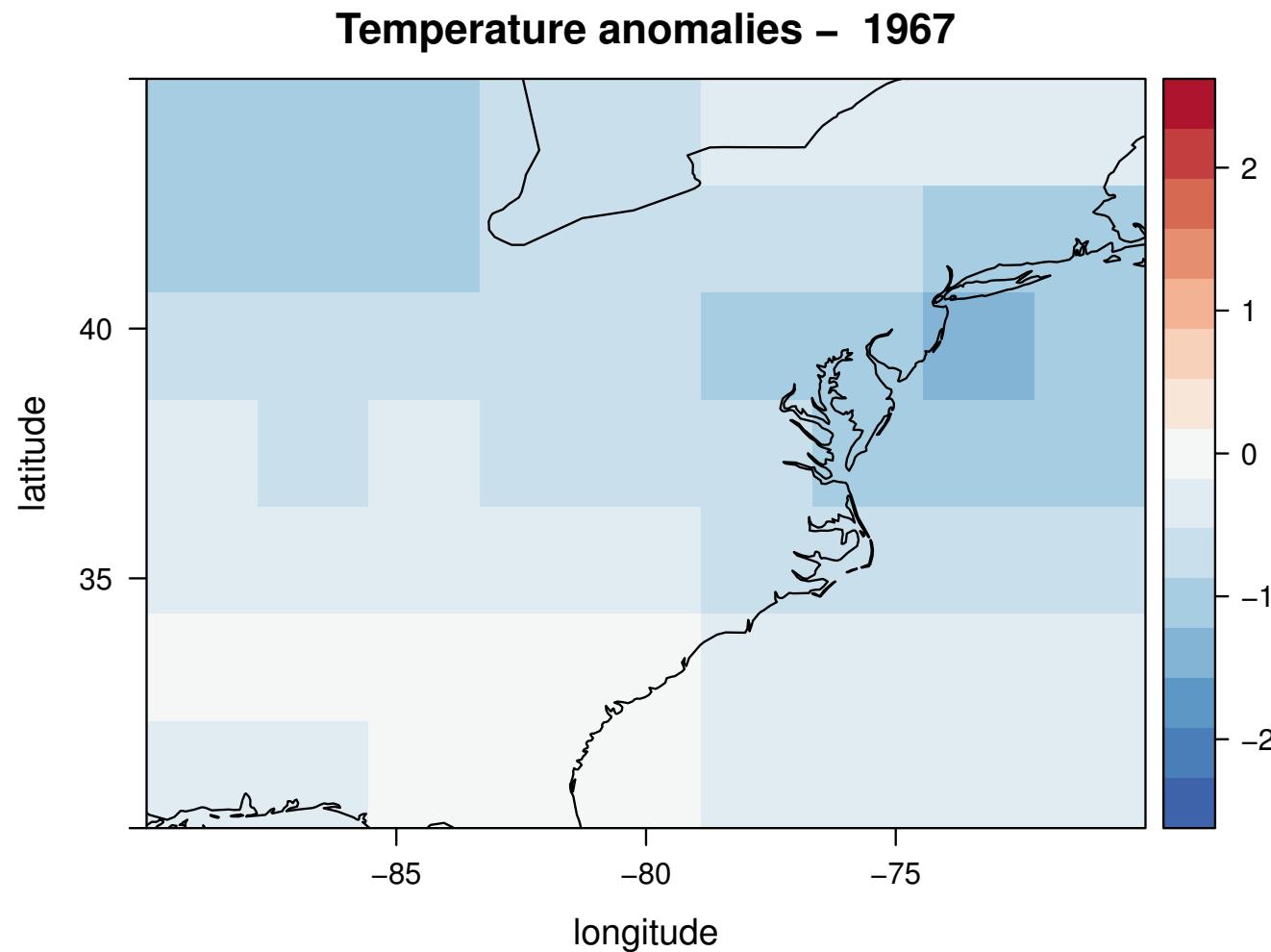
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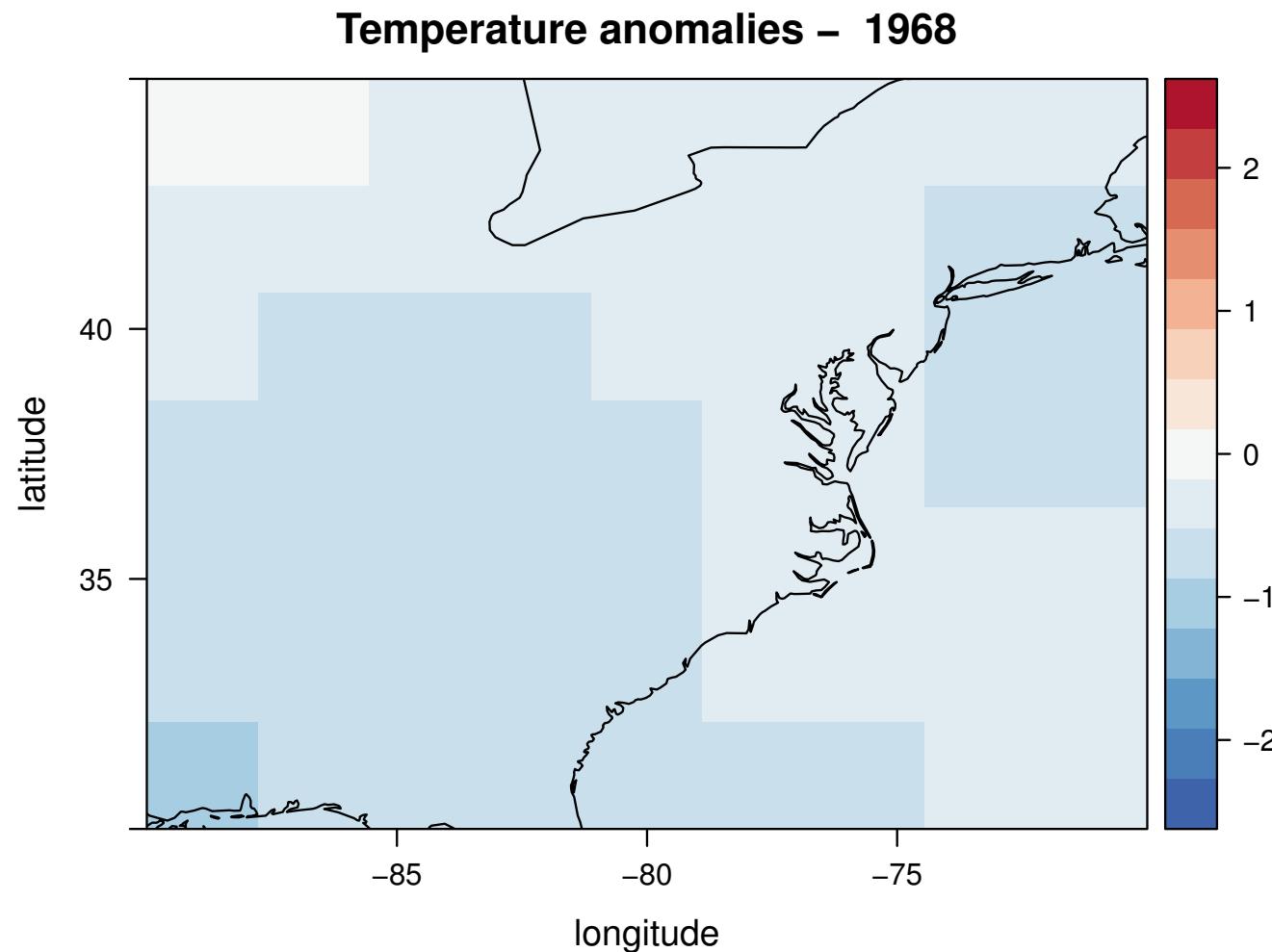
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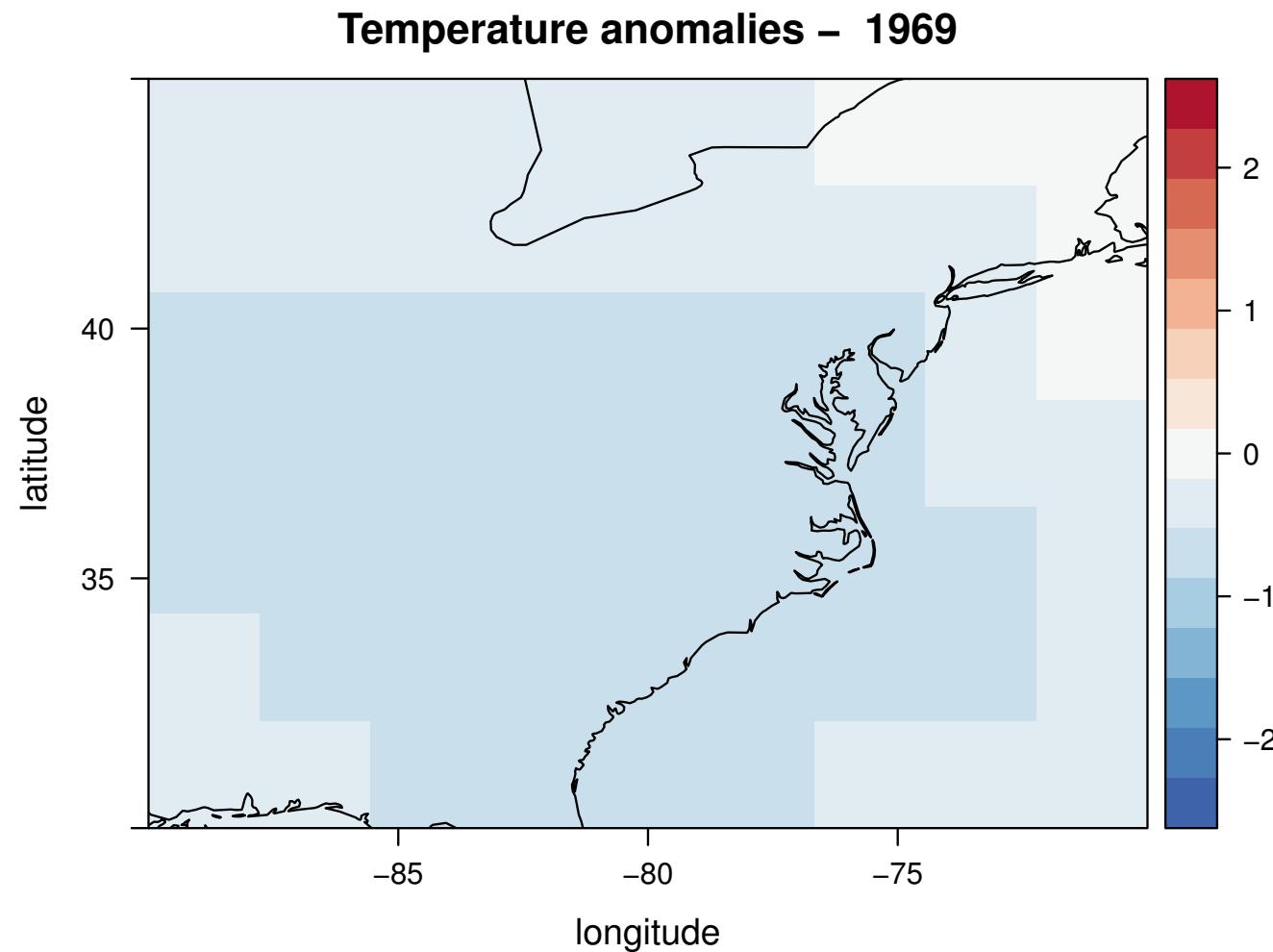
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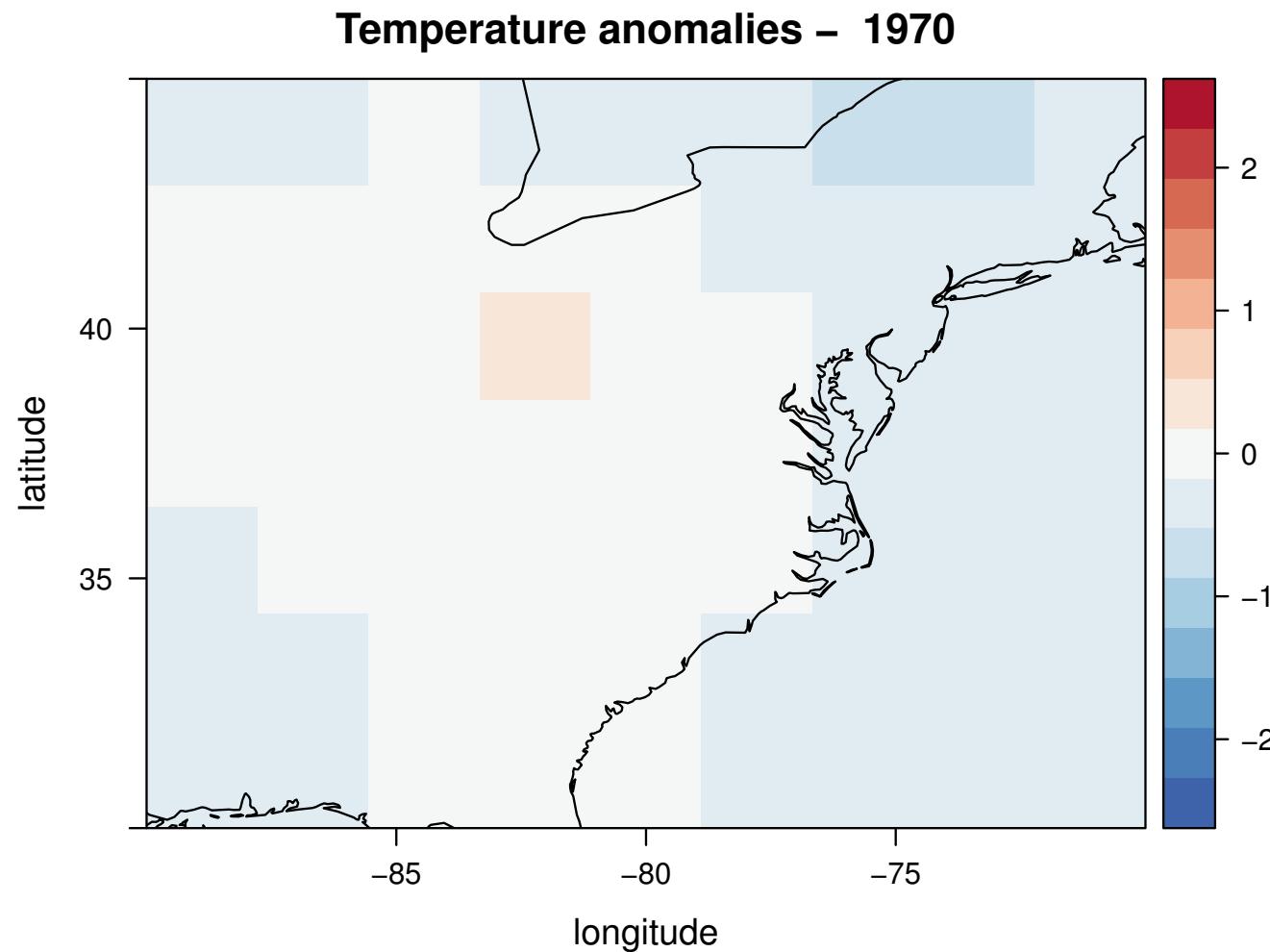
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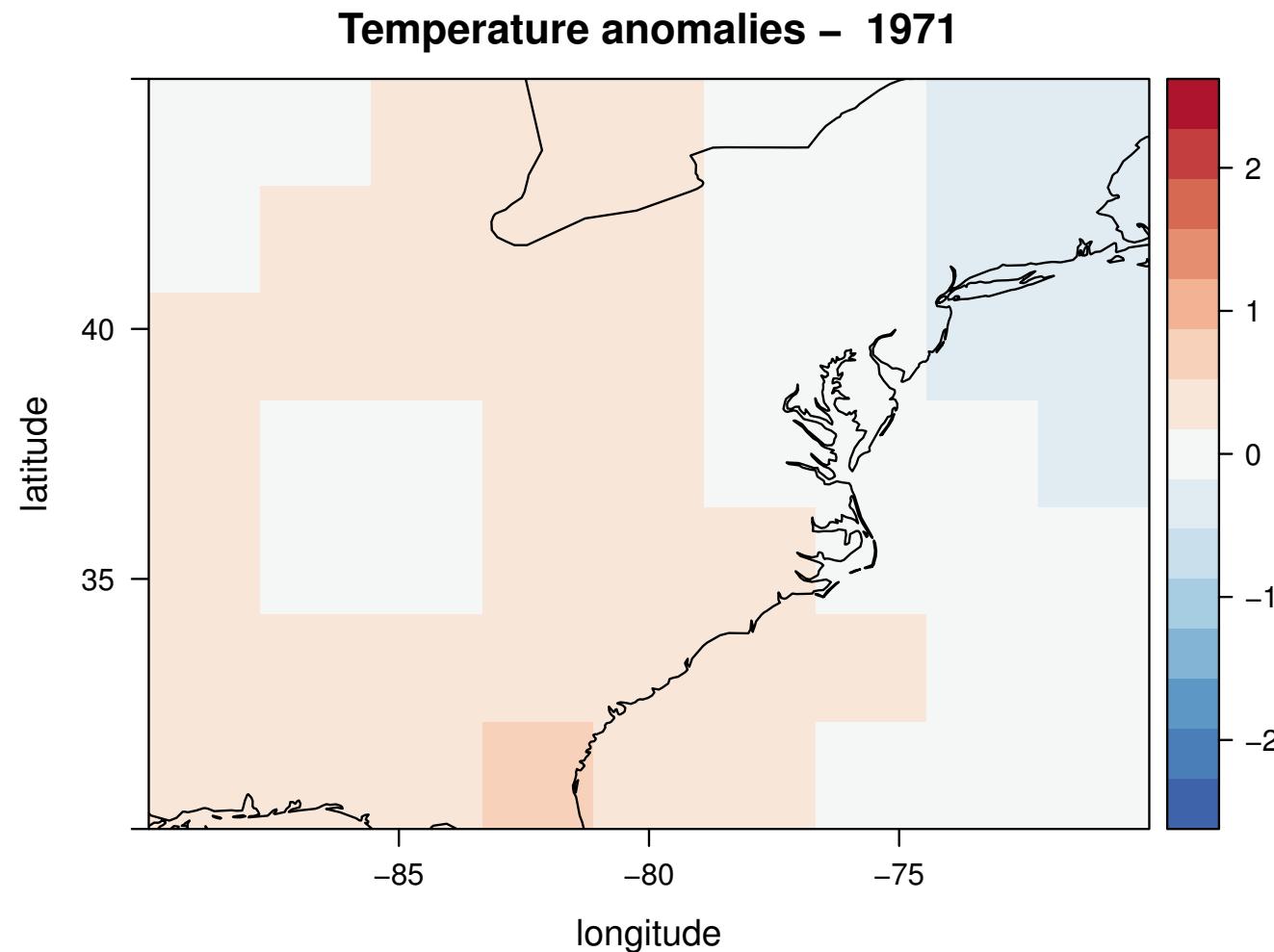
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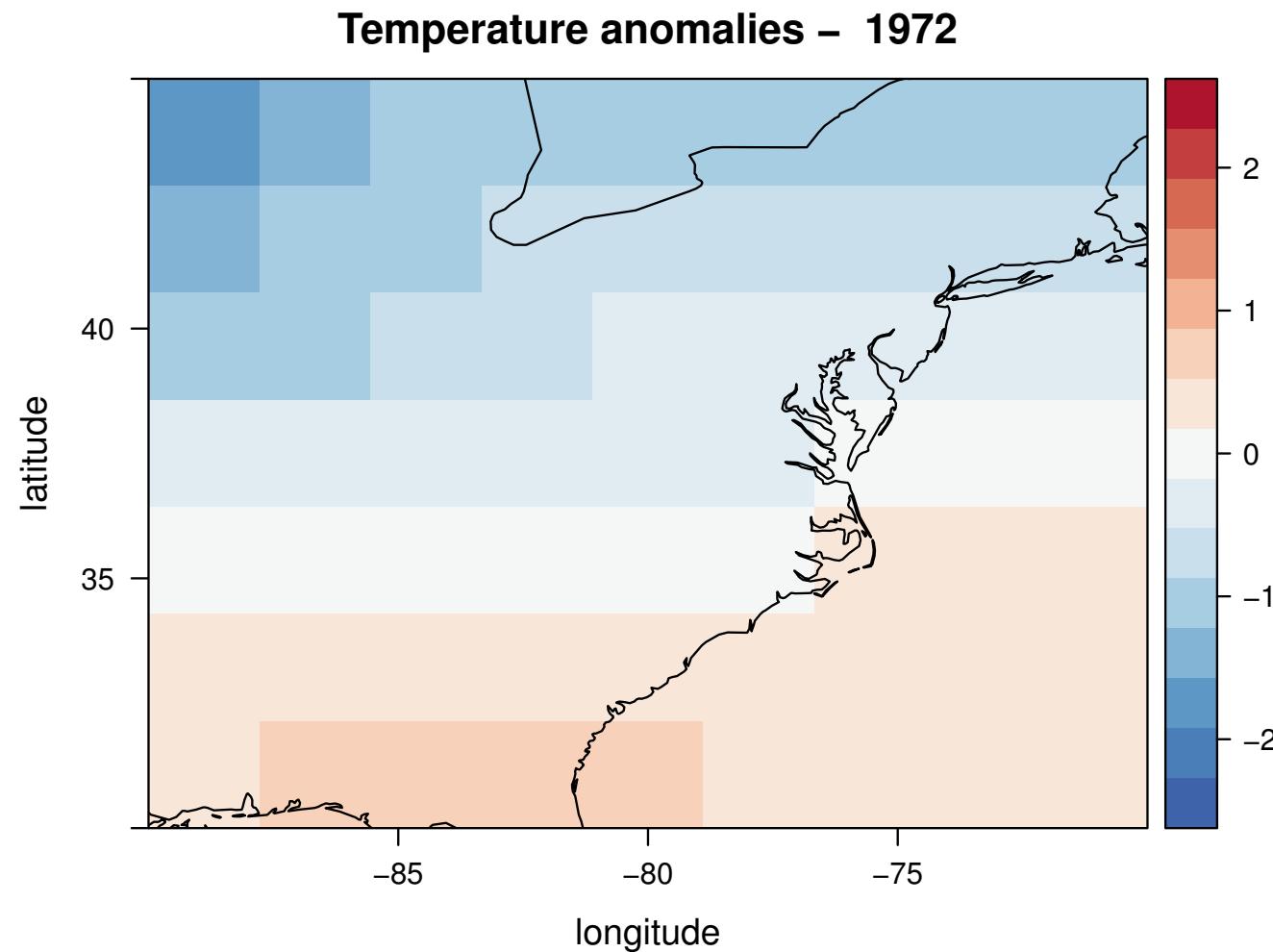
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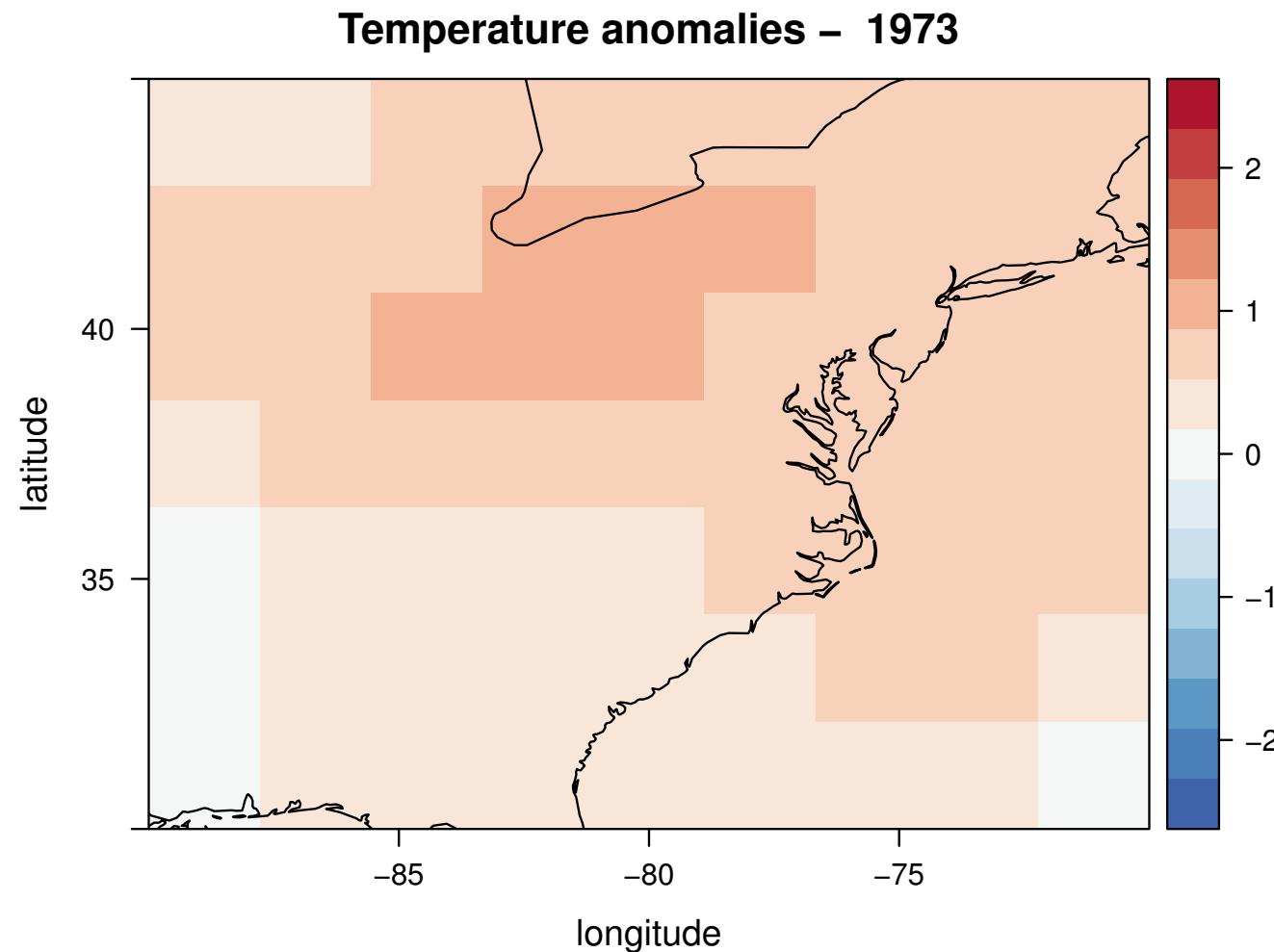
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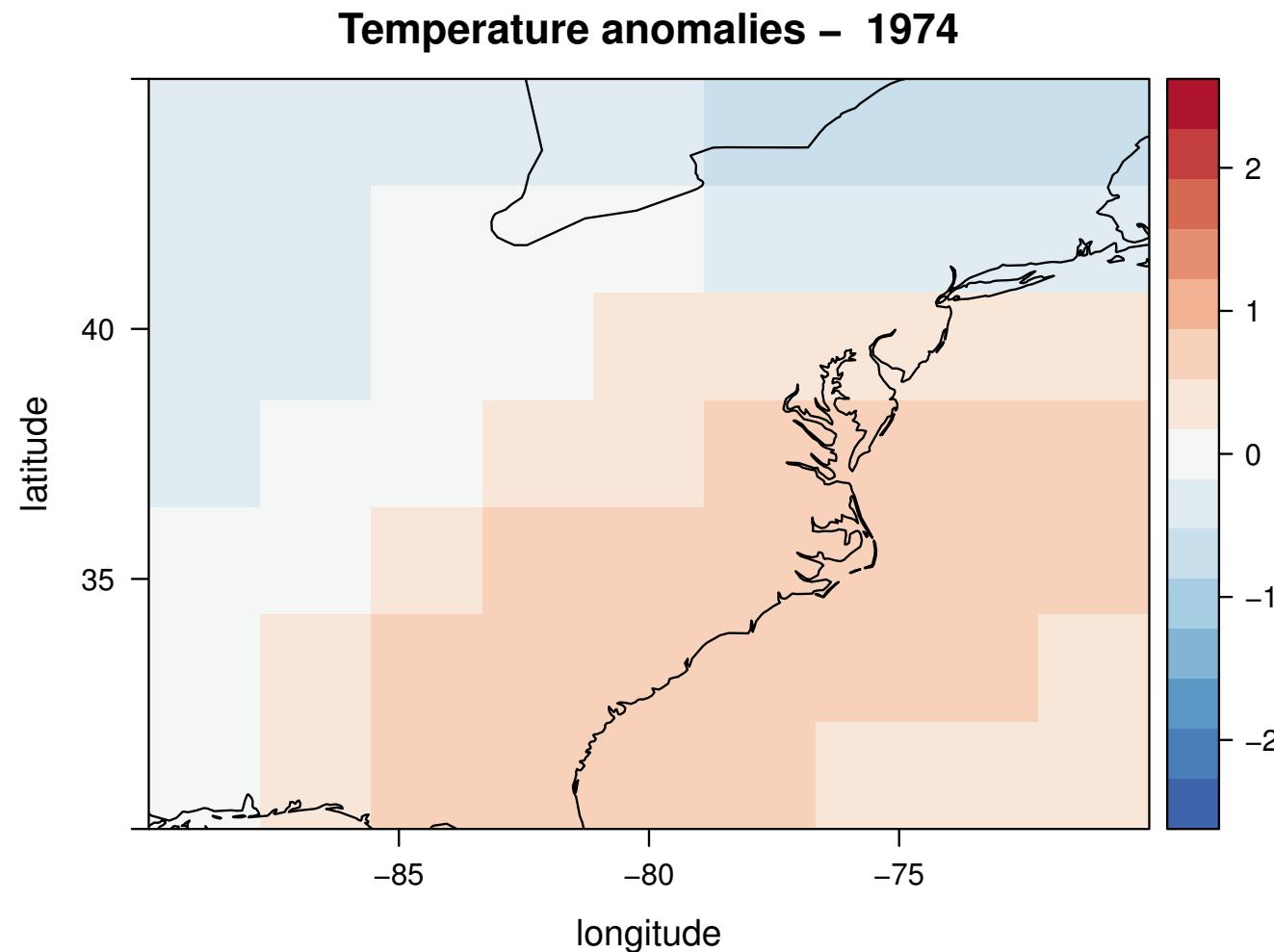
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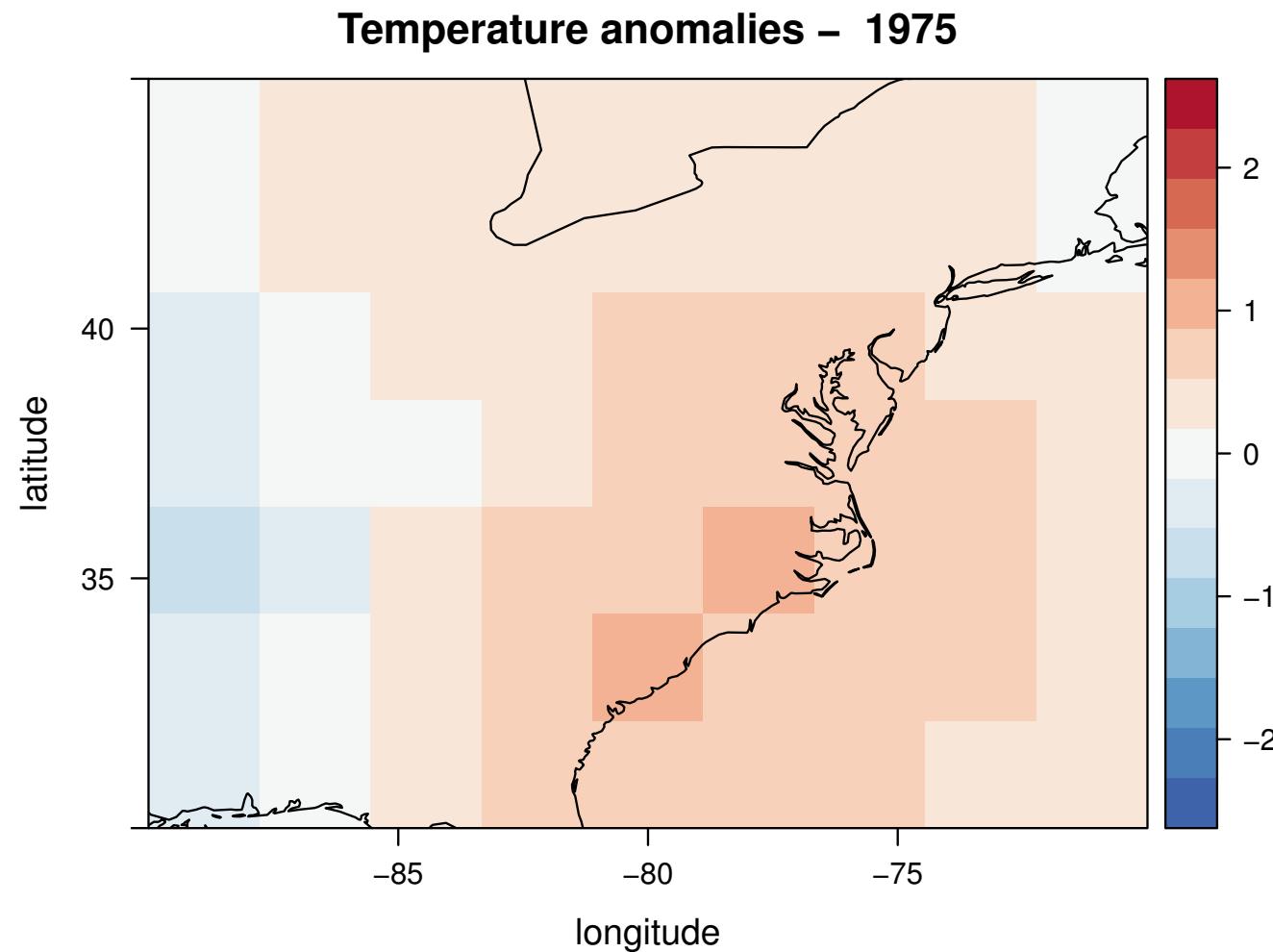
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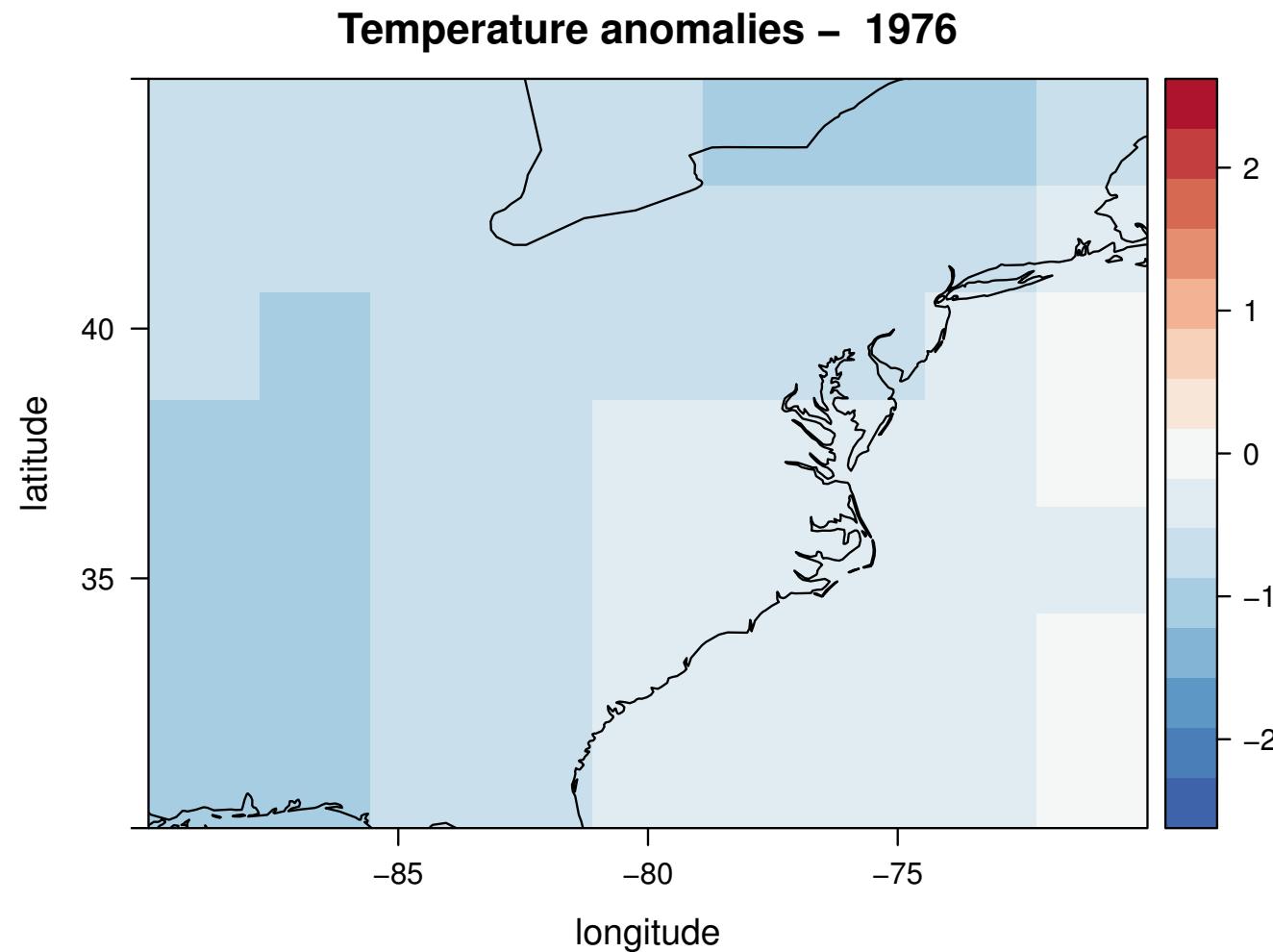
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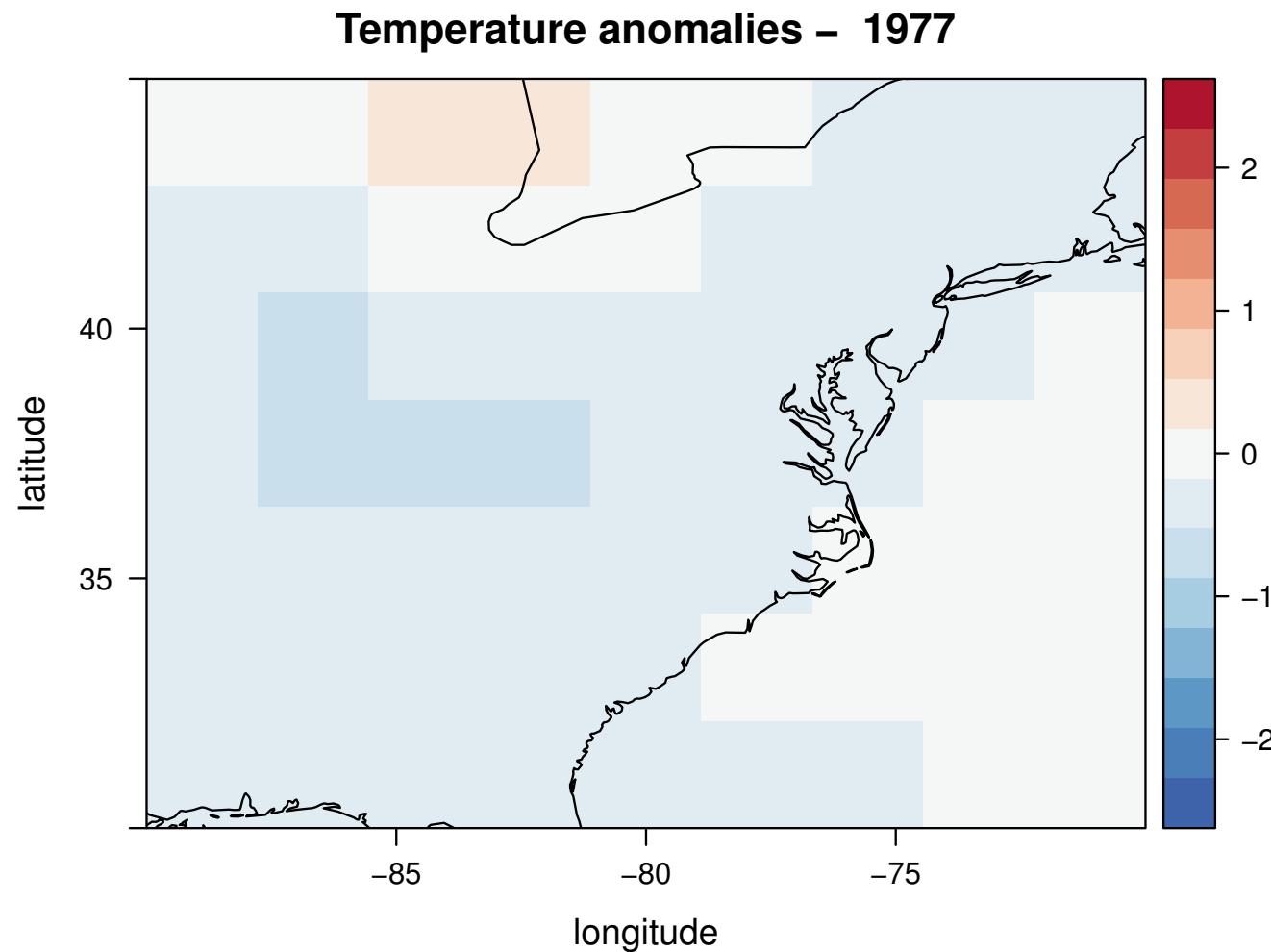
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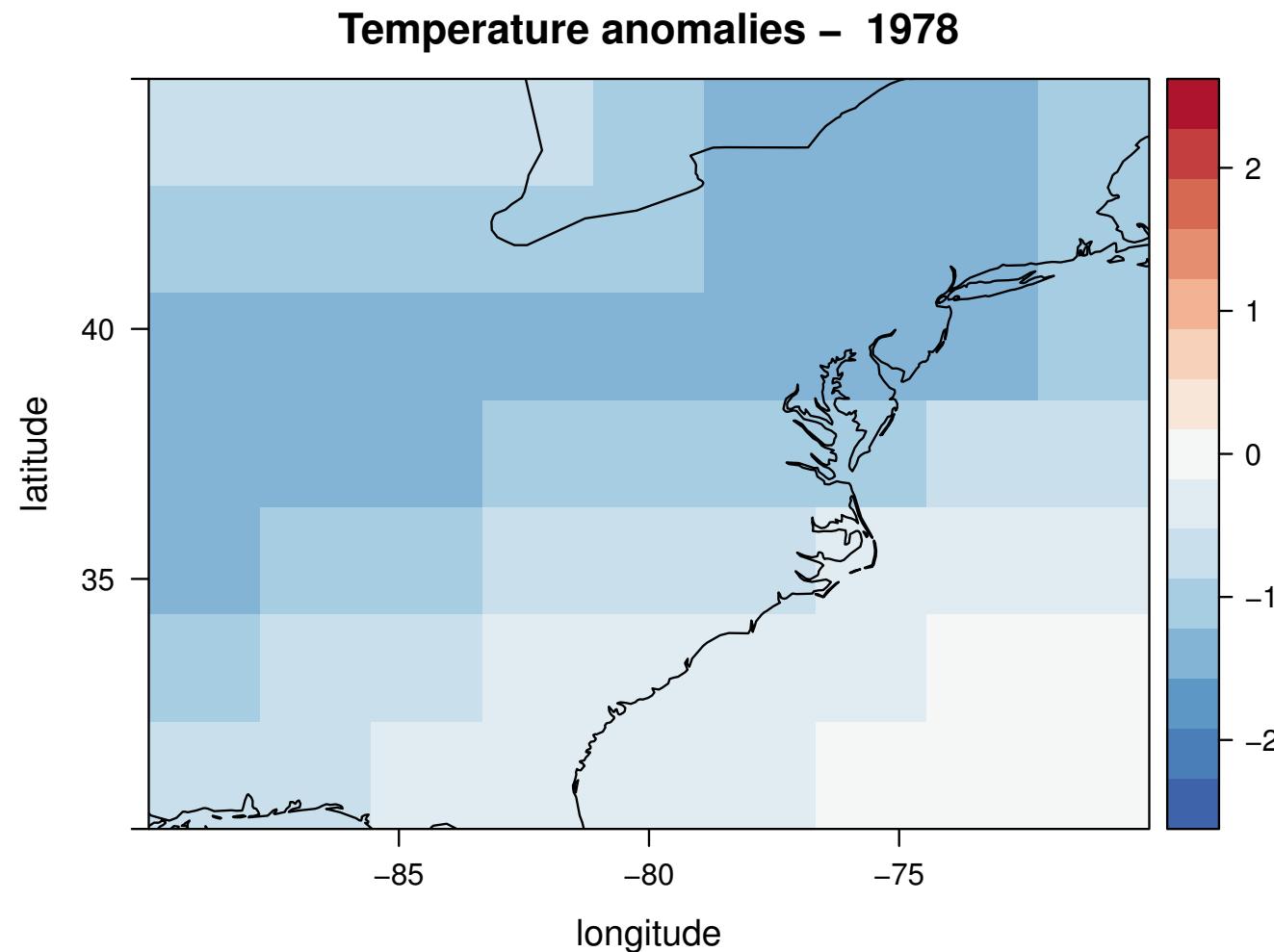
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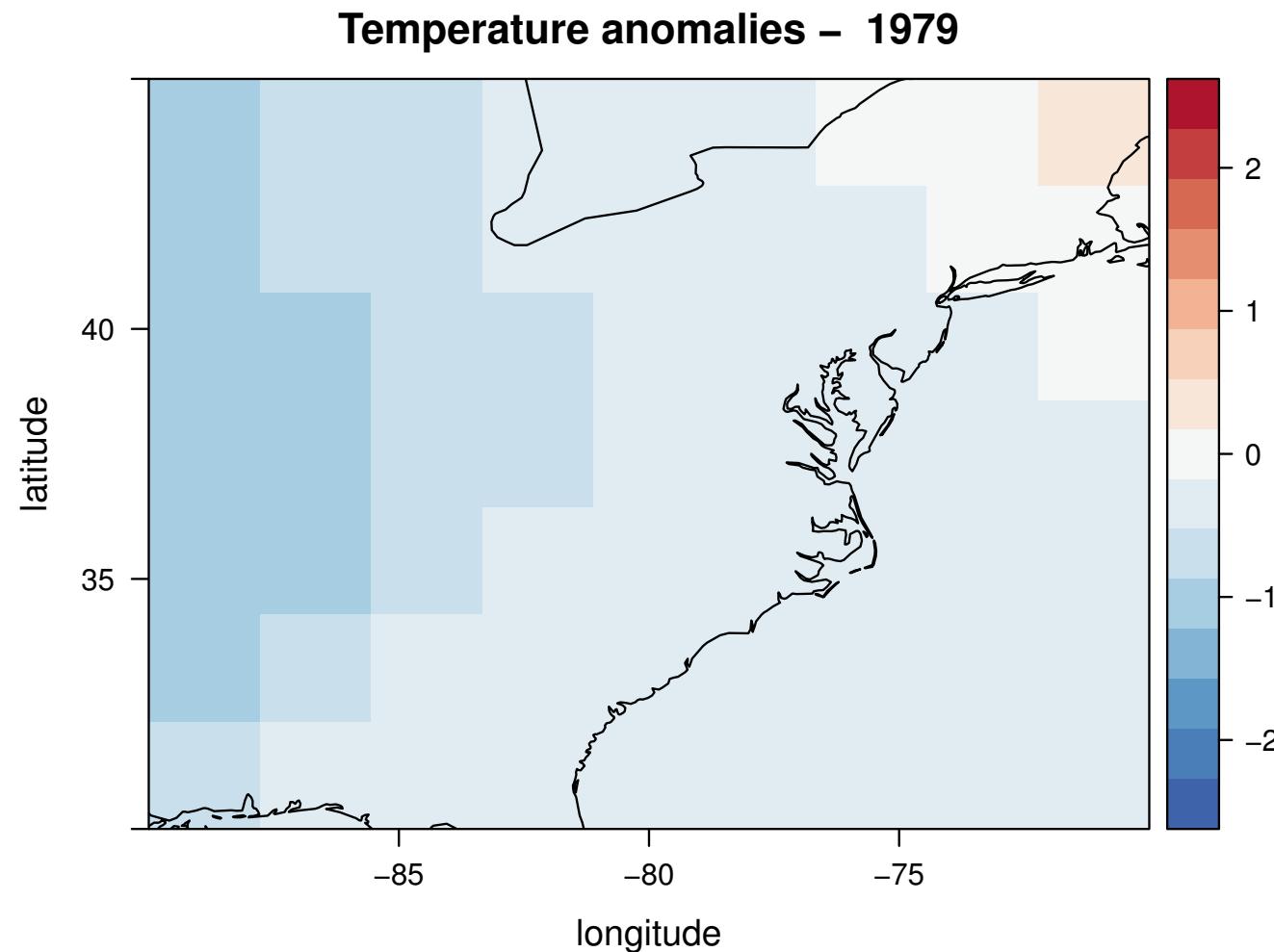
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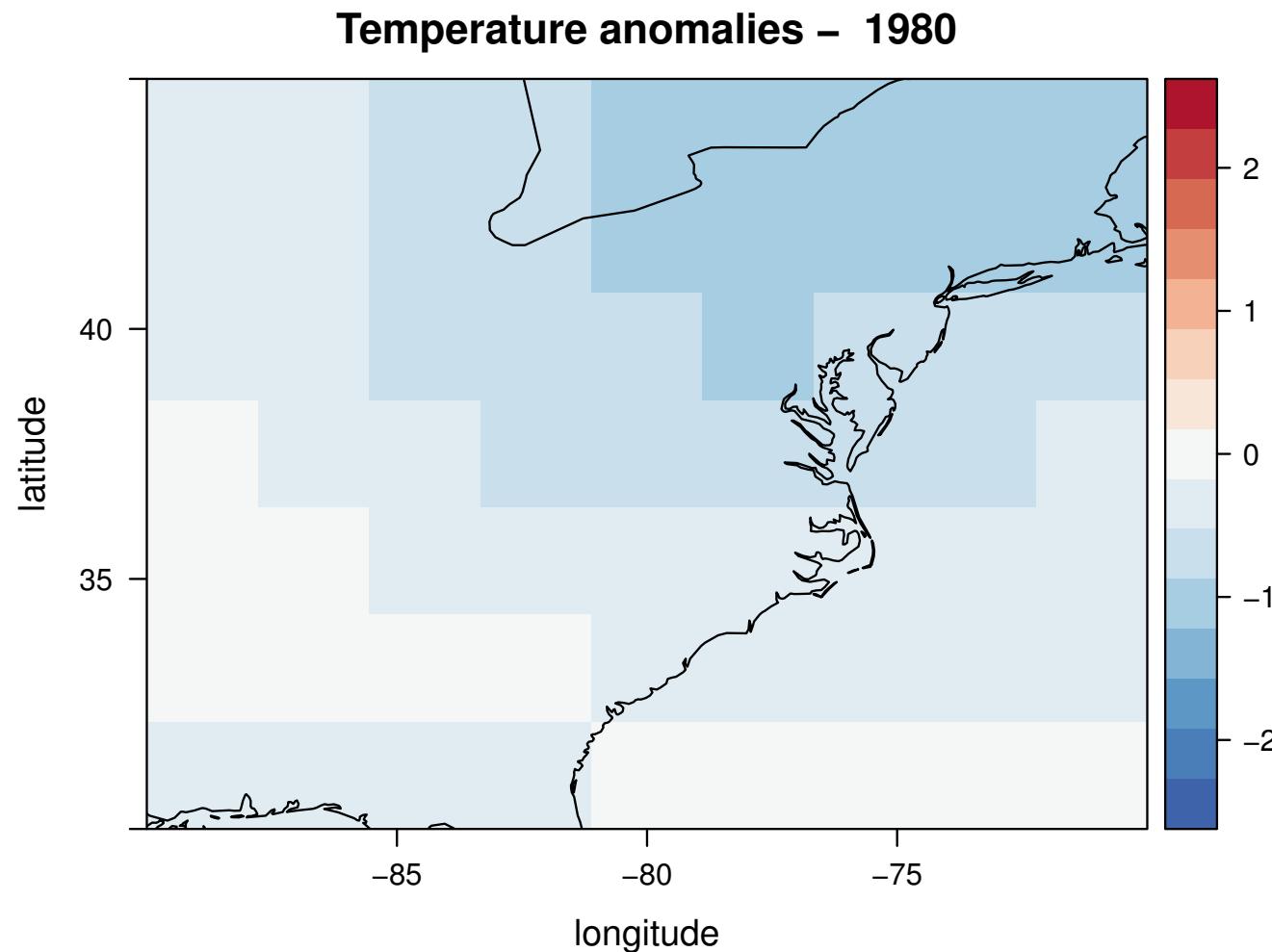
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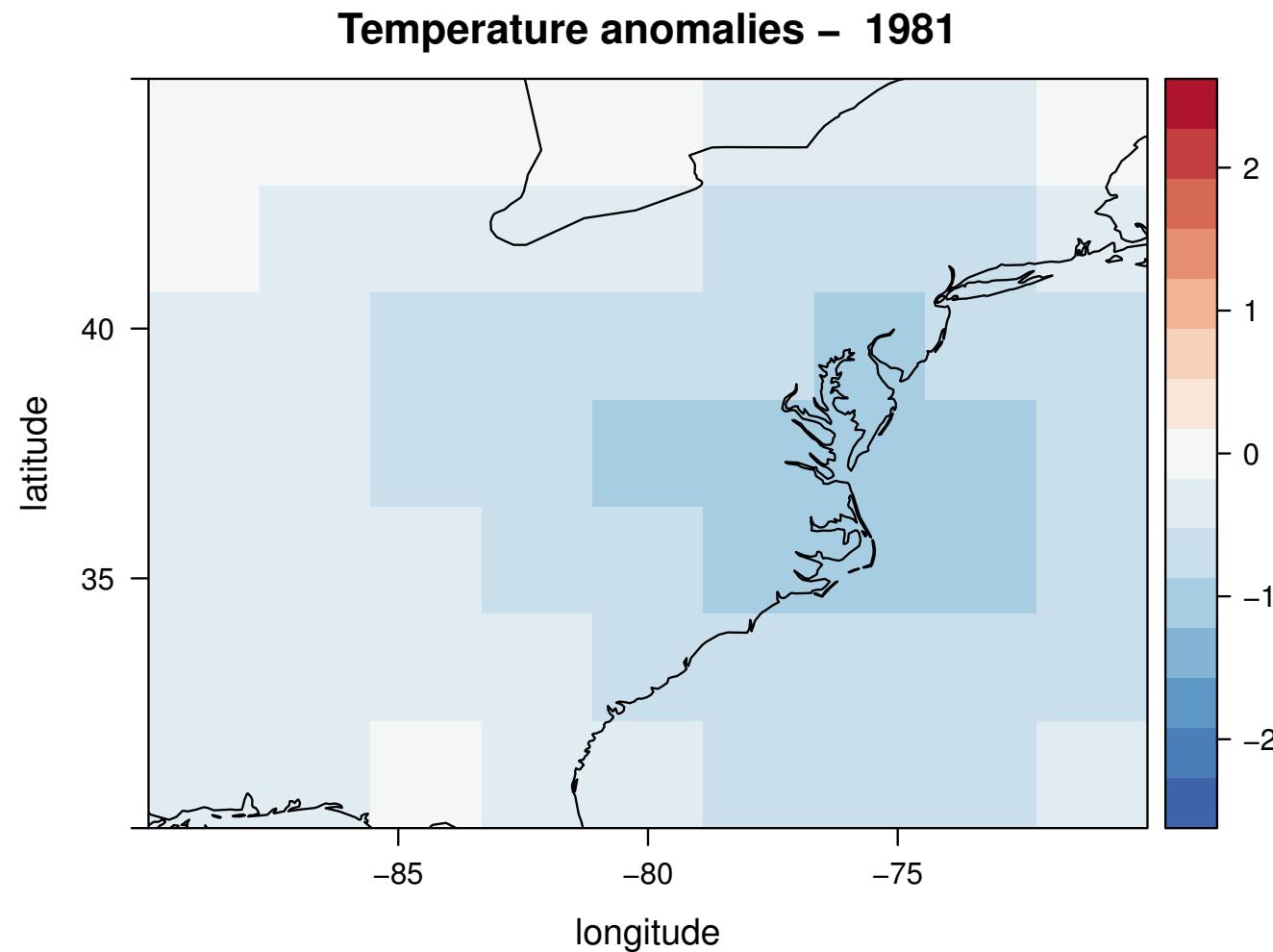
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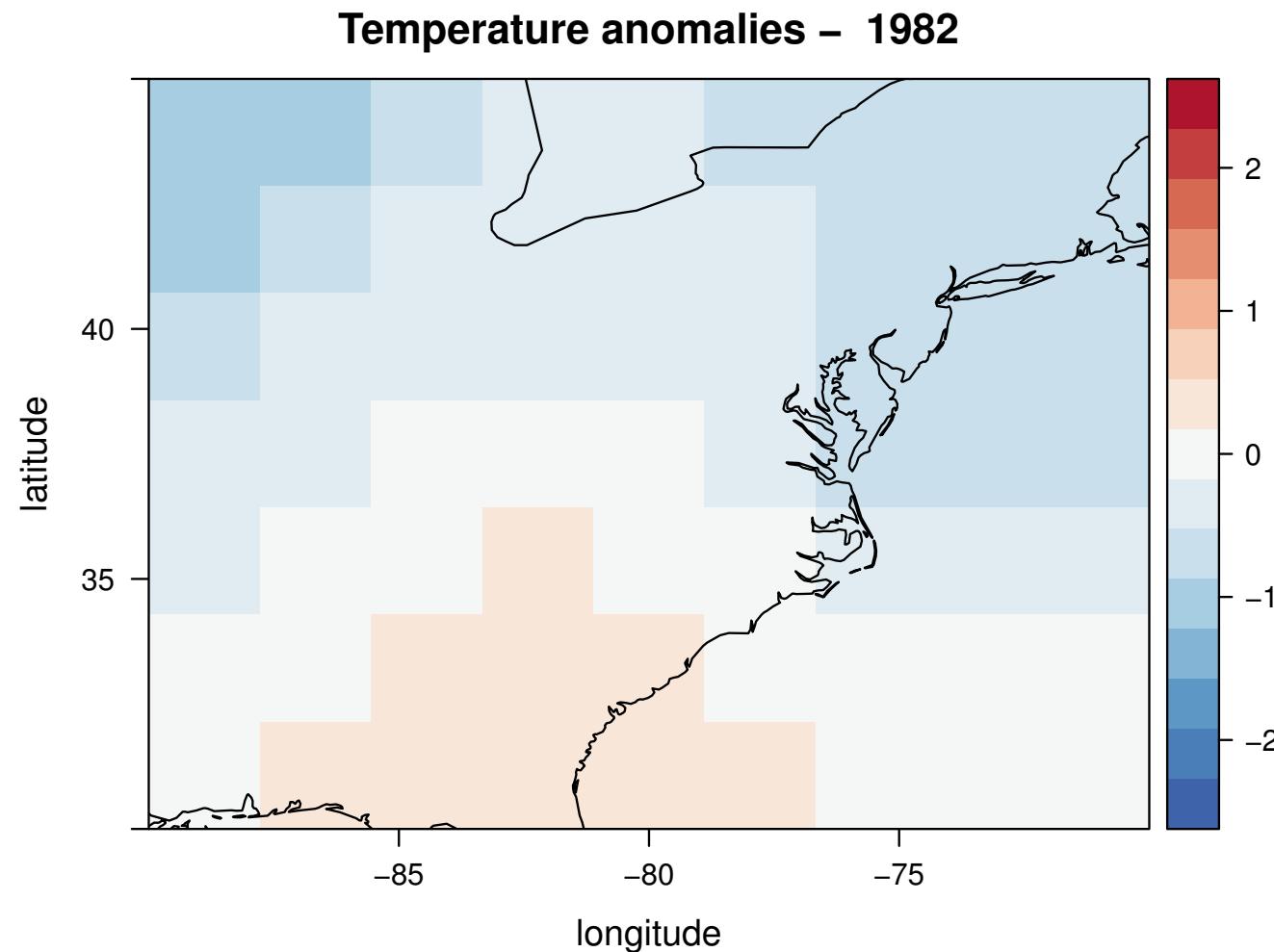
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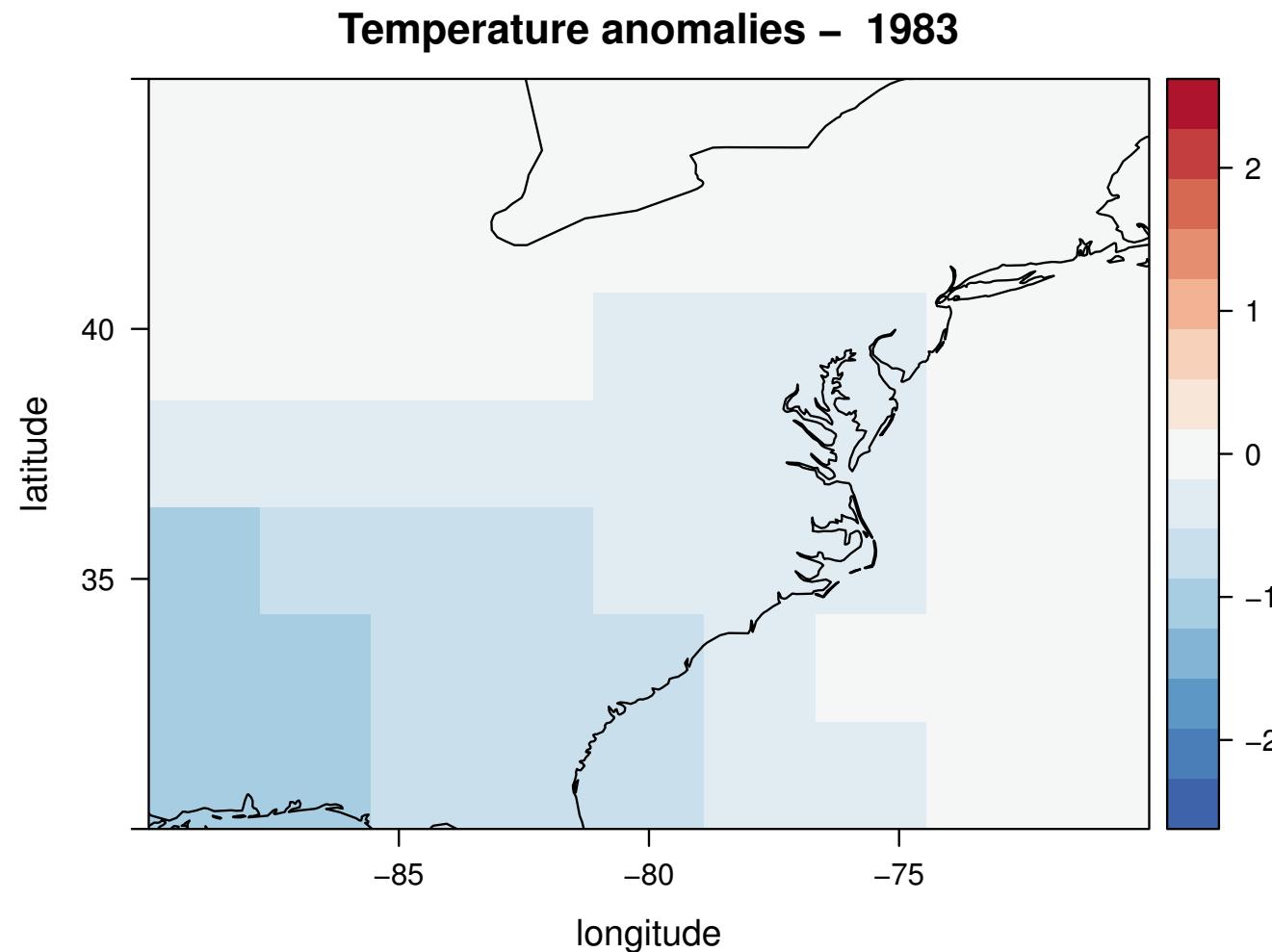
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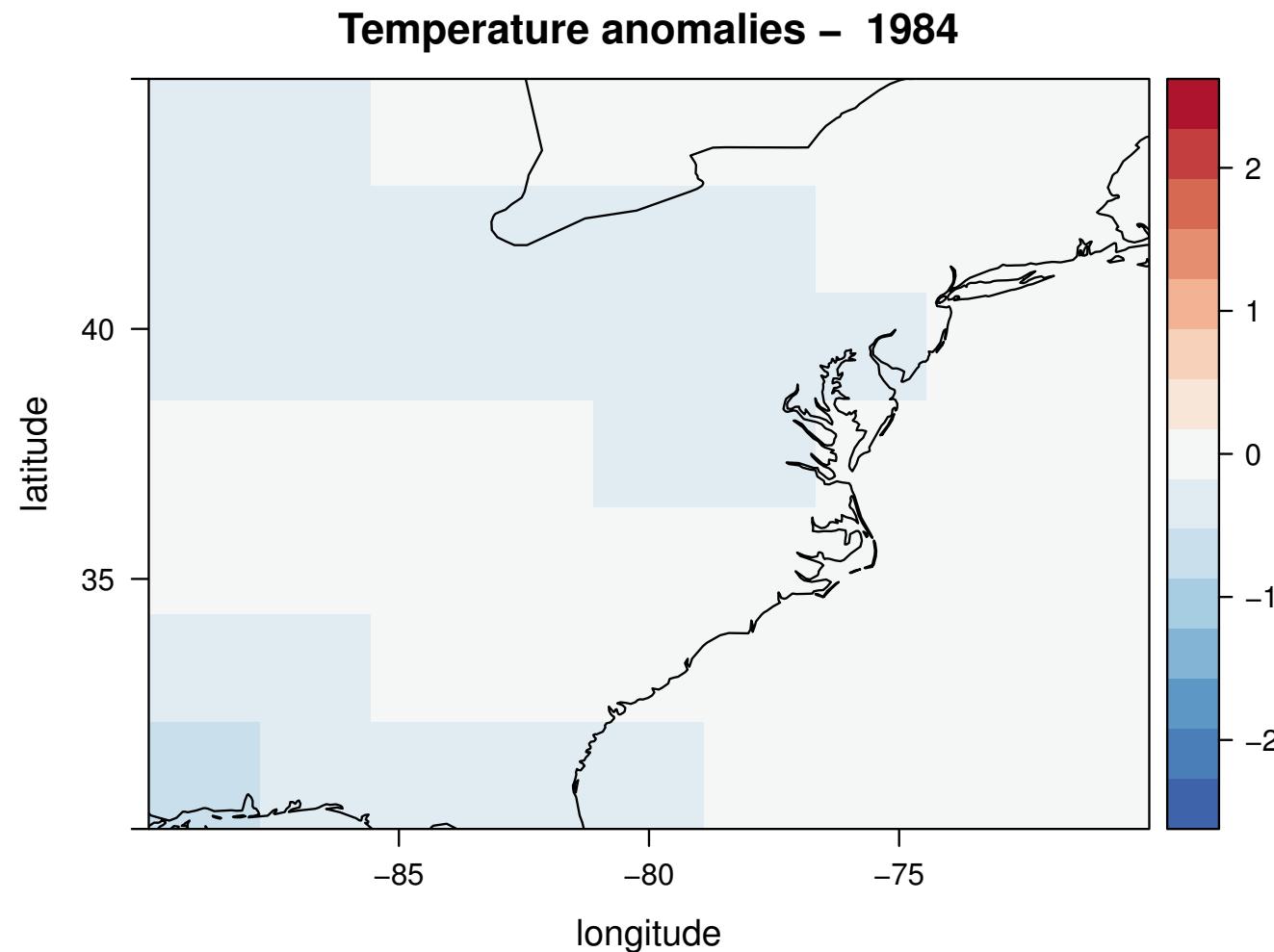
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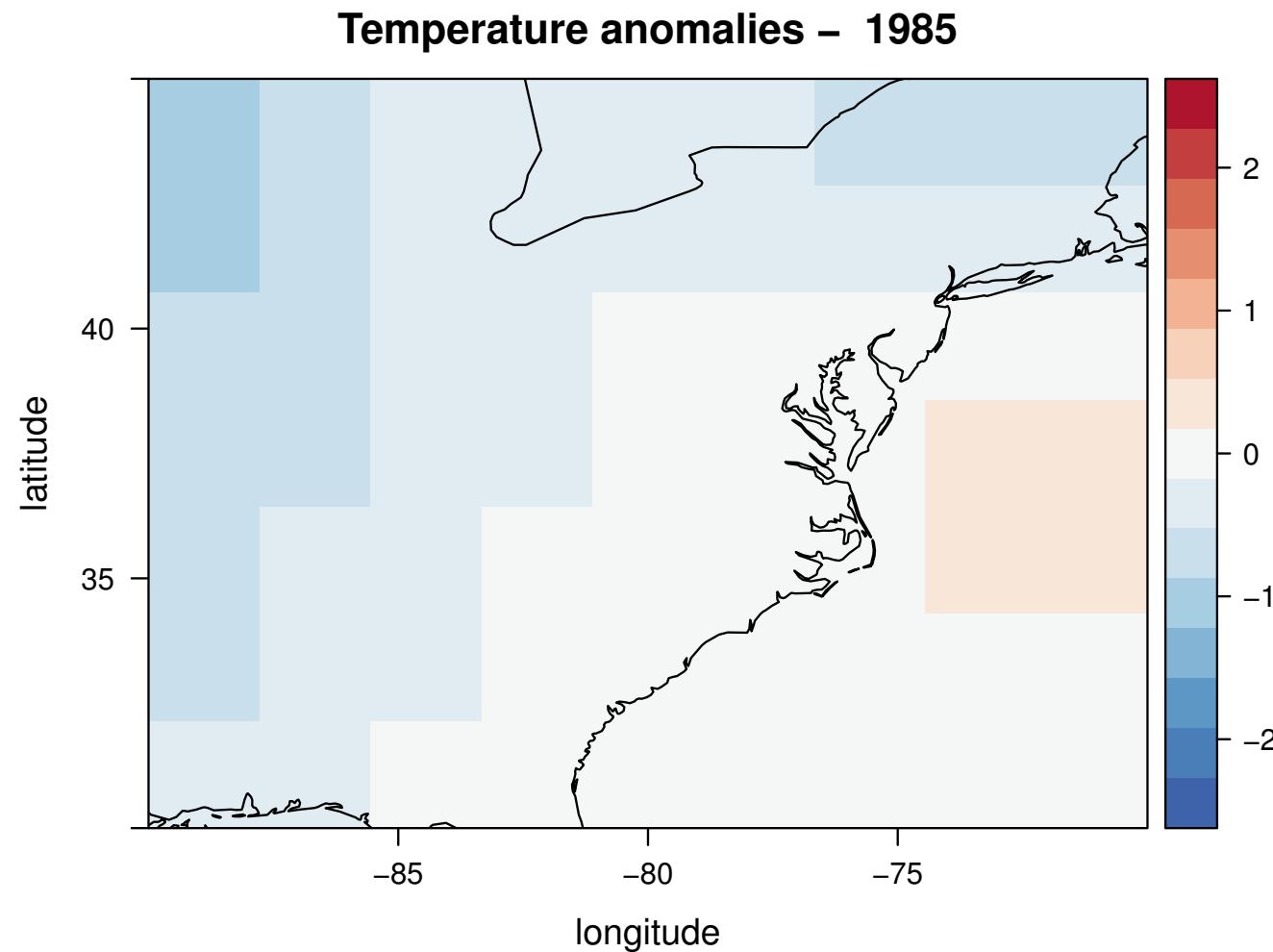
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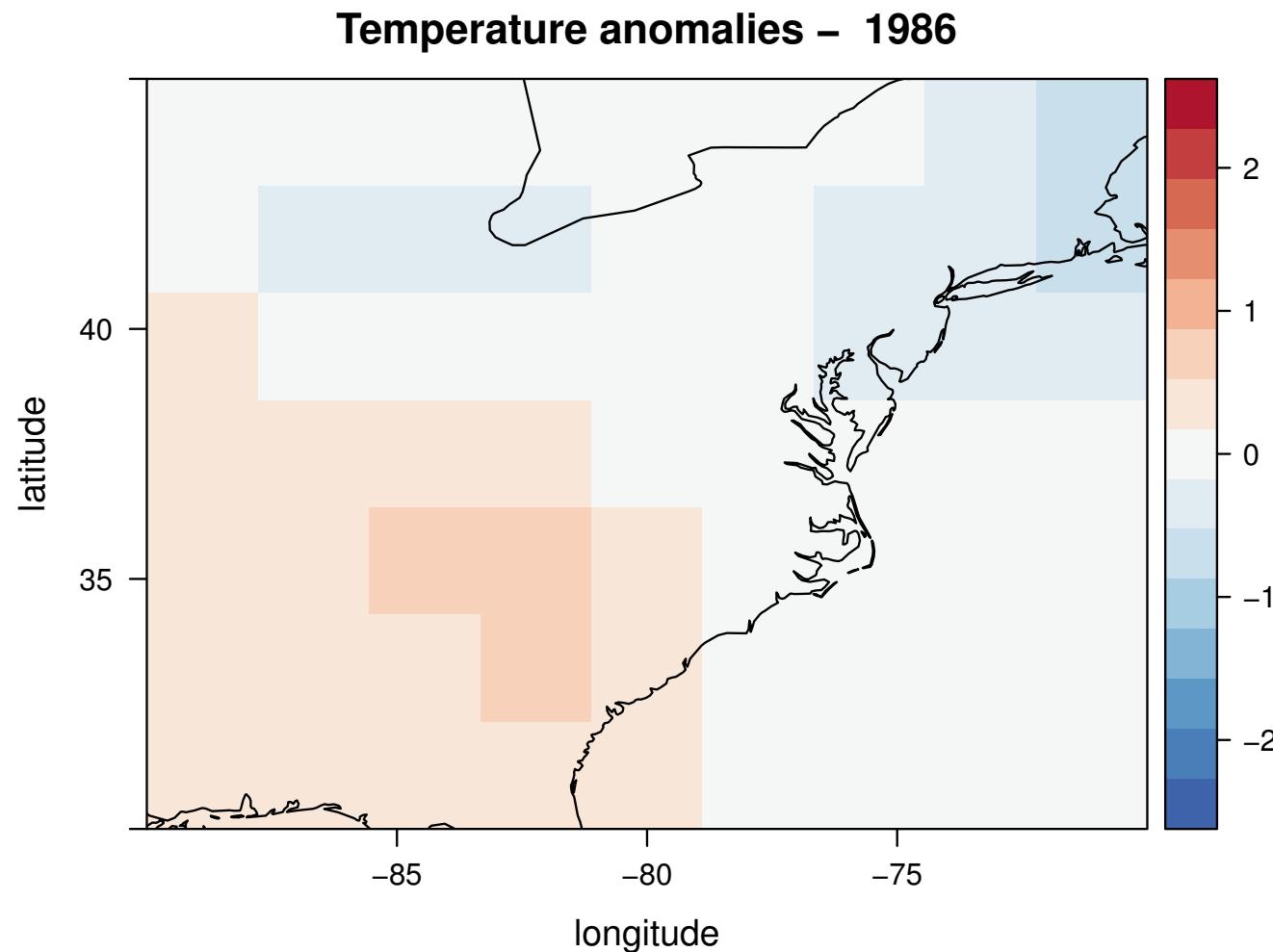
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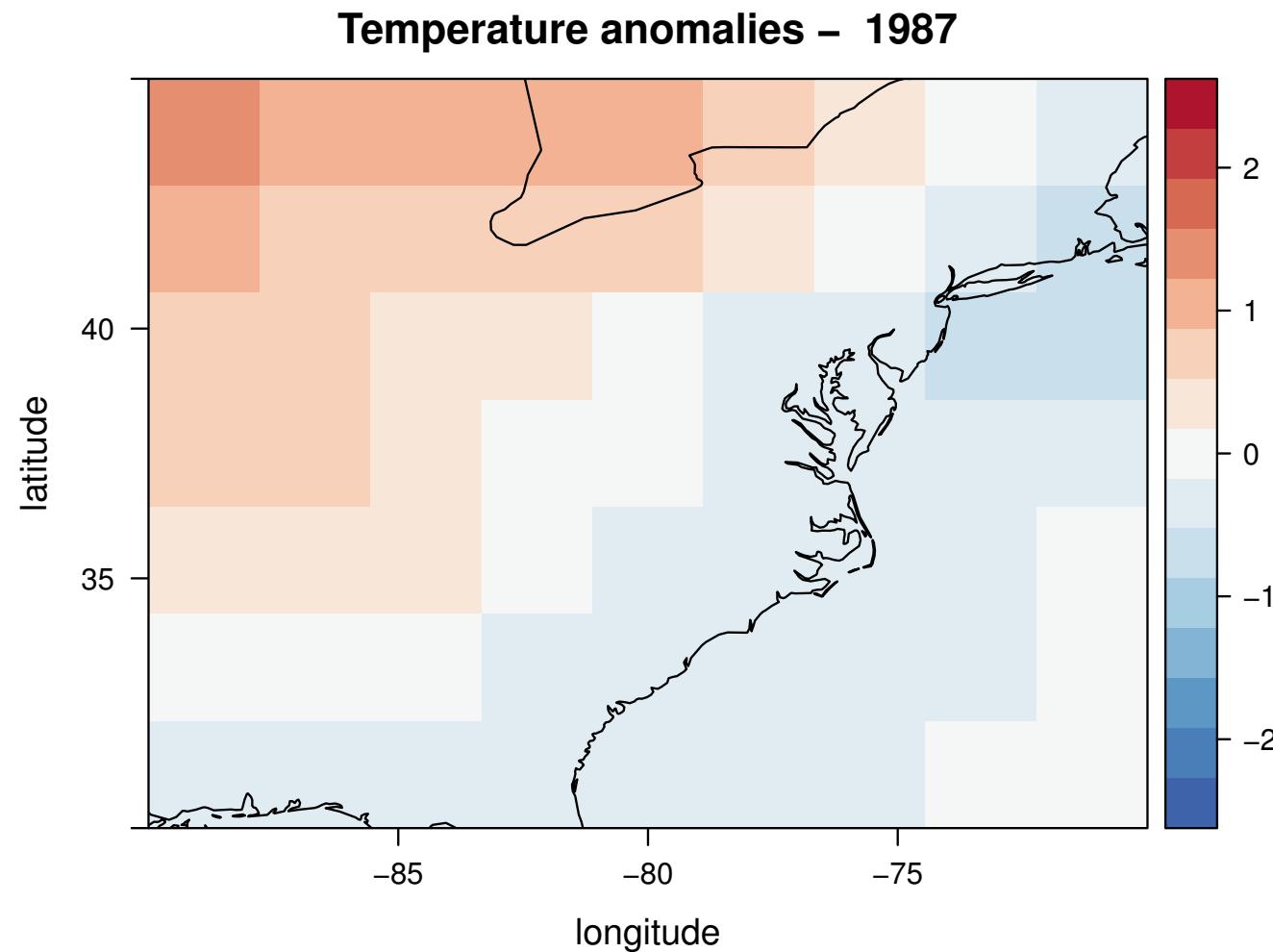
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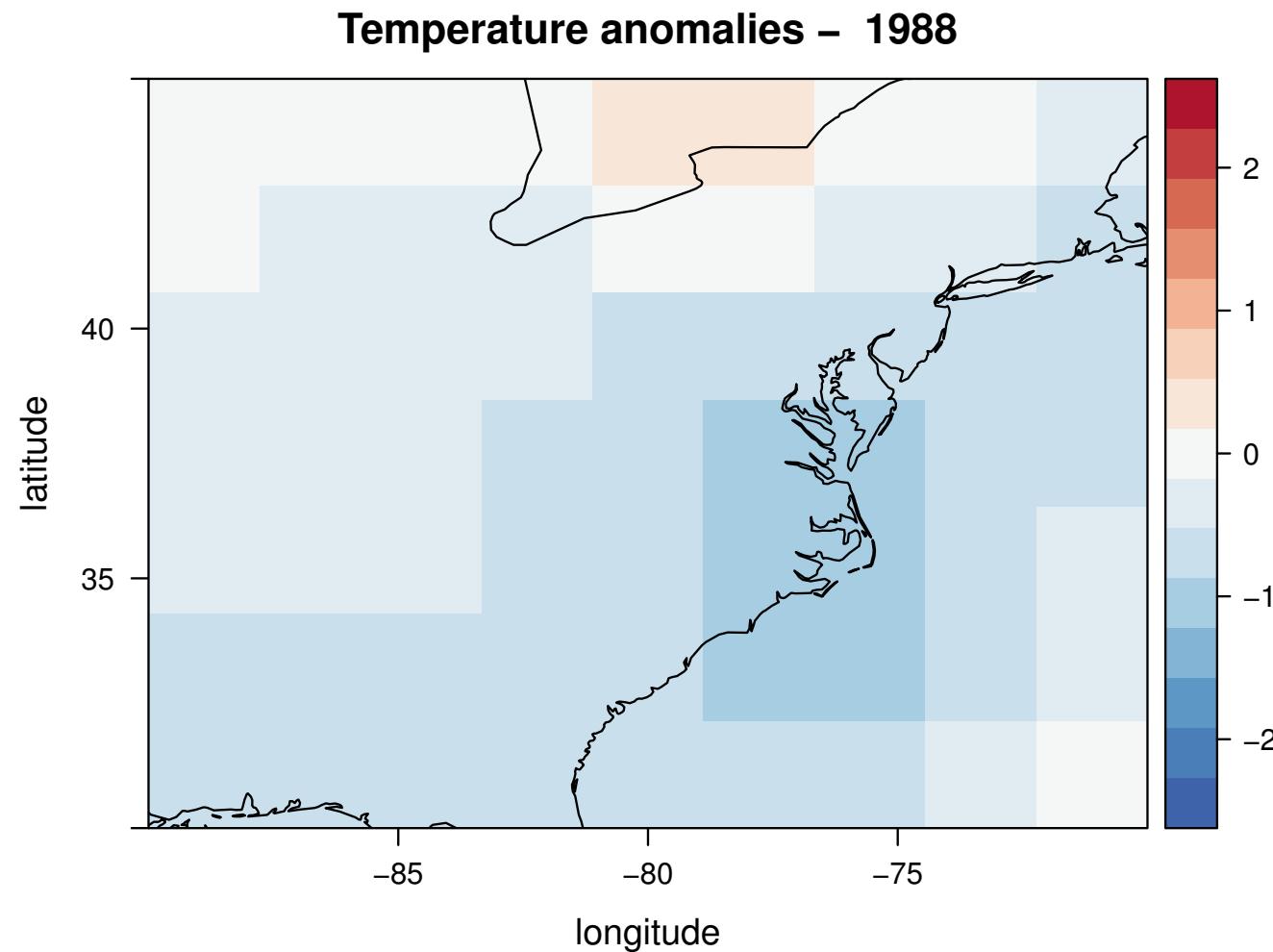
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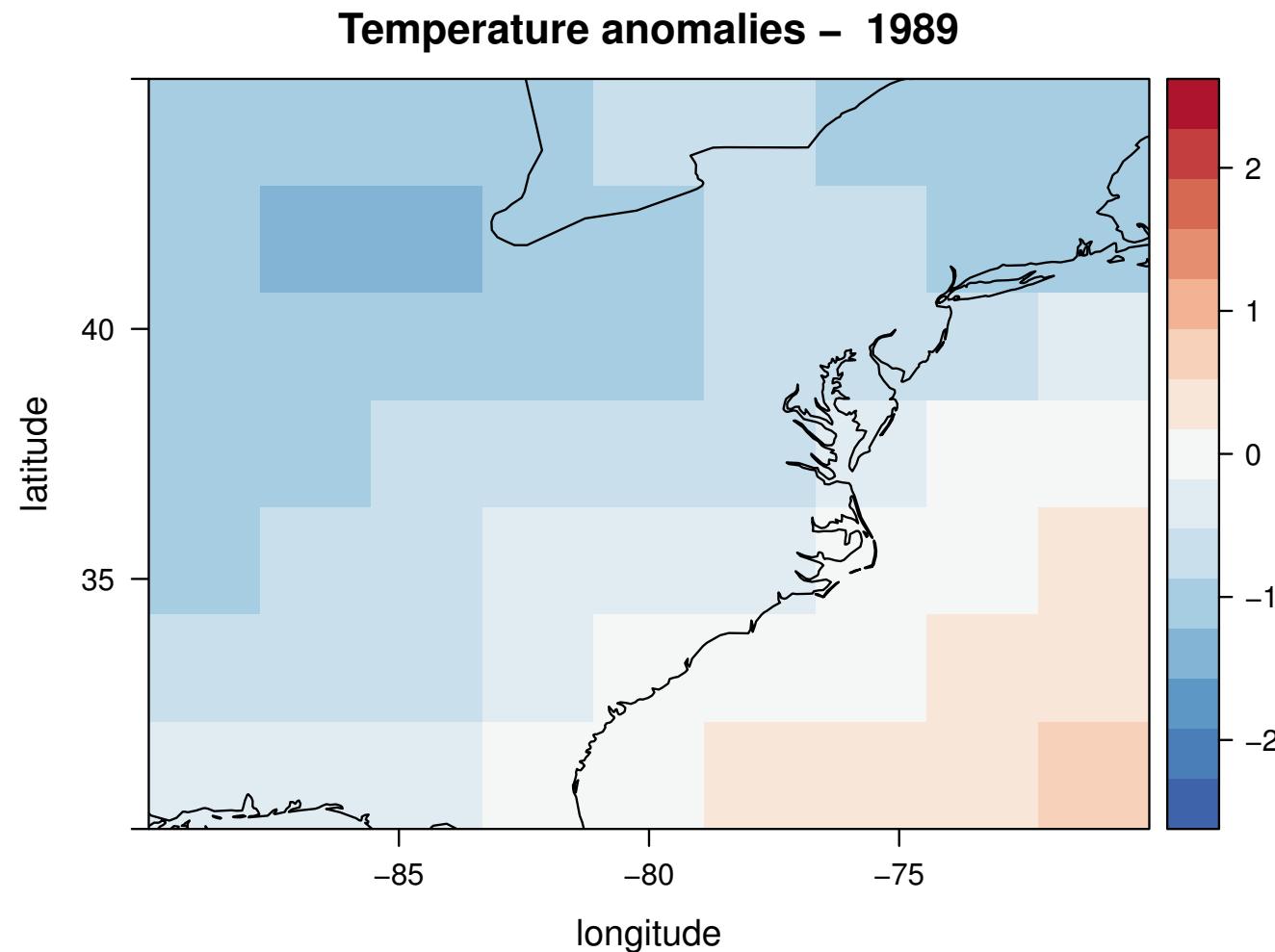
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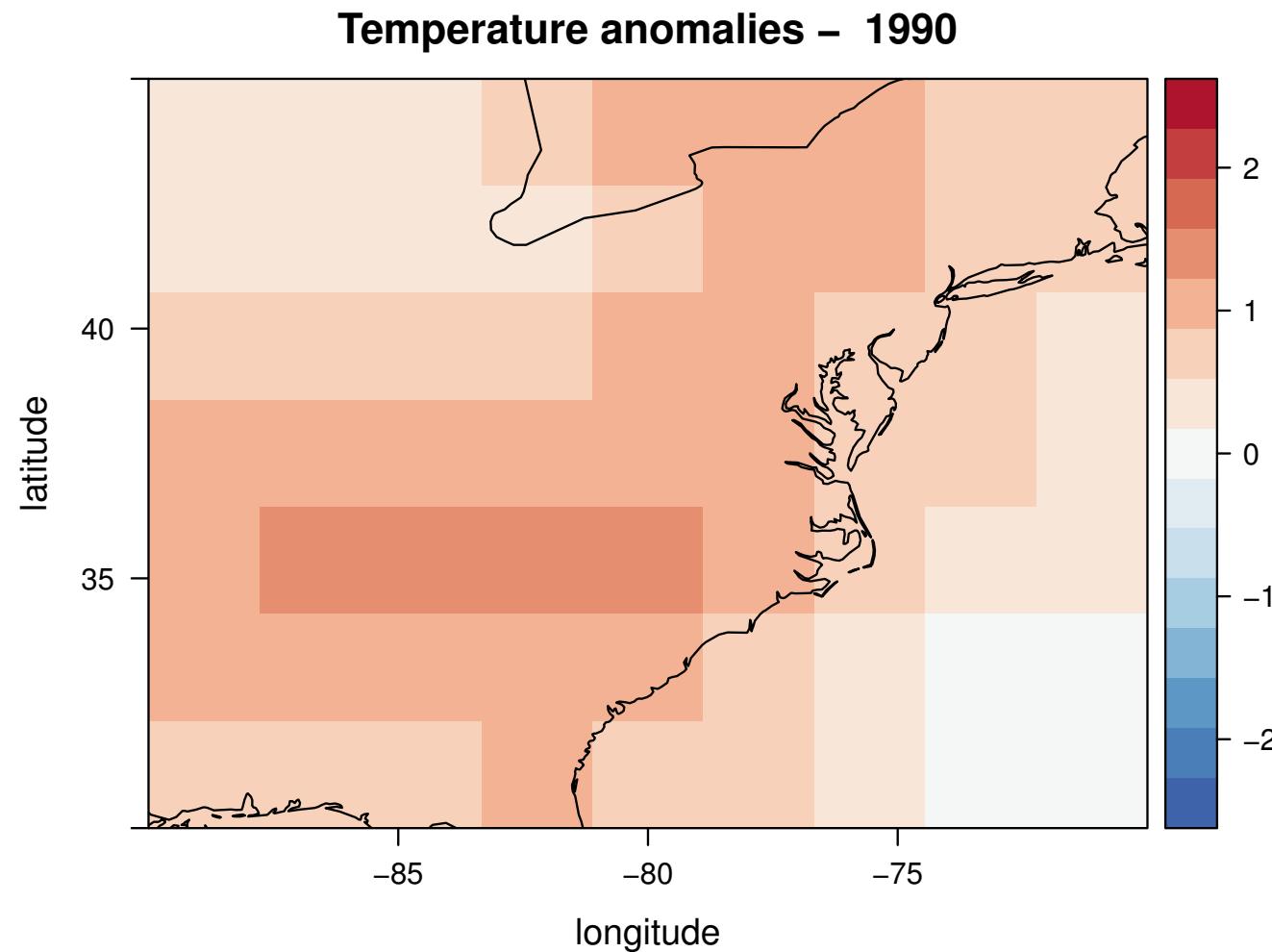
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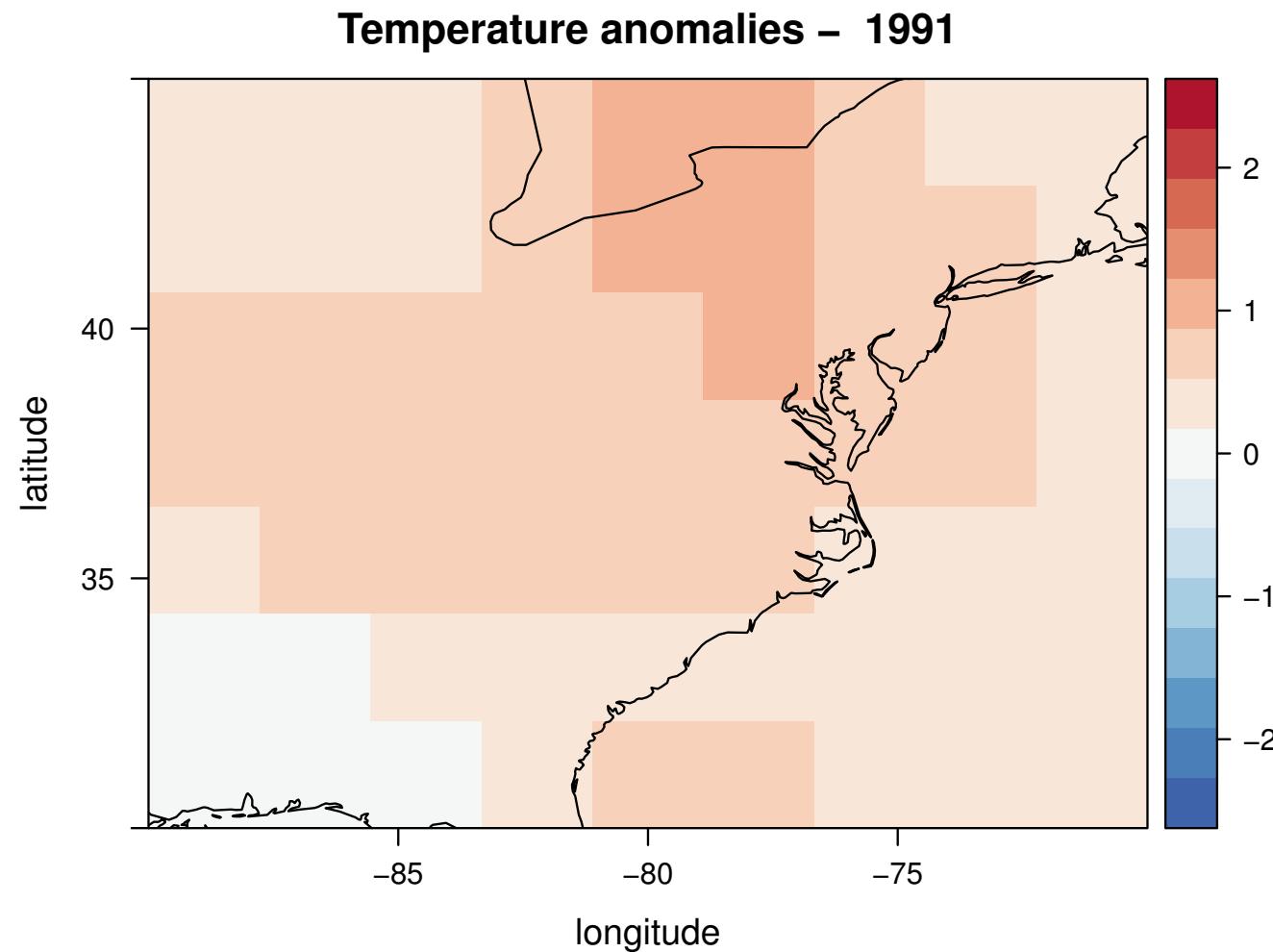
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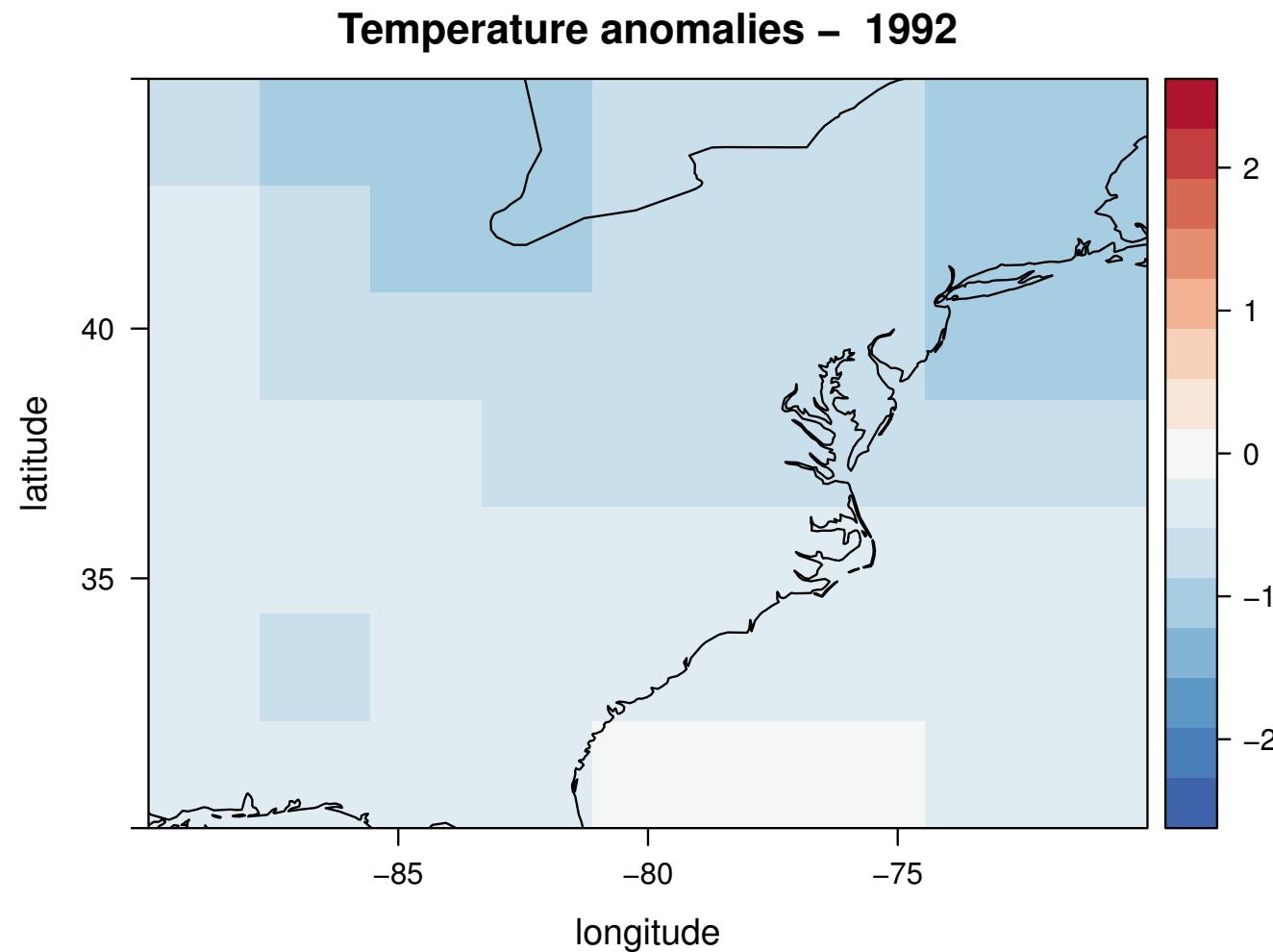
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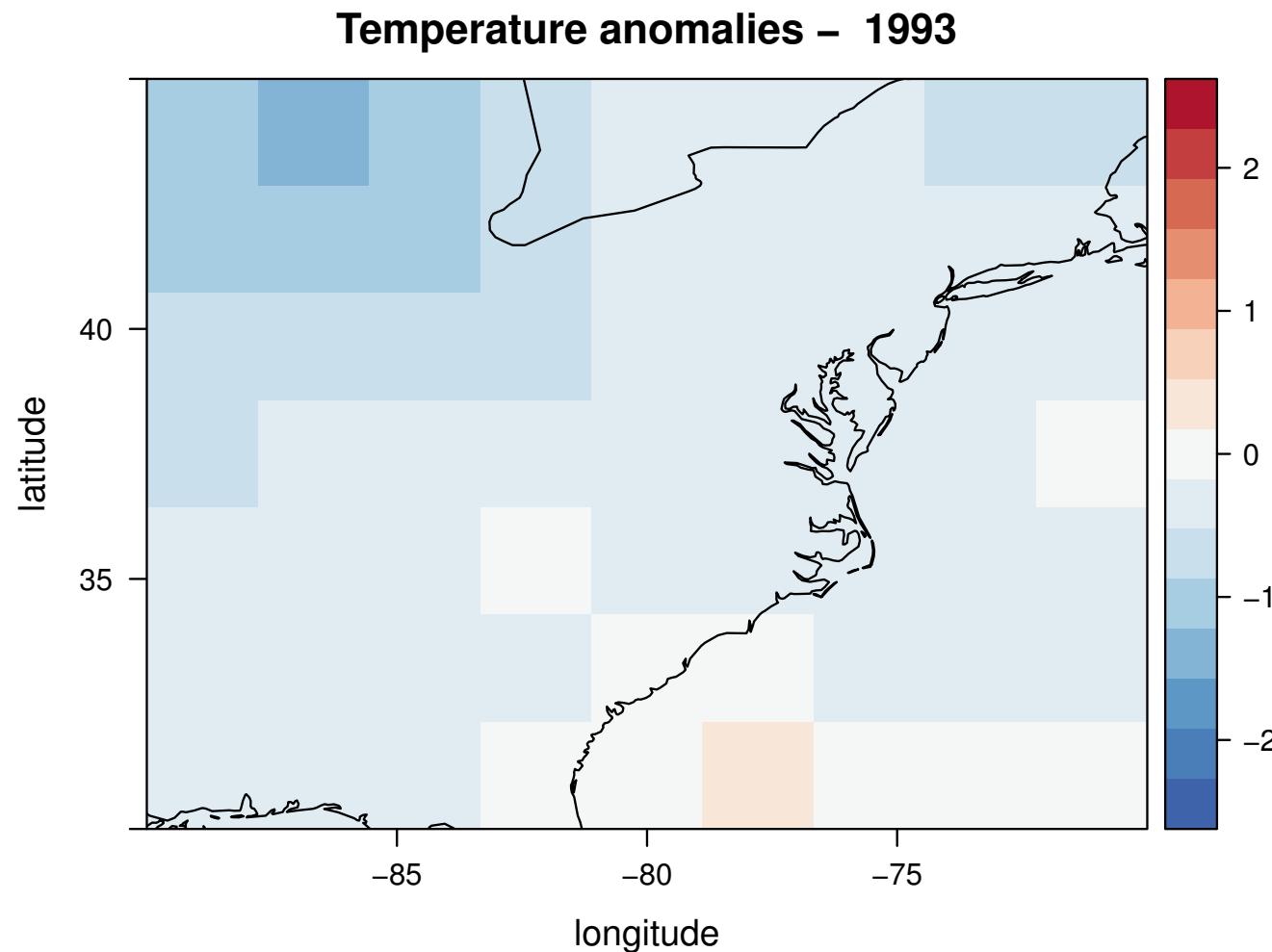
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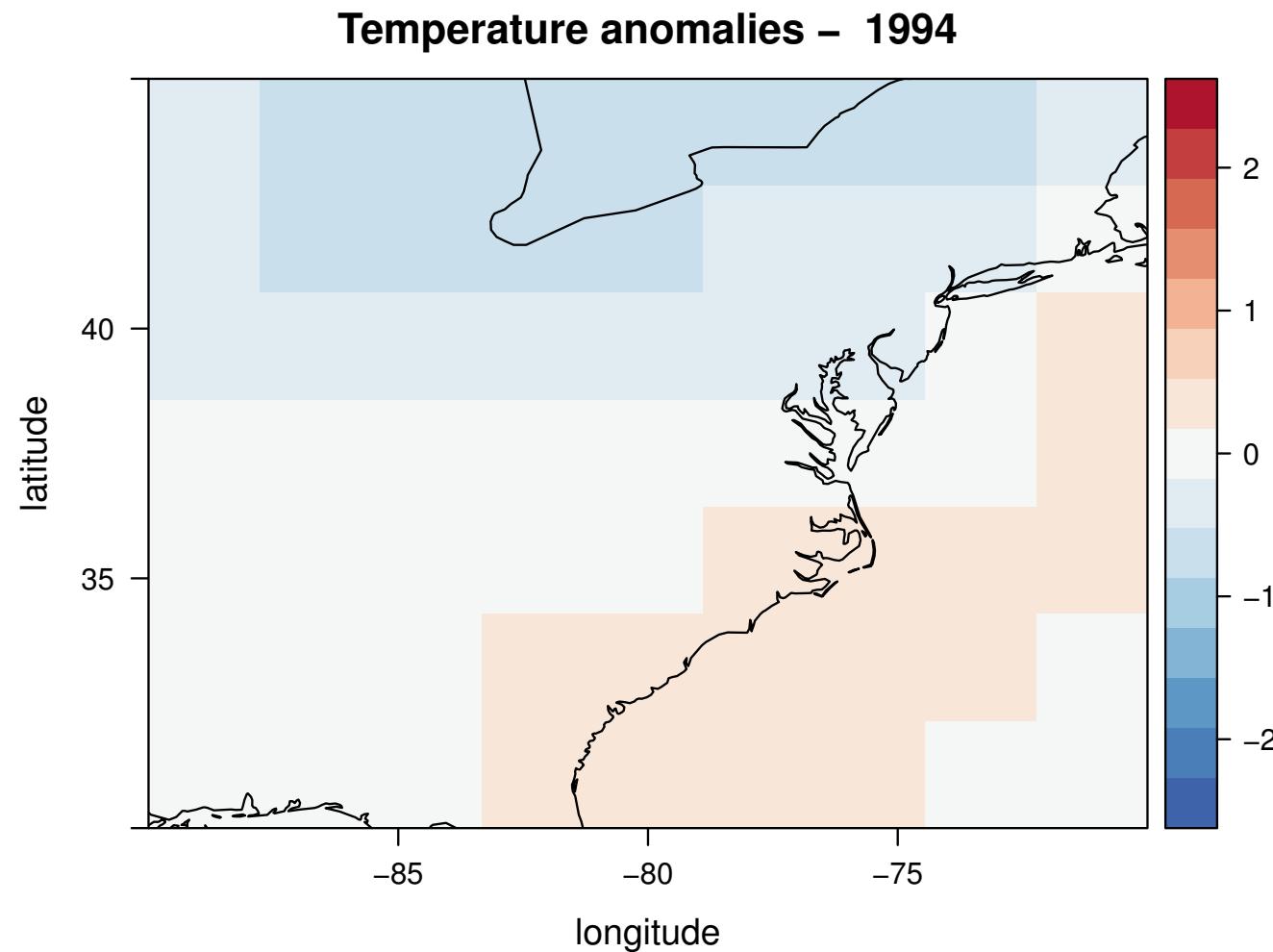
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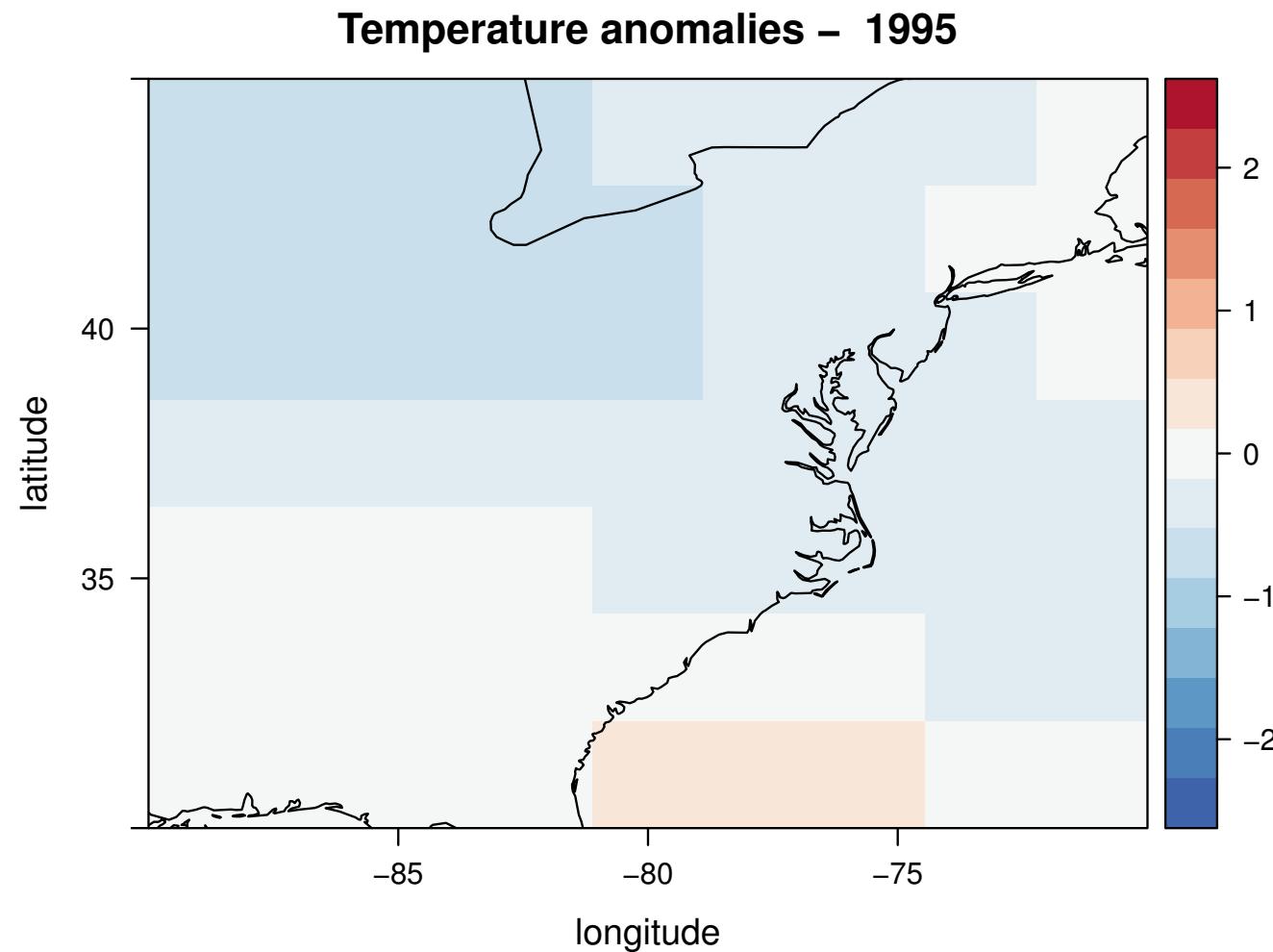
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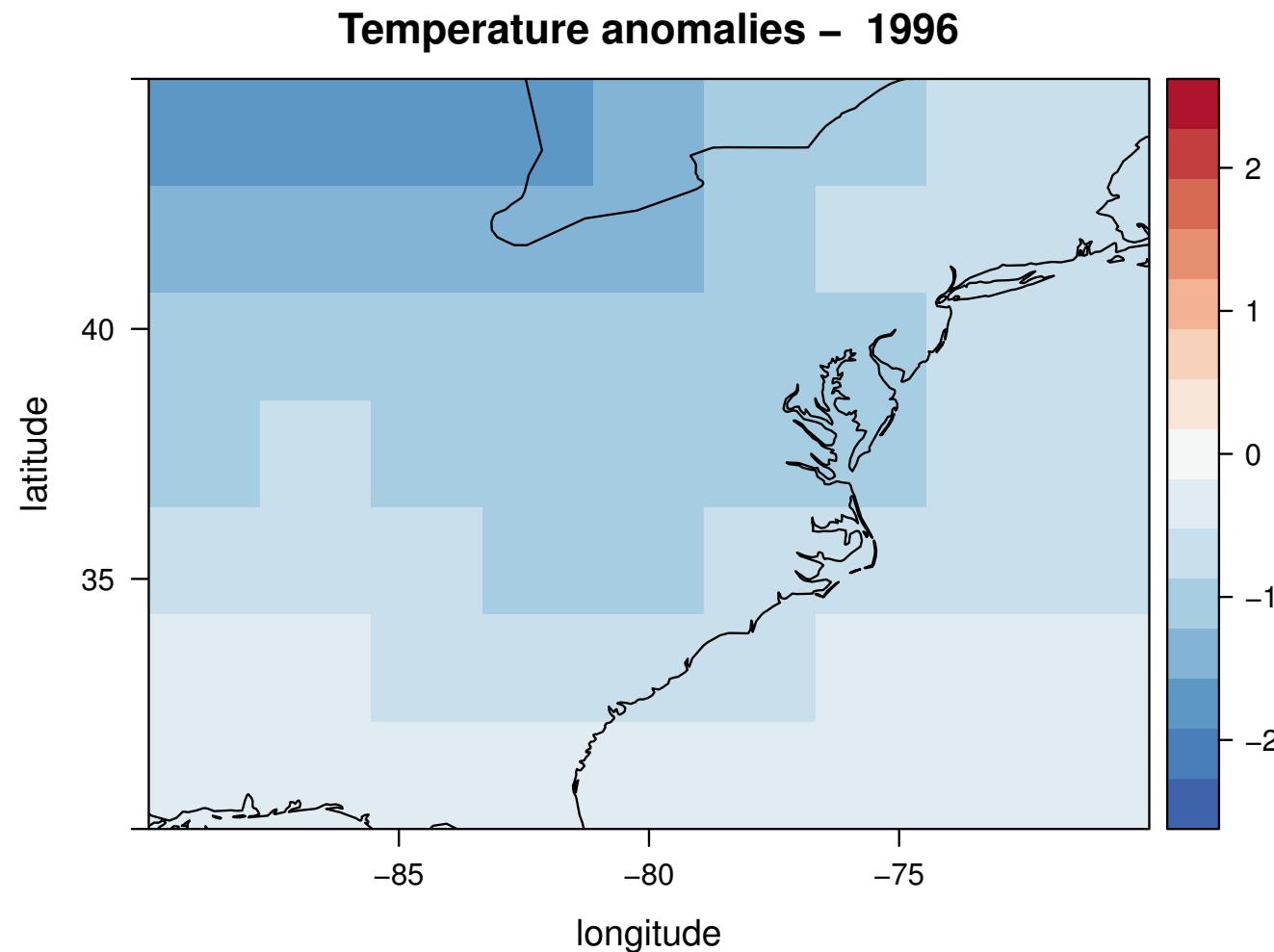
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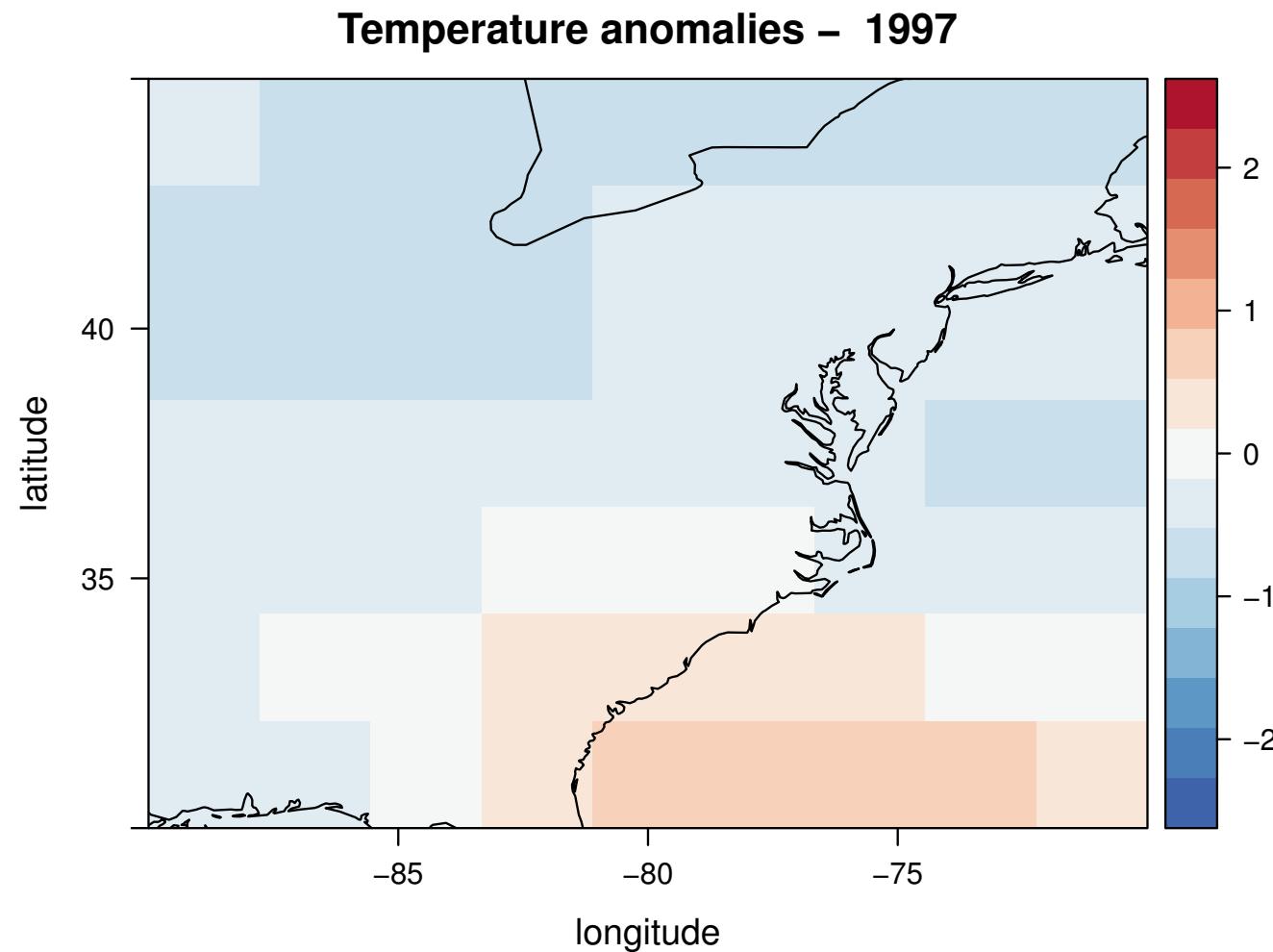
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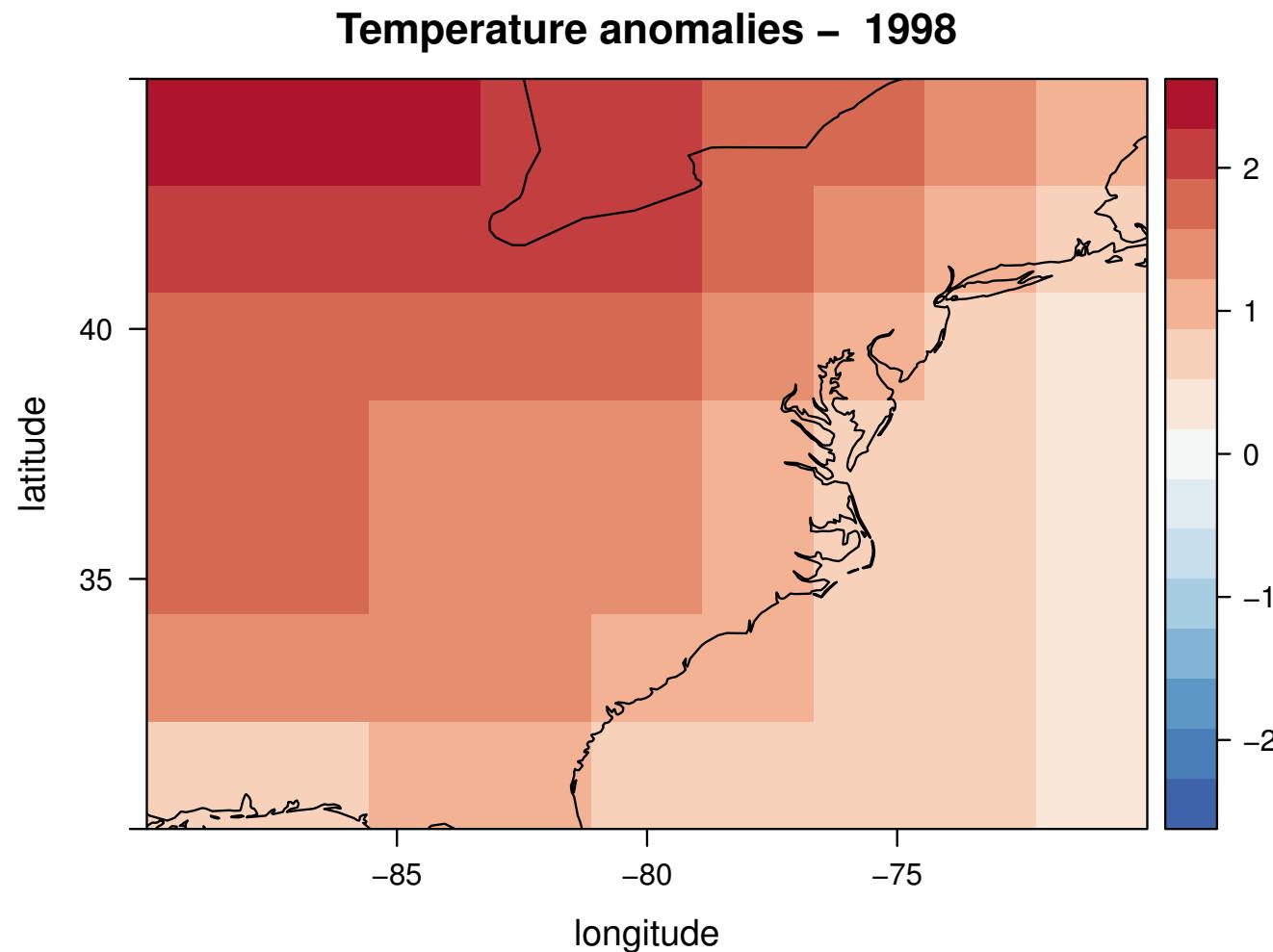
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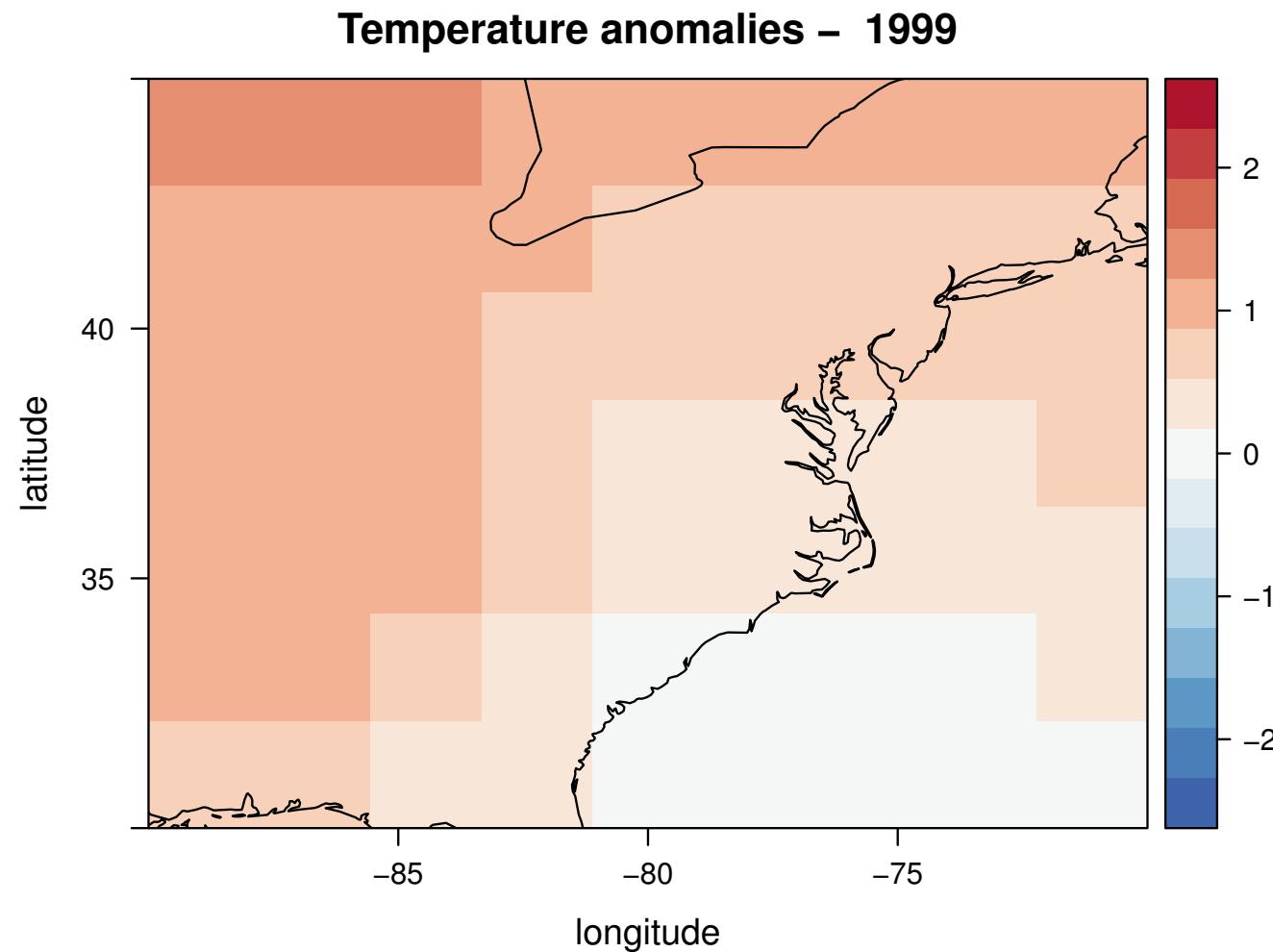
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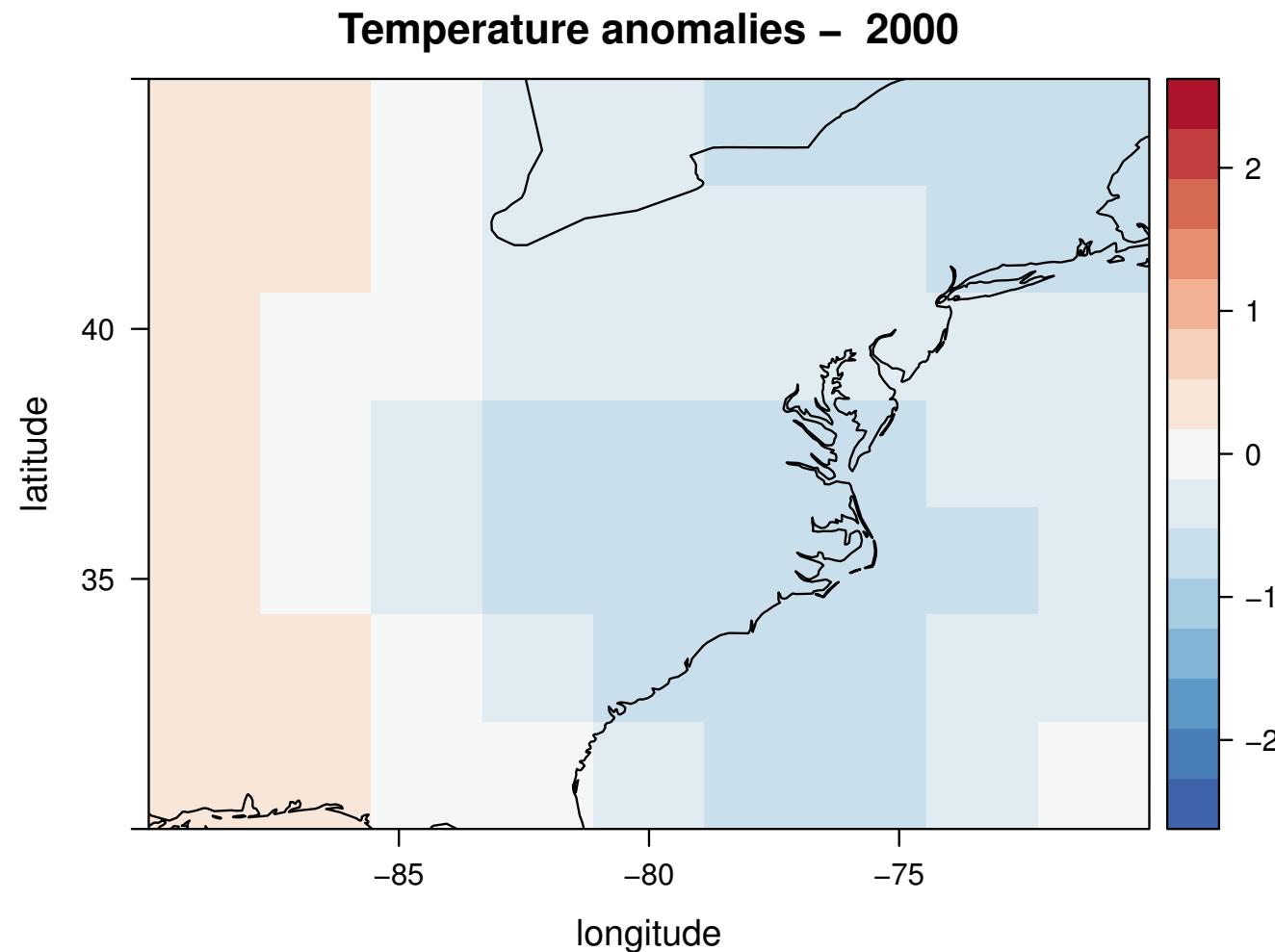
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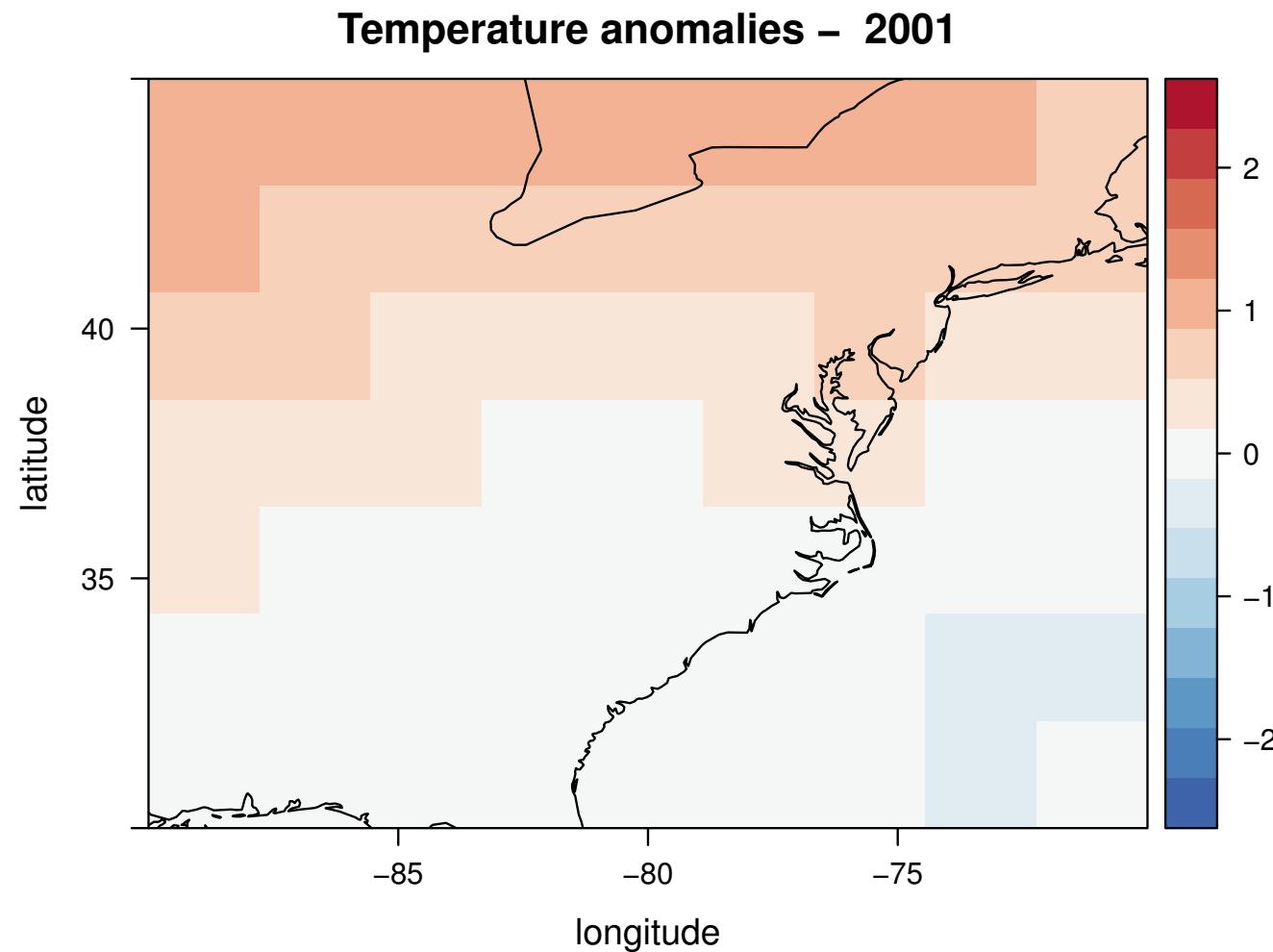
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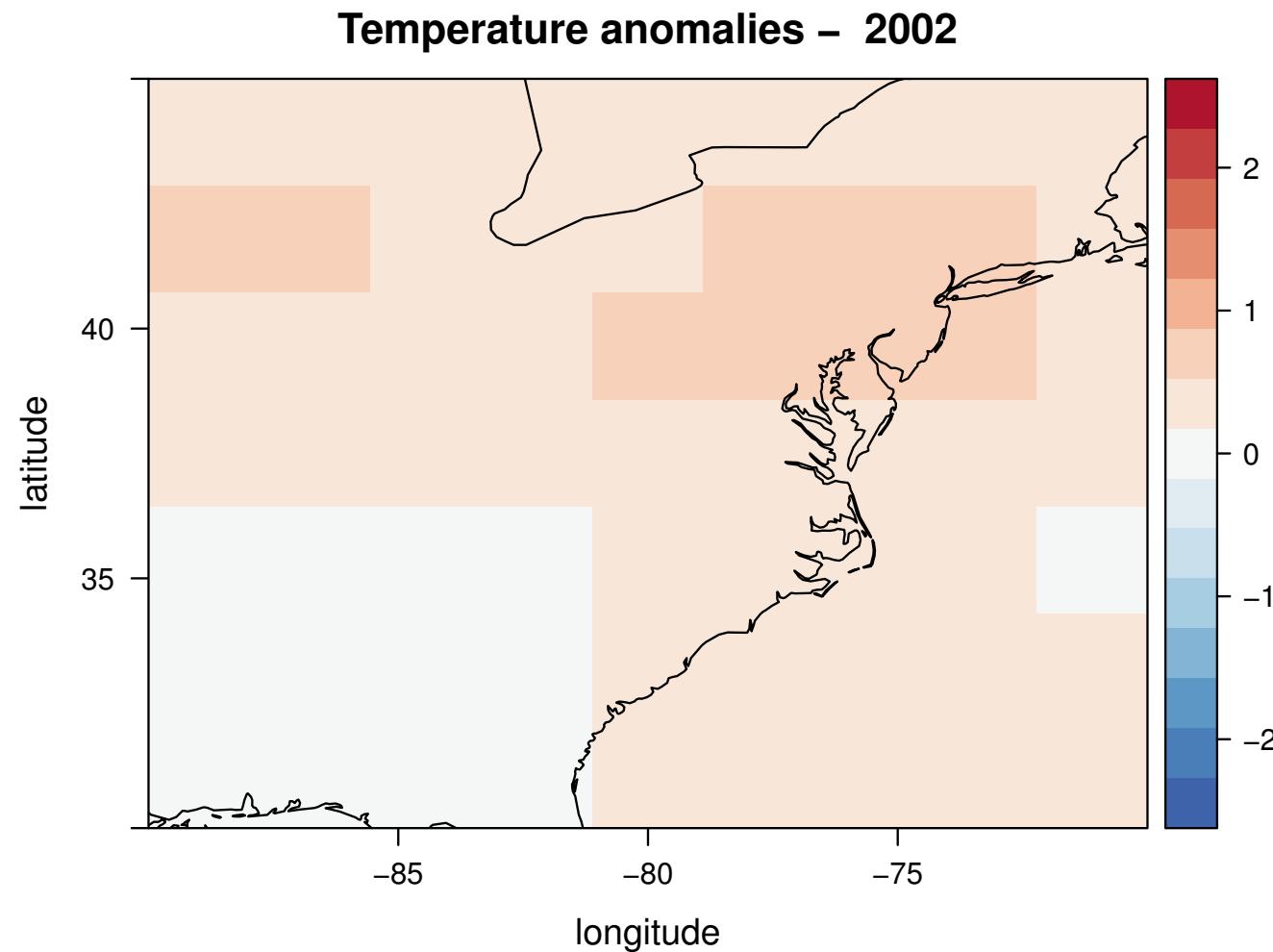
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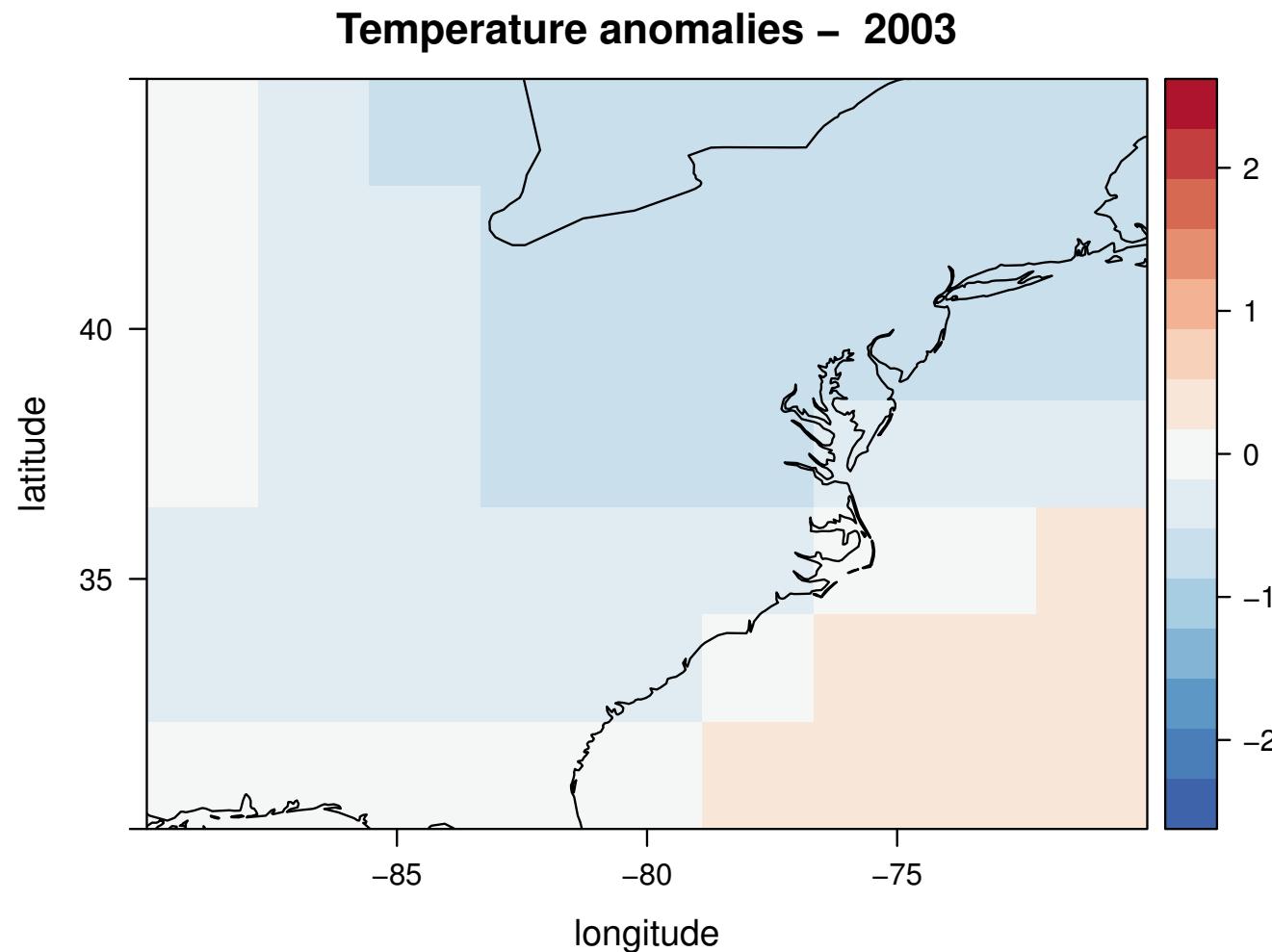
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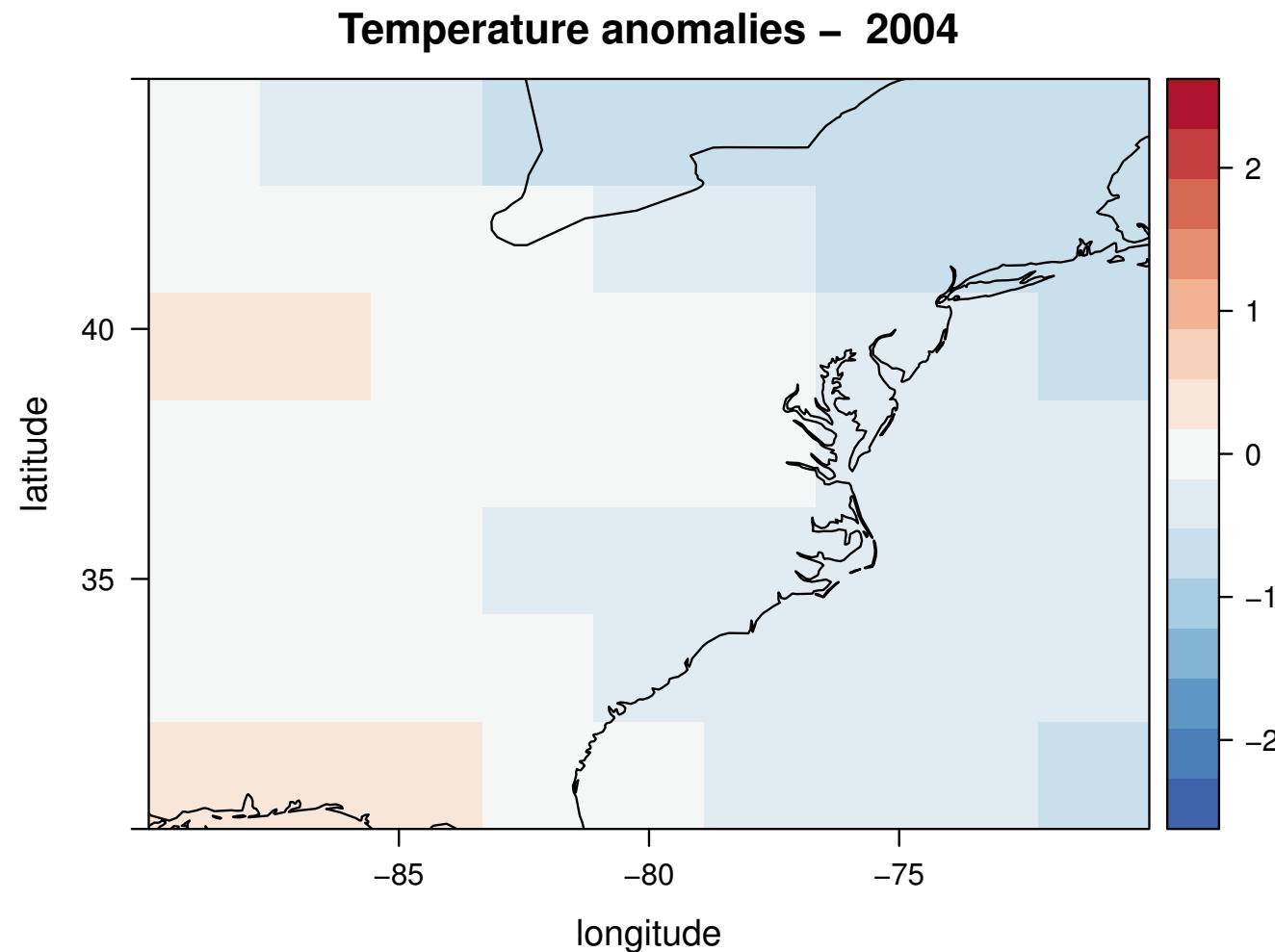
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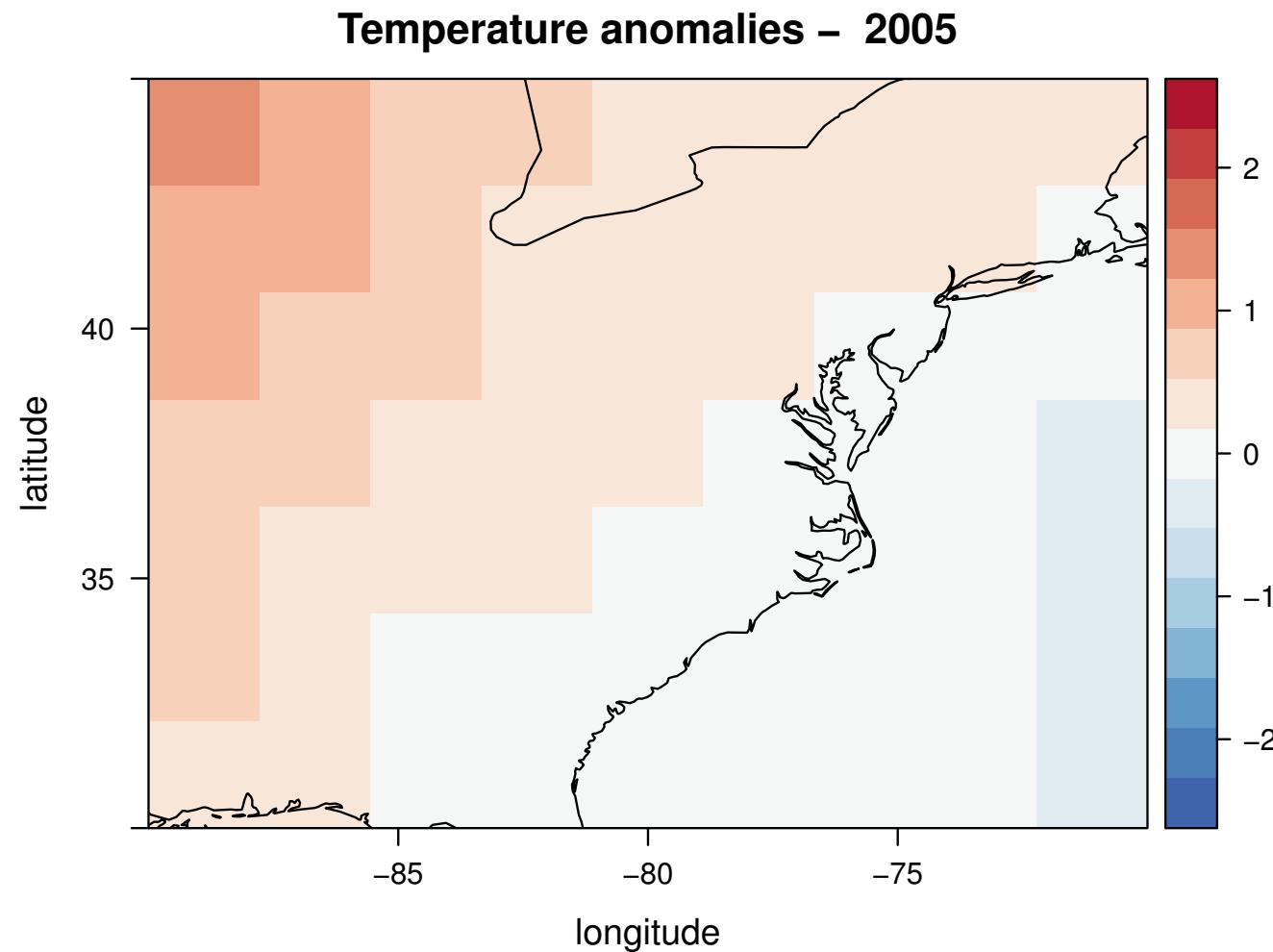
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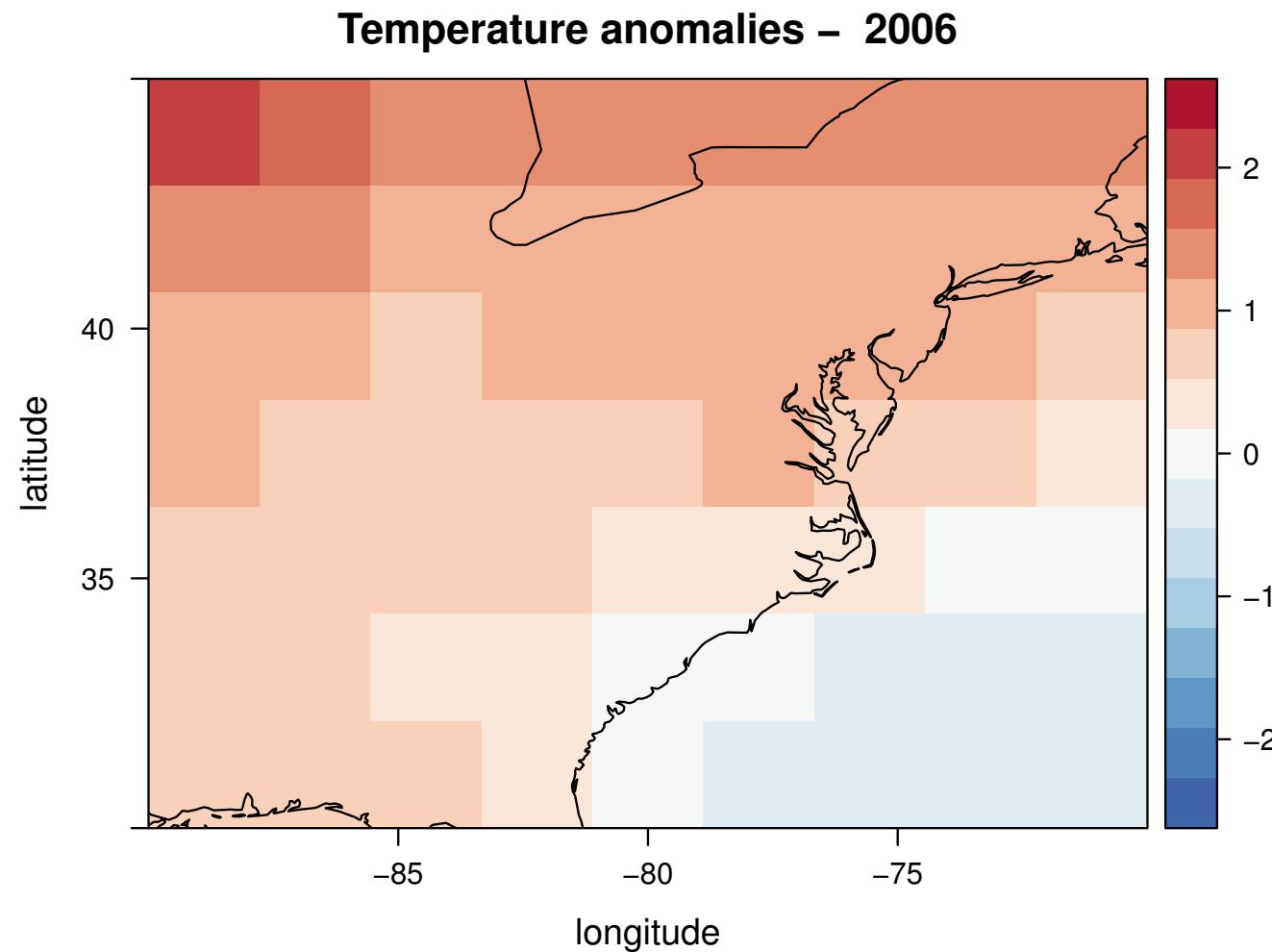
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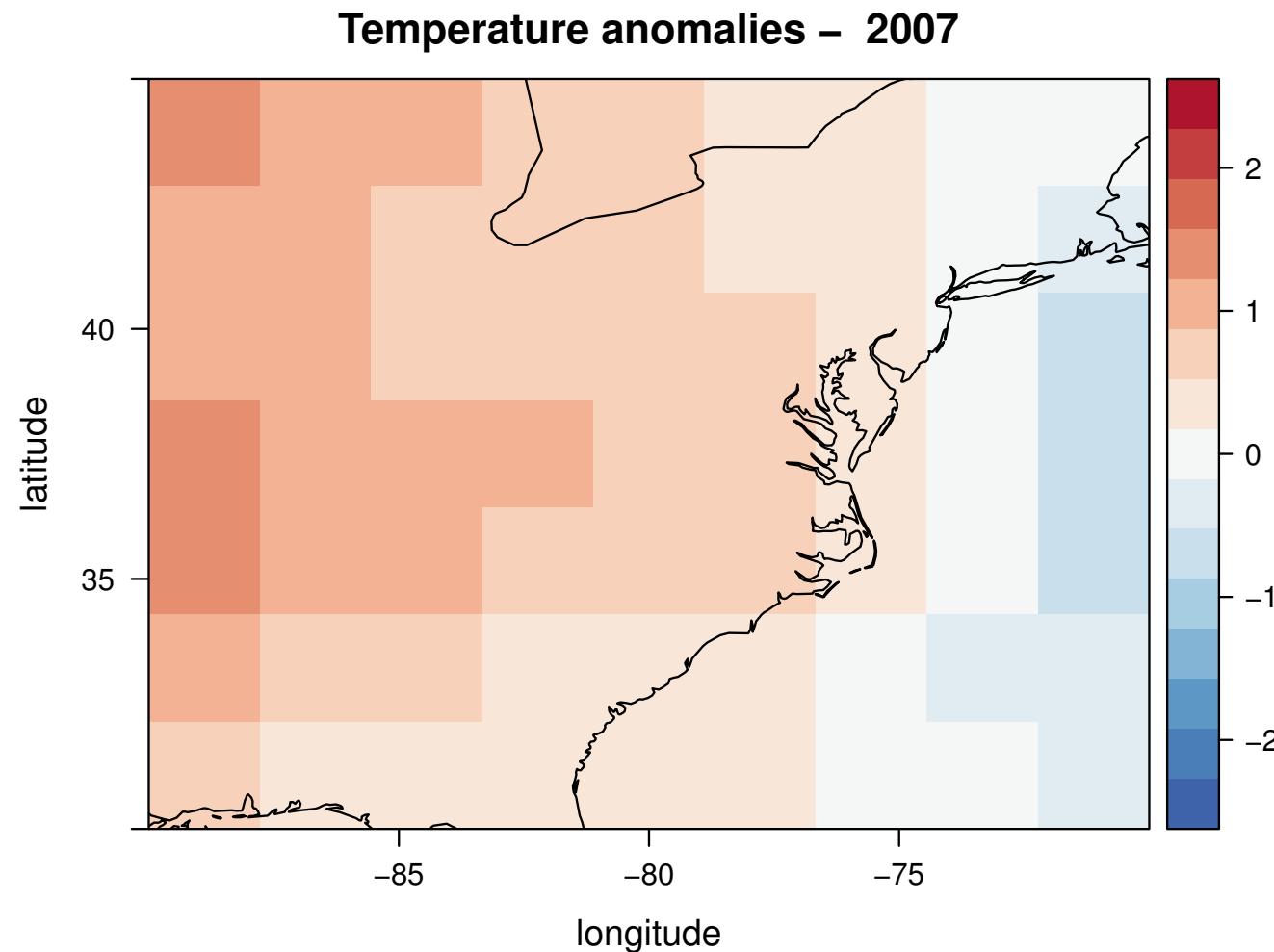
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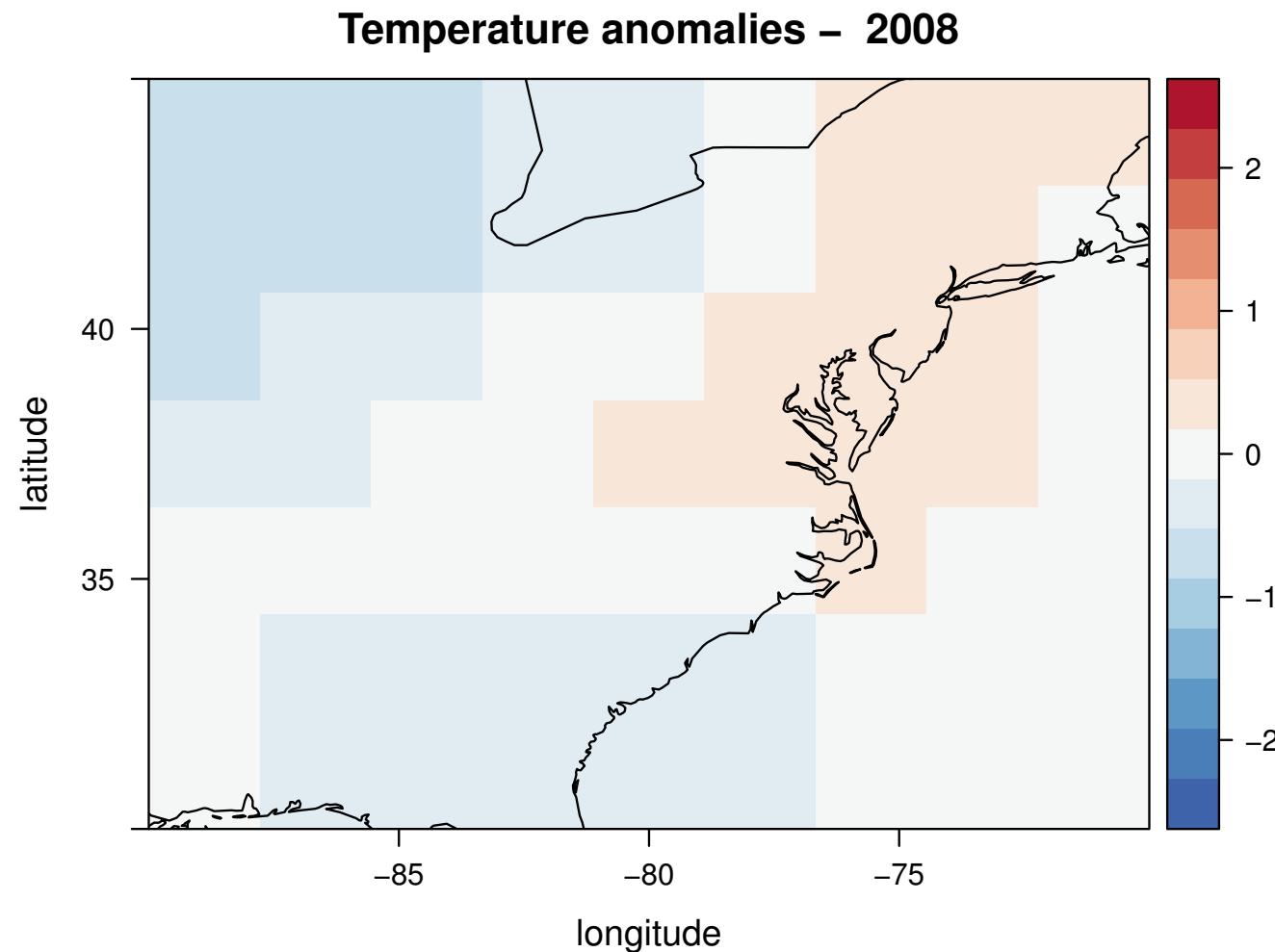
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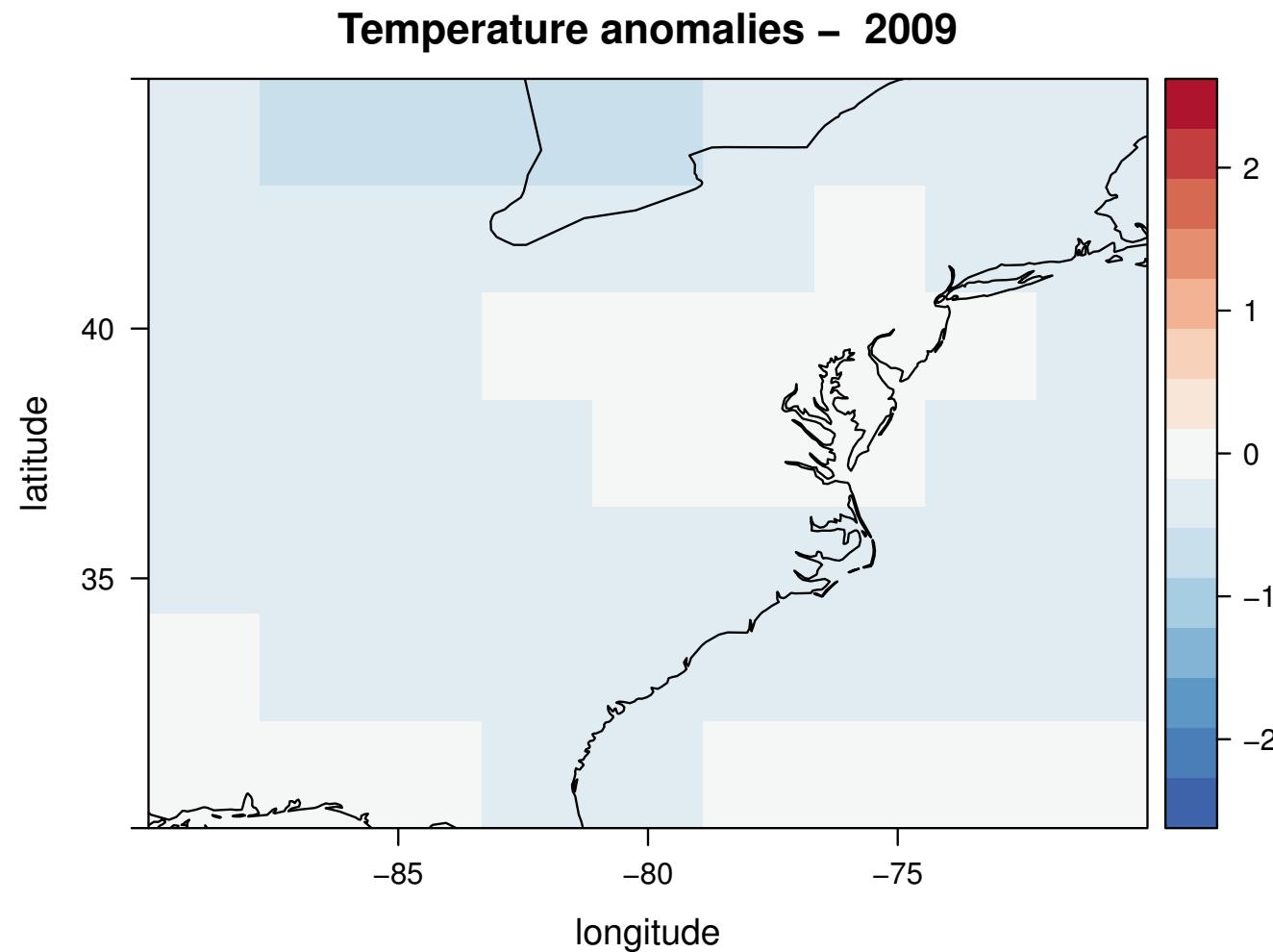
# Temperature Anomalies in Eastern USA



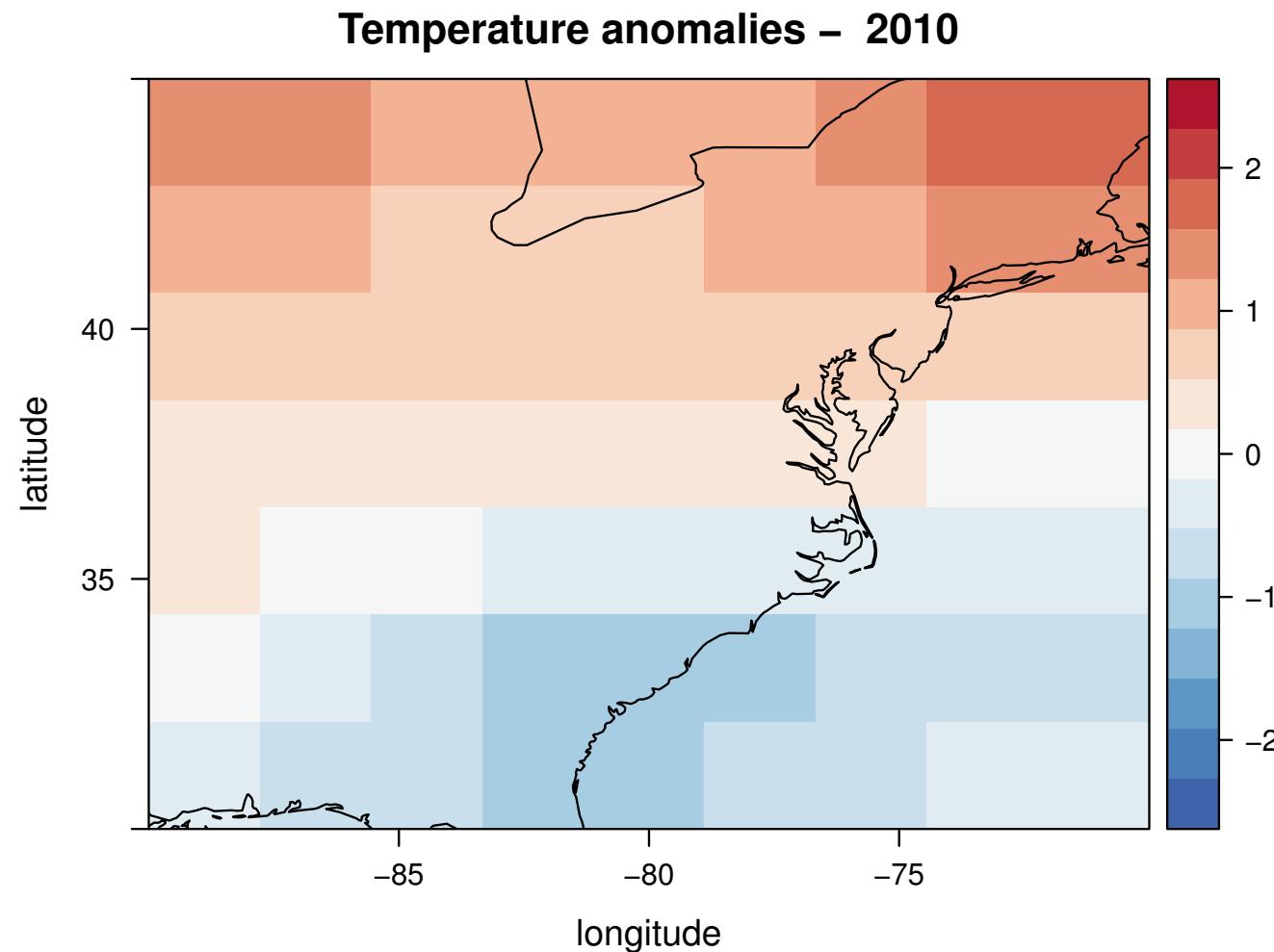
# Temperature Anomalies in Eastern USA



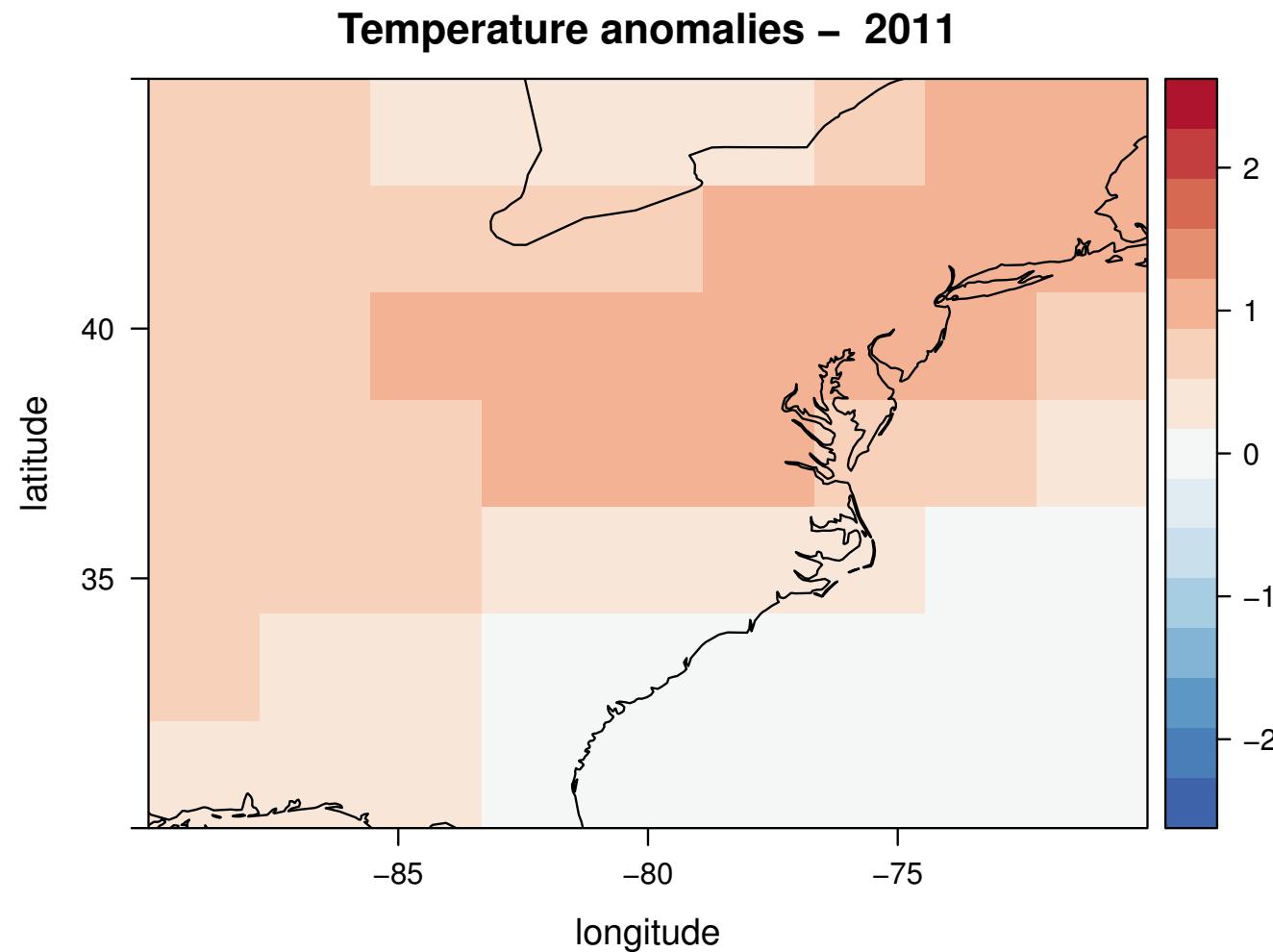
# Temperature Anomalies in Eastern USA



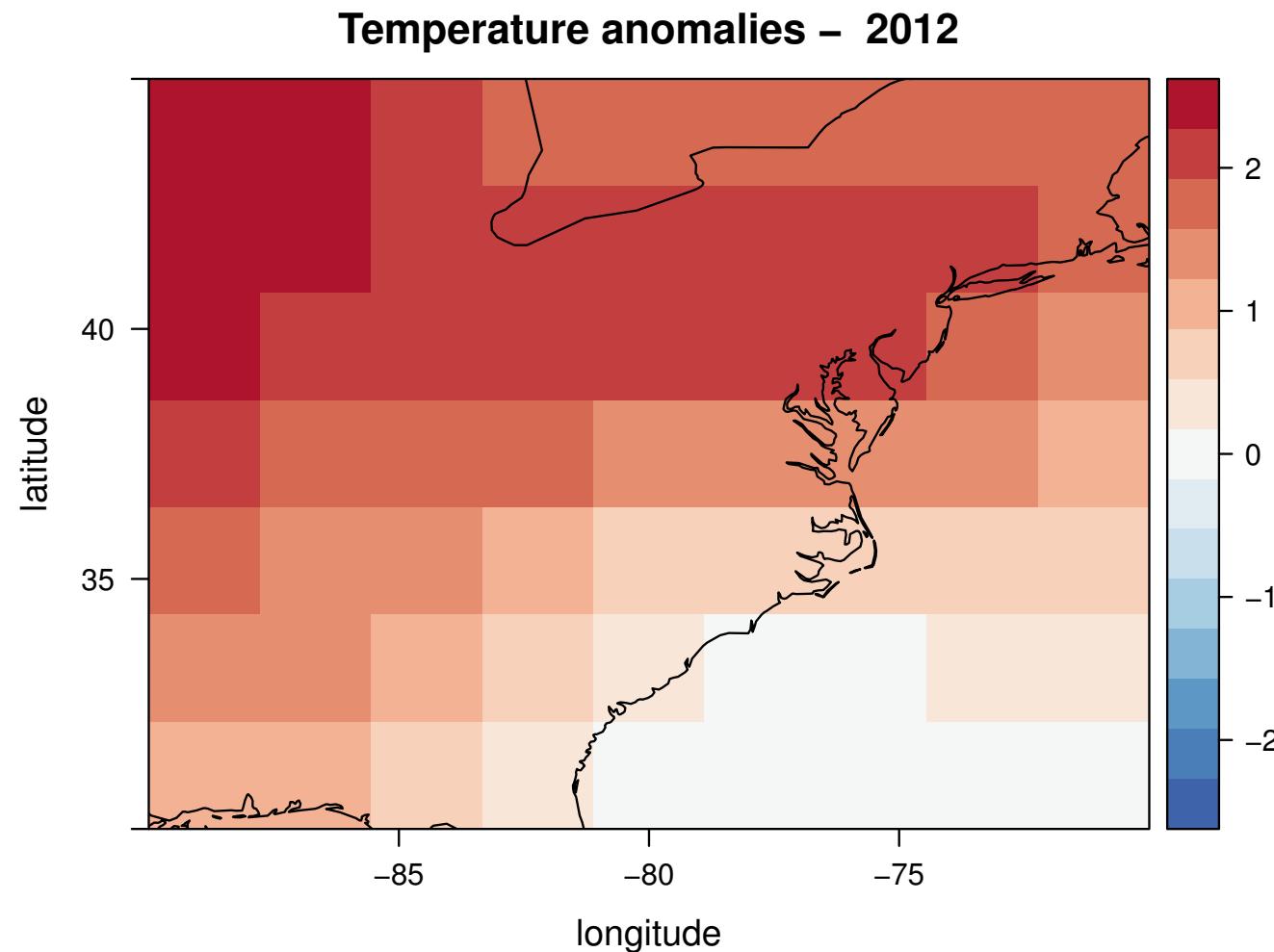
# Temperature Anomalies in Eastern USA



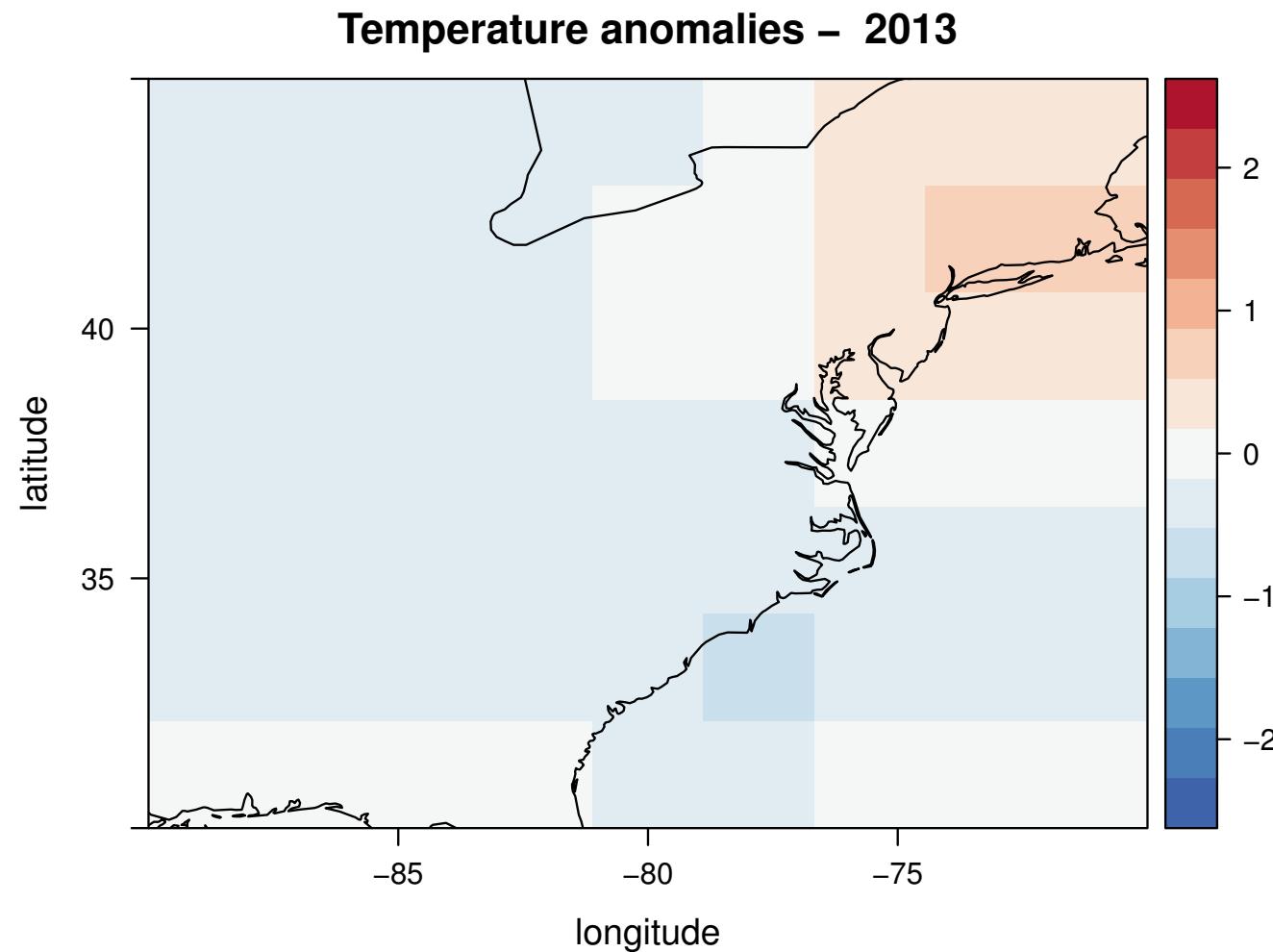
# Temperature Anomalies in Eastern USA



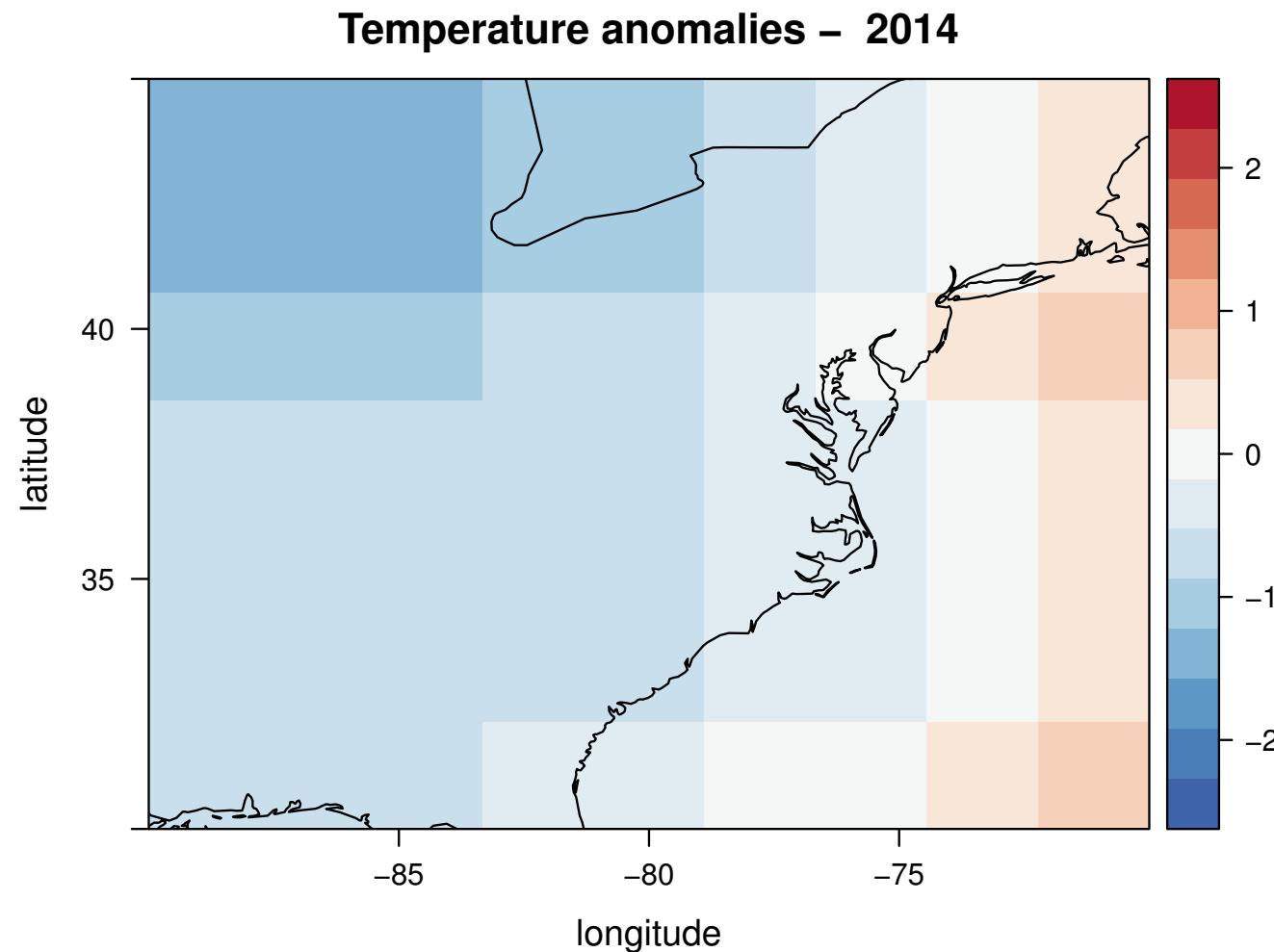
# Temperature Anomalies in Eastern USA



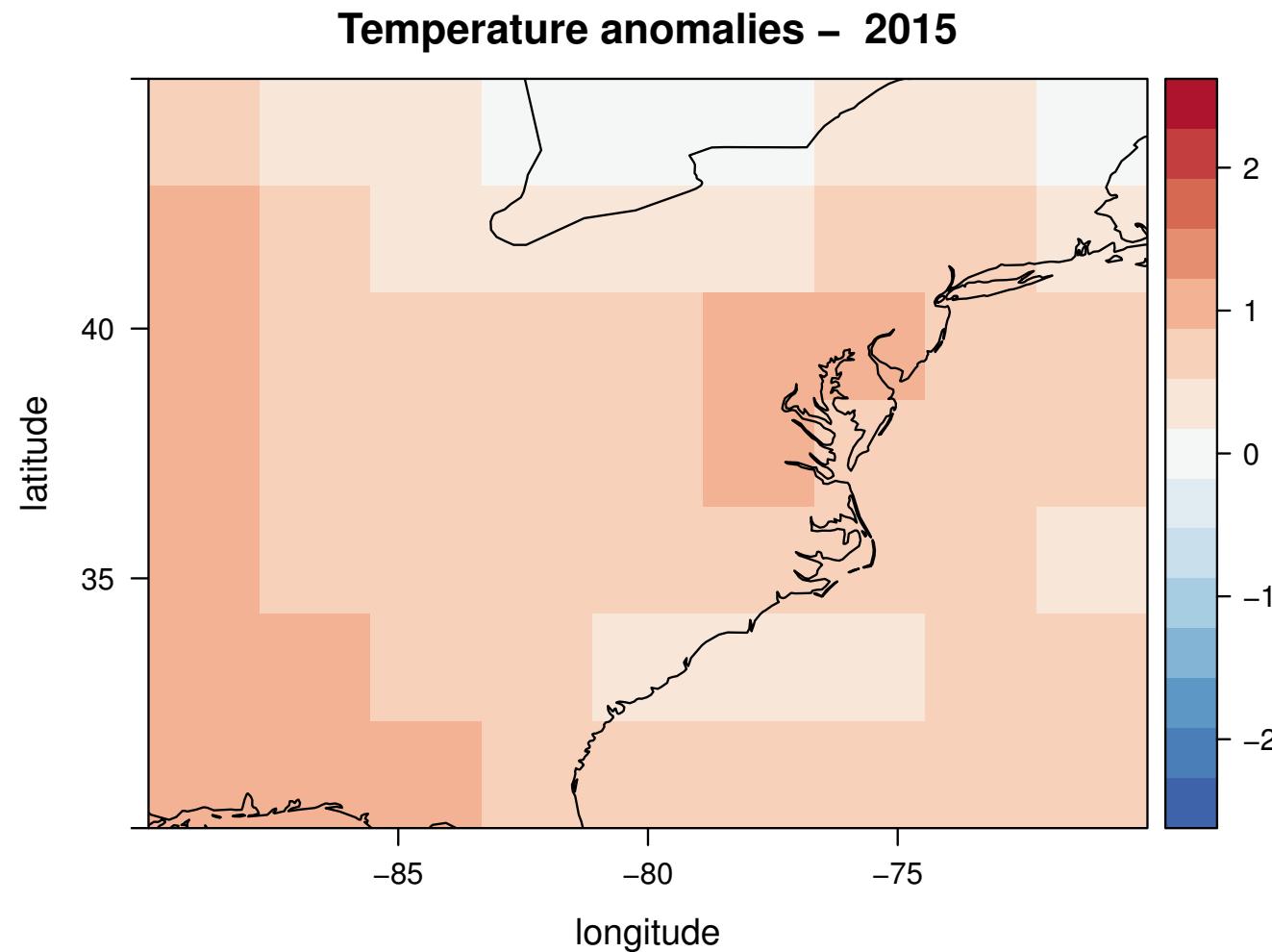
# Temperature Anomalies in Eastern USA



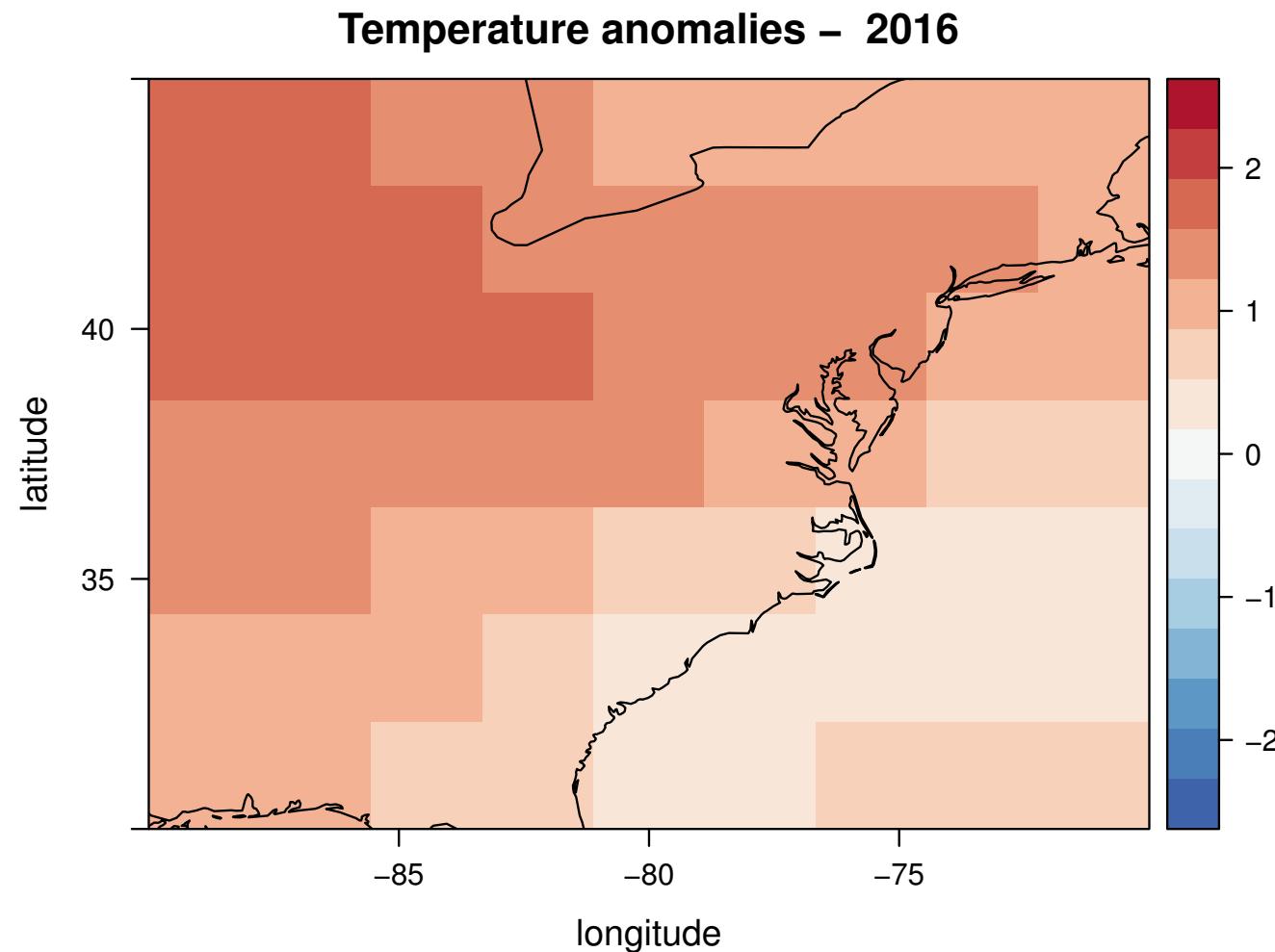
# Temperature Anomalies in Eastern USA



# Temperature Anomalies in Eastern USA



# Temperature Anomalies in Eastern USA



# Dynamic spatiotemporal factor model for temperature anomalies

- ▶  $\mathbf{y}_t$  = vector of observed temperatures in year  $t$ ;
- ▶ Factor loadings vary spatially.
- ▶ Elements of each column of factor loadings matrix  $\mathbf{B}$  follow a spatial Gaussian process;
- ▶  $\mathbf{x}_t$  is a  $k$ -dimensional vector of common factors.
- ▶  $l$ th element  $x_{tl}$  follows an AR( $p_l$ ) process.

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# Dynamic spatiotemporal factor model for temperature anomalies

$$\begin{aligned}\mathbf{y}_t &= \mathbf{Bx}_t + \boldsymbol{\nu}_t, \quad \boldsymbol{\nu}_t \sim N(\mathbf{0}, \mathbf{V}), \\ \mathbf{x}_t &= \mathbf{F}'\boldsymbol{\theta}_t, \\ \boldsymbol{\theta}_t &= \mathbf{G}\boldsymbol{\theta}_{t-1} + \boldsymbol{\omega}_t, \quad \boldsymbol{\omega}_t \sim N(\mathbf{0}, \mathbf{W}).\end{aligned}$$

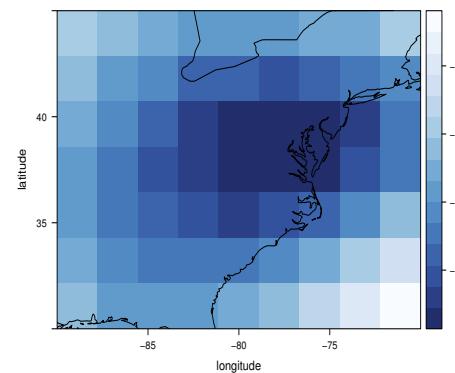
- ▶  $b_I \sim N(\mathbf{0}, \Sigma_I),$
- ▶  $\{\Sigma_I\}_{ij} = \tau_I^2 \rho_I(||s_i - s_j||; \lambda_I).$

# Dynamic spatiotemporal factor model for temperature anomalies

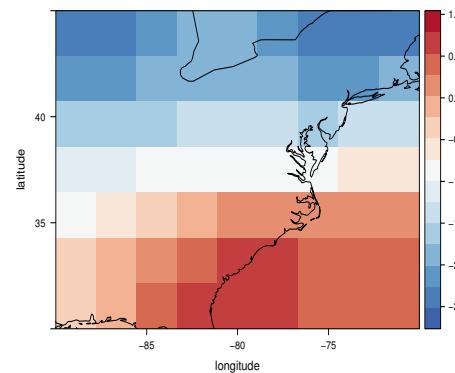
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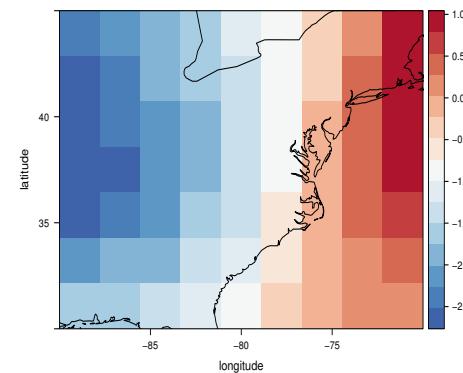
# Dynamic spatiotemporal 3-factor model: Factor loadings



1st factor



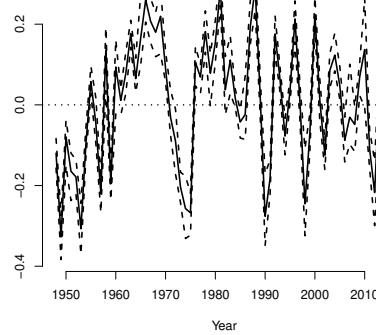
2nd factor



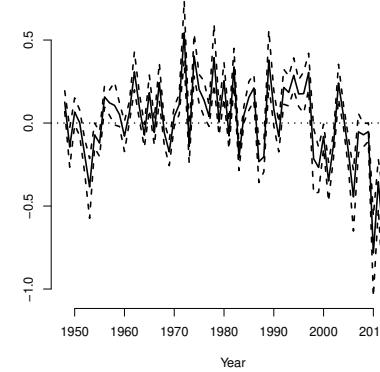
3rd factor

# Common factors

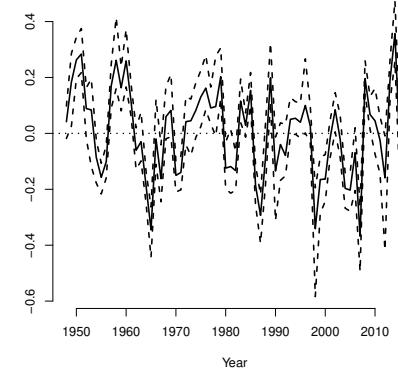
1st factor



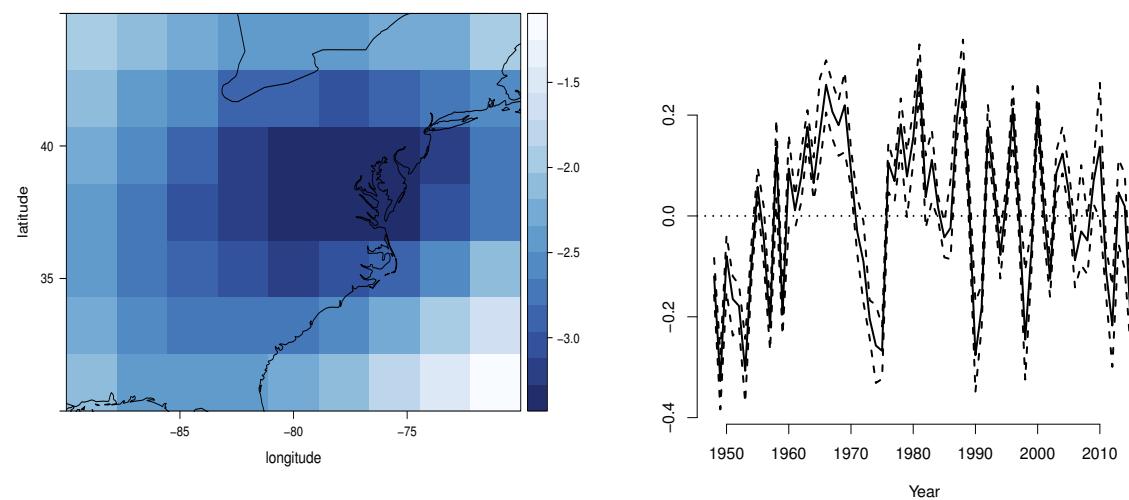
2nd factor



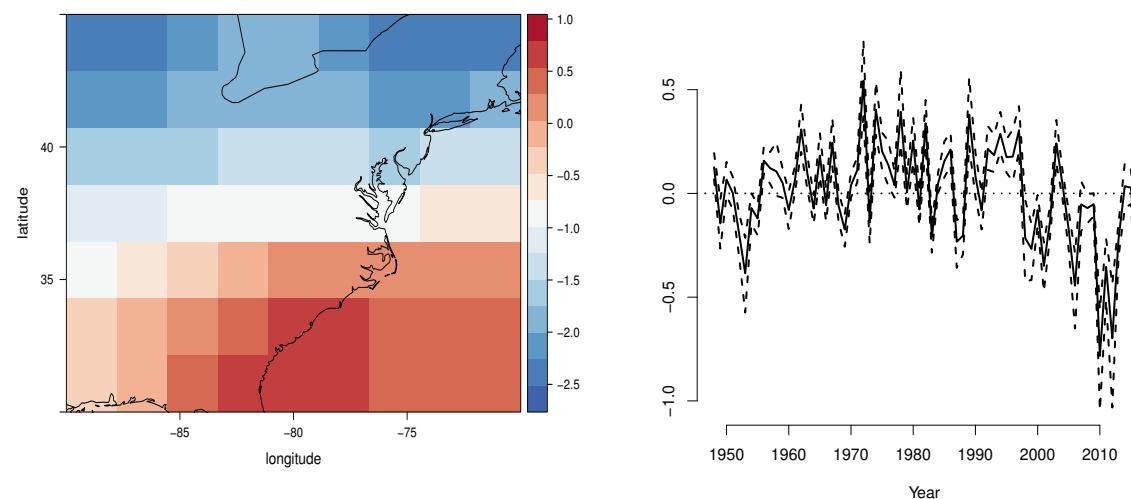
3rd factor



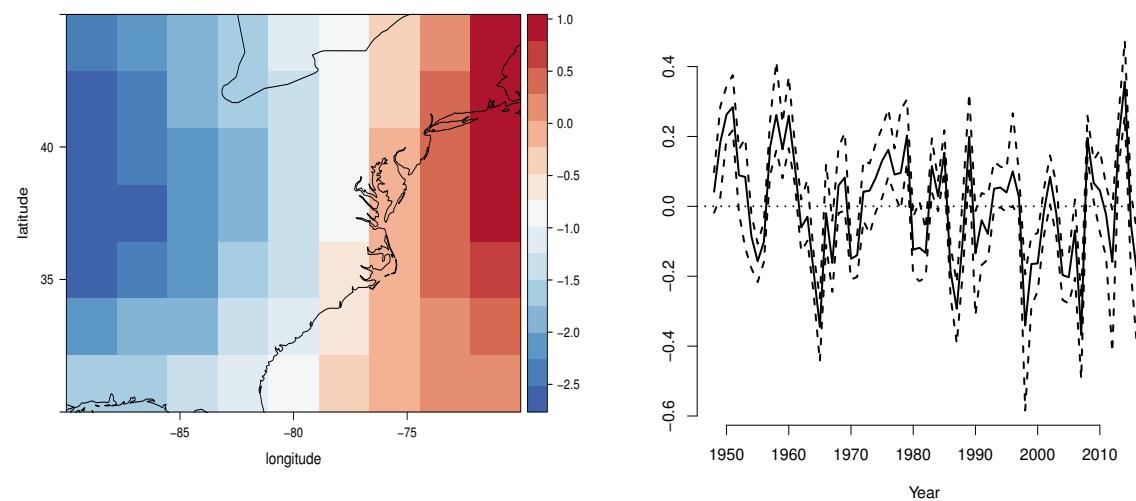
# 1st common factor and factor loadings



## 2nd common factor and factor loadings



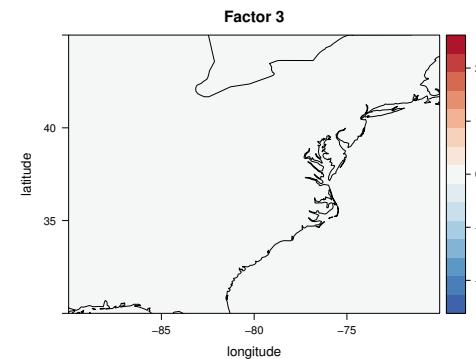
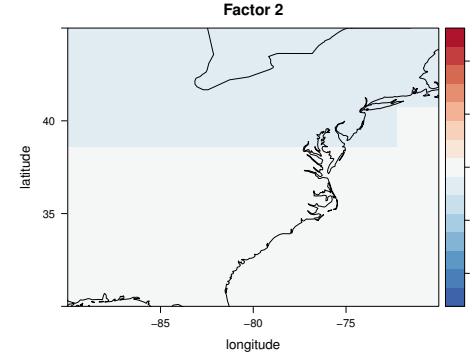
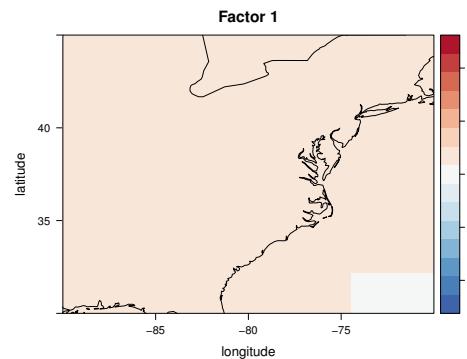
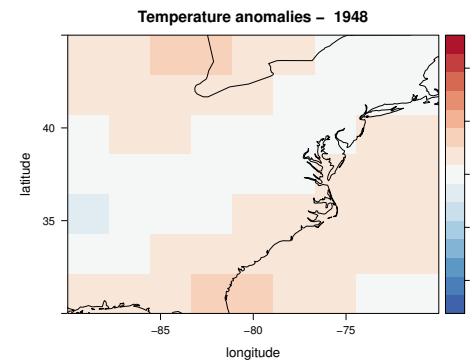
# 3rd common factor and factor loadings



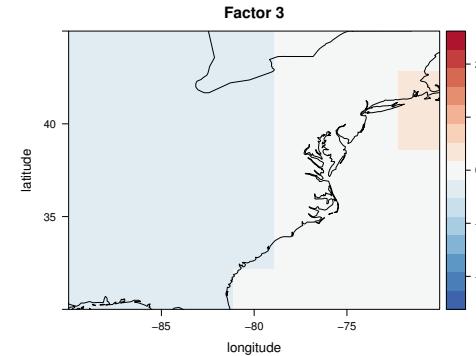
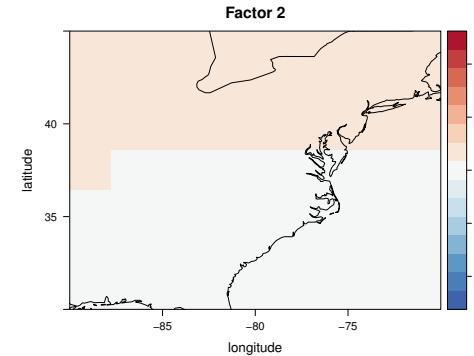
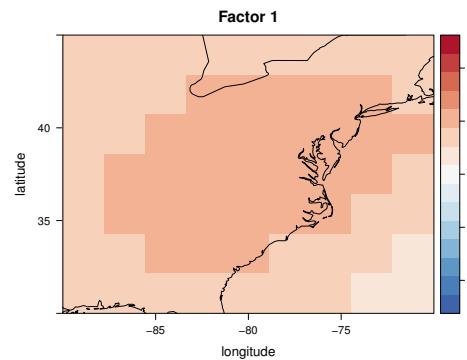
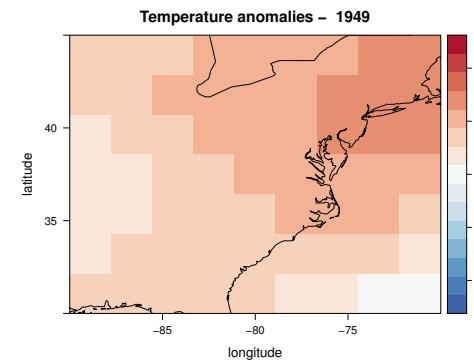
# Factor model for temperature anomalies

$$\mathbf{y}_t = \mathbf{x}_{t1} b_{.1} + \mathbf{x}_{t2} b_{.2} + \mathbf{x}_{t3} b_{.3} + \nu_t$$

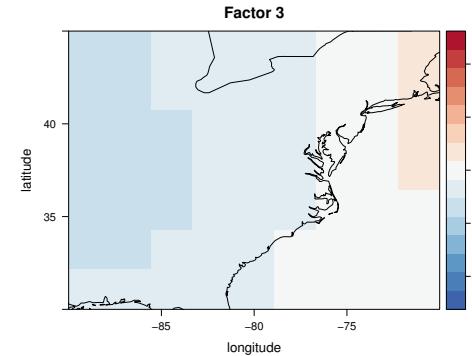
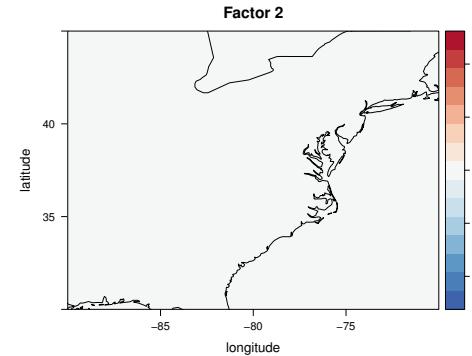
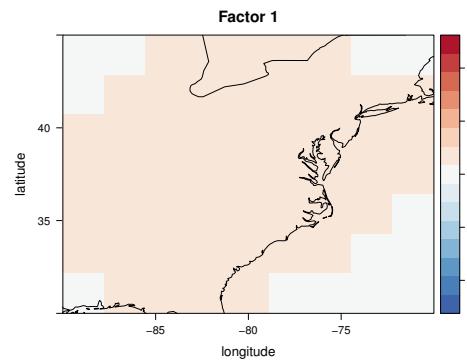
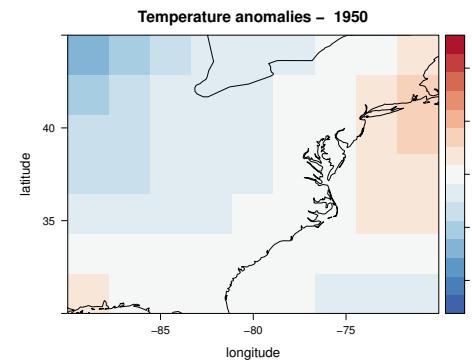
# Factor contributions in 1948



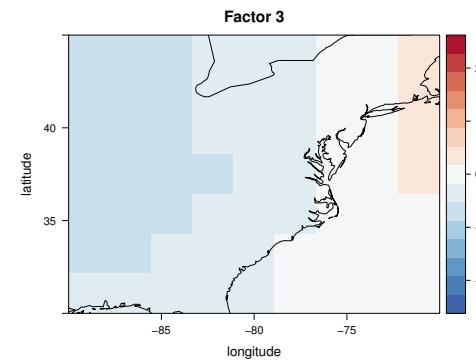
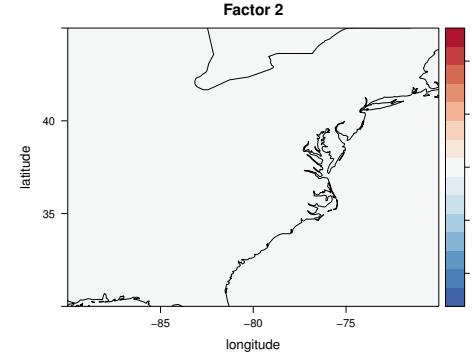
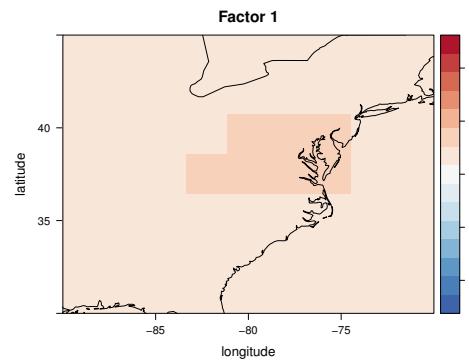
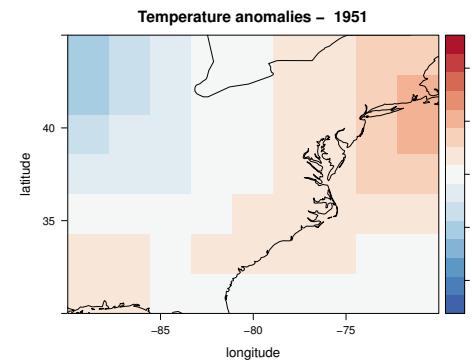
# Factor contributions in 1949



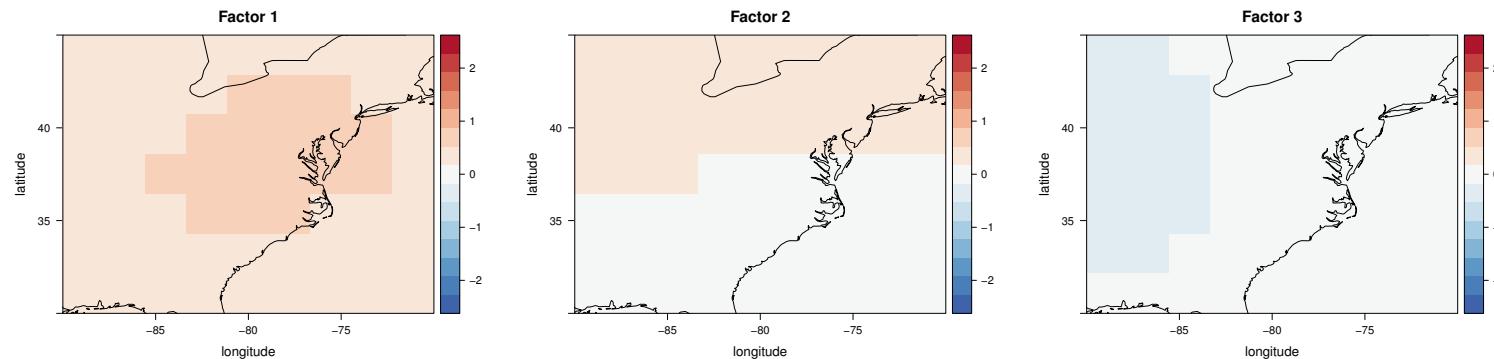
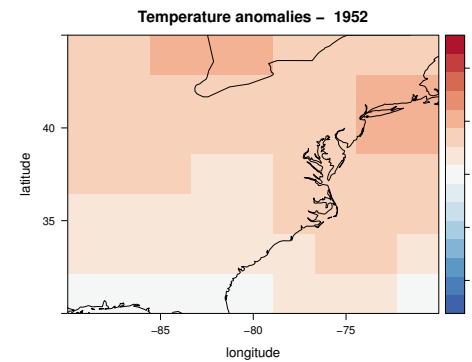
# Factor contributions in 1950



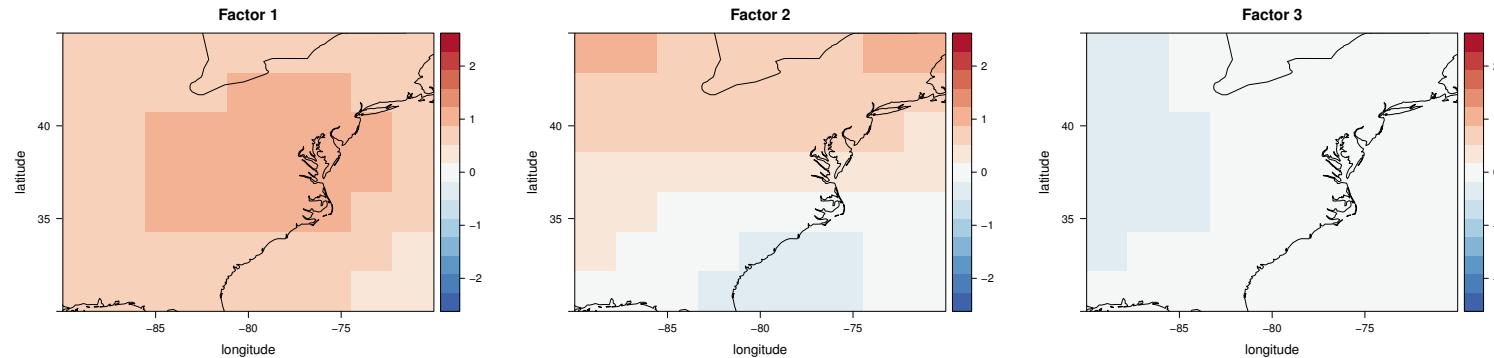
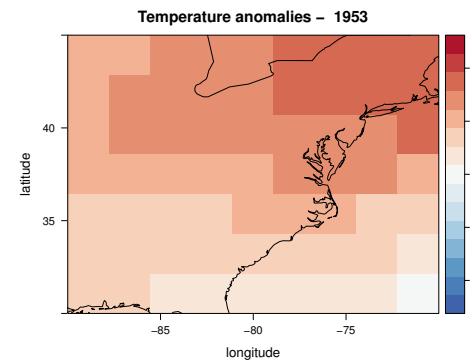
# Factor contributions in 1951



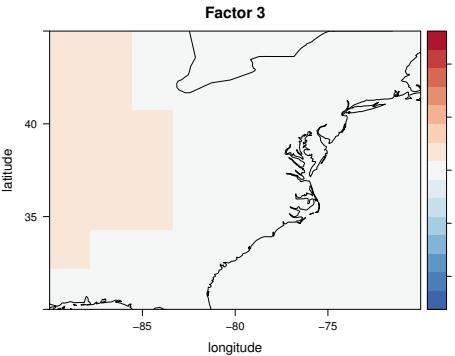
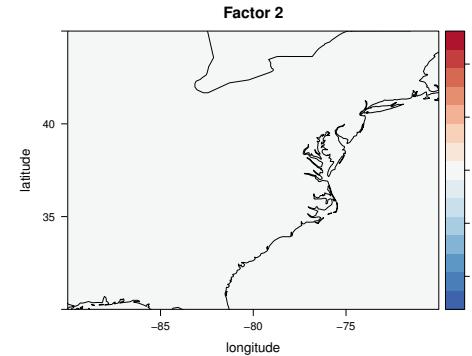
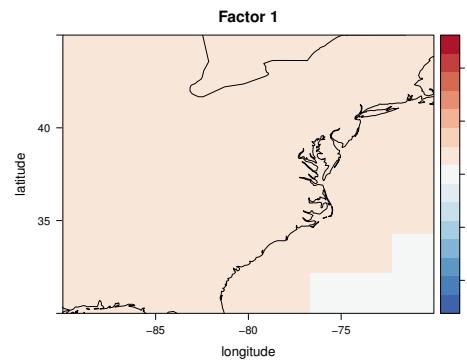
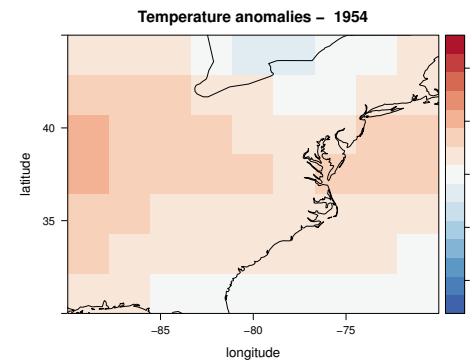
# Factor contributions in 1952



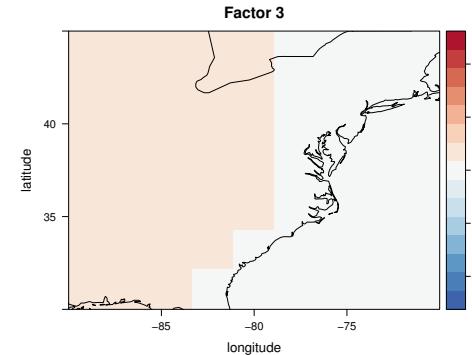
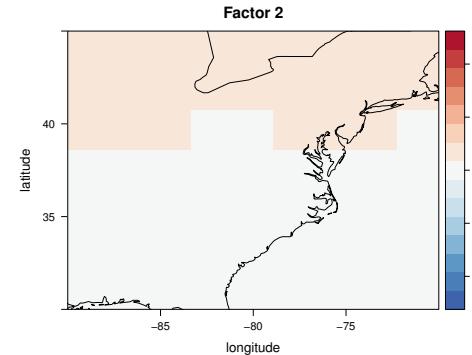
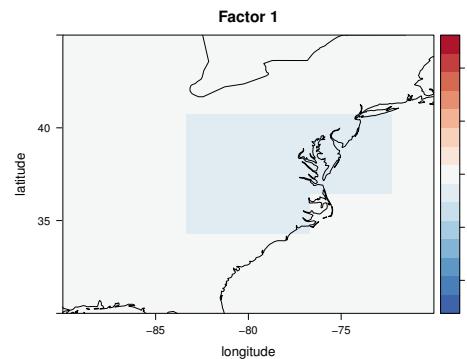
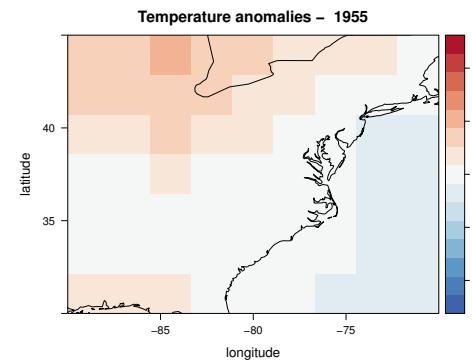
# Factor contributions in 1953



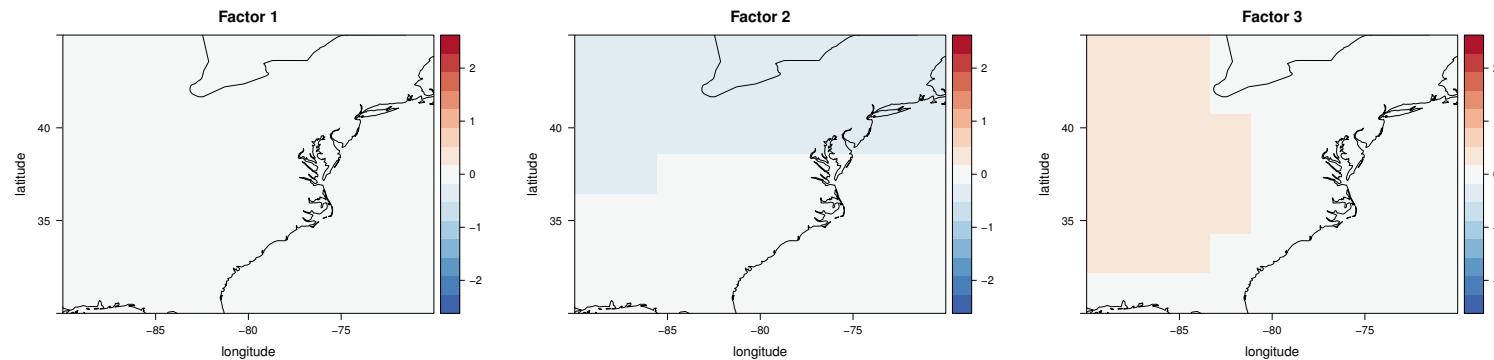
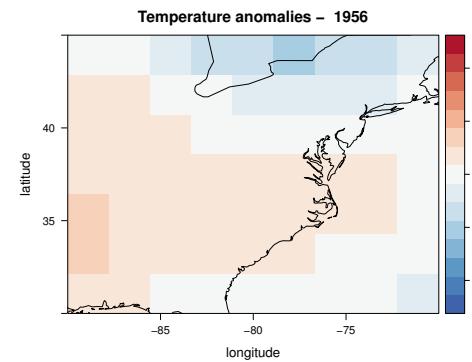
# Factor contributions in 1954



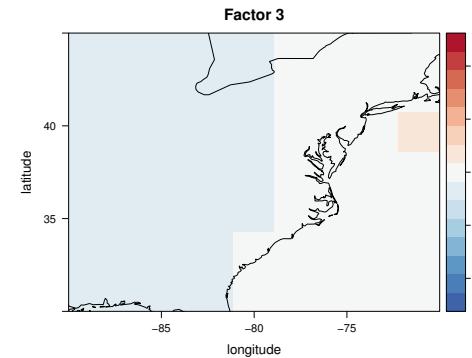
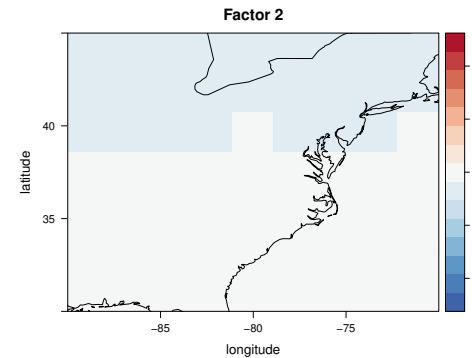
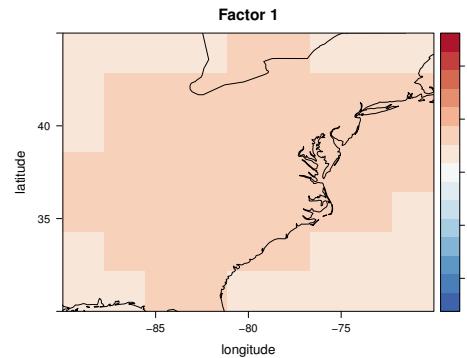
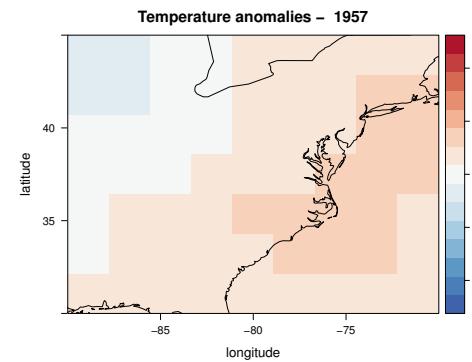
# Factor contributions in 1955



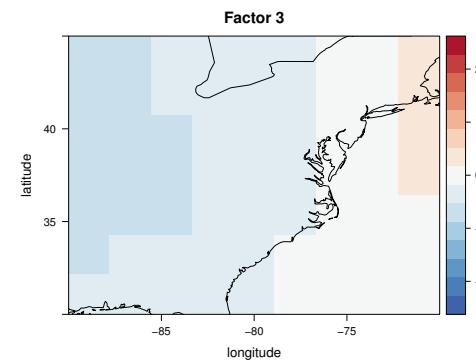
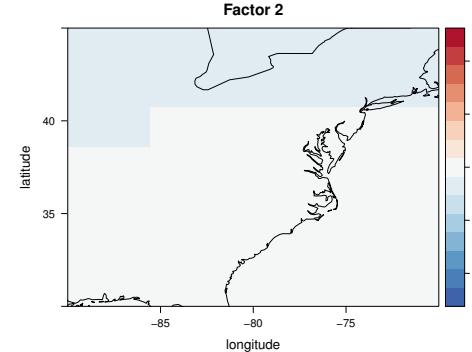
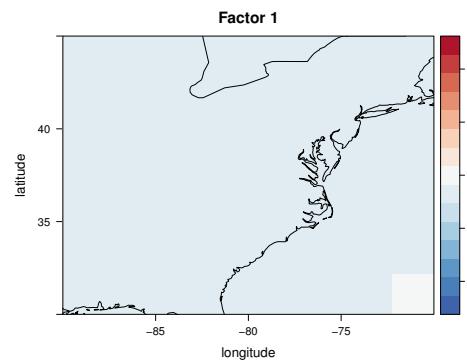
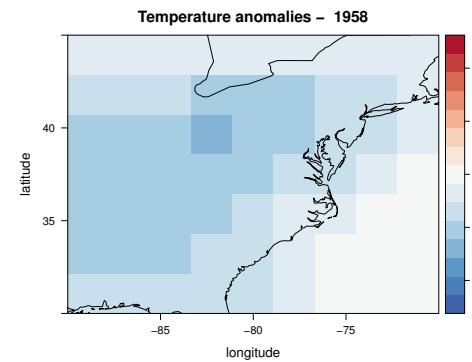
# Factor contributions in 1956



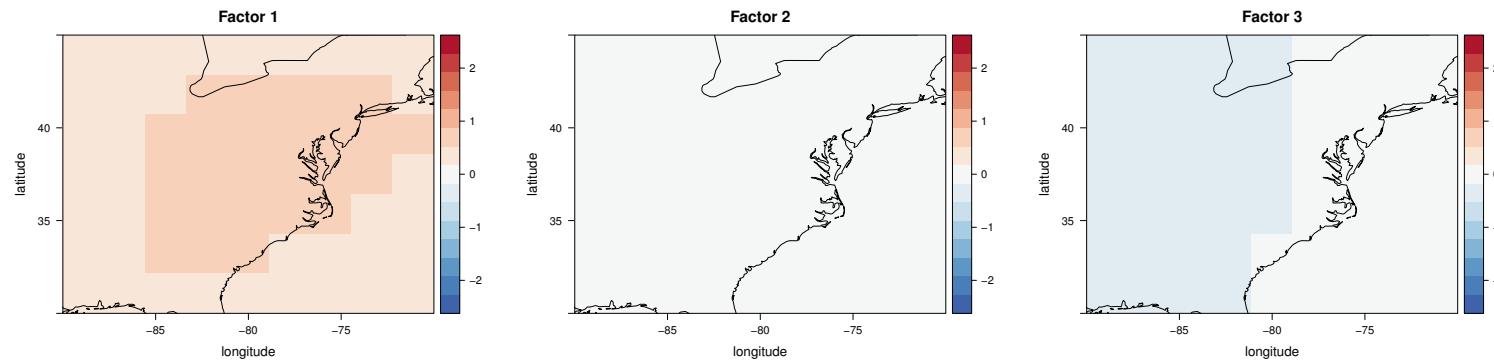
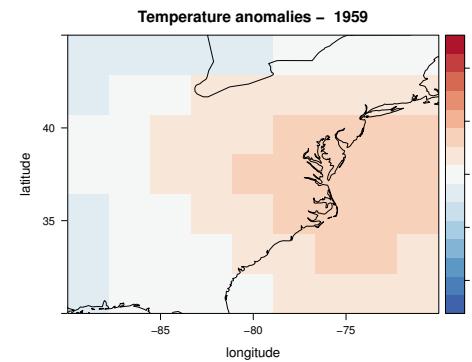
# Factor contributions in 1957



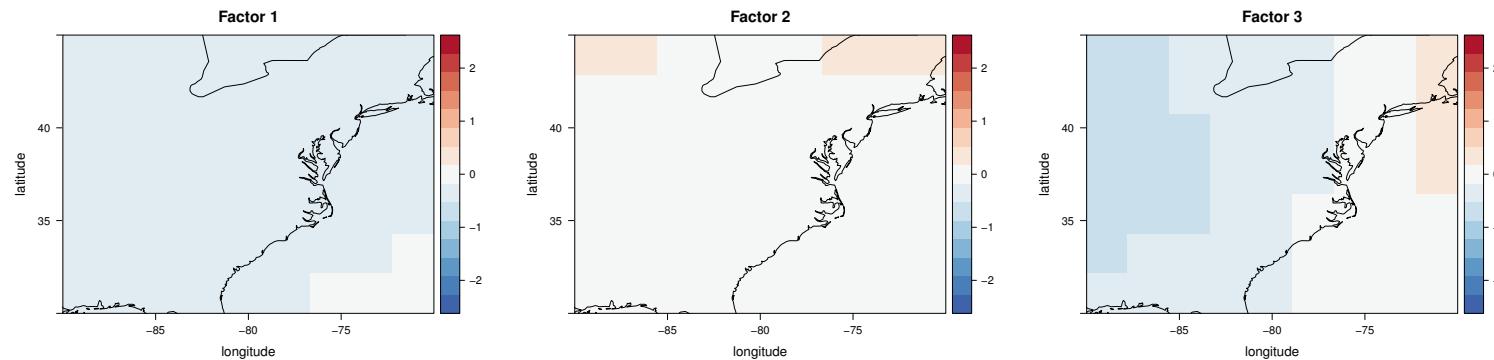
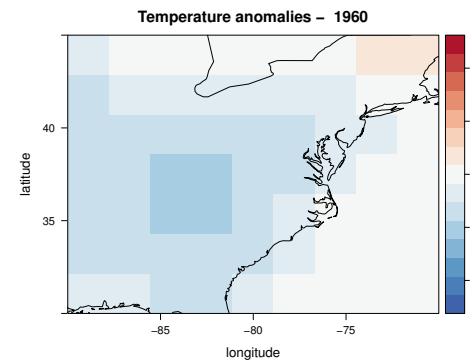
# Factor contributions in 1958



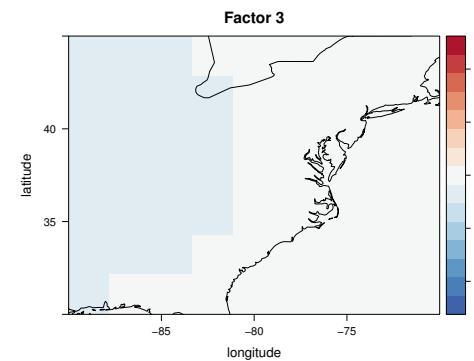
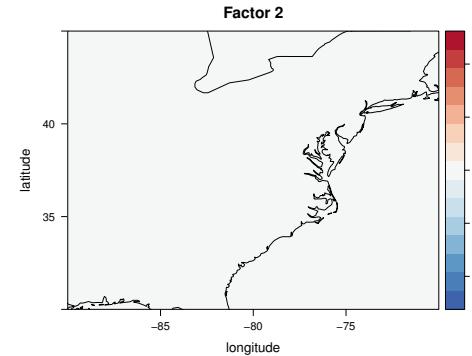
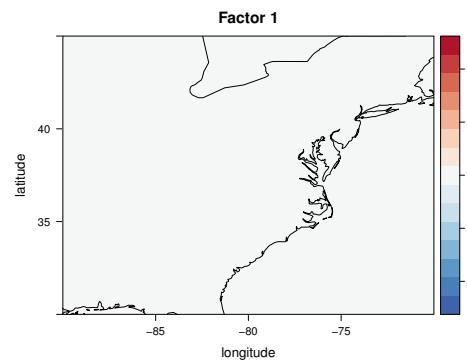
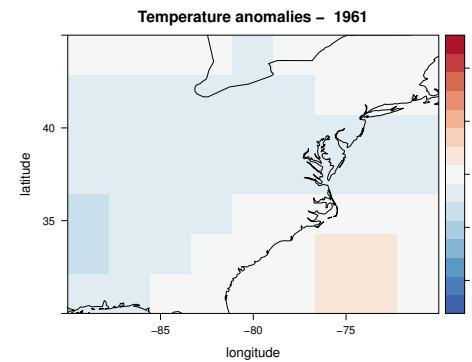
# Factor contributions in 1959



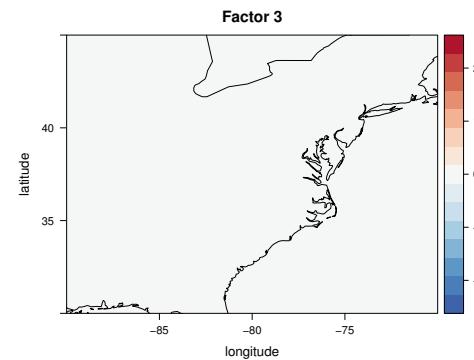
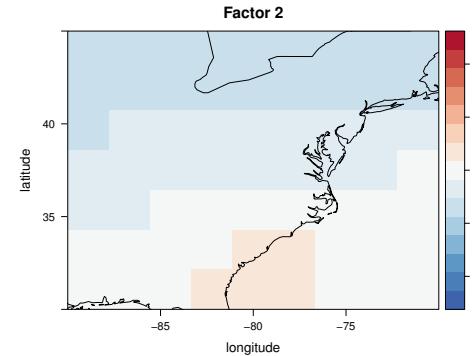
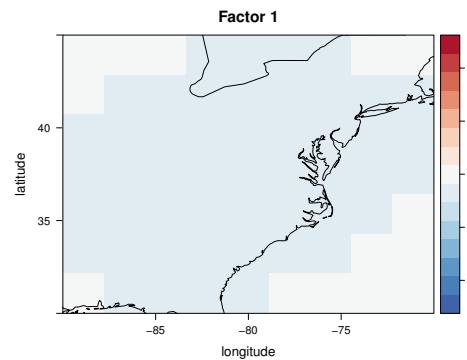
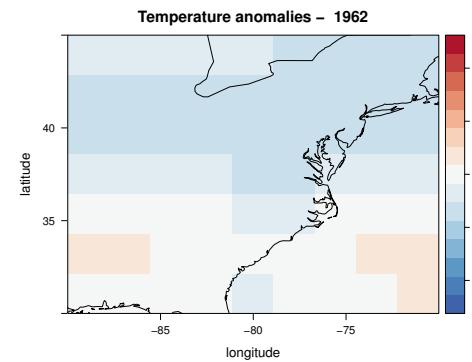
# Factor contributions in 1960



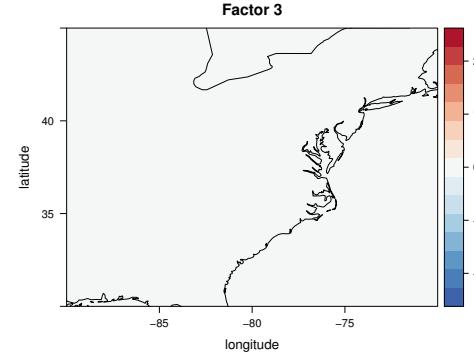
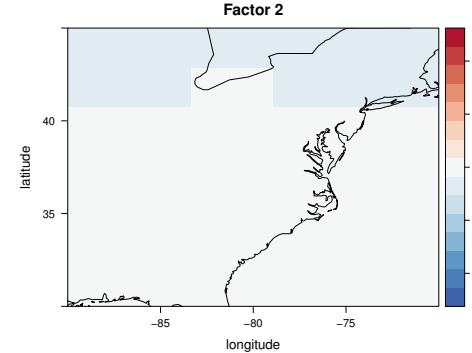
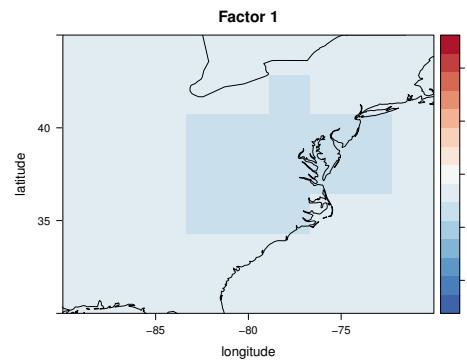
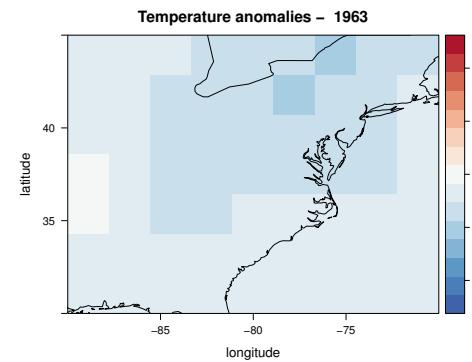
# Factor contributions in 1961



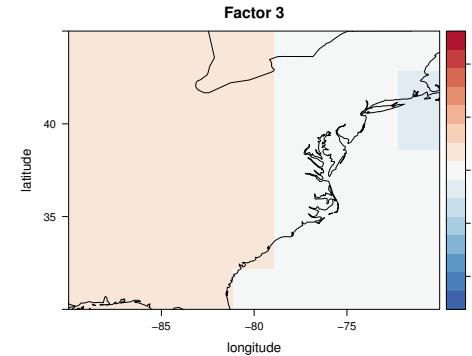
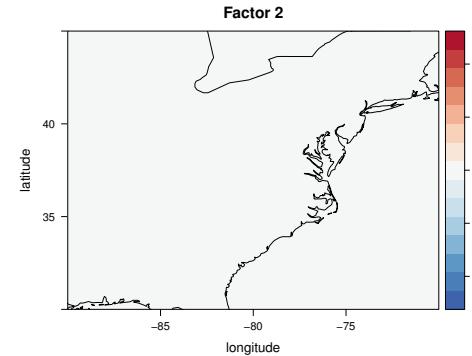
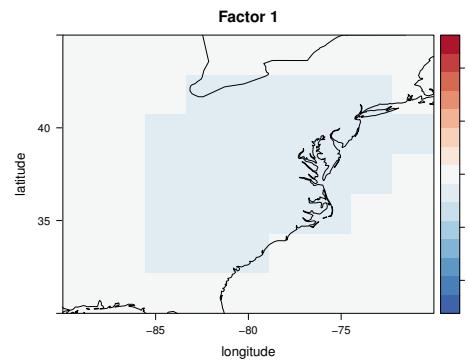
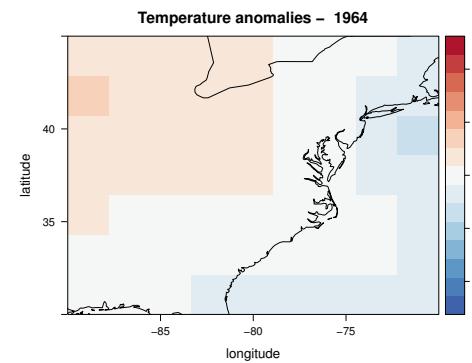
# Factor contributions in 1962



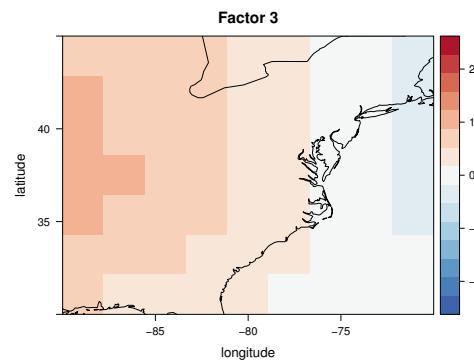
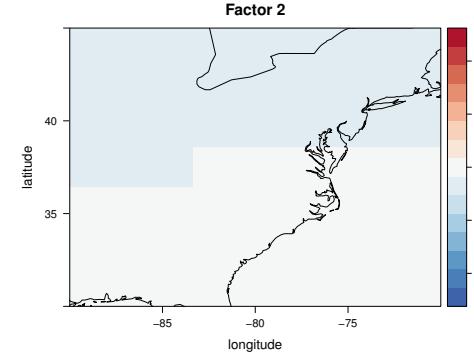
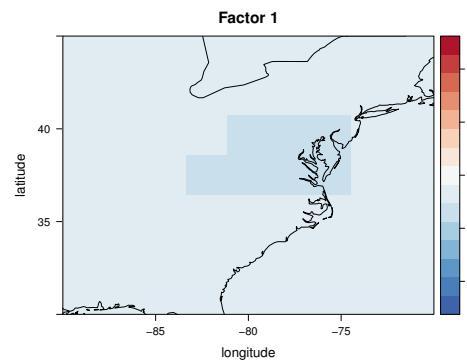
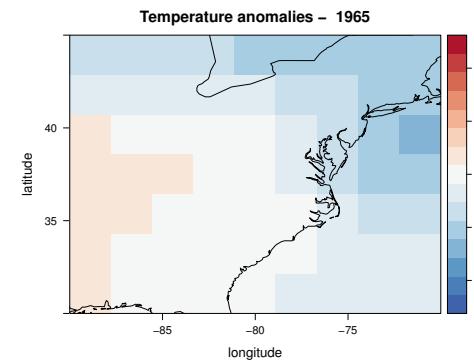
# Factor contributions in 1963



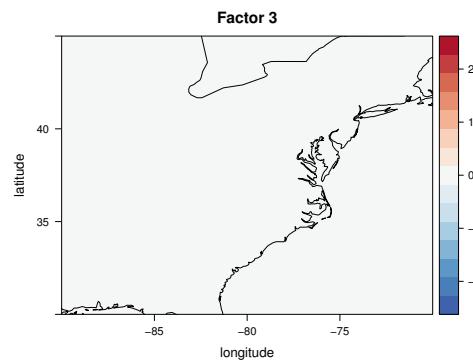
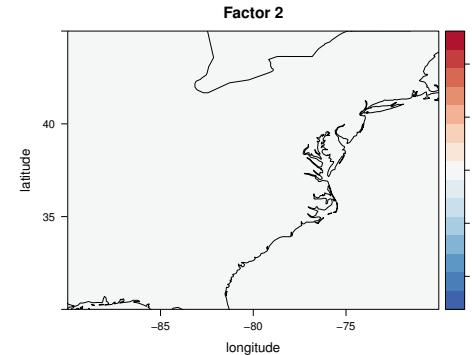
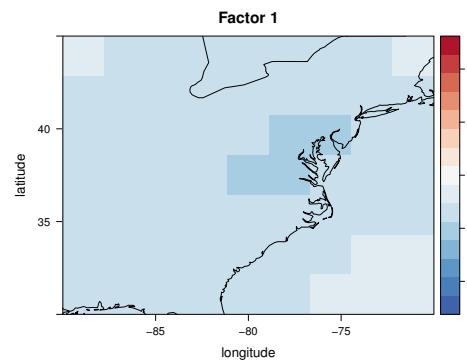
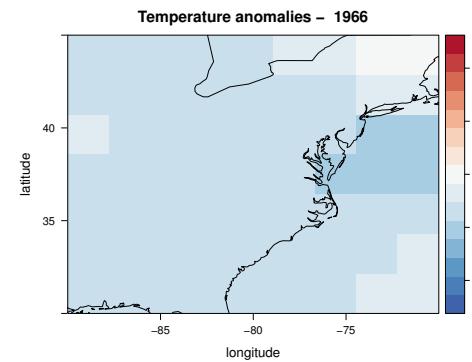
# Factor contributions in 1964



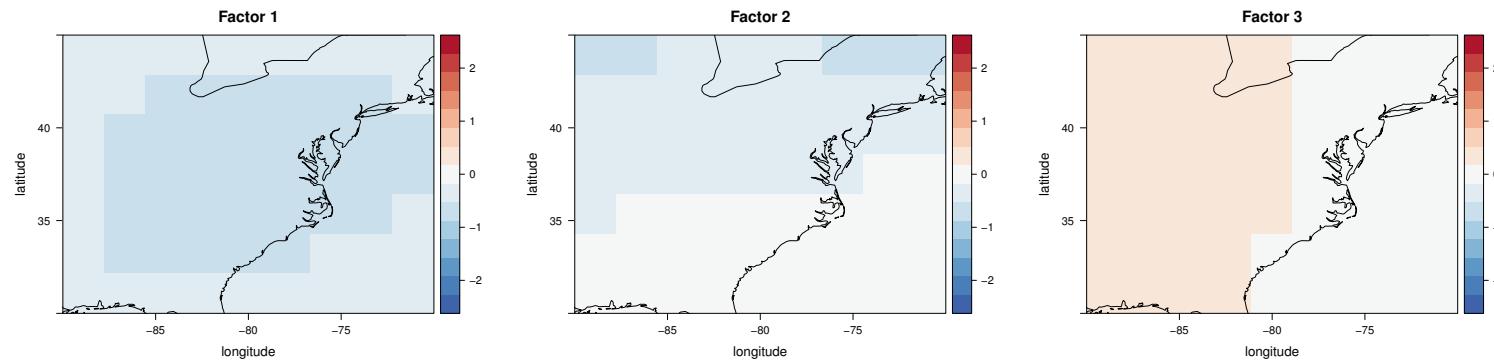
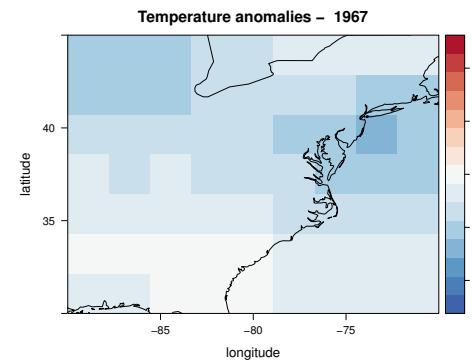
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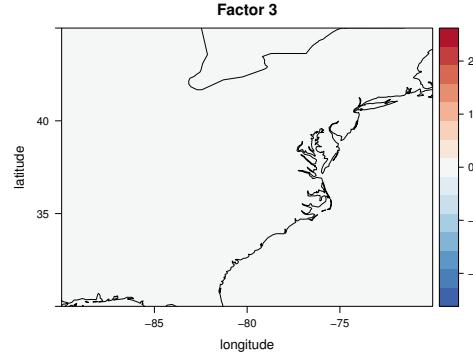
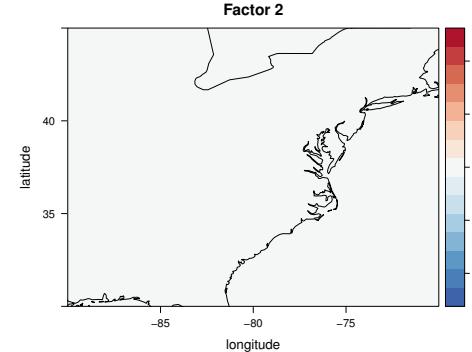
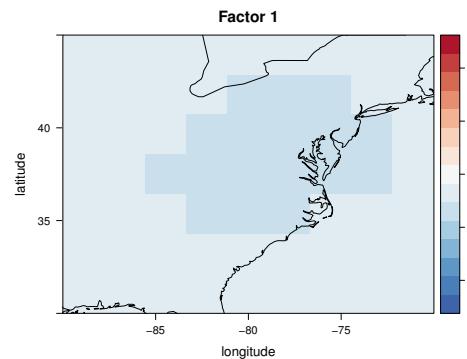
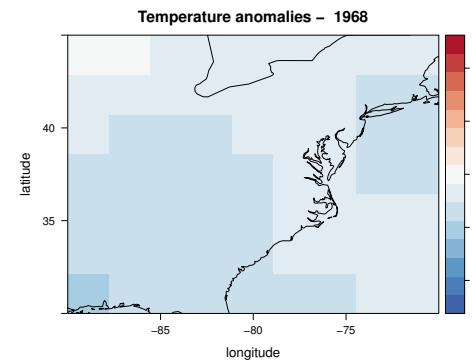
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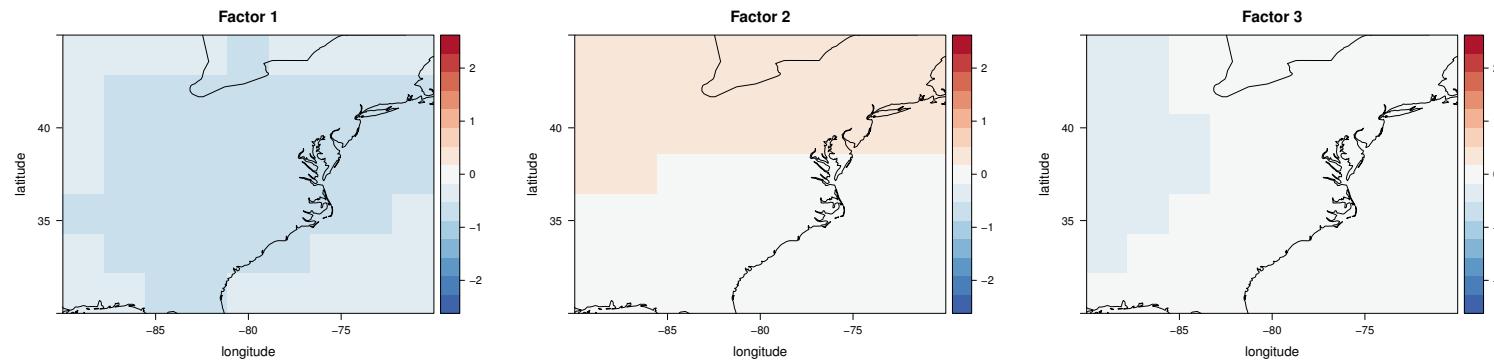
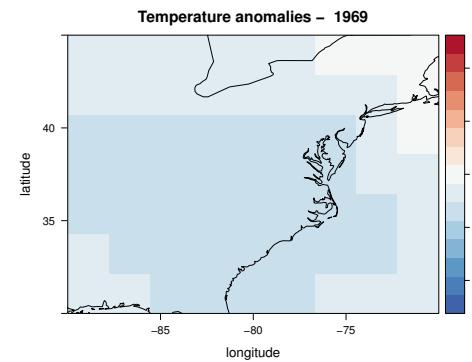
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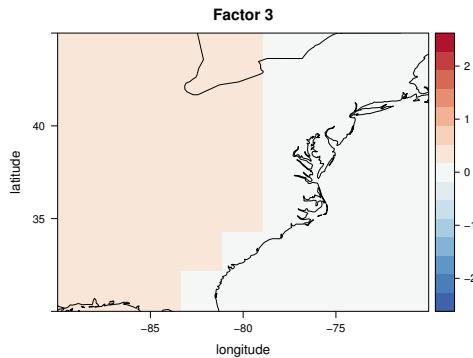
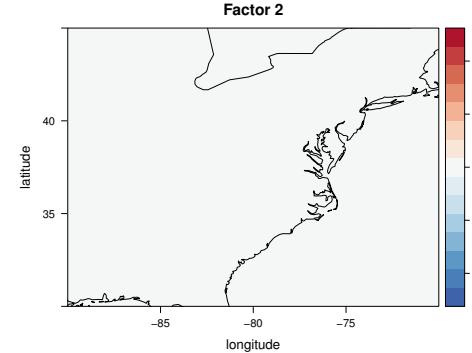
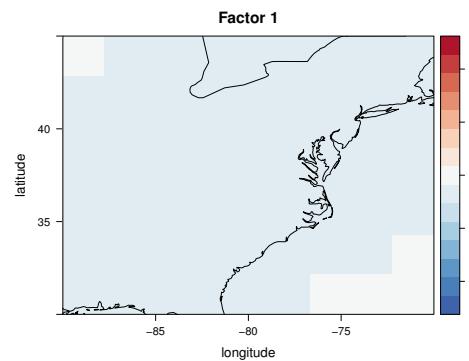
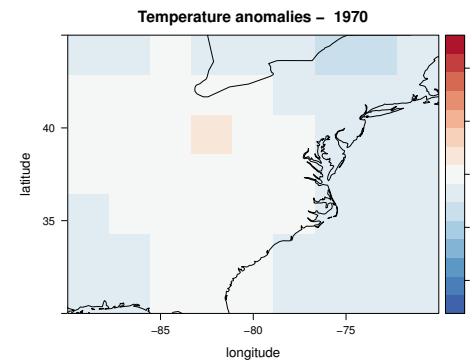
# Factor contributions in 1968



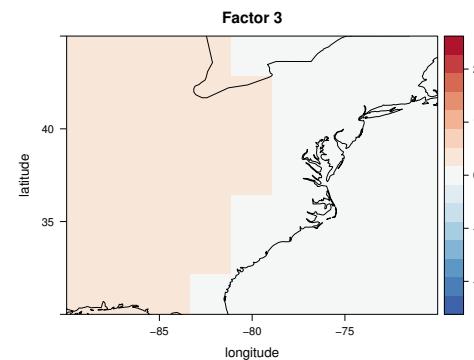
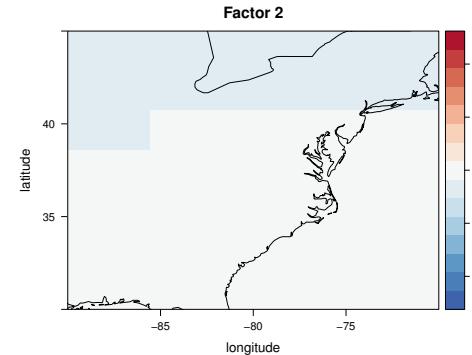
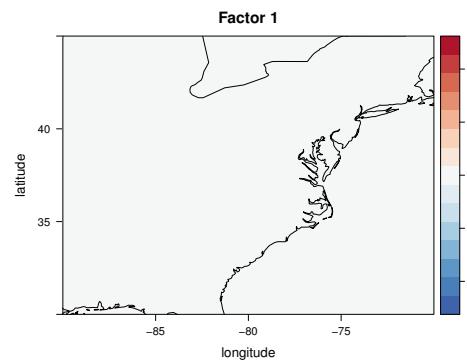
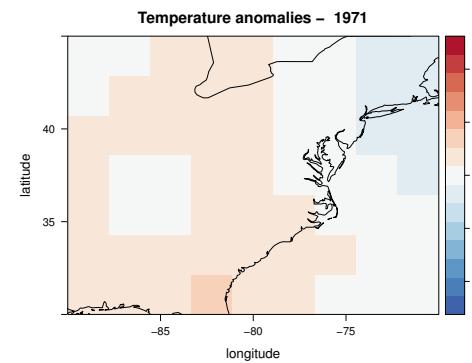
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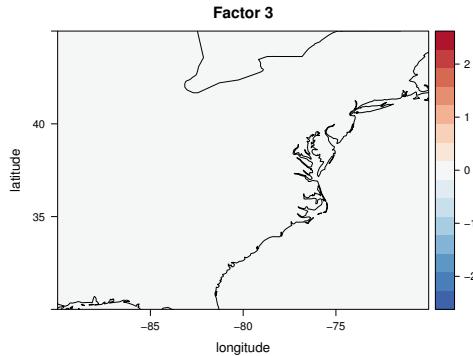
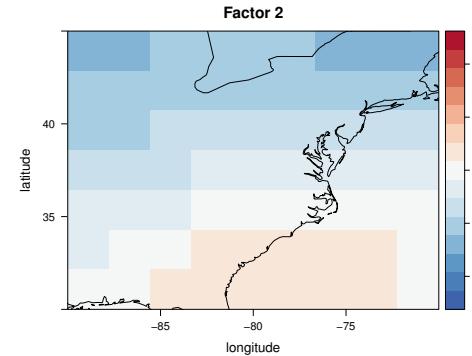
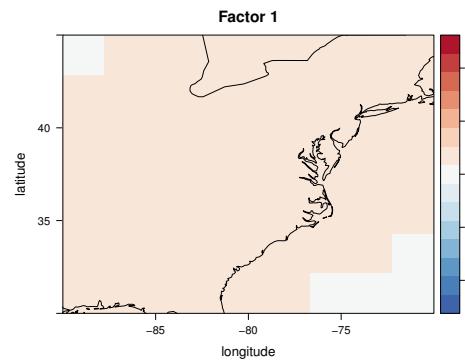
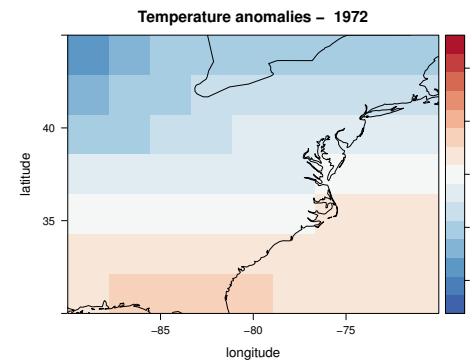
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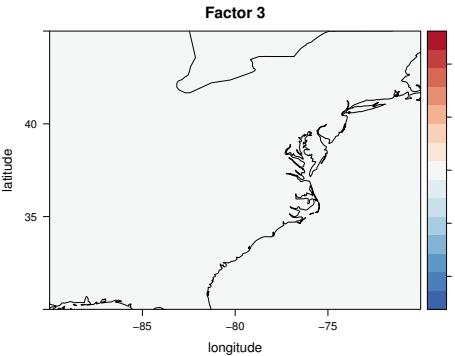
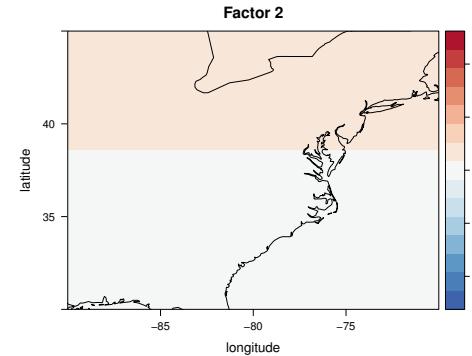
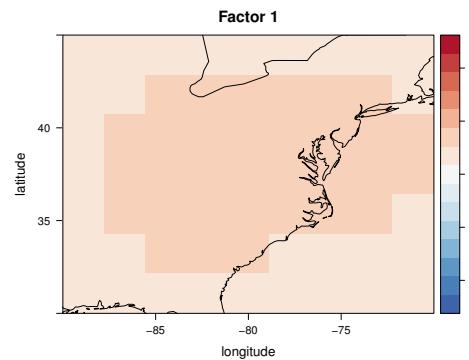
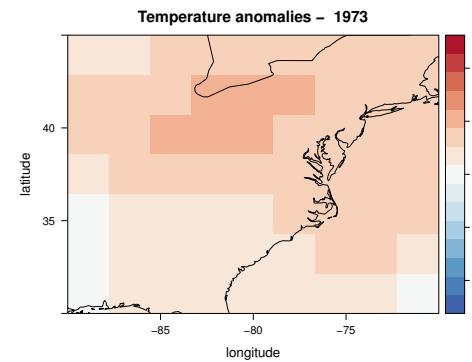
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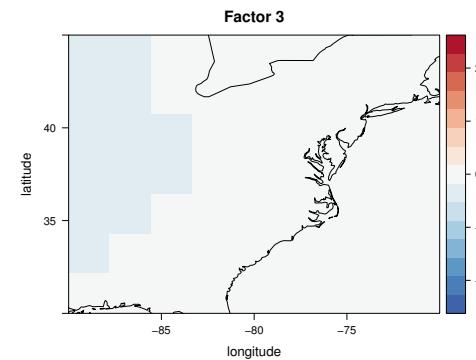
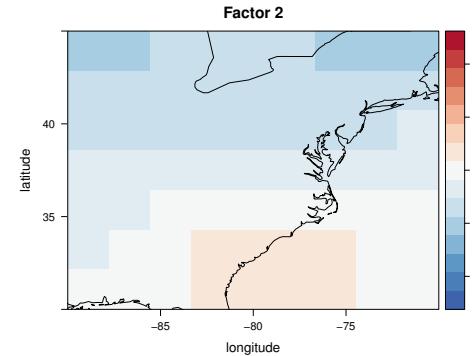
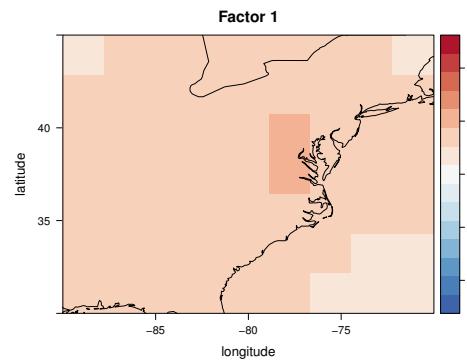
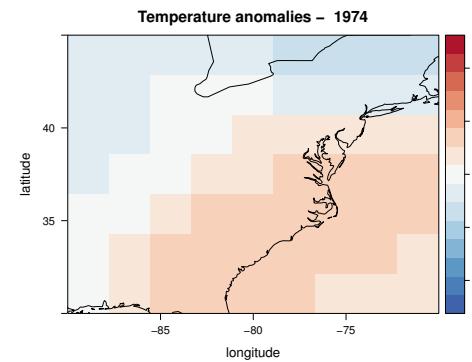
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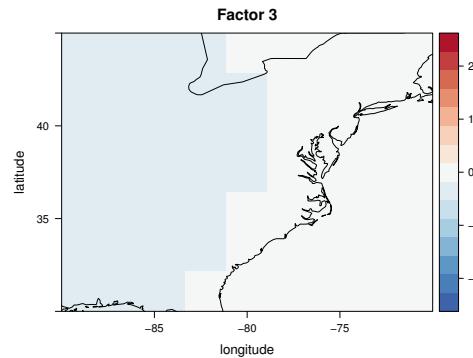
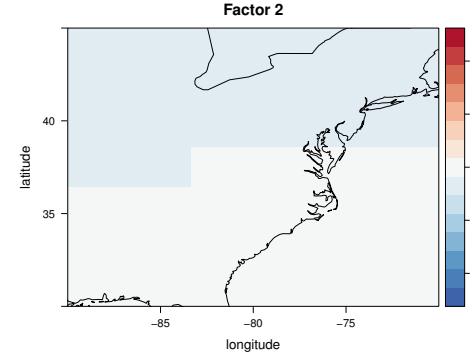
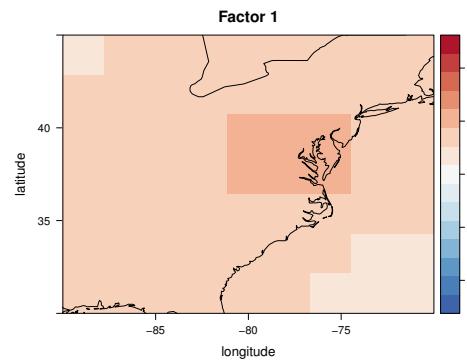
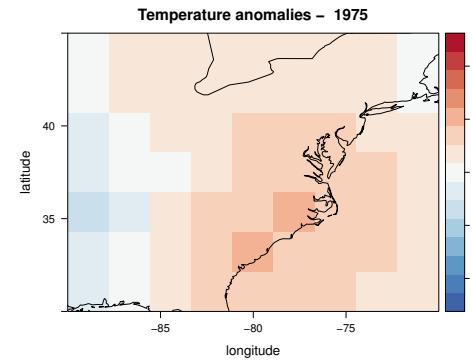
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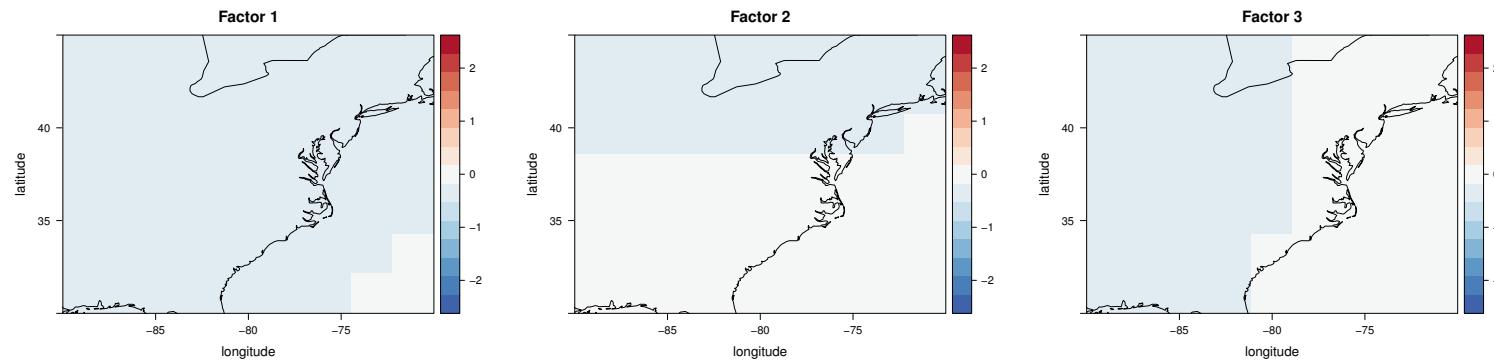
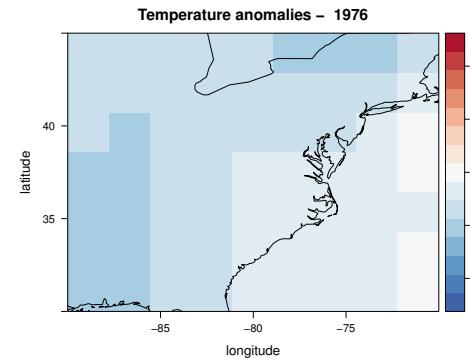
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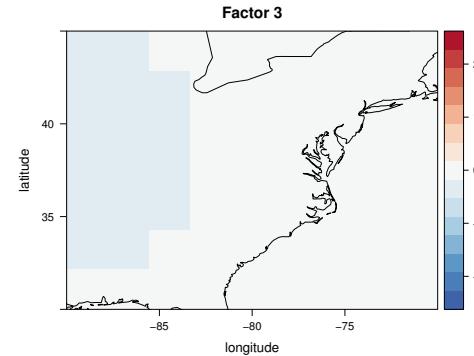
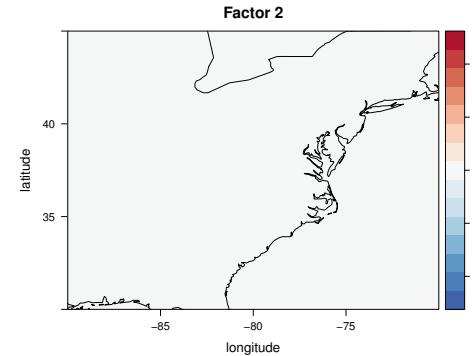
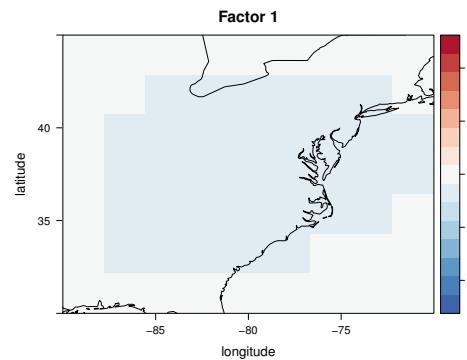
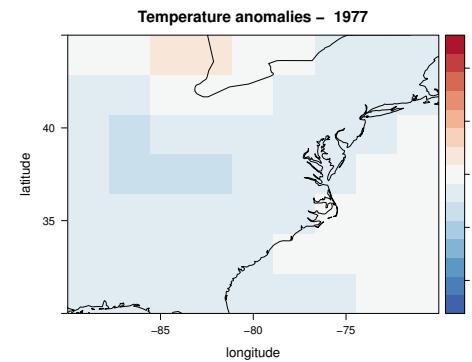
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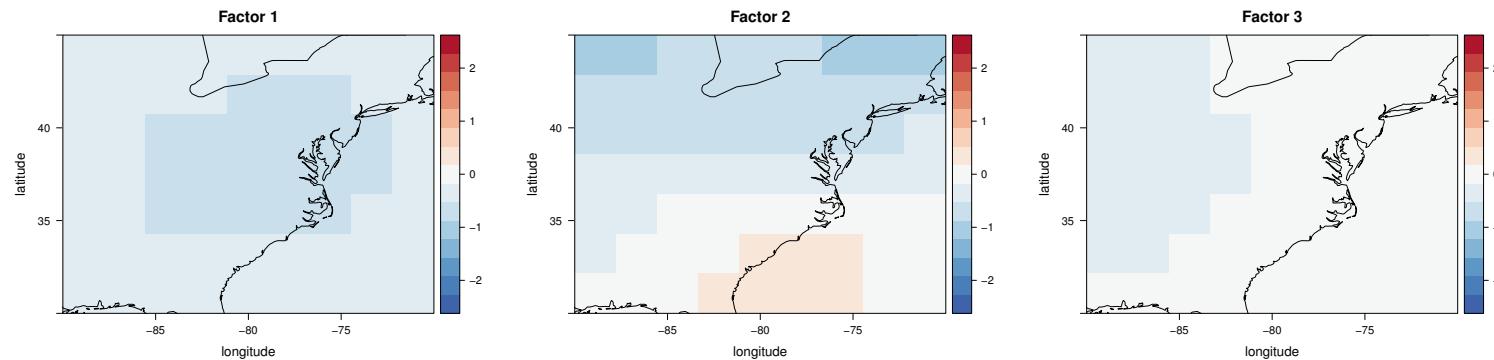
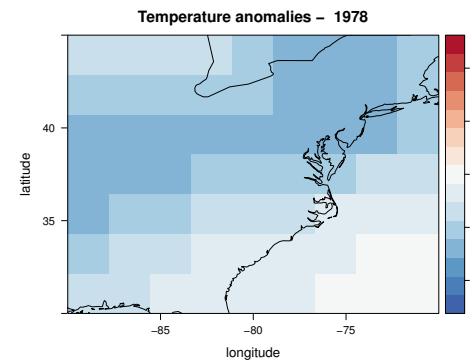
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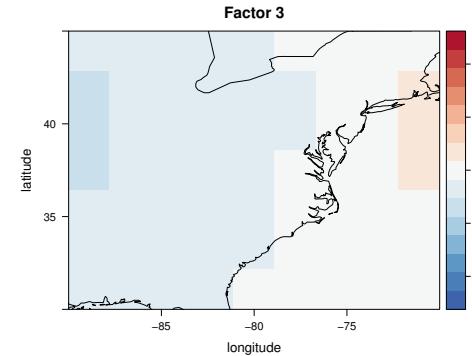
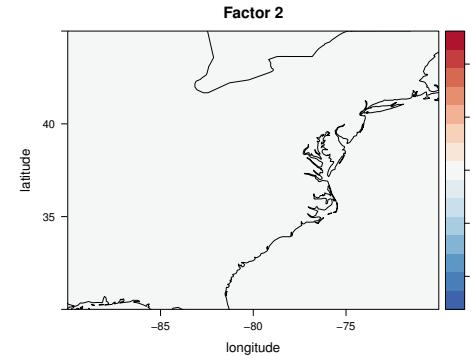
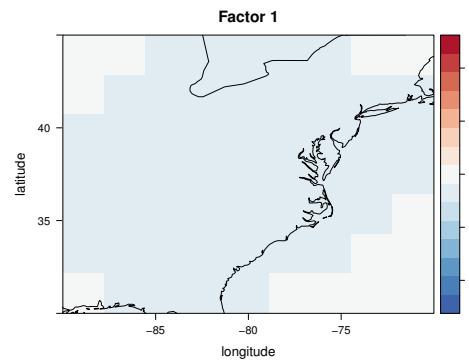
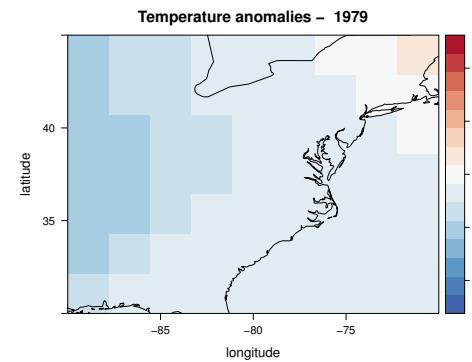
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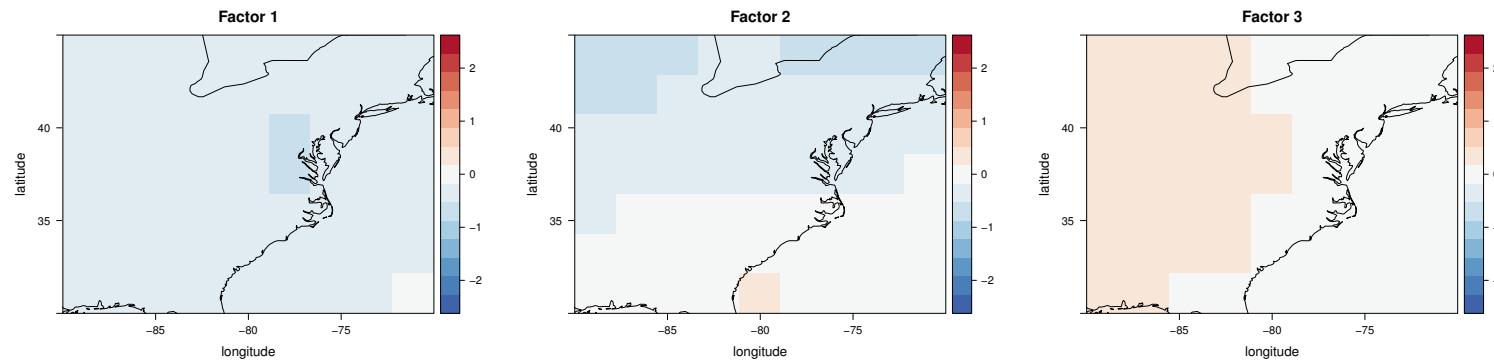
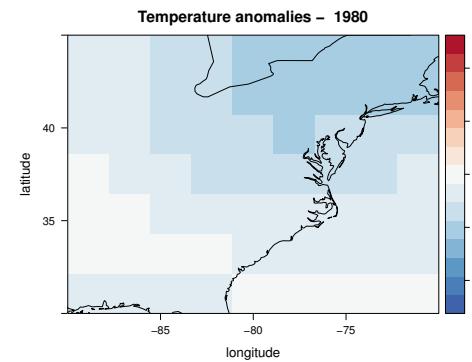
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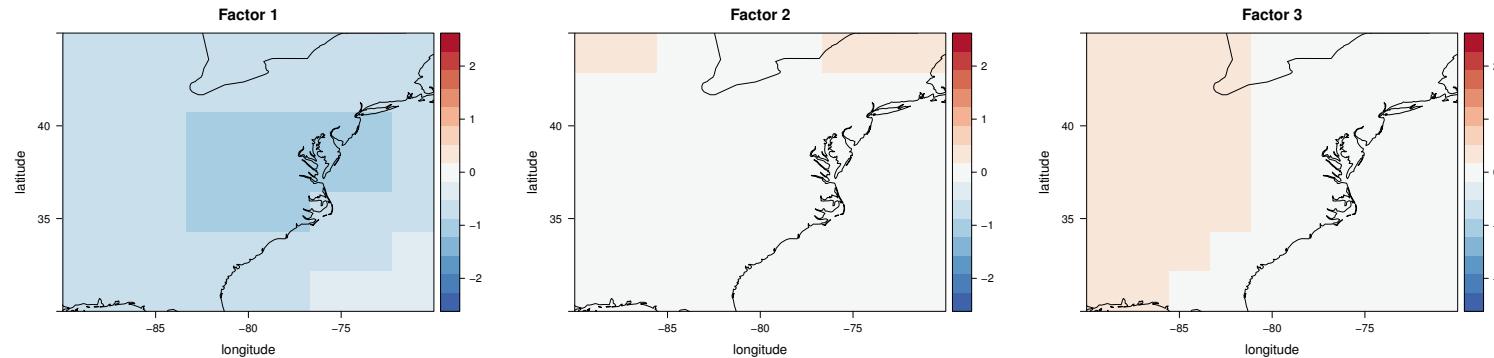
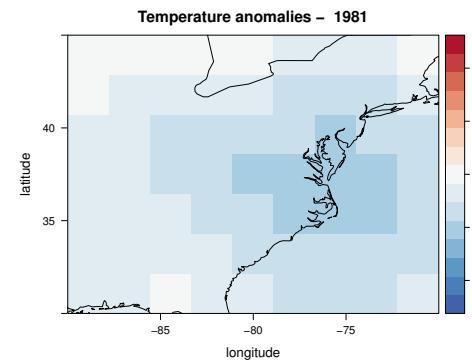
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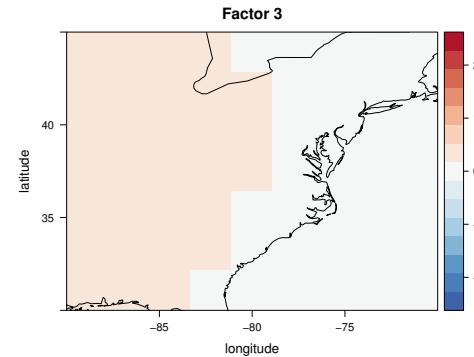
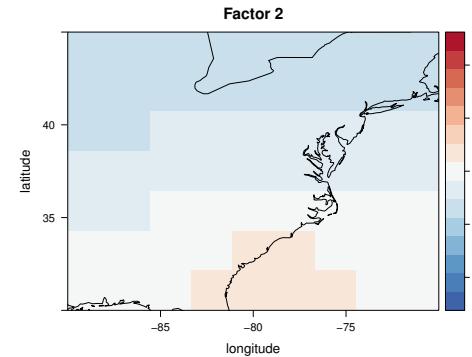
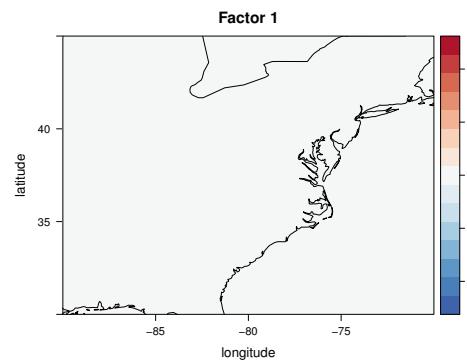
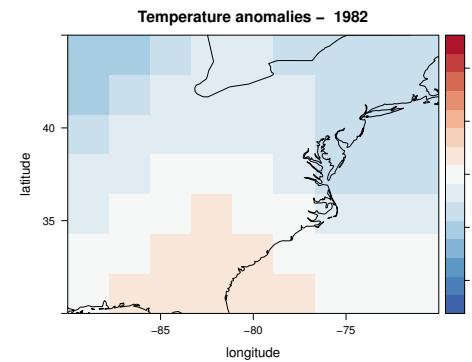
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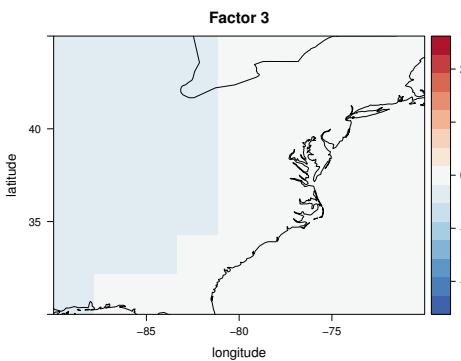
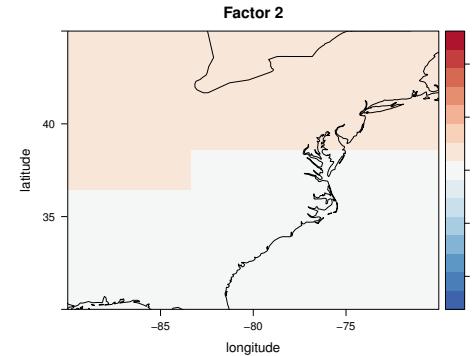
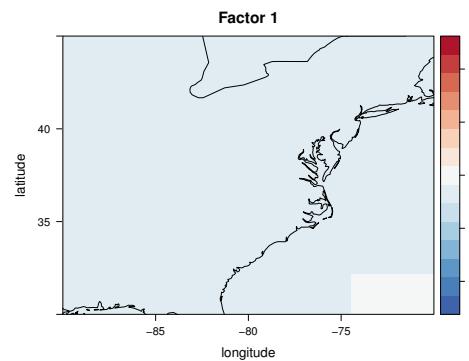
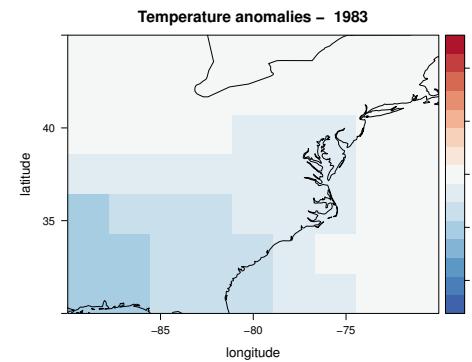
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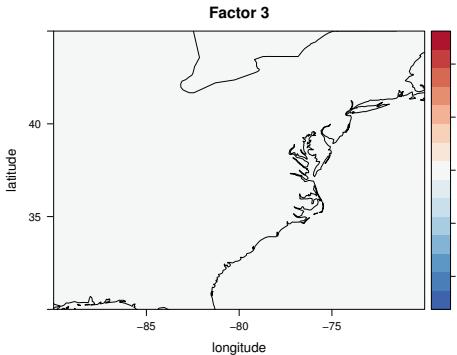
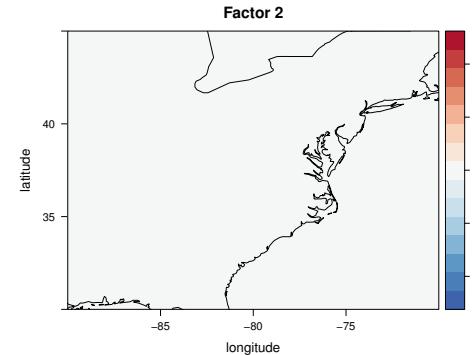
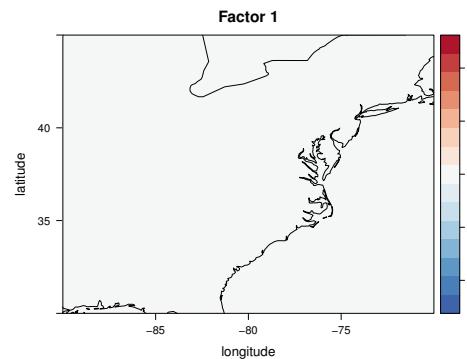
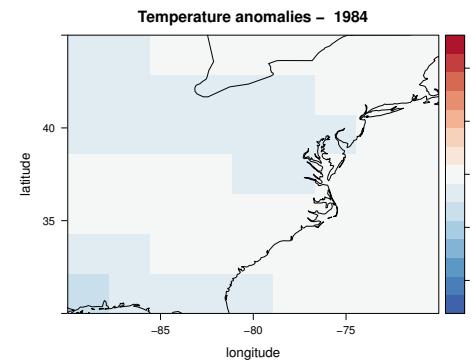
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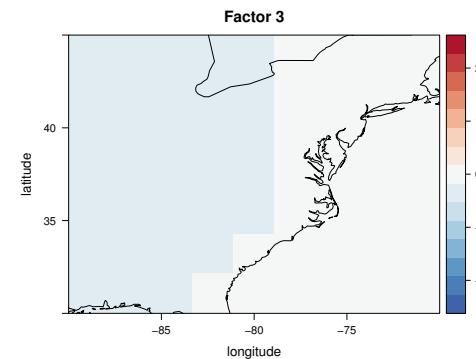
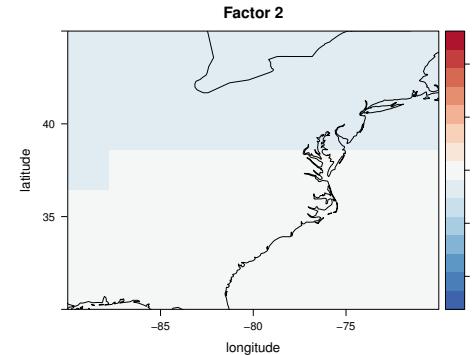
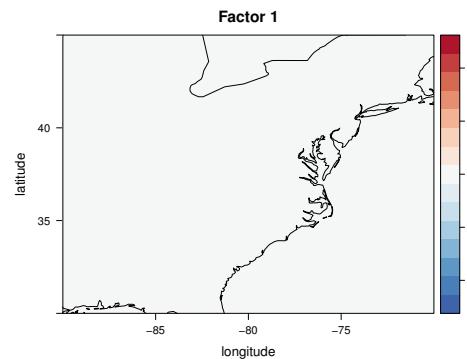
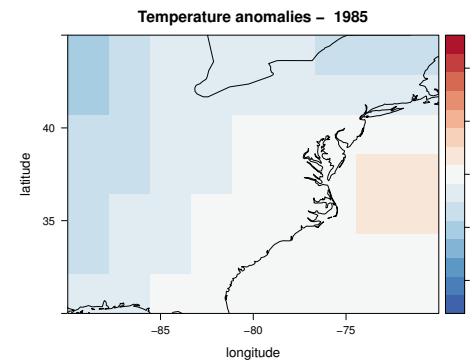
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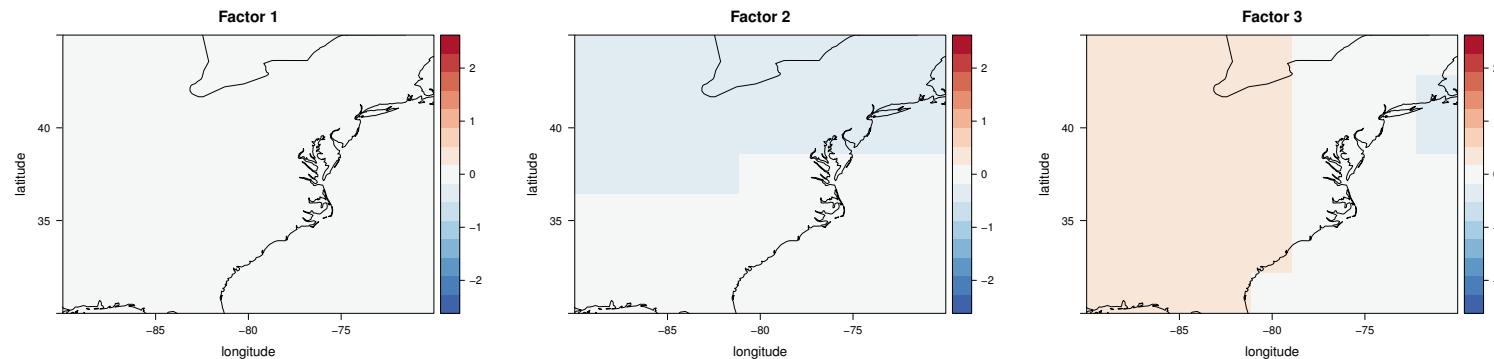
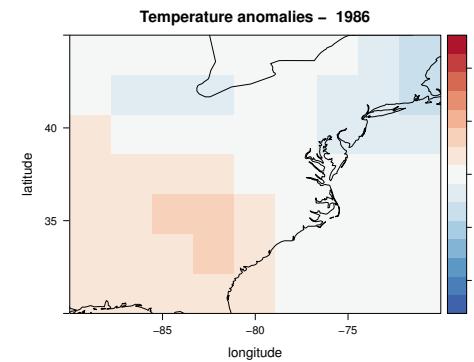
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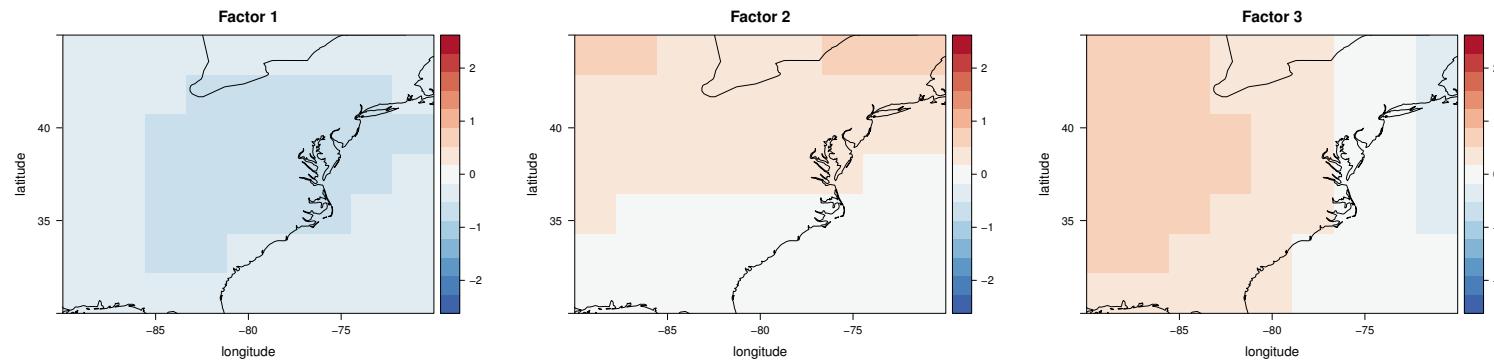
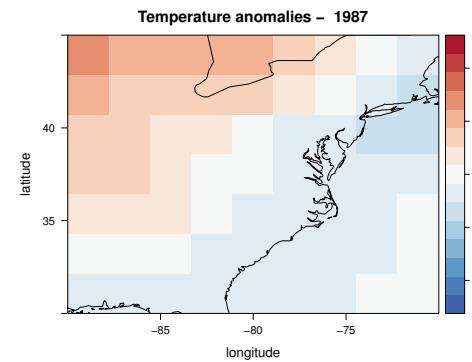
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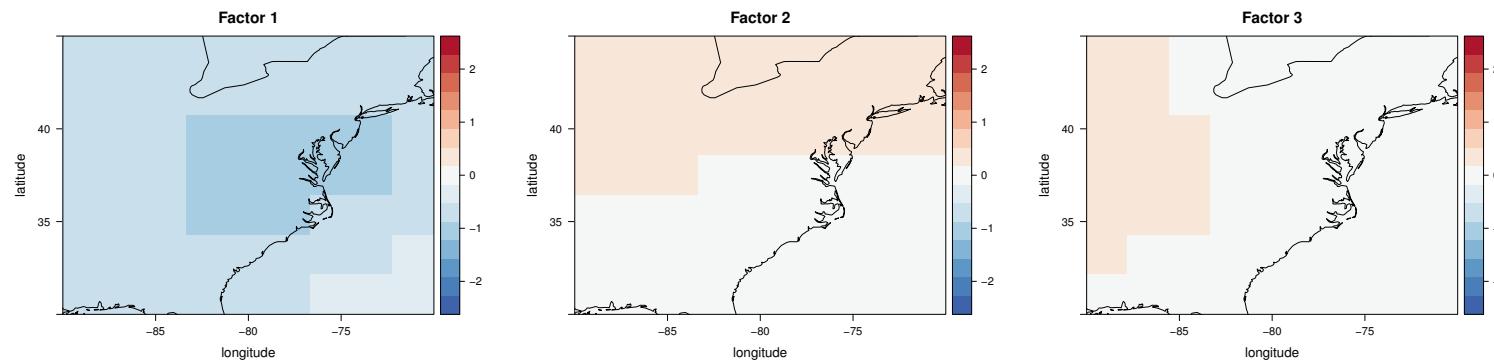
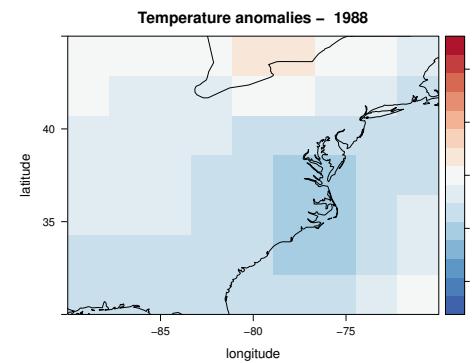
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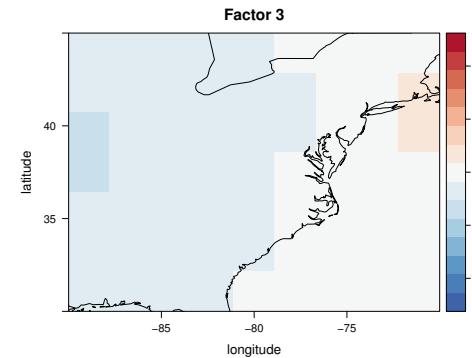
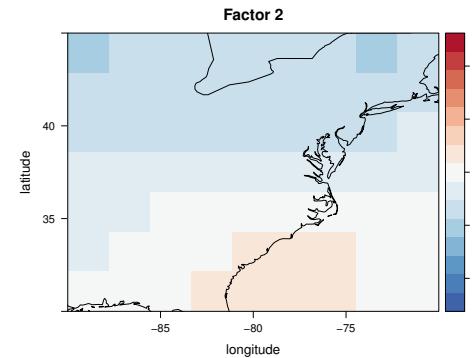
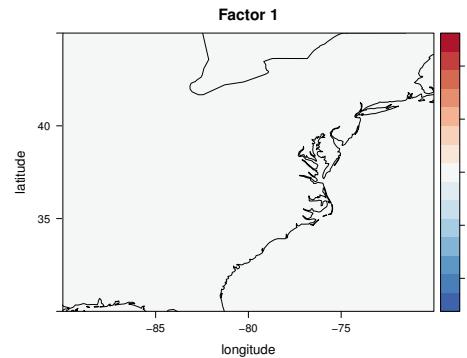
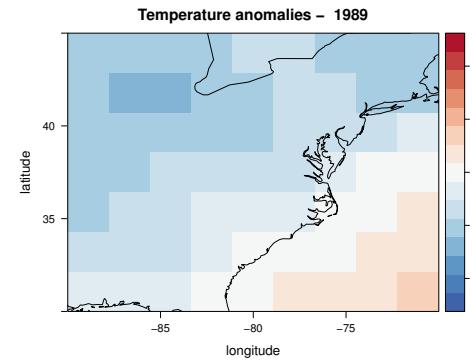
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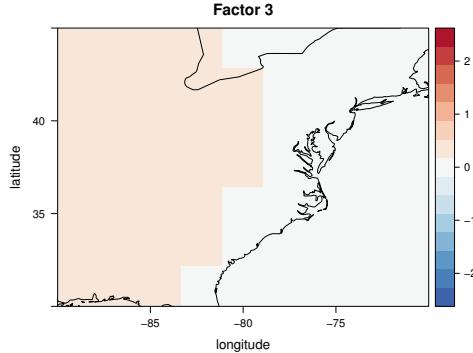
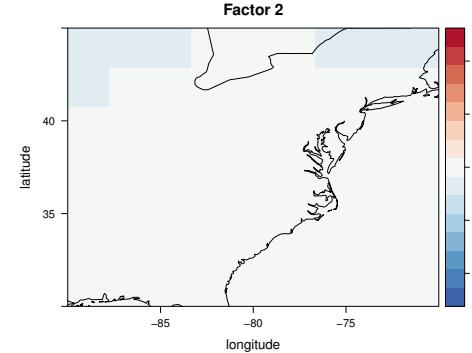
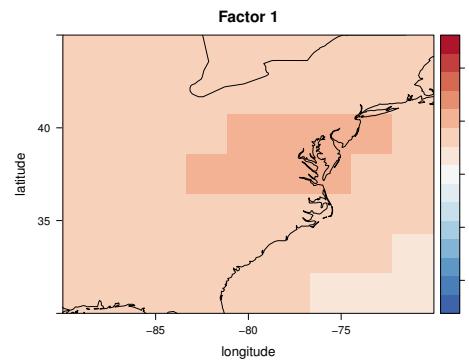
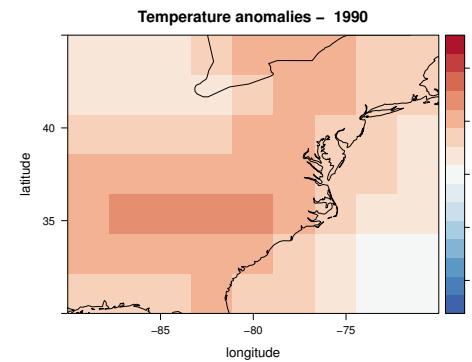
# Factor contributions in 1988



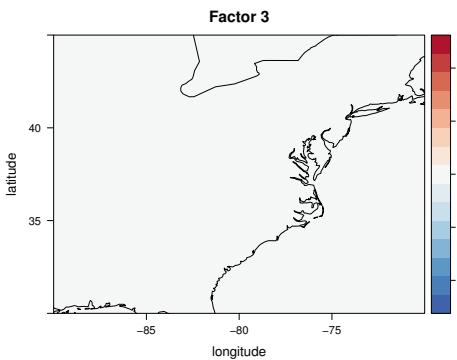
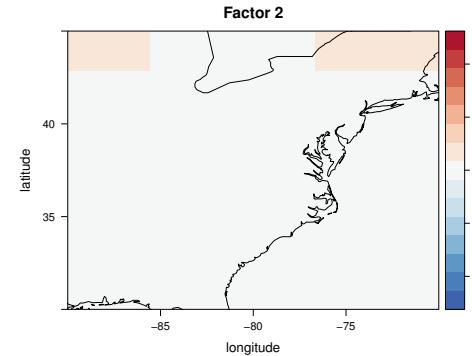
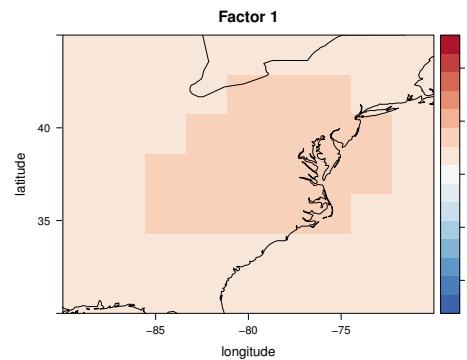
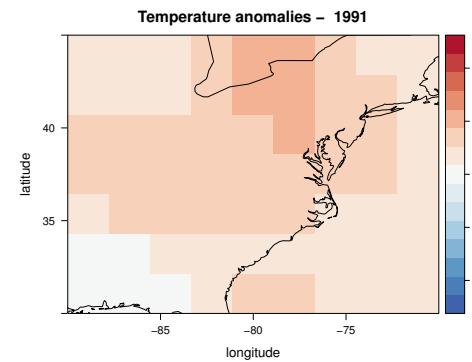
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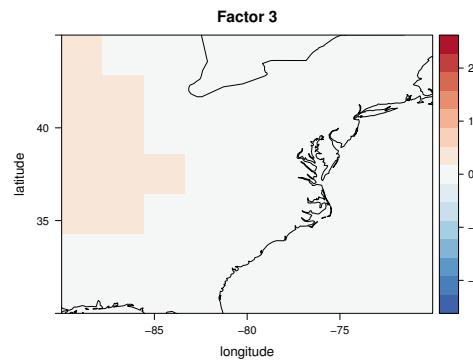
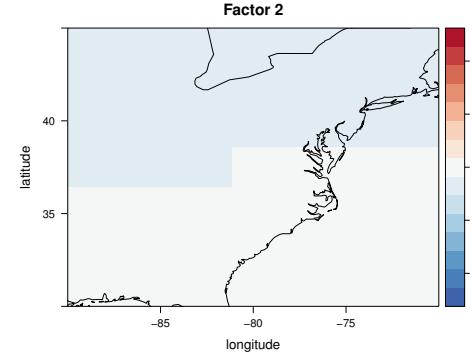
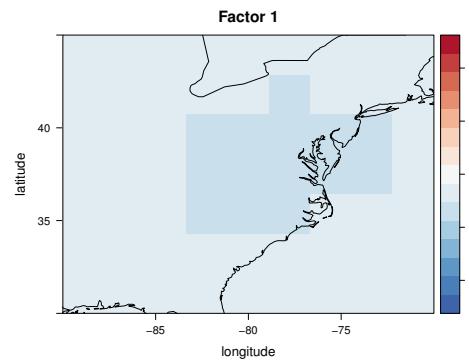
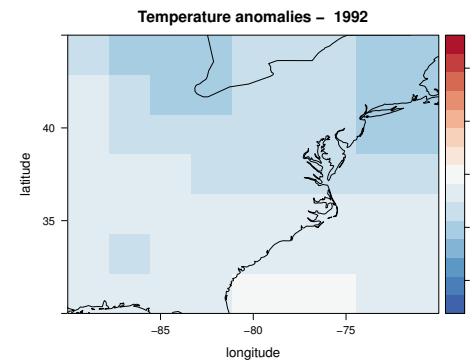
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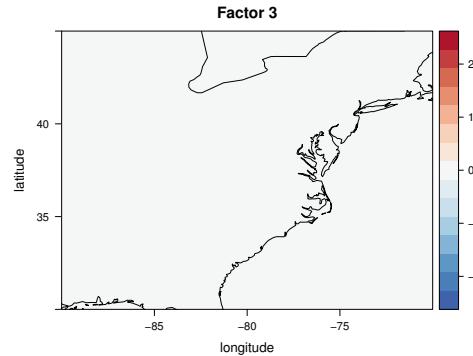
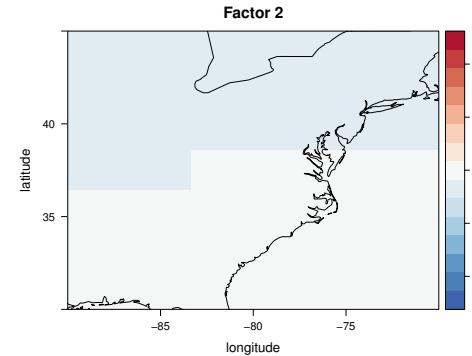
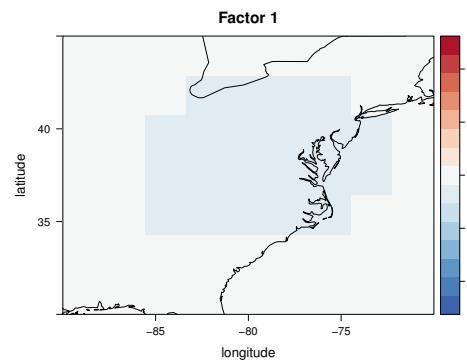
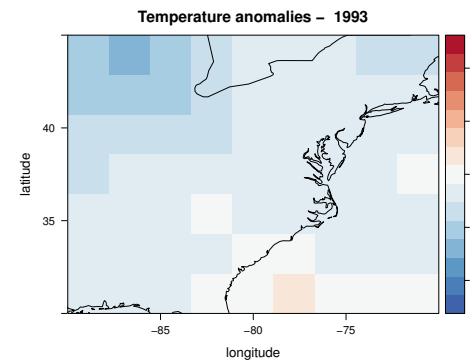
# Factor contributions in 1991



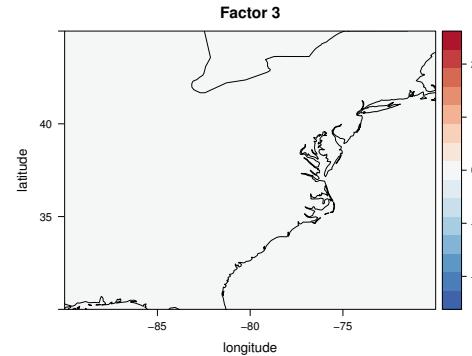
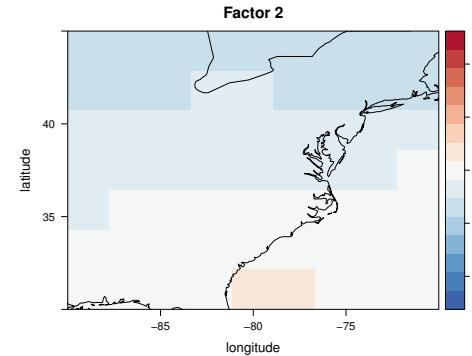
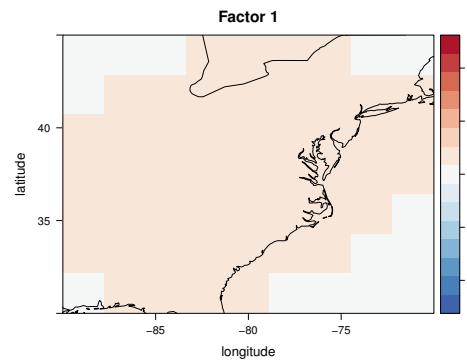
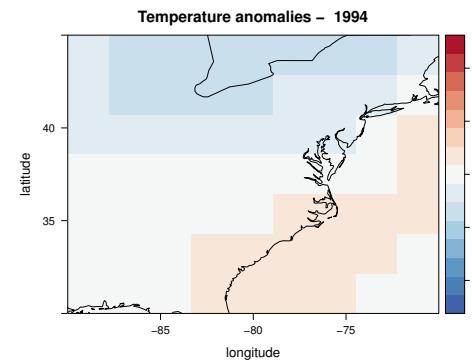
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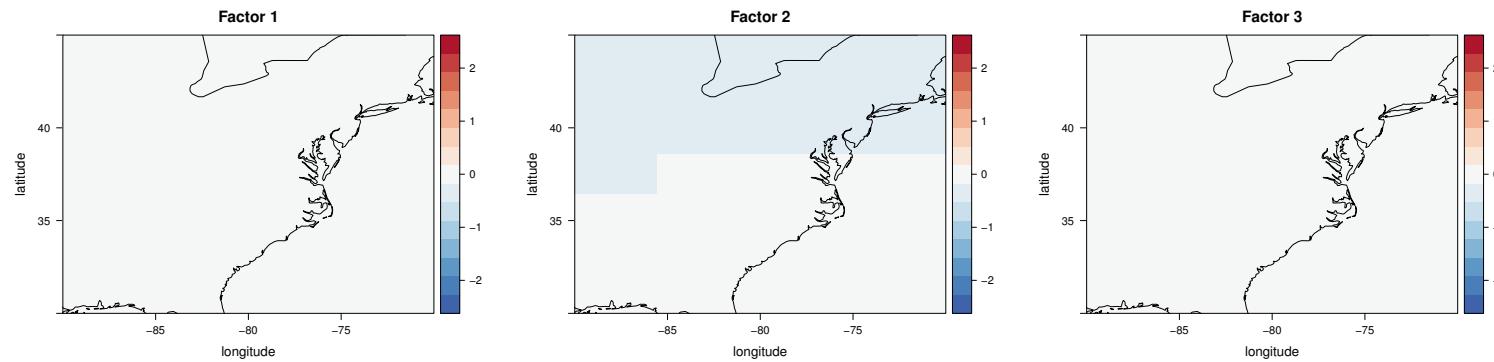
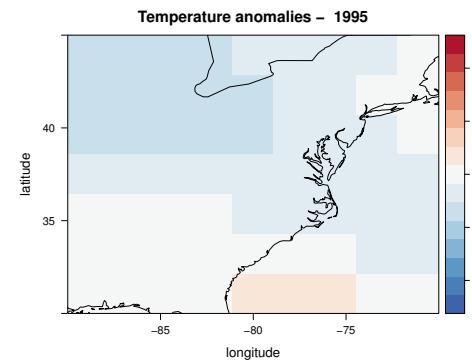
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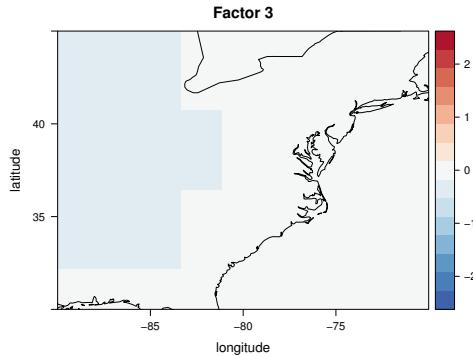
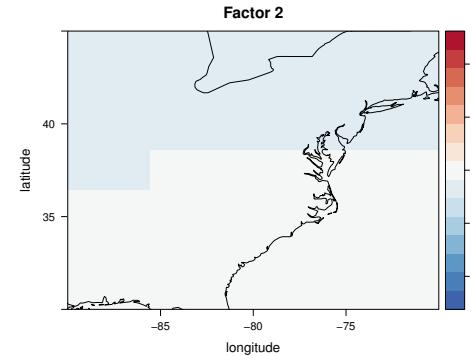
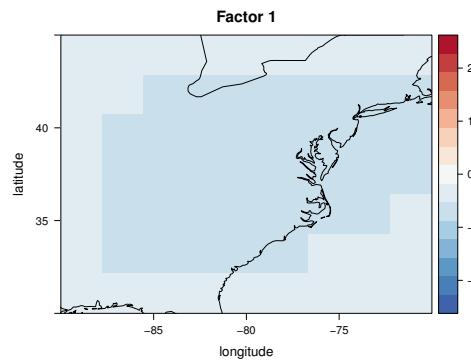
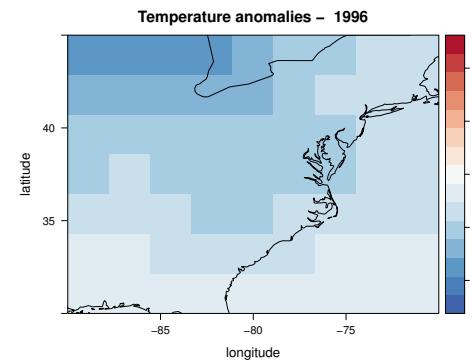
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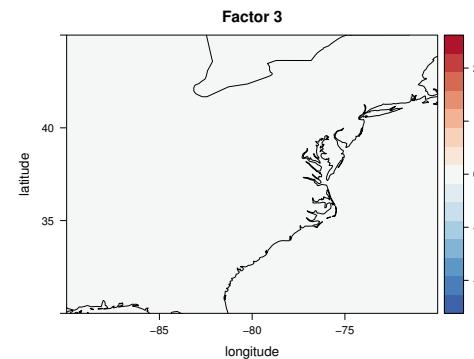
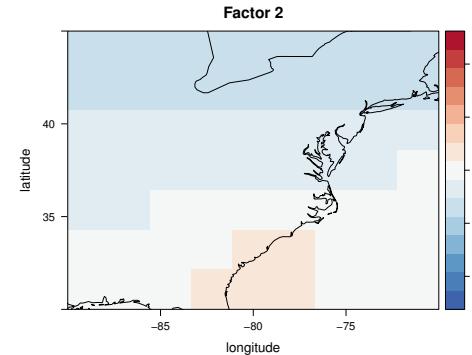
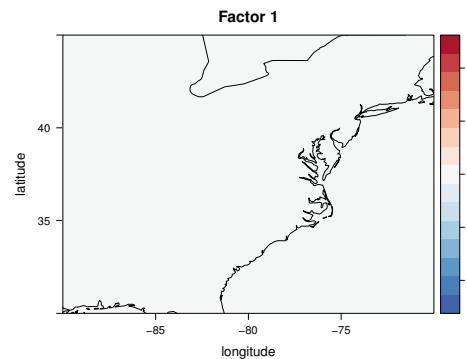
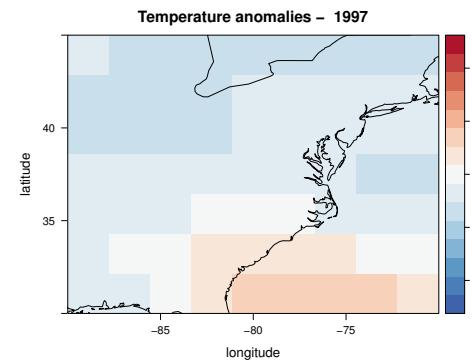
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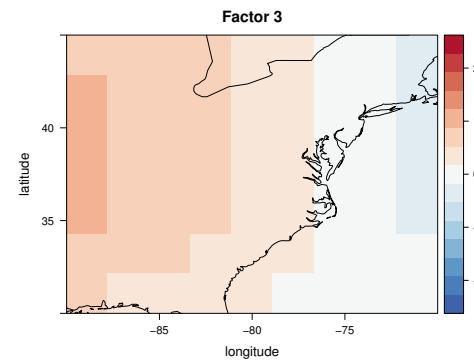
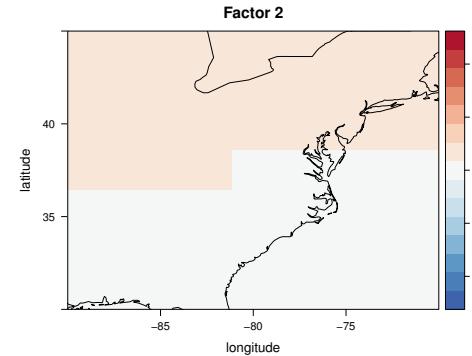
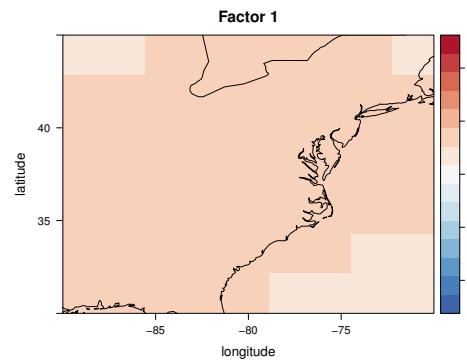
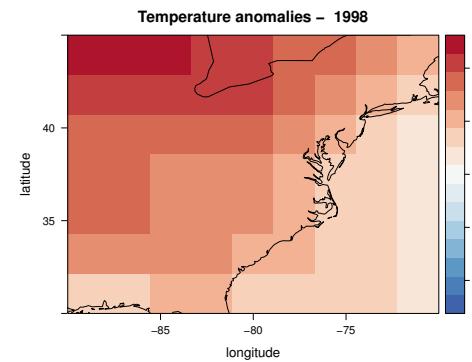
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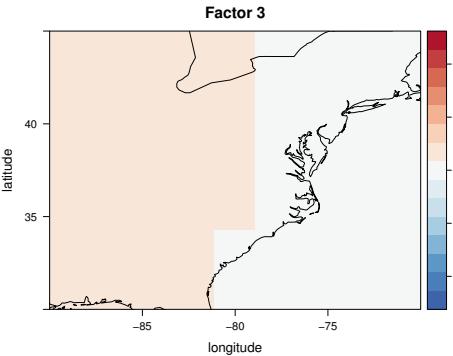
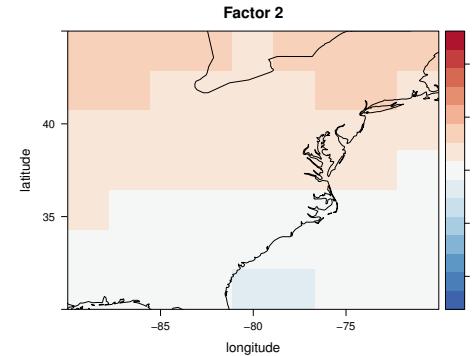
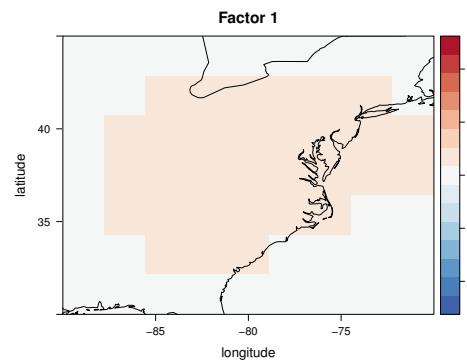
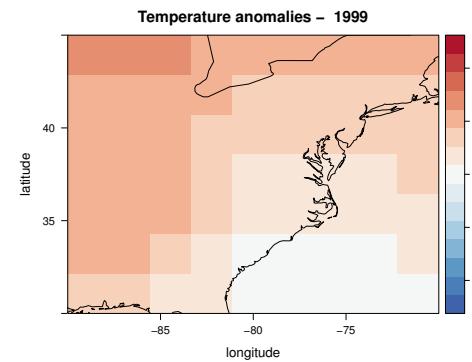
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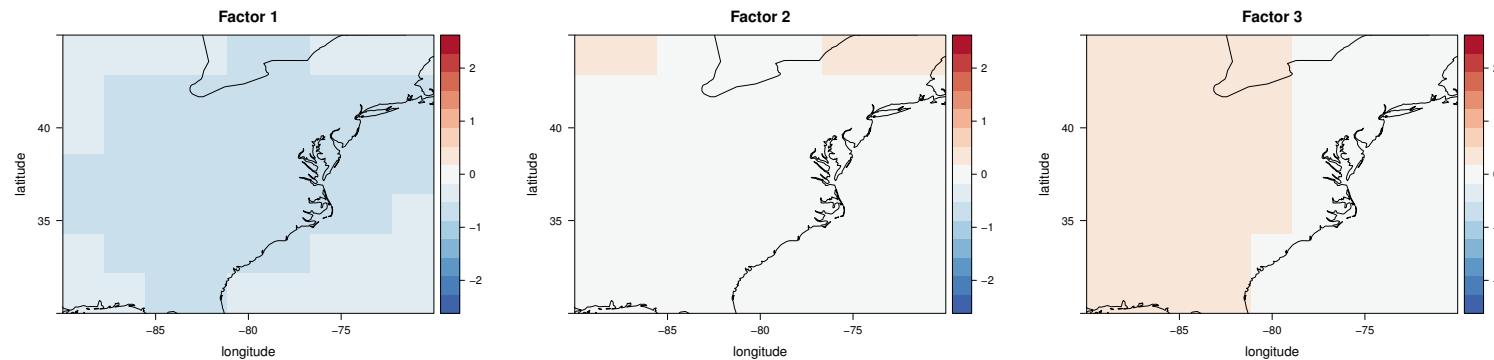
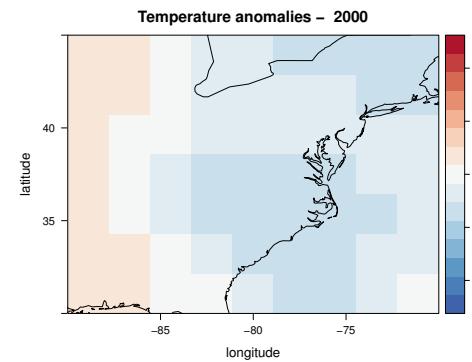
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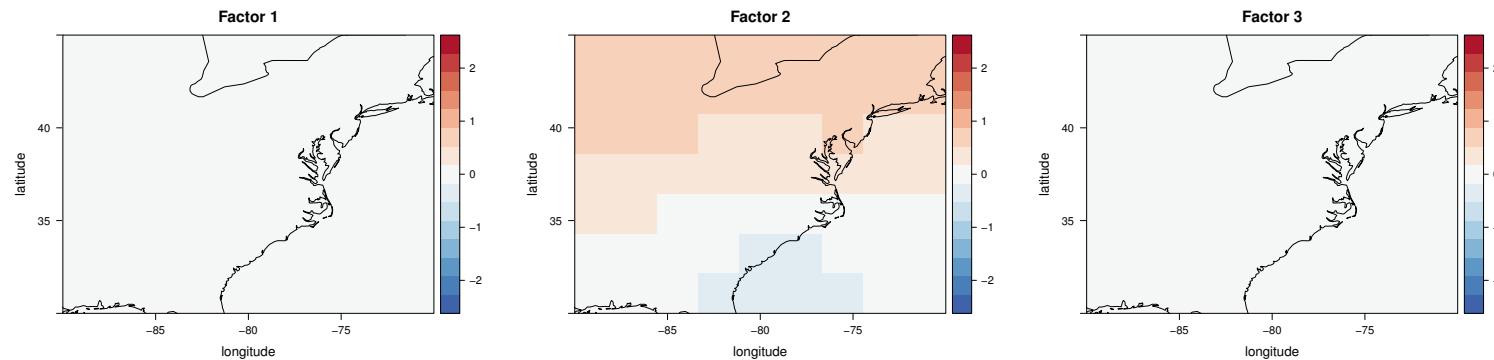
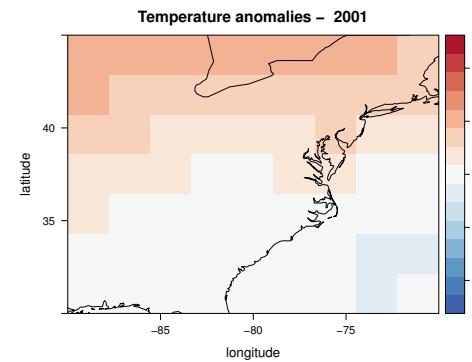
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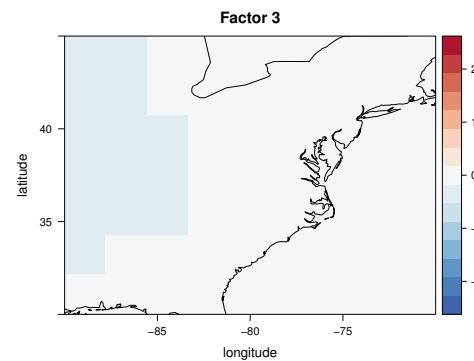
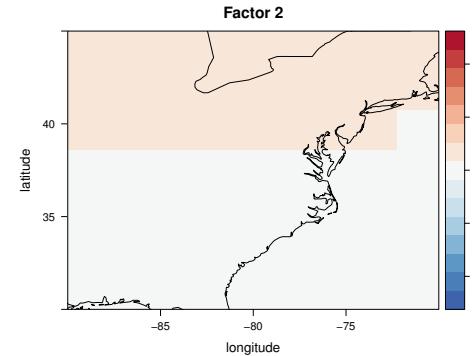
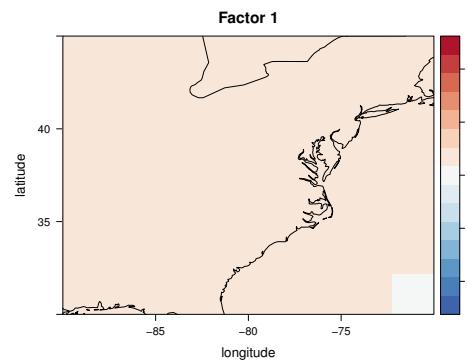
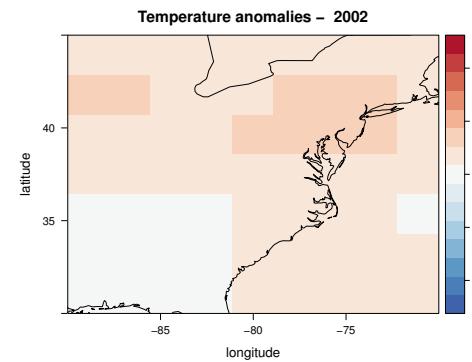
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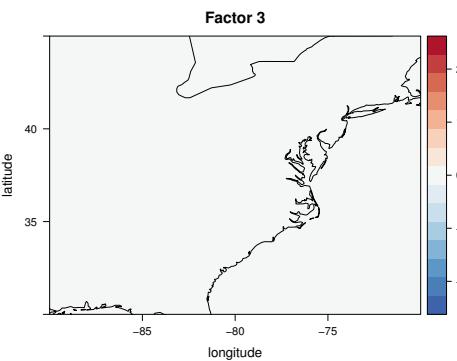
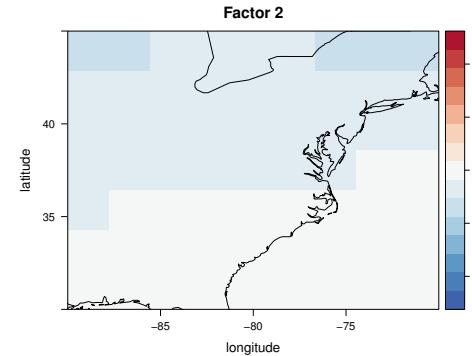
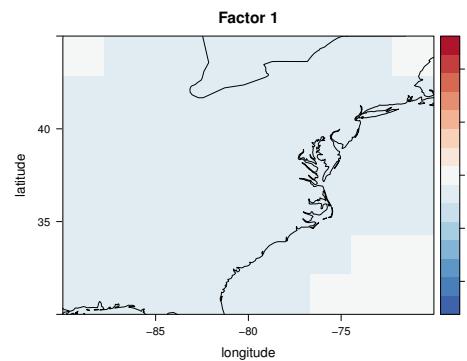
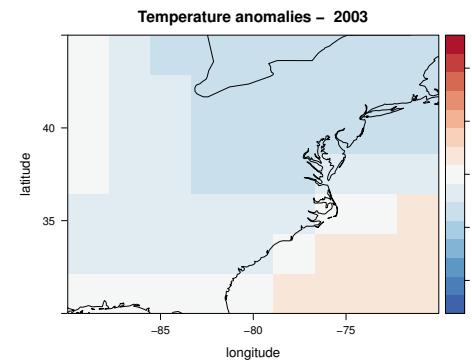
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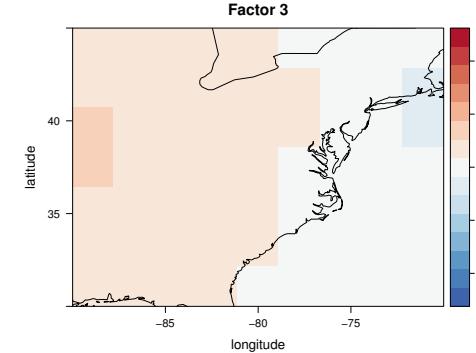
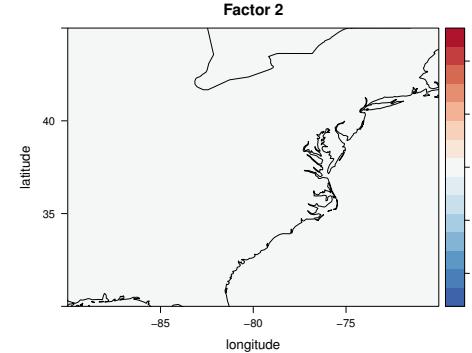
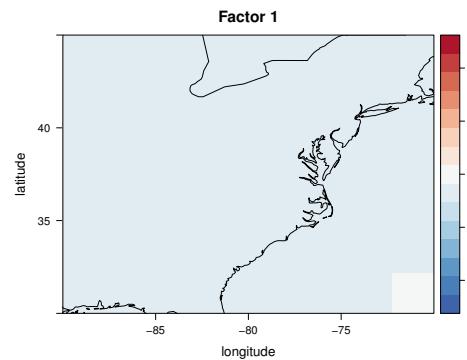
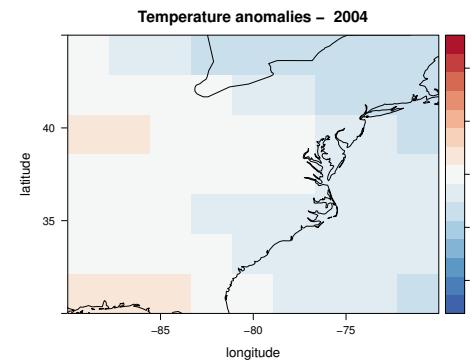
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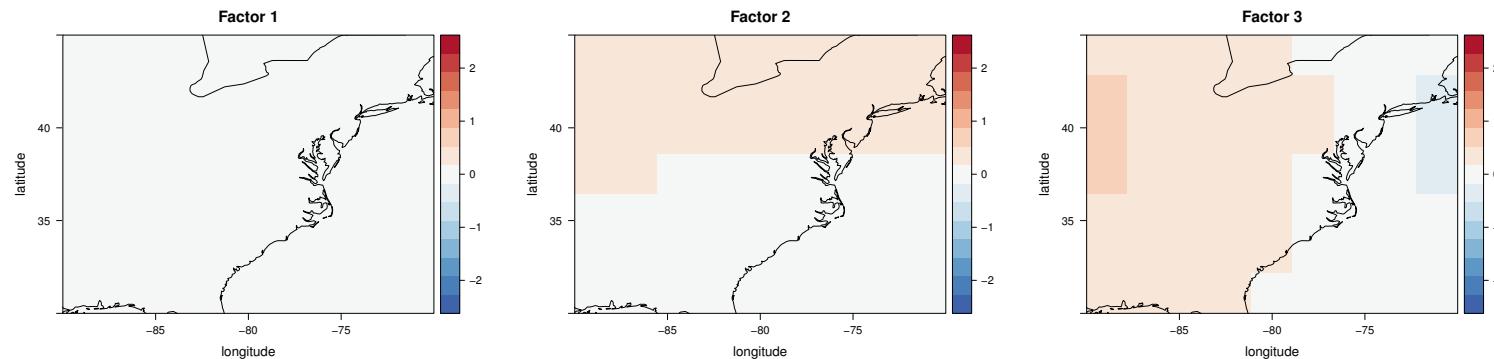
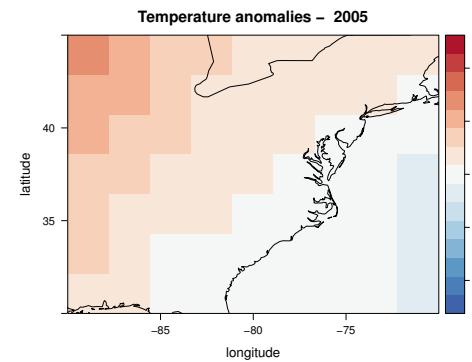
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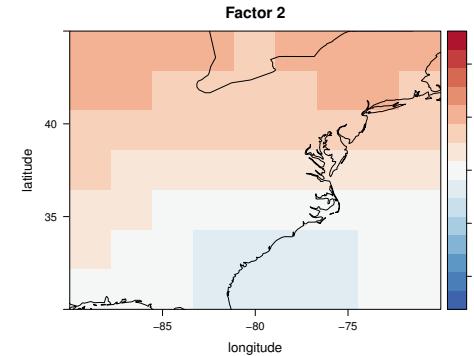
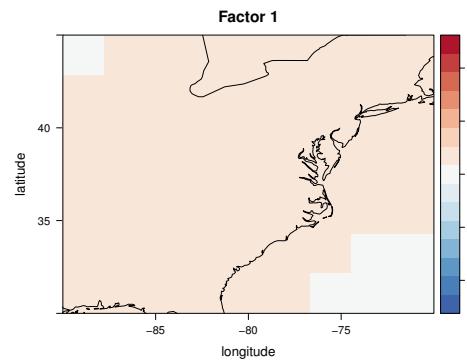
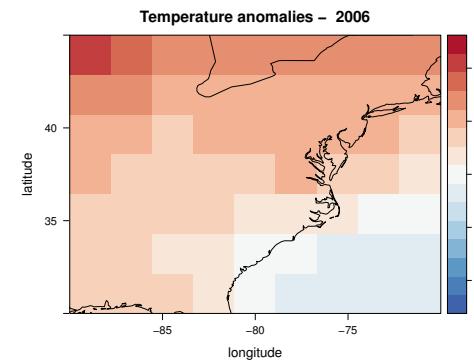
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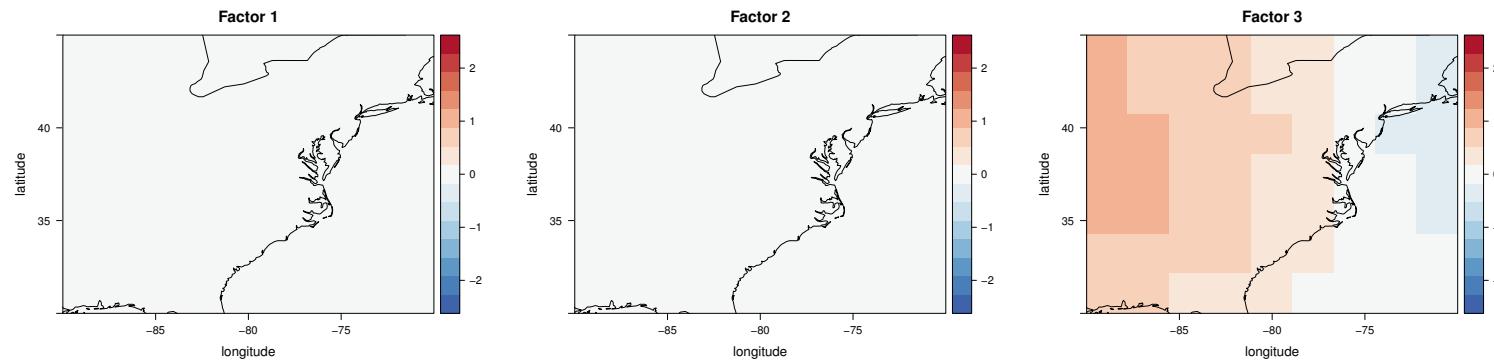
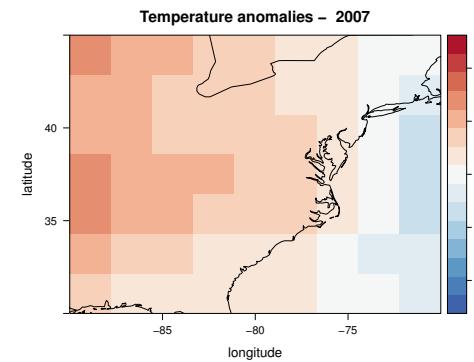
# Factor contributions in 2005



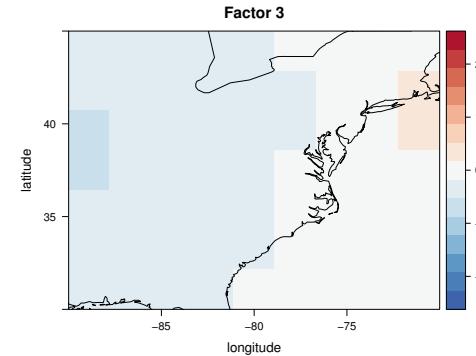
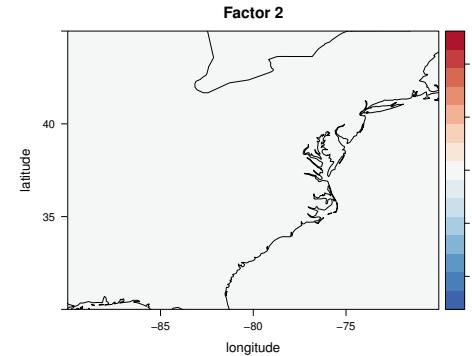
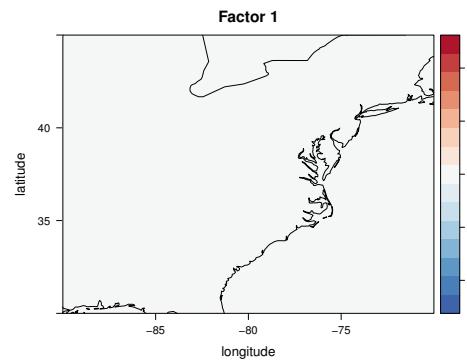
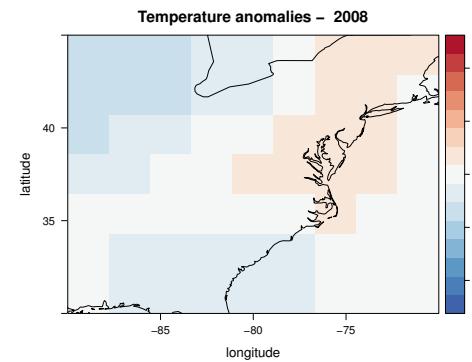
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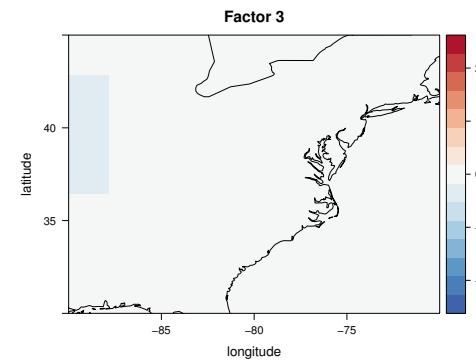
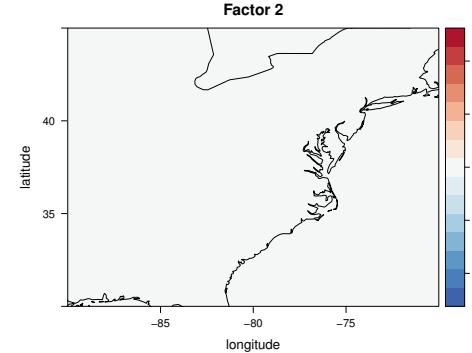
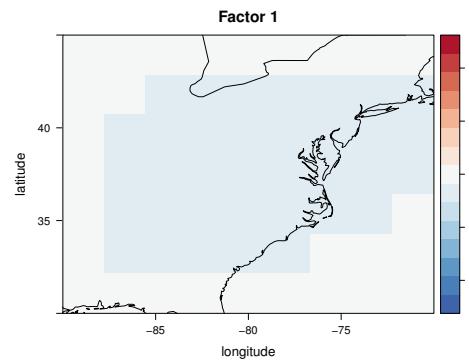
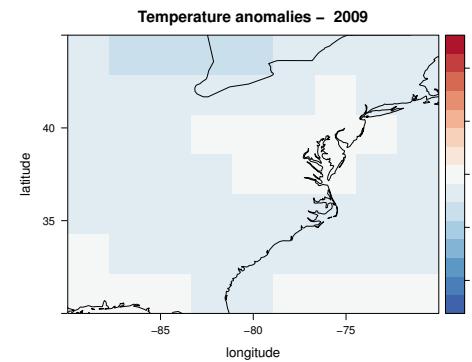
# Factor contributions in 2007



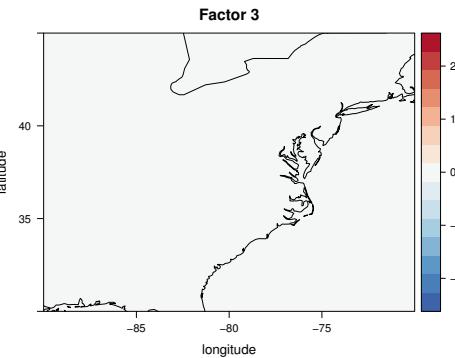
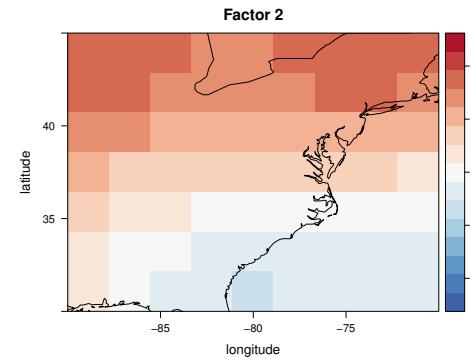
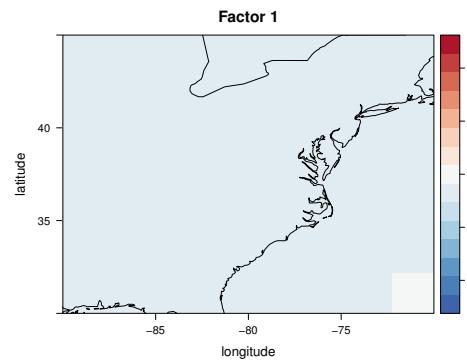
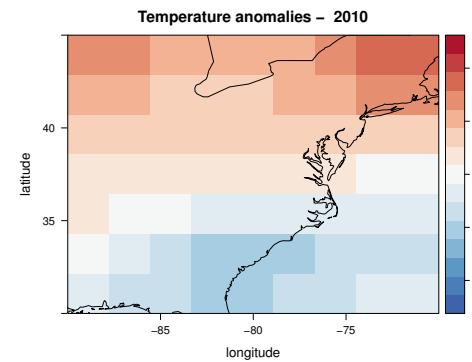
# Factor contributions in 2008



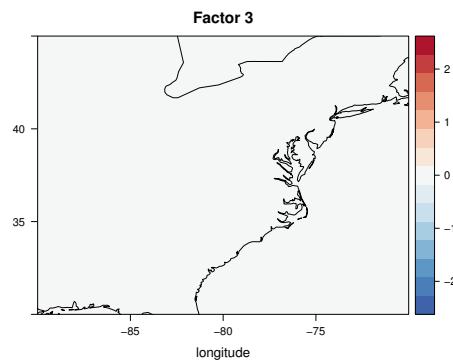
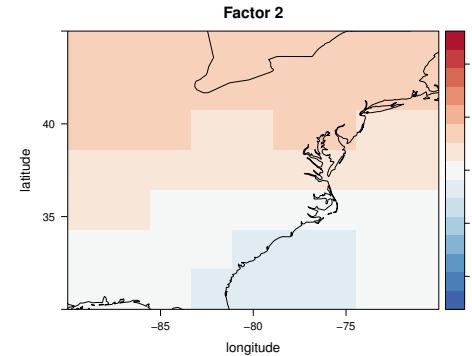
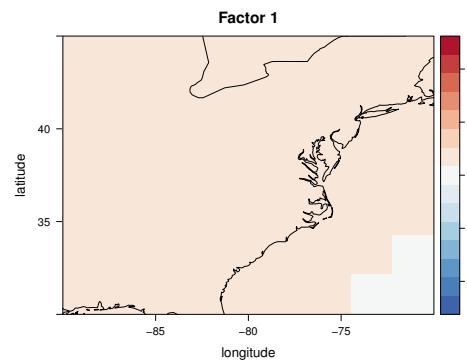
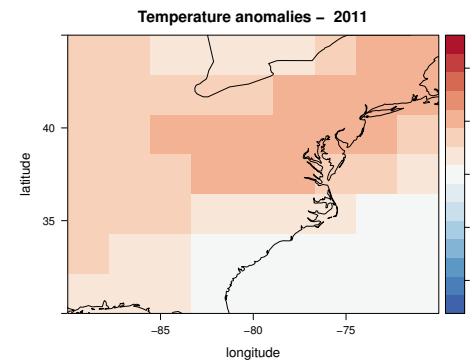
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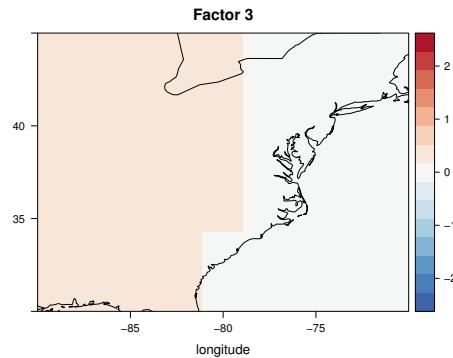
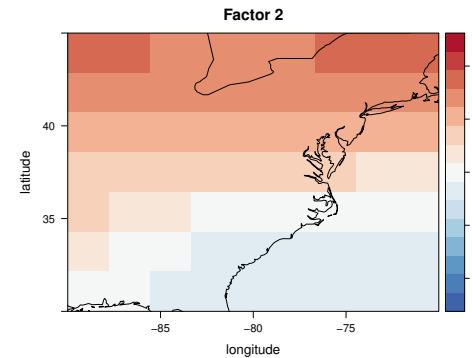
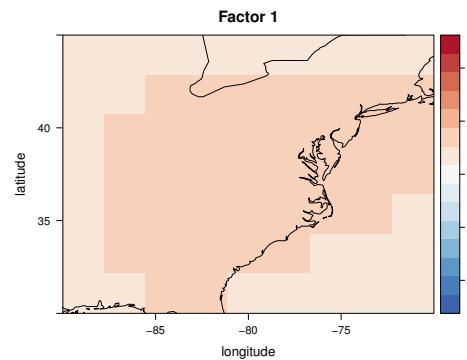
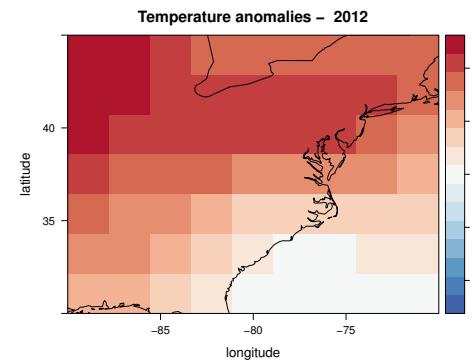
# Factor contributions in 2010



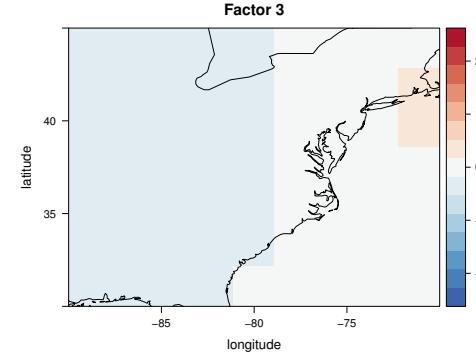
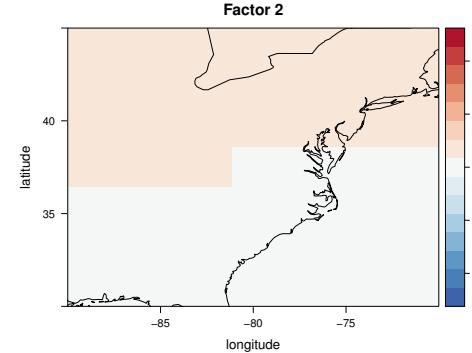
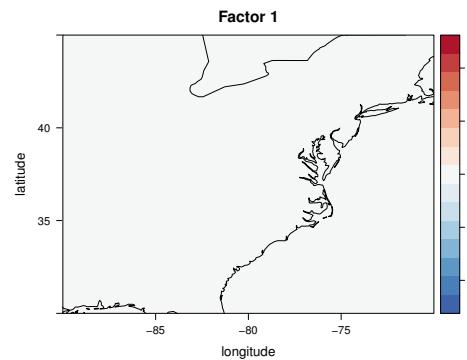
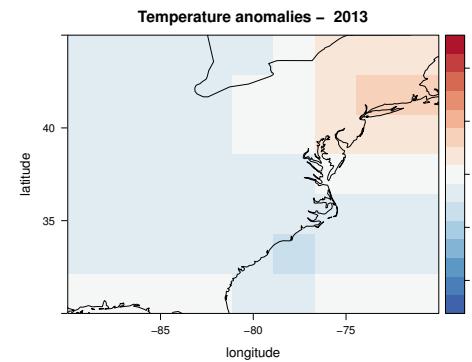
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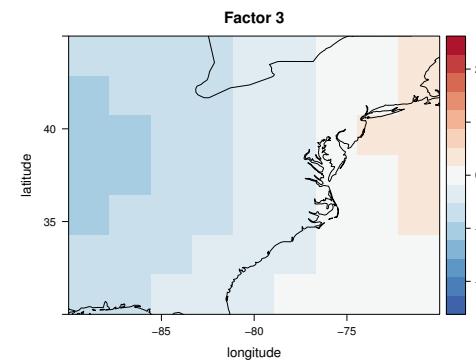
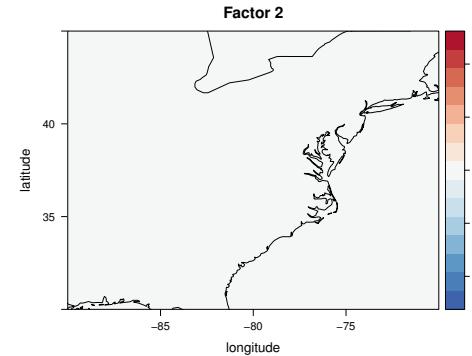
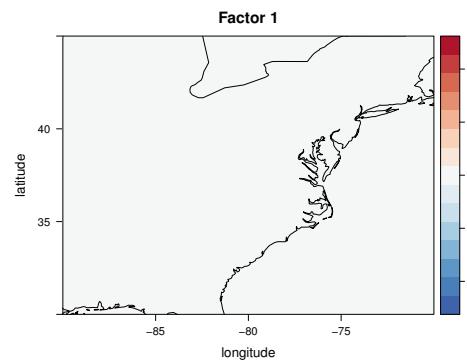
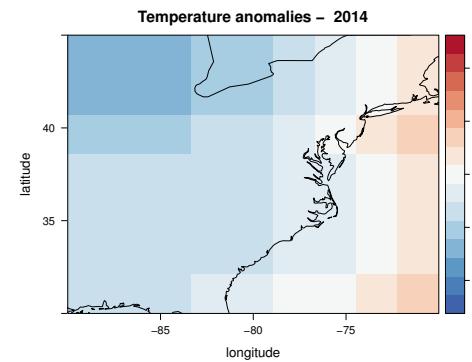
# Factor contributions in 2012



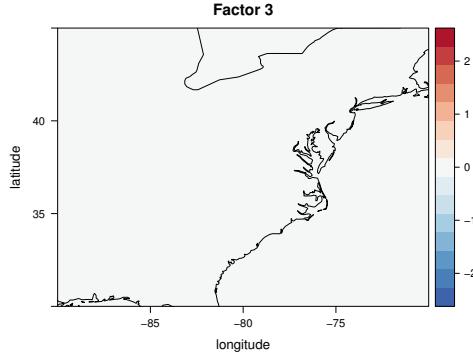
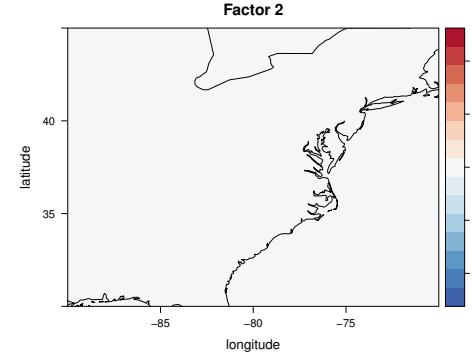
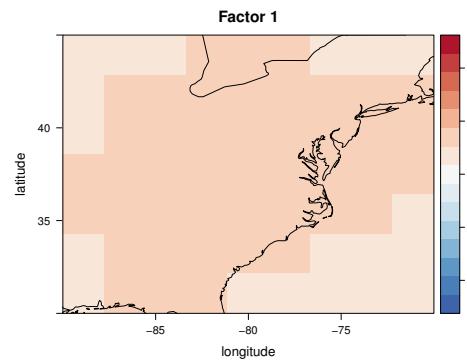
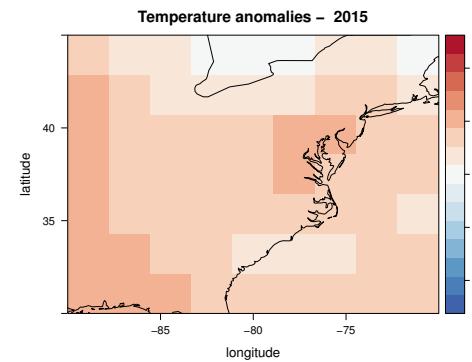
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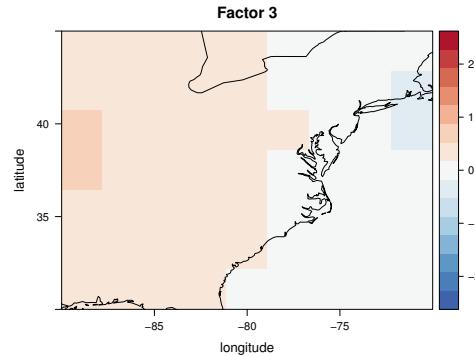
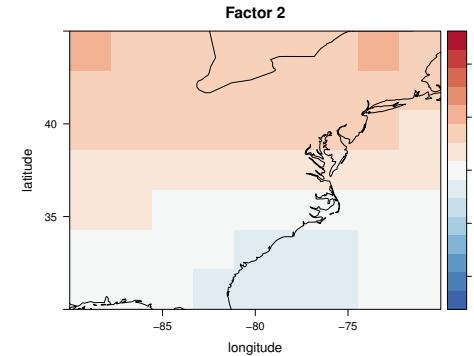
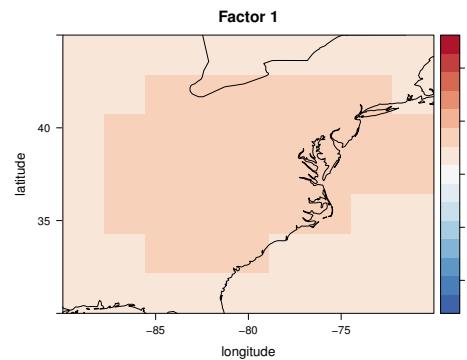
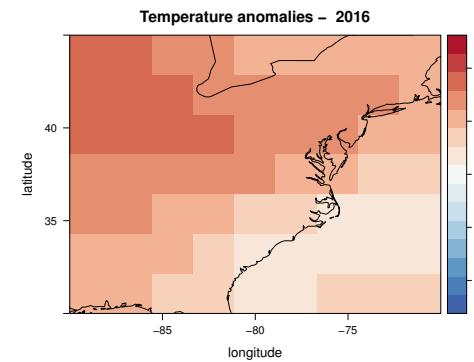
# Factor contributions in 2014



# Factor contributions in 2015

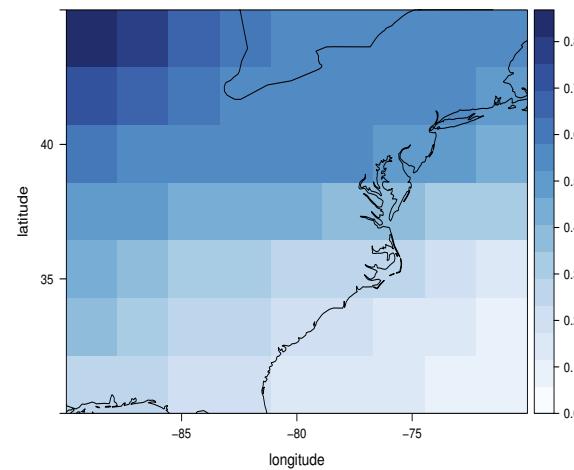


# Factor contributions in 2016

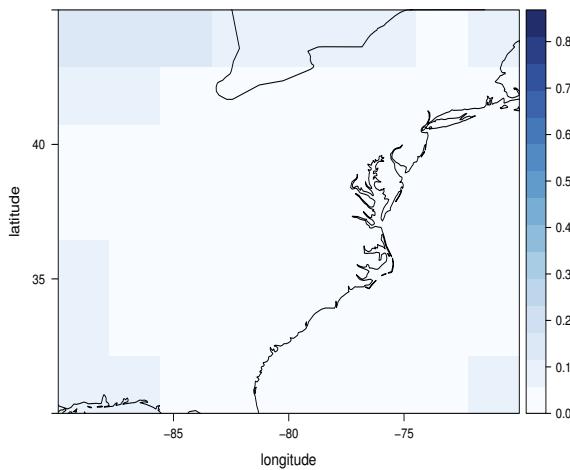


# Observed and idiosyncratic variances

Observed



Idiosyncratic



- Model explains about 90% of the total variability.

# Wrapping up Sessions 4 and 5

- ▶ Models for multivariate time series;
- ▶ Shared structure/dependence through latent factors;
- ▶ Dynamic latent factor models (environmental application);
- ▶ Dynamic spatiotemporal factor models (environmental application).

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- ▶ Dynamic latent factor models (environmental application);
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